

backpropagation算法python代码实现讲解

具体神经网络参见第一个笔记

$$w_k \rightarrow w'_k = w_k - \eta \frac{\partial C}{\partial w_k}$$

$$b_l \rightarrow b'_l = b_l - \eta \frac{\partial C}{\partial b_l}.$$

批量梯度更新

```
class Network(object):
    ...
    # 参数, mini_batch:要批量更新的输入实例的集合;eta:学习率
    def update_mini_batch(self, mini_batch, eta):
        # nable_w、nable_b分别用来装对每层权重矩阵和偏向向量求的偏导数
        nable_b = [np.zeros(b.shape) for b in self.biases]
        nable_w = [np.zeros(w.shape) for w in self.weights]
        # x是输入实例, y是输出标签,对mini_batch的所有实例求偏导
        for x, y in mini_batch:
            # 通过backpropagation算法求出对权重和偏向的偏导数
            delta_nable_b, delta_nable_w = self.backprop(x, y)
            # 对所有实例的偏导数进行累加(因为是随机梯度下降)
            # nb:一层的偏向向量的累积和,nw一层的权重矩阵的累积和, dnb:一层的偏向向量的
            # 偏导数, dnw,一层的矩阵矩阵的偏导数
            nable_b = [nb+dnb for nb, dnb in zip(nable_b, delta_nable_b)]
            nable_w = [nw+dnw for nw, dnw in zip(nable_w, delta_nable_w)]
            # 随机梯度下降需要除mini_batch的size
        # 根据公式计算最后的每层的权重矩阵和偏向向量
        # weights:保存每层的权重矩阵, biases: 保存每层的偏向向量
        self.weights = [w-(eta/len(mini_batch))*nw
                        for w, nw in zip(self.weights, nable_w)]
        self.biases = [b-(eta/len(mini_batch))*nb
                       for b, nb in zip(self.biases, nable_b)]
```

backpropagation算法

```
class Network(object):
    ...
    def backprop(self, x, y):
        nable_b = [np.zeros(b.shape) for b in self.biases]
        nable_w = [np.zeros(w.shape) for w in self.weights]
        # feedforward (正向更新)
        # 输入层的activation
```

```

activation = x
# 用来存储神经网络每层的activation值(包括输入层, 隐藏层, 输出层)
activations = [x]
# 一个list用来存储每层中间变量
zs = []
for b, w in zip(self.biases, self.weights):
    # 求出中间变量的值
    z = np.dot(w, activation)+b
    # 添加到list中
    zs.append(z)
    # 求出该层activation
    activation = sigmoid(z)
    # 添加到activations中
    activations.append(activation)
# backward pass (反向更新参数)
# 根据公式求出输出层的error
delta = self.cost_derivative(activations[-1], y) * \
    sigmoid_prime(zs[-1])
# 根据公式求出输出层的偏导数 dC/dw和dC/dw
nabla_b[-1] = delta
nabla_w[-1] = np.dot(delta, activations[-2].transpose())
# 从倒数第二层向第二层反向更新
for l in xrange(2, self.num_layers):
    # 中间变量, 对应-l层的activation (注意-l)
    z = zs[-l]
    # 求出-l层激活函数导函数值
    sp = sigmoid_prime(z)
    # 根据公式计算出-l层的error
    delta = np.dot(self.weights[-l+1].transpose(), delta) * sp
    # 根据公式求出-l层的偏导数 dC/dw和dC/dw
    nabla_b[-l] = delta
    nabla_w[-l] = np.dot(delta, activations[-l-1].transpose())
# 返回计算好的2-L层的所有对权重和偏向的偏导数
return (nabla_b, nabla_w)

...
# Cost对最后一层activation求导
def cost_derivative(self, output_activations, y):
    # 根据Cost函数: cost = 1/2 * (y-a)^2, 求导得出cost' = a-y
    return (output_activations-y)
# 激活函数
def sigmoid(z):
    """The sigmoid function."""
    return 1.0/(1.0+np.exp(-z))
# 激活函数的导函数
def sigmoid_prime(z):
    return sigmoid(z)*(1-sigmoid(z))

```

backpropagation算法步骤

1. 输入 x : 设置输入层相应的activation $a^{\{1\}}$
2. 正向更新 对于每层 $l = 2, 3, \dots, L$ 计算: $z^{\{l\}} = w^{\{l\}} a^{\{l-1\}} + b^{\{l\}}$
 $a^{\{l\}} = \sigma(z^{\{l\}})$

3. 计算输出层的error δ^L : $\delta^L = \nabla_a C \odot \sigma'(z^L)$
4. 反向更新error(Backpropagate the error) 对于每层 $l = L-1, L-2, \dots, 2$ 计算: $\delta^l = (w^{l+1})^T \delta^{l+1} \odot \sigma'(z^l)$
5. 输出每层的偏导数($l = 2, 3, \dots, L$) 更新公式: $\frac{\partial C}{\partial w_{jk}^l} = a_{k,l-1} \delta_j^l \quad \text{和} \quad \frac{\partial C}{\partial b_j^l} = \delta_j^l$.
6. 返回所有的偏导数(∇_b, ∇_w)