ResNet-Grad-Cam

May 27, 2020

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[1]: import torch
     from torchvision import datasets, transforms as T
     from torch.utils.data import DataLoader, TensorDataset
     from torch import nn
     import torchvision.models as models
     from matplotlib import pyplot
     import numpy as np
     import json
     import cv2 as cv
     import torch.nn.functional as F
     normalize = T.Normalize(mean=[0.485, 0.456, 0.406],
                             std=[0.229, 0.224, 0.225])
     #load ImageNet validation data
     transform = T.Compose([T.Resize((224, 224)),
                            T.ToTensor()
                            #normalize
                           ])
     #input image
     input_image = datasets.ImageFolder(root='/home/jason/Documents/Uni/
      →multimedia_project/multimedia_project/data/',
                                    transform=transform)
     #y labels
     filepath = 'ILSVRC2015_clsloc_validation_ground_truth.txt'
     def get_valid_label(filepath):
         label_list = []
         with open(filepath, 'r') as f:
             ctx = f.readlines()
             for tmp in ctx:
                 label_list.append(int(tmp.rstrip('\n')))
         return label_list
     y = get_valid_label(filepath)
```

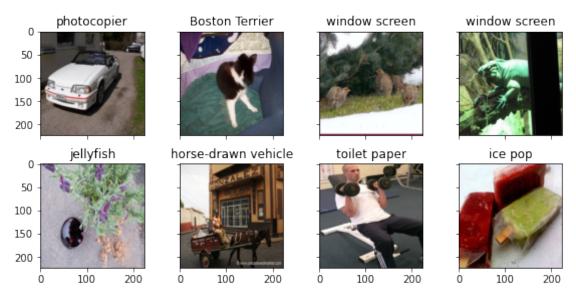
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testloader = DataLoader(input_image, batch_size=1, shuffle=True, num_workers=2)
#load imagenet label
with open('labels.json') as f:
    label = json.load(f)
    f.close()
```

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[2]: #image plot help function
     def plot_multiple(images, titles, colormap='gray', max_columns=np.inf,_
     ⇒share_axes=True):
         """Plot multiple images as subplots on a grid."""
         assert len(images) == len(titles)
         n_images = len(images)
         n_cols = min(max_columns, n_images)
         n_rows = int(np.ceil(n_images / n_cols))
         fig, axes = pyplot.subplots(
             n_rows, n_cols, figsize=(n_cols * 2, n_rows * 2),
             squeeze=False, sharex=share_axes, sharey=share_axes)
         axes = axes.flat
         # Hide subplots without content
         for ax in axes[n_images:]:
             ax.axis('off')
         if not isinstance(colormap, (list,tuple)):
             colormaps = [colormap]*n_images
         else:
             colormaps = colormap
         for ax, image, title, cmap in zip(axes, images, titles, colormaps):
             ax.imshow(image, cmap=cmap)
             ax.set_title(title)
         fig.tight_layout()
```

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[3]: #import pre trained model
    model = models.resnet18(pretrained=True)
    #set the model to evaluate mode
    model.eval()

def predict_image(num=8, coloum = 4):
    titles = []
    images = []
    for _ in range(num):
        image = iter(testloader).next()
        x = model(image[0])
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result = torch.argmax(x)
    npimg = np.array(image[0]).squeeze()
    images.append(np.transpose(npimg, (1, 2, 0)))
    titles.append(label[result])
    plot_multiple(images, titles, max_columns=4)
predict_image()
```



```
[4]: def generate_random_image():
    image = iter(testloader).next()
    return image[0]

def saliency_detection_function(image):
    saliency = cv.saliency.StaticSaliencySpectralResidual_create()
    (success, saliencyMap) = saliency.computeSaliency(image)
    saliencyMap = (saliencyMap * 255).astype("uint8")
    return saliencyMap
```

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[5]: # output original image list and heatmap image list
def generate_heat_map_image(model, saliency=True):
    #get the gradient value by using hook
    gradList = []
    featureList = []

#using grad hook and feature hook to get gradient and feature map
def gradhook(module, grad_input, grad_output):
    gradList.append(grad_output[0])

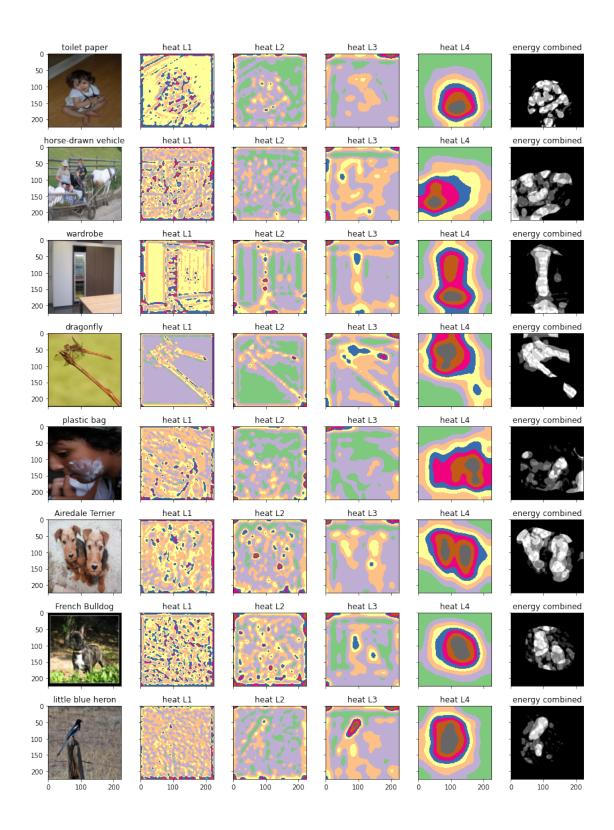
def featurehook(module, i, o):
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featureList.append(o[0])
#connect hook function to each layers
for layerIdx in range(1, 5):
    #link the hook back the model to the specific layer
    getattr(model, "layer"+str(layerIdx)).register_backward_hook(gradhook)
    getattr(model, "layer"+str(layerIdx)).register_forward_hook(featurehook)
#get a random image
image = generate_random_image()
out = model(image)
result = torch.argmax(out)
title = label[result]
loss = torch.sum(F.log_softmax(out, -1), -1)
mean_loss = loss.mean()
#generate the gradient via back propagation
mean_loss.backward()
#covert to numpy image
npimg = np.array(image).squeeze()
originimg = np.transpose(npimg, (1, 2, 0))
heatmapList = []
#calculate the weight of global average pooling of the gradient
for layerIdx in range(1, 5):
    a = gradList[layerIdx-1].squeeze()
   a = torch.nn.functional.max_pool2d(a, a.shape[1]) # weight
    #normalize weight and apply relu as activation map
   weight = a / torch.sum(a)
   weight = torch.nn.functional.relu(weight)
   weight = weight.detach().numpy().squeeze()
    feature = featureList[layerIdx-1].detach().numpy()
    #generate the heatmap
   heatmap = np.zeros_like(feature[0])
   for coef, tmp in zip(weight, feature):
        heatmap += tmp*coef
   heatmap = heatmap * 255
    heatmap = cv.resize(heatmap, (224, 224), interpolation=cv.INTER_CUBIC)
    #bin equalization to adjust the contrast ratio
   lowerbound = heatmap.min()
   higherbound = heatmap.max()
    totalRange = higherbound - lowerbound
   heatmap = (heatmap - lowerbound) / totalRange * 255
```

```
#covert the color map
heatmap = heatmap.astype(np.uint8)
#implemented saliency map
if saliency:
    heatmap = saliency_detection_function(heatmap)
heatmapList.append(heatmap)

return originimg, heatmapList, title
```

```
[8]: def ostu_energy_function(imgList):
        tmpList = []
        for tmpIg in imgList:
           blur = cv.GaussianBlur(tmpIg,(5,5),0)
            _,heatmap = cv.threshold(blur,0,255,cv.THRESH_BINARY+cv.THRESH_OTSU)
            tmpList.append(heatmap)
        dilatation size = 4
        element = cv.getStructuringElement(cv.MORPH ELLIPSE, (2*dilatation size +11
     →1, 2*dilatation_size+1), (dilatation_size, dilatation_size))
        tmpList[1] = cv.dilate(tmpList[1], element)
        tmpList[2] = cv.dilate(tmpList[2], element)
        imageholder = np.zeros_like(tmpList[0])
        →tmpList[2] * tmpList[-1]*3
        imageholder = (imageholder - imageholder.min())/imageholder.max()
        return imageholder
    def plot_result(num=6):
        imglist = []
        titlelist = []
        cmaplist = []
        outputtitle = []
        for idx in range(8):
            img, heatmapList, title = generate_heat_map_image(model, False)
            combined = ostu_energy_function(heatmapList)
            imglist = imglist + [img] + heatmapList + [combined]
           titlelist = titlelist + [title, 'heat L1', 'heat L2', 'heat L3', 'heat_
     cmaplist.append('gray')
            cmaplist += ['Accent'] * 4
           cmaplist += ['gray']
           pyplot.imsave('./{}-{}'.format(idx, 'origin.jpg'), img)
            for nameIdx in range(1, 5):
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[7]: def plot_merge_heatmap(titlelist):
 outputlist = []

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imglist = []
for idx in range(8):
    #define path
   oripath = './{}-{}'.format(idx, 'origin.jpg')
   heatpath = './{}-{}'.format(idx, 'heat3.jpg')
    #get original image
    ori = cv.imread(oripath, cv.IMREAD_COLOR)
    tmp_ori = cv.cvtColor(ori, cv.COLOR_RGB2BGR)
    imglist.append(tmp_ori)
    outputlist.append('{}'.format(titlelist[idx]))
    #get combined image
   heat = cv.imread(heatpath, cv.IMREAD_COLOR)
   heat_tmp = cv.cvtColor(heat, cv.COLOR_RGB2BGR)
    imglist.append(heat_tmp)
    outputlist.append('{}'.format('heatmap'))
    cv.addWeighted(ori, 0.5, heat, 0.5, 0, heat)
    combinedpath = './{}-{}'.format(idx, 'combined.jpg')
    cv.imwrite(combinedpath, heat)
    tmp = cv.cvtColor(heat, cv.COLOR_BGR2RGB)
    imglist.append(tmp)
    outputlist.append('{}'.format('combine'))
plot_multiple(imglist, outputlist, max_columns= 3)
```