

FER 2 Električni krugovi Aktivni i pasivni filtri

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PASIVNI FILTERI

① NISKOPROPUSNI

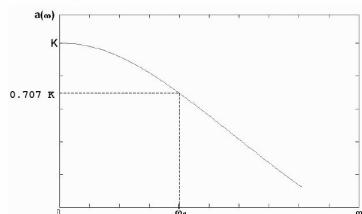
- područje propuštanja: $0 < \omega < \omega_g$

NP FILTAR 1. REDA

$$H(s) = K \cdot \frac{\omega_g}{s + \omega_g}$$

$$s_p = -\omega_g$$

$$s_0 \rightarrow \infty$$

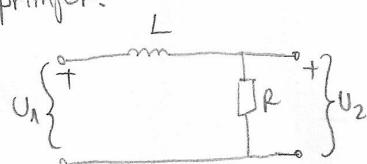


$$|H(j\omega)| = \sqrt{1 + (\frac{\omega}{\omega_g})^2}$$

$$|H(j\omega_g)| = \frac{K}{\sqrt{2}} = 0.707 K$$

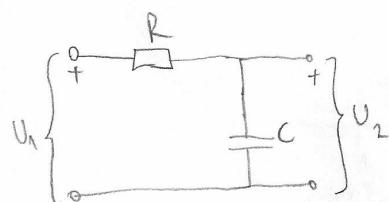
AMPLITUDNO –
-FREKUENCIJSKA
KARAKTERISTIKA

- primjer:



$$H(s) = \frac{R}{L} s + \frac{1}{R} \frac{1}{s + \frac{1}{LC}}$$

$$\omega_g = \frac{1}{\sqrt{LC}}, K=1$$



$$H(s) = \frac{1}{RC} s + \frac{1}{s + \frac{1}{RC}}$$

$$\omega_g = \frac{1}{\sqrt{RC}}, K=1$$

NP FILTAR 2. REDA

$$H(s) = K \cdot \frac{\omega_p^2}{s^2 + \frac{\omega_p^2}{Q_p} \cdot s + \omega_p^2}$$

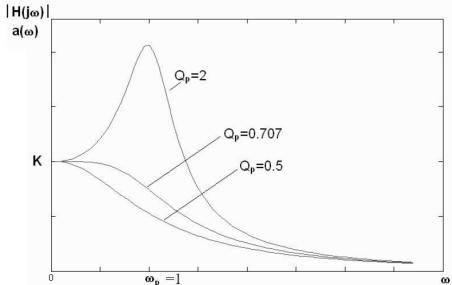
$$s_{p1,2} = \tilde{\omega}_p \pm j\tilde{\omega}_p = \frac{-\omega_p}{2Q_p} \pm j\omega_p \sqrt{1 - \frac{1}{4Q_p^2}}$$

$$s_{o1,2} \rightarrow \infty$$

FREKVENCIJSKA
POLOVA

$$\omega_p = \sqrt{\tilde{\omega}_p^2 + \tilde{\omega}_p^2}$$

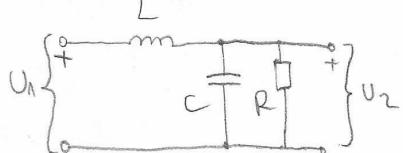
$$Q_p = \frac{\omega_p}{2\tilde{\omega}_p} \Rightarrow \text{FAKTOR KVALITETE}$$



$$a(\omega) = |H(j\omega)| = K \cdot \frac{1}{\sqrt{\left(1 - \frac{\omega^2}{\omega_p^2}\right) + \left(\frac{1}{Q_p} \cdot \frac{\omega}{\omega_p}\right)^2}}$$

- za: $\omega \rightarrow 0 \Rightarrow a(\omega) \rightarrow K$
 $\omega \rightarrow \infty \Rightarrow a(\omega) \rightarrow 0$

- primjer:



$$H(s) = \frac{1}{s^2 + \frac{s}{RC} + \frac{1}{LC}}$$

(2) VISOKOPROPUSNI

- propušta $\omega > \omega_g$

VP FILTAR 1. REDA

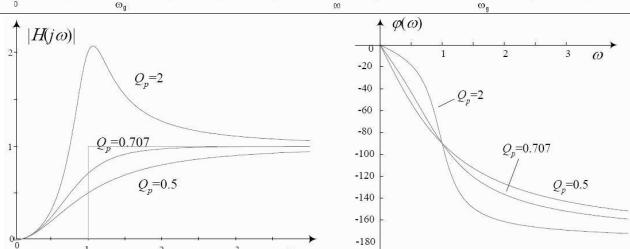
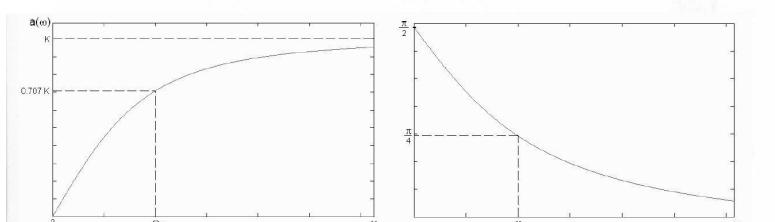
$$H_{vp}(s) = \frac{k \cdot s}{s + \omega_g}$$

$$\omega_p = -\omega_g \quad s_0 = 0$$

$$a(\omega) = |H(j\omega)| = k \cdot \frac{\omega}{\sqrt{\omega^2 + \omega_g^2}}$$

$$\varphi(\omega) = \frac{\pi}{2} - \arctg\left(\frac{\omega}{\omega_g}\right)$$

- realizacije: RL i RC četveropolom



VP FILTAR 2. REDA

$$H(s) = k \cdot \frac{s^2}{s^2 + \frac{\omega_p^2}{Q_p} s + \omega_p^2}$$

$$\omega_{p1,2} = -\frac{\omega_p}{Q_p} \pm j\omega_p \sqrt{1 - \frac{1}{4Q_p^2}}$$

$$s_{0,1,2} = 0$$

$$\omega_p = \sqrt{\omega_p^2 + \tilde{\omega}_p^2}$$

$$Q_p = \frac{-\omega_p}{2\tilde{\omega}_p}$$

- realizacija: RLC četveropolom
 (kao kod NP-filtara)

$$a(\omega) = |H(j\omega)| = k \cdot \frac{\omega^2}{\sqrt{\left(\omega_p^2 - \omega^2\right)^2 + \left(\frac{\omega \omega_p}{Q_p}\right)^2}}$$

$$\varphi(\omega) = \pi - \arctg\left(\frac{\omega_p \cdot \frac{\omega}{Q_p}}{\omega_p^2 - \omega^2}\right)$$

(3) POSASNO – PROPUSNI FILTRI

- propušta: $\omega_d < \omega < \omega_g$

- za PP karakteristiku, filter mora biti
NAJMANJE 2. REDA

PP FILTAR 2. REDA

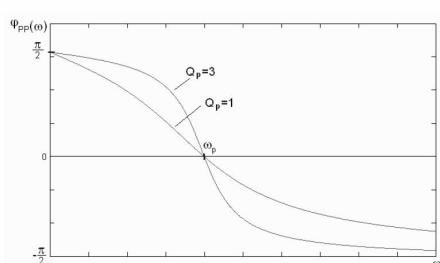
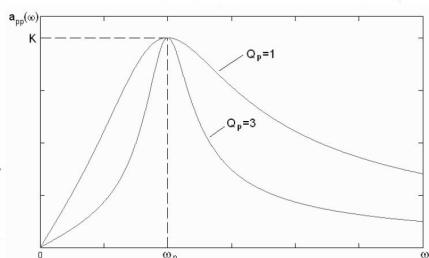
$$H_{pp}(s) = K \cdot \frac{s \cdot \frac{\omega_p}{Q_p}}{s^2 + \frac{\omega_p}{Q_p} s + \omega_p^2}$$

$$s_{pp} = -\frac{\omega_p}{2Q_p} \pm j\omega_p \sqrt{1 - \frac{1}{4Q_p^2}}$$

$$s_{o1} = 0, \quad s_{o2} \rightarrow \infty$$

$$\alpha_{pp}(w) = \frac{K}{\sqrt{1 + Q_p^2 \left(\frac{w}{\omega_p} - \frac{\omega_p}{w} \right)^2}}$$

$$\varphi_{pp}(w) = -\arctg \left(Q_p \left(\frac{w}{\omega_p} - \frac{\omega_p}{w} \right) \right)$$



- za: $\omega = \omega_p \Rightarrow \alpha(w) \rightarrow K$ (MAXIMUM)
- $\omega \rightarrow 0 \Rightarrow \alpha(w) \rightarrow 0$
- $\omega \rightarrow \infty \Rightarrow \alpha(w) \rightarrow 0$

- propušta signale s frekvencijom oko ω_p
- poređanjem Q_p , karakteristika se sužava

$$\alpha_{pp}(\omega_d) = \alpha_{pp}(\omega_g) = \frac{K}{\sqrt{2}}$$

$$\omega_{g,1d} = \omega_p \sqrt{1 + \frac{1}{4Q_p^2}} \pm \frac{\omega_p}{2Q_p}$$

$$B = \omega_g - \omega_d = \frac{\omega_p}{Q_p}$$

$$\omega_p = \omega_c = \sqrt{\omega_d \cdot \omega_g}$$

CENTRALNA FREKVENCija

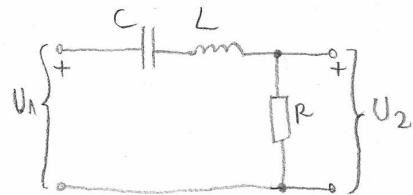
- uskopojasni PP filtri: $B \ll \omega_c$

$$Q_p = \frac{\omega_c}{B} \geq 10$$

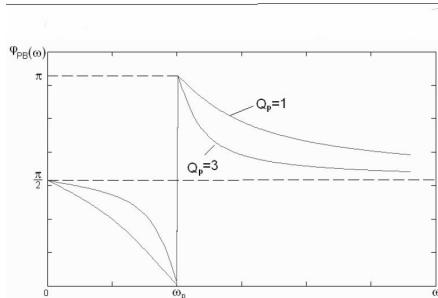
$$\text{- tada je: } \omega_{g,d} = \omega_p \pm \frac{1}{2} B$$

- realizacija:

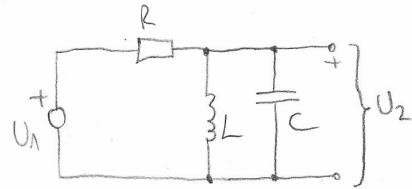
SERIJSKIM RLC KRUGOM



$$H(s) = \frac{s \cdot \frac{R}{L}}{s^2 + s \cdot \frac{R}{L} + \frac{1}{LC}}$$



PARALELnim RLC KRUGOM



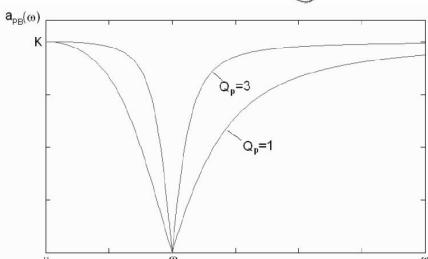
$$H(s) = \frac{s \cdot \frac{1}{RC}}{s^2 + s \cdot \frac{1}{RC} + \frac{1}{LC}}$$

④. POSASNA BRANA

- propušta: $\omega > \omega_g$ i $\omega < \omega_d$

- prijenosna funkcija PB mora biti

NASMANJE 2. REDA



POSASNA BRANA 2. REDA

$$H(s) = K \cdot \frac{s^2 + \omega_p^2}{s^2 + \frac{\omega_p}{Q_p} \cdot s + \omega_p^2}$$

$$s_{p,2} = \frac{\omega_p}{2Q_p} \pm j\omega_p \sqrt{1 - \frac{1}{4Q_p^2}}$$

$$s_{o,2} = \pm j\omega_p$$

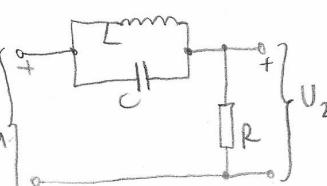
$$a_{PB}(w) = K \cdot \frac{Q_p \cdot \left| \frac{\omega_p - w}{\omega_p} \right|}{\sqrt{1 + Q_p^2 \left(\frac{\omega_p - w}{\omega_p} \right)^2}}$$

$$\varphi_{PB}(w) = \pi \cdot S(w - \omega_p) - \arctg(Q_p \cdot \left(\frac{\omega_p - w}{\omega_p} \right)) - \arctg(Q_p \cdot \left(\frac{w - \omega_p}{\omega_p} \right))$$

$$a_{PB}(w_k) = a_{PB}(\omega_g) = \frac{K}{\sqrt{2}}$$

$$\begin{cases} \text{za: } \omega = \omega_p \Rightarrow a(\omega) = 0 \\ \omega \rightarrow 0 \Rightarrow a(\omega) \rightarrow K \\ \omega \rightarrow \infty \Rightarrow a(\omega) \rightarrow K \end{cases}$$

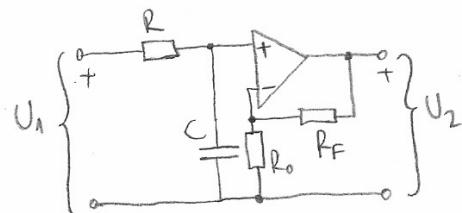
- realizacija: sa RLC četveropolom



$$H(s) = \frac{s^2 + \frac{1}{LC}}{s^2 + s \cdot \frac{1}{RC} + \frac{1}{LC}}$$

AKTIVNI FILTERI

① AKTIVNI FILTRI 1. REDA

1. NP FILTAR

$$H_{NP}(s) = k \cdot \frac{\omega_g}{s + \omega_g}$$

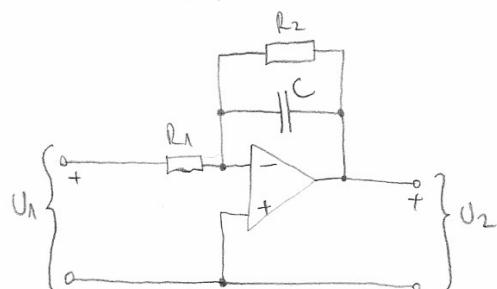
$$k = 1 + \frac{R_F}{R_o}$$

$$\omega_g = \frac{1}{RC}$$

$$a(\omega) = |H(j\omega)| = k \cdot \frac{\omega_g}{\sqrt{\omega^2 + \omega_g^2}}$$

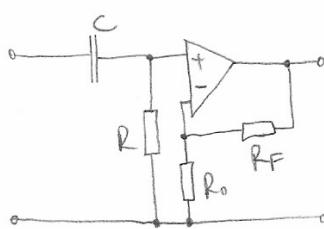
- moguća realizacija
pojačalom:

sa invertirajućim



$$k = -\frac{R_2}{R_1}$$

$$\omega_g = \frac{1}{R_2 C}$$

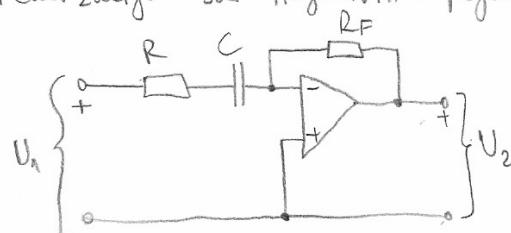
2. VP FILTAR

$$H_{VP}(s) = k \cdot \frac{s}{s + \omega_g}$$

$$k = 1 + \frac{R_F}{R_o} > 1$$

$$\omega_g = \frac{1}{RC}$$

- realizacija sa negativnim pojačanjem:

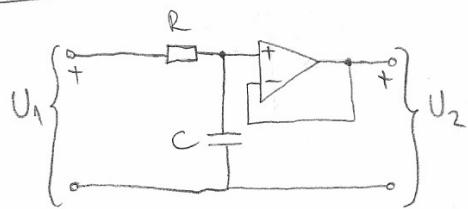


$$k = -\frac{R_F}{R}$$

$$\omega_g = \frac{1}{RC}$$

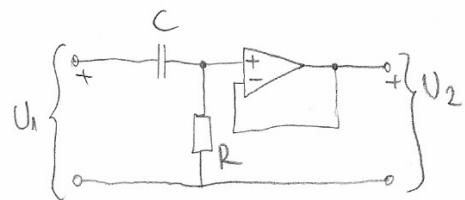
REALIZACIJA VP I NP FILTARA SA SEDINIČNIM POSAČALOM

-NP:



$$k = 1$$
$$\omega_g = \frac{1}{RC}$$

-VP

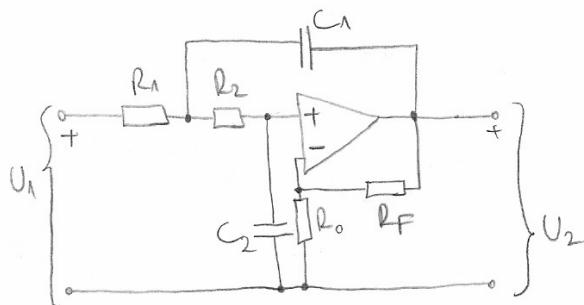


$$k = 1$$
$$\omega_g = \frac{1}{RC}$$

(2) AKTIVNI FILTRI 2. REDA

1. NP FILTAR

$$H_{NP}(s) = k \cdot \frac{\omega_p^2}{s^2 + \frac{\omega_p}{Q_p} \cdot s + \omega_p^2}$$

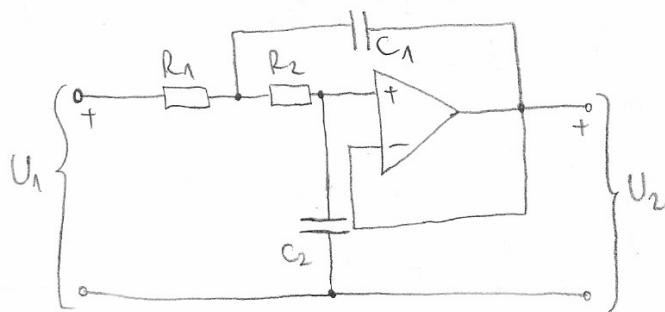


$$k = 1 + \frac{G_0}{G_F}$$

$$\omega_p = \sqrt{\frac{G_1 G_2}{C_1 C_2}}$$

$$Q_p = \sqrt{\frac{C_1 G_1}{C_2 G_2}} \cdot \frac{1 + \frac{G_1}{G_2} + (1-k) \cdot \frac{C_1}{C_2}}{1 + \frac{G_1}{G_2}}$$

-realizacija sa jediničnim pojачalom:



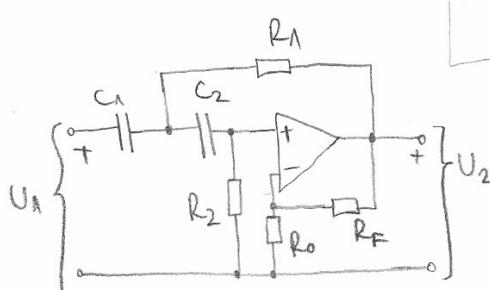
$$k = 1$$

$$\omega_p = \sqrt{\frac{G_1 G_2}{C_1 C_2}}$$

$$\frac{\omega_p}{Q_p} = \frac{G_1 + G_2}{C_1}$$

2. VP FILTAR

$$H_{VP}(s) = k \cdot \frac{s^2}{s^2 + \frac{\omega_p}{Q_p} s + \omega_p^2}$$

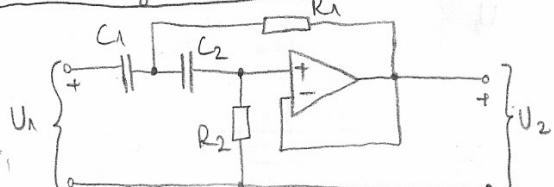


$$k = 1 + \frac{G_0}{G_F}$$

$$\omega_p = \sqrt{\frac{G_1 G_2}{C_1 C_2}}$$

$$Q_p = \sqrt{\frac{C_1 G_1}{C_2 G_2}} \cdot \frac{1 + \frac{C_1}{C_2} - \frac{G_1}{G_2} \cdot \frac{G_0}{G_F}}{1 + \frac{C_1}{C_2}}$$

-realizacija jediničnim pojачalom:

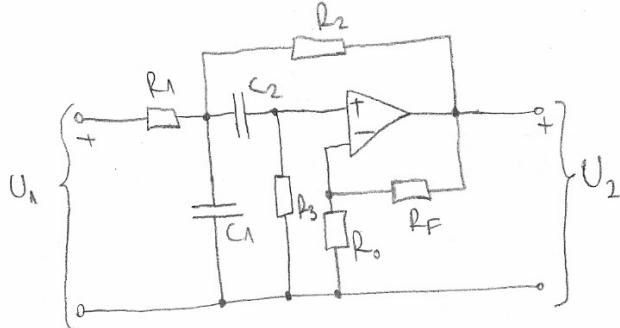


$$k = 1$$

$$\omega_p = \sqrt{\frac{G_1 G_2}{C_1 C_2}}$$

$$Q_p = \sqrt{\frac{C_1 G_1}{C_2 G_2}} \cdot \frac{1 + \frac{C_1}{C_2}}{1 + \frac{C_1}{C_2}}$$

3. PP FILTAR



$$H_{PP}(s) = b_1 \cdot \frac{\frac{\omega_p}{Q_p} \cdot s}{s^2 + \frac{\omega_p}{Q_p} \cdot s + \omega_p^2}$$

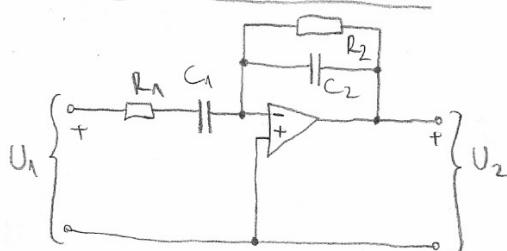
$$b = 1 + \frac{R_F}{R_o}$$

$$\omega_p = \sqrt{\frac{(G_1 + G_2) \cdot G_3}{C_1 C_2}}$$

$$Q_p = \sqrt{\frac{G_3}{G_1 + G_2}} \cdot \frac{C_2}{C_1}$$

$$Q_p = \frac{G_3}{G_1 + G_2} \cdot \left(1 + \frac{C_2}{C_1} \right) + \frac{C_2}{C_1} - \left(1 + \frac{G_3}{G_F} \right) \cdot \frac{G_2}{G_1 + G_2}$$

ŠIROKOPOSASNI FILTAR



$$\omega_p = \frac{1}{\sqrt{R_1 R_2 C_1 C_2}}$$

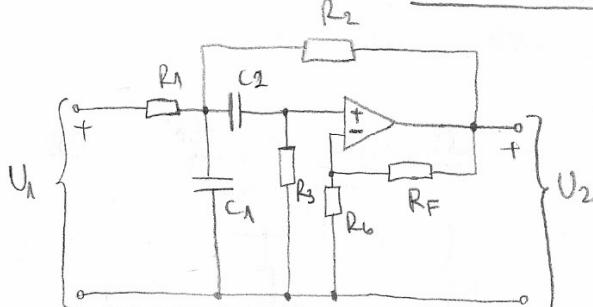
$$k = \frac{1}{\frac{C_2}{C_1} + \frac{R_1}{R_2}}$$

$$S_{p1} = -\frac{1}{R_1 C_1} = -\omega_d$$

$$S_{p2} = -\frac{1}{R_2 C_2} = -\omega_g$$

$$Q_p = \frac{1}{\sqrt{\frac{R_1 C_1}{R_2 C_2}} + \sqrt{\frac{R_2 C_2}{R_1 C_1}}} \leq 0.5$$

USKOPOSASNI FILTAR

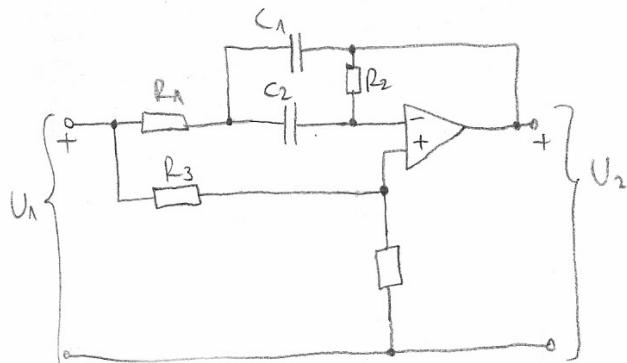


$$\omega_p = \sqrt{\frac{(G_1 + G_2) \cdot G_3}{C_1 C_2}}$$

$$Q_p = \frac{\omega_p}{\frac{G_3}{C_1} + \frac{G_3}{C_2} + \frac{G_1 + G_2}{C_1} - \left(1 + \frac{G_3}{G_F} \right) \cdot \frac{G_2}{C_1}}$$

4.

PODASNA BRANA



$$H_{PB}(s) = k \cdot \frac{s^2 + \frac{w_p}{Q_2} \cdot s + w_p^2}{s^2 + \frac{w_p}{Q_p} s + w_p^2}$$

$$Q_2 \rightarrow \infty$$

- ovaj uvjet je moguće postići ako je:

$$G_2 \cdot \left(\frac{1}{C_1} + \frac{1}{C_2} \right) = \frac{G_1 \cdot G_4}{C_1 \cdot G_3}$$

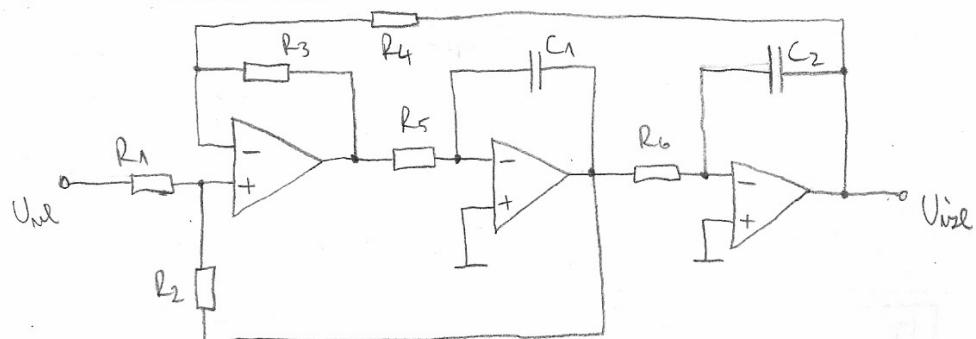
$$k = \frac{G_3}{G_3 + G_4}$$

$$\omega_p = \sqrt{\frac{G_1 G_2}{C_1 C_2}}$$

$$Q_p = \frac{\omega_p}{G_2} \cdot \frac{C_1 C_2}{C_1 + C_2}$$

5.

UNIVERZALNA FILTARSKA SEKCIJA



- analiza sekcija:

$$U_{in21}(s) = -\frac{1}{R_6 \cdot C_2 \cdot s} \cdot U_{in23}(s)$$

$$U_{in23}(s) = -\frac{1}{R_5 \cdot C_1 \cdot s} \cdot U_{in22}(s)$$

$$U_{in22}(s) = \left(1 + \frac{R_3}{R_4} \right) \cdot \frac{R_2 \cdot U_{in1}}{R_1 + R_2} + \left(1 + \frac{R_3}{R_4} \right) \cdot \frac{R_1 \cdot U_{in23}}{R_1 + R_2} - \frac{R_3}{R_4} U_{in21}$$

- NP prijenosna funkcija:

$$H_{NP}(s) = \frac{U_{iz_1}}{U_{nl}} = \frac{\frac{G_1(G_4+G_3) \cdot G_5 \cdot G_6}{G_3 \cdot (G_1+G_2) \cdot C_1 \cdot C_2}}{s^2 + s \cdot \left(\frac{G_2 \cdot G_5 \cdot (G_4+G_3)}{G_3 \cdot (G_1+G_2) \cdot C_1} \right) + \frac{G_4 \cdot G_5 \cdot G_6}{G_3 \cdot C_1 \cdot C_2}}$$

izlazni napon

ulazni napon

- VP prijenosna funkcija:

$$H_{VP}(s) = \frac{U_{iz_2}}{U_{nl}} = \frac{\frac{G_1 \cdot (G_4+G_3) \cdot s^2}{G_3 \cdot (G_1+G_2)}}{s^2 + s \cdot \left(\frac{G_2 \cdot G_5 \cdot (G_4+G_3)}{G_3 \cdot (G_1+G_2) \cdot C_1} \right) + \frac{G_4 \cdot G_5 \cdot G_6}{G_3 \cdot C_1 \cdot C_2}}$$

- PP prijenosna funkcija:

$$H_{PP}(s) = \frac{U_{iz_3}}{U_{nl}} = \frac{-\frac{G_1 \cdot (G_4+G_3) \cdot G_5}{G_3 \cdot (G_1+G_2) \cdot C_1} \cdot s}{s^2 + s \cdot \left(\frac{G_2 \cdot G_5 \cdot (G_4+G_3)}{G_3 \cdot (G_1+G_2) \cdot C_1} \right) + \frac{G_4 \cdot G_5 \cdot G_6}{G_3 \cdot C_1 \cdot C_2}}$$

- općenito vrijedi:

$$\omega_p = \sqrt{\frac{G_4 \cdot G_5 \cdot G_6}{G_3 \cdot C_1 \cdot C_2}}$$

$$Q_p = \sqrt{\frac{C_1}{C_2}} \cdot \frac{\sqrt{G_4 G_6}}{\sqrt{G_3 G_5}} \cdot \frac{1 + \frac{G_1}{G_2}}{1 + \frac{G_4}{G_3}}$$

$$k_{NP} = \frac{G_1 (G_4 + G_3)}{G_4 (G_1 + G_2)}$$

$$k_{PP} = \frac{G_1}{G_2}$$

$$k_{VP} = \frac{G_1 (G_4 + G_3)}{G_3 (G_1 + G_2)}$$

- broj pasivnih elemenata filtra je 8, a broj uvjeta koje treba ispuniti 3 \Rightarrow 5 elemenata je moguće proizvoljno odabrati

- uobičajeno:

$$G_5 = G_6 = G, \quad C_1 = C_2 = C \Rightarrow$$

$$\omega_p = \sqrt{\frac{G_4}{G_3}} \cdot \frac{G}{C} \quad Q_p = \sqrt{\frac{G_4}{G_3}} \cdot \frac{1 + \frac{G_1}{G_2}}{1 + \frac{G_4}{G_3}}$$