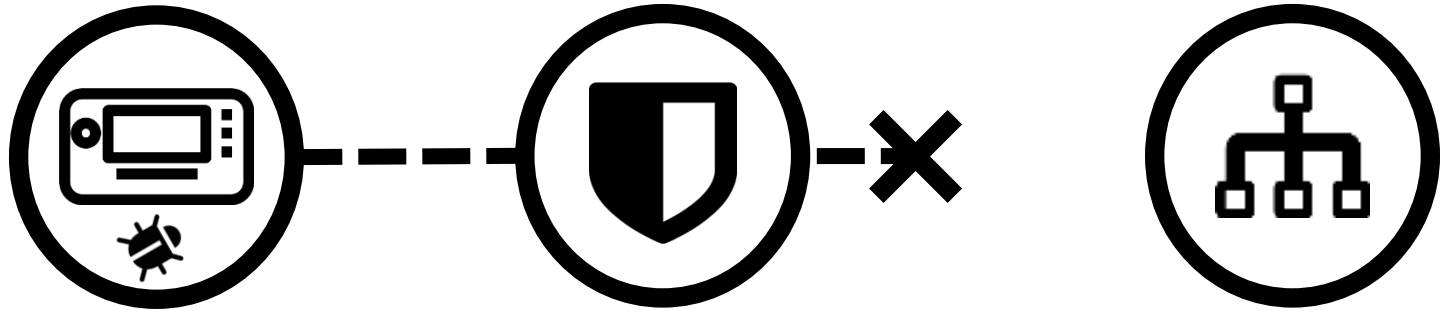


CAN Bus Firewall



Purpose



Ensure compromised IVIs



cannot disrupt



safety critical systems

Overview



IVI

Runs a wide variety of software that may be compromised through telematics link

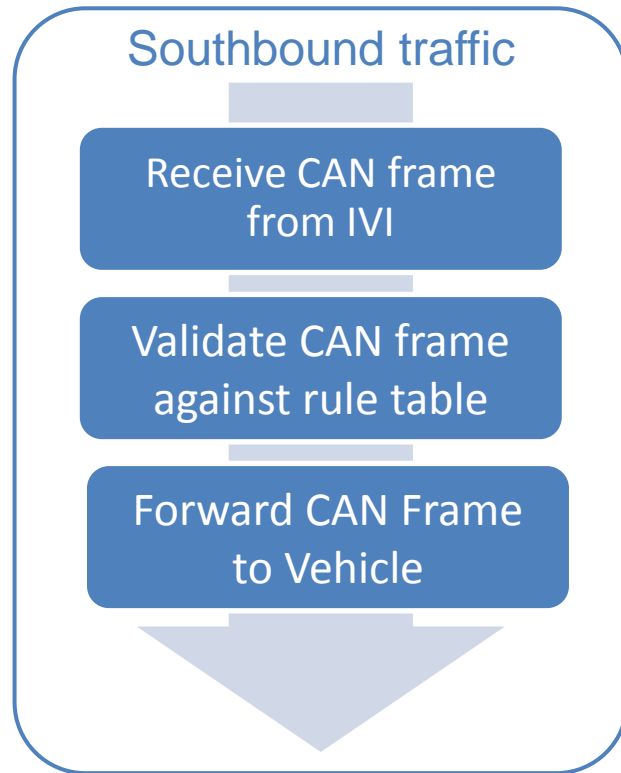
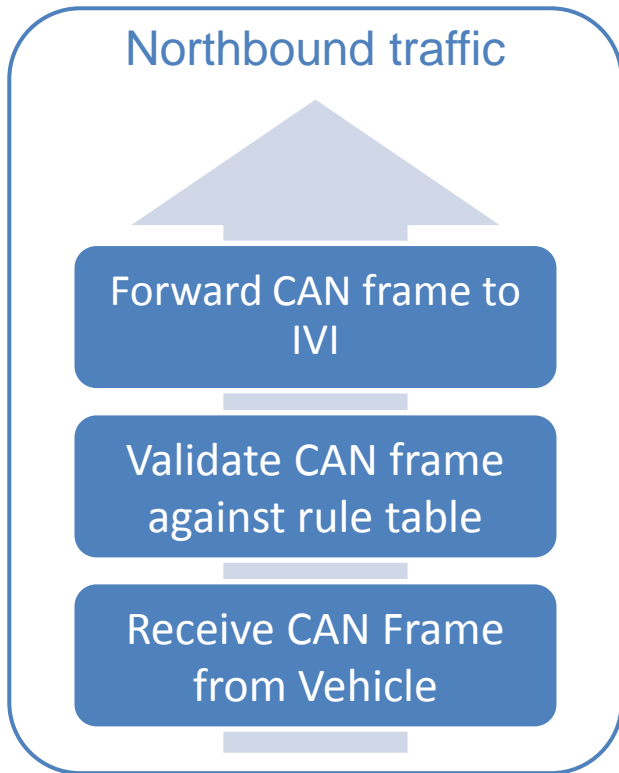
CAN Firewall

Hardware microcontroller on CAN bus filtering CAN traffic based on configurable rules

ECUs

Safety-critical vehicle controllers managing breaks, throttle, steering, etc.

Northbound vs. Southbound Traffic



Use Case: Update rules

A new firewall rule is created and is signed using device-specific key

Rule is pushed over the air to the IVI

IVI Firewall Manager forwards the signed rule to the firewall as a specific CAN frame

Firewall validates signature of received frame and stores new rule.

Backend Server

Rule Admin



IVI

Firewall Manager



Firewall

Rule Manager

Rule Structure [1/2]

Mask	Filter	ID XForm	Data XForm	ID Operand	Data Operand
0xFFFFFFFF	0x00000012	AND	OR	0x00FFFFFF	0x000000FFFFFFFFFFFF

Mask

- Frame ID of an incoming frame is masked against rule mask
- Only bits set in the mask will be matched against the filter

Filter

- ANDed against the masked Frame ID of incoming frame
- Frame IDs passing filter are intercepted

See <http://www.cse.dmu.ac.uk/~eg/tele/CanbusIDandMask.html> for details

Rule Structure [2/2]

Mask	Filter	ID XForm	Data XForm	ID Operand	Data Operand
0xFFFFFFFF	0x00000012	AND	OR	0x00FFFFFF	0x000000FFFFFFFFFFFF

ID XForm

- Determines transformation applied to outbound Frame ID (SET, AND, OR, XOR, INV)

Data XForm

- Determines transformation applied to outbound Data (SET, AND, OR, XOR, INV)

ID Operand

- Transformation operand applied to outbound Frame ID

Data Operand

- Transformation operand applied to outbound Data

A Rule can also specify that the frame is to be silently dropped or passed as is.

CAN Rule Table

Prio	Mask	Filter	ID XForm	Data XForm	ID Operand	Data Operand
0x01	0xFFFFFFFF	0x00000012	AND	OR	0x00FFFFFF	0x000000FFFFFFFFFFFF
0x02	0xFFFFFFFF0	0x00000120	SET	SET	0x01234567	0x0123456780ABCDEF
0x7E	0x00000000	0x00000000	DROP	DROP	0x00000000	0x0000000000000000

Prioritize

- Rules are applied to incoming frames in order of ascending priority

Match and process

- A rule-matching frame is processed by that rule and is then forwarded to its destination

Forward to next rule

- A non-matching frame passed on to the rule with the next ascending ID

If no rule matches, the frame is forwarded unmodified to its destination

CAN Rule Configuration – Common Header

Frame ID	Data: Prio [1]	Data: Cmd [1]
0x00004711	0x04	[RULE]

Frame ID [32 bits]

Factory-configured CAN Frame that is intercepted and interpreted by the CAN Firewall.

Prio [0x00-0x7F | 0x80-0xFF] [1 byte]

Specifies the priority of the rule that is being prepared and which .
0x00-0x7F applies to northbound traffic. 0x80-0xFF applies to southbound traffic.
All commands setting up and storing a single rule will use the same Prio.

Cmd [PREP_RULE1, PREP_RULE2, PREP_RULE3 , PREP_RULE4, PREP_RULE5,PREP_RULE6, STORE_RULE] [1 byte]

Sets up a single rule. PREP_RULE1 – PREP_RULE6 are transmitted with the same Prio. STORE_RULE is then transmitted with the given Prio to store the single rule specified by the previous PREP rule commands.

CAN Rule Configuration – PREP_RULE1

Frame ID	Prio [1]	Cmd [1]	Mask [4]	XForm [1]	Rsvd [1]
0x00004711	0x04	0x01	0x0000FFFF	0x01	0x00

Cmd [PREP_RULE1] [1 byte]

PREP_RULE1 specifies the rule priority and the mask to apply, and the transform operators for the rule.

Mask [32 bit value] [4 bytes]

Mask to apply to incoming Frame ID prior to filtering.

XForm [SET_AND] [1 byte]

The transformation to apply to Frame ID and Data. Combination of SET, AND, OR, XOR, and NEG. Upper four bits defines Frame ID operator. Lower four bits defines Data operator.

Reserved for future use. Set to 0

CAN Rule Configuration – PREP_RULE2

Frame ID	Prio [1]	Cmd [1]	Filter [4]	DtOper1 [2]
0x00004711	0x04	0x02	0x0000AAC1	0x0100

Cmd [PREP_RULE2] [1 byte]

PREP_RULE2 specifies the filter to apply to incoming Frame IDs and the low 16 bits of the Data transformation operand

Filter [4] [32 bit value] [4 bytes]

Filter to apply to incoming Frame ID that has been masked.

DtOper1 [16 bit value] [2 bytes]

Specifies the lower 16 bits of the data operand to provide to the data transform operator (AND, OR, XOR, NEG).

CAN Rule Configuration – PREP_RULE3

Frame ID	Prio [1]	Cmd [1]	DtOper2 [6]
0x00004711	0x04	0x03	0x070605040302

Cmd [PREP_RULE3] [1 byte]

PREP_RULE2 specifies the high 48 bits of the operand to apply to the payload transform operator.

DtOper2 [48 bit value] [6 bytes]

Specifies the upper 48 bits of the data operand to provide to the data transform operator (AND, OR, XOR, NEG).

DtOper1 and DtOper2 in the example above are concatenated to: 0x0706050403020100

CAN Rule Configuration – PREP_RULE4

Frame ID	Prio [1]	Cmd [1]	IDOper [4]	HMAC1 [2]
0x00004711	0x04	0x04	0xFFFF0000	0x0100

Cmd [PREP_RULE4] [1 byte]

Specifies the Frame ID operand and the lowest 2 bytes of the HMAC-SHA1signature

IDOper [32 bit value] [4 bytes]

Specifies the Frame ID operand to provide to the Frame ID transform operator

HMAC1 [16 bit value] [2 bytes]

Specifies bits 0-15 bits of the HMAC-SHA1 signature, generated with the key flashed into the Firewall at the factory.

CAN Rule Configuration – PREP_RULE5

Frame ID	Prio [1]	Cmd [1]	HMAC2 [6]
0x00004711	0x04	0x05	0x070605040302

Cmd [PREP_RULE5] [1 byte]

Specifies six bytes of the HMAC-SHA1 signature

HMAC2 [48 bit value] [6 bytes]

Specifies bits 16-63 of the HMAC-SHA1 signature

CAN Rule Configuration – PREP_RULE6

Frame ID	Prio [1]	Cmd [1]	HMAC3 [6]
0x00004711	0x04	0x06	0x0D0C0B0A0908

Cmd [PREP_RULE6] [1 byte]

Specifies six bytes of the HMAC-SHA1 signature

HMAC3 [48 bit value] [6 bytes]

Specifies bits 64-127 of the HMAC-SHA1 signature

CAN Rule Configuration – STORE_RULE

Frame ID	Prio [1]	Cmd [1]	HMAC4 [4]	Seq [2]
0x00004711	0x04	0x07	0x11100F0E	0x0001

Cmd [STORE_RULE] [1 byte]

Stores the rule specified by PREP_RULE1 to PREP_RULE6

HMAC4 [32 bit value] [4 bytes]

Specifies bits 128-159 of the HMAC-SHA1 signature

Seq [16 bit value] [2 byte]

Unique sequence number for this given Prio. Value must be greater than previously received value for the given Prio in order for the rule to be processed. Stops replay attacks.

CAN Rule Configuration – Example

Frame ID	Prio	Cmd	Command Parameters		
0x00004711	0x04	0x01 [PREP_RULE1]	Mask: 0x0000FFFF	XForm: 0x01	Rsvd: 0x00
0x00004711	0x04	0x02 [PREP_RULE2]	Filter: 0x0000AAC1	DtOper1: 0x0100	
0x00004711	0x04	0x03 [PREP_RULE3]	DtOper2: 0x070605040302		
0x00004711	0x04	0x04 [PREP_RULE4]	IDOper: 0xFFFF0000	HMAC1: 0x0100	
0x00004711	0x04	0x05 [PREP_RULE5]	HMAC2: 0x070605040302		
0x00004711	0x04	0x06 [PREP_RULE6]	HMAC3: 0x0D0C0B0A0908		
0x00004711	0x04	0x07 [STORE_RULE]	HMAC4: 0x11100F0E	Seq: 0x0001	



Prio	Mask	Filter	ID XForm	Data XForm	ID Operand	Data Operand
0x04	0x0000FFFF	0x0000AAC1	SET	AND	0xFFFF0000	0x0706050403020100

Signature Payload used by HMAC-SHA1

Frame ID	Prio	Cmd	Command Parameters		
0x00004711	0x04	0x01 [PREP_RULE1]	Mask: 0x0000FFFF	XForm: 0x01	Rsvd: 0x00
0x00004711	0x04	0x02 [PREP_RULE2]	Filter: 0x0000AAC1	DtOper1: 0x0100	
0x00004711	0x04	0x03 [PREP_RULE3]	DtOper2: 0x070605040302		
0x00004711	0x04	0x04 [PREP_RULE4]	IDOper: 0xFFFF0000	HMAC1: 0x0100	
0x00004711	0x04	0x05 [PREP_RULE5]	HMAC2: 0x070605040302		
0x00004711	0x04	0x06 [PREP_RULE6]	HMAC3: 0x0D0C0B0A0908		
0x00004711	0x04	0x07 [STORE_RULE]	HMAC4: 0x11100F0E	Seq: 0x0001	



Prio	Mask	Filter	XForm	Rsvd	ID Operand	Data Operand	Sequence
0x04	0x0000FFFF	0x0000AAC1	0x01	0x00	0xFFFF0000	0x0706050403020100	0x0001



Signature Payload string [25 bytes]

0x040000FFFF0000AAC10100FFFF000007060504030201000001