

**Full system  
simulation in  
gem5**



# Intro to Syscall Emulation Mode

# What is Syscall Emulation mode, and when to use/avoid it

**Syscall Emulation (SE)** mode does not model all the devices in a system. It focuses on simulating the CPU and memory system. It only emulates Linux system calls, and only models user-mode code.

SE mode is a good choice when the experiment does not need to model the OS (such as page table walks), does not need a high fidelity model (emulation is ok), and faster simulation speed is needed.

However, if the experiment needs to model the OS interaction, or needs to model a system in high fidelity, then we should use the full-system (FS) mode. The FS mode will be covered in [07-full-system](#).

# Example

## 00-SE-hello-world

Under `materials/04-Advanced-using-gem5/03-running-in-gem5/00-SE-hello-world`, there is a small example of an SE simulation.

[00-SE-hello-world.py](#) will run the [00-SE-hello-world](#) binary with a simple X86 configuration.

This binary prints the string `Hello, World!`.

If we use the debug flag `SyscallAll` with it, we will be able to see what syscalls are simulated.

We can do it with the following command:

```
gem5 -re --debug-flags=SyscallAll 00-SE-hello-world.py
```

`-re` is an alias for `--stdout-file` and `--stderr-file` to redirect the output to a file.

The default output is in `m5out/simout.txt` and `m5out/simerr.txt`.

## 00-SE-hello-world

Then in [simout.txt](#), we should see:

```
280945000: board.processor.cores.core: T0 : syscall Calling write(1, 21152, 14)...  
Hello, World!  
280945000: board.processor.cores.core: T0 : syscall Returned 14.
```

On the left is the timestamp for the simulation.

As the timestamp suggests, **SE simulation DOES NOT record the time for the syscall.**

Note that in the `simout.txt` file the standard out from the *simulator* and the *guest* are mixed together.

# Full system mode



# What is Full System Simulation?

gem5's **Full System (FS) mode** simulates an entire computer system. This is in contrast to SE mode which uses the host OS.

This is in contrast to SE mode which uses the host OS, thus side-stepping the need to simulate the entire system; a costly process.

# Basics of Booting Up a Real System in gem5

Unlike in SE mode where we can just provide a binary, in FS mode we need to provide much more information to boot up a real system. In particular we need:

1. A disk image containing the operating system and any necessary software or data. This disk image serves as the virtual hard drive for the simulated system.
2. A kernel binary compatible with the simulated architecture is needed to boot the operating system.

Beyond these essentials, you might need to provide other files like a bootloader, depending on the complexity of the simulation.



# How does gem5 know it's in FS mode or SE mode?

In `simulator.py` the root object is created, in which the `full_system` parameter is set to `True` or `False` depending on whether the full system is being simulated.

```
root = Root(
    full_system=(
        self._full_system
        if self._full_system is not None
        else self._board.is_fullsystem()
    ),
    board=self._board,
)
```

In `abstract_board.py`:

```
def is_fullsystem(self) -> bool:
    # ...
    if self._is_fs == None:
        raise Exception(
            "The workload for this board not ..."
        )
    return self._is_fs
```

# Ultimately determined by what `set_workload` function is called

In `kernel_disk_workload.py`:

```
class KernelDiskWorkload:

    # ...

    def set_kernel_disk_workload(
        self,
        kernel: KernelResource,
        disk_image: DiskImageResource,
        bootloader: Optional[BootloaderResource] = None,
        disk_device: Optional[str] = None,
        readfile: Optional[str] = None,
        readfile_contents: Optional[str] = None,
        kernel_args: Optional[List[str]] = None,
        exit_on_work_items: bool = True,
        checkpoint: Optional[Union[Path, CheckpointResource]] = None,
    ) -> None:

        # ...

        self._set_fullsystem(True)
```

## These `set_workload` classes mixin with the boards

```
class X86Board(AbstractSystemBoard, KernelDiskWorkload):  
    #...
```

So, in short, **the `set_workload` function called determines whether the simulation is in FS mode or SE mode.**

# Creating your own disk images

# Creating disk images using Packer and QEMU

To create a generic Ubuntu disk image that we can use in gem5, we will use:

- Packer: This will automate the disk image creation process.
- QEMU: We will use a QEMU plugin in Packer to actually create the disk image.
- Ubuntu autoinstall: We will use autoinstall to automate the Ubuntu install process.

gem5 resources already has code that can create a generic Ubuntu image using the aforementioned method.

- Path to code: `gem5-resources/src/x86-ubuntu`

Let's go through the important parts of the creation process.



# Getting the ISO and the user-data file

As we are using Ubuntu autoinstall, we need a live server install ISO.

- This can be found online from the Ubuntu website: [iso](#)

We also need the user-data file that will tell Ubuntu autoinstall how to install Ubuntu.

- The user-data file on gem5-resources specifies all default options with a minimal server installation.

# How to get our own user-data file

To get a user-data file from scratch, you need to install Ubuntu on a machine.

- Post-installation, we can retrieve the `autoinstall-user-data` from `/var/log/installer/autoinstall-user-data` after the system's first reboot.

You can install Ubuntu on your own VM and get the user-data file.

# Using QEMU to get the user-data file

We can also use QEMU to install Ubuntu and get the aforementioned file.

- First, we need to create an empty disk image in QEMU with the command: `qemu-img create -f raw ubuntu-22.04.2.raw 5G`
- Then we use QEMU to boot the diskimage:

```
qemu-system-x86_64 -m 2G \  
    -cdrom ubuntu-22.04.2-live-server-amd64.iso \  
    -boot d -drive file=ubuntu-22.04.2.raw,format=raw \  
    -enable-kvm -cpu host -smp 2 -net nic \  
    -net user,hostfwd=tcp::2222-:22
```

After installing Ubuntu, we can use ssh to get the user-data file.



# Important parts of the Packer script

Let's go over the Packer file.

- **bootcommand:**

```
"e<wait>",  
"<down><down><down>",  
"<end><bs><bs><bs><bs><wait>",  
"autoinstall ds=nocloud-net\\;s=http://{{ .HTTPIP }}:{{ .HTTPPort }}/ ---<wait>",  
"<f10><wait>"
```

This boot command opens the GRUB menu to edit the boot command, then removes the `---` and adds the autoinstall command.

- **http\_directory:** This directory points to the directory with the user-data file and an empty file named meta-data. These files are used to install Ubuntu.

## Important parts of the Packer script (Conti.)

- **qemu\_args:** We need to provide Packer with the QEMU arguments we will be using to boot the image.
  - For example, the QEMU command that the Packer script will use will be:

```
qemu-system-x86_64 -vnc 127.0.0.1:32 -m 8192M \  
-device virtio-net,netdev=user.0 -cpu host \  
-display none -boot c -smp 4 \  
-drive file=<Path/to/image>,cache=writeback,discard=ignore,format=raw \  
-machine type=pc,accel=kvm -netdev user,id=user.0,hostfwd=tcp::3873-:22
```

- **File provisioners:** These commands allow us to move files from the host machine to the QEMU image.
- **Shell provisioner:** This allows us to run bash scripts that can run the post installation commands.



# Let's use the base Ubuntu image to create a disk image with the GAPBS benchmarks

Update the [x86-ubuntu.pkr.hcl](#) file.

The general structure of the Packer file would be the same but with a few key changes:

- We will now add an argument in the `source "qemu" "initialize"` block.
  - `diskimage = true` : This will let Packer know that we are using a base disk image and not an iso from which we will install Ubuntu.
- Remove the `http_directory = "http"` directory as we no longer need to use autoinstall.
- Change the `iso_checksum` and `iso_urls` to that of our base image.

Let's get the base Ubuntu 24.04 image from gem5 resources and unzip it.

```
wget https://storage.googleapis.com/dist.gem5.org/dist/develop/images/x86/ubuntu-24-04/x86-ubuntu-24-04.gz  
gzip -d x86-ubuntu-24-04.gz
```

`iso_checksum` is the `sha256sum` of the iso file that we are using. To get the `sha256sum` run the following in the linux terminal.

```
sha256sum ./x86-ubuntu-24-04.gz
```

- **Update the file and shell provisioners:** Let's remove the file provisioners as we don't need to transfer the files again.
- **Boot command:** As we are not installing Ubuntu, we can write the commands to login along with any other commands we need (e.g. setting up network or ssh). Let's update the boot command to login and enable network:

```
"<wait30>",  
"gem5<enter><wait>",  
"12345<enter><wait>",  
"sudo mv /etc/netplan/50-cloud-init.yaml.bak /etc/netplan/50-cloud-init.yaml<enter><wait>",  
"12345<enter><wait>",  
"sudo netplan apply<enter><wait>",  
"<wait>"
```

# Changes to the post installation script

For this post installation script we need to get the dependencies and build the GAPBS benchmarks.

Add this to the [post-installation.sh](#) script

```
git clone https://github.com/sbeamer/gapbs
cd gapbs
make
```

Let's run the Packer script and use this disk image in gem5!

```
cd /workspaces/2024/materials/04-Advanced-using-gem5/07-full-system
x86-ubuntu-gapbs/build.sh
```

## Let's use our built disk image in gem5

Let's add the md5sum and the path to our [local JSON](#).

Let's run the [gem5 GAPBS config](#).

```
GEM5_RESOURCE_JSON_APPEND=./completed/local-gapbs-resource.json gem5 x86-fs-gapbs-kvm-run.py
```

This script should run the bfs benchmark.

