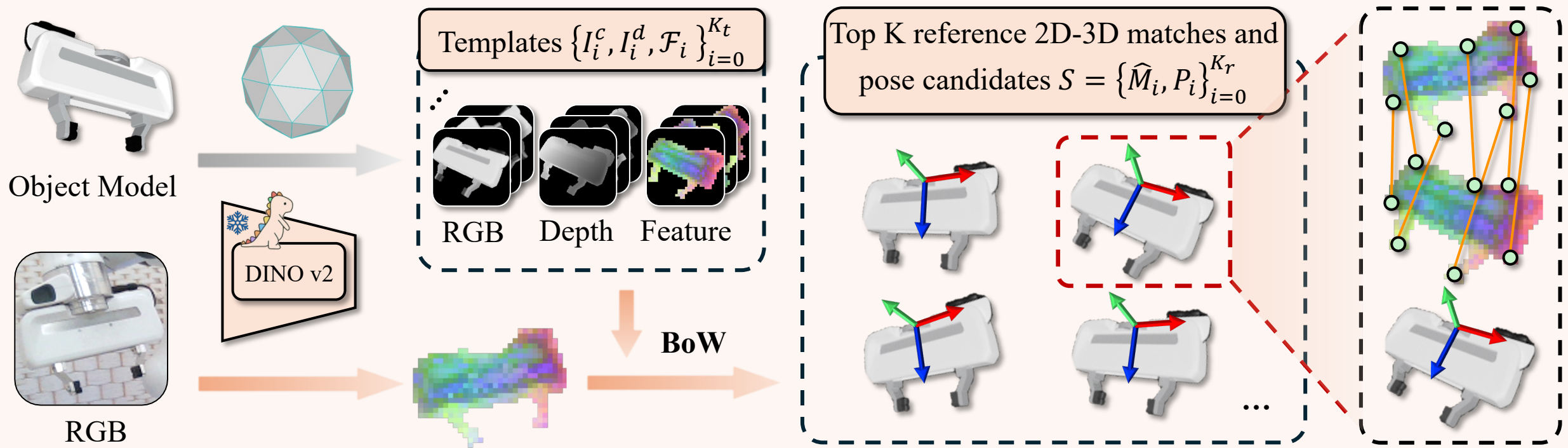
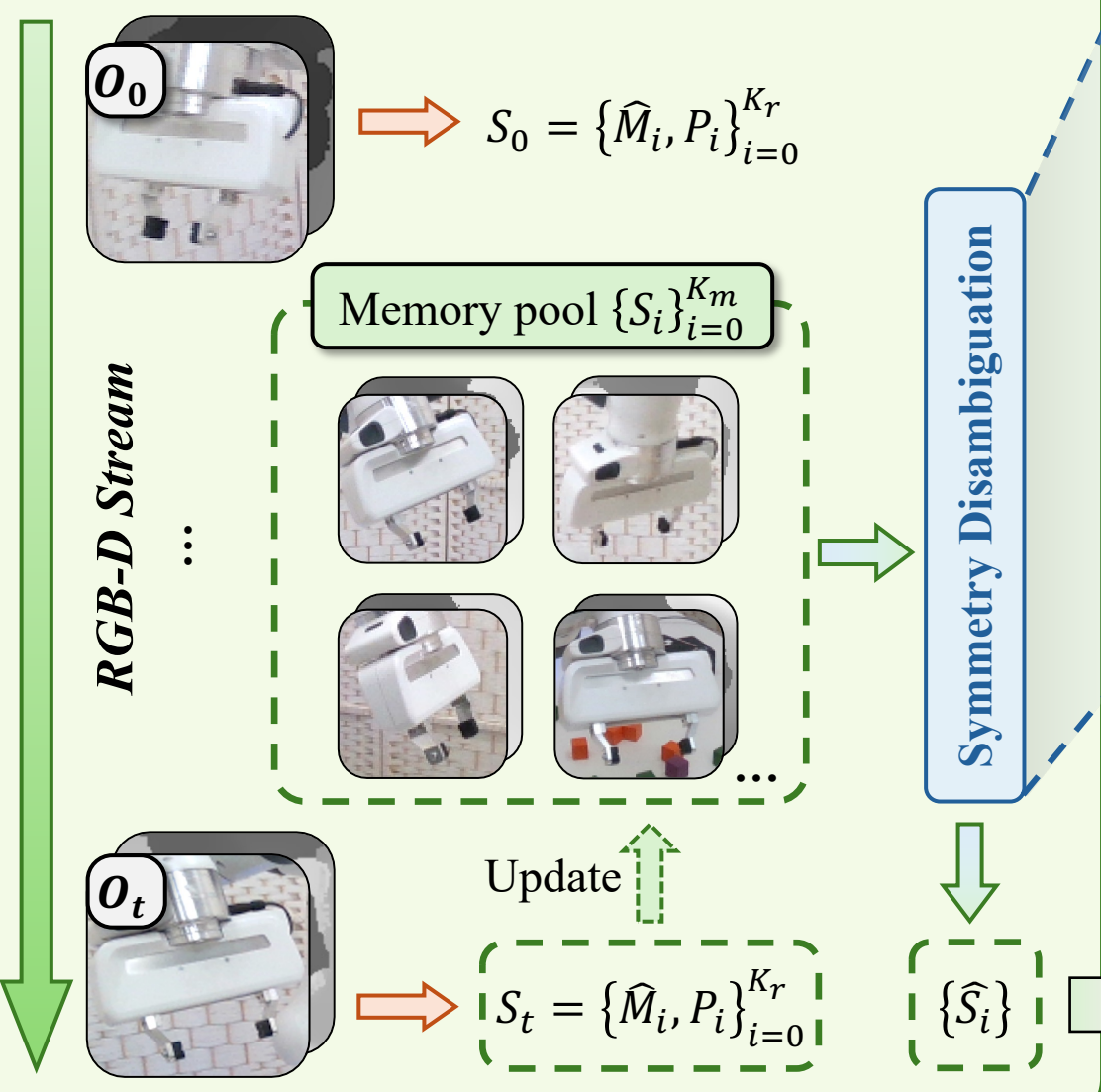


Foundation Feature-Driven 2D-3D Matching (Sec. 3.1)

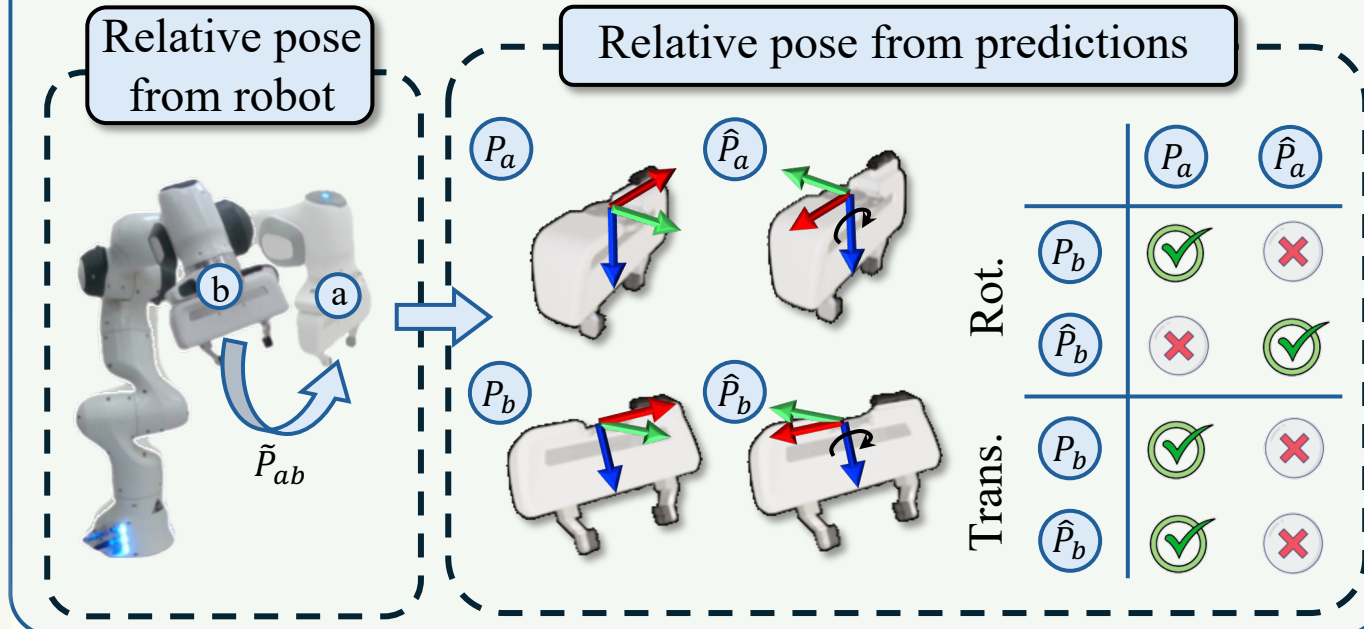


Temporal Key Frames-Enhanced Pose Optimization (Sec. 3.2)

Memory Pool Creation and Update (Sec. 3.2.1)



Symmetry Disambiguation Discriminator (Sec. 3.2.2)



Key Frame Enhanced Pose Optimization (Sec. 3.2.3)

