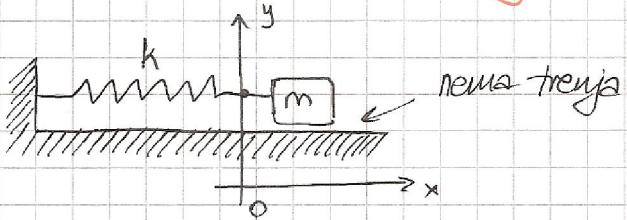


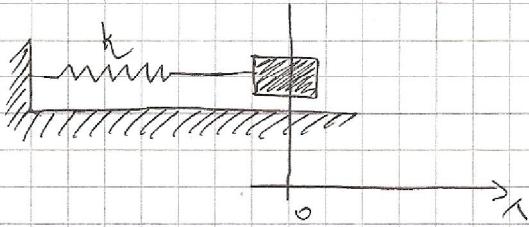
Jednostavno harmoničko titranje



Jednačina gibanja:

$$\begin{aligned} F &= -kx \\ m \cdot a &= -kx \\ m \cdot \frac{d^2x}{dt^2} &= -kx \\ m \cdot \ddot{x} + kx &= 0 \quad | :m \\ \ddot{x} + \frac{k}{m}x &= 0 \\ \ddot{x} + \omega_0^2 x &= 0 \quad \omega_0^2 = \frac{k}{m} > 0 \end{aligned}$$

Dobivanje jednačine gibanja preko $E = \text{konst.}$



$$E = E_{\text{kin}} + E_{\text{pot}}$$

$$\begin{aligned} &= \frac{1}{2}mv^2 + \frac{1}{2}kx^2 \\ &= \frac{1}{2}m\dot{x}^2 + \frac{1}{2}kx^2 \end{aligned}$$

$$E = \text{konst.} \Rightarrow \frac{dE}{dt} = 0$$

$$\begin{aligned} \frac{dE}{dt} &= m\dot{x}\ddot{x} + k\dot{x}x \\ &= \dot{x}(m\ddot{x} + kx) \\ &= \dot{x}\left(\ddot{x} + \frac{k}{m}x\right) \\ \text{Ako je ovo } 0 \text{ onda je} \\ \text{u ravnotežnom položaju} \quad &\quad = 0 \end{aligned}$$

$$\ddot{x} + \frac{k}{m}x = 0$$

Rješavanje jednadžbe gibanja

$$\ddot{x} + \omega_0^2 x = 0$$

Početni uvjeti u $t = t_0$:

$$x(t_0) = x_0, \quad \dot{x}(t_0) = \dot{x}_0 = v_0$$

"Ansatz" rješenje: $x[t] = e^{nt}$

$$n^2 e^{nt} + \omega_0^2 e^{nt} = 0$$

$$n^2 + \omega_0^2 = 0$$

$$n_{1,2} = \pm i\omega_0$$

Opće rješenje (linearna kombinacija):

$$x[t] = a_1 e^{i\omega_0 t} + a_2 e^{-i\omega_0 t}$$

Fizikalni značaj: $x[t] \in \mathbb{R}$

$$e^{i\phi} = \cos\phi + i\sin\phi$$

$$a_1 = \bar{a}_2 = \frac{A}{2} e^{i\phi}$$

$$x[t] = \frac{A}{2} e^{i(\omega_0 t + \phi)} + \frac{A}{2} e^{-i(\omega_0 t + \phi)}$$

$$= \frac{A}{2} (\cos[\omega_0 t + \phi] + i\sin[\omega_0 t + \phi] + \cos[-(\omega_0 t + \phi)] + i\sin[-(\omega_0 t + \phi)])$$

$$= \frac{A}{2} (2\cos(\omega_0 t + \phi) + 0)$$

$$= A \cos[\omega_0 t + \phi]$$

Energija titranja

$$E = E_{kin} + E_{pot}$$

$$= \frac{1}{2} m \dot{x}^2 + \frac{1}{2} k x^2$$

$$= \frac{1}{2} m (\omega_0 A)^2 \sin^2[\omega_0 t + \phi] + \frac{1}{2} k A^2 \cos^2[\omega_0 t + \phi]$$

$$= \frac{1}{2} m \frac{k}{m} \cdot A^2 \sin^2[\phi] + \frac{1}{2} k A^2 \cos^2[\phi]$$

$$= \frac{1}{2} A^2 k (\sin^2[\phi] + \cos^2[\phi])$$

$$= \frac{A^2 k}{2}$$

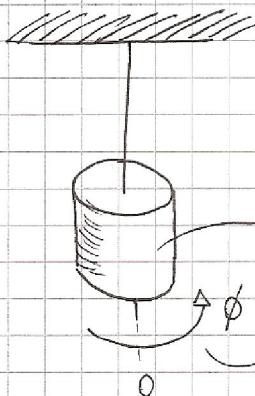
Srednja kinetička energija

$$\overline{E_{kin}} = \frac{1}{T} \int_0^T E_{kin}(t) dt$$

$$E_{kin} = \frac{1}{2} m \dot{x}^2 = \frac{1}{2} m (\omega_0 A)^2 \sin^2[\omega_0 t + \phi]$$

$$\overline{E_{kin}} = \frac{m (\omega_0 A)^2}{4} = \overline{E_{pot}}$$

TORZIONO "NJITHALO"



Konstanta torzije za šipku $D = \frac{G I R^4}{2L}$

moment trenosti I

kut zaslona $\dot{\phi} = \omega$

Jednadžba gibanja

$$L = I \cdot \omega = I \cdot \dot{\phi} \quad \frac{dL}{dt} = M$$

$$M = -D \cdot \phi$$

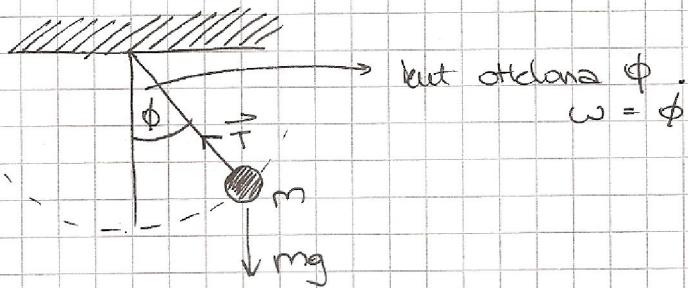
$$I \ddot{\phi} = -D\phi$$

$$I \ddot{\phi} + D\phi = 0 \quad / : I$$

$$\ddot{\phi} + \omega_0^2 \phi = 0$$

$$\omega_0^2 = \frac{D}{I}$$

MATEMATIČKO „NJITHALO“



Vrijedi da dojedisti:

$$L = I\omega, \omega = \dot{\phi}, I = ml^2$$

$$M = -mg l \sin \phi$$

$$\text{Jednadžba gibanja: } \frac{dL}{dt} = M$$

$$\rightarrow ml^2 \ddot{\phi} = -mgl \sin \phi \quad | : ml^2 \\ \ddot{\phi} + \frac{g}{l} \sin \phi = 0$$

za $\phi \ll 1 \quad \sin \phi \approx \phi + \dots$

$$\ddot{\phi} + \omega_0^2 \phi = 0 \\ \boxed{\ddot{\phi} + \frac{g}{l} \phi = 0}$$

Pričko z OE:

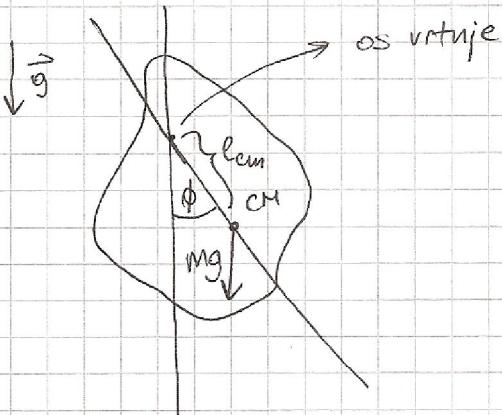
$$E = E_{kin} + E_{pot} \\ = \frac{1}{2} I \omega^2 + mgh \\ = \frac{1}{2} ml^2 \dot{\phi}^2 + mgl(1 - \cos \phi) \\ \text{za } \phi \ll 1 \quad \cos \phi \approx 1 - \frac{\dot{\phi}^2}{2}$$

$$E = \frac{1}{2} ml^2 \dot{\phi}^2 + mgl \frac{\dot{\phi}^2}{2}$$

$$\frac{dE}{dt} = 0 = ml^2 \ddot{\phi} + mgl \dot{\phi} \\ = ml^2 \dot{\phi} \left(\ddot{\phi} + \frac{g}{l} \phi \right)$$

$$\ddot{\phi} + \omega_0^2 \phi = 0$$

FIZIČKO MÍHALO



$$\text{Jednačina gibanja: } \frac{dL}{dt} = M$$

$$I\ddot{\phi} = -mgl_{cm}\sin\phi$$

$$\ddot{\phi} + \frac{mgl_{cm}}{I}\sin\phi = 0$$

$$\phi \ll 1 \quad \sin\phi \propto \phi$$

$$\ddot{\phi} + \frac{mgl_{cm}}{I}\phi = 0$$

$$\text{Steinerov tm.} \Rightarrow I = I_{cm} + ml_{cm}^2$$

$$\omega_0^2 = \frac{mg/l_{cm}}{I_{cm} + ml_{cm}^2}$$

Jednačina gibanja preko E konstante:

$$E = E_{kin} + E_{pot}$$

$$= \frac{1}{2} I \omega^2 + mgh$$

$$= \frac{1}{2} I \dot{\phi}^2 + mgl_{cm}(1 - \cos\phi)$$

$$\phi \ll 1, \cos\phi \approx 1 - \frac{\dot{\phi}^2}{2}$$

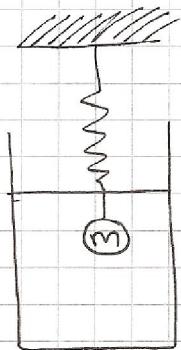
$$E = \frac{1}{2} I \dot{\phi}^2 + mgl_{cm} \frac{\dot{\phi}^2}{2}$$

$$\frac{dE}{dt} = 0$$

$$I\ddot{\phi}\dot{\phi} + mgl_{cm}\dot{\phi}\dot{\phi} = 0$$

$$I\ddot{\phi}(\ddot{\phi} + \frac{mgl_{cm}}{I}\dot{\phi}) = 0$$

PRIGUŠENI OSCILATOR



Sila otpora:

$$F_{\text{opr}} = -b\dot{x} \quad \begin{matrix} \leftarrow \\ \text{brzina} \end{matrix}$$

↳ sila viskoznog člana

Jednadžba gibanja:

$$m\ddot{x} = -kx - b\dot{x} \quad | :m$$

$$\ddot{x} + 2\delta\dot{x} + \omega_0^2 x = 0$$

$$2\delta = \frac{b}{m}$$

Rješavanje jednadžbe gibanja:

"Ansatz" rješenje: $e^{\alpha t}$

$$\alpha^2 e^{\alpha t} + 2\delta\alpha e^{\alpha t} + \omega_0^2 e^{\alpha t} = 0 \quad | :e^{\alpha t}$$

$$\alpha^2 + 2\delta\alpha + \omega_0^2 = 0$$

$$\alpha_{1,2} = -\delta \pm \sqrt{\delta^2 - \omega_0^2}$$

SLABO PRIGUŠENJE ($\delta < \omega_0$)

$$\alpha_{1,2} = -\delta \pm i\omega$$

$$\omega \equiv \sqrt{\omega_0^2 - \delta^2}$$

$$x(t) = a_1 e^{\alpha_1 t} + a_2 e^{\alpha_2 t}$$

$$x(t) \in \mathbb{R}! \Rightarrow a_1 = \overline{a_2} = \frac{A}{2} e^{i\phi}$$

rješenje:

$$x(t) = A \cdot e^{-\delta t} \cos[\omega t + \phi]$$



KRITIČNO PRIGUŠENJE

$$\omega_0 = \delta$$

$$x[t] = (a_1 + a_2 t) e^{-\delta t}$$

Početni uvjeti: $t=0$

$$x_0 = x[0] \quad v_0 = \dot{x}[0]$$

Rješenje:

$$x[t] = e^{-\delta t} (x_0 + (v_0 + x_0 \delta) t)$$

SNAŽNO (NADKRITIČNO) PRIGUŠENJE ($\delta > \omega_0$)

$$\omega_{1,2} = -\delta \pm \sqrt{\omega_0^2 - \delta^2}, \quad \sqrt{\omega_0^2 - \delta^2}$$

$$\begin{aligned} x[t] &= a_1 e^{\alpha_1 t} + a_2 e^{\alpha_2 t} \\ &= e^{-\delta t} [b_1 \cosh(\sqrt{\omega_0^2 - \delta^2} t) + b_2 \sinh(\sqrt{\omega_0^2 - \delta^2} t)] \end{aligned}$$

Početni uvjeti:

$$x[0] = x_0, \quad \dot{x}[0] = v_0$$

Rješenje:

$$x[t] = e^{-\delta t} (x_0 \cosh(\sqrt{\omega_0^2 - \delta^2} t) + \frac{v_0 + x_0 \delta}{\sqrt{\omega_0^2 - \delta^2}} \sinh(\sqrt{\omega_0^2 - \delta^2} t))$$

MJERE JAKOŠTI PRIGUŠENJA (samo za $\delta < \omega_0$)!

* Logaritamski dekrement prigušenja

$$\begin{aligned} \zeta &= \ln \frac{x[t]}{x[t+\tau]} = \ln e^{\delta \tau} = \delta \tau = \delta \frac{2\pi}{\omega} \\ \tau &= \frac{2\pi}{\omega} \approx 2\pi \frac{\delta}{\omega_0} \end{aligned}$$

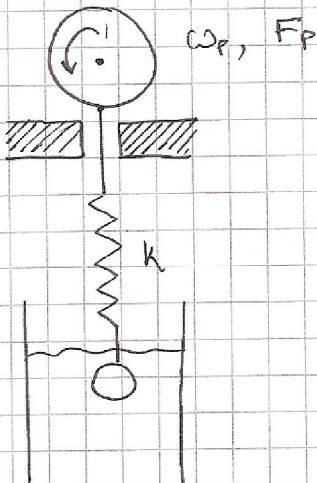
* Q-faktor (faktor kvalitete)

$$Q^{-1} = -\frac{1}{2\pi} \left(\frac{\Delta E}{E} \right)$$

$$Q = -2\pi \left(\frac{1}{\frac{\Delta E}{E}} \right) = \dots = \frac{\omega}{2\delta} \approx \frac{\omega_0}{2\delta}$$

PRISILNO TITRANJE

$$\omega_0^2 = \frac{k}{m} \Rightarrow \text{vlastita frekvencija oscilatora}$$



Vrijeska sila $F_p(t) = F_p \cos[\omega_p t]$

amplituda

Jednadžba gibanja:

$$m \ddot{x} + b\dot{x} + kx = F_p \cos[\omega_p t]$$

$$2\delta = \frac{b}{m} \quad \omega_0^2 = \frac{k}{m} \quad f_p = \frac{F_p}{m}$$

$$\ddot{x} + 2\delta\dot{x} + \omega_0^2 x = f_p \cos[\omega_p t]$$

Očekujemo rješenje oblika $x(t) = A \cos[\omega_p t - \phi]$

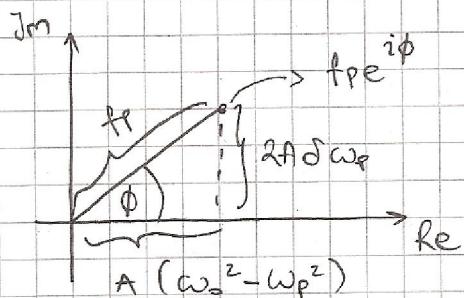
pisemo: $\ddot{x} + 2\delta\dot{x} + \omega_0^2 x = f_p e^{i\omega t}$

"Ansatz" rješenje: $x(t) = A e^{i(\omega_p t - \phi)}$

$$(-\omega_p^2 + i\omega_p 2\delta + \omega_0^2) A e^{i\omega_p t - i\phi} = f_p e^{i\omega_p t}$$

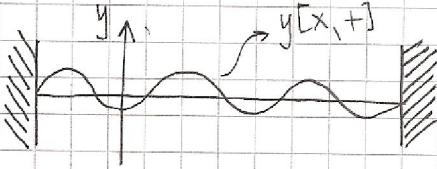
$$[(\omega_0^2 - \omega_p^2) + i2\delta\omega_p] A = f_p e^{i\phi}$$

$$A[\omega_p] = \sqrt{\frac{f_p}{(\omega_0^2 - \omega_p^2) - (2\delta\omega_p)^2}}$$



$$\tan \phi = \frac{2\delta\omega_p}{\omega_0^2 - \omega_p^2}$$

TRANSVERZALNO TITRANJE NAPETOG UŽETA

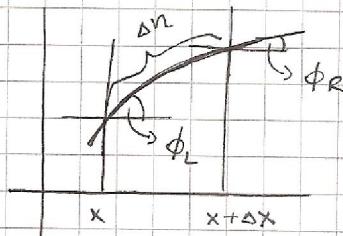


M - masa
L - duljina
T - napetost

Jednadžba gibanja za el. uže

\ddot{y} - derivacija po t

y' - derivacija po x



$$\Delta m \ddot{y}[x, +] = T_R \sin \phi_R + T_L \sin \phi_L \approx$$

$$\approx (T_R \tan \phi_R - T_L \tan \phi_L) \approx$$

$$\approx T (y'[x + \Delta x, +] - y'[x, +])$$

$$sm = \mu \Delta x, \quad \mu = \frac{M}{L}, \quad \ddot{y}[x, +] = \frac{T}{\mu} \quad \underbrace{y'[x + \Delta x, +] - y'[x, +]}_{\Delta x}$$

$$\Delta x \rightarrow 0 = y''[x, +]$$

$$\Rightarrow \ddot{y} - \frac{T}{\mu} y'' = 0$$

$$Rj: \quad y[x, +] = f[x \pm vt] \quad v = \sqrt{\frac{T}{\mu}}$$

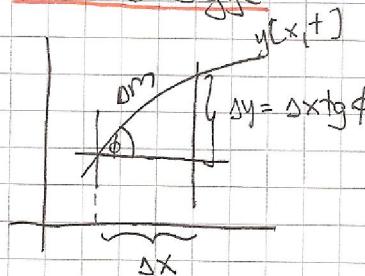
$$Vlina jednadžba \quad \ddot{y} - v^2 y'' = 0$$

$$Rj: \quad y[x, +] = f[x \pm vt]$$

$$\ddot{y} = f''[x \pm vt] \cdot (\pm v)^2 = v^2 f''$$

$$y'' = f''[x \pm vt] (1)^2 = f''$$

Preko energije



$$\Delta E = \Delta E_{kin} + \Delta E_{pot}$$

$$\Delta E_{kin} = \frac{1}{2} \Delta m v^2 = \frac{1}{2} \mu \Delta x \dot{y}^2$$

jer je došlo do produženja
čiće ukoso, a ne ravno.

linijska gustoća mase

brzine u y smjeru
u kojem mas sustav
titra.

$$\Delta E_{pot} = \Delta W = T (\Delta l - \Delta x)$$

$$\Delta l = \sqrt{(\Delta x)^2 + (\Delta x \tan \phi)^2} \\ = \Delta x \sqrt{1 + (\tan \phi)^2}$$

$$= \Delta x \left(1 + \frac{1}{2} \tan^2 \phi + \dots \right)$$

$$= \Delta x \left(1 + \frac{1}{2} y'^2 \right)$$

$$\Delta E_{pot} = \frac{1}{2} T \Delta x y'^2$$

$$\frac{\Delta E}{\Delta x} = \frac{1}{2} \mu y^2 + \frac{1}{2} T y_1^2$$

za harmonički val $y(x,t) = A \cos[\omega t \pm kx]$

$$\frac{\Delta E}{\Delta x} = \left(\frac{1}{2} \mu \omega^2 + \frac{1}{2} T k^2 \right) A^2 \sin^2[\omega t \pm kx]$$

$$= A^2 \mu \omega^2 \sin^2[\omega t \pm kx]$$

$$\frac{\Delta E}{\Delta x} = \frac{1}{2} A^2 \mu \omega^2$$

$$\frac{1}{P} = \frac{\Delta E}{\Delta x} - V$$

LONGITUDINALNO (VALNO) GIBANJE

čas po fluidu:

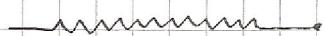
$$0 \equiv \equiv \equiv \equiv \equiv \equiv$$

L, S, M, E ili B

→ za fluid

↳ Youngov modul za čas

ekvivalentna optuža istoduljine i mase

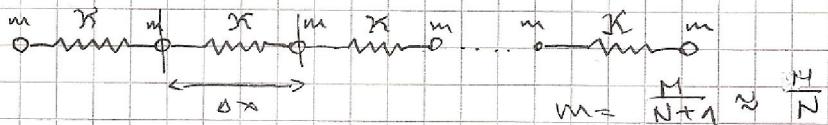


$$L, M, k = \frac{SE}{L}$$

$$k = \frac{SB}{L}$$

za čas
za fluid

ekvivalentni raz masu: optuža



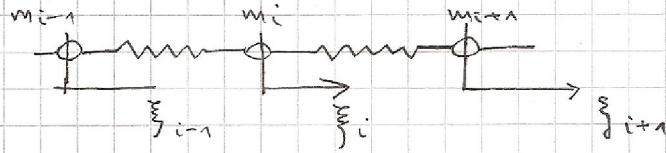
$$k = NK$$

$$\Delta x = \frac{L}{N}$$

$$m = \frac{M}{L} \Delta x = \mu \Delta x$$

$$m = \frac{Lk}{\Delta x}$$

Jednadžba gibanja



$$m_i \ddot{\xi}_i = -k_i(\xi_i - \xi_{i+1})$$

- $k_i(\xi_i - \xi_{i-1})$ → produžuje opruge u odnosu
na ravnotečnu duljinu

uvodimo $\xi[x, t]$

$$(\ddot{\xi}_i = \ddot{\xi}[x + \Delta x, t])$$

$$\mu \Delta x \ddot{\xi}[x, t] = Lk \frac{\ddot{\xi}[x + \Delta x, t] - \ddot{\xi}[x, t]}{\Delta x} - Lk \frac{\ddot{\xi}[x, t] - \ddot{\xi}[x - \Delta x, t]}{\Delta x}$$

$$= \frac{Lk}{\Delta x} \left(\ddot{\xi}[x + \frac{\Delta x}{2}, t] - \ddot{\xi}[x - \frac{\Delta x}{2}, t] \right)$$

$$= Lk \ddot{\xi}[x, t]$$

$$\ddot{\xi}[x, t] = \frac{Lk}{\mu} \ddot{\xi}[x, t] = 0$$

$$\ddot{\xi} - v^2 \ddot{\xi} = 0$$

$$v^2 = \frac{Lk}{\mu} = \frac{k}{m} \cdot \frac{SE}{k} = \frac{SE}{m} = \frac{E}{P}$$

$$\frac{B}{P}$$

Energijski model

$$\begin{aligned} \Delta E &= \frac{1}{2} m \dot{\xi}^2 + \frac{1}{2} k (\xi_{i+1} - \xi_i)^2 \\ &= \frac{1}{2} \mu \Delta x \dot{\xi}^2 + \frac{1}{2} \frac{Lk}{\Delta x} (\dot{\xi}_{\Delta x})^2 \end{aligned}$$

$$\frac{\partial E}{\partial x} = \frac{1}{2} \mu \dot{\xi}^2 + \frac{1}{2} k \frac{SE}{k} \cdot \dot{\xi}^2$$

za harmonički val $\xi[x, t] = A \cos[\omega t \pm kx]$

$$\begin{aligned} \frac{\partial E}{\partial x} &= \frac{1}{2} \mu \omega^2 A^2 \sin^2[\omega t \pm kx] + \frac{1}{2} SE k^2 A^2 \sin^2[\omega t \pm kx] \\ k^2 &= \left(\frac{\omega}{v}\right)^2 = \omega^2 \frac{P}{E} \quad SP = \mu \end{aligned}$$

$$\frac{\partial E}{\partial x} = \mu \omega^2 A^2 \sin^2[\omega t \pm kx]$$

$$\begin{aligned} \frac{\partial E}{\partial x} &= \frac{1}{2} \mu \omega^2 A^2 \Rightarrow \text{linijska gustoća energije} \\ &= \frac{1}{2} SP \omega^2 A^2 \end{aligned}$$

$$\frac{\overline{\Delta E}}{\Delta V} = \frac{1}{S} \frac{\overline{\Delta E}}{\Delta t} = \frac{1}{2} \rho \omega^2 A^2 \Rightarrow \text{volumna gustoća energije}$$

$$\overline{P} = \frac{\overline{\Delta E}}{\Delta x} \cdot v \Rightarrow \text{srednja snaga}$$

$$\text{Intenzitet } I = \frac{\overline{P}}{S} \quad (\text{srednja snaga po površini})$$

STOJANI VAL



$$\xi[x, t] = a \cos[\omega t - kx] + a \cos[\omega t + kx]$$

$$= 2a \underbrace{\cos[kx]}_{\text{"amplituda"}} \cos[\omega t] \quad \rightarrow \text{titrajući član}$$

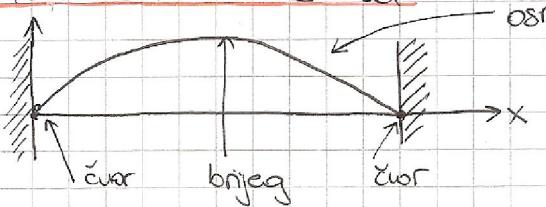
$$\text{Općenito: } \xi[x, t] = A \cos[kx + \phi] \cos[\omega t + \psi]$$

čvorovi - točke u kojima vrijedi $\xi[x, t] = 0$

brijegovi - točka za koju vrijedi $\xi[x, t] = -A \cos[\omega t + \psi]$

brijegovi - točke u kojima vrijedi $\xi[x, t] = 0$

* transverzalni val na vježbu



osnovni rad titraja

$$y[x, y] = A \sin[kx] \cos[\omega t]$$

$$\omega = kv, v = \sqrt{\frac{k}{\mu}}$$

za osnovni mod

$$k = \frac{2\pi}{\lambda}, \lambda = 2l$$

$$\Rightarrow k = \frac{\pi}{l}, \omega = \frac{\pi}{l} \sqrt{\frac{F}{\mu}}$$

općenito $n = 1, 2, \dots$

$$l = n \frac{\lambda}{2}$$

$$k_p = \frac{2\pi}{\lambda_n} = \frac{n\pi}{l}$$

$$\omega = k_n v = \frac{n\pi}{l} \sqrt{\frac{F}{\mu}}$$

* situacija: čvrst - slobodan



osnovni mod

$$l = \frac{\lambda}{4}$$

$\geq n \geq 1$

$$l = \frac{\lambda}{4} + (n-1) \frac{\lambda}{2}$$

$$= \frac{2n-1}{4} \lambda_n \quad \lambda_n = \frac{4l}{2n-1}$$

$$k_n = \frac{2\pi}{\lambda_n} = 2\pi \cdot \frac{2n-1}{4l}$$

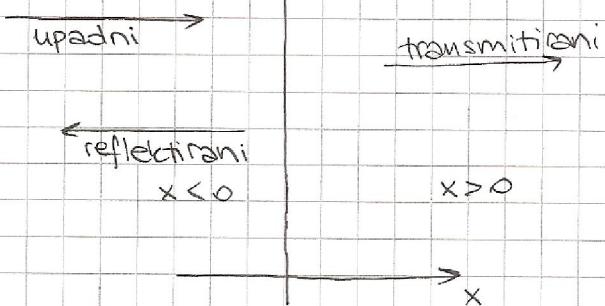
$$k_n = \frac{2n-1}{2l} \pi$$

$$\omega_n = k_n \cdot v = \frac{(2n-1)}{2l} \pi \sqrt{\frac{E}{\rho}}$$

REFLEKSIJA I TRANSMISIJA VALA

sredstvo 1. v_1

v_2 sredstvo 2.



$$\mu_1 \quad T \quad \mu_2 \quad v = \sqrt{\frac{T}{\mu}}$$

$$v_1 = \sqrt{\frac{T}{\mu_1}}$$

$$v_2 = \sqrt{\frac{T}{\mu_2}}$$

$$\xi_{upad}[x, t] = a_{upad} \cdot \cos(\omega t - k_1 x)$$

$$\xi_{ref}[x, t] = a_{ref} \cdot \cos(\omega t + k_1 x)$$

$$\xi_{tran}[x, t] = a_{tran} \cdot \cos(\omega t - k_2 x)$$

UVJET 1: spojenost

$$\xi_{upad} + \xi_{ref} = \xi_{tran} \quad u \quad x=0$$

$$a_u + a_r = a_t$$

UVJET 2: "glatka" spojenost

$$\xi_u' + \xi_r' = \xi_t' \quad u \quad x=0$$

$$k_1 a_u - k_1 a_r = k_2 a_t$$

$$a_r = \frac{k_1 - k_2}{k_1 + k_2} a_u \quad a_t = \frac{2k_1}{k_1 + k_2} a_u$$

ZVUK

* oscilacija tlaka

$$p = p_{\text{atm}} + (\Delta p)_{\text{max}} \sin[\omega t \pm kx]$$

↳ amplituda oscilacije tlaka

$$= B k A = B \frac{\omega}{v} A$$

$$\frac{(\Delta p)_{\text{max}}^2}{2 \rho v} = \frac{B^2 \frac{\omega^2}{v^2} A^2}{2 \rho v} = \frac{B \omega^2 A^2}{2 v} = \frac{B \omega^2 A^2 P}{2 \rho v} = \frac{\rho \omega^2 A^2 v}{2}$$

* intenzitet

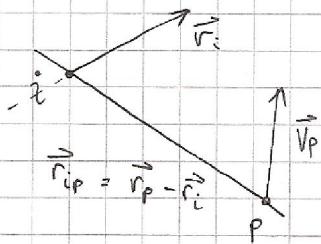
$$I = \frac{P}{S} = \frac{1}{2} \rho \omega^2 A^2 v = \frac{(\Delta p)_{\text{max}}^2}{2 \rho v}$$

* Razina buke

$$L_{\text{dB}} = 10 \log_{10} \frac{I}{I_0}$$

$$I = 10^{-12} \frac{\text{W}}{\text{m}^2}$$

* Dopplerov efekt



i = izvor

p = prijemnik

$$\frac{f_p}{f_i} = \frac{v_z - \frac{1}{r_{ip}} \cdot \vec{v}_p}{v_z - \frac{1}{r_{ip}} \cdot \vec{v}_i}$$

\vec{r} → ide ujek od izvora prema prijemniku!

$$\vec{r}_{ip} \cdot \vec{v}_p, \vec{r}_{ip} \cdot \vec{v}_i \rightarrow \text{skalarni umnožak} \rightarrow v_p \cdot \cos \gamma(v_p, r) \\ v_i \cdot \cos \gamma(v_i, r)$$

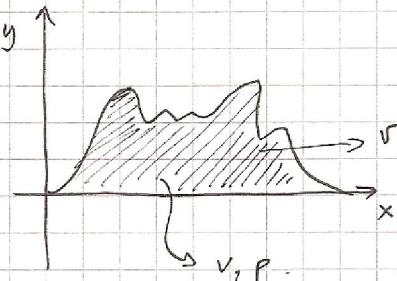
* Dispersija vala

1. nedispersivno sredstvo

$$\ddot{y} - v^2 \dot{x}'' = 0$$

$$y[x, t] = f[x \pm vt]$$

↪ valni paket
ne mijenja oblik



Superpozicija, $\omega_1 \approx \omega_2$

$$y[x, t] = A \cos[\omega_1 t - k_1 x] + A \cos[\omega_2 t - k_2 x]$$

$$= 2A \cos[\omega_- t - k_- x] \cos[\omega_+ t - k_+ x]$$

$$\left[\omega_{\pm} = \frac{\omega_1 \pm \omega_2}{2} \quad k_{\pm} = \frac{k_1 \pm k_2}{2} \right]$$

$$= 2A \underbrace{\cos[k_-(x - \frac{\omega_-}{k_-} t)]}_{\text{sporotrajući faktor}} \underbrace{\cos[k_+(x - \frac{\omega_+}{k_+} t)]}_{\text{brzotrajući faktor}}$$

2. dispersivno sredstvo

superpozicija:

$$y[x, t] = 2A \cos[k_-(x - \frac{\omega_-}{k_-} t)] \cos[k_+(x - \frac{\omega_+}{k_+} t)]$$

$$\left. \begin{aligned} v_- &= \frac{\omega_-}{k_-} = \frac{\Delta \omega}{\Delta k} = \frac{d\omega}{dk} \\ v_+ &= \frac{\omega_+}{k_+} = \frac{\omega_{1,2}}{k_{1,2}} \end{aligned} \right\} \neq$$

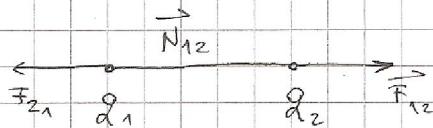
$$\frac{d\omega}{dk} < \frac{\omega}{k} \Rightarrow v_- < v_+$$

↪ fazna brzina
↪ grupna brzina

ELEKTROMAGNETIZAM

Električno polje :

Coulumbov zakon



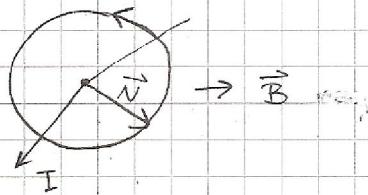
$$\vec{N}_{12} = \vec{N}_2 - \vec{N}_1$$

$$N_{12} = |\vec{N}_{12}| \cdot |\vec{N}_1 - \vec{N}_2|$$

$$\vec{N}_{12} = \frac{\vec{N}_{12}}{|N_{12}|}$$

$$\vec{F}_{12} = \frac{1}{4\pi\epsilon_0} \cdot \frac{q_1 q_2}{r_{12}^2} \cdot \vec{r}_{12} = -\vec{F}_{21}$$

Magnetsko polje :



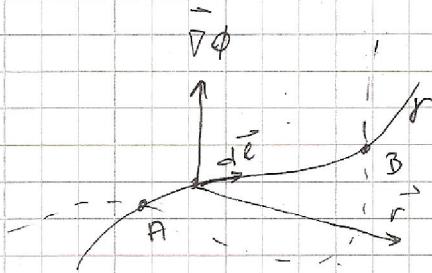
$$I = \frac{dy}{dt}$$

$$|\vec{B}| = \frac{1}{2\pi\epsilon_0 c^2} \int \frac{I}{r}$$

$$= \frac{\mu_0}{2\pi} \cdot \frac{I}{N_0}$$

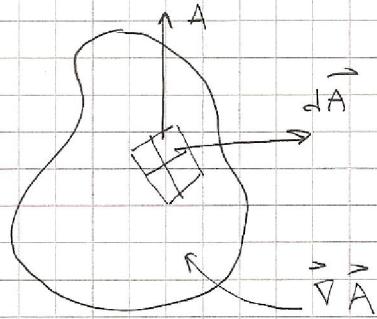
Tm o gradijentu

$$\int \vec{\nabla} \phi \cdot d\vec{l} = \phi[\vec{r}_B] - \phi[\vec{r}_A]$$



Tm o divergenciji (Gaussov tm)

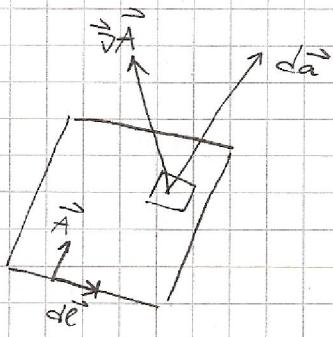
$$\int_V (\vec{\nabla} \cdot \vec{A}) dV = \oint_{S=\partial V} \vec{A} \cdot d\vec{A}$$



Tm o rotaciji (Stokesov tm)

$$\int_s (\vec{\nabla} \times \vec{A}) \cdot d\vec{a} = \oint \vec{A} \cdot d\vec{e}$$

\curvearrowright as



1. Maxwellova jednačina

$$\vec{\nabla} \cdot \vec{E} = \frac{\rho}{\epsilon_0}$$

→ primjena Gaussovog teorema

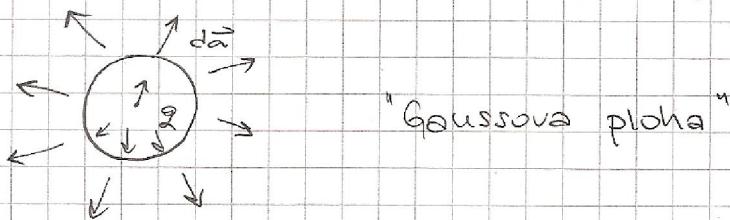
lijeva strana: $\int_V \vec{\nabla} \cdot \vec{E} dV = \int_{r=\partial V} \vec{E} \cdot d\vec{A} = \Phi_E$

desna strana: $\int_V \frac{\rho}{\epsilon_0} dV = \frac{1}{\epsilon_0} \int_V \rho dV = \frac{q}{\epsilon_0}$

Gaussov zakon za \vec{E} polje

$$\Phi_E = \frac{1}{\epsilon_0} \frac{q}{2}$$

• Primjena Gaussovog zakona za \vec{E} polje



zbog simetrije \vec{E} je radijalno polje (desmito na s)

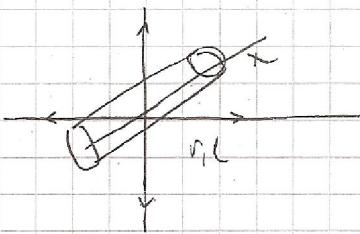
i svugdje na S ono je jednakice jakosti

$$\Phi_E = \int_S \vec{E} \cdot d\vec{a} = E \cdot 4\pi r^2 \frac{q}{2}$$

$$E = \frac{1}{4\pi\epsilon_0} \cdot \frac{q}{r^2}$$

$\rightarrow \vec{E}$ polje beskonačnog linjskog naboja

$$\nabla = \frac{dg}{dl}$$



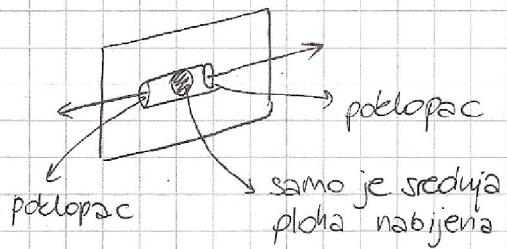
$$\Phi_E = \oint \vec{E} \cdot d\vec{a} = E \cdot 2\pi r \cdot l$$

$$= \frac{1}{\epsilon_0} \cdot 2 = \frac{1}{\epsilon_0} \cdot l \cdot \nabla$$

$$E = \frac{1}{2\pi\epsilon_0} \cdot \frac{\nabla}{r}$$

$\rightarrow \vec{E}$ polje uniformno nabijene ravnine

$$\nabla = \frac{dg}{da}$$



$$\Phi_E = \oint_S \vec{E} \cdot d\vec{a} = 2Ew^2\pi$$

$$= \frac{1}{\epsilon_0} \cdot 2 = \frac{1}{\epsilon_0} \cdot r^2\pi \nabla$$

$$E = \frac{1}{2\epsilon_0} \cdot \nabla$$

2. Maxwellova jednadžba

$$\nabla \cdot \vec{B} = 0$$

↓

$$\oint_B = 0$$

3. Maxwellova jednadžba

$$\nabla \times \vec{E} = -\frac{\partial \vec{B}}{\partial t}$$

rotacija el. polja = vremenska promjena magnetskog polja

Primjena Stokesa:

lijeva strana B.MJ:

$$\int_s (\nabla \times \vec{E}) \cdot d\vec{a} = \oint \vec{E} \cdot d\vec{l} = E$$

\downarrow

EHS!

desna strana B.MJ:

$$\int_s \left(-\frac{\partial \vec{B}}{\partial t} \right) \cdot d\vec{a} = -\frac{\partial}{\partial t} \int_s \vec{B} \cdot d\vec{a} = -\frac{d\Phi_B}{dt}$$

Taradayev zakon indukcije

$$\varepsilon = -\frac{\partial}{\partial t} \Phi_B$$

4. Maxwellova jednadžba

$$c^2 \nabla \times \vec{B} = \frac{\vec{J}}{\varepsilon_0} + \frac{\partial \vec{E}}{\partial t}$$

$$c^2 \left(\text{rotacija mag. polja} \right) = \frac{1}{\varepsilon_0} \left(\text{gustota el. struje} \right) + \left(\text{vremenska promjena el. polja} \right)$$

Primjena Stokessova teorema:

$$\text{lijeva strana: } \int_S c^2 (\vec{\nabla} \times \vec{B}) \cdot d\vec{a} - c^2 \oint_{\gamma = \partial S} \vec{B} \cdot d\vec{e}$$

desna strana:

$$\begin{aligned} \int_S \left(\frac{\vec{J}}{\epsilon_0} + \frac{\partial \vec{E}}{\partial t} \right) \cdot d\vec{a} &= \underbrace{\frac{1}{\epsilon_0} \int_S \vec{J} \cdot d\vec{a}}_I + \underbrace{\frac{\partial}{\partial t} \int_S \vec{E} \cdot d\vec{a}}_{\Phi_E} \\ &= \frac{1}{\epsilon_0} I + \frac{\partial}{\partial t} \Phi_E \\ \Rightarrow c^2 \int_{\gamma = \partial S} \vec{B} \cdot d\vec{e} &= \frac{1}{\epsilon_0} I + \frac{\partial}{\partial t} \Phi_E \\ c^2 \left(\frac{I_{\text{int}} + \vec{B}_{\text{poz}}}{\text{zatvorenoj}} \right) &= \frac{1}{\epsilon_0} \left(\underbrace{\text{struja kroz } S}_{\text{Maxwellov zakon}} \right) + \underbrace{\frac{\partial}{\partial t} \left(\text{tok } E \text{ kroz } S \right)}_{\text{AMPER-MAXWELLOV ZAKON (točno!)}} \end{aligned}$$

* Jedn. kontinuiteta sa električni naboј (očuvanje naboja)

$$\vec{\nabla} \cdot \vec{J} = - \frac{\partial \rho}{\partial t} \rightarrow \text{gustota naboja}$$

\rightarrow gradijent gustoće struje.

interpretacija:

$$\int_V \vec{\nabla} \cdot \vec{J} dv = \int \vec{J} \cdot d\vec{a}$$

$$\int_V \left(- \frac{\partial \rho}{\partial t} \right) dv = - \frac{\partial}{\partial t} \int_V \rho dv = - \frac{\partial}{\partial t} Q$$

$$\Rightarrow \int_{S=\partial V} \vec{J} \cdot d\vec{a} = - \frac{\partial Q}{\partial t} \rightarrow \text{vremenska promjena naboja unutar volumena}$$

ele. tok kroz
plohu

Iznod iz MJ:

$$\frac{\partial \rho}{\partial t} \stackrel{(MJ)}{=} \frac{d}{dt} \left(t_0 \vec{\nabla} \cdot \vec{E} \right) = \epsilon_0 \vec{\nabla} \cdot \frac{\partial \vec{E}}{\partial t}$$

$$\stackrel{(4M)}{=} \epsilon_0 \vec{\nabla} \left(c^2 \vec{\nabla} \times \vec{B} - \frac{\vec{J}}{\epsilon_0} \right)$$

$$= - \vec{\nabla} \cdot \vec{J} \quad (\text{zbog ješ } \vec{\nabla} \cdot (\vec{\nabla} \times \vec{A}) = 0)$$

* Elektrostatika

$$\frac{\partial \vec{E}}{\partial t} = - \frac{\partial \vec{B}}{\partial t} = 0$$

$$\vec{\nabla} \cdot \vec{E} = \frac{\rho}{\epsilon_0}$$

$$\vec{\nabla} \cdot \vec{B} = 0$$

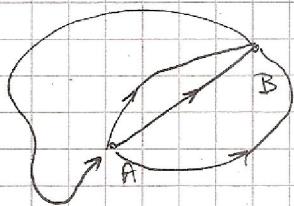
$$\boxed{\vec{\nabla} \times \vec{E} = 0}$$

$$c^2 \vec{\nabla} \times \vec{B} = \frac{\rho}{\epsilon_0}$$

"konzervativno polje"

$$\oint \vec{E} \cdot d\vec{l} = 0$$

(stokes)



→ svi integrali su jednaki nuli

$$\int_A^B \vec{E} \cdot d\vec{l}$$

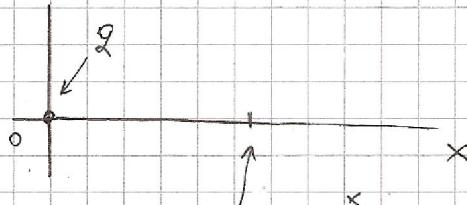
ne ovisi o putu

$$V[\vec{r}] = - \int_{\vec{r}_0}^{\vec{r}} \vec{E} \cdot d\vec{l}$$

$$\int_{\vec{r}_0}^{\vec{r}} \vec{E} \cdot d\vec{l} = (-V[\vec{r}]) - (-V[\vec{r}_0])$$

primjenom tm o gradijentu:

$$\vec{E} = -\vec{\nabla} V$$



$$V[x] = - \int_{+\infty}^x E_x dx$$

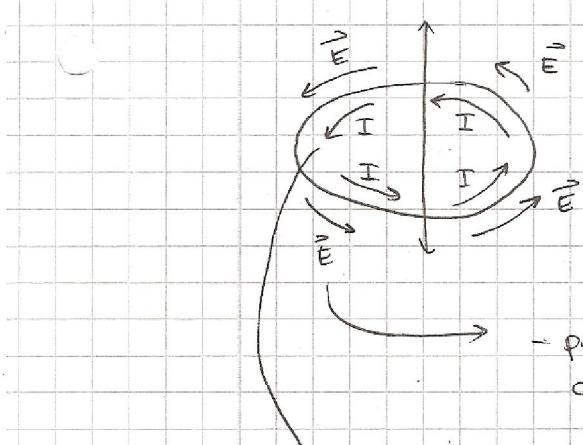
$$= - \int_{+\infty}^x \frac{1}{4\pi\epsilon_0} \frac{q}{x^{1/2}} dx = \frac{q}{4\pi\epsilon_0} \int_x^{+\infty} \frac{dx}{x^{1/2}}$$

$$= \frac{q}{4\pi\epsilon_0} \left(-\frac{1}{x} \right) \Big|_x^{+\infty} = \frac{q}{4\pi\epsilon_0} \cdot \frac{1}{x}$$

$$V[\vec{r}] = \frac{1}{4\pi\epsilon_0} \frac{q}{|\vec{r} - \vec{r}_i|}$$

$$\text{Za sve nabioje: } V[\vec{r}] = \frac{1}{4\pi\epsilon_0} \sum_i \frac{q_i}{|\vec{r} - \vec{r}_i|} = \frac{1}{4\pi\epsilon_0} \int \frac{\rho dV}{|\vec{r} - \vec{r}_i|}$$

LENZOV PRAVILO



$\vec{\nabla} \times \vec{E}$ - rotacija el. polja

$$\text{B. MJ: } \vec{\nabla} \times \vec{E} = - \frac{\partial \vec{B}}{\partial t}$$

$$\frac{\partial \vec{B}}{\partial t}$$

\sim promjena magnetskog toka

- po Stokesu će \vec{E} imati barem 1 komponentu
će kružiti redom

→ to polje izaziva struju u istom smjeru - pravilo
dodjeljuje smjer mag. polja (palac pokazuje u
smjeru struje)