

# Product Line Testing



KV Product Line Engineering (343.354)

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# Overview of SPL Testing

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- ▶ Describe the main challenges that variability adds for software testing
- ▶ Present a taxonomy of the different approaches available for SPL testing
- ▶ Illustrate with more detail Combinatorial Interaction Testing in the SPL context

# Verification vs Validation

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## ► Verification

- Activities to assess if a program implements some specific functionality or provides a quality
- Are we building the product **right**?

## ► Validation

- Activities to assess if a program is what the user actually requires
- Are we building the **right** product?

# Some Approaches to Verification

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## ▶ Testing

- Experimenting with the behavior of a program
- Dynamic – runs or executes a program

## ▶ Analysis

- Deduces the correct operation of programs from static models

# Software Testing in General

- ▶ Software Testing – IEEE Glossary of terms 1990
  - The process of operating a system or component ***under specified conditions***, observing or recording the results, and making an evaluation of some aspect of the system or component.
- ▶ Why is testing important?
  - Errors are unavoidable human nature and problem complexity
  - Improve product confidence in developers and users
  - Mandatory activity for some domains like safety critical systems

# Goals of Testing

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- ▶ Dijkstra's quote
  - Program testing can be used to show the presence of bug, but never to show their absence
  
- ▶ Goals
  - What failures does my program have?
  - What causes the failures in my program?
  - How can those failures be fixed?

# What is a failure?

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- ▶ Failure
  - A manifest symptom of the presence of an error
  
- ▶ How do you know a failure is a failure?
  - Non conformance to a specification
  
- ▶ What is a specification?
  - Statement of user or program requirements

# Some Terminology

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- ▶ Defect
  - An error in a program that can cause a failure
  
- ▶ Fault
  - An incorrect state in a program execution that leads to a failure
  
- ▶ Bug
  - Synonym of defect



# Testing Should Be ...

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- ▶ Systematic
  - Planned activity
  
- ▶ Repeatable
  - Same tests should produce same results
  
- ▶ Accurate
  - Concise information on testing conditions and expected outcomes

# When to do testing?

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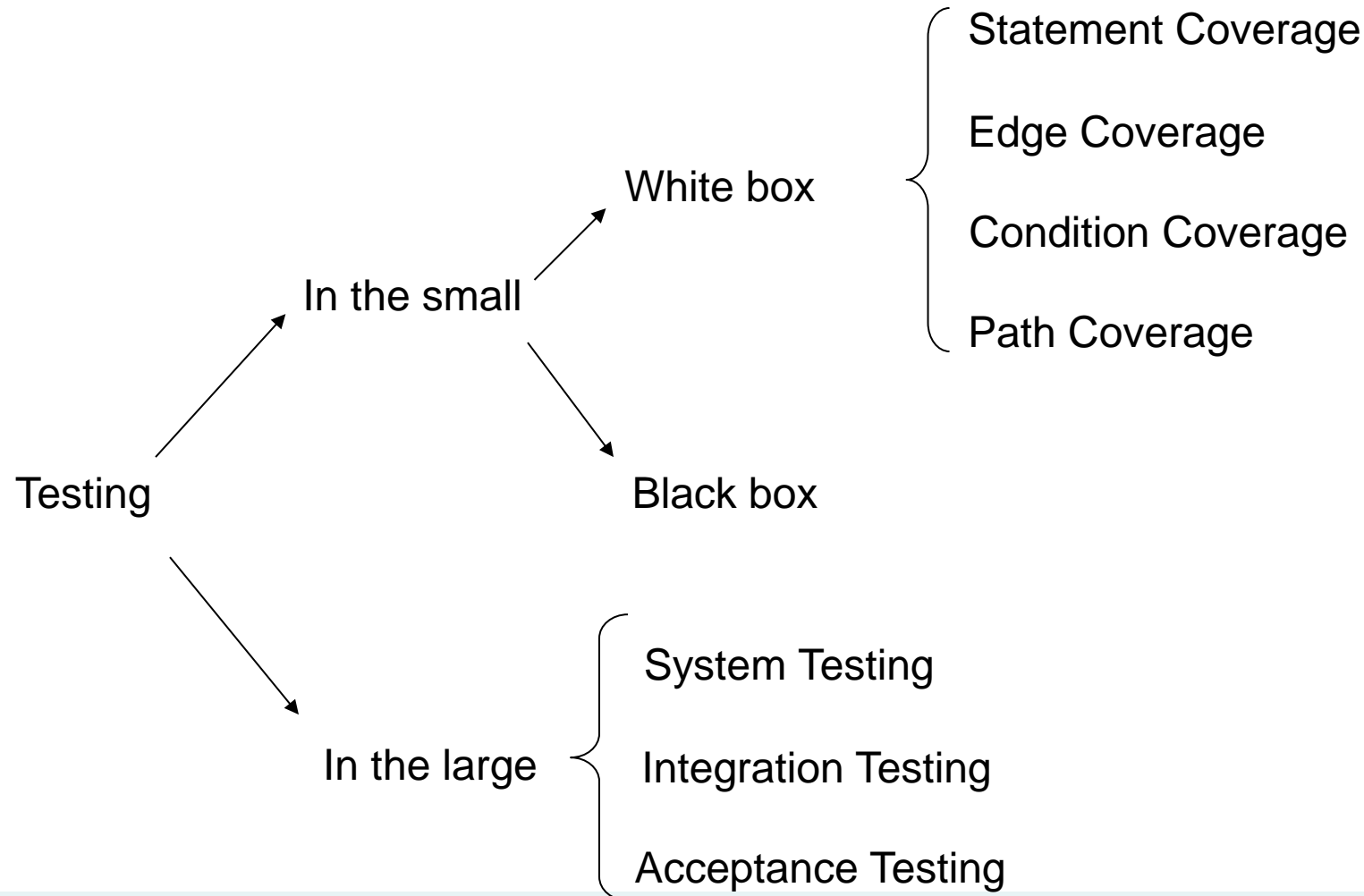
- ▶ As early as possible
  - In the development life cycle
    - regardless of model (waterfall, spiral, etc.)
  
- ▶ As frequent as possible
  - Incremental development approach
  
- ▶ As exhaustive as possible
  - Test everything that is of interest
    - User interface, functionality, response time

# Testing Myths

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- ▶ Programs can be tested completely
  - Possible to achieve 100% failure free programs
  
- ▶ Testing is a fully automated activity
  - No need for software engineers
  
- ▶ The more tests used the more reliable programs are
  - Quantity over quality of tests

# Software Testing Panorama



# What about SPL testing?

- ▶ The key different is the large number of products that form a product line
- ▶ Some key questions:
  - Which testing should be done at domain engineering and which at application engineering?
  - How can testing artifacts be reused?
  - Should all products be tested? If not, which ones to select? In what order to test them?

# Taxonomy of SPL Testing Approaches (1) – [Neto11]

## ▸ Testing strategy

- What is the process to test the products?

## ▸ Possibilities

- Test product by product
  - Do not take advantage of reuse
  - May not be feasible for SPL with many products
- Incremental testing
  - Test a first product and use regression testing techniques for the next products
- Opportunistic reuse
  - Ad hoc reuse of testing artifacts and effort
- Design of test assets for reuse
  - Ideal case

# Taxonomy of SPL Testing Approaches (2)

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- ▶ **Type of analysis techniques**
  - What kinds of analysis can be used for testing?
  
- ▶ Two alternatives
  - Dynamic
    - Based on the execution of the products
  - Static
    - Examples: walkthroughs, model checking, type checking

# Taxonomy of SPL Testing Approaches (3)

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## ▸ Testing Level

- Level of granularity and development activity

## ▸ Possibilities

- At Domain Engineering
  - Unit testing: smallest unit of software implementation. Usually at the code level.
  - Integration testing: applied when modules (features) are integrated to form the common platform
- At Application Engineering
  - System testing: does the product meet the required features?
  - Acceptance testing: is the customer satisfied with the product?
  - Integration testing: applied when modules (features) are integrated to create a product.



# Other Important SPL Testing Issues

- ▶ Testability
  - Making a system more suitable for testing
  - Using additional information such as control flow to reduce the number of tests to apply
  
- ▶ Test coverage
  - Extensions of the coverage criteria of one-off programs (e.g. branch coverage, statement coverage, etc.)

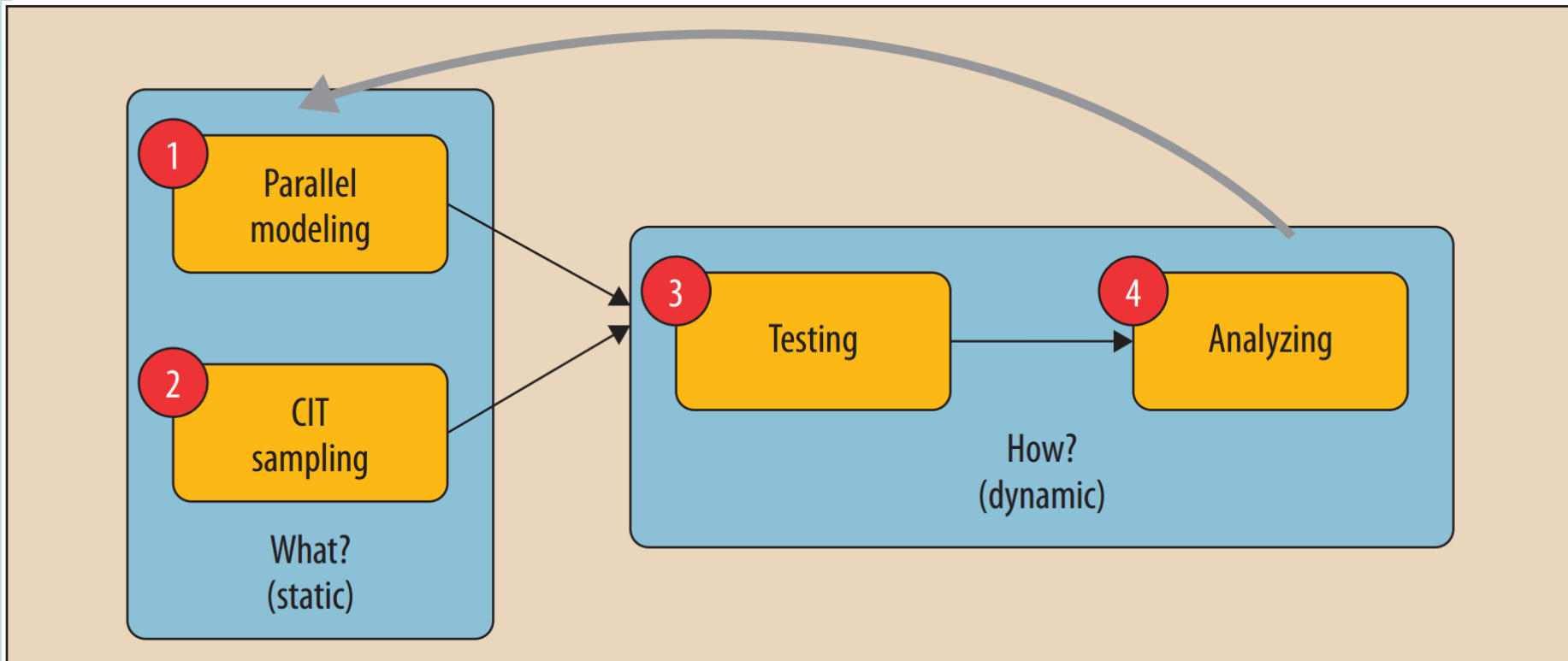
# Combinatorial Interaction Testing for SPL

# Combinatorial Interaction Testing (CIT)

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- ▶ Combinatorial interaction testing
  - Basic idea: select a representative subset of program elements where interaction errors are more likely to occur.
  
- ▶ Applied to SPL testing consist of the following steps
  - Select a set of products from the product line
  - Configure and implement the selected products
  - Apply standard testing techniques to each individual selected product

# CIT Phases

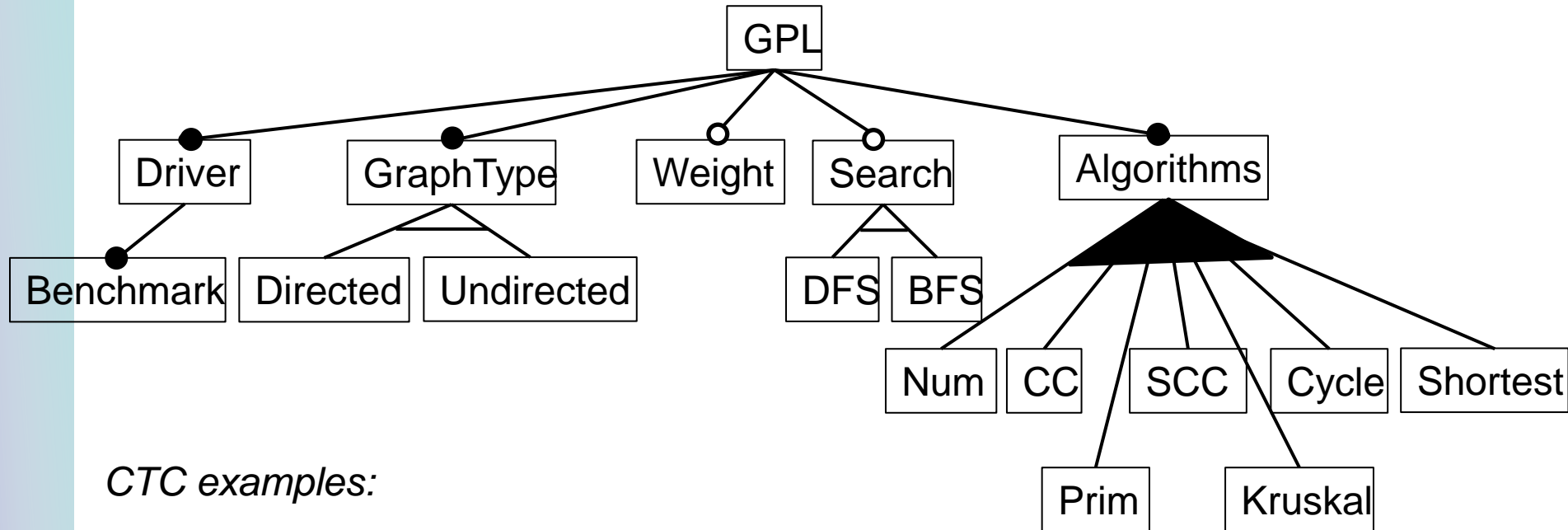


C. Yilmaz, S. Fouche', M. B. Cohen, A. A. Porter, G. Demiröz, and U. Koc, "Moving forward with combinatorial interaction testing," *IEEE Computer*, vol. 47, no. 2, pp. 37–45, 2014.

# CIT Phases

- ▶ **What** products have to be tested?
  - To sufficiently test the SPL
- ▶ **How** should the products be tested?
  - Do we need to run all tests for all the products?
  - Which tests execute which features?
  - Prioritize test execution (e.g. importance, time, ...)
- ▶ Feedback analysis information to what-phase
  - Execution time for certain tests -> reduce testing of this feature if possible
  - Features with more faults -> test more thoroughly

# Running Example – Graph Product Line (GPL)



*CTC examples:*

Num requires Search    Prim requires Weight

Cycle requires DFS    Prim requires Undirected

Kruskal excludes Prim

# Terminology (1)

- ▶ **Feature List (FL)** is the list of features in a feature model.
  - For GPL feature model the feature list FL is [GPL, Driver, Benchmark, GraphType, Directed, Undirected, Weight, Search, DFS, BFS, Algorithms, Num, CC, SCC, Cycle, Shortest, Prim, Kruskal ].

# Terminology (2)

- ▶ **Feature Set (FS)** is a 2-tuple  $[sel, \neg sel]$  where  $sel$  and  $\neg sel$  are respectively the set of selected and not-selected features of a member product.
- ▶ Let  $FL$  be a feature list, thus
$$sel \subseteq FL, \quad \neg sel \subseteq FL$$
$$sel \cap \neg sel = \emptyset$$
$$sel \cup \neg sel = FL$$
- ▶ The terms  $p.sel$  and  $p.\neg sel$  respectively refer to the set of selected and not-selected features of product  $p$ .



# Terminology (3)

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## ► Valid feature set

- A feature set  $fs$  is valid in feature model  $fm$ , i.e.  $valid(fs, fm)$  holds, if it does not contradict any of the constraints introduced by  $fm$ .
- Recall, we have seen how this operation is implemented in the previous class

# In GPL, some valid feature sets

FS	GPL	Dri	Gtp	W	Se	Alg	B	D	U	DFS	BFS	N	CC	SCC	Cyc	Sh	Prim	Kru
fs0	✓	✓	✓	✓		✓	✓		✓								✓	
fs1	✓	✓	✓	✓	✓	✓	✓		✓	✓			✓					✓
fs2	✓	✓	✓		✓	✓	✓	✓		✓		✓			✓			
fs3	✓	✓	✓	✓	✓	✓	✓	✓			✓	✓				✓		
fs4	✓	✓	✓	✓	✓	✓	✓	✓		✓		✓		✓	✓	✓		
fs5	✓	✓	✓	✓	✓	✓	✓		✓	✓		✓	✓		✓		✓	
fs6	✓	✓	✓	✓	✓	✓	✓		✓		✓	✓	✓					✓
fs7	✓	✓	✓	✓	✓	✓	✓		✓	✓		✓	✓		✓			

Driver (Dri), GraphType (Gtp), Weight (W), Search (Se), Algorithms (Alg),  
Benchmark (B), Directed (D), Undirected (U), Num (N), Cycle (Cyc), Shortest (Sh),  
Kruskal (Kr).

# Terminology (4)

## ► Definition of t-set

- A **t-set**  $ts$  is a 2-tuple  $[sel, \neg sel]$  representing a partially configured product, defining the selection of  $t$  features of feature list  $FL$ :

$$ts.sel \cup ts.\neg sel \subseteq FL \wedge$$

$$ts.sel \cap ts.\neg sel = \emptyset \wedge$$

$$|ts.sel \cup ts.\neg sel| = t.$$

- We say t-set  $ts$  is covered by feature set  $fs$  iff

$$ts.sel \subseteq fs.sel \wedge ts.\neg sel \subseteq fs.\neg sel.$$

- A t-set  $ts$  is valid in a feature model  $fm$  if there exists a valid feature set  $fs$  that covers  $ts$ .

# Example of 2-wise sets – pairwise testing (1)

FS	GPL	Dri	Gtp	W	Se	Alg	B	D	U	DFS	BFS	N	CC	SCC	Cyc	Sh	Prim	Kru
fs0	✓	✓	✓	✓		✓	✓		✓								✓	
fs1	✓	✓	✓	✓	✓	✓	✓		✓	✓			✓					✓
fs2	✓	✓	✓		✓	✓	✓	✓		✓		✓			✓			
fs3	✓	✓	✓	✓	✓	✓	✓	✓			✓	✓				✓		
fs4	✓	✓	✓	✓	✓	✓	✓	✓		✓		✓		✓	✓	✓		
fs5	✓	✓	✓	✓	✓	✓	✓		✓	✓		✓	✓		✓		✓	
fs6	✓	✓	✓	✓	✓	✓	✓		✓		✓	✓	✓					✓
fs7	✓	✓	✓	✓	✓	✓	✓		✓	✓		✓	✓		✓			

Driver (Dri), GraphType (Gtp), Weight (W), Search (Se), Algorithms (Alg),  
Benchmark (B), Directed (D), Undirected (U), Num (N), Cycle (Cyc), Shortest (Sh),  
Kruskal (Kr).

2-wise set [{Driver},{Prim}] covered by fs1-fs4, fs6-fs7

# Example of 2-wise sets – pairwise testing (2)

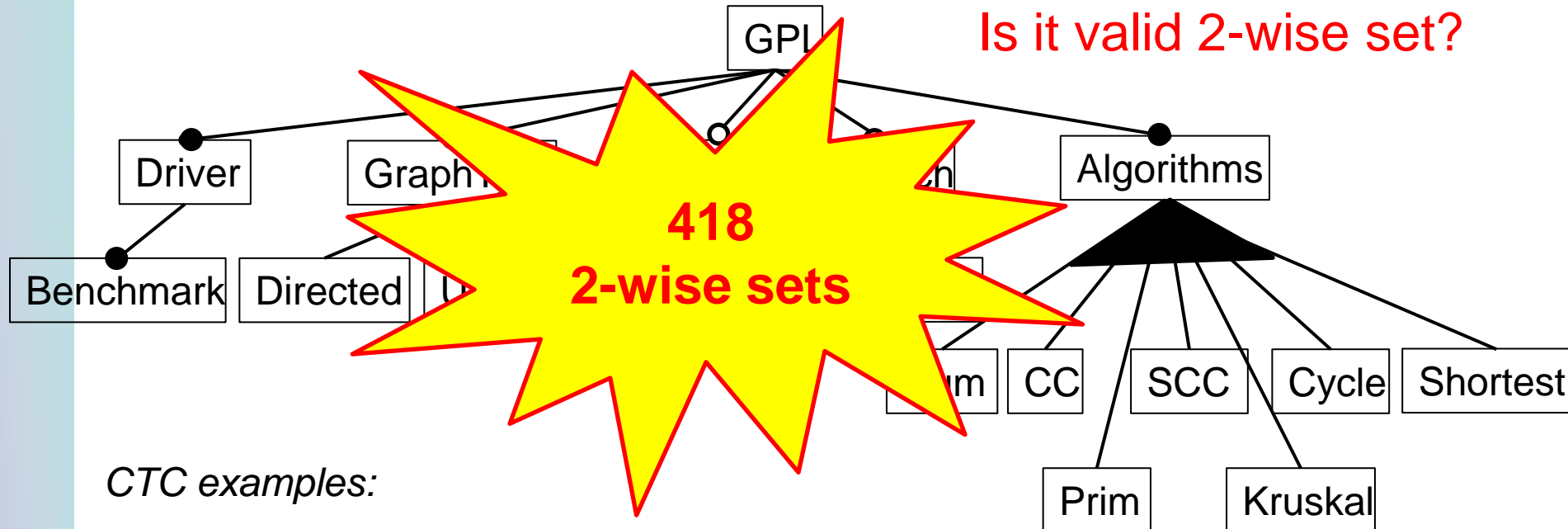
FS	GPL	Dri	Gtp	W	Se	Alg	B	D	U	DFS	BFS	N	CC	SCC	Cyc	Sh	Prim	Kru
fs0	✓	✓	✓	✓		✓	✓		✓								✓	
fs1	✓	✓	✓	✓	✓	✓	✓		✓	✓			✓					✓
fs2	✓	✓	✓		✓	✓	✓	✓		✓		✓			✓			
fs3	✓	✓	✓	✓	✓	✓	✓	✓			✓	✓				✓		
fs4	✓	✓	✓	✓	✓	✓	✓	✓		✓		✓		✓	✓	✓		
fs5	✓	✓	✓	✓	✓	✓	✓		✓	✓		✓	✓		✓		✓	
fs6	✓	✓	✓	✓	✓	✓	✓		✓		✓	✓	✓					✓
fs7	✓	✓	✓	✓	✓	✓	✓		✓	✓		✓	✓		✓			

Driver (Dri), GraphType (Gtp), Weight (W), Search (Se), Algorithms (Alg),  
Benchmark (B), Directed (D), Undirected (U), Num (N), Cycle (Cyc), Shortest (Sh),  
Kruskal (Kr).

2-wise set  $[\{\text{Kruskal}, \text{DFS}\}, \emptyset]$  covered by fs1

# Example of 2-wise sets – pairwise testing (3)

Is it valid 2-wise set?



*CTC examples:*

Num requires Search    Prim requires Weight  
Cycle requires DFS    Prim requires Undirected  
Kruskal excludes Prim

2-wise set  $[\emptyset, \{\text{Directed}, \text{Undirected}\}]$

# Terminology (5)

## ► Definition t-wise covering array

- A tCA for a feature model  $fm$  is a set of valid feature sets that covers all valid t-sets denoted by  $fm$ .

## ► Questions:

- How can t-wise covering arrays be computed?
- Can a minimum covering array be found?

## ► Answer

- Complex problem – NP complete

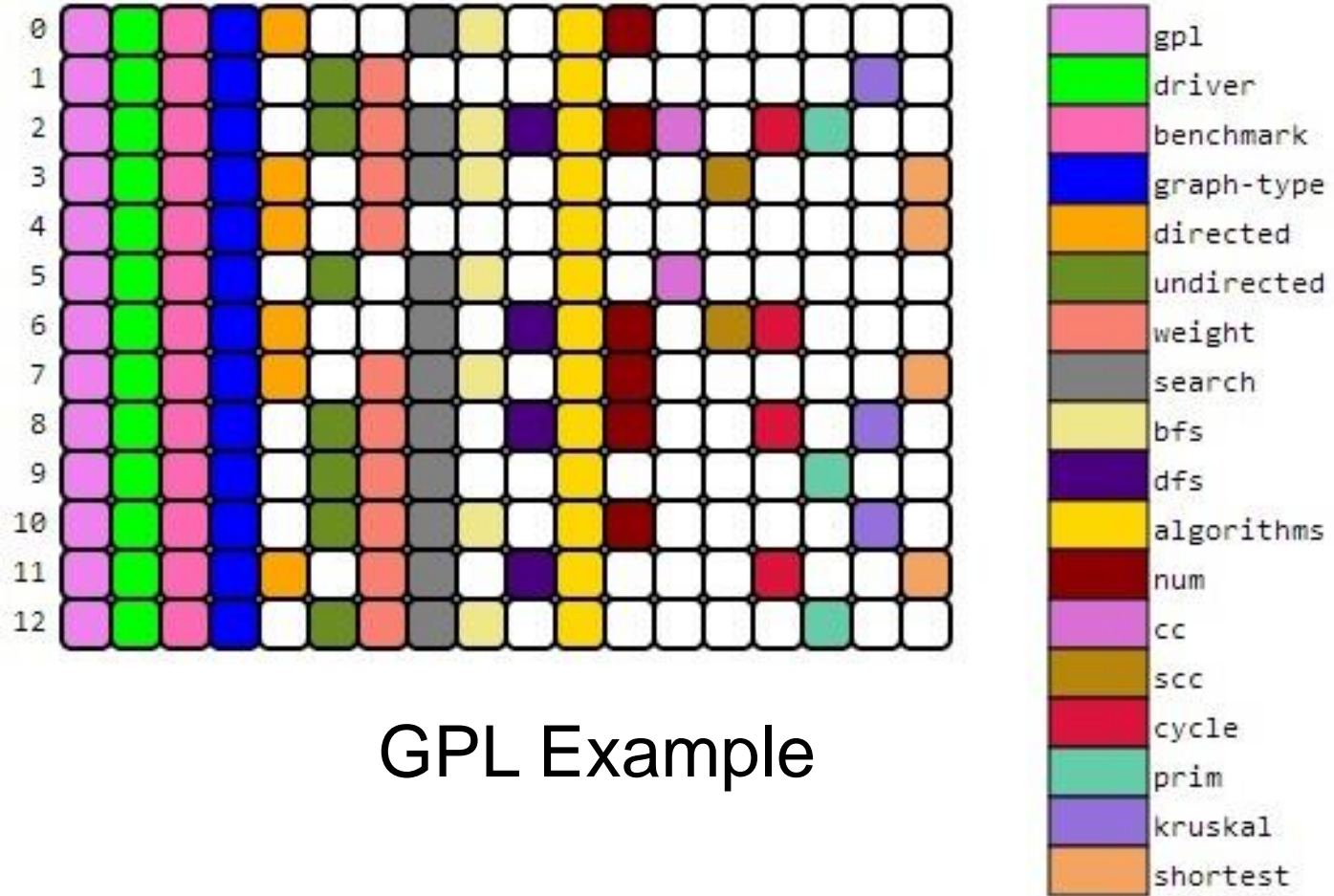
# Terminology (6) – Pairwise Testing SPL

- ▶ **Pairwise Covering Array**
  - A test suite whose products contain **all** the pairwise (i.e.  $t=2$ ) feature combinations denoted by the corresponding feature model
  
- ▶ For example, GPL
  - Has 73 different products
  - Has 418 valid pairs of features to cover



# Covering Array Visualization

VISSOFT<sub>13</sub>



GPL Example



# SPL Pairwise CIT

- ▶ Question:
  - How to compute the pairwise covering arrays from the feature models?
  
- ▶ Multiple approaches:
  - Perrouin et al. – Alloy based
  - MoSo-Polite – CSP based technique
  - PACOGEN – constraint programming
  - ICPL – greedy algorithm
  - CASA – simulated annealing
  - Ensan – genetic algorithm with cyclomatic complexity metric
  - Henard et al. (2012) search based on similarity metrics
  - .....

# Search-Based Software Engineering (SBSE)

Basics – Interlude

# Evolutionary Computation

## ▶ Evolutionary Computation

- Includes several stochastic search methods which computationally simulate the natural evolutionary process

## ▶ Example techniques

- Genetic algorithms
  - Individuals are typically represented as binary strings, commonly used in numerical optimization problems
- Genetic programming
  - Individuals encode programs typically represented as tree-structures whose fitness function evaluate how well the programs execute a computational task

# Evolutionary Computation Illustration

- ▶ Randomly creates an initial population
- ▶ Evaluates the initial population
- ▶ At each generation
  1. select the individuals with best fitness
  2. mutate their characteristics
  3. re-evaluate them

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## Algorithm 1 Basic Evolutionary Algorithm

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```
1:  $t \leftarrow 0$ 
2: initialize  $P(t)$ 
3: evaluate  $P(t)$ 
4: while not termination – condition do
5:    $t \leftarrow t + 1$ 
6:   select  $P(t)$  from  $P(t - 1)$ 
7:   mutate  $P(t)$ 
8:   evaluate  $P(t)$ 
9: end while
```

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# Search-Based Software Engineering (SBSE)

- ▶ **Search-Based Software Engineering** focuses on the application of search-based optimization techniques to problems in software engineering [Harman10]
- ▶ Typical techniques are:
  - Basic searches, e.g. hill-climbing, simulated annealing
  - Techniques based on evolutionary computation



# Hill Climbing Illustration

- ▶ Looks at a neighborhood of SampleSize states and selects the one with best fitness
- ▶ Main problem
  - Can get stuck in a local maxima

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## Algorithm 1 Steepest Ascent Hill Climbing

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```

1:  $X \leftarrow$  random initial state
2:  $I \leftarrow 0$ 
3:  $Best \leftarrow X$ 
4: while ( $I < MaxIter$ )  $\wedge$  ( $evaluate(Best) \neq BestFitness$ ) do
5:    $S \leftarrow 0$ 
6:   while  $S < SampleSize$  do
7:      $X' \leftarrow move(Best)$ 
8:     if  $evaluate(X')$  better than  $evaluate(X)$  then
9:        $X \leftarrow X'$ 
10:    end if
11:     $S \leftarrow S + 1$ 
12:  end while
13:  if  $evaluate(X)$  better than  $evaluate(Best)$  then
14:     $Best \leftarrow X$ 
15:  end if
16:   $I \leftarrow I + 1$ 
17: end while
18: return  $Best$ 

```

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# A Genetic Algorithm for CIT SPL Testing

## Overview

# Prioritized Generic Solver (PGS)

- ▶ A constructive genetic algorithm for computing a pairwise covering array from a feature model
- ▶ Salient characteristics
  - An individual represents a sets of products
  - PGS adds a new product to the partial solution in each iteration until all pairwise combinations are covered
  - In each iteration the algorithm tries to find the product that adds the most coverage to the partial solution
  - Provides a *fix* operation in case the new offspring are not valid products

# PGS Algorithm Overview

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## Algorithm 1. Pseudocode of PGS.

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```

1: proc Input:(PGS)      //Algorithm parameters in 'PGS'
2: TS  $\leftarrow \emptyset$     // Empty the test suite
3: RP  $\leftarrow$  pairs_to_cover(FM) // Initialize the pairwise configurations
4: while not empty(RP) do
5:   t=0
6:   P(t)  $\leftarrow$  Create_Population() // P = population
7:   while evals < totalEvals do
8:     Q  $\leftarrow \emptyset$  // Q = auxiliary population
9:     for i  $\leftarrow$  1 to (PGS.popSize / 2) do
10:      parents $\leftarrow$  Selection(P(t))
11:      offspring $\leftarrow$  Recombination(PGS.Pc,parents)
12:      offspring $\leftarrow$  Mutation(PGS.Pm,offspring)
13:      Fix(offspring)
14:      Evaluate_Fitness(offspring)
15:      Insert(offspring,Q)
16:    end for
17:    P(t+1) := Replace (Q,P(t))
18:    t = t + 1
19:  end while //internal loop
20:  TS  $\leftarrow$  TS  $\cup$  best_solution(P(t))
21:  RemovePairs(RP, best_solution(P(t)))
22: end while //external loop
23: end_proc
  
```

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# PGS comparison

- ▶ We select 19 realistic feature models
  - There exist an available implementation of the SPLs they model
- ▶ Compared against
  - ICPL – greedy approach
  - CASA – simulated annealing approach
- ▶ Preliminary results
  - Fixing operation imposes a heavy performance penalty
  - PGS obtains comparable results in size with CASA

# Multi-Objective Evolutionary Algorithms for Pairwise Testing of SPLs

# Multi-Objective Optimization (MOO) for SPL Testing [CEC14]

- ▶ Some recent work
  - Wang, Ali, Gotlieb – GECCO13
  - Henard, Papadakis, Perrouin, Klein, Traon – SPLC13
- ▶ Common thread
  - Use a linearization approach where each optimization objective is given a weight and later added
$$\sum_{i=1..n} w_i \times Obj_i$$
  - Coverage and test suite size are the recurrent optimization objectives

# Our Two Objectives

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For pairwise testing:

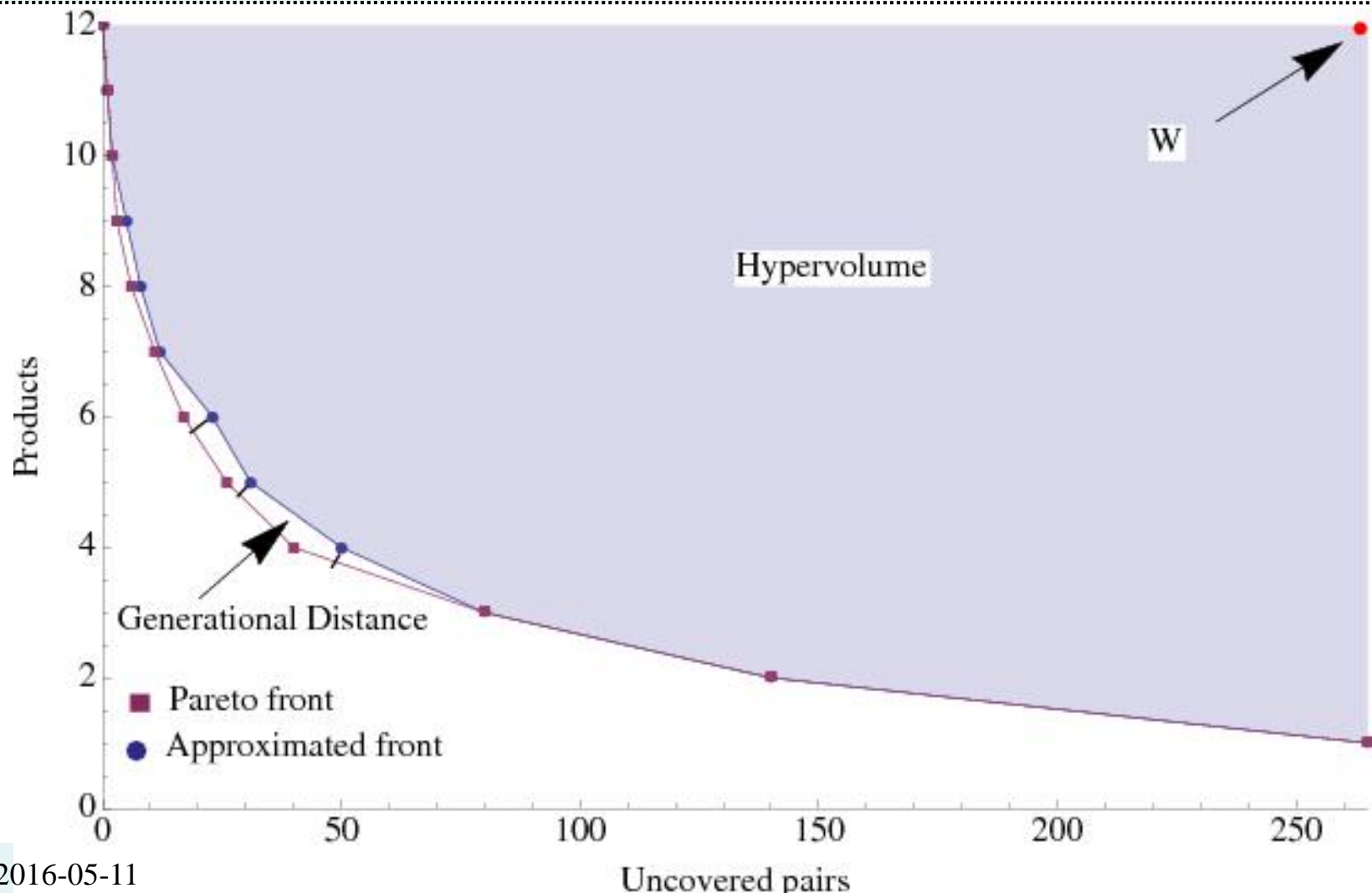
1. Minimize test suite size
2. Minimize pairs to uncover
  - Out of the total of valid pairs denoted by a feature model

# Our work

- ▶ Uses *classical* MOO algorithms
  - NSGA-II – crowding distance and ranking
  - MOCeII – cellular GA, based on neighbourhood
  - SPEA2 – population and archive
  - PAES – evolution strategy
  
- ▶ Use standard comparison MOO metrics
  - Hypervolume
    - Volume in the objective space covered by a non-dominated set of solutions
  - Generational distance
    - Summarizes the distance between the points in a front and the Pareto front.



# Metrics Example – GPL



2016-05-11

Uncovered pairs  
KV PLE SS2016

# Impact of Seeding

- ▶ Seeding
  - Embed domain knowledge into the individuals of the population
  
- ▶ We used 3 seeding strategies for the initial population
  - Size-based Random Seeding
    - Computed a covering array with CASA and use its size to generate the population
  - Greedy Seeding
    - Greedily computes a covering array and uses its elements to generate the population
  - Single-Objective Based Seeding
    - Creates a population based on a single-objective output CASA

# Experimental Setting

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- ▶ We select 17 realistic feature models
  - Feature models publicly available (not reversed engineered)
  - There exist an available implementation of their SPLs
- ▶ Executed 30 independent runs
- ▶ Performed standard statistical analysis

# Findings

- ▶ Seeding has a strong impact on the final result
  - Best strategy was Single-Objective seeding
  
- ▶ What is the best algorithm?
  - Statistically no best winner → NSGA-II, SPEA2, MOCell are comparable on both metrics
  - PAES offer lower quality indicators
    - possible reason – trajectory based approach

# Future Work

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- ▶ SBSE SPL testing
  - Extend the set of feature models case studies
  - Explore beyond pairwise testing
  - Explore beyond two objectives

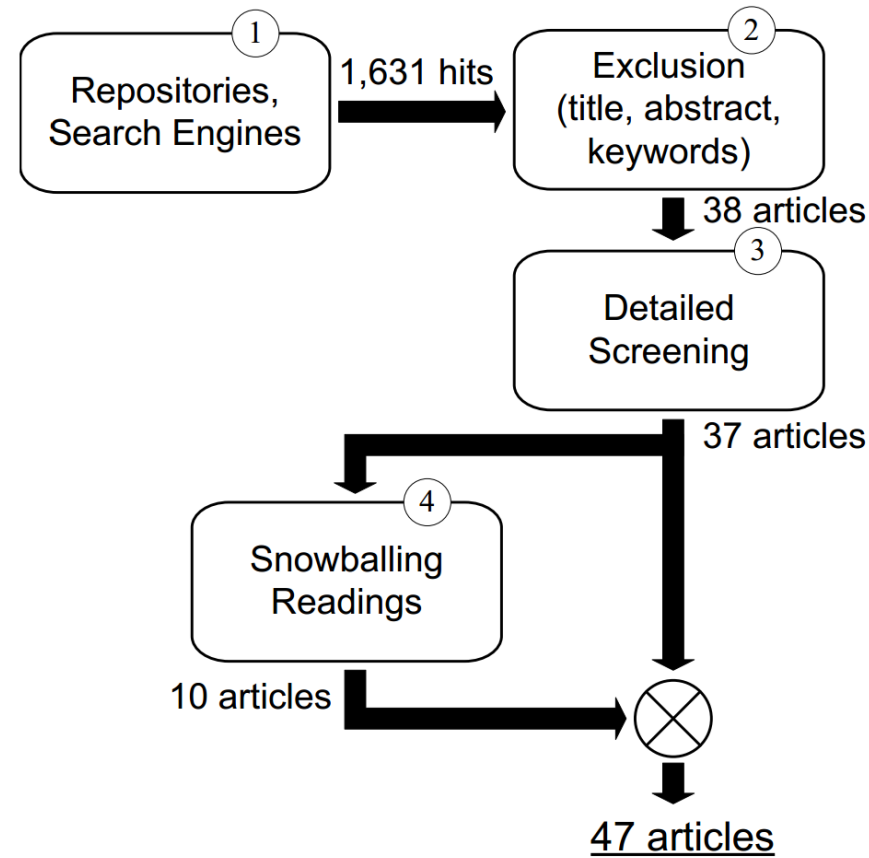
# Systematic Mapping Study on CIT Testing for SPLs

Lopez-Herrejon et al. [ICSTw2015]

# Systematic Mapping Study

- ▶ Systematic mapping study
  - One of the approaches advocated by Evidence-Based Software Engineering whose goal is to provide an overview of the results available within an area by categorizing them along criteria such as type, forum, frequency, etc
  
- ▶ Research questions
  - RQ1: What are the techniques that have been used for CIT in SPLs?
  - RQ2: What phases of CIT have been explored for SPLs?
  - RQ3: What are the case studies used for evaluation of the CIT approaches applied to SPLs and what is their provenance?
  - RQ4: What are the publication fora used?

# Results



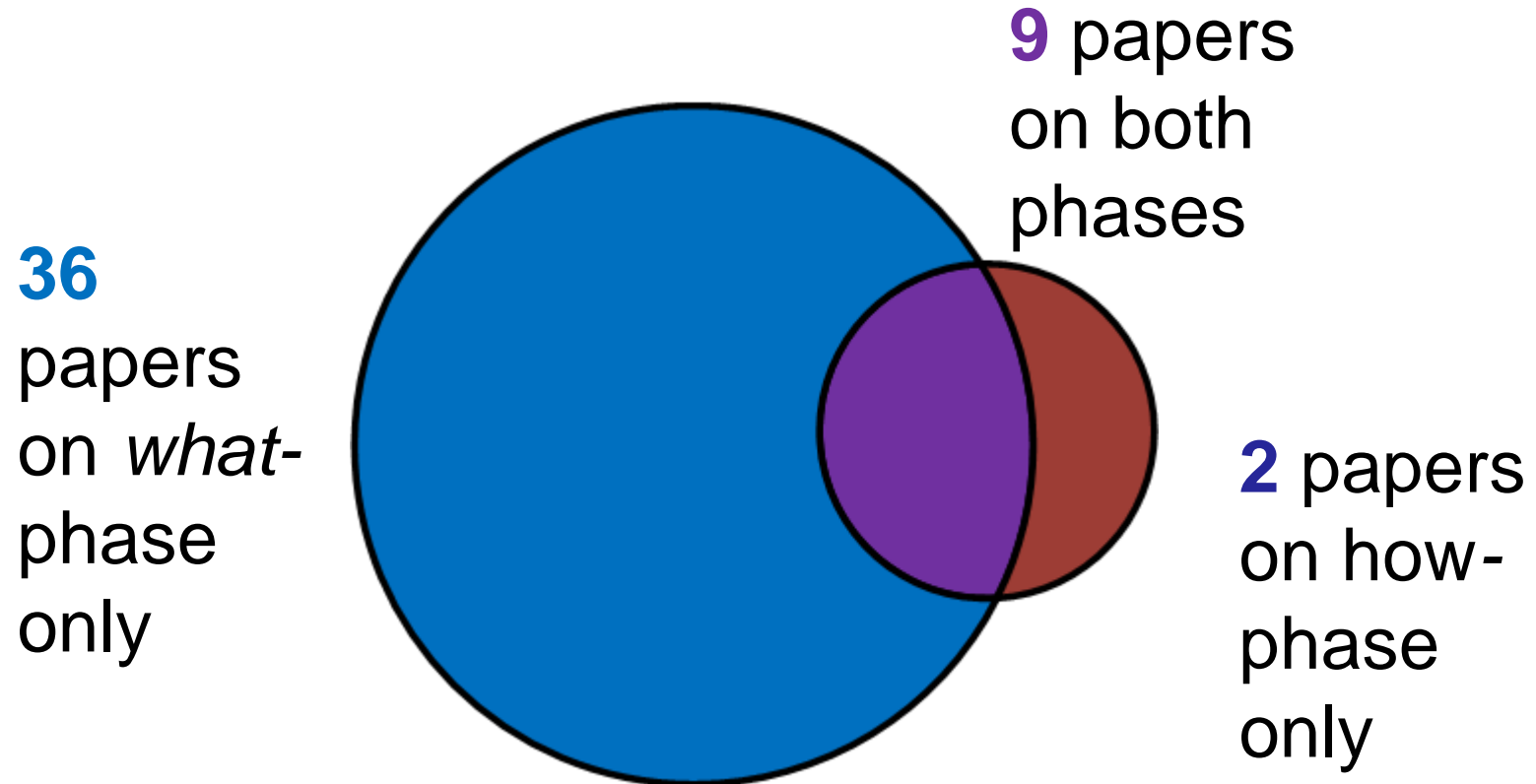


# RQ1: Techniques Used

- ▶ 13 different techniques for CIT for SPLs
- ▶ Most frequent techniques
  - 13 publications greedy algorithms
  - 8 publications constraint programming

Technique	Primary Sources Identifiers
Constraint Handling	S21
Constraint Programming	S1, S3, S13, S18, S25, S26, S30, S37
Evolutionary Algorithm (1+1)	S10, S32, S35
Exact Multi-Objective Algorithm	S19
Generic	S2, S11, S24, S27, S33, S36
Genetic Algorithm	S16, S40, S45, S47
Greedy algorithm	S4, S5, S8, S14, S15, S17, S22, S23, S28, S29, S31, S34, S38
Model-Based	S43
Multi-Objective Evolutionary Algorithm	S20, S44, S46
Random Search	S41
Simulated Annealing	S14, S23, S39, S42
Static Analysis	S7, S9, S12
Statistical Test	S6

# RQ2: CIT Phases

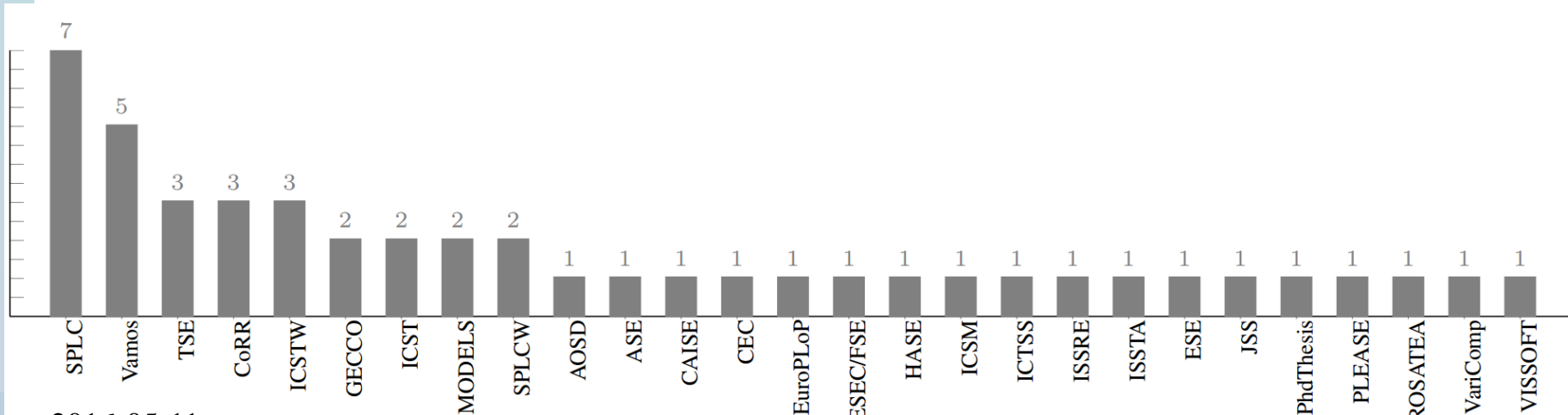


# RQ3: Case Studies and Provenance

- ▶ The Linux kernel is still a frequently used SPL case study
- ▶ The majority of case studies only consisted of variability models – no code available
- ▶ Most of the papers used feature models to model variability (39 papers)
- ▶ Most of them from the SPLOT repository (Software Product Line Online Tools – a Repository of Feature Models and Tools, etc.)

# RQ4: Publication Fora

- ▶ 24 conference, 5 journal and 18 other (i.e. workshop, PhD thesis, ...) publications
- ▶ SPLC and VaMos
  - Product Line specific conference and workshop
- ▶ ICST and ICSTW
  - Testing specific



2016-05-11

# Open Question

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- ▶ How do all these approaches compare?
- ▶ Some incipient work
  - Comparison framework applied to Alloy-Based alternative and constraint programming [Oster10]
  - Proposed by Perrouin et al. [Perrouin 12].
  - Problems
    - Limited number of feature models studied
    - Only two approaches

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