

$$4a) \quad \int_0^\theta \sec \phi \, d\phi = \int_0^\theta \sec \phi \frac{\sec(\phi) + \tan(\phi)}{\sec(\phi) + \tan(\phi)} \, d\phi$$

$$= \int_0^\theta \frac{\sec^2 \phi + \sec \phi \tan \phi}{\sec \phi + \tan \phi} \, d\phi$$

$$u = \sec \phi + \tan \phi$$

$$\frac{du}{d\phi} = \sec^2 \phi + \sec \phi \tan \phi$$

~~$$\int_a^b \frac{du}{u} = \ln(u) \Big|_a^b = \ln|\sec(\phi) + \tan(\phi)| \Big|_0^\theta$$~~

$$\int_a^b \frac{du}{u} = \ln(u) \Big|_a^b = \ln|\sec(\phi) + \tan(\phi)| \Big|_0^\theta$$

$$\therefore \int_0^\theta \sec \phi \, d\phi = \ln|\sec(\theta) + \tan(\theta)|$$