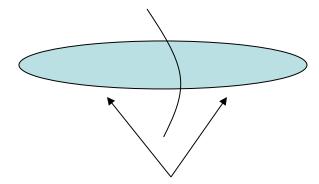
Design & Analysis of Algorithms CSE 304

Dynamic Programming

DP - Two key ingredients

 Two key ingredients for an optimization problem to be suitable for a dynamic-programming solution:

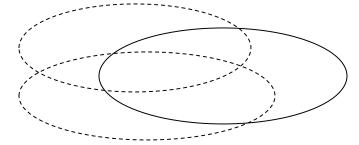
1. optimal substructures



Each substructure is optimal.

(Principle of optimality)

2. overlapping subproblems



Subproblems are dependent.

(otherwise, a divide-and-conquer approach is the choice.)

- Suppose we have a sequence or chain A₁, A₂,
 ..., A_n of n matrices to be multiplied
 - That is, we want to compute the product $A_1A_2...A_n$
- There are many possible ways (parenthesizations) to compute the product

...contd

- Example: consider the chain A₁, A₂, A₃, A₄ of 4 (i.e. *n*) matrices
 - Let us compute the product $A_1A_2A_3A_4$

$$P(n) = P(n-1) + P(2) \times P(n-2) + P(3) \times P(n-3) + P(3) \times P(n-3$$

```
\cdots + P(n-1) \times P(1)
```

- There are 5 possible ways:
 - 1. $(A_1(A_2(A_3A_4)))$
 - 2. $(A_1((A_2A_3)A_4))$
 - 3. $((A_1A_2)(A_3A_4))$
 - 4. $((A_1(A_2A_3))A_4)$
 - 5. $(((A_1A_2)A_3)A_4)$

```
def P(n):
    if n == 1 or n == 2:
        return 1
    total = 0
    for i in range(1, n):
        total += P(i) * P(n-i)
    return total
```

```
P_4 = P(4)

P_5 = P(5)

P_8 = P(8)

P_10 = P(10)

print(P_4, P_5, P_8, P_10)
```

...contd

- To compute the number of scalar multiplications necessary, we must know:
 - Algorithm to multiply two matrices
 - Matrix dimensions

Algorithm to multiply two matrices?

Algorithm to Multiply 2 Matrices

Input: Matrices $A_{p \times q}$ and $B_{q \times r}$ (with dimensions $p \times q$ and $q \times r$)

Result: Matrix $C_{p \times r}$ resulting from the product $A \cdot B$

```
MATRIX-MULTIPLY (A_{p \times q}, B_{q \times r})

1. for i \leftarrow 1 to p

2. for j \leftarrow 1 to r

3. C[i,j] \leftarrow 0

4. for k \leftarrow 1 to q

5. C[i,j] \leftarrow C[i,j] + A[i,k] \cdot B[k, j]
```

Scalar multiplication in line 5 dominates time to compute CNumber of scalar multiplications = pqr

...conto

- Example: Consider three matrices $A_{10\times100}$, $B_{100\times5}$, and $C_{5\times50}$
- There are 2 ways to parenthesize
 - $((AB)C) = D_{10\times5} \cdot C_{5\times50}$
 - AB \Rightarrow 10·100·5=5,000 scalar multiplications
 - DC \Rightarrow 10·5·50 =2,500 scalar multiplications
 - $(A(BC)) = A_{10 \times 100} \cdot E_{100 \times 50}$
 - BC \Rightarrow 100·5·50=25,000 scalar multiplications
 - AE \Rightarrow 10·100·50 =50,000 scalar multiplications

Total: 75,000 Total: 7,500



Given a chain of matrices 〈A₁, A₂, ..., A_n〉, where
 for i = 1, 2, ..., n matrix A_i has dimensions p_{i-1}x p_i,
 fully parenthesize the product A₁ · A₂ · · · · A_n in a
 way that minimizes the number of scalar
 multiplications.

$$A_1 \cdot A_2 \cdot \cdots A_i \cdot A_{i+1} \cdot \cdots A_n$$
 $p_0 \times p_1 \quad p_1 \times p_2 \quad p_{i-1} \times p_i \quad p_i \times p_{i+1} \quad p_{n-1} \times p_n$

2. A Recursive Solution

Consider the subproblem of parenthesizing

$$A_{i...j} = A_i A_{i+1} \cdot \cdot \cdot \cdot A_j$$
 for $1 \le i \le j \le n$

$$= A_i A_{i+1} \cdot \cdot \cdot \cdot A_j$$
 for $1 \le i \le j \le n$

$$= A_i A_{i+1} \cdot \cdot \cdot \cdot A_j$$
 for $1 \le i \le j \le n$

$$= A_i A_{i+1} \cdot \cdot \cdot \cdot A_j$$
 for $1 \le i \le j \le n$

Assume that the optimal parenthesization splits

the product
$$A_i$$
 A_{i+1} · · · · A_j at k (i \leq k \leq j)

$$m[i, j] = \underbrace{m[i, k]}_{m[i, j]} + \underbrace{m[k+1, j]}_{m[k+1, j]} + \underbrace{p_{i-1}p_kp_j}_{m[i, j]}$$

min # of multiplications to compute $A_{i,k}$

min # of multiplications # of multiplications to compute $A_{k+1...j}$ to compute $A_{i...k}A_{k...j}$

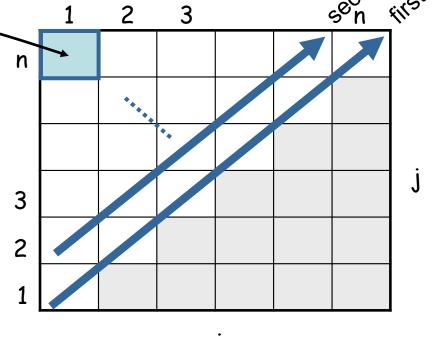
3. Computing the Optimal Costs

$$m[i, j] = \begin{cases} 0 & \text{if } i = j \\ \min \{m[i, k] + m[k+1, j] + p_{i-1}p_kp_j\} & \text{if } i < j \end{cases}$$

- Length = 1: i = j, i = 1, 2, ..., n
- Length = 2: j = i + 1, i = 1, 2, ..., n-1

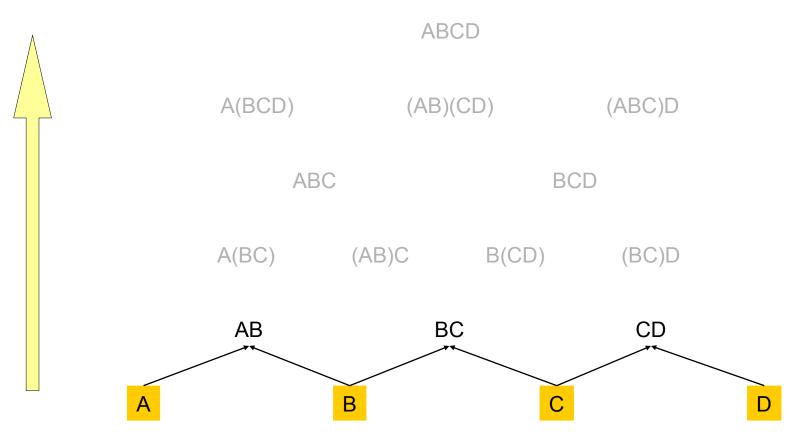
m[1, n] gives the optimal solution to the problem

Compute rows from bottom to top and from left to right In a similar matrix s we keep the optimal values of k



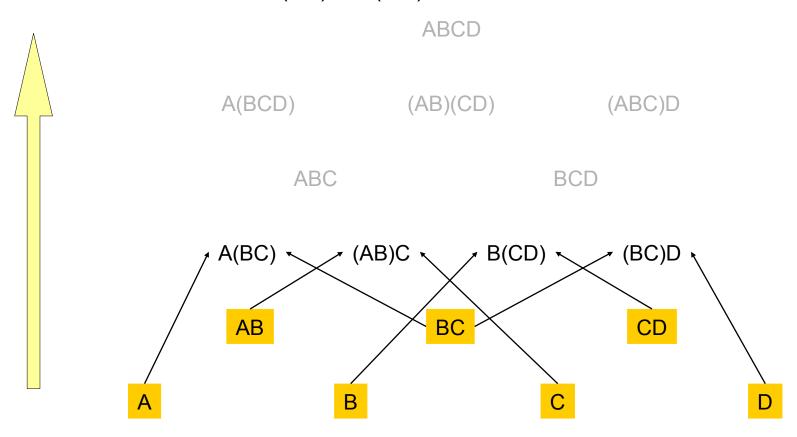
Multiply 4 Matrices: A×B×C×D (1)

- Compute the costs in the bottom-up manner
 - First we consider AB, BC, CD
 - No need to consider AC or BD



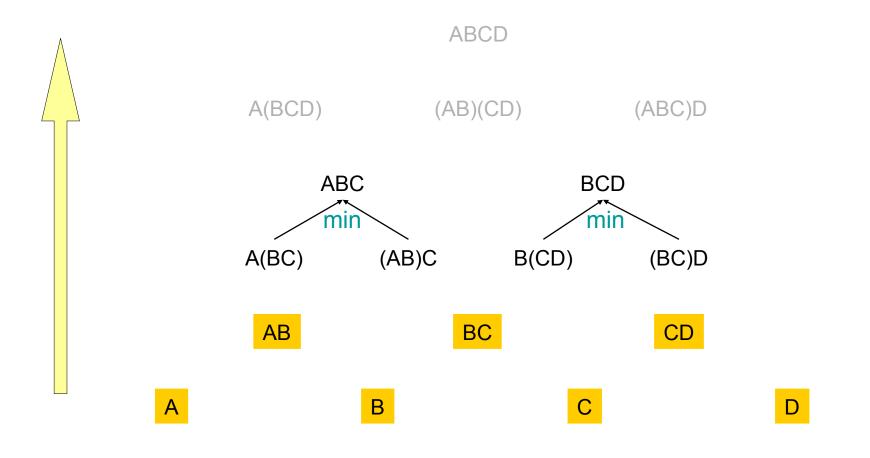
Multiply 4 Matrices: A×B×C×D (2)

- Compute the costs in the bottom-up manner
 - Then we consider A(BC), (AB)C, B(CD), (BC)D
 - No need to consider (AB)D, A(CD)



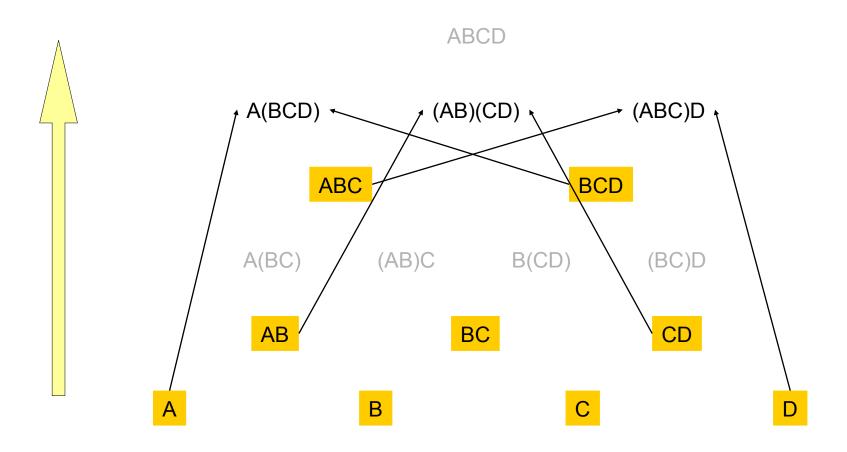
Multiply 4 Matrices: A×B×C×D (3)

- Compute the costs in the bottom-up manner
- Select minimum cost matrix calculations of ABC & BCD



Multiply 4 Matrices: A×B×C×D (4)

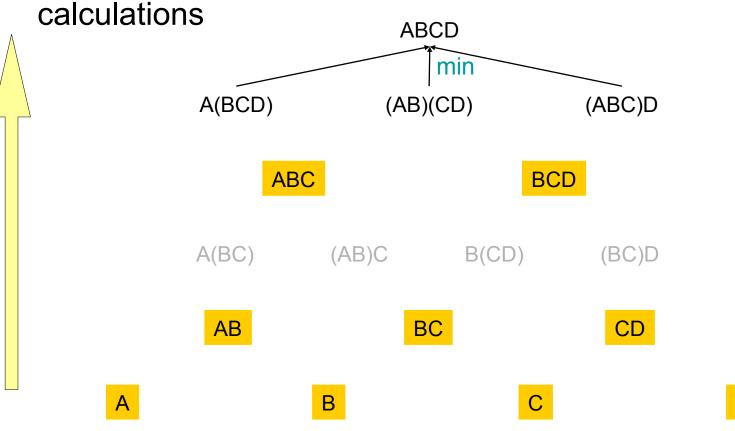
- Compute the costs in the bottom-up manner
 - We now consider A(BCD), (AB)(CD), (ABC)D



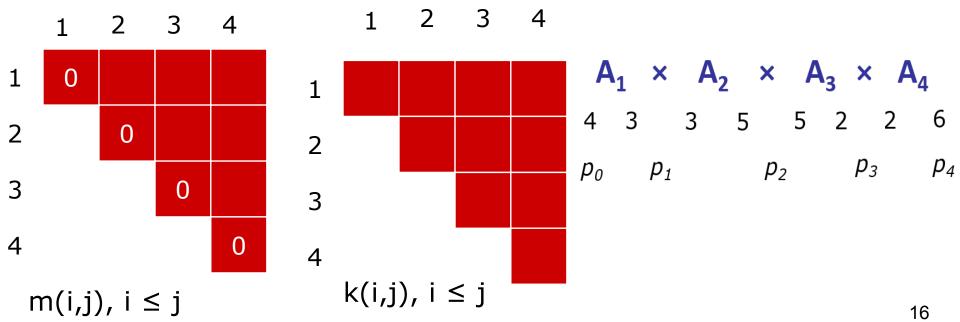
Multiply 4 Matrices: A×B×C×D (5)

Compute the costs in the bottom-up manner

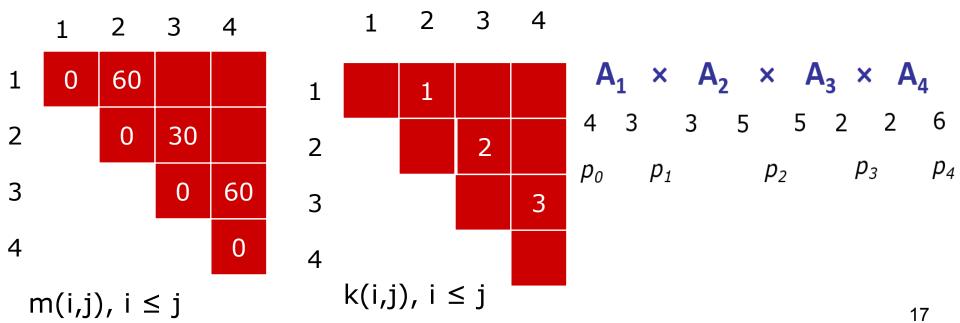
Finally choose the cheapest cost plan for matrix



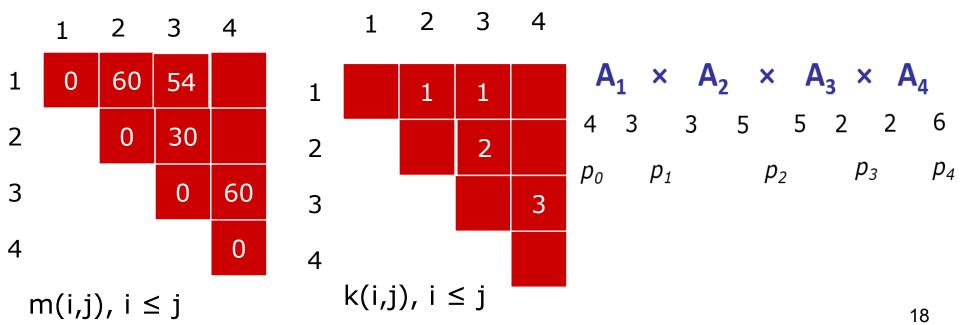
$$m[i,j] = \begin{cases} 0 & \text{if } i = j \\ \min_{i \le k < j} \{m[i,k] + m[k+1,j] + p_{i-1}p_k p_j\} & \text{if } i < j \end{cases}$$



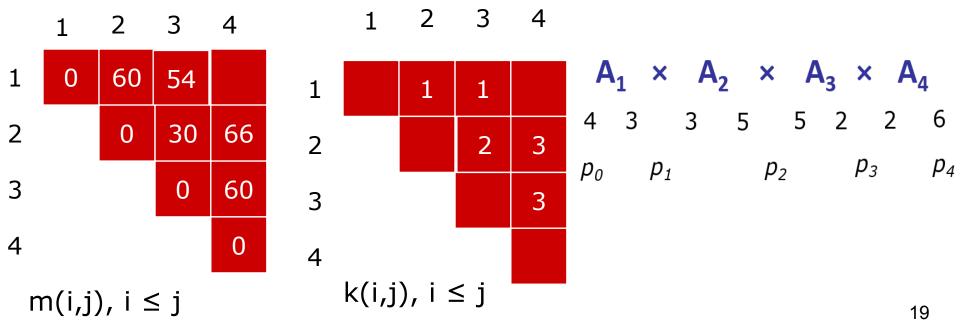
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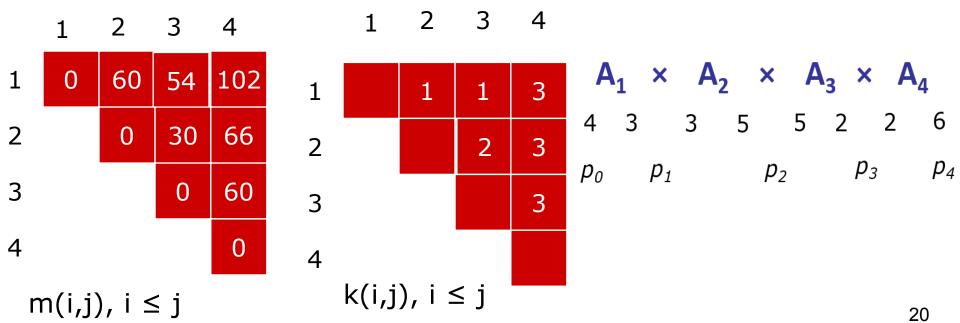
$$m[i,j] = \begin{cases} 0 & \text{if } i = j \\ \min_{i \le k < j} \{m[i,k] + m[k+1,j] + p_{i-1}p_k p_j\} & \text{if } i < j \end{cases}$$



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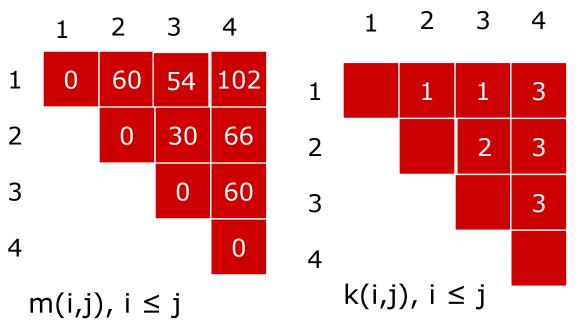


$$m[i,j] = \begin{cases} 0 & \text{if } i = j \\ \min_{i \le k < j} \{m[i,k] + m[k+1,j] + p_{i-1}p_kp_j\} & \text{if } i < j \end{cases}$$

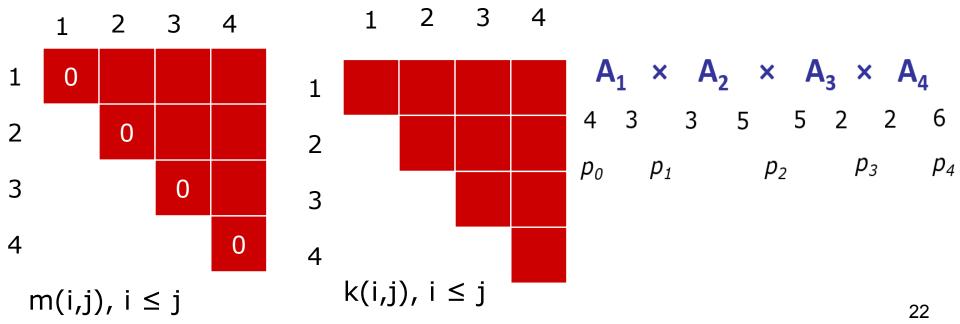
$$A_1 \times A_2 \times A_3 \times A_4 & A_1 \times A_2 \times A_3 \times A_4$$

$$4 \quad 3 \quad 3 \quad 5 \quad 5 \quad 2 \quad 2 \quad 6$$

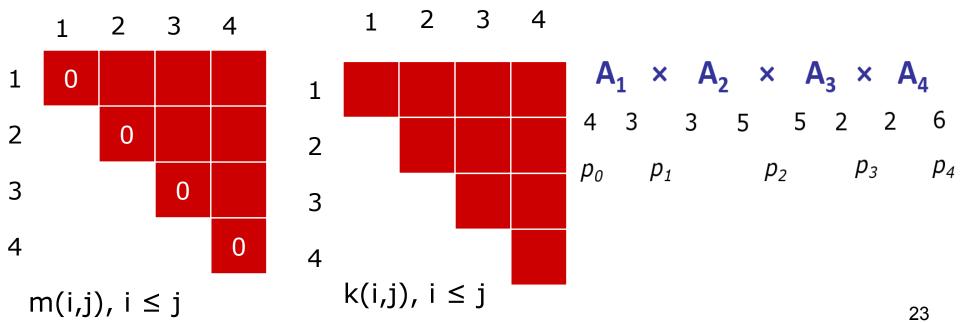
$$p_0 \quad p_1 \qquad p_2 \qquad p_3 \quad p_4 \qquad p_0 \quad p_1 \qquad p_2 \qquad p_3 \quad p_4$$



$$m[i,j] = \begin{cases} 0 & \text{if } i = j \\ \min_{i \le k < j} \{m[i,k] + m[k+1,j] + p_{i-1}p_k p_j\} & \text{if } i < j \end{cases}$$



$$m[i,j] = \begin{cases} 0 & \text{if } i = j \\ \min_{i \le k < j} \{m[i,k] + m[k+1,j] + p_{i-1}p_k p_j\} & \text{if } i < j \end{cases}$$



```
MATRIX-CHAIN-ORDER (p)
   n = p.length - 1
   let m[1...n, 1...n] and s[1...n-1, 2...n] be new tables
   for i = 1 to n
        m[i,i] = 0
    for l = 2 to n // l is the chain length
        for i = 1 to n - l + 1
 6
            j = i + l - 1
            m[i,j] = \infty
 9
            for k = i to j - 1
                q = m[i,k] + m[k+1,j] + p_{i-1}p_kp_i
10
                if q < m[i, j]
11
12
                    m[i,j]=q
                    s[i,j] = k
13
14
    return m and s
                             PRINT-OPTIMAL-PARENS (s, i, j)
                                 if i == j
                                     print "A"<sub>i</sub>
                                 else print "("
                                      PRINT-OPTIMAL-PARENS (s, i, s[i, j])
                                      PRINT-OPTIMAL-PARENS (s, s[i, j] + 1, j)
                                      print ")"
                             6
```

Memoization

- Top-down approach with the efficiency of typical dynamic programming approach
- Maintaining an entry in a table for the solution to each subproblem
 - memoize the inefficient recursive algorithm
- When a subproblem is first encountered its solution is computed and stored in that table
- Subsequent "calls" to the subproblem simply look up that value

Memoized Matrix-Chain

Alg.: MEMOIZED-MATRIX-CHAIN(p)

- 1. $n \leftarrow length[p] 1$
- 2. for $i \leftarrow 1$ to n
- 3. do for $j \leftarrow i$ to n
- 4. do m[i, j] $\leftarrow \infty$

Initialize the m table with large values that indicate whether the values of m[i, j] have been computed

5. return LOOKUP-CHAIN(p, 1, n) ← Top-down approach

Memoized Matrix-Chain

```
Alg.: LOOKUP-CHAIN(p, i, j)
                                                          Running time is O(n^3)
     if m[i, j] < \infty
2.
               then return m[i, j]
3.
     if i = j
        then m[i, j] \leftarrow 0
                                          m[i, j] = min \{m[i, k] + m[k+1, j] + p_{i-1}p_kp_i\}
        else for k \leftarrow i to j - 1
                                                   i≤k<j
5.
                          do q \leftarrow LOOKUP-CHAIN(p, i, k) +
6.
                                  LOOKUP-CHAIN(p, k+1, j) + p<sub>i</sub>
     _{1}p_{k}p_{j}
                               if q < m[i, j]
8.
                                  then m[i, j] \leftarrow q
                                                                                27
```

Dynamic Progamming vs. Memoization

- Advantages of dynamic programming vs. memoized algorithms
 - No overhead for recursion, less overhead for maintaining the table
 - The regular pattern of table accesses may be used to reduce time or space requirements
- Advantages of memoized algorithms vs. dynamic programming
 - Some subproblems do not need to be solved