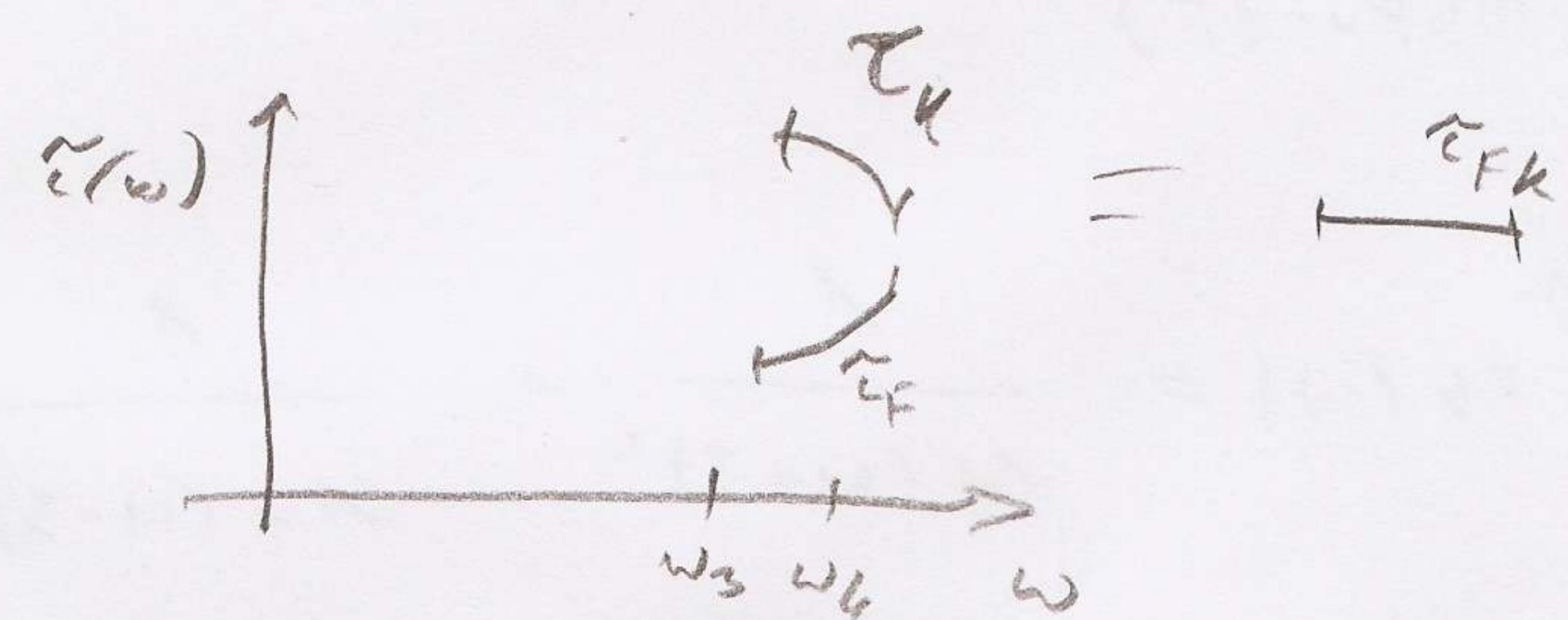
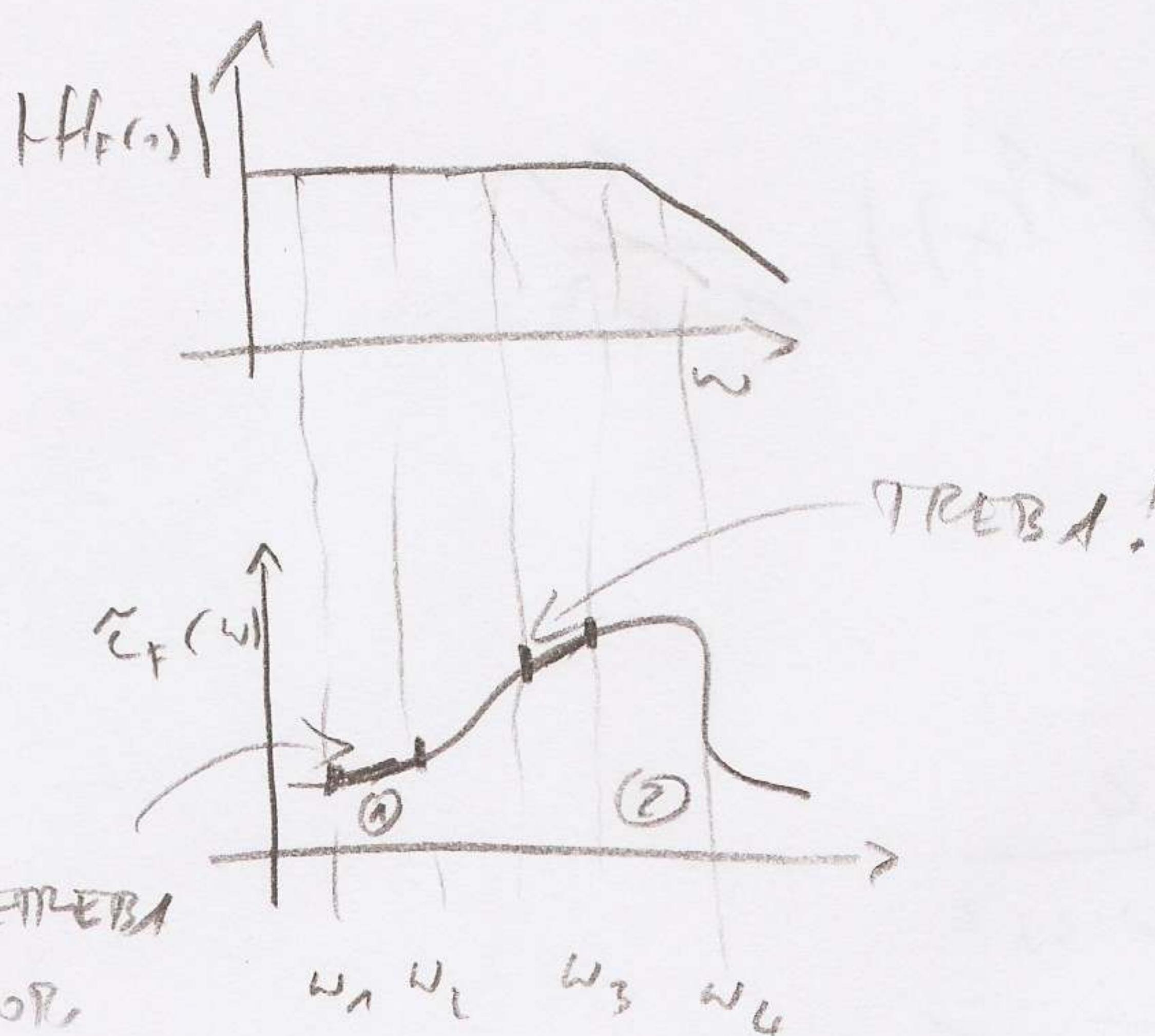


1. NP 2.

$$H_F(z) = \frac{10}{z^2 + 2z + 10}$$

$$H_K(z) = \frac{z-2}{z+2}$$

Fazni korektor je nepravilan filter koji koristi
faznu zadržavajuću funkciju u decom faza.



U podnagoju ① nije potrebna korekcija, a podnagoju ② je potrebna.

a) Polovi filtera

$$s^2 + 2s + 10 = 0$$

$$\lambda_{F_{1,2}} = -1 \pm 3j$$

Polovi korektora

$$s+2=0$$

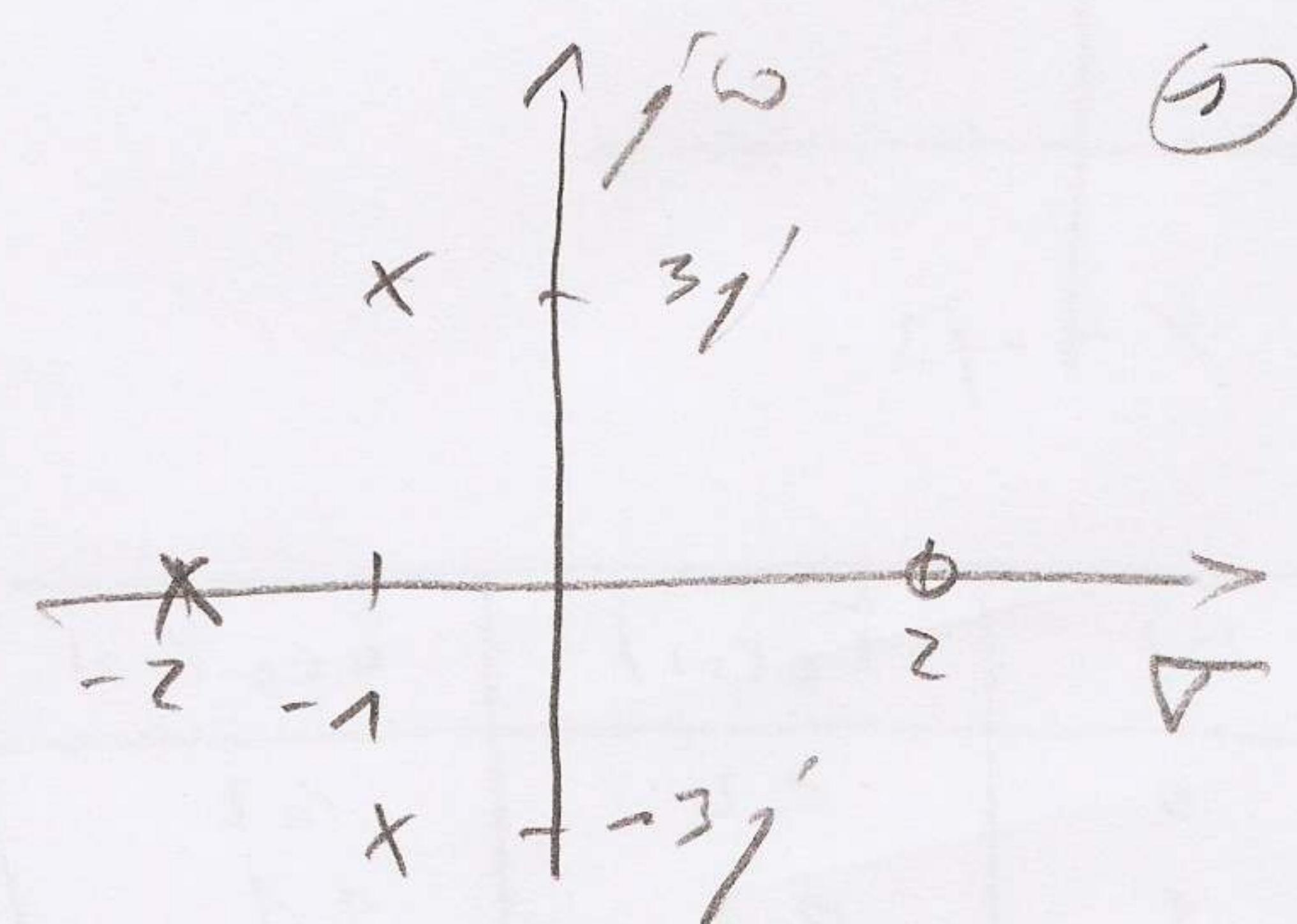
$$\lambda_K = -2$$

Koeficijenti

Nule korektora

$$s-2=0$$

$$\lambda_K = 2$$



U digitalizaciji su nule = # polovi, nule
u ishodlito

b) Grupno klasiranje
a. faktorizacija!

$$H_{FK}(z) = \frac{10}{(z+j)(z+1-j)} \cdot \frac{z-2}{z+2}$$

$$z=jw$$

$$H_{FK}(w) = \frac{10}{(w+j+3)(w-j+3)} \cdot \frac{-2j/w}{z+jw}$$

$$\varphi_{FK}(w) = -\underbrace{\cancel{j}^{-1}(w+3) - \cancel{j}^{-1}(w-3)}_{= \varphi_F(w)} - \underbrace{2\cancel{j}^{-1}\left(\frac{w}{2}\right)}_{= \varphi_k(w)}$$

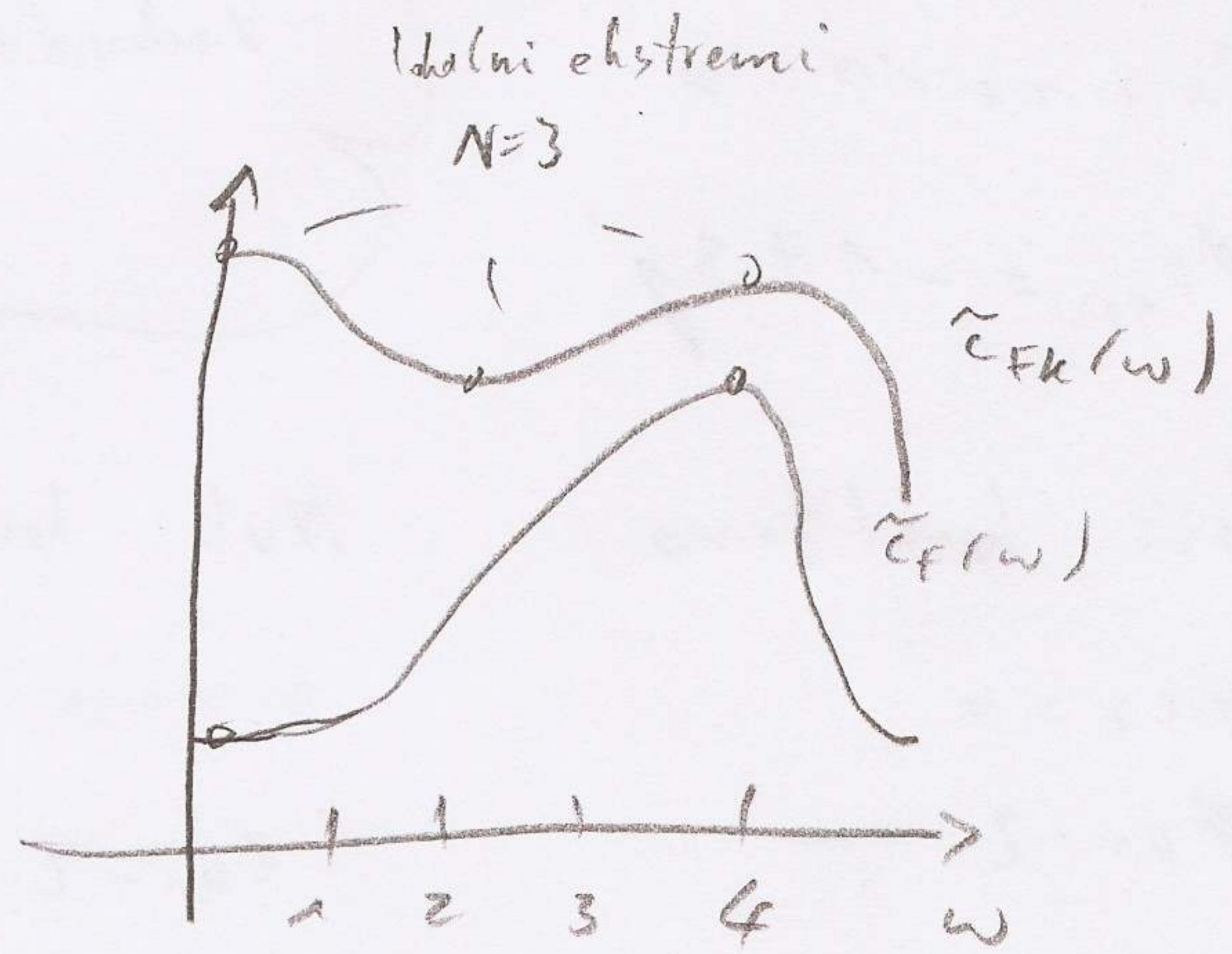
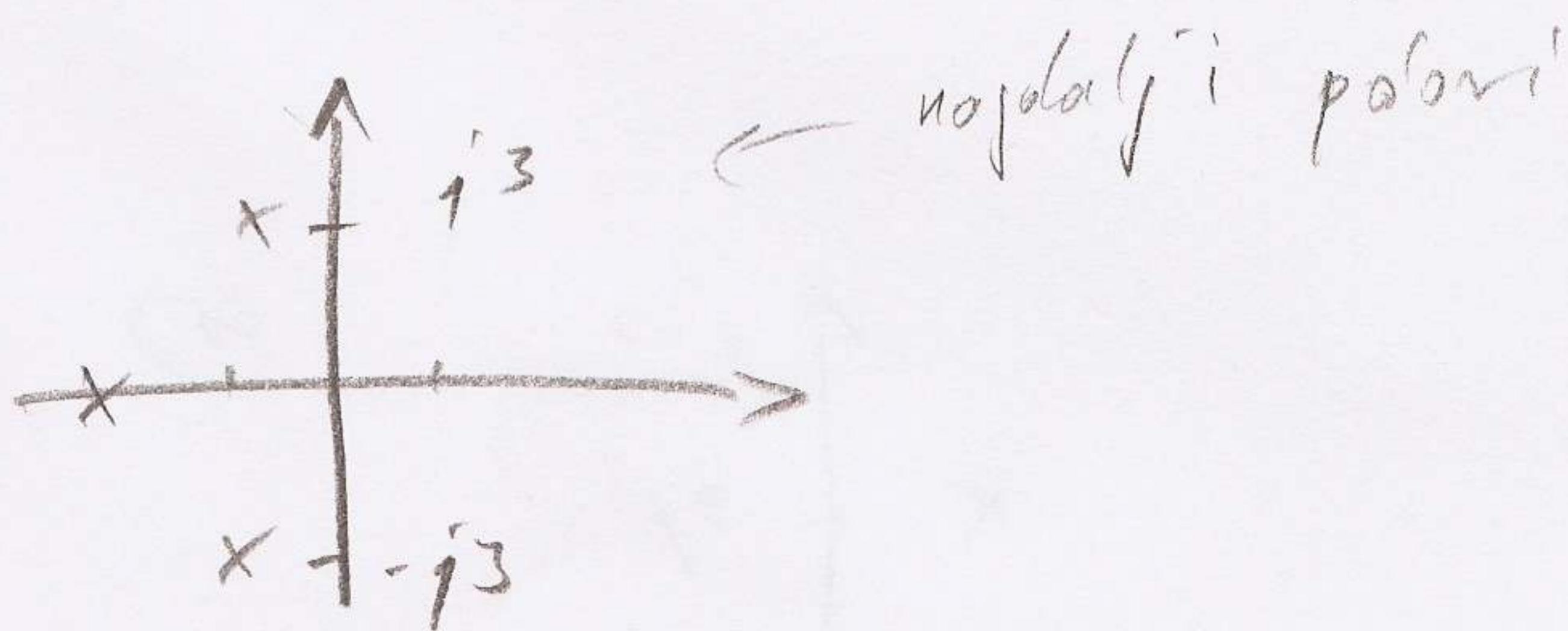
$$\tilde{\epsilon}_{FK}(w) = -\frac{1}{jw} \varphi_{FK}(w)$$

(j^{-1}(x)) = \frac{1}{1+x^2}

\hookrightarrow GRUPA
FREKVENCija
(PODRUČJE)

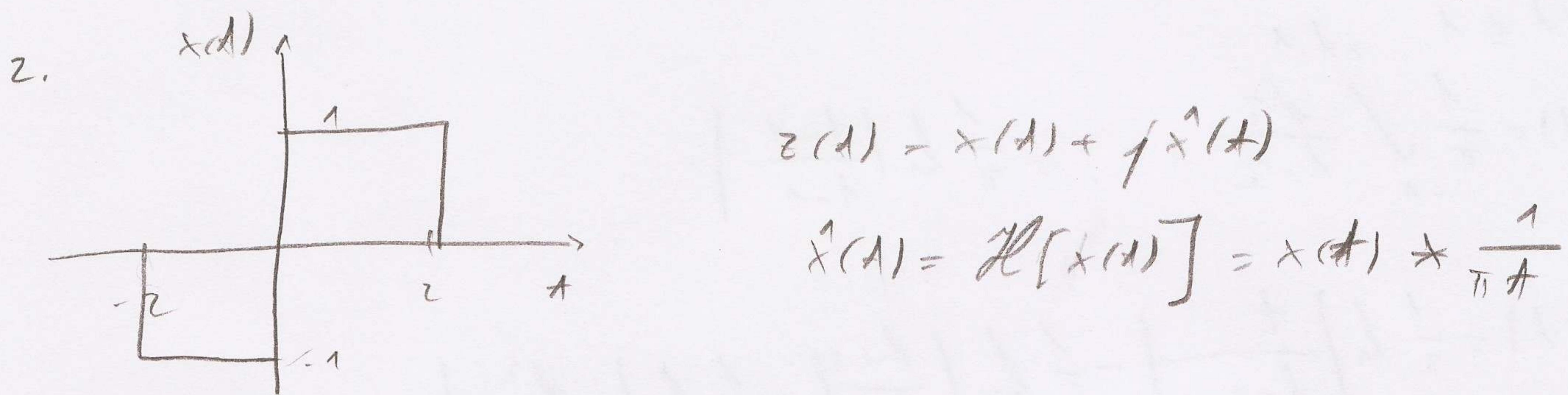
$$\tilde{\epsilon}_{FK}(w) = \underbrace{\frac{1}{1+(w+3)^2} + \frac{1}{1+(w-3)^2}}_{= \tilde{\epsilon}_F(w)} + \underbrace{\frac{4}{4+w^2}}_{= \tilde{\epsilon}_k(w)}$$

Koji w vrati? Očitavajući iz polova.

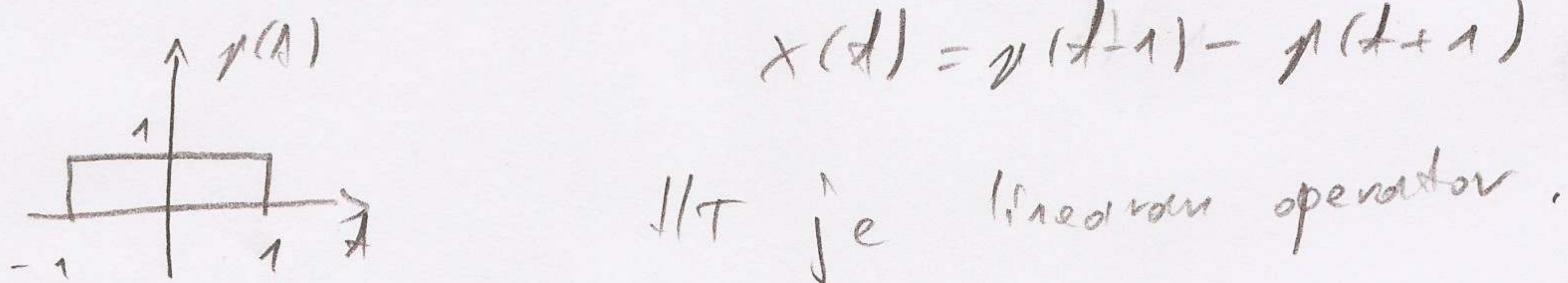


w	$\tilde{\epsilon}_F(w)$	$\tilde{\epsilon}_{FK}(w)$
0	0.2	1.2
1	0.3	1.1
2	0.5	1
3	1	1.3
4	0.5	0.2
5	0.2	0.4

1. U nečistim slučaju se se krovna grupa raspršenja (amplitudo) može raznije od tih red sistema. To je broj svih lokalnih ekstremi.



Vvodimo signal



$\mathcal{H}T$ je linearan operator.

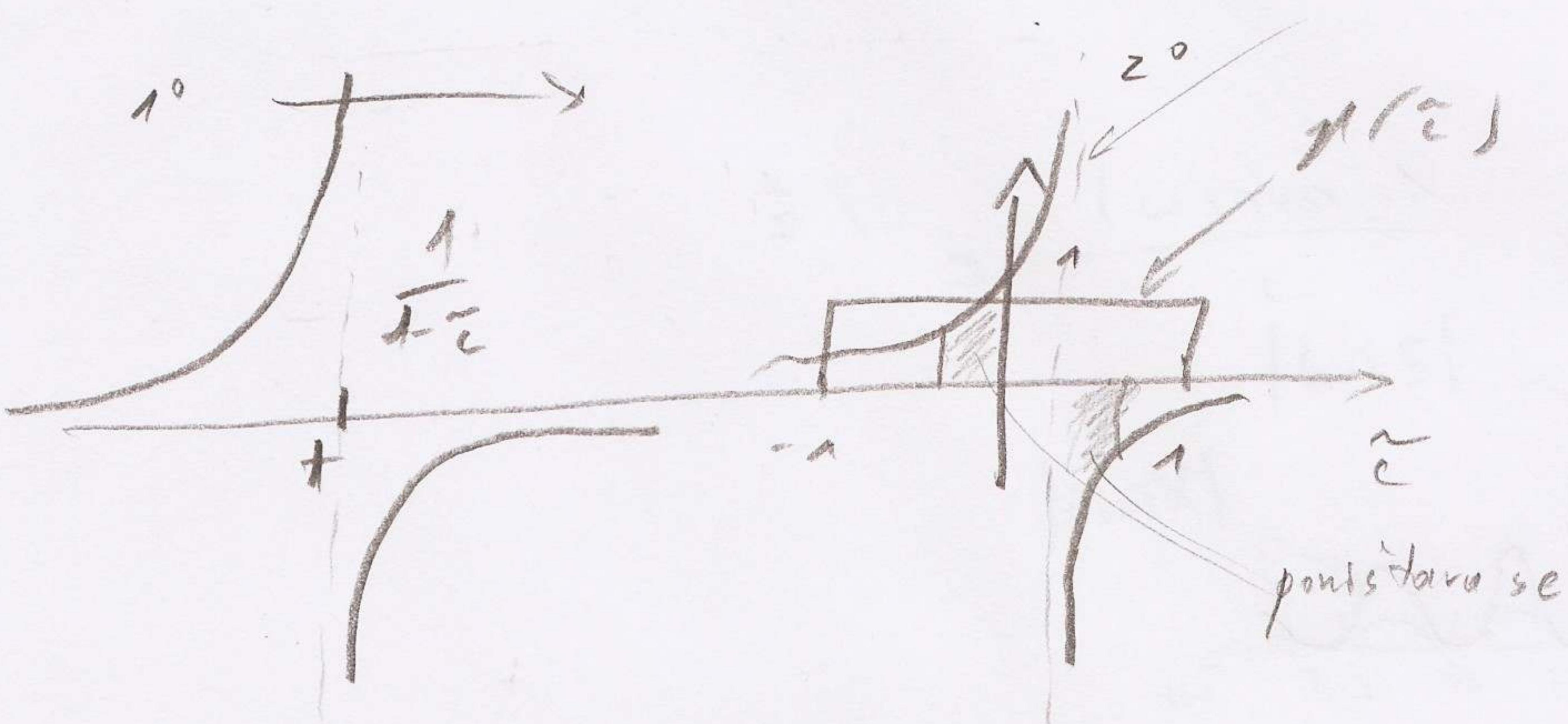
$$\hat{x}(d) = \hat{r}(d-1) - \hat{r}(d+1) \Rightarrow \hat{r}(d) = ?$$

Računanje $\mathcal{H}T$:

- 1) izvorno, računanjem Hilbertovog integrala
- 2) neizvorno, prebacivanjem u FD, a potom računanjem IF

$$\hat{r}(d) = \frac{1}{\pi} \operatorname{PV} \int_{-\infty}^{\infty} \frac{r(\tilde{c})}{d-\tilde{c}} d\tilde{c}$$

DISKONTINUITET



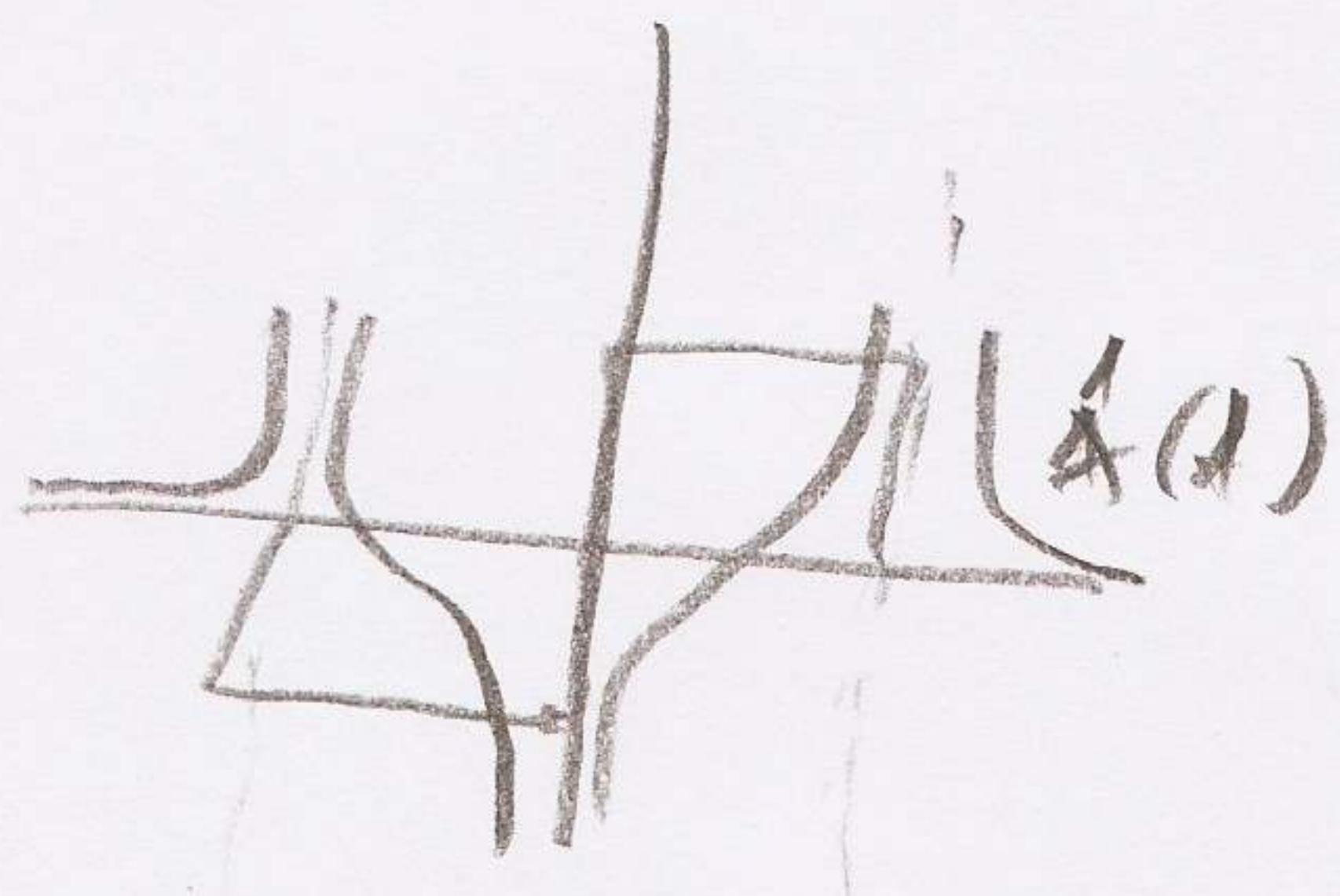
1° $t \leq -1, t \geq 1$

$$\hat{x}(t) = \frac{1}{\pi} \int_{-1}^1 \frac{1}{t-\tilde{z}} d\tilde{z} = -\frac{1}{\pi} \ln|z-t| = \frac{1}{\pi} \ln \left| \frac{t+1}{t-1} \right|$$

2° $-1 \leq t \leq 1$

$$\hat{x}(t) = \frac{1}{\pi} \int_{-1}^{2t-1} \frac{d\tilde{z}}{t-\tilde{z}} = \dots = \frac{1}{\pi} \ln \left| \frac{t+1}{t-1} \right|$$

$$\Rightarrow \hat{x}(t) = \frac{1}{\pi} \ln \left| \frac{t}{t-2} \right| - \frac{1}{\pi} \ln \left| \frac{t+2}{t+4} \right| = \frac{1}{\pi} \ln \left| \frac{t^2}{t^2-4} \right|$$



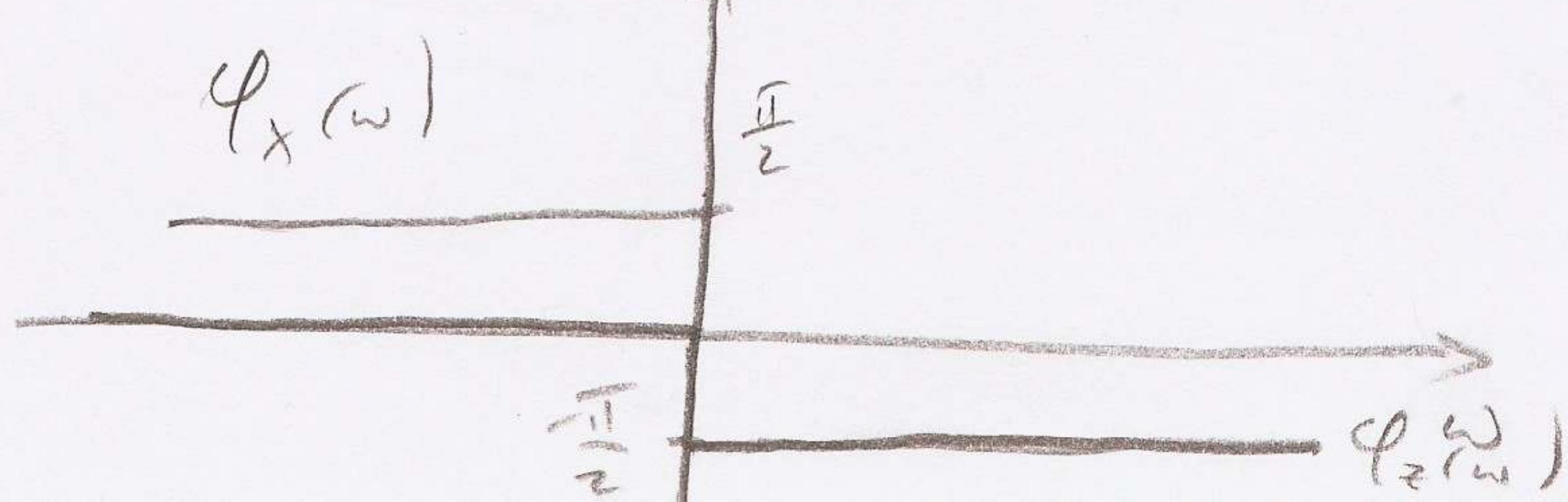
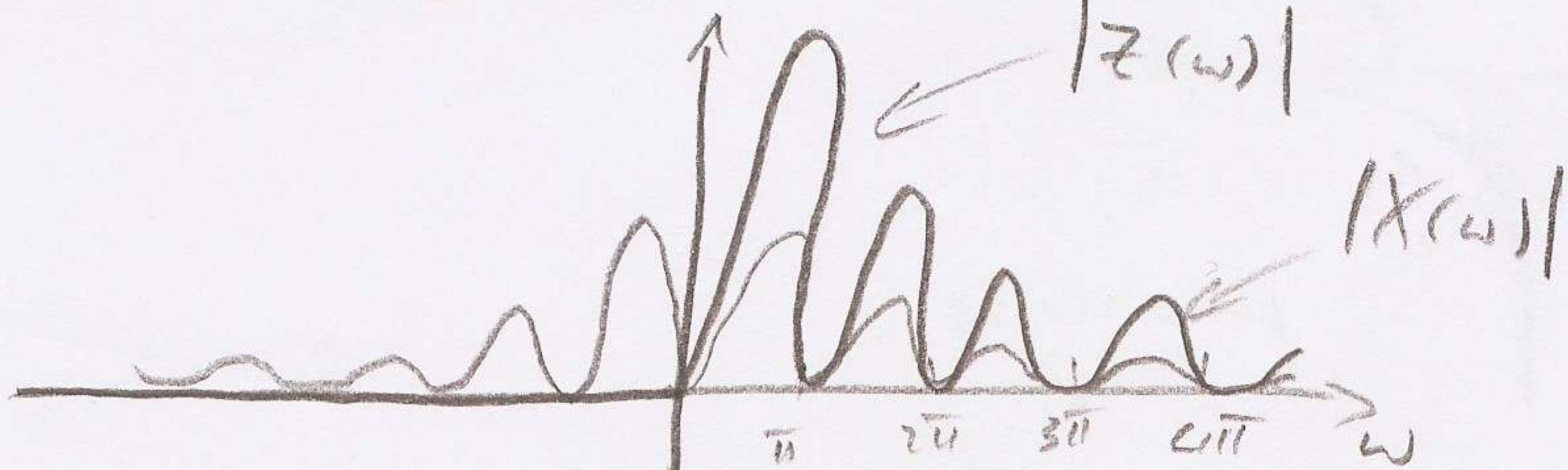
$z(\omega) = ?$

$$z(\omega) = \begin{cases} 0, & \omega < 0 \\ X(\omega), & \omega = 0 \\ 2X(\omega), & \omega > 0 \end{cases}$$

$$X(\omega) = \int_{-\infty}^{\infty} x(t) e^{-j\omega t} dt = -j2 \int_0^{\infty} \sin(\omega t) dt = j2 \frac{\omega(2\omega)}{\omega} \stackrel{\omega=0}{=} 0$$

\uparrow
neparmo $t-j\omega$

$$= -j2 \frac{1-\cos(2\omega)}{\omega} = 2 \frac{1-\cos(2\omega)}{\omega} e^{-j\frac{\pi}{2}}$$



3.

$$v_m(t) = \frac{\omega_f}{\pi} \sin(\omega_f t)$$

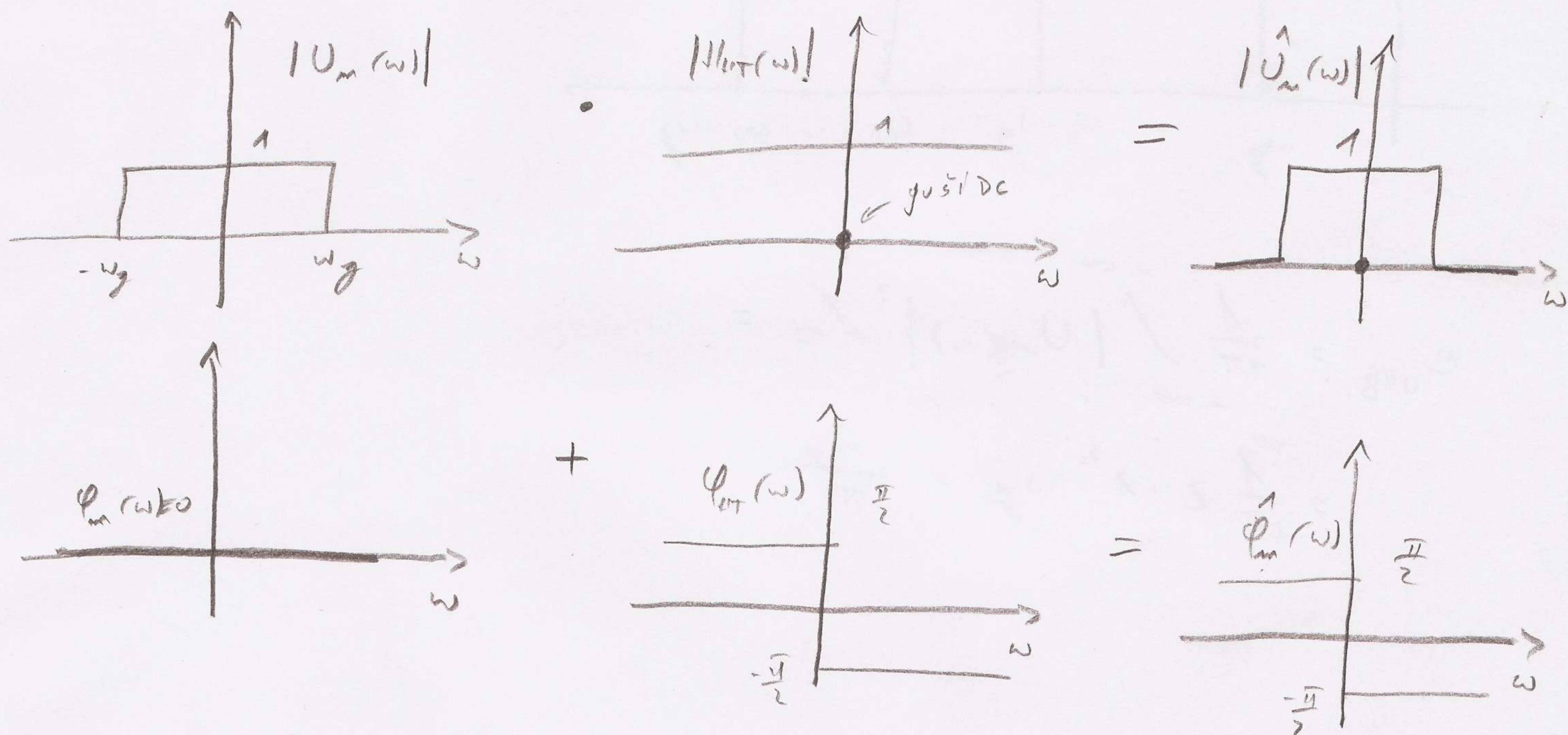
- $\frac{v_m(t)}{\omega_f t}$
NORMIRUNG -

$$u_{SSB}(t) = u_m(t) - \cos(\omega_0 t) \pm \frac{\hat{u}_m(t) \cdot \sin(\omega_0 t)}{\omega_0 t}$$

$$\hat{u}_m(t) = u_m(t) \neq \frac{1}{\pi f}$$

$$\hat{U}_m(\omega) = U_m(\omega) \cdot H_{HT}(j\omega) \quad (\text{neutrales Rad.})$$

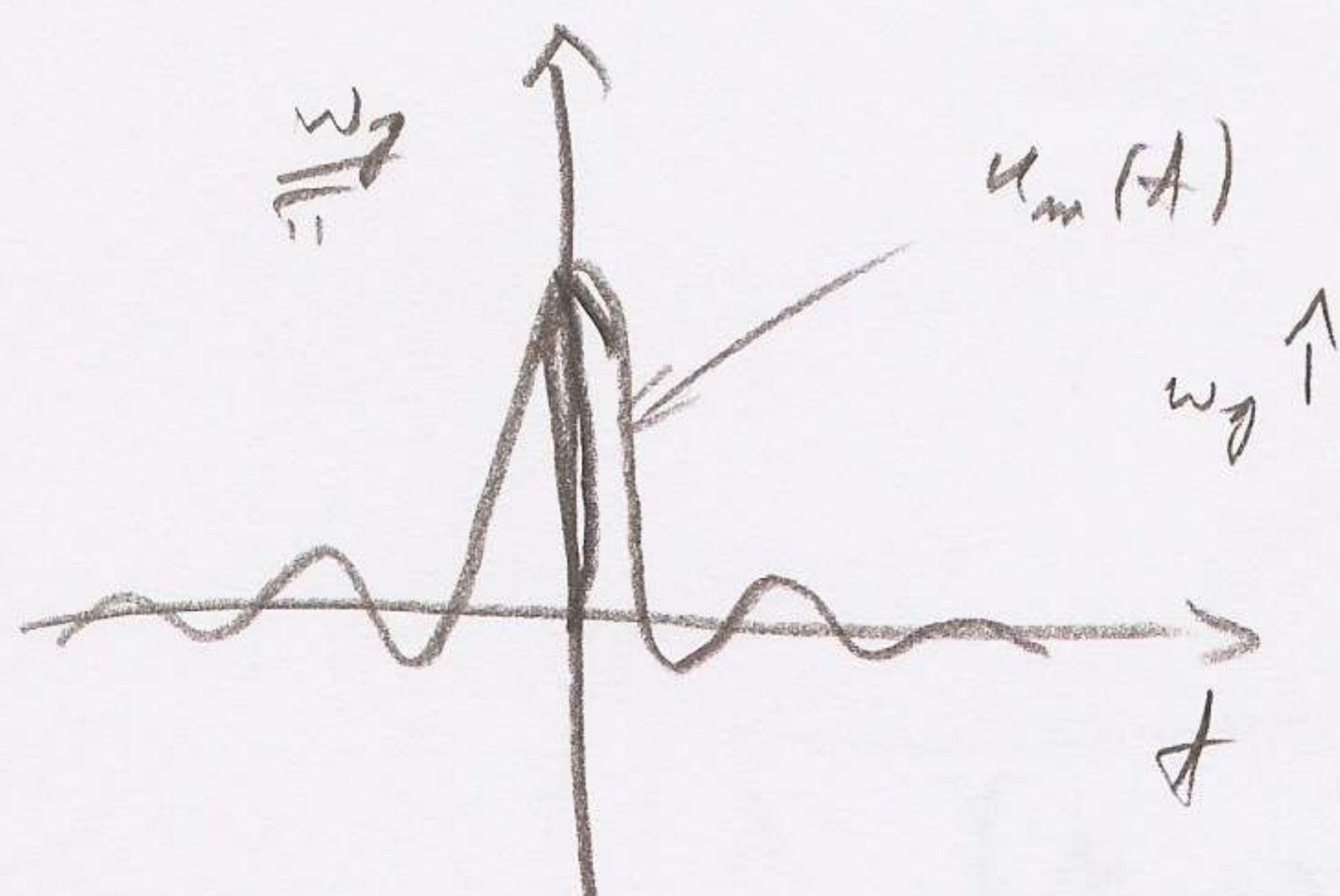
$$H_{HT}(\omega) = -j \operatorname{sgn}(\omega)$$



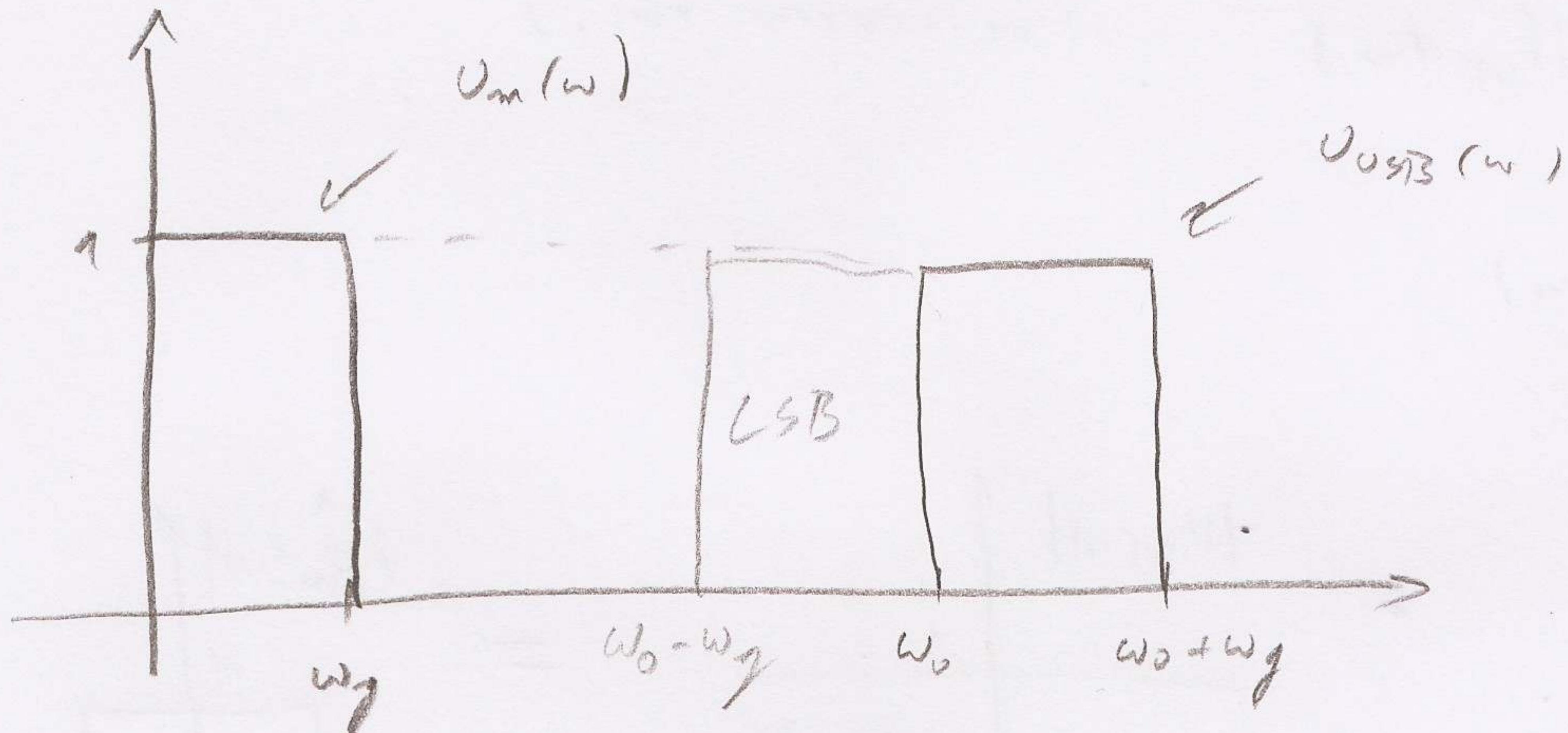
$$\hat{u}_m(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} \hat{U}_m(\omega) e^{j\omega t} d\omega =$$

$$= \frac{1}{2\pi} \left\{ \int_{-w_f}^0 1 \cdot e^{j\frac{\pi}{2}} \cdot e^{j\omega t} d\omega + \int_0^{w_f} 1 \cdot e^{-j\frac{\pi}{2}} \cdot e^{j\omega t} d\omega \right\} =$$

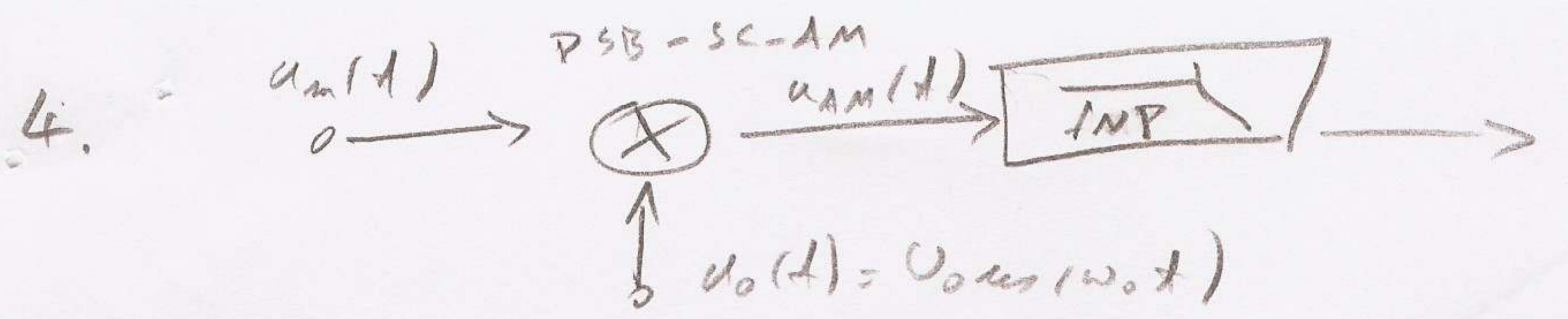
$$= \frac{1}{2\pi} \frac{1 - e^{-jw_f t} - e^{jw_f t} + 1}{j} = \frac{1 - \cos(w_f t)}{\pi f}$$



$$u_{USB}(t) = \frac{w_2}{\pi} \sin(w_2 t) \cos(\omega_0 t) - \frac{1 - \cos(w_2 t)}{\pi t} \sin(\omega_0 t)$$



$$e_{USB} = \frac{1}{2\pi} \int_{-\infty}^{+\infty} |U_{USB}(\omega)|^2 d\omega = \\ = \frac{1}{2\pi} 2 \cdot 1^2 \cdot w_2 = \frac{w_2}{\pi}$$



$$f_{NP} = 3.4 \text{ kHz} = f_Z$$

$$u_m(t) : f_I = 200 \text{ Hz}$$

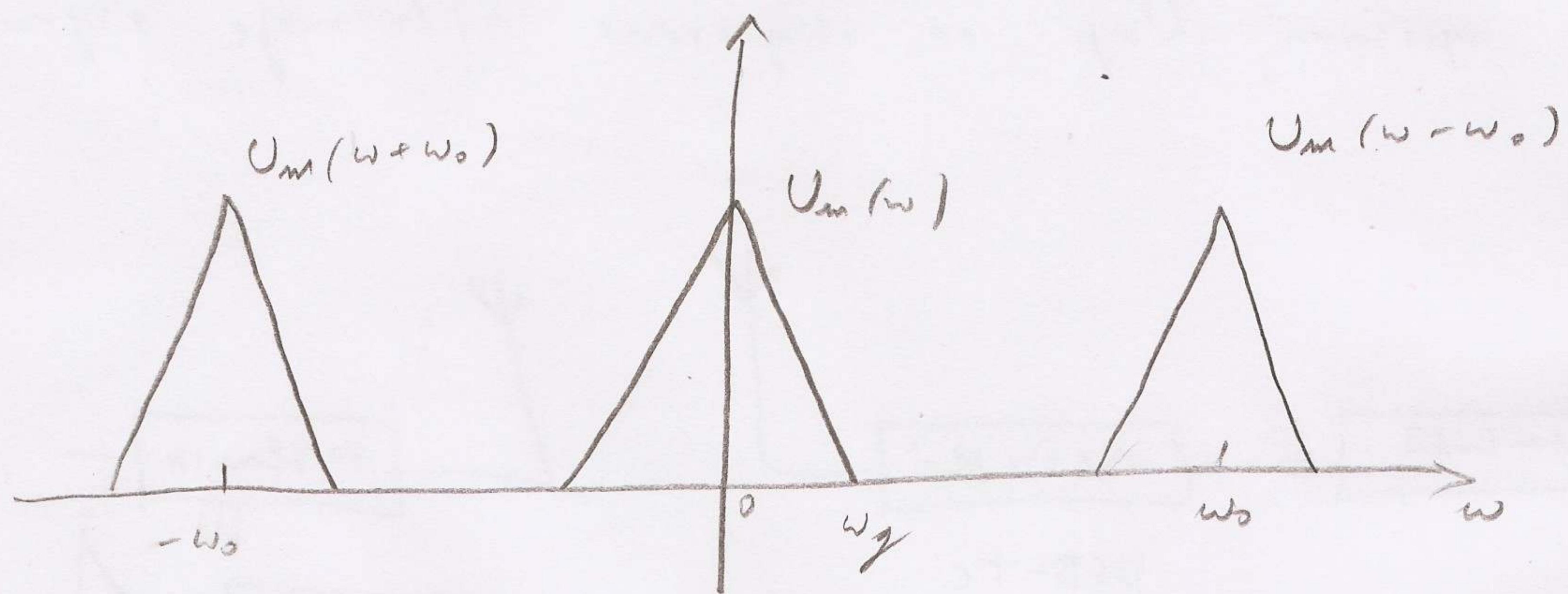
$$f_Z = 3.4 \text{ kHz}$$

$$f_0 = 3.6 \text{ kHz}$$

$$u_{AM}(t) = u_m(t) \cdot u_o(t) \Rightarrow U_{AM}(\omega) = \frac{1}{2\pi} U_m(\omega) * U_o(\omega)$$

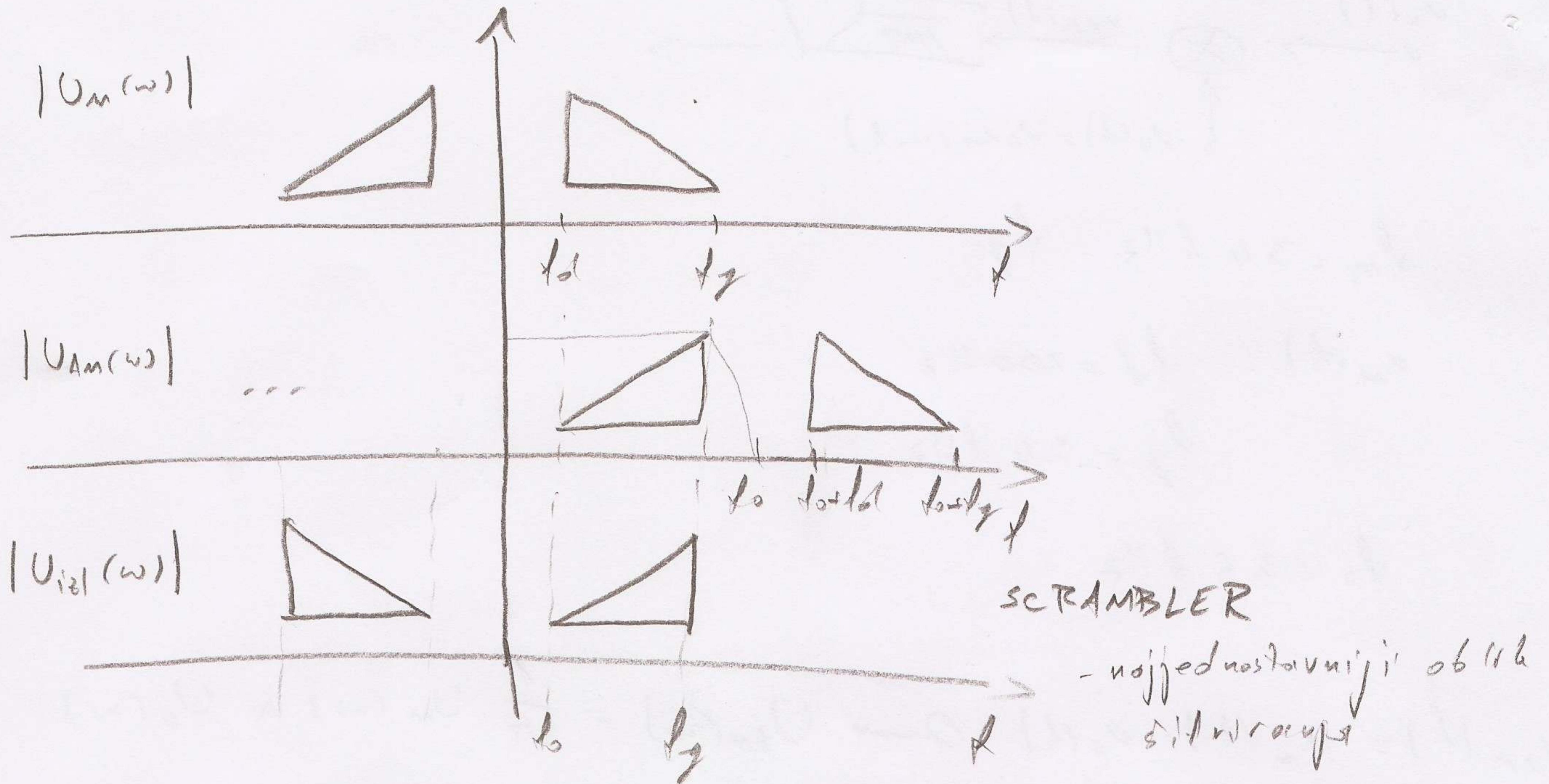
Izvod je na predavačju Pogl. 4.4.2.

$$U_{AM}(\omega) = \frac{U_0}{2} \left[U_m(\omega + \omega_0) + U_m(\omega - \omega_0) \right]$$

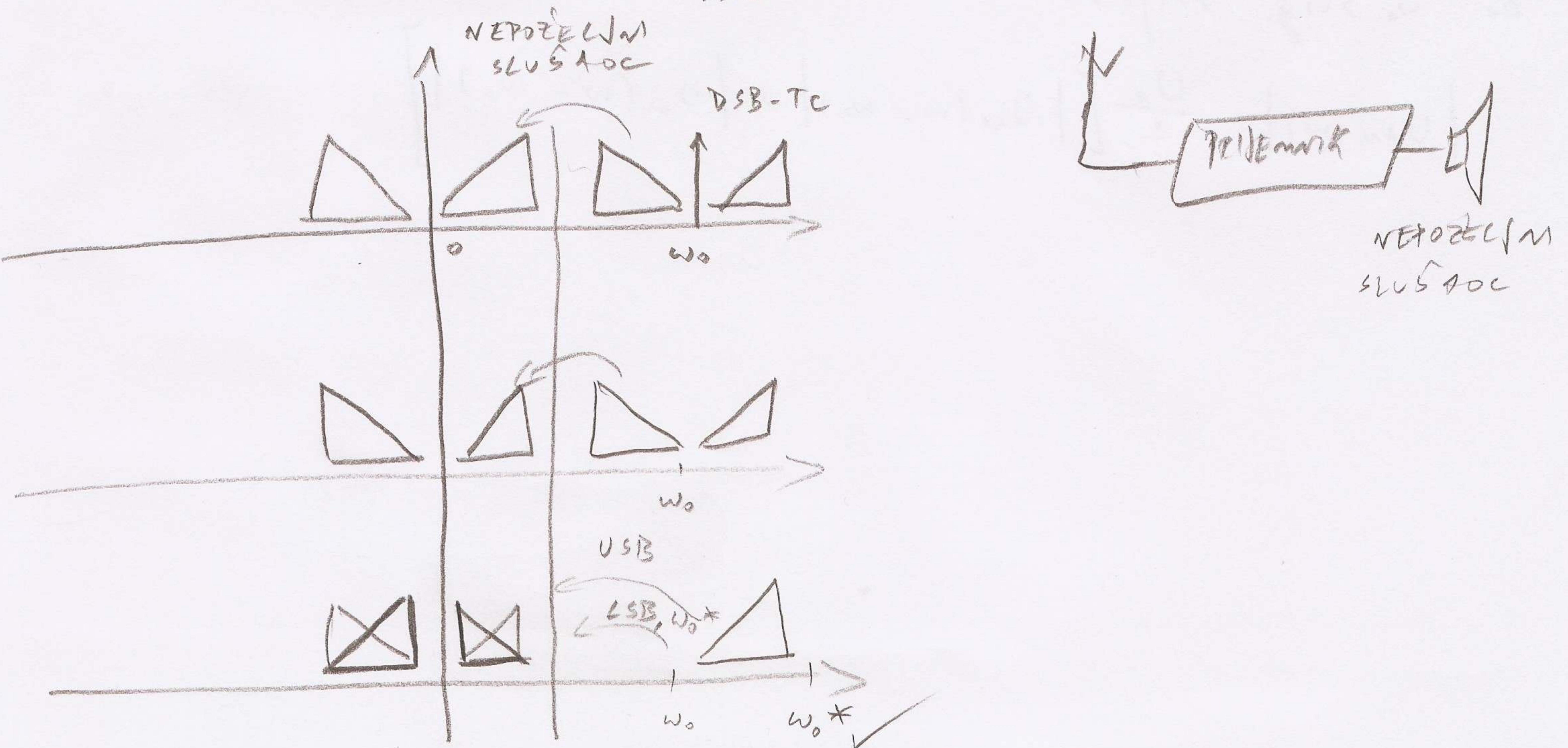
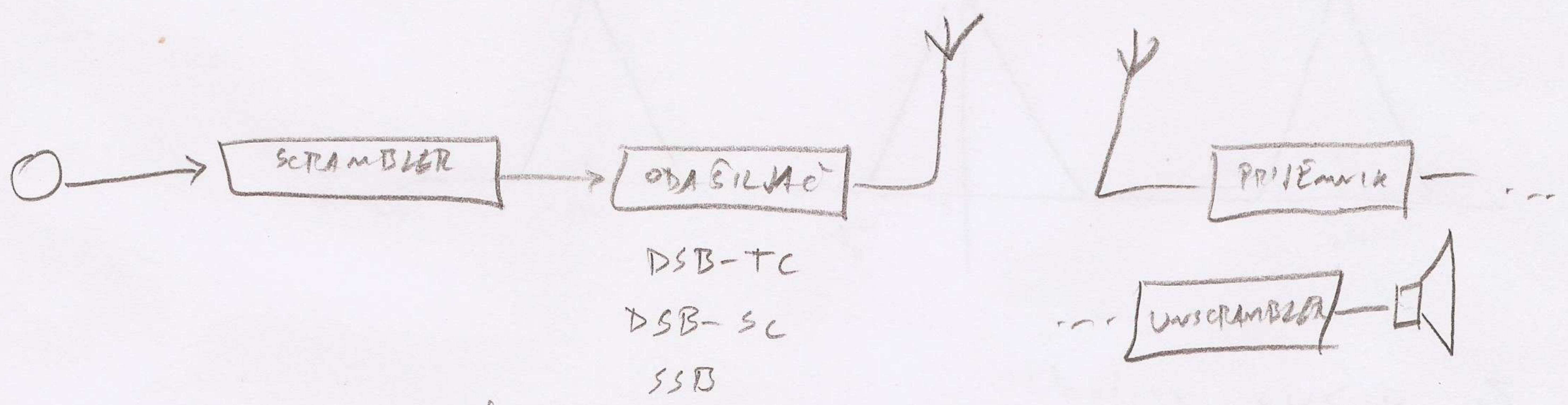


Za $\omega_0 > \omega_Z$ vrijedi!

$$|U_{AM}(\omega)| = \frac{U_0}{2} \left[|U_m(\omega + \omega_0)| + |U_m(\omega - \omega_0)| \right]$$

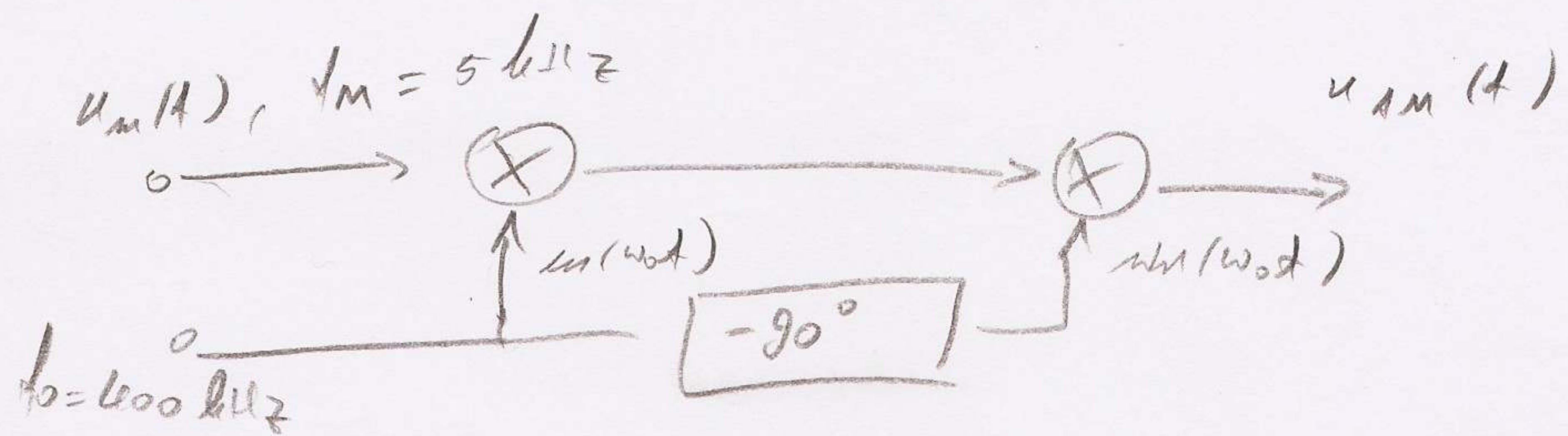


Pretpostavimo da je orakar sklop postavljen na vlast odosobljaku, te ma slobze programika koji su 3 tipa AM.
Objeva slučaje opisanog sklop ne osigurava slijednje signale i zastave?



Ako nep. sli. postavim frekvenciju na $\omega_0 + \Delta$ te postavim prihvajanje LSB kanala tako da opisani algoritam ne ostvaruje zadržavanje jer prilikom demodulacije dobijamo izvorni signal.

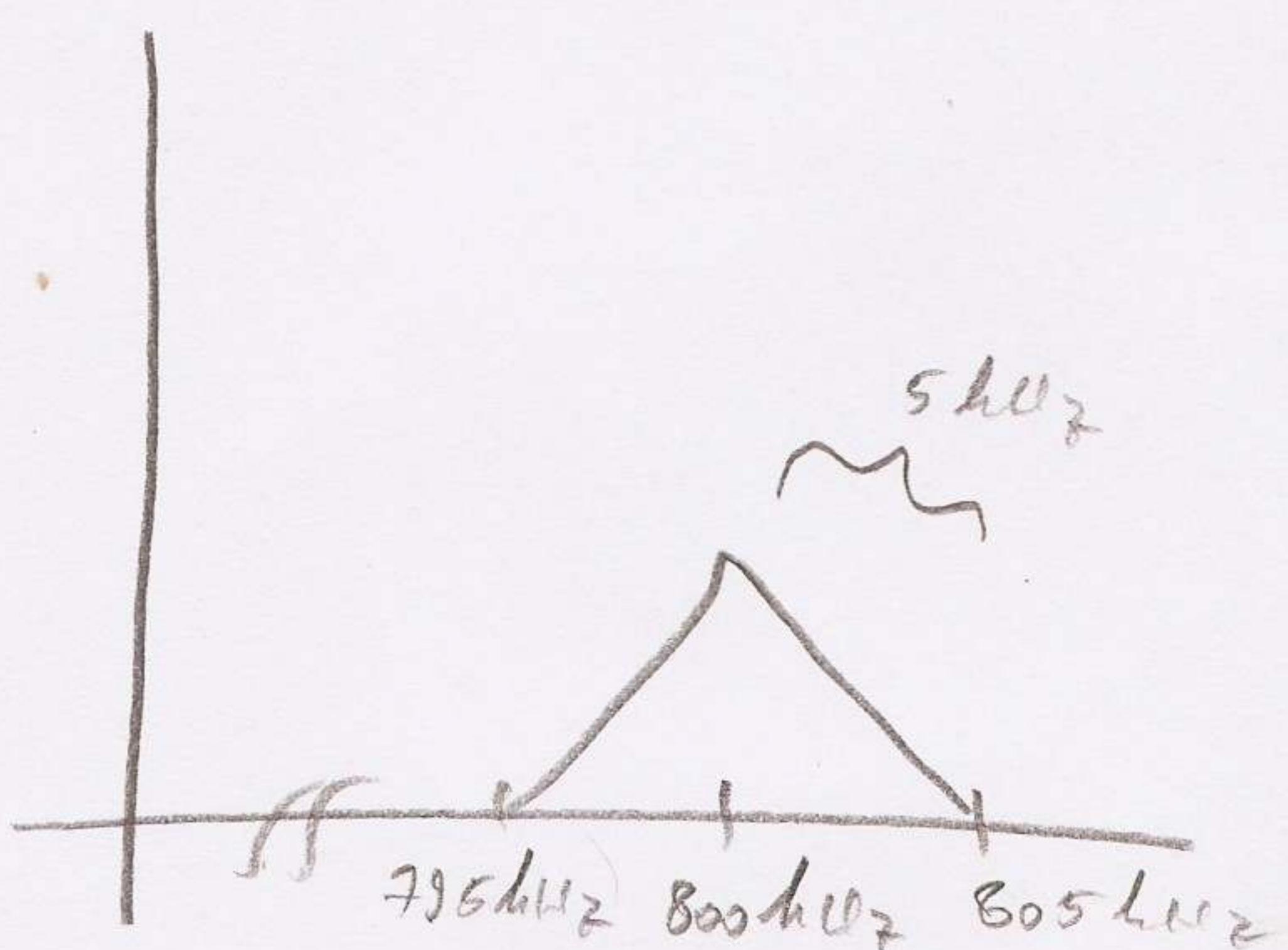
5. Prikazuje DSB-SC-demodulatora na frekv. $2f_0$



Određiti frekv. područje demod. signala

$$u_{AM}(t) = u_m(t) \cdot u_l(\omega_0 t) \cdot u_l(\omega_0 t) =$$

$$= \frac{1}{2} u_m(t) \sin(2\omega_0 t)$$



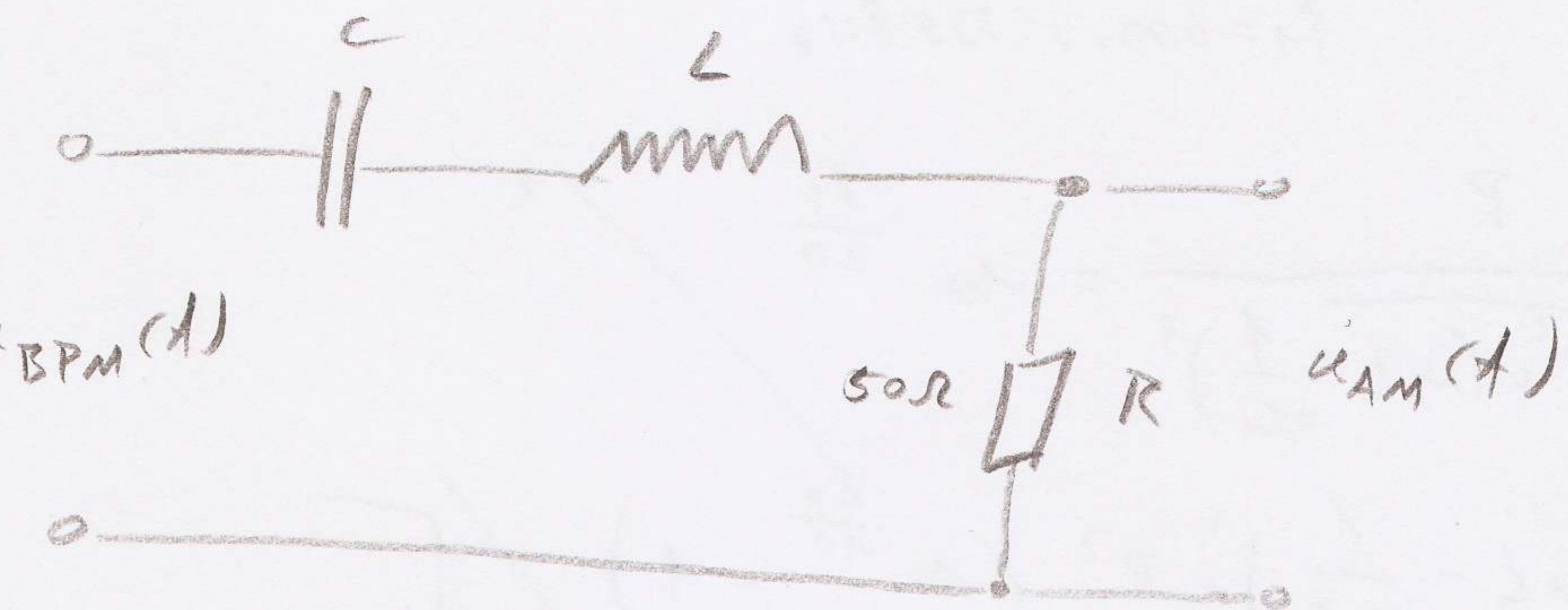
$$6. f_m = 5 \text{ kHz}$$

$$f_0 = 400 \text{ kHz}$$

$$A_p = 0.05 \text{ dB}$$

$$L, C = ?$$

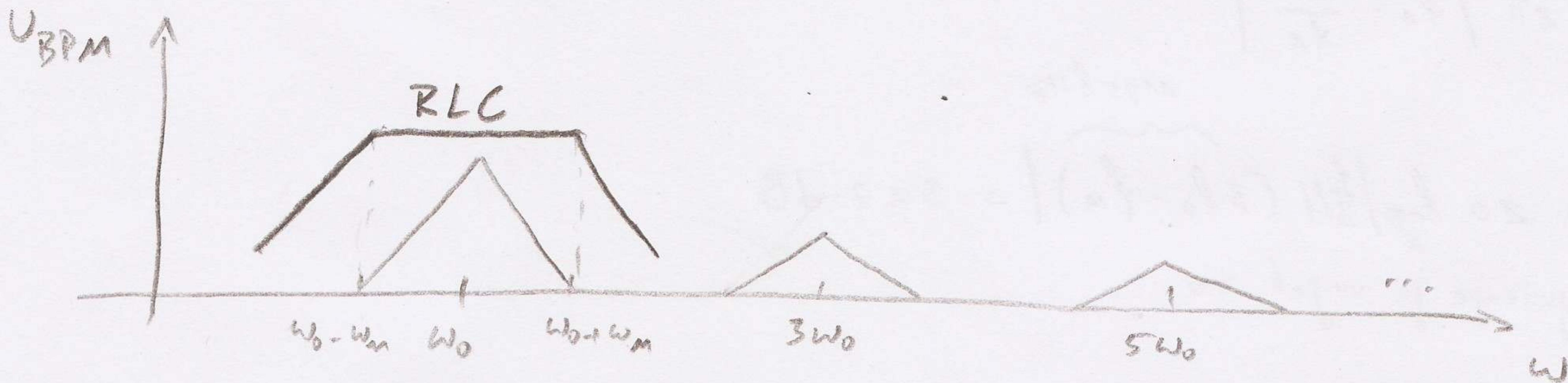
$$A_s = ?$$



$$u_{BPM}(t) = u_m(t) \cdot \operatorname{sgn}[U_0 \sin(\omega_0 t)]$$

$$= u_m(t) \cdot \operatorname{square}(\omega_0 t)$$

$$= \frac{4}{\pi} \left[\underbrace{u_m(t) \sin(\omega_0 t)}_{\text{DSB-SC-AM}} - \frac{1}{3} u_m(t) \sin(3\omega_0 t) + \frac{1}{5} \sin(5\omega_0 t) \pm \dots \right]$$



$$H(\omega) = \frac{R}{R + j(\omega L - \frac{1}{\omega C})}$$

$$= 0 \Rightarrow \omega_n = \frac{1}{\sqrt{LC}} = \omega_0 \Rightarrow$$

$$C = \frac{1}{6\pi^2 f_0^2 L}$$



$$20 \lg |H(f_0 - f_u)| \geq -A_p$$

$$f_1 = 600 - 5 = 395 \text{ Hz}$$

$$\frac{R}{\sqrt{R^2 + (\omega_1 L - \frac{1}{\omega_1 C})^2}} = 10^{-\frac{A_p}{20}}$$

$$(\omega_1 L - \frac{1}{\omega_1 C})^2 = R^2 (10^{\frac{A_p}{20}} - 1) / 5$$

$$L \cdot \left| \omega_1 - \frac{1}{\omega_1 LC} \right| = R \sqrt{10^{\frac{A_p}{20}} - 1}$$

$$\frac{\omega_0^2}{\omega_1} = 2\pi \frac{f_0^2}{f_1}$$

$$L = \frac{R \sqrt{10^{\frac{A_p}{20}} - 1}}{2\pi \left| f_1 - \frac{f_0^2}{\omega_1} \right|} = 85 \mu H \Rightarrow C = 1.8 \mu F$$

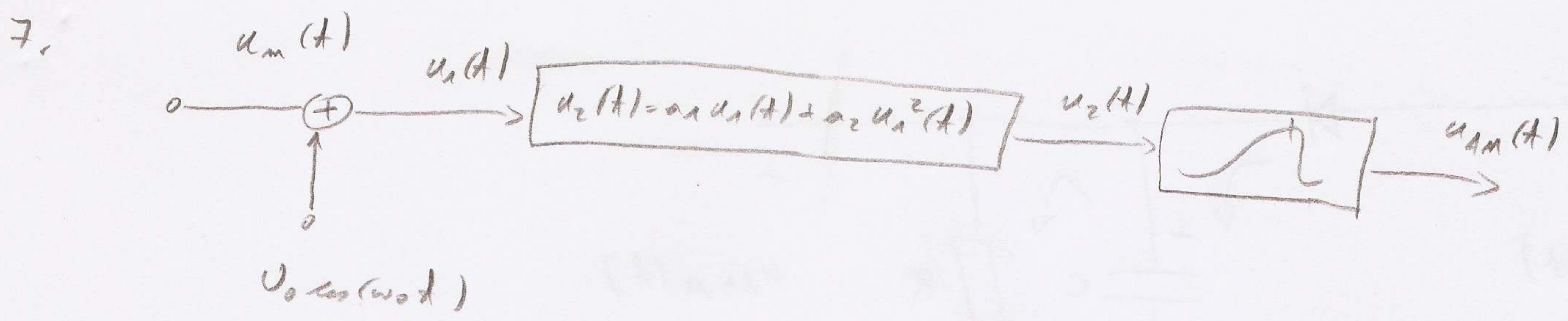
\approx

$$A_s = -20 \lg |H(3f_0 - f_u)| = 30.7 \text{ dB}$$

\approx

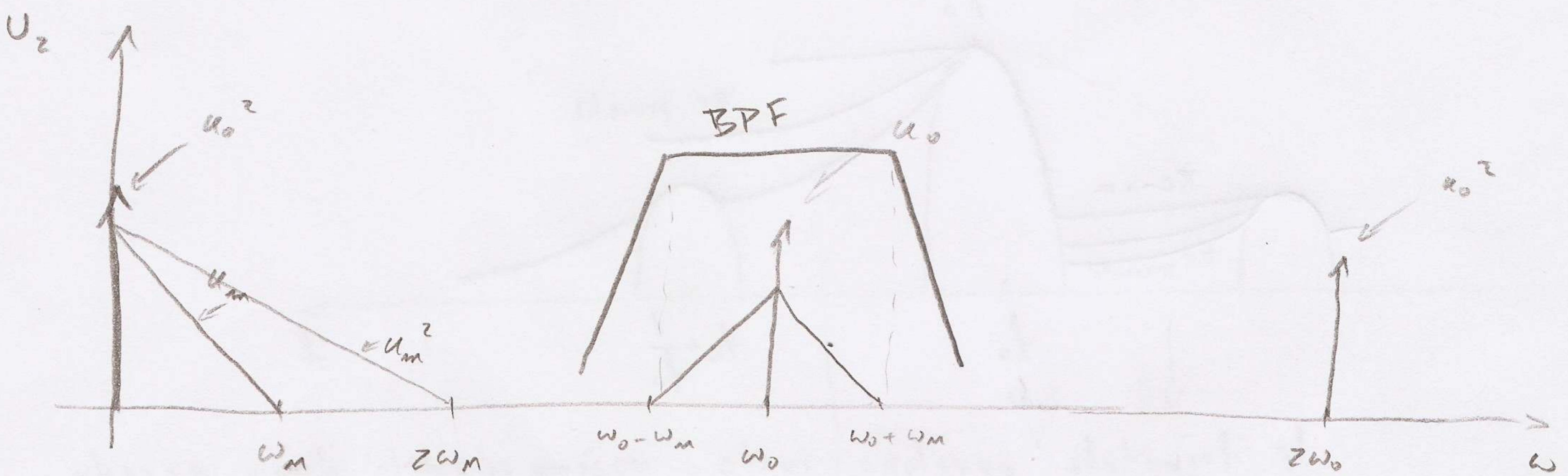
$f_0 = 395 \text{ Hz}$

$(\text{gusenje je uvijek} > 0)$



a) $u_1(t) = u_m(t) + U_0 \cos(\omega_0 t)$

$$u_2(t) = \alpha_1 u_m(t) + \alpha_1 U_0 \cos(\omega_0 t) + \alpha_2 u_m^2(t) + 2\alpha_2 U_0 u_m(t) \cos(\omega_0 t) + \underbrace{\alpha_2 U_0^2 \cos^2(\omega_0 t)}$$



b) BPF $[\omega_0 - \omega_m, \omega_0 + \omega_m]$

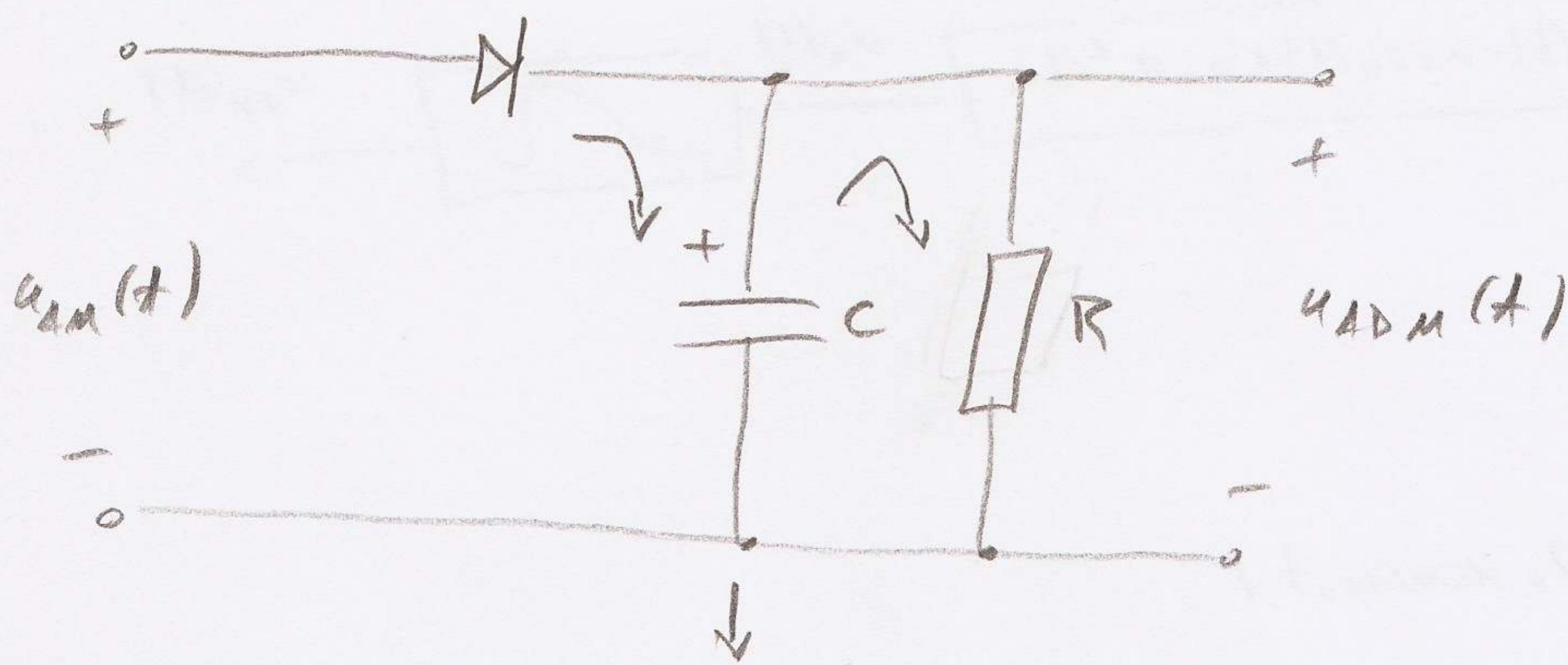
c) $u_{AM}(t) = \alpha_1 U_0 \cos(\omega_0 t) + 2\alpha_2 U_0 u_m(t) \cos(\omega_0 t)$

d) $u_{AM}(t) = [U_{0,AM} + K_a u_m(t)] \cdot \cos(\omega_0 t)$

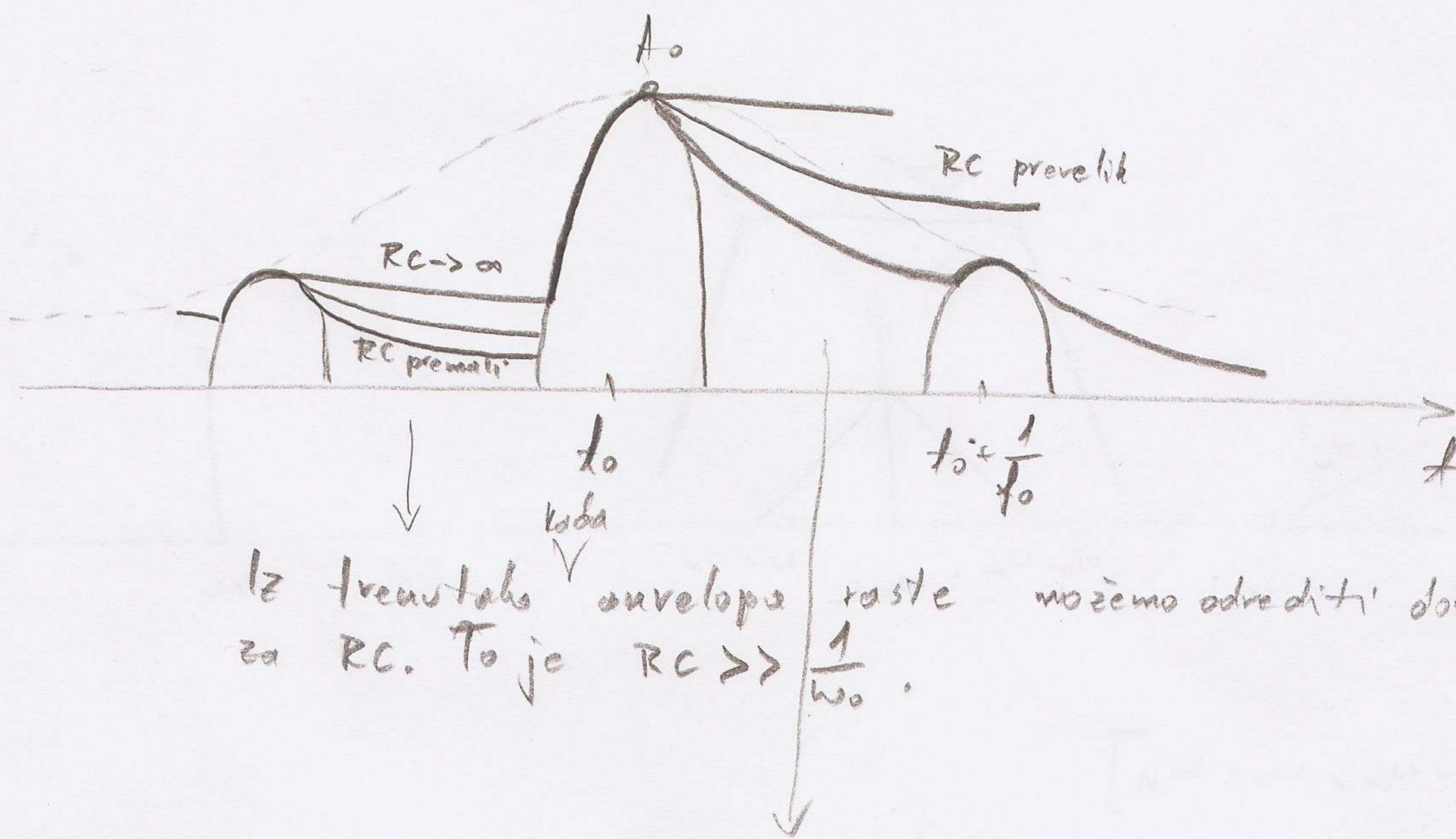
$$\Rightarrow U_{0,AM} = \alpha_1 U_0$$

$$K_a = 2\alpha_2 U_0$$

8.



C se tijekom početne poloperiode od $u_m(t)$ nabija, a vrijek se izbija preko R.



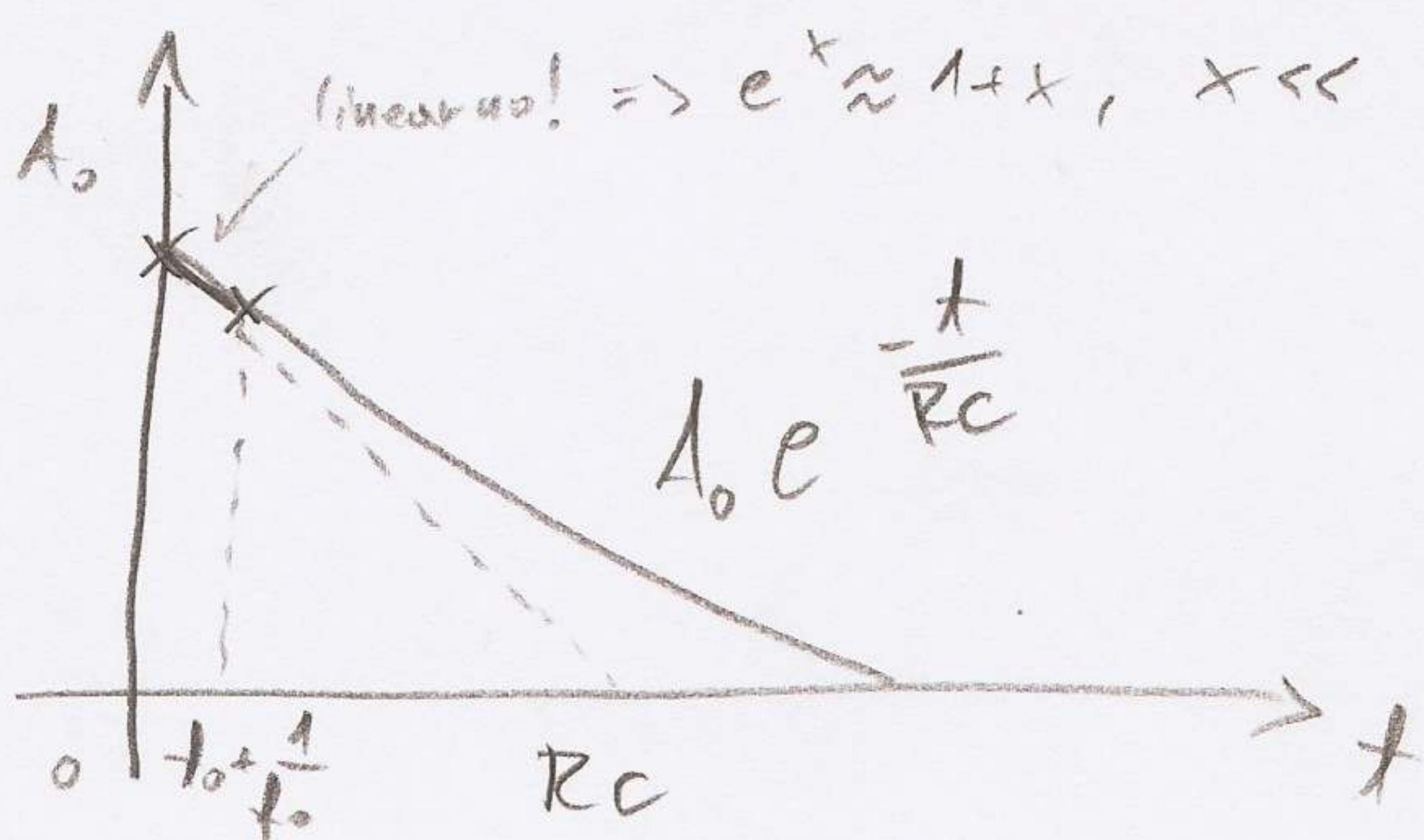
Iz trenutaka kada uvelopu za RC. To je $RC \gg \frac{1}{w_0}$.

Iz trenutaka kada uvelopu poda možemo odrediti gorujuću ogradi za RC.

$$u_m(t) = (U_0 + K_a u_m(t)) \cos(\omega_m t) = U_0 (1 + m \cdot \cos(\omega_m t)) \cos(\omega_m t)$$

$$U_m \cos(\omega_m t)$$

Pretpostavimo da se kondenzator izbija od maksimalne vrijednosti $A_0 = U_0(1 + m \cdot \cos(\omega_m t_0))$. Napomena RC članu je



$$u_{ADM}(t) = A_0 e^{-\frac{t-t_0}{RC}}$$

8. Za $RC \gg \frac{1}{\omega_0}$ vrijedi aproksimacija

$$u_{ADM}(t) \approx A_0 \left(1 - \frac{t-t_0}{RC} \right)$$

Napon na kondenzatoru ne smije preći maksimum u sljedećoj poloperiodi.

$$u_{ADM}(t_0 + \frac{1}{f_0}) \leq U_0 \left(1 + m \cdot \cos(\omega_m(t_0 + \frac{1}{f_0})) \right)$$

$$\underbrace{U_0 \left(1 + m \cdot \cos(\omega_m t_0) \right)}_{A_0} \cdot \left(1 - \frac{1}{RC f_0} \right) \leq U_0 \left[1 + \underbrace{m \cos \left(\omega_m t_0 + \frac{\omega_m}{f_0} \right)}_{\approx 1} \right]$$

$$\begin{aligned} \text{Za } \omega_m \ll \omega_0 \text{ vrijedi} &= m \cos(\omega_m t_0) \cos \left(\frac{\omega_m}{f_0} \right) - \\ &- m \sin(\omega_m t_0) \sin \left(\frac{\omega_m}{f_0} \right) \\ &\approx \frac{\omega_m}{f_0} \end{aligned}$$

$$\sqrt{m \cdot \cos(\omega_m t_0) - \frac{1}{RC f_0} (1 + m \cdot \cos(\omega_m t_0))} \leq \sqrt{m \cos(\omega_m t_0)} - \frac{m \omega_m}{f_0} \sin(\omega_m t_0)$$

$$\frac{1}{RC} + \frac{m}{RC} \cos(\omega_m t_0) \geq m \omega_m \sin(\omega_m t_0)$$

$$\frac{1}{RC} \geq m \left(\omega_m \sin(\omega_m t_0) - \frac{1}{RC} \cos(\omega_m t_0) \right)$$

$$a \sin(\varphi) + b \cos(\varphi) \leq \sqrt{a^2 + b^2}$$

$$\leq \sqrt{\omega_m^2 + \left(\frac{1}{RC} \right)^2}$$

$$\frac{1}{RC} \geq m \sqrt{\omega_m^2 + \left(\frac{1}{RC} \right)^2}$$

$$RC \leq \frac{1}{\omega_m} \frac{\sqrt{1-m^2}}{m}$$

$$RC \gg \frac{1}{\omega_0}$$

$$\text{Tu: } f_m = 38 \text{ Hz}, f_0 = 1 \text{ MHz}, m = 0.9$$

$$RC \gg 1.6 \cdot 10^{-7} \text{ s}, RC \leq 2.6 \cdot 10^{-5} \text{ s}$$

$$9. \quad U_0 = 1.5 \text{ V}$$

$$f_0 = 1 \text{ MHz}$$

$$f_m = 5 \text{ kHz}$$

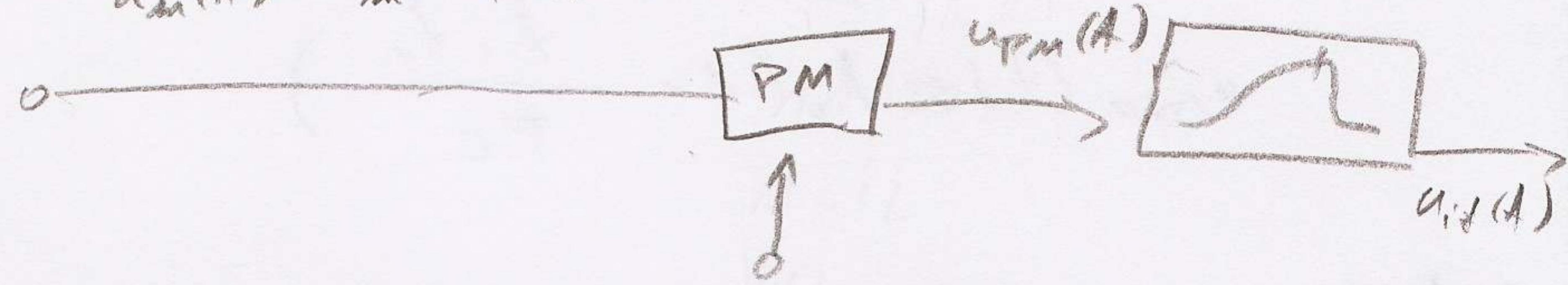
$$\Delta \phi = 0.5 \text{ rad} \Rightarrow m = 0.5$$

$$f_c = 1 \text{ MHz} = f_0$$

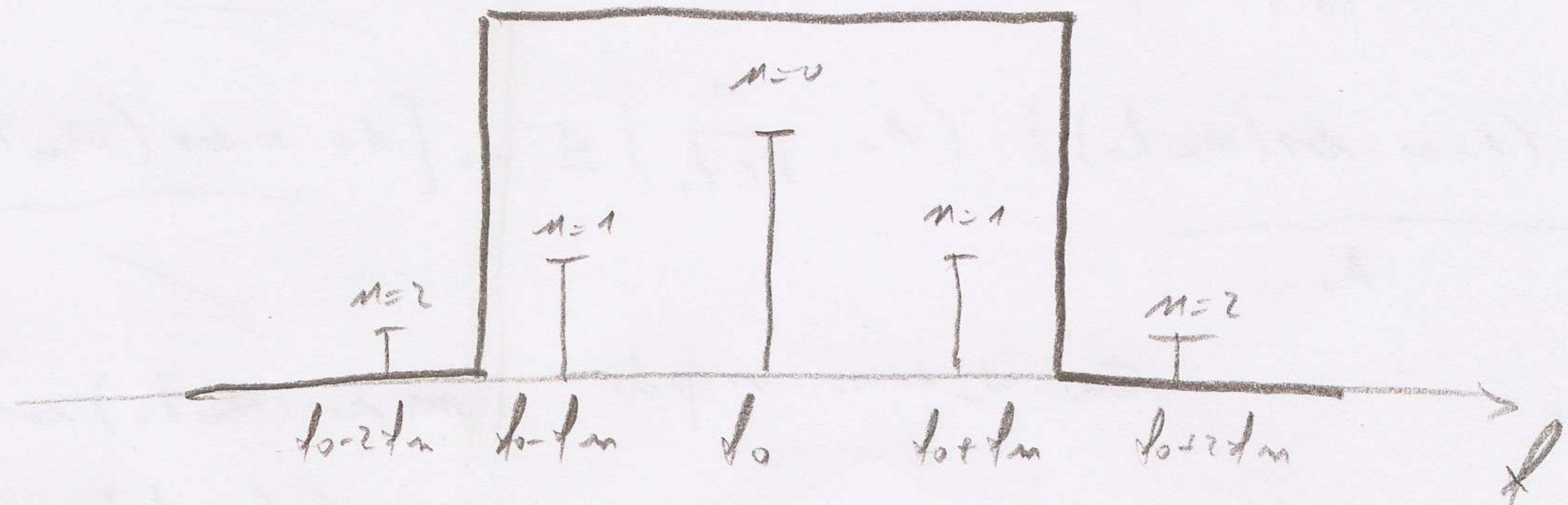
$$B = 15 \text{ kHz}$$

$$m_{AM} = ?$$

$$u_m(t) = U_m \cos(\omega_m t)$$



$$u_0(t) = U_0 \cos(\omega_0 t)$$



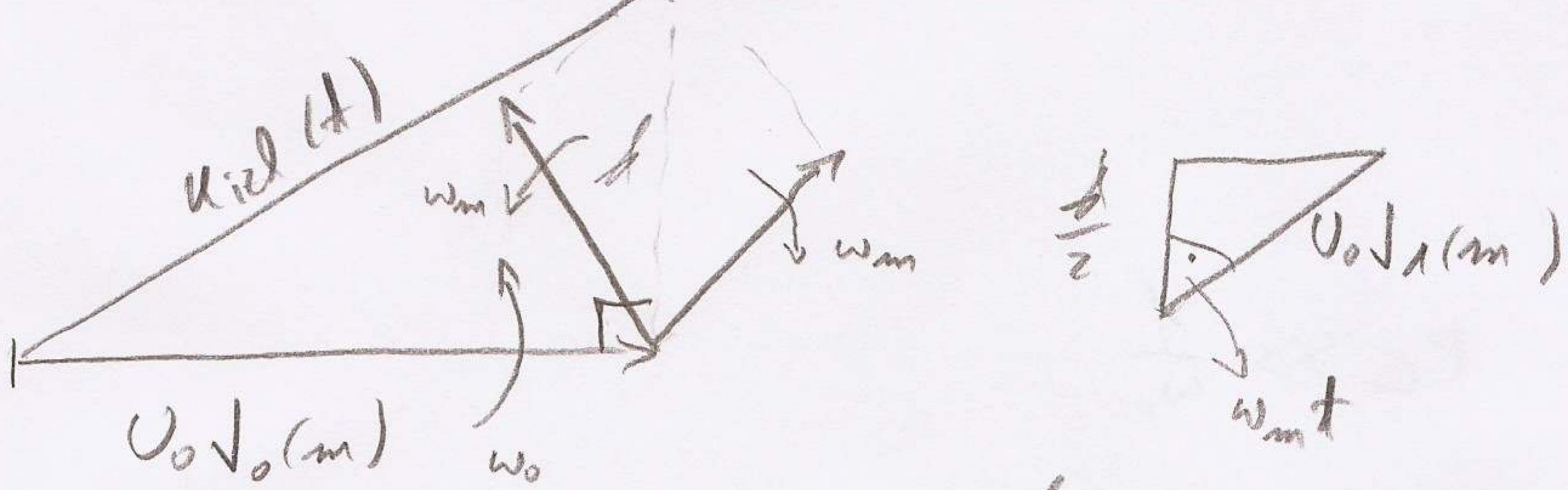
$$u_{PM}(t) = U_0 \cos[\omega_0 t + K_p u_m(t)] = U_0 \cos(\omega_0 t + m \cdot \cos(\omega_m t))$$

$$m = K_p / |u_m(t)|_{\max}$$

No preduvrađjimo je izvedeno

$$u_{PM}(t) = U_0 J_0(m) \cos(\omega_0 t) + U_0 \sum_{n=1}^{\infty} J_n(m) \left\{ \cos[(\omega_0 - n\omega_m)t + \frac{m\pi}{2}] + \cos[(\omega_0 + n\omega_m)t + \frac{m\pi}{2}] \right\}$$

$$u_{iel}(t) = U_0 J_0(m) \cos(\omega_0 t) + U_0 J_1(m) \cos[\omega_0 t - \frac{\pi}{2} - \omega_m t] + U_0 J_1(m) \cos[\omega_0 t + \frac{\pi}{2} + \omega_m t]$$



$$\delta = 2 U_0 J_1(m) \cos(\omega_m t)$$

9.

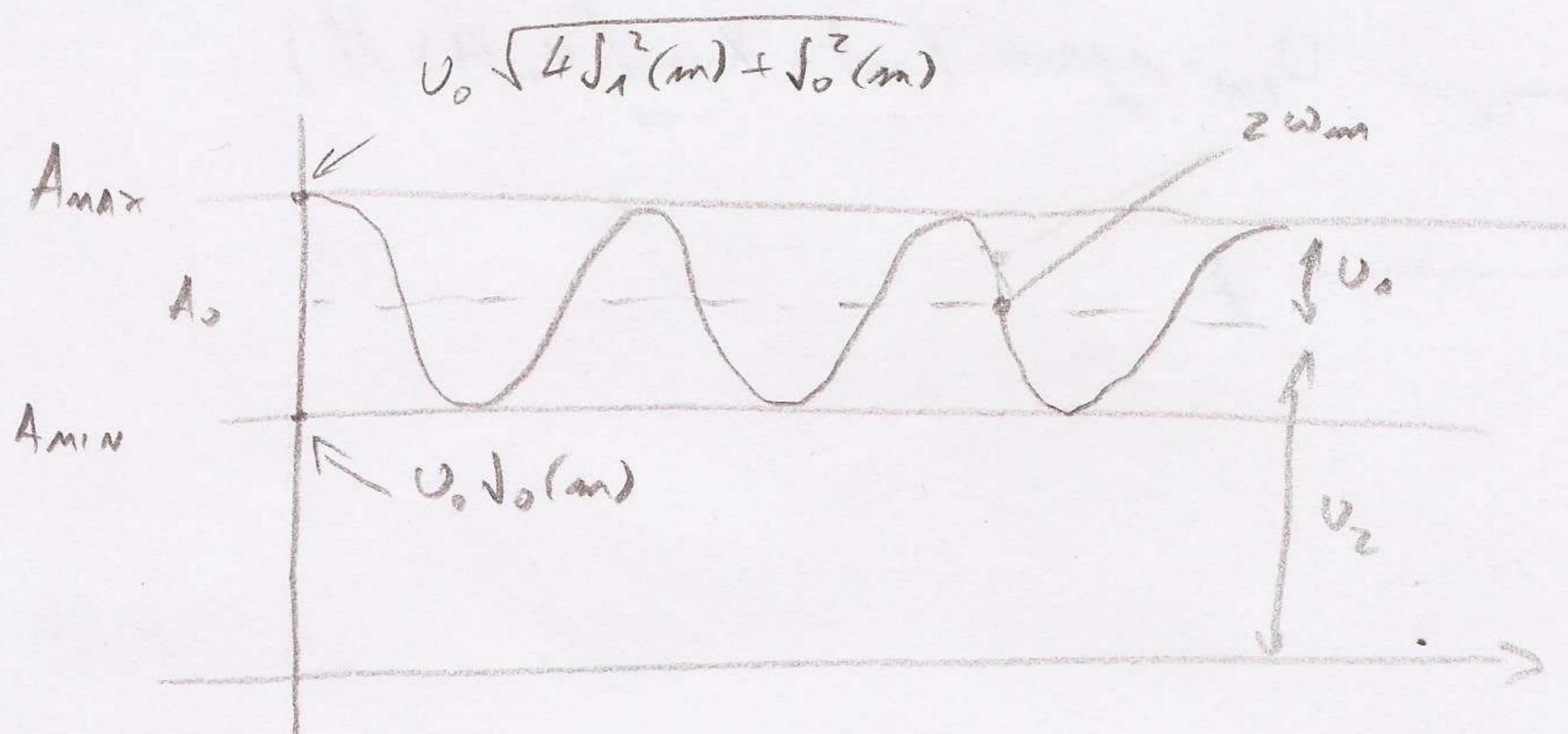
Konvelupa (t) = envelope od $u_{i2}(t)$

$$= \sqrt{J_1^2 + U_0^2 J_0^2(m)}$$

$$= U_0 \sqrt{4 J_1^2(m) \sin^2(\omega_m t) + J_0^2(m)} \\ = \underbrace{\frac{1}{2} + \frac{1}{2} \cos(2\omega_m t)}$$

$$= U_0 \sqrt{2 J_1^2(m) \cos(2\omega_m t) + 2 J_1^2(m) + J_0^2(m)}$$

↳ PARAZITNA AM!



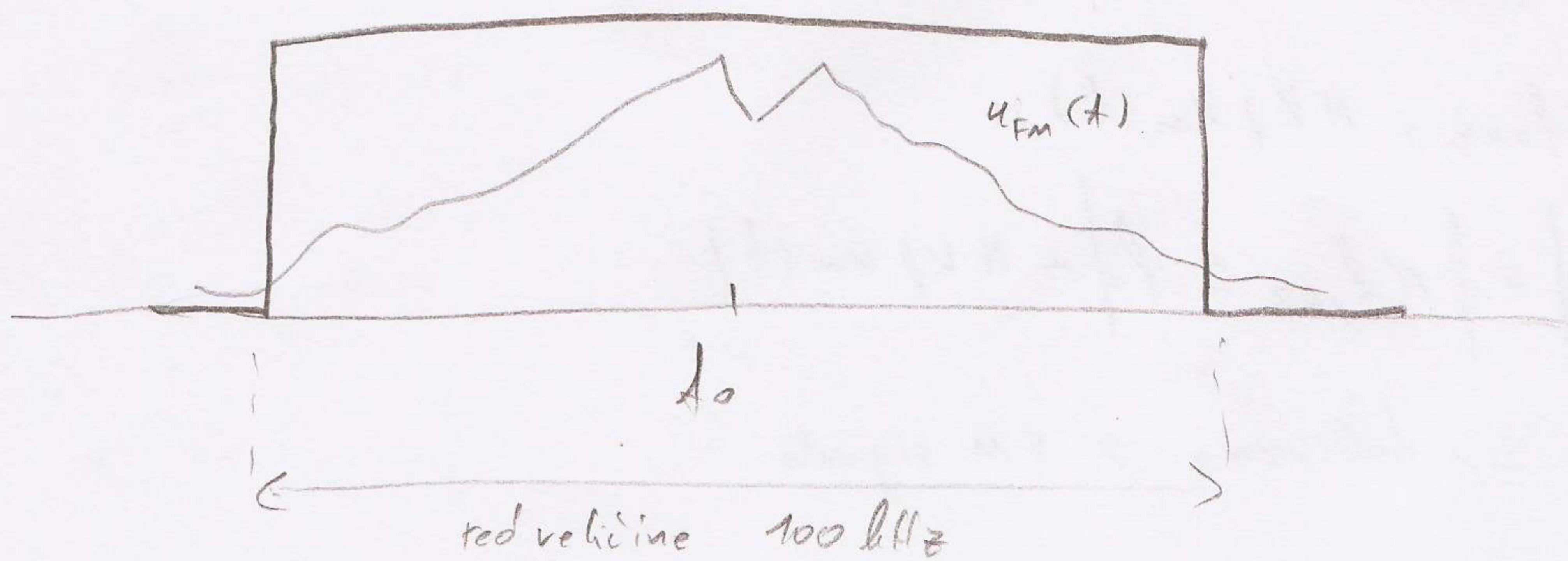
$$m_{AM} = \frac{U_1}{U_2} = \frac{A_{max} - A_0}{A_0}$$

$$A_0 = \frac{A_{max} + A_{min}}{2}$$

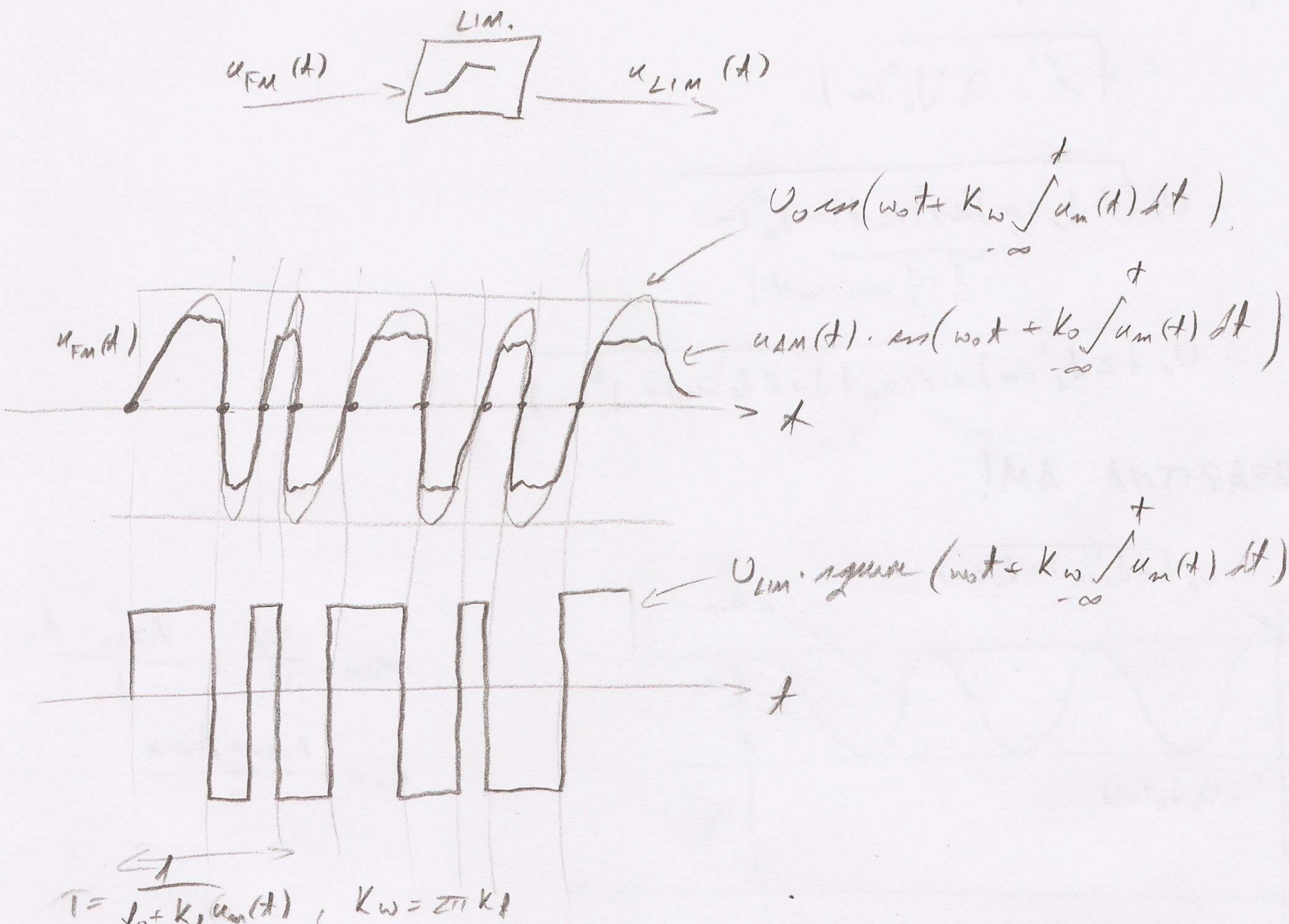
$$m_{AM} = \left| \frac{\sqrt{4 J_1^2(m) + J_0^2(m)} - J_0(m)}{\sqrt{4 J_1^2(m) + J_0^2(m)} + J_0(m)} \right| = \begin{cases} J_0(0.5) = 0.32 \\ J_1(0.5) = 0.26 \end{cases}$$

$$m_{AM} = 0.07$$

Ograničenje beskonačnog spektra FM signala utroškuje pojuru PARZITNE AM koja se u postupku demodulacije uklanja limiterima (realni demodulator) i dijelilom (kompleksni modulator).



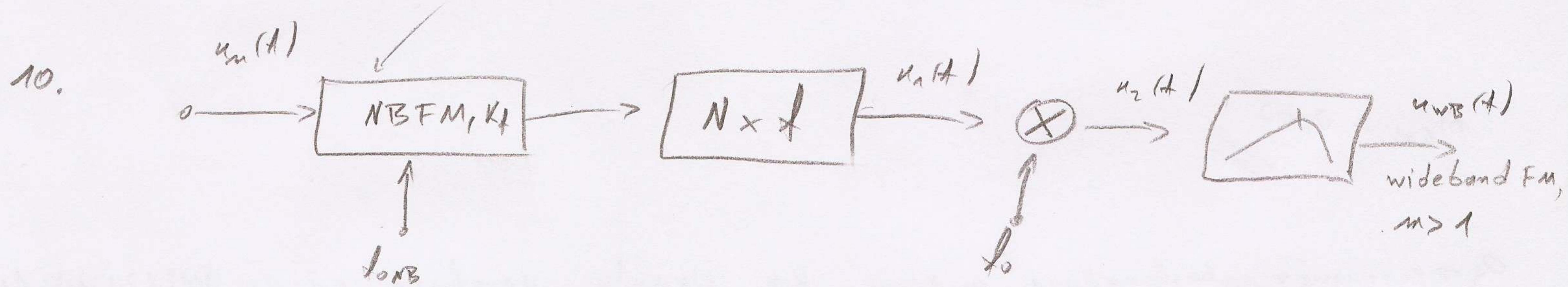
6 postupku demodulacije



$$T = \frac{1}{1 + K_F u_m(t)}, \quad K_W = 2\pi K_F$$

$u_{m, rec}(t)$ je FM signal kod kojeg je signal nosilaca pravokutnog valnog oblikov.

narrowband FM, $m < 1$



$$u_m(t) : f_m = 15 \text{ kHz}$$

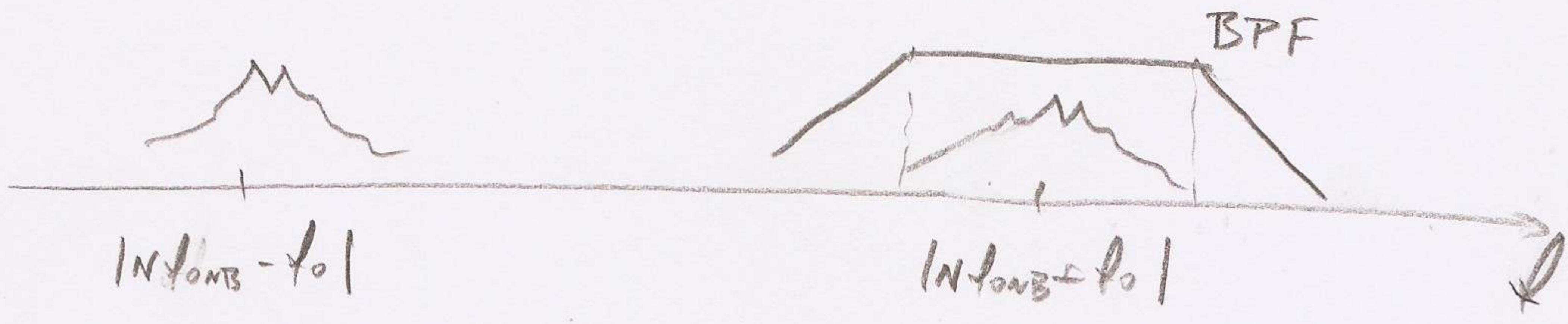
$$u_{NB}(t) : f_{NB} = f_{onB} + K_F \cdot u_m(t), \quad \Delta f_{NB} = K_F \cdot |u_m(t)|_{max} = 3 \text{ kHz} \cdot 0.5 = 1.5 \text{ kHz}$$

$$u_1(t) : f_1 = N f_{NB} = N f_{onB} + N K_F u_m(t)$$

$$u_2(t) : f_2 = |f_1 \pm f_0| = |N f_{onB} \pm f_0| + N K_F u_m(t)$$

\Rightarrow dobivamo 2 FM signala

10.



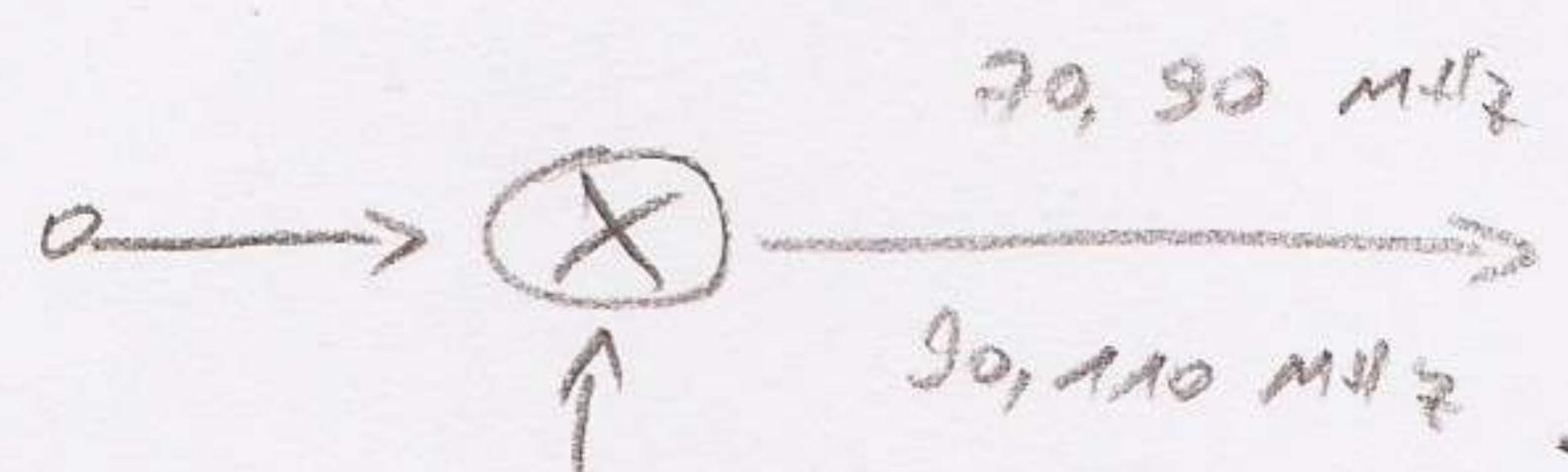
$$\Delta \rho_{WB} = N K_1 |u_m(t)|_{\max} = N \Delta x_{WB}$$

$$\Rightarrow N = \frac{\Delta \gamma_{WB}}{\Delta \gamma_{NB}} = \frac{75}{1.5} = 50 //$$

$$|N_{\gamma_{\text{onB}} \pm \gamma_0}| = \gamma_{\text{onB}} = 90 \text{ mHz}$$

↓ ↓
50.200

$$= 10 \text{ mHz}$$



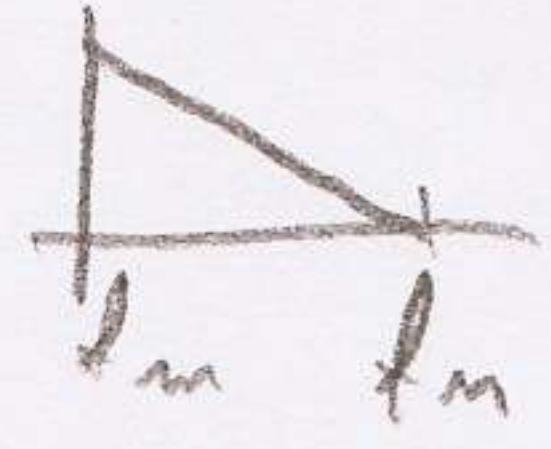
$$V_0 = 80 \text{ MHz}$$

115 - 1000 April 2

$$u_{WB}(t); \quad y_{WB} = N_{\text{donB}} + \phi_0 + N k_F u_m(t)$$

BPF :

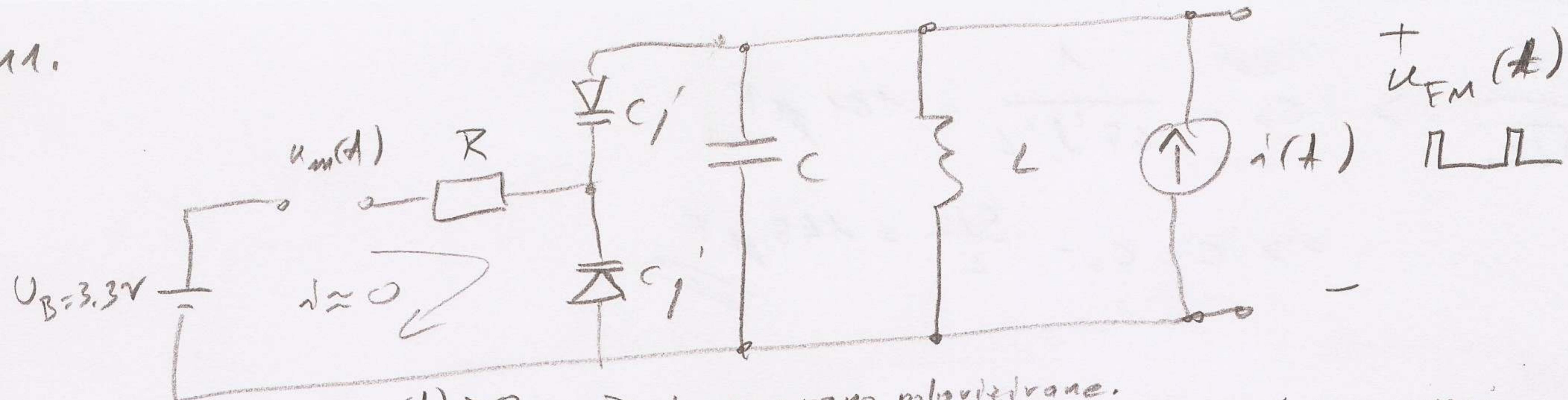
$$B = 2 \sum_{m=1}^{\infty} l_m(m+1) = 2(\Delta l + l_m)$$



$$B = 2 \cdot (75 Hz + 15 Hz) = 180 Hz$$

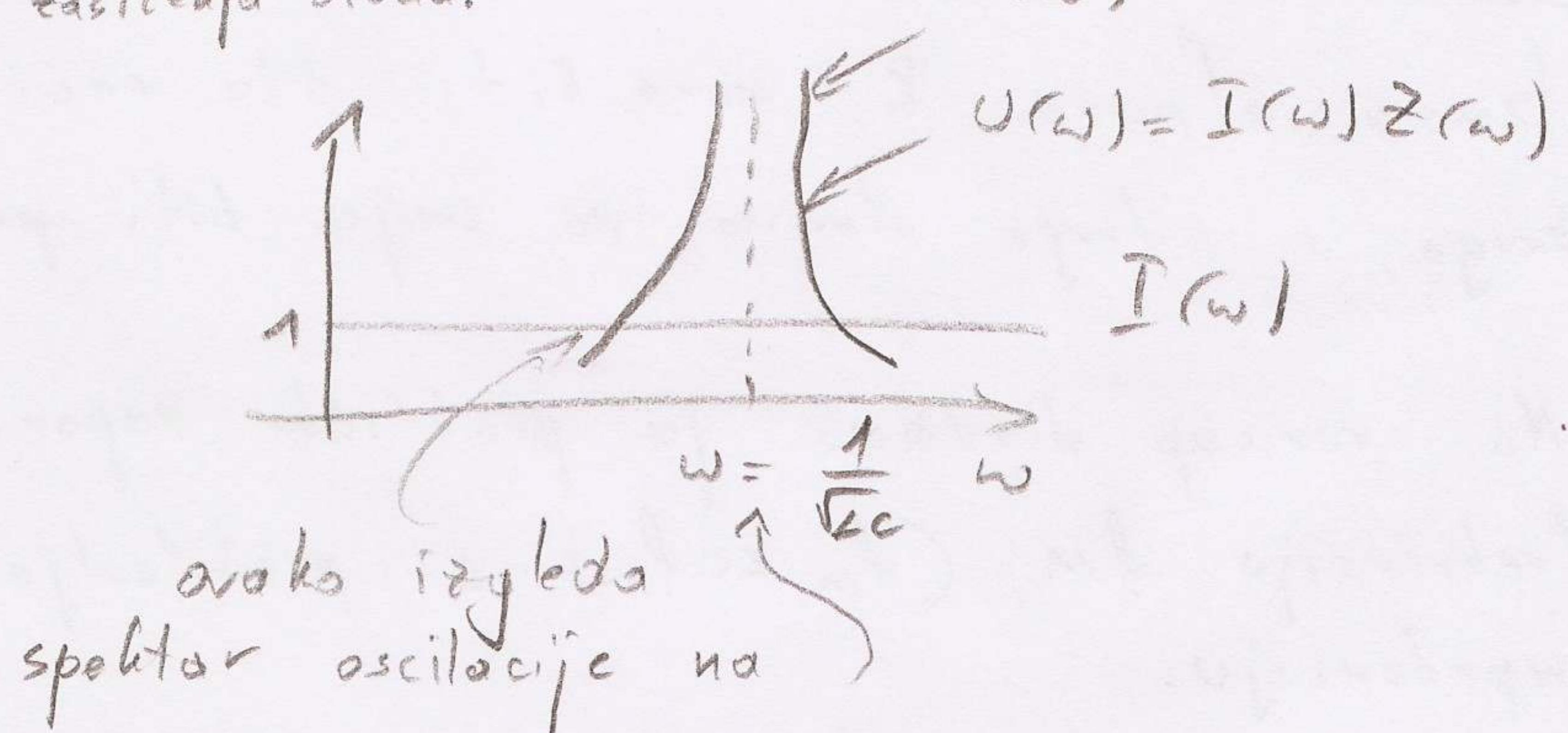
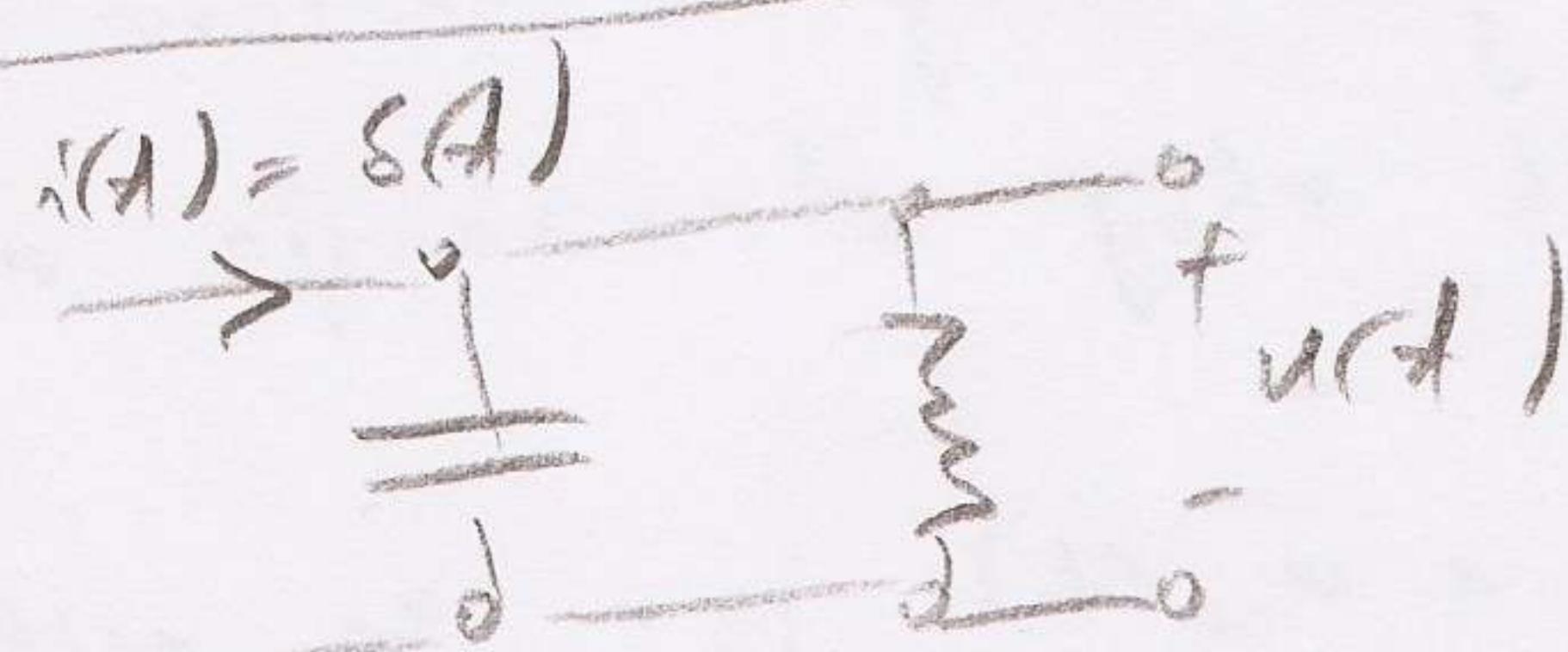
$$f_c = 90 \text{ MHz}$$

11.

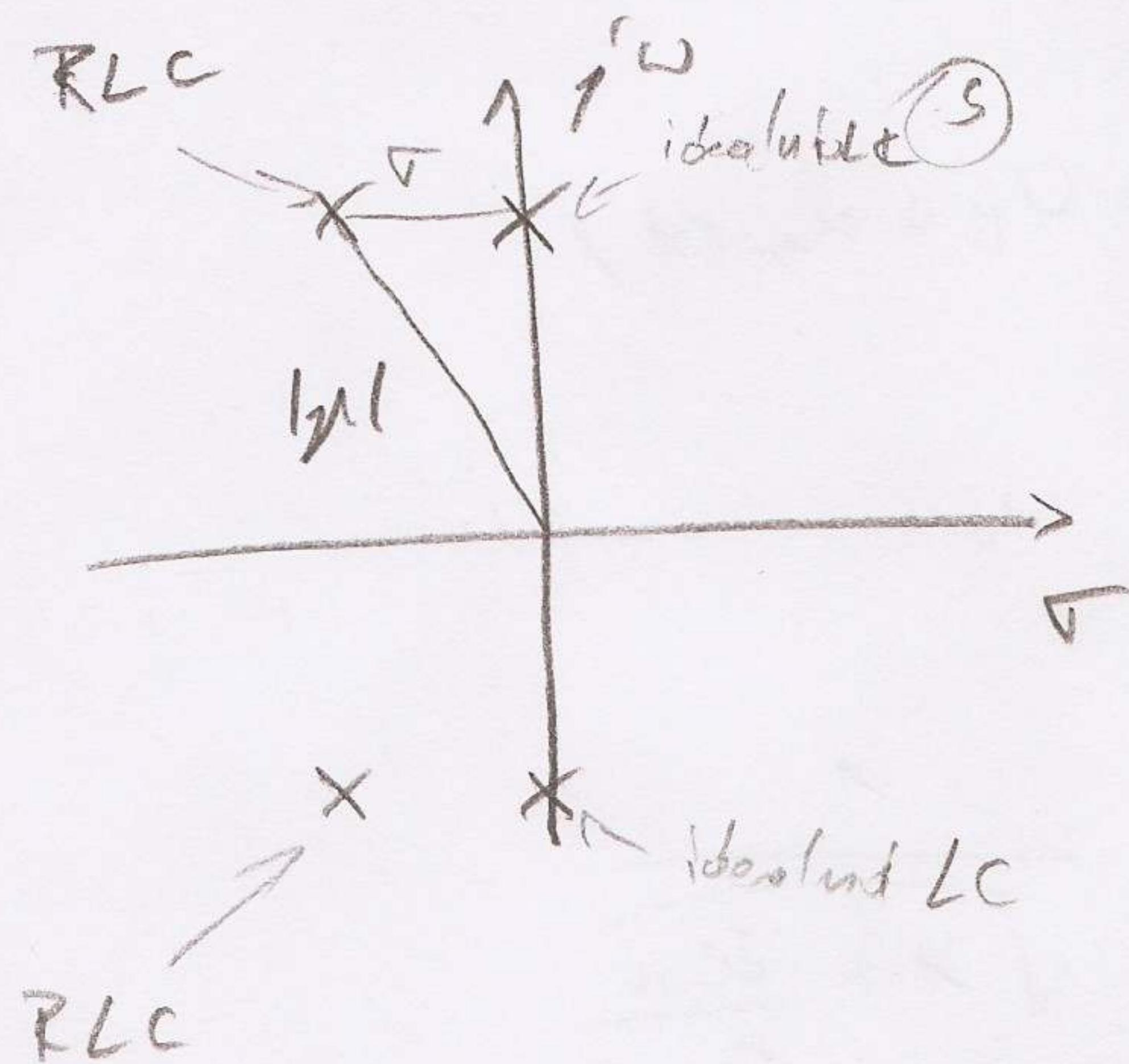
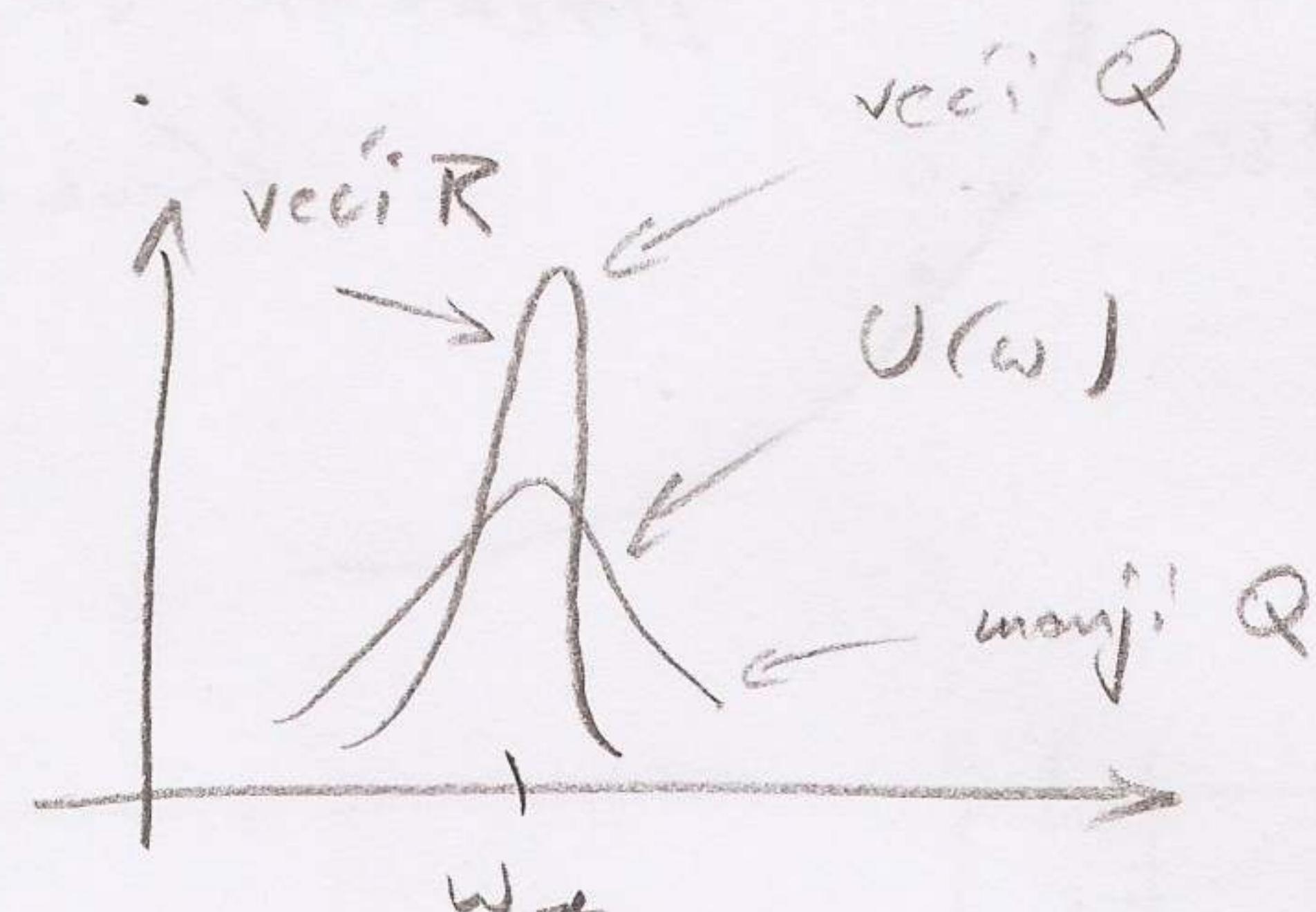
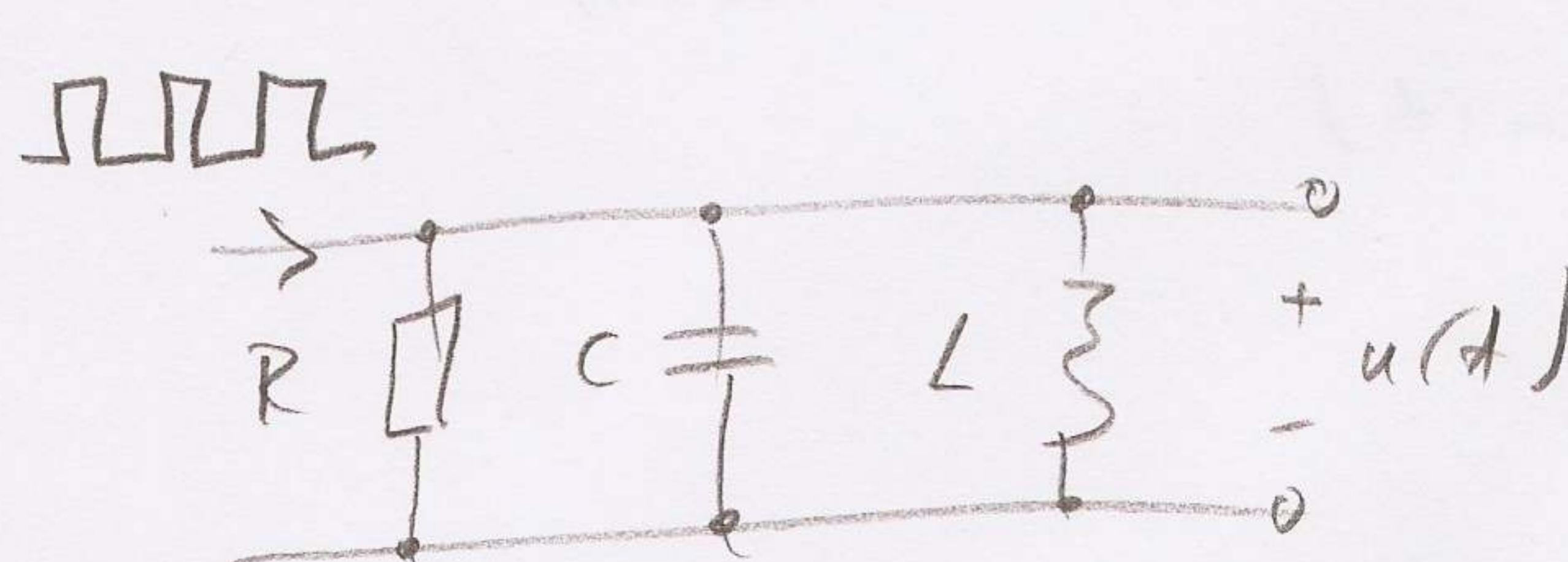


$U_B + u_m(t) > 0 \rightarrow$ Diode reverzno polarizirane.
Na otporniku zavodimo pod napona \rightarrow boj reverzene
struje ticanja dioda.

Idealni LC oscilator



U praksi imamo otpornicke gubitke.

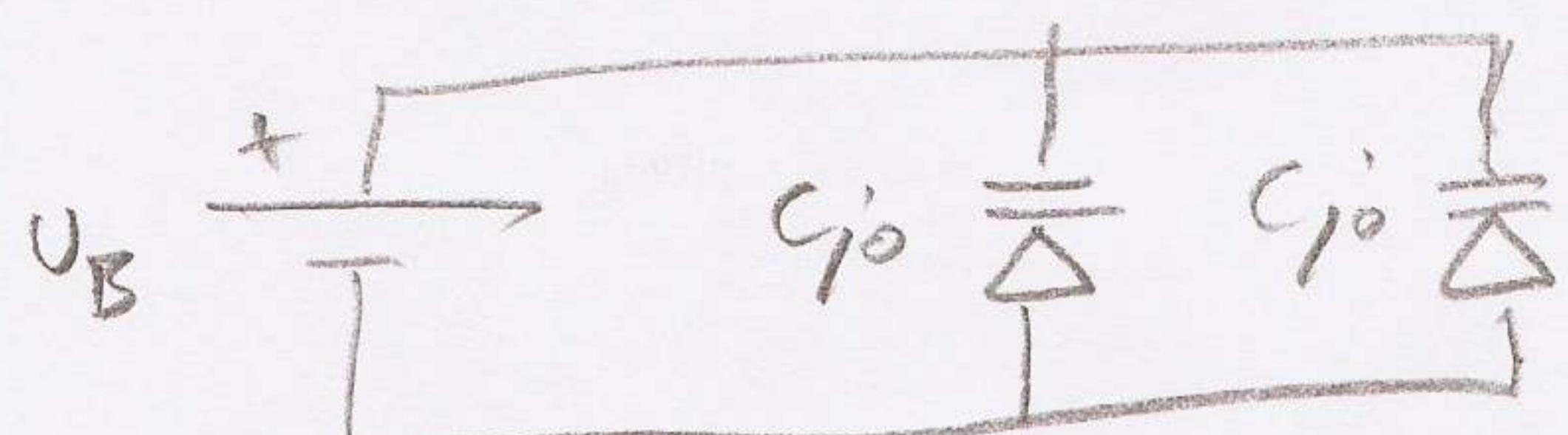


$$Q = \frac{|I_\infty|}{Z_0} = R \sqrt{\frac{C}{L}}$$

Za LC oscilatore Q red velikine 100
Za buarcne oscilatore Q red velikine 1000

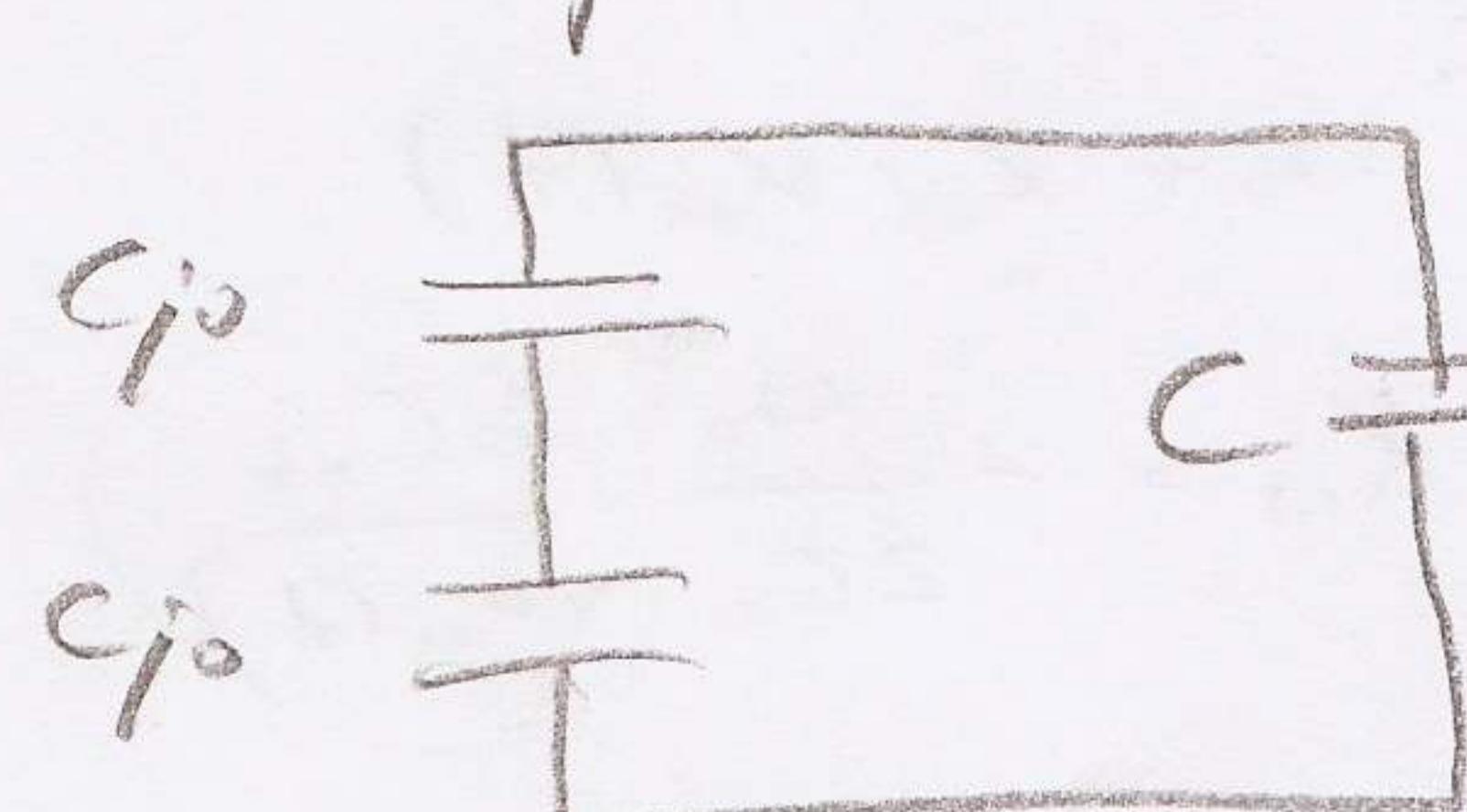
DC analiza

$$u_m(t) = 0V$$



$$C_{10} = \frac{120}{U_B} = \frac{120}{3.3} = 36 \mu F$$

Strujni izvor vidi kapacitet



$$C_0 + \frac{C_0 C_{10}}{C_0 + C_{10}} = C_0 + \frac{C_0 \cdot 36}{C_0 + 36} = C_0 + \frac{C_0}{2}$$

$$\omega = \frac{1}{\sqrt{LC_0}} \Rightarrow C_0 = \frac{1}{4\pi^2 f_0^2 L} = 181 \mu F$$

$$\Rightarrow C = C_0 - \frac{C_0}{2} = 148 \mu F$$

AC analiza

1) Iznos otpora R mora biti što veći zbog visokog Q faktora LC kruga, a s druge strane ne smije biti prevelik zbog atenuacije $u_m(t)$.

2) Na varicap diodama je praktički napon $U_B + u_m(t)$ jer za niske frekvencije f_m ($f_m \ll f_0$) L predstavlja vrlo nisku, a C vrlo visoku impedanciju.

$$C_{uk}(t) = C + \frac{C_j(t)}{2} = C + \frac{C_j + \delta C_j(t)}{2} = C_0 + \underbrace{\frac{\delta C_j(t)}{2}}_{\delta C_{uk}(t)}$$



Trenutna frekvencija

$$\omega_i = \frac{1}{\sqrt{LC_{uk}}} = \frac{1}{\sqrt{L(C_0 + \delta C_{uk})}} = \underbrace{\frac{1}{\sqrt{LC_0}}}_{\omega_0} \cdot \underbrace{\frac{1}{\sqrt{1 + \frac{\delta C_{uk}}{C_0}}}}$$

$U_B \gg \delta C_{uk} \ll C_0$ vrijedi

$$\omega_i = \omega_0 \left(1 - \frac{\delta C_{uk}}{2C_0} \right) \quad \left(\frac{1}{\sqrt{1+x}} \approx 1 - \frac{x}{2}, x \ll 1 \right)$$

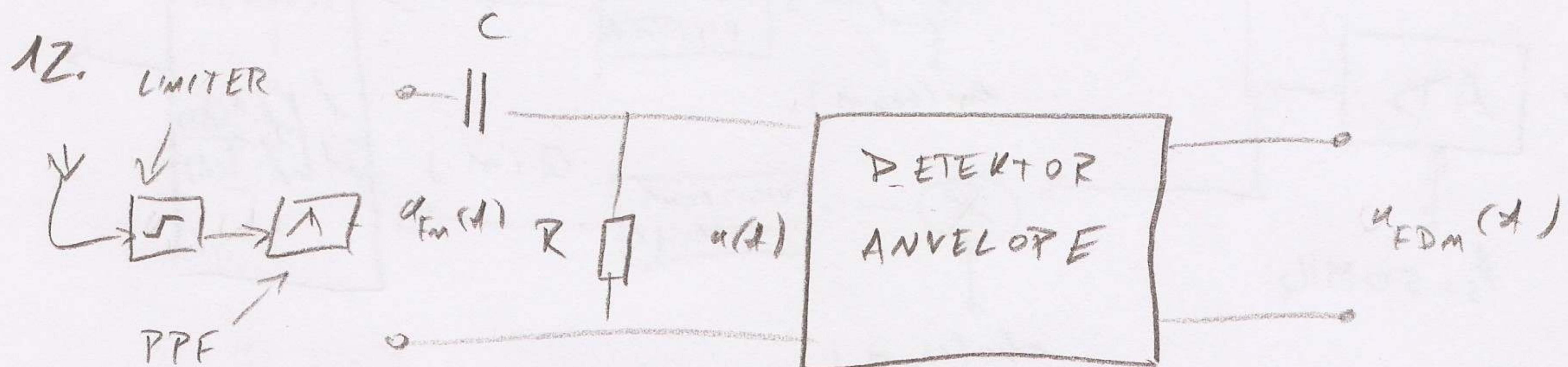
$$\omega_i = \omega_0 - \frac{\omega_0}{2C_0} \delta C_{uk} \stackrel{\text{DEF.}}{=} \omega_0 + K_\omega \cdot u_m(t) \quad \Rightarrow k$$

$$\Rightarrow K_\omega = -\frac{\omega_0}{2C_0} \frac{\delta C_{uk}}{u_m(t)}$$

$$k = \frac{\delta C_{ok}}{\delta u} \Big|_{u=U_B} = \frac{1}{2} \frac{\delta C_1}{\delta u} \Big|_{u=U_B} = - \frac{30}{\sqrt{U_B^3}}$$

$$\Rightarrow K_F = - \frac{f_0}{2C_0} \frac{-30}{\sqrt{U_B^3}} = \frac{2 \cdot 10^6 \cdot 30}{2 \cdot 181 \cdot \sqrt{3.3}} = 27.6 \frac{kHz}{V}$$

$$B = 2\Delta f + 2f_m = 2K_F |u_m(t)|_{\max} + 2f_m = \underbrace{22.8 \text{ kHz}}_{50 \text{ mV}} + \underbrace{10 \text{ kHz}}_{NB FM}$$



$$R \ll \frac{1}{\omega C} \quad \text{so} \quad \omega_0 - \frac{B_{FM}}{2} \leq \omega \leq \omega_0 + \frac{B_{FM}}{2}$$

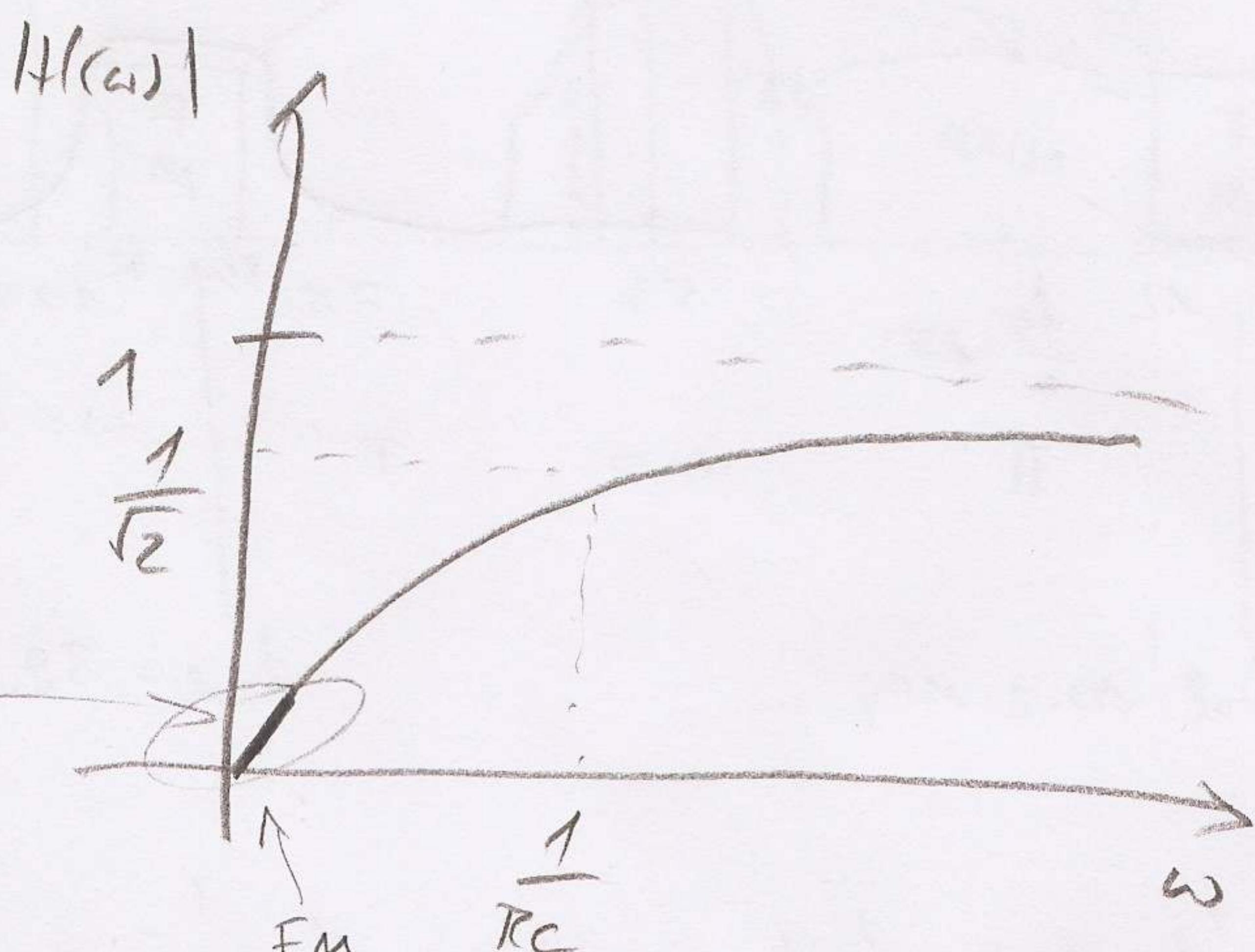
$$\omega \ll \frac{1}{RC} = \omega_{-3dB}$$

$$H(\omega) = \frac{R}{R + \frac{1}{j\omega C}} \approx j\omega RC$$

znamenava

$$|H(j) = sRC$$

DERIVATOR
u po prvoj
gesci



$$u(t) = RC \frac{du_{fm}(t)}{dt}$$

$$u_{fm}(t) = U_0 \cos \left[\omega_0 t + K_w \int_{-\infty}^t u_m(\tau) d\tau \right]$$

$$\Rightarrow u(t) = -RCU_0 \sin \left[\omega_0 t + K_w \int_{-\infty}^t u_m(\tau) d\tau \right] \cdot \left[\omega_0 + K_w u_m(t) \right]$$

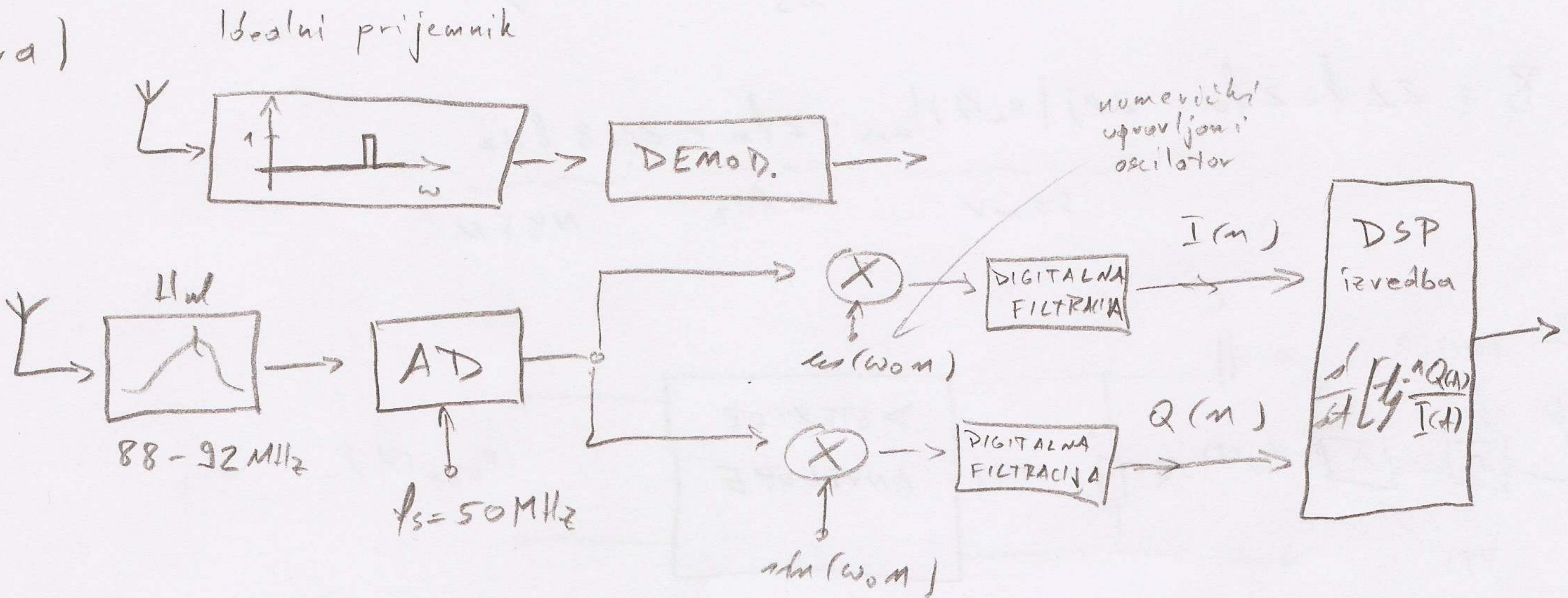
FM AM

Ovo se zove DISKRIMINATOR jer FM pretvara u AM.

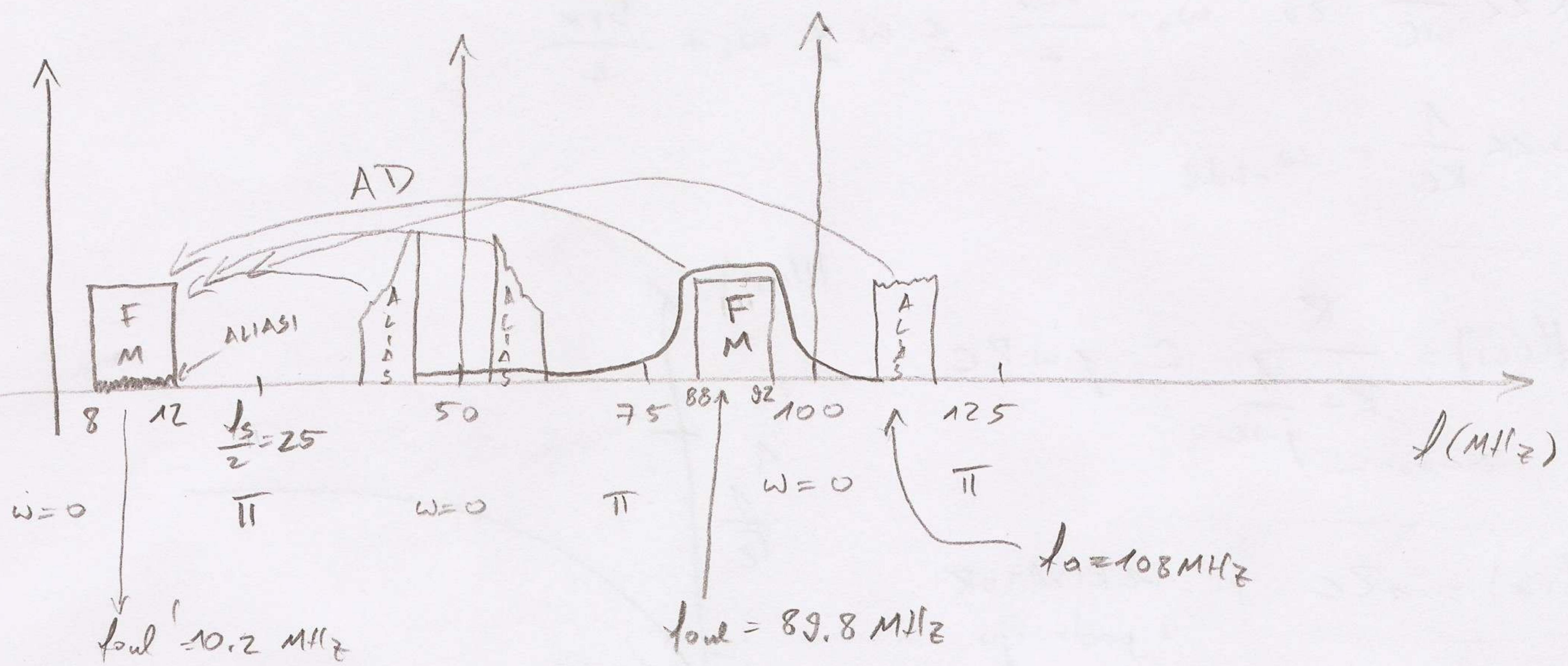
Uz idealan detektor amplitudne oblike dobivamo

$$u_{FDM}(t) = RCU_0 \omega_0 + RCU_0 K_w \cdot u_m(t)$$

13.a)



b)



$$\text{foul odgovara frekvenciji } f_{\text{oul}} = 100 - 89.8 = 10.2 \text{ MHz}$$

Budući se radi o direktnoj pretvorbi, digitalni oscillator mora odgovarati toj frekvenciji tj. $\omega_0 = \frac{10.2}{25} \pi = 0.408 \pi \text{ rad}$

c) Hul je antialiasing filter (AAF) za AD.

Neglijir alijs komponenta kanalima je $f_a = 108 \text{ MHz}$.

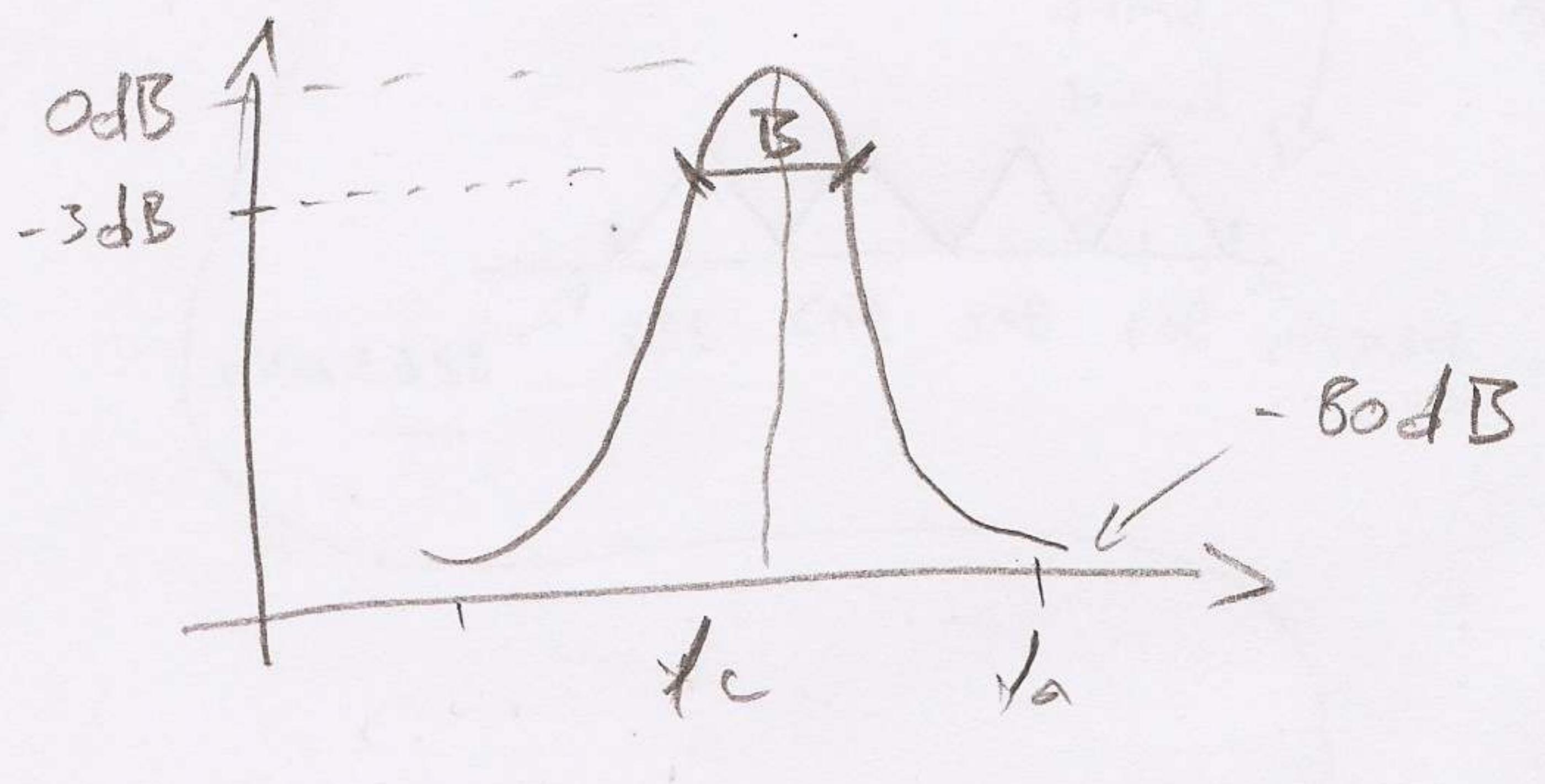
$$f_c = \sqrt{38 \cdot 92} \approx 90 \text{ MHz}$$

$$B = 4 \text{ MHz}$$

redan N

BP Butterworth filter Vima karakteristiku

$$|H(f)| = \frac{1}{\sqrt{1 + \left(\frac{f^2 - f_c^2}{B \cdot f}\right)^{2N}}}$$



$$20 \lg |H(f_a)| \leq -80 \text{ dB}$$

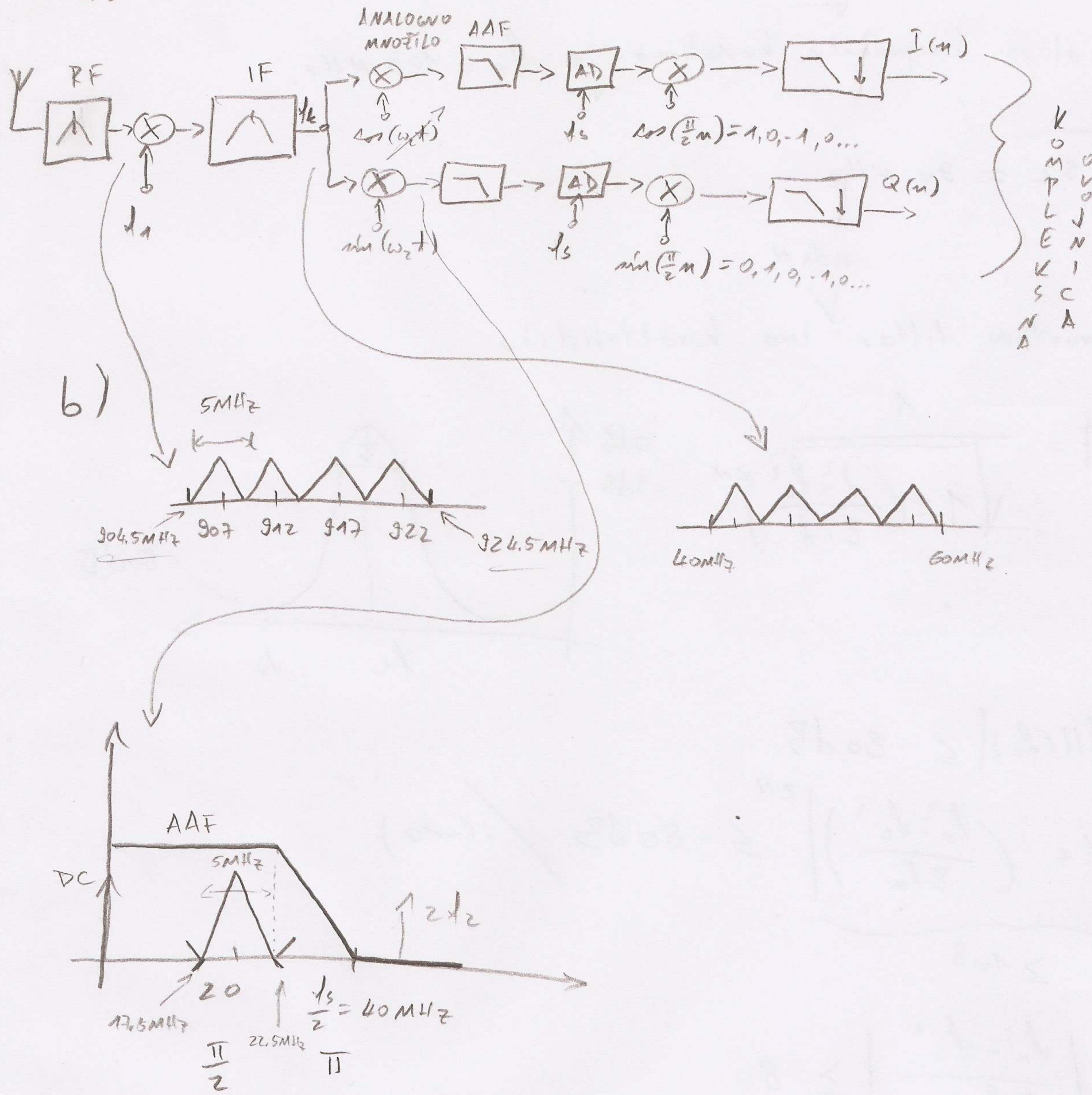
$$-10 \lg \underbrace{\left| 1 + \left(\frac{f_a^2 - f_c^2}{B f_a} \right) \right|^{2N}}_{\geq 108} \leq -80 \text{ dB} / :(-10)$$

$$2N \lg \left| \frac{f_a^2 - f_c^2}{B f_a} \right| \geq 8$$

$$N \geq \frac{4}{\lg \left| \frac{108^2 - 90^2}{4 \cdot 108} \right|} = 4.3 \Rightarrow N = 5$$

U praksi se koristi eliptički filter.

14. a)



$$f_1 = 904.5 \text{ MHz} - 40 \text{ MHz} = 864.5 \text{ MHz}$$

$$f_k = \{42.5, 47.5, 52.5, 57.5\} \text{ MHz}$$

$$\xrightarrow{\text{preslivanje}} \xrightarrow{\cos(2\pi f_2 t)} 20 \text{ MHz}$$

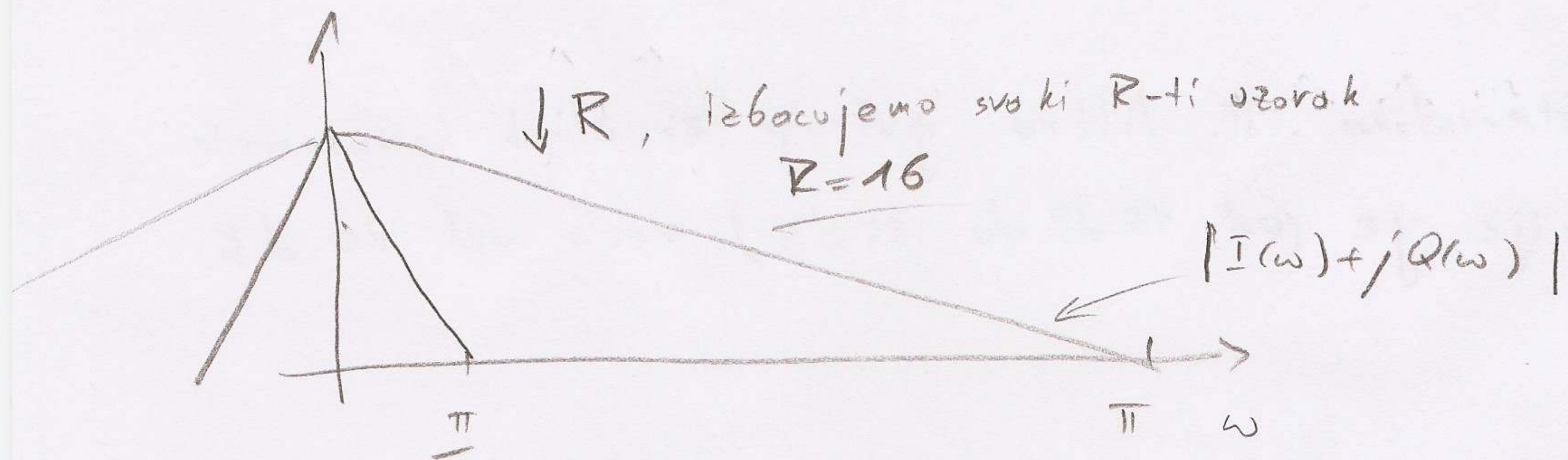
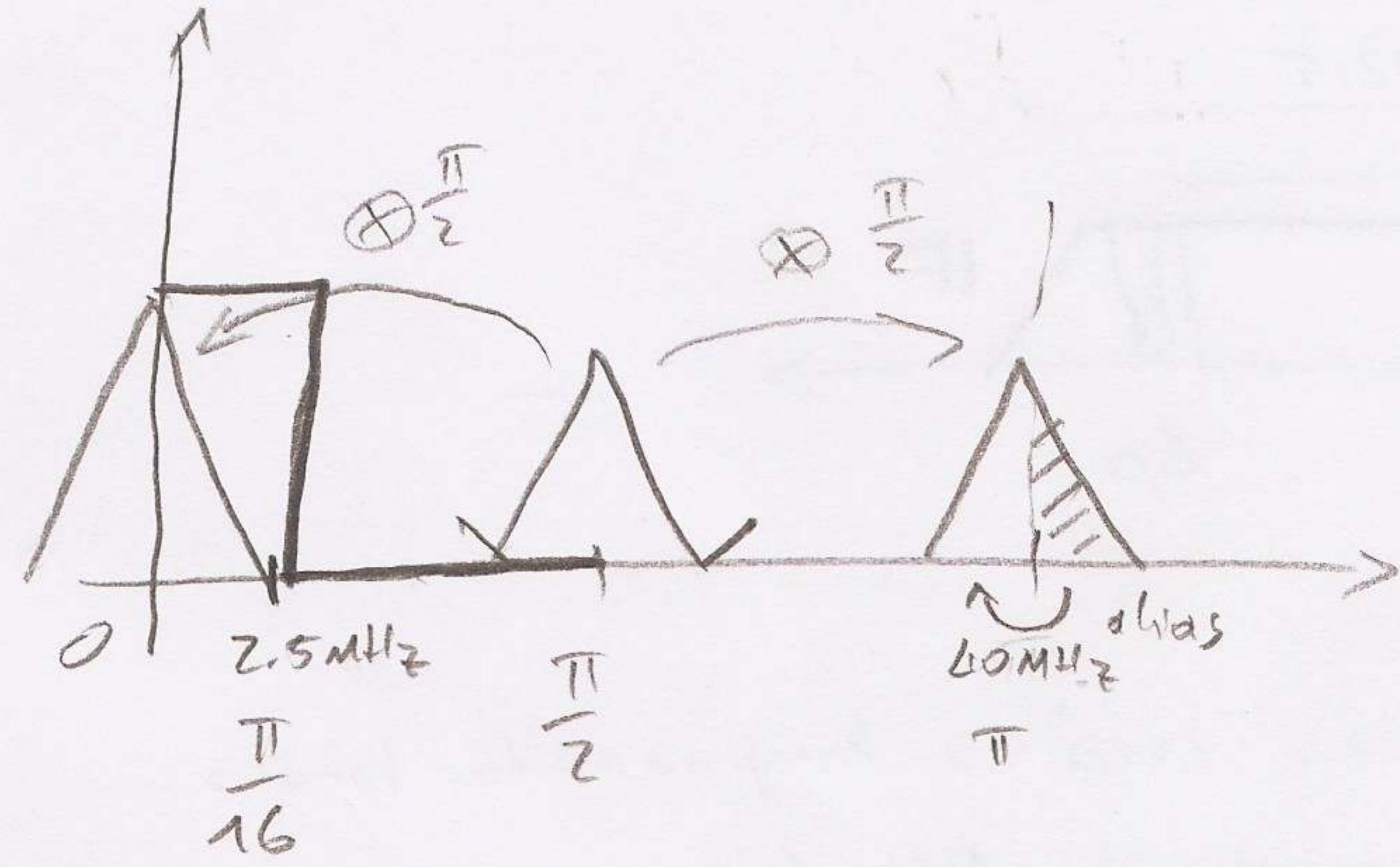
$$f_2 = f_k - 20 =$$

$$= \{22.5, 27.5, 32.5, 37.5\} \text{ MHz}$$

Zbog analognog mjesala dolazi do preslučavanja f_2 na signalnu ulaz. Pritom se javljuju komponente zf_2 i o koje u ovom slučaju ne upadaju u kanal.

Zato se radi mješanje sa $f_2 + \frac{\pi}{2}$.

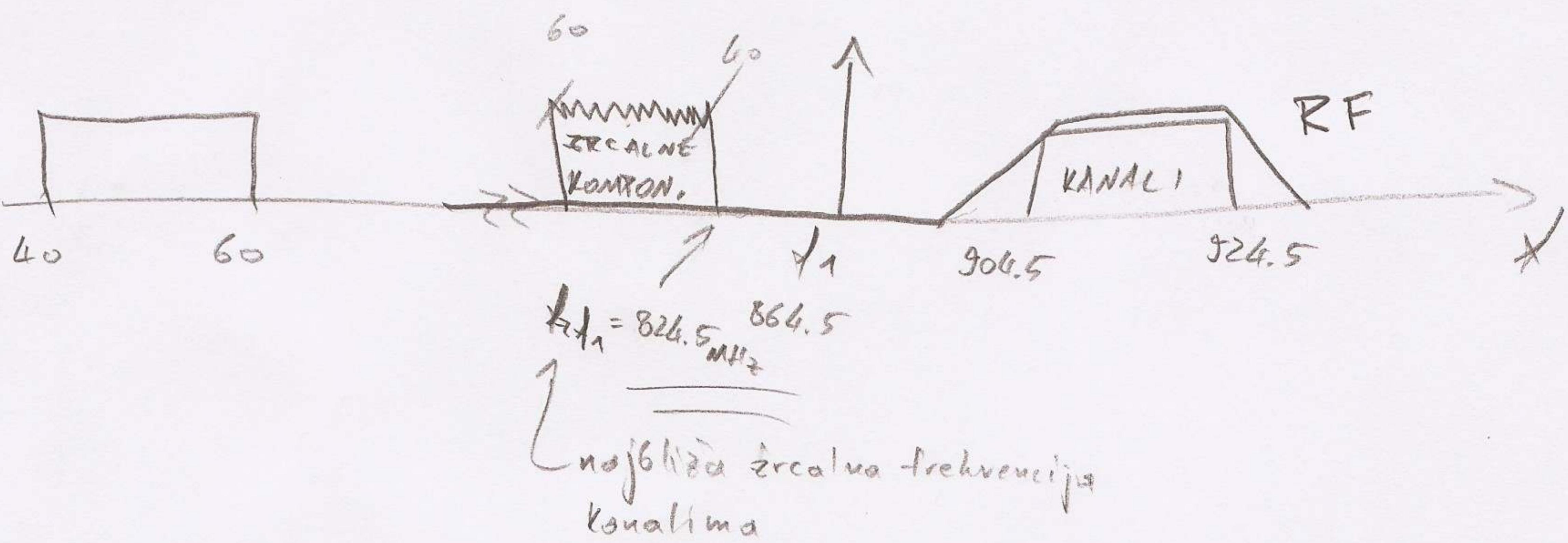
14. Dobivanje kompleksne orouice $I+jQ$ u digitalnoj domeni.



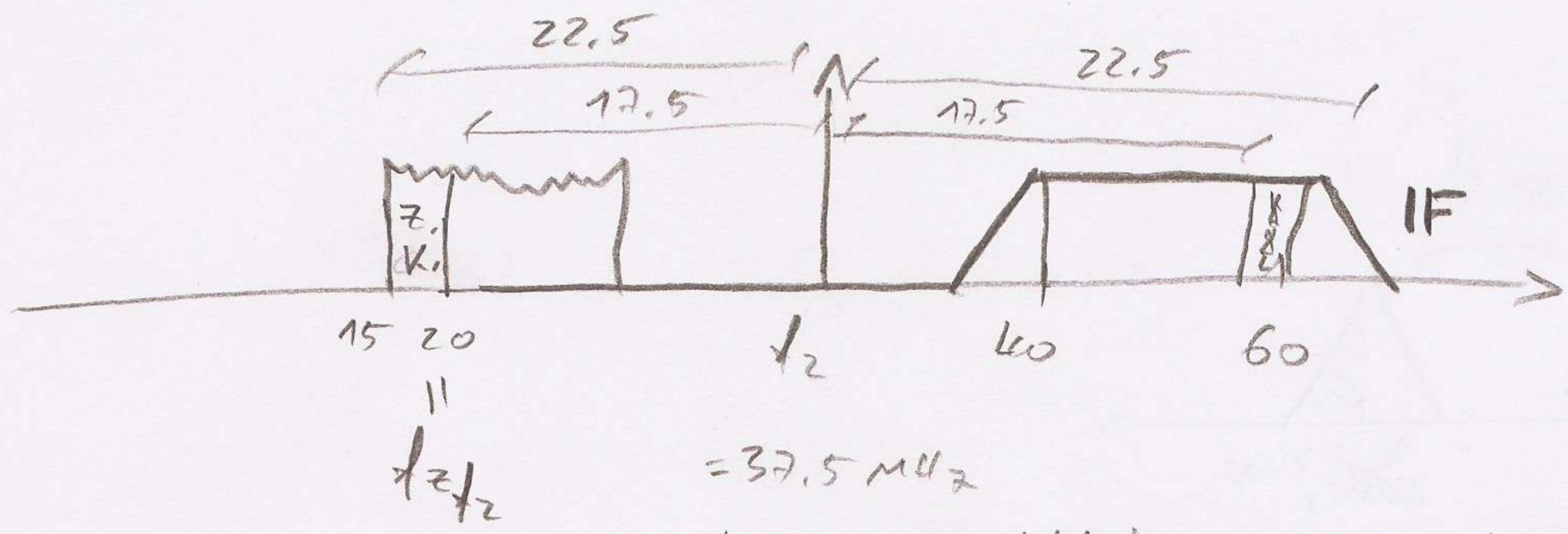
$$f_{sL} = \frac{f_s}{R} = \frac{80}{16} = 5 \text{ MHz}$$

c) Žrealne frekvencije se pojavljuju kod snake transpozicije frekvencije (osim na frekvenciju nula).

U našem slučaju su to kod mješanja s f_1 i f_2 .



Ocitanjem iz amplitudne karakteristike RF filtra vidimo da je gvoženje veće od 50 dB.



$$= 37.5 \text{ MHz}$$

(> daje najbolju zracunu komponentu kanala
(najgore, najstomljeniji si Har!))

Očitavajući iz karakteristike IF filtra gubenje zracnih komponenti kod druge transportacije je (od 15 dB do 85 dB) veće od 20 dB.