Deep Learning & Applied Al

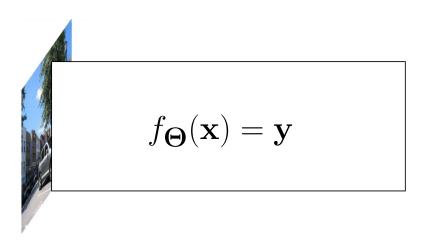
Overfitting and going nonlinear

Emanuele Rodolà rodola@di.uniroma1.it



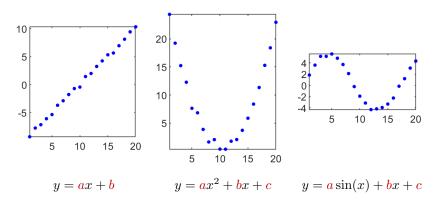
A glimpse into neural networks

In deep learning, we deal with highly parametrized models called deep neural networks:

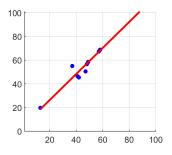


Parametrized models

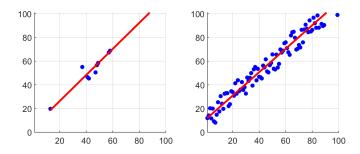
The parameters describe the behavior of the network, and must be solved for.



From a technical standpoint, our task is to determine the parameters Θ .

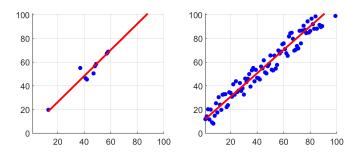


Assumption: linear model



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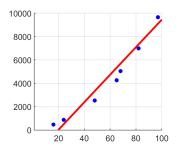
More data allows us to improve our prediction



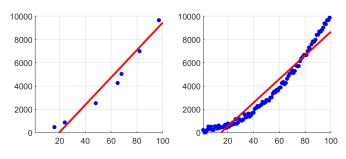
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What if the assumption (i.e. linear prior here) is wrong?

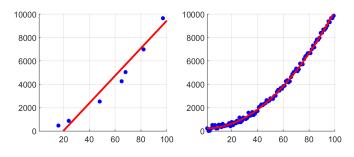


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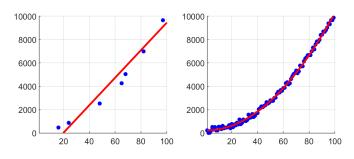


Assumption: linear model

More data confutes our assumptions



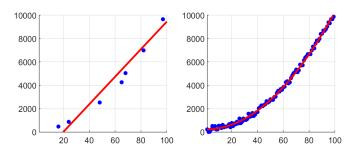
Assumption: quadratic model



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Key questions:

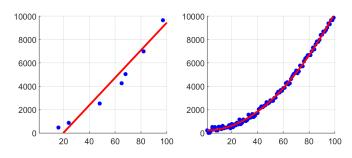
• How to select the correct distribution?



Assumption: quadratic model

Key questions:

- How to select the correct distribution?
- How much data do we need?



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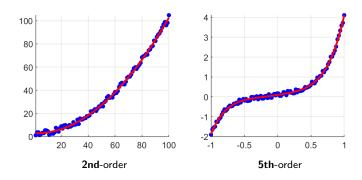
How to select the correct distribution?



- How much data do we need?
- What if the correct distribution does not admit a simple expression? questo ultimo punto è riferito particolarmente al DL

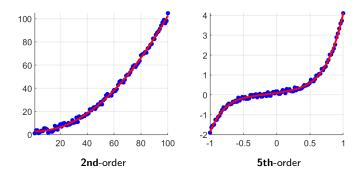
Polynomial regression

After the linear model, the simplest thing is a polynomial model.



Polynomial regression

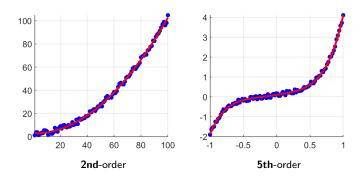
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The number of parameters grows with the order.

Polynomial regression

After the linear model, the simplest thing is a polynomial model.



The number of parameters grows with the order.

More data are needed to make an informed decision on the order.

sembra che sia possibile trovare una curva polinomiale che si adatta bene a qualsiasi problema. In realtà questo è in parte vero, ma le curve polinomiali hanno alcune limitazioni...

attenzione al nome: chiamata così sembra che la funzione Polynomial regression non sia lineare, ma invece lo è! Per evitare confusione, si può chiamare...

$$y_i = a_3 x_i^3 + a_2 x_i^2 + a_1 x_i + b$$
 for all data points $i = 1, ..., n$

$$y_i = b + \sum_{j=1}^k a_j x_i^j$$
 for all data points $i = 1, \dots, n$

$$y_i = \mathbf{b} + \sum_{j=1}^k \mathbf{a}_j x_i^j$$
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Remark: Despite the name, polynomial regression is still linear in the parameters. It is polynomial with respect to the data.

$$y_i = \mathbf{b} + \sum_{j=1}^k \mathbf{a}_j x_i^j$$
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In matrix notation:

$$\underbrace{\begin{pmatrix} y_1 \\ y_2 \\ \vdots \\ y_n \end{pmatrix}}_{\mathbf{y}} = \underbrace{\begin{pmatrix} x_1^k & x_1^{k-1} & \cdots & x_1 & 1 \\ x_2^k & x_2^{k-1} & \cdots & x_2 & 1 \\ \vdots & \vdots & \vdots & \vdots & \vdots & \vdots \\ x_n^k & x_n^{k-1} & \cdots & x_n & 1 \end{pmatrix}}_{\mathbf{X}} \underbrace{\begin{pmatrix} a_k \\ a_{k-1} \\ \vdots \\ a_1 \\ b \end{pmatrix}}_{\mathbf{\theta}}$$

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The same exact least-squares solution as with linear regression applies, with the requirement that k < n. Ia condizione in specifica che bisogna avere sempre almeno più data points del grado della polinomiale

Polynomial fitting

An application of the Stone-Weierstrass theorem tells us:

If f is continuous on the interval [a,b], then for every $\epsilon>0$ there exists a polynomial p such that $|f(x)-p(x)|<\epsilon$ for all x.

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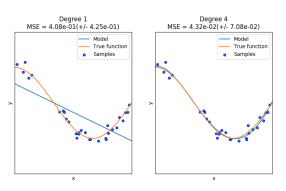
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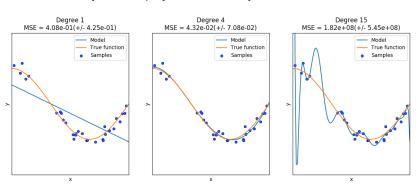
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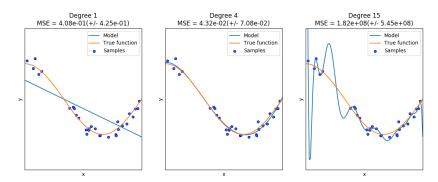


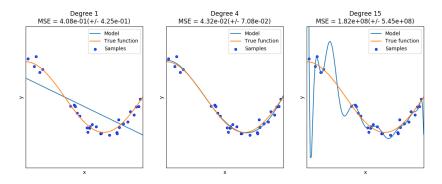
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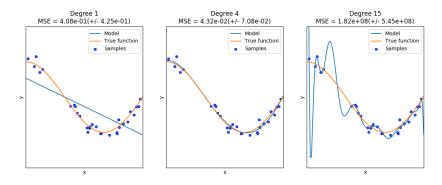
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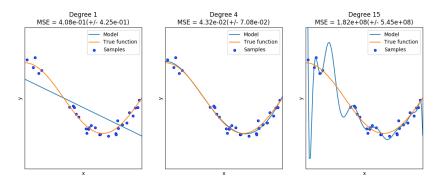




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Adding complexity can lead to overfitting and thus worse generalization.

This trade-off is always present, and still an open problem.

Different mechanisms defend us from under- and overfitting.

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Detection is relatively easier:

• Estimate the model parameters on a training set. (the MSE is minimized on example data)

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- Estimate the model parameters on a training set. (the MSE is minimized on example data)
- ② Large MSE on the training ⇒ underfitting
- Small MSE on the training ⇒
 Apply the model parameters to a validation set.
 (the MSE is computed on different example data)

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Different mechanisms defend us from under- and overfitting.

- Estimate the model parameters on a training set. (the MSE is minimized on example data)
- ② Large MSE on the training ⇒ underfitting
- Small MSE on the training ⇒ Apply the model parameters to a validation set. (the MSE is computed on different example data)
- $\textbf{ 4 Large MSE on the validation} \Rightarrow \textbf{overfitting} \Rightarrow \textbf{bad generalization}$

Underfitting vs. Overfitting

Underfitting: large training error, large validation error

Underfitting vs. Overfitting

Underfitting: large training error, large validation error

Overfitting: (very) small training error, large validation error

Not done yet

"If f is continuous on the interval [a,b], then for every $\epsilon>0$ there exists a polynomial p such that $|f(x)-p(x)|<\epsilon$ for all x."

So is polynomial regression all we need?

Not done yet

"If f is continuous on the interval [a, b], then for every $\epsilon > 0$ there exists a polynomial p such that $|f(x) - p(x)| < \epsilon$ for all x."

So is polynomial regression all we need?

Not really!

- Different loss than MSF
- Regularization ===
- se si conoscono altre informazioni sui dati a priori, queste rendono Additional priors difficile l'individuazione della soluzione polinomiale
- le reti neurali, durante il processo di allenamento producono Intermediate features le feature intermedie che sono molto utili. I modelli polinomiali non permettono ciò
- Flexibility
- Regression (predict a value) vs. classification (predict a category)

What if we want to predict a category instead of a value?

$$f_{\Theta}(\bigcirc) = \{0, 1\}$$

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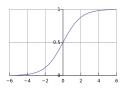
Instead: Modify the loss to minimize over categorical values directly.

New loss:

$$\ell_{\Theta}(\lbrace x_i, y_i \rbrace) = \sum_{i=1}^{n} (y_i - \sigma(\underbrace{ax_i + b}))^2$$

Here, σ is the nonlinear logistic sigmoid:

$$\sigma(x) = \frac{1}{1 + e^{-x}}$$

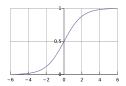


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New loss:

in pratica applica il tresholding (dato dalla sigmoide) all'interno della loss function stessa

$$\ell_{\Theta}(\{x_i, y_i\}) = \sum_{i=1}^{n} (y_i - \sigma(\underbrace{ax_i + b}))^2$$
 non-convex

anche detta saturation function o equalizer

Here, σ is the nonlinear logistic sigmoid:

se si moltiplica x per un coeff, la curva diventa più ripida $\sigma(x) = \frac{1}{1 + e^{-x}}$ (quindi cambia più in fretta)

 σ has a saturation effect as it maps $\mathbb{R} \mapsto (0,1)$.

New loss: quindi ora la loss function è così

$$\ell_{\Theta}(\{x_i,y_i\}) = \sum_{i=1}^n c(x_i,y_i) \,, \quad \text{with}$$

$$c(x_i,y_i) = \begin{cases} -\ln(\sigma(ax_i+b)) & y_i = 1 \\ -\ln(1-\sigma(ax_i+b)) & y_i = 0 \end{cases}$$
scritta in formula...

Here, σ is the nonlinear logistic sigmoid:

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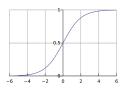
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$$c(x_i,y_i) = -y_i \ln(\sigma(ax_i+b)) - (1-y_i) \ln(1-\sigma(ax_i+b))$$
 hvex 1 se giusto 0 se è giusto ...è così

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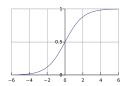
New convex loss:

è la cross-entropy loss

$$\ell_{\Theta}(\{x_i, y_i\}) = -\sum_{i=1}^{n} y_i \ln(\sigma(ax_i + b)) + (1 - y_i) \ln(1 - \sigma(ax_i + b))$$

Here, σ is the nonlinear logistic sigmoid:

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(taylor?)

Since the loss is convex, the first-order conditions apply:

$$\nabla_{\Theta}\ell_{\Theta}=0$$

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$$\nabla_{\Theta}\sum_{i=1}^n y_i \ln(\sigma(ax_i+b)) + (1-y_i) \ln(1-\sigma(ax_i+b)) = 0$$
 ci va il - where $\Theta=\{a,b\}.$

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where $\Theta = \{a, b\}$.

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$$y_i \nabla_{\Theta} \underbrace{\ln(\sigma(ax_i + b))}_{f(g(h(\Theta)))} + (1 - y_i) \nabla_{\Theta} \ln(1 - \sigma(ax_i + b))$$

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where $\Theta = \{a, b\}$.

Consider the gradient of each term in the summation:

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$$\frac{\partial}{\partial \mathbf{a}} f(g(h(\mathbf{a}, b))) = \frac{\partial f}{\partial g} \cdot \frac{\partial g}{\partial h} \cdot \frac{\partial h}{\partial \mathbf{a}}$$

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$$\nabla_{\Theta} \sum_{i=1}^{n} y_i \ln(\sigma(ax_i + b)) + (1 - y_i) \ln(1 - \sigma(ax_i + b)) = 0$$

where $\Theta = \{a, b\}$.

Consider the gradient of each term in the summation:

$$y_i \nabla_{\Theta} \underbrace{\ln(\sigma(ax_i + b))}_{f(g(h(\Theta)))} + (1 - y_i) \nabla_{\Theta} \ln(1 - \sigma(ax_i + b))$$

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Apply the chain rule to each partial derivative:

$$\frac{\partial}{\partial a}\ln(\sigma(\mathbf{a}x_i+b)) = (1 - \sigma(\mathbf{a}x_i+b))x_i$$

And similarly for the second term and for parameter b.

By looking at the partial derivative:

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we see that the parameters enter the gradient in a nonlinear way.

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linear regression		
linear regression $+$ Tikhonov		
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linear regression	convex	least squares
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quindi non c'è una soluzione per a e b

model		loss	solution
linear regression		convex	least squares
linear regression $+$ Tikho	nov	convex	least squares
logistic regression	/	convex	nonlinear optimization

matrice di regolarizzazione nella minimizzazione del MSE (anche detta **ridge regression**)

che sarebbe GD

Suggested reading

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On polynomial regression vs. neural nets: https://arxiv.org/pdf/1806.06850
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Proof that the logistic loss is convex:
https://math.stackexchange.com/questions/1582452/
logistic-regression-prove-that-the-cost-function-is-convex