

1.

?

2.

obmejení sumy

$$S_{xx} = \begin{cases} 3 & \text{za } 0 < |w| < 2\pi \\ 0 & \text{levný pojasa} \end{cases}$$

a) zjednodušit $R_{xx}(\tau) = ?$

$$R_{xx}(\tau) = \frac{1}{\pi} \int_0^{2\pi} S_{xx}(w) \cos(w\tau) \sqrt{w} dw = \frac{1}{\pi} \int_0^{2\pi} 3 \cdot \cos(w\tau) \sqrt{w} dw = \frac{3}{\pi} \cdot \left. \frac{\sin(w\tau)}{\tau} \right|_0^{2\pi} =$$

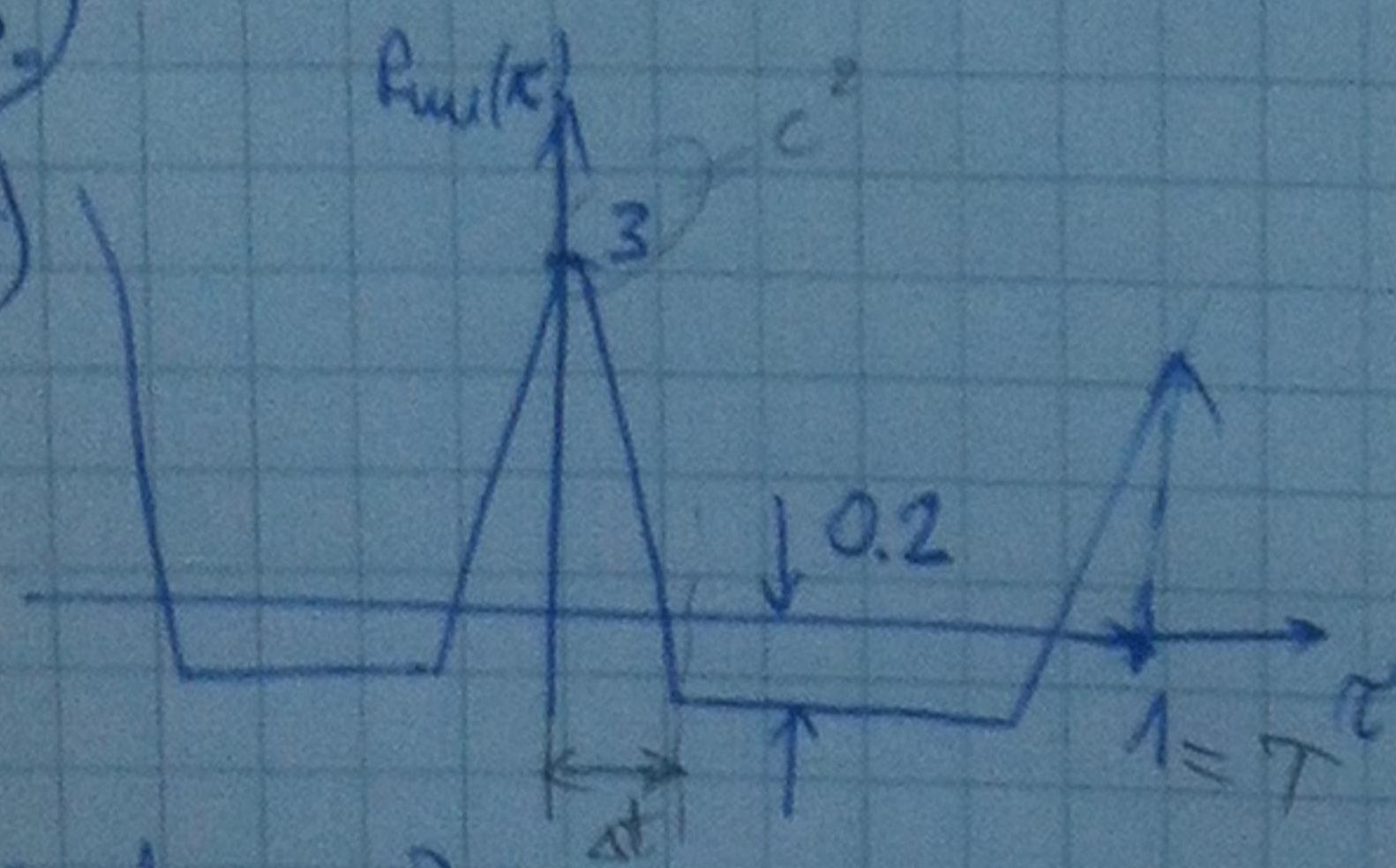
$$= \frac{3}{\pi\tau} \cdot (\sin(2\pi\tau) - \sin(0 \cdot \tau)) = \frac{3}{\pi\tau} \cdot \sin(2\pi\tau)$$

b) $\bar{P}_x = ?$

$$\bar{P}_x = R_{xx}(0) = \frac{3 \cdot 2\pi \cdot \cos(0 \cdot \tau)}{\pi} = 6$$

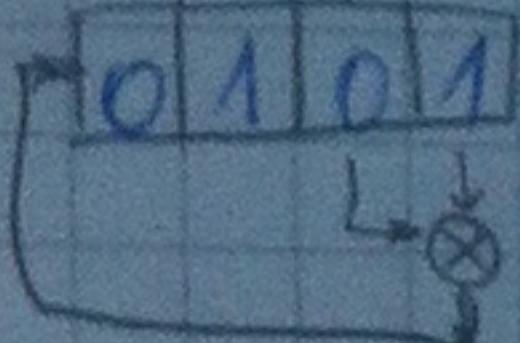
3.

a)

 $C, \Delta t, N = ?$

$$C = \sqrt{3}$$

b)



| | | | |
|---|---|---|---|
| 1 | 0 | 1 | 0 |
| 1 | 1 | 0 | 1 |
| 1 | 1 | 1 | 0 |
| 1 | 1 | 1 | 1 |
| 0 | 1 | 1 | 1 |
| 0 | 0 | 1 | 1 |
| 0 | 0 | 0 | 1 |

$$P_{uu}(\tau) = \frac{-C^2}{N}$$

$$N = -\frac{C^2}{P_{uu}(\tau)} = -\frac{3^2}{-9.2} = \underline{15}$$

$$T = N \cdot \Delta t$$

$$\Delta t = \frac{T}{N} = \frac{1}{15} = 0.06$$



c) $N \gg$, dtc

$$R_{yy}(\tau) = ? \quad \text{izaz}$$

$$R_{yy}(\tau) = \int_0^\infty R_{yy}(\tau - \sigma) \cdot g(\sigma) d\sigma$$

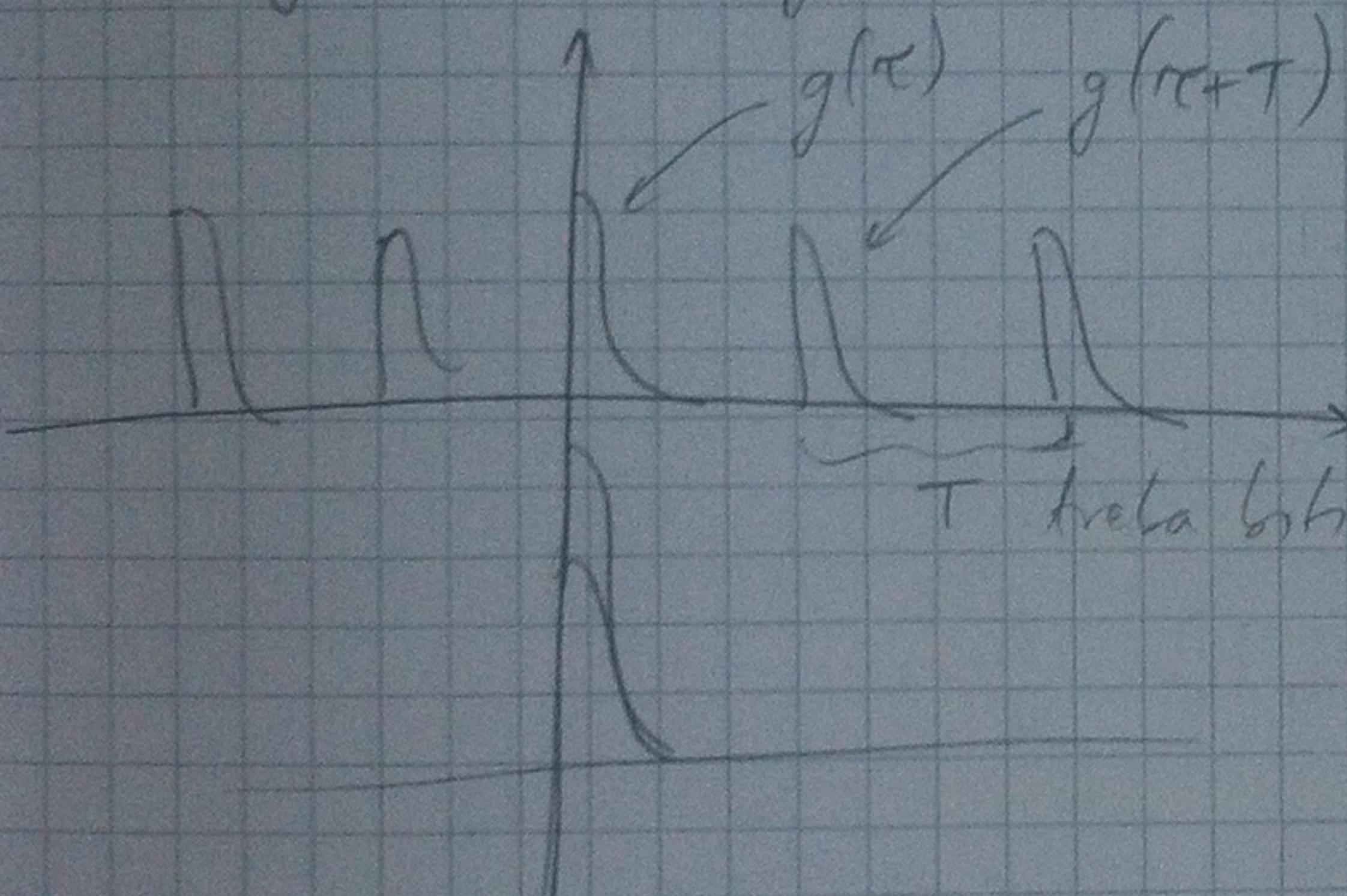
$$R_{yy}(\tau) = c^2 \Delta t \sum_{n=-\infty}^{\infty} \delta(\tau - nT)$$

$$R_{yy}(\tau) = c^2 \Delta t \sum_{n=-\infty}^{\infty} \int_0^\infty g(\sigma) \cdot \delta(\tau - \sigma - nT) d\sigma = c^2 \Delta t \sum_{n=0}^{\infty} g(\tau - nT) =$$

$$= c^2 \cdot \Delta t \cdot (g(\tau + \Delta t) + \dots + g(\tau + T) + g(\tau) + g(\tau - T) + \dots + g(\tau - nT))$$

$$\tau < T, g(\tau) = 0, \forall \tau$$

$$\Rightarrow R_{yy}(\tau) = c^2 \Delta t \cdot (g(\tau) + g(\tau + T) + \dots)$$



T trece brii dulpmi velle da se re scrie probabilitate
sigură ...

4.

$$f(t) = \lambda e^{-\lambda t}, t \geq 0$$

ML metodom obiectivită estimat λ .

$$L = \prod_{i=1}^N \lambda e^{-\lambda t_i} = \lambda^N \cdot e^{-\lambda \sum_i^N t_i} \quad / \ln$$

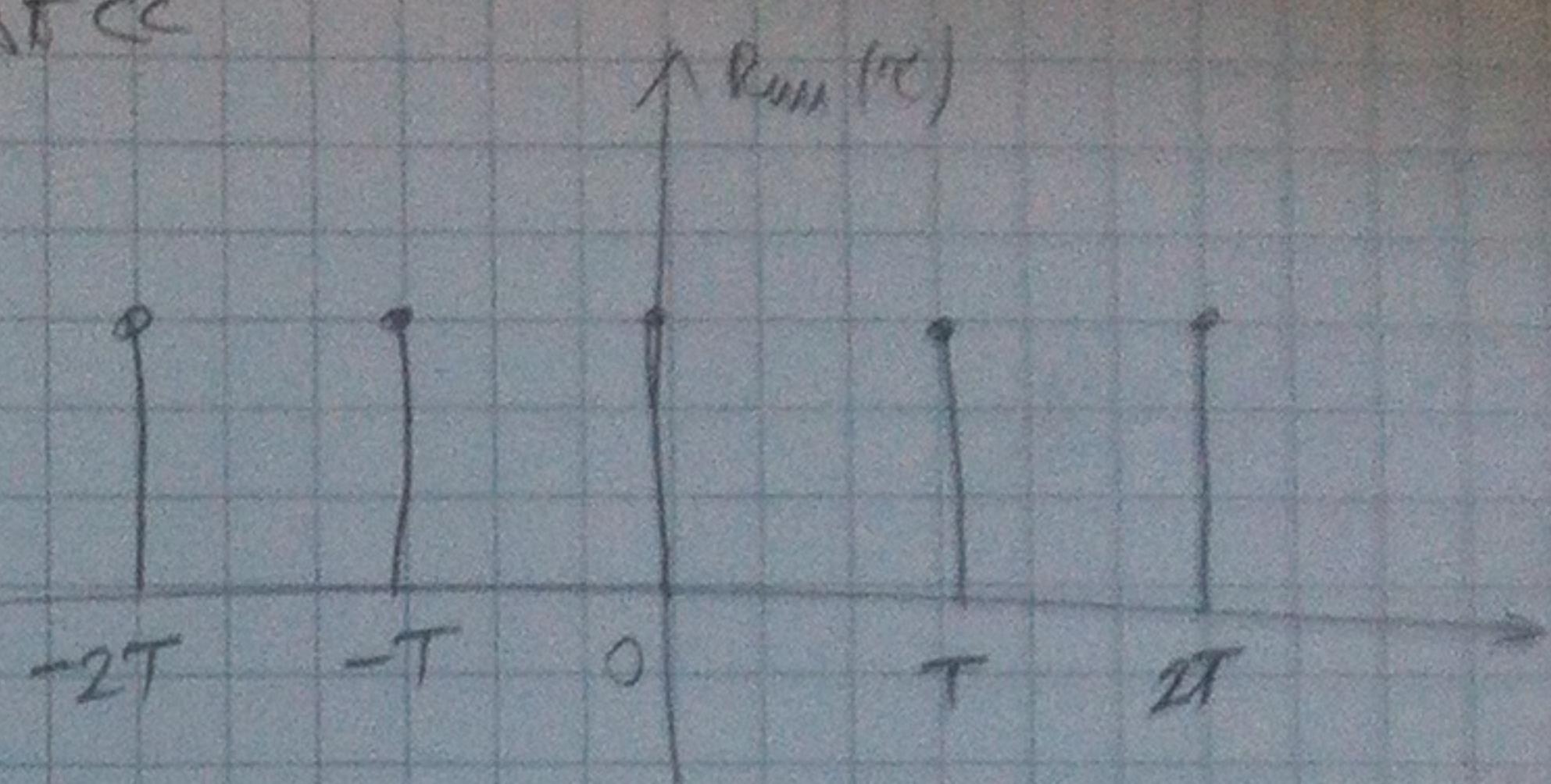
$$\partial_\lambda L = N \cdot \ln \lambda + (-\lambda) \sum_i^N t_i$$

trojim max.

$$\frac{\partial L}{\partial \lambda} = N \cdot \frac{1}{\lambda} - \sum_i^N t_i = 0$$

$$\lambda = \frac{N}{\sum_i^N t_i}$$

za atcc



$$5. \quad y(k) = ay(k-1) + bu(k-1) + v(k)$$

$$v(k) = 0,3u(k) + \varepsilon(k)$$

tablica: $\begin{array}{|c|c|} \hline k & u(k) \\ \hline 0 & 1 \\ 1 & 2 \\ 2 & 3 \\ 3 & 4 \\ 4 & 5 \\ \hline \end{array}$

$$Y = \Phi \cdot \Theta + \varepsilon$$

a) $\hat{a} = ?$, $\hat{b} = ?$, LS metoda.

$$y(k) = ay(k-1) + bu(k-1) + 0,3u(k) + \varepsilon(k)$$

$$y(k) - 0,3u(k) = ay(k-1) + bu(k-1) + \varepsilon(k)$$

$$y(1) - 0,3u(1) = ay(0) + bu(0) + \varepsilon(1)$$

$$y(2) - 0,3u(2) = ay(1) + bu(1) + \varepsilon(2)$$

$$y(3) - 0,3u(3) = ay(2) + bu(2) + \varepsilon(3)$$

$$y(4) - 0,3u(4) = ay(3) + bu(3) + \varepsilon(4)$$

$$y(5) - 0,3u(5) = ay(4) + bu(4) + \varepsilon(5)$$

Y - vektor izbranog signala

Φ - matrica podataka

Θ - vektor parametara

ε - vektor pogreške

$$\hat{\Theta} = \begin{bmatrix} \hat{a} \\ \hat{b} \end{bmatrix}, \quad \hat{\Theta} = (\Phi^T \cdot \Phi)^{-1} \cdot \Phi^T \cdot Y$$

$$\Phi = \begin{bmatrix} y(0) & u(0) \\ y(1) & u(1) \\ y(2) & u(2) \\ y(3) & u(3) \\ y(4) & u(4) \end{bmatrix} = \begin{bmatrix} 1 & -1 \\ 0,76 & 1 \\ 0,86 & -1 \\ 0,92 & -1 \\ -0,72 & -1 \end{bmatrix}, \quad Y = \begin{bmatrix} 0,76 - 0,3 \\ 0,86 + 0,3 \\ 0,02 + 0,3 \\ -0,72 + 0,3 \\ -0,85 - 0,3 \end{bmatrix} = \begin{bmatrix} 0,46 \\ 1,16 \\ 0,32 \\ -0,42 \\ -1,15 \end{bmatrix}$$

$$\hat{\Theta} = \left(\begin{bmatrix} 1 & -1 \\ 0,76 & 1 \\ 0,86 & -1 \\ 0,92 & -1 \\ -0,72 & -1 \end{bmatrix} \right)^{-1} \cdot \begin{bmatrix} 0,46 \\ 1,16 \\ 0,32 \\ -0,42 \\ -1,15 \end{bmatrix}$$

$$= \begin{bmatrix} 2,836 & -0,6 \\ -0,6 & 5 \end{bmatrix}^{-1} \cdot \begin{bmatrix} 0,46 \\ 1,16 \\ 0,32 \\ -0,42 \\ -1,15 \end{bmatrix} = \begin{bmatrix} 0,3566 & 0,0285 \\ 0,0285 & 0,2022 \end{bmatrix} \cdot \begin{bmatrix} 0,46 \\ 1,16 \\ 0,32 \\ -0,42 \\ -1,15 \end{bmatrix} = \begin{bmatrix} 0,924395 \\ 0,463727 \end{bmatrix}$$

b) konzistentni?

?

$$c) IV = \text{Methoden}$$

$$y_H(l) = u(l-1)$$

$W = ?$, $\phi = ?$, $Y = ?$, $\text{Zwei zu Identifizierung passende IV-methode.}$

$$\hat{\Theta} = (W^T, \phi)^{-1} \cdot \phi^T Y$$

$$W = \begin{bmatrix} y_H(0) & u(-1) \\ \vdots & \vdots \\ y_H(4) & u(4) \end{bmatrix} = \begin{bmatrix} u(0) & u(1) \\ u(1) & u(2) \\ u(2) & u(3) \\ u(3) & u(4) \end{bmatrix}, \quad \phi = \begin{bmatrix} g(1) & u(1) \\ \vdots & \vdots \\ y(4) & u(4) \end{bmatrix}, \quad Y = ?$$

6.

a) $R_{xy}(r) = \frac{1}{N} \sum_{l=0}^{N-1} x(l) y(l+r)$

$$N = 4 \quad (\text{period})$$

$$R_{xy}(0) = \frac{1}{4} \cdot (x(0)y(0) + x(1)y(1) + x(2)y(2) + x(3)y(3)) = 1$$

$$R_{xy}(1) = \frac{1}{4} \cdot (x(0)y(1) + x(1)y(2) + x(2)y(3) + x(3)y(4)) = 1$$

$$R_{xy}(2) = \frac{1}{4} \cdot (x(0)y(2) + x(1)y(3) + x(2)y(4) + x(3)y(5)) = 1$$

$$R_{xy}(3) = \frac{1}{4} \cdot (x(0)y(3) + x(1)y(4) + x(2)y(5) + x(3)y(6)) = 1$$

b)

$$R_{yx}(-3 \pi/2) = R_{xy}(3\pi/2) = 1$$

7.

$$S_{uu}(\omega) = \frac{4+25\omega^2}{\omega^2+9}, \quad S_{yy}(\omega) = \frac{16}{\omega^2+9}$$

a) $|G(j\omega)| = ?$

$$|G(j\omega)|^2 = \frac{S_{yy}(\omega)}{S_{uu}(\omega)} = \frac{16}{4+25\omega^2}$$

$$|G(j\omega)| = \sqrt{\frac{4}{4+25\omega^2}}$$

b) $G(j\omega) = \frac{a}{4+bj\omega}, \quad a > 0, \quad b > 0$

$$S_{uy}(j\omega) = S_{uu} \cdot G(j\omega)$$

$$S_{uy}(j\omega) = \frac{4+25\omega^2}{\omega^2+9} \cdot \frac{4}{2+j\omega 5}$$

$$G(j\omega) = \frac{4}{2+j\omega 5}$$

8.

$$y(k) = \rho y(k-1) + (1-\rho) u(k-1) + \varepsilon(k) - 0,2 \varepsilon(k-1)$$

a) ARMAX model

$$A(z^{-1}) \cdot y(z) = B(z^{-1}) \cdot u(z) + C(z^{-1}) \cdot \varepsilon(z)$$

$$y(k) - \rho y(k-1) = (1-\rho) u(k-1) + \varepsilon(k) - 0,2 \cdot \varepsilon(k-1)$$

$$A(z^{-1}) = 1 - \rho z^{-1}$$

!?

$$B(z^{-1}) = (1-\rho) z^{-1}$$

$$C(z^{-1}) = 1 - 0,2 z^{-1}$$

b)

?