



# Real-world Anomaly Detection in Surveillance Videos

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# Section 1: Introduction to Anomaly Detection<sup>1</sup>

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<sup>1</sup>R. Chalapathy and S. Chawla, “Deep learning for anomaly detection: A survey,” *arXiv preprint arXiv:1901.03407*, 2019.

## Anomaly Detection and Novelty Detection

**Anomaly Detection:** Determining instances stand out as being dissimilar to all others.

**Novelty Detection:** Identification of a novel or unobserved patterns in the data [1].

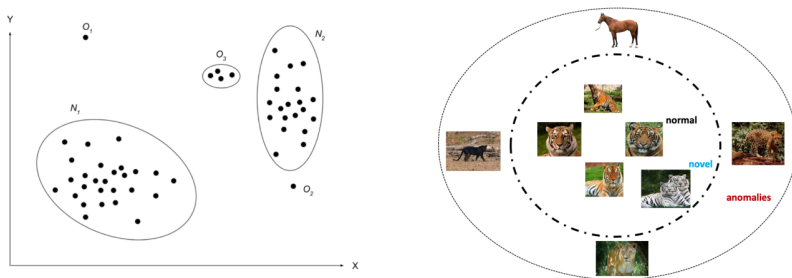
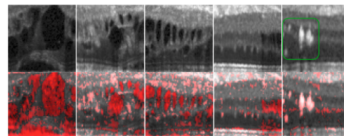


图 1: Illustration of anomaly detection and novelty detection

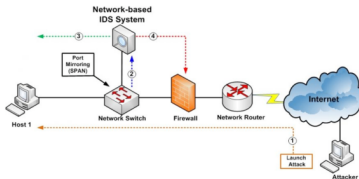
# Applications of Anomaly Detection



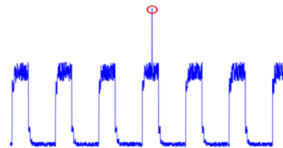
(a) Illegal Traffic Flow detection



(b) Detecting Retinal Damage



(c) Cyber-Network Intrusion detection



(d) Internet Of Things (IoT) Big-Data Anomaly detection

图 2: Applications of anomaly detection technique

# Classification of Models

## 1 Unsupervised

One-class NN/SVM  
Auto-encoder  
Generative Network

## 2 Semi-supervised

Reinforcement Learning

## 3 Weakly-supervised

Multi-instance learning

## 4 Hybrid

Extractor + classifier

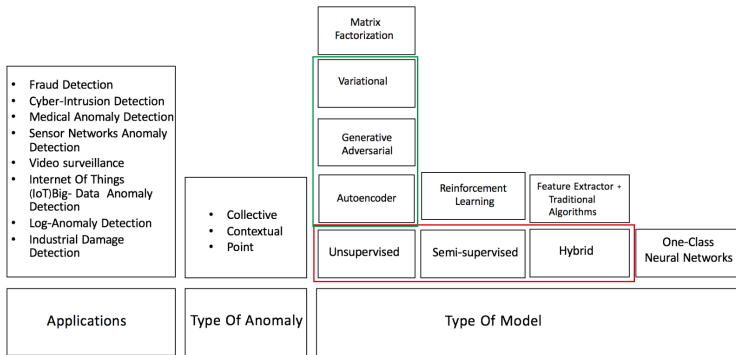


图 3: Key components in DL-based AD models



## Section 2: Real-world Anomaly Detection in Surveillance Videos<sup>2</sup>

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<sup>2</sup>W. Sultani, C. Chen, and M. Shah, "Real-world anomaly detection in surveillance videos," in *Proceedings of the IEEE Conference on Computer Vision and Pattern Recognition*, 2018, pp. 6479–6488.

# Introduction

Assumption of other approaches: *Any pattern that deviates from the learned normal patterns would be considered as an anomaly [2].*

- Difficult to define a normal event.
- Ambiguous boundary.
- Behaviour nature changed with condition.

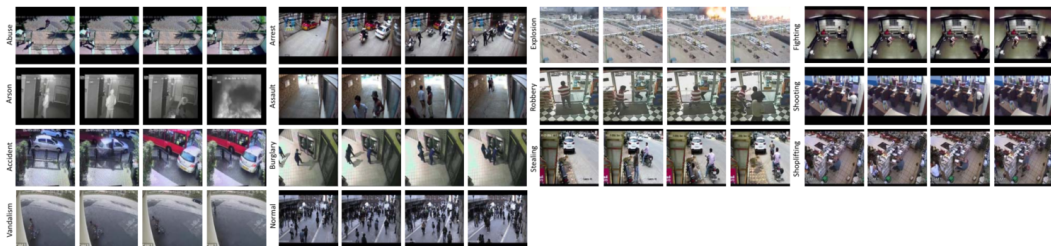


图 4: Examples of different anomalies in real-world



**Video-level labels:** A video is normal or contains anomaly somewhere, but do not know where.

**Clip-level labels:** Uneasy to acquire.

*Considering normal and anomalous videos as bags and video segments as instances.*

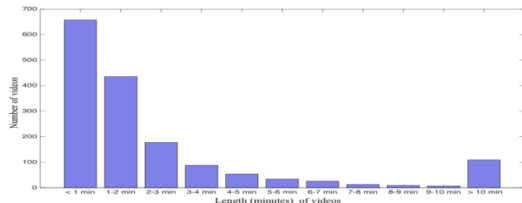


图 6: Distribution of videos length

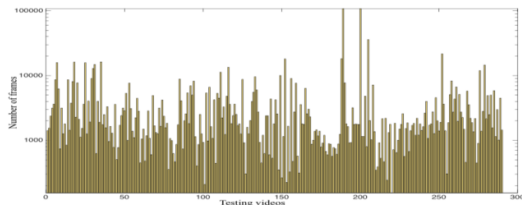


图 5: Distribution of video frames

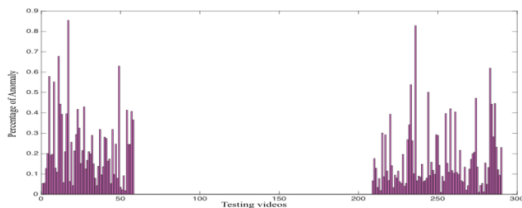


图 7: Percentage of anomaly in each video



# Multiple Instance Learning

## Optimization function of SVM:

$$\min_{\mathbf{w}} \frac{1}{k} \sum_{i=1}^k \overbrace{\max(0, 1 - y_i(\mathbf{w} \cdot \phi(x) - b))}^1 + \frac{1}{2} \|\mathbf{w}\|^2 \quad (1)$$

where  $\phi x$  denotes feature representation of an image patch or a video segment,  $\mathbf{w}$  is the classifier to be learned.

## Multiple Instance Learning:

Positive bag  $\mathcal{B}_a$ : a video with anomalies containing temporal segments (instances)  $(p^1, p^2, \dots, p^m)$ .

Negative bag  $\mathcal{B}_n$ : a video without anomalies,  $(n^1, n^2, \dots, n^m)$ .

$$\min_{\mathbf{w}} \frac{1}{z} \sum_{j=1}^z \max \left( 0, 1 - Y_{\mathcal{B}_j} \left( \max_{i \in \mathcal{B}_j} (\mathbf{w} \cdot \phi(x_i)) - b \right) \right) + \frac{1}{2} \|\mathbf{w}\|^2 \quad (2)$$



# Deep MIL Ranking Model

Encouraging high scores for anomalous video segments as compared to normal segments:

$$f(\mathcal{V}_a) > f(\mathcal{V}_n) \quad (3)$$

where  $\mathcal{V}_a$ ,  $\mathcal{V}_b$  represent anomalous and normal video segments,  $f(\mathcal{V}_a)$ ,  $f(\mathcal{V}_n)$  represent the corresponding predicted anomaly scores ranging from 0 to 1.

**Multiple instance ranking objective function:**

$$\max_{i \in \mathcal{B}_a} f(\mathcal{V}_a^i) > \max_{i \in \mathcal{B}_n} f(\mathcal{V}_n^i) \quad (4)$$

**Ranking loss:**

$$l(\mathcal{B}_a, \mathcal{B}_n) = \max \left( 0, 1 - \max_{i \in \mathcal{B}_a} f(\mathcal{V}_a^i) + \max_{i \in \mathcal{B}_n} f(\mathcal{V}_n^i) \right) \quad (5)$$



# Deep MIL Ranking Mode

**Loss function with parsity and smoothness constraints:**

$$l(\mathcal{B}_a, \mathcal{B}_n) = \max \left( 0, 1 - \max_{i \in \mathcal{B}_a} f(\mathcal{V}_a^i) + \max_{i \in \mathcal{B}_n} f(\mathcal{V}_n^i) \right) + \lambda_1 \sum_1^{n-1} (f(\mathcal{V}_a^i) - f(\mathcal{V}_a^{i+1}))^2 + \lambda_2 \sum_i^n f(\mathcal{V}_a^i) \quad (6)$$

**Final loss function:**

$$\mathcal{L}(\mathcal{W}) = l(\mathcal{B}_a, \mathcal{B}_n) + \lambda_3 \|\mathcal{W}\|_F \quad (7)$$

- In real-world scenarios, anomaly often occurs only for a short time. only a few segments may contain the anomaly.
- Since the video is a sequence of segments, the anomaly score should vary smoothly between video segments.

# Model Framework

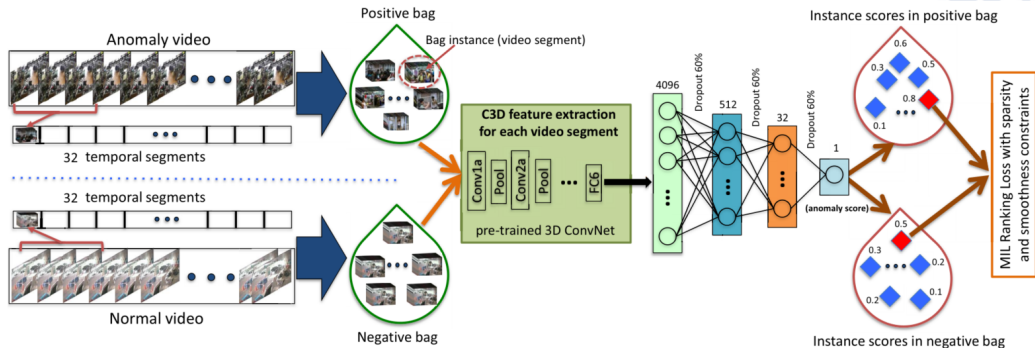


图 8: Flow diagram of the proposed anomaly detection approach

# Model Framework

- ① re-size each video frame to  $240 \times 320$  pixels and fix the frame rate to 30 fps.
- ② compute C3D features for every 16-frame video clip followed by  $L_2$  normalization.
- ③ take the average of all 16-frame clip features as features of a segment.
- ④ input these features (4096D) to a 3-layer FC neural network.
  - 4096 units, 60% dropout, relu
  - 512 units, 60% dropout, relu
  - 32 units, 60% dropout, sigmoid

Using adagrad optimizer with learning rate  $\alpha = 0.001$ , set  $\lambda_1 = \lambda_2 = 8 \times 10^{-5}$ ,  $\lambda_3 = 0.01$ .

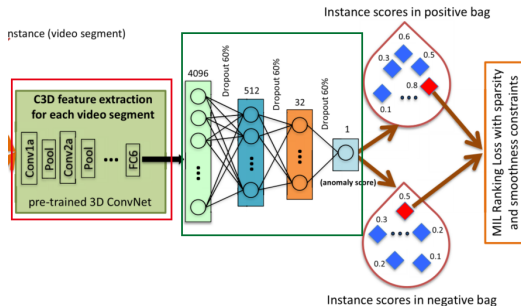


图 9: Deep MIL ranking model

# Results

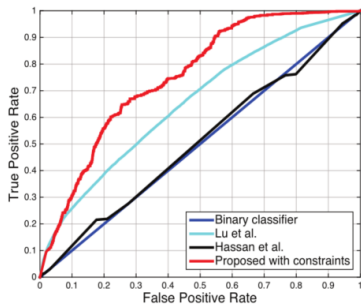


图 10: ROC comparison

Method	AUC
Binary classifier	50.0
Hasan <i>et al.</i> [18]	50.6
Lu <i>et al.</i> [28]	65.51
Proposed w/o constraints	74.44
<b>Proposed w constraints</b>	<b>75.41</b>

图 11: AUC comparison

# Results

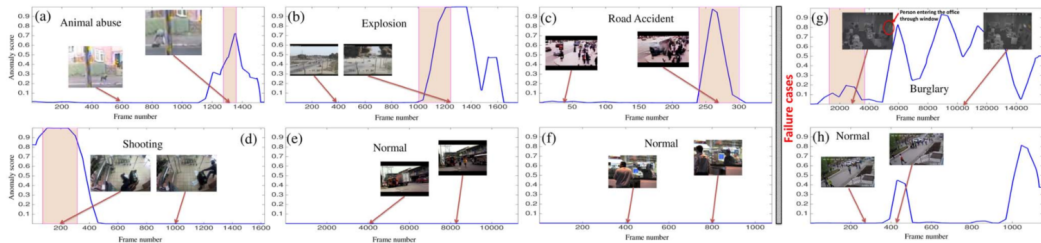


图 12: Qualitative results on testing videos

- (a), (b), (c) and (d) show videos containing animal abuse (beating a dog), explosion, road accident and shooting, respectively.
- (e) and (f) show normal videos with no anomaly.
- (g) and (h) present two failure cases of our anomaly detection method.





# References

- [1] R. Chalapathy and S. Chawla, “Deep learning for anomaly detection: A survey,” *arXiv preprint arXiv:1901.03407*, 2019.
- [2] W. Sultani, C. Chen, and M. Shah, “Real-world anomaly detection in surveillance videos,” in *Proceedings of the IEEE Conference on Computer Vision and Pattern Recognition*, 2018, pp. 6479–6488.



Thank you for listening  
Please feel free to ask questions

