



CODE COMPOSER TUTORIAL

Importing and general code operation

Abstract

This is a general user guide on how to run the code that was produced for testing the flywheel and accompanying hardware during the summer term 2017.

Tyler Larson

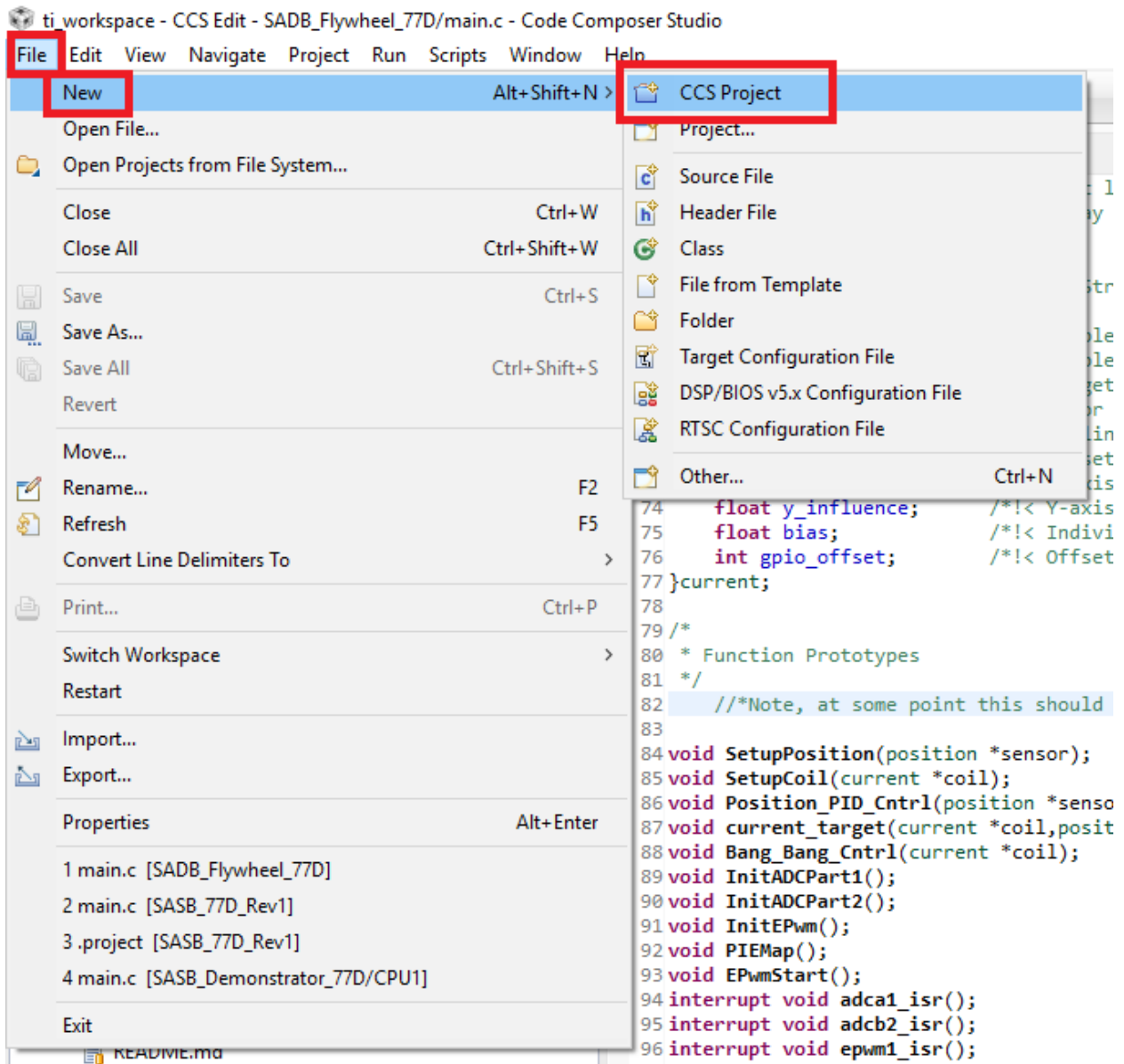
Tmlarson94@gmail.com or Lars9996@vandals.uidaho.edu

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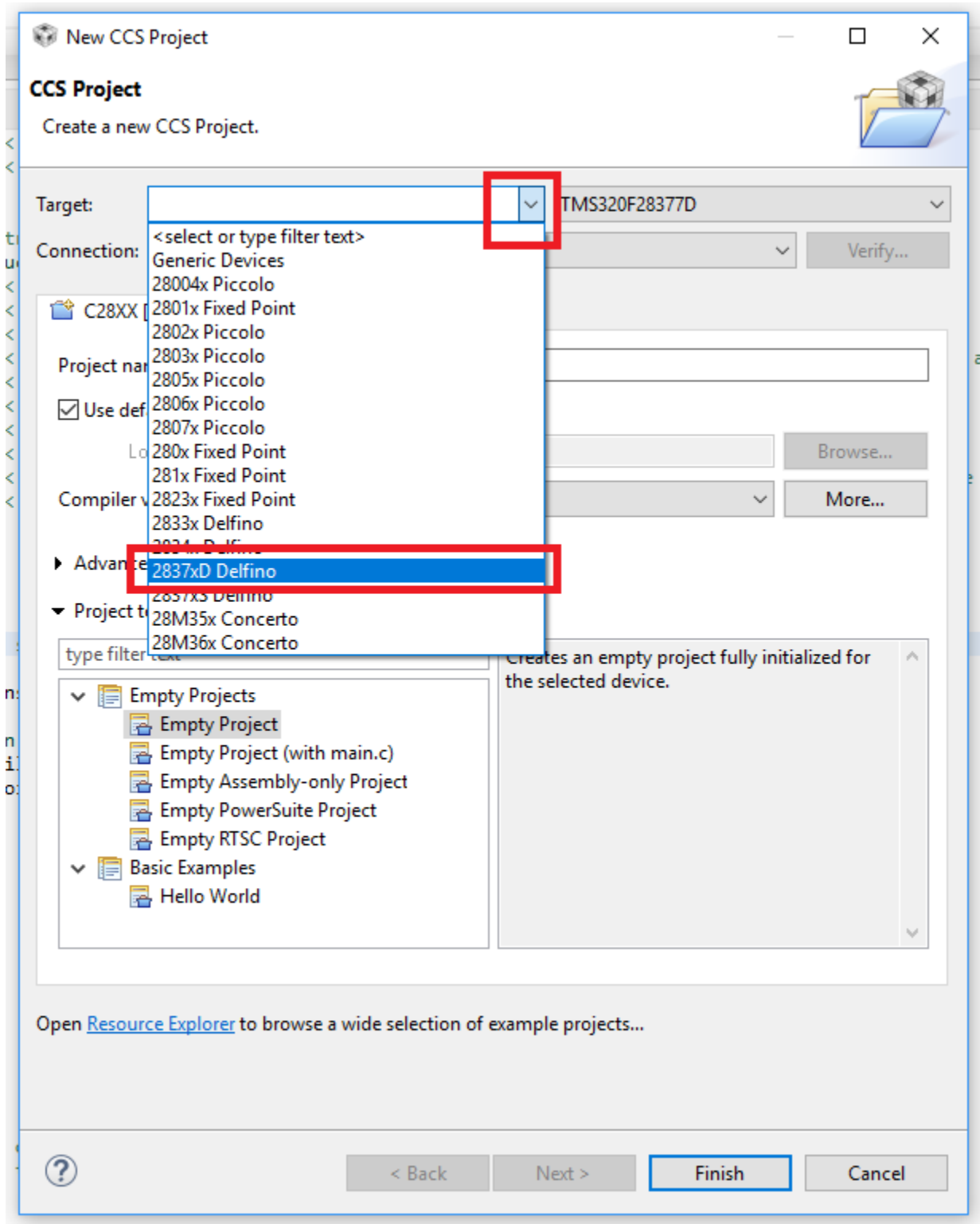
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Importing

- Click on "File", hover over "New", then click on "CSS Project"



- Next click on the Dropdown by "Target", and select "2837xD Delfino"



- After it is selected, the next dropdown automatically opens. Select "TMS320F28377D"

New CCS Project

Create a new CCS Project.

Target: **2837xD Delfino**

Connection: **TMS320F28377D**

C28XX [C2000]

Project name: **DADB_Flywheel_77D**

☒ Use default location

Location: **C:\ti_workspace\DADB_Flywheel_77D** **Browse...**

Compiler version: **TI v16.9.3.LTS** **More...**

Advanced settings

Project templates and examples

type filter text

- Empty Projects
 - Empty Project
 - Empty Project (with main.c)
 - Empty Assembly-only Project
 - Empty PowerSuite Project
 - Empty RTSC Project
- Basic Examples
 - Hello World

Creates an empty project fully initialized for the selected device. The project will contain an empty 'main.c' source-file.

Open [Resource Explorer](#) to browse a wide selection of example projects...

Finish **Cancel**

- Next make a name for the project and select a location to save it

New CCS Project

CCS Project
Create a new CCS Project.

Target: 2837xD Delfino TMS320F28377D

Connection: Verify...

C28XX [C2000]

Project name: DADB_Flywheel_77D

☒ Use default location

Location: C:\ti_workspace\DADB_Flywheel_77D Browse...

Compiler version: TI v16.9.3.LTS More...

Advanced settings

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Creates an empty project fully initialized for the selected device. The project will contain an empty 'main.c' source-file.

Open [Resource Explorer](#) to browse a wide selection of example projects...

? < Back Next > Finish Cancel

- Lastly select “Empty Project”, then click “Finish”

New CCS Project

CCS Project
Create a new CCS Project.

Target: 2837xD Delfino TMS320F28377D

Connection: Verify...

C28XX [C2000]

Project name: DADB_Flywheel_77D

☒ Use default location

Location: C:\ti_workspace\DADB_Flywheel_77D Browse...

Compiler version: TI v16.9.3.LTS More...

Advanced settings

Project templates and examples

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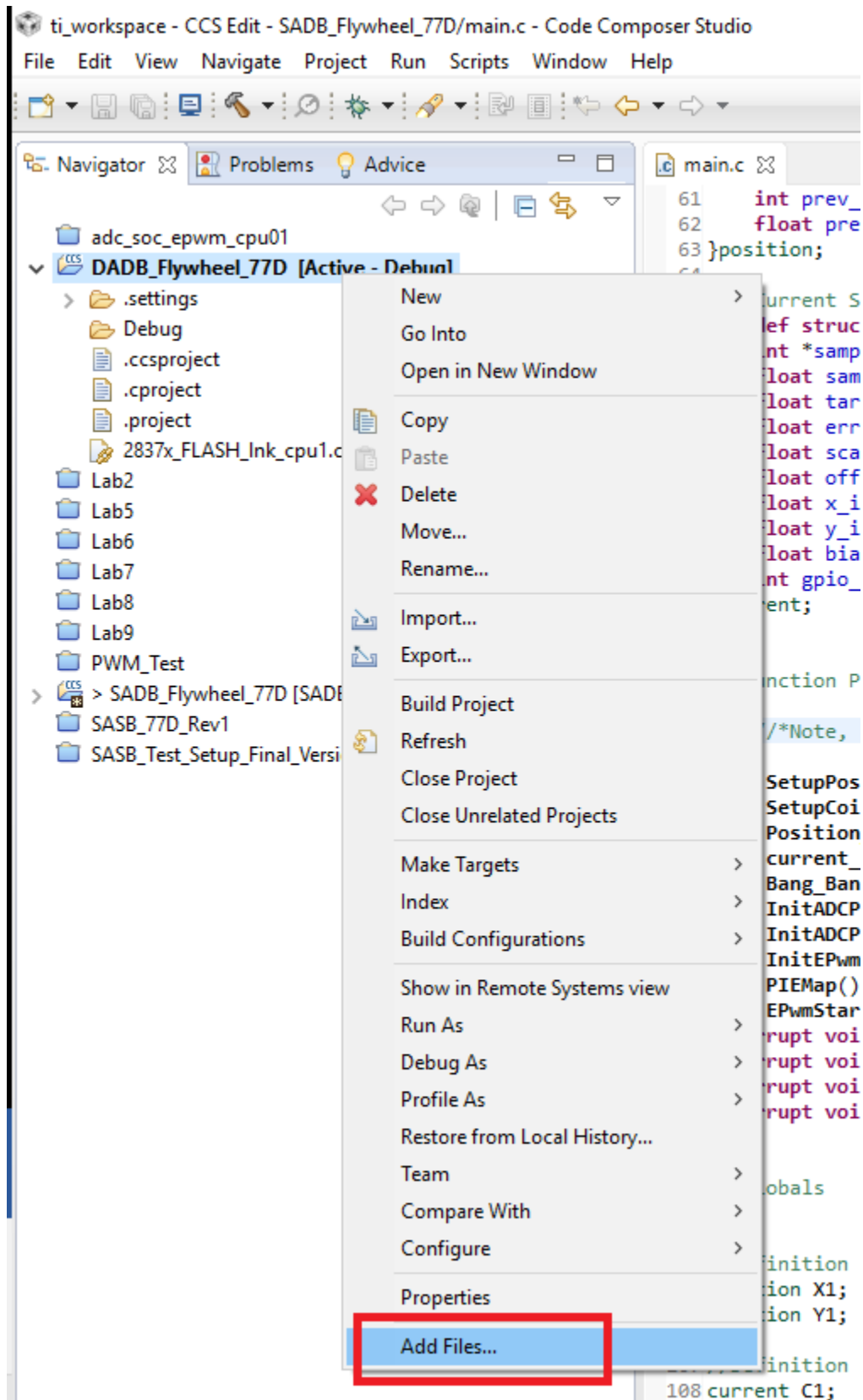
- Empty Projects
 - Empty Project**
 - Empty Project (with main.c)
 - Empty Assembly-only Project
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Creates an empty project fully initialized for the selected device.

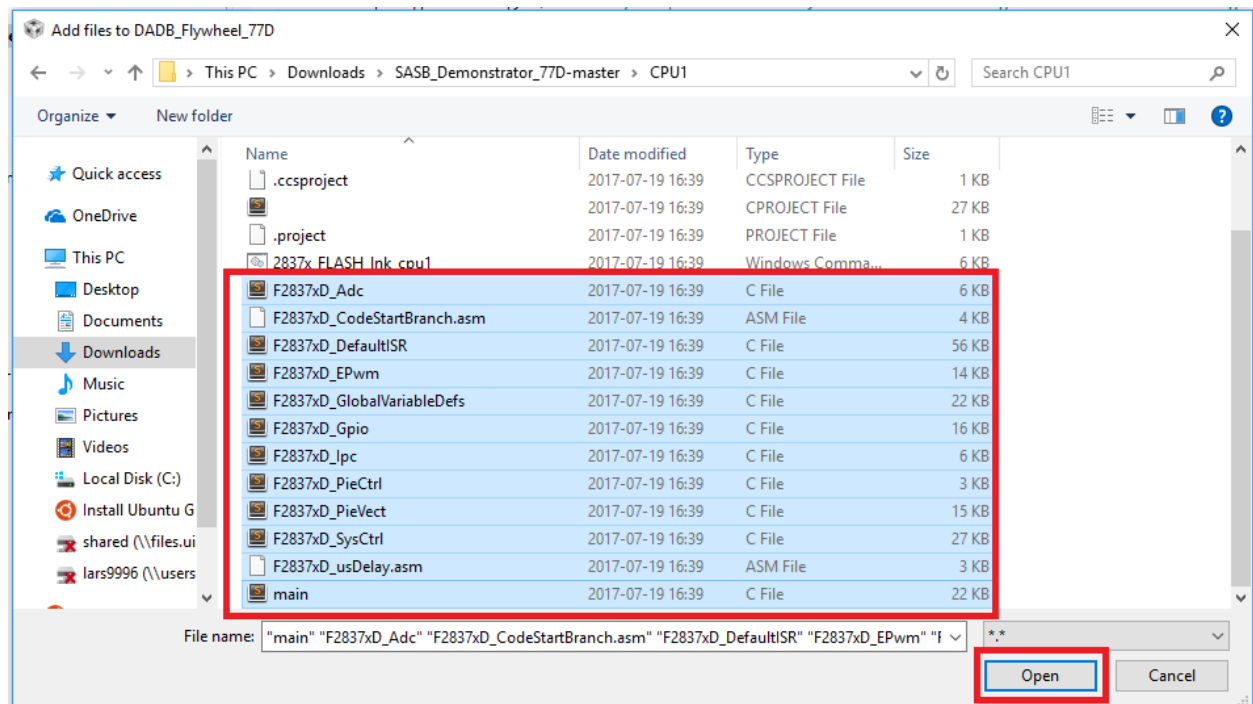
Open [Resource Explorer](#) to browse a wide selection of example projects...

Finish

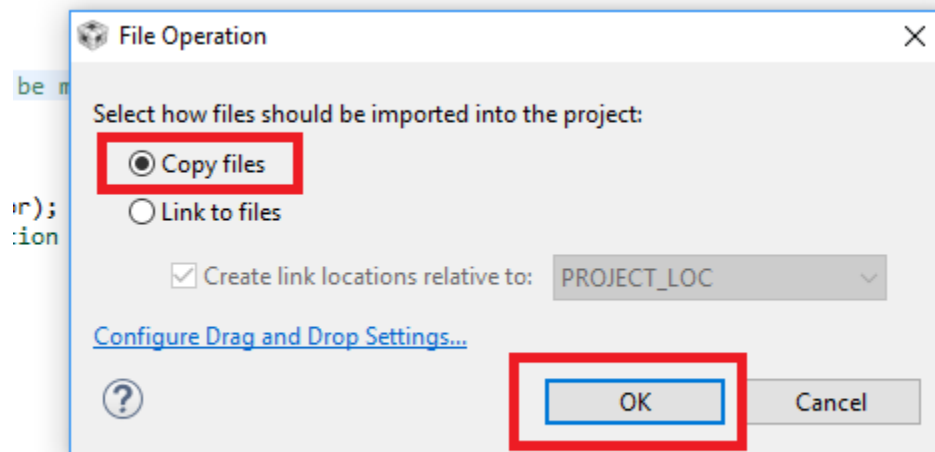
- Now right click on the new project and select "Add Files..."



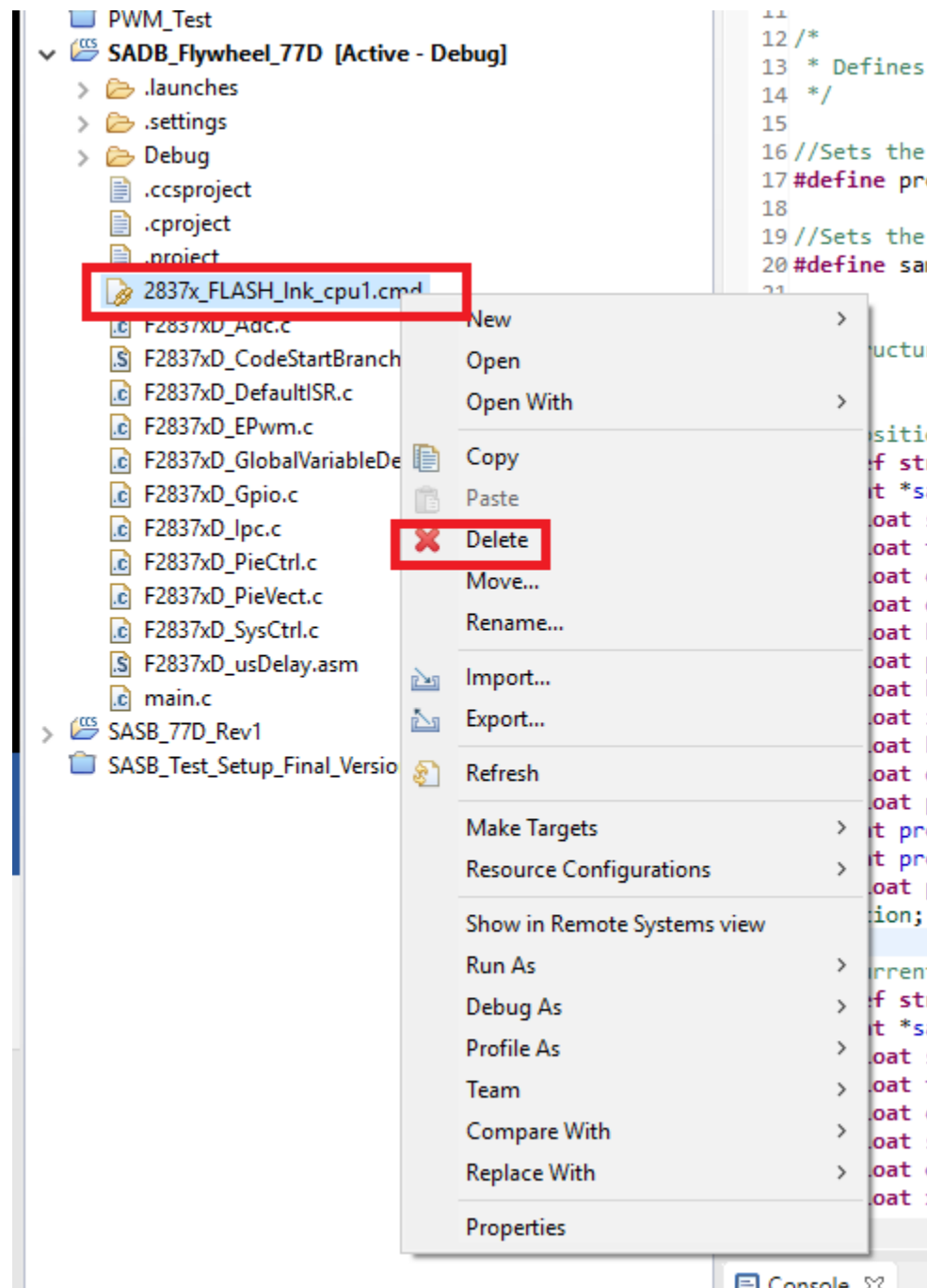
- Select the files shown in the image below and select “Open”



- Make sure that "Copy files" is selected, then press "OK"

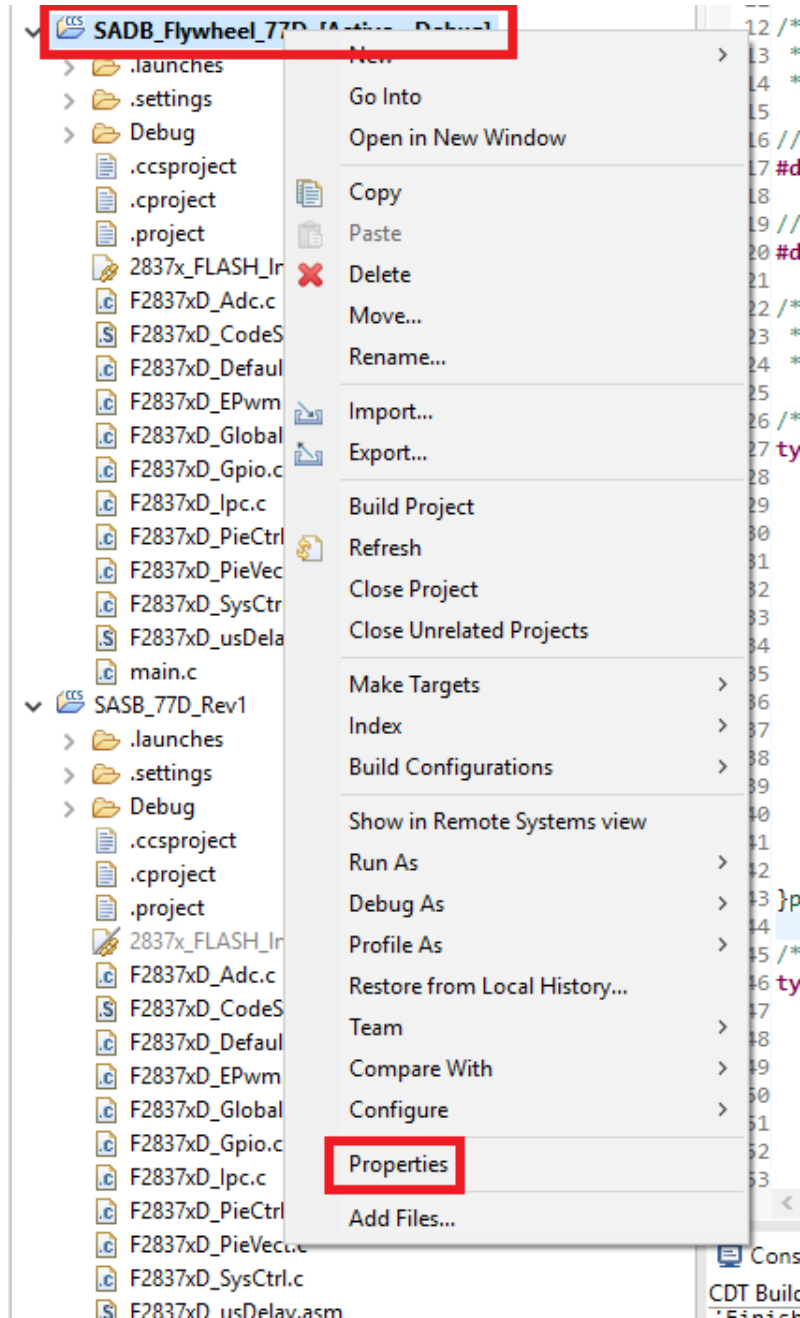


- The last step is to delete the “2837x_FLASH_Ink_cpu1.cmd” file from the resource list

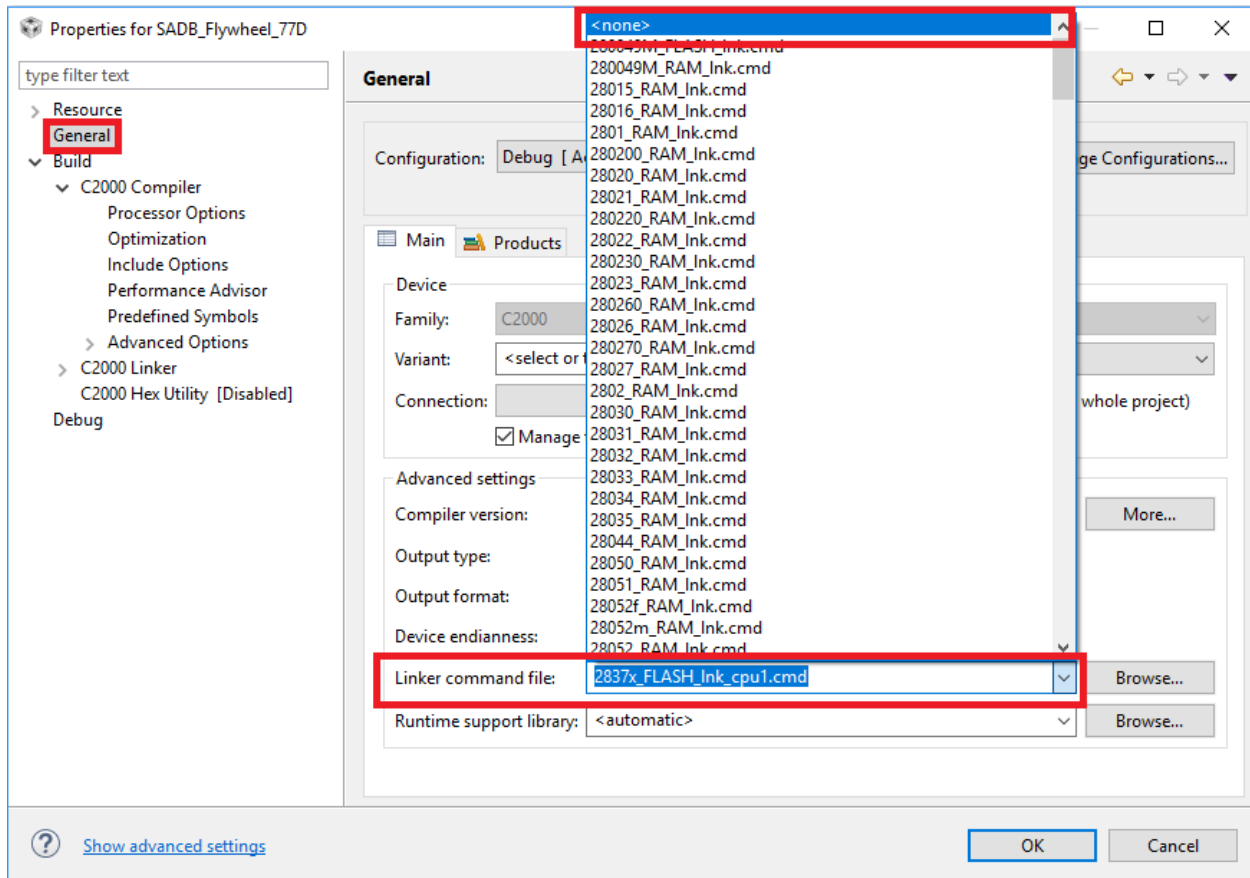


Properties Configuration

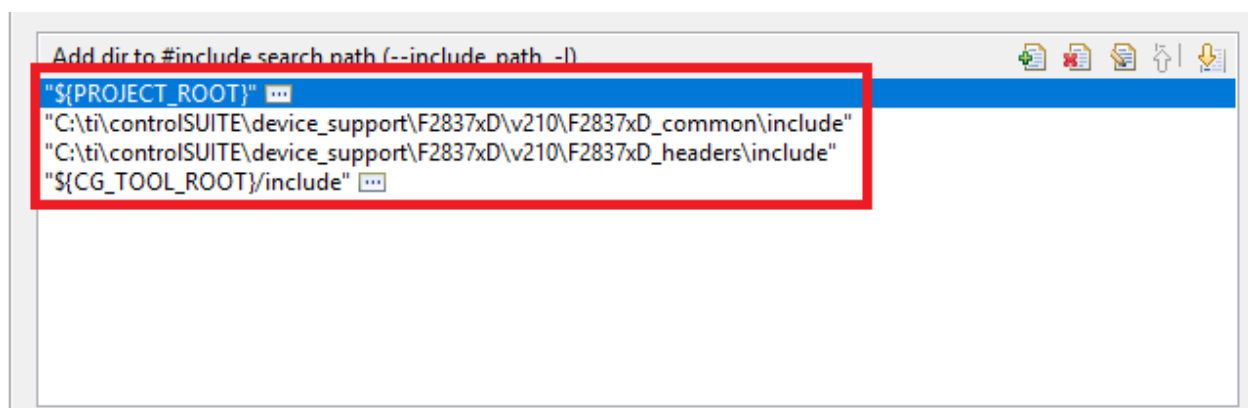
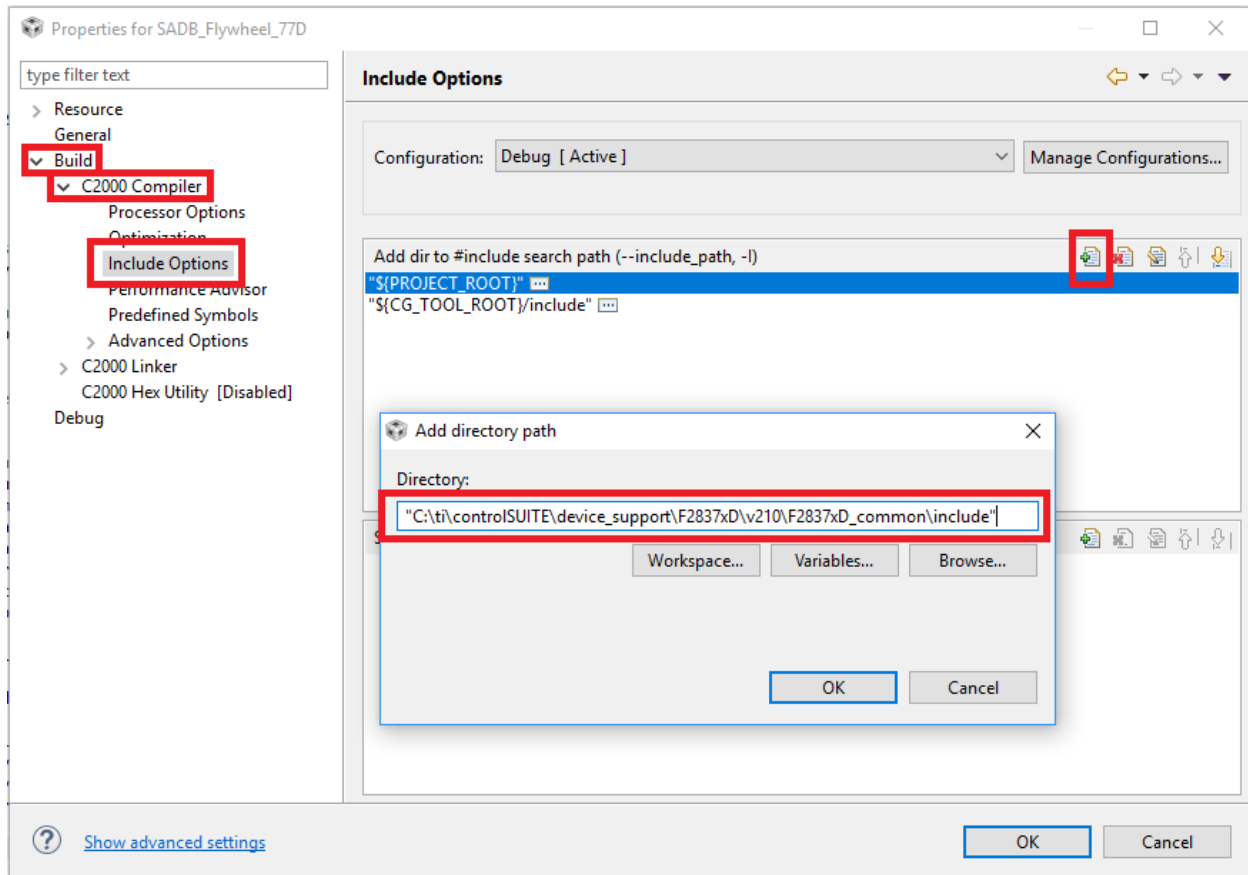
- Right click on the project and select “Properties”, to open the properties window



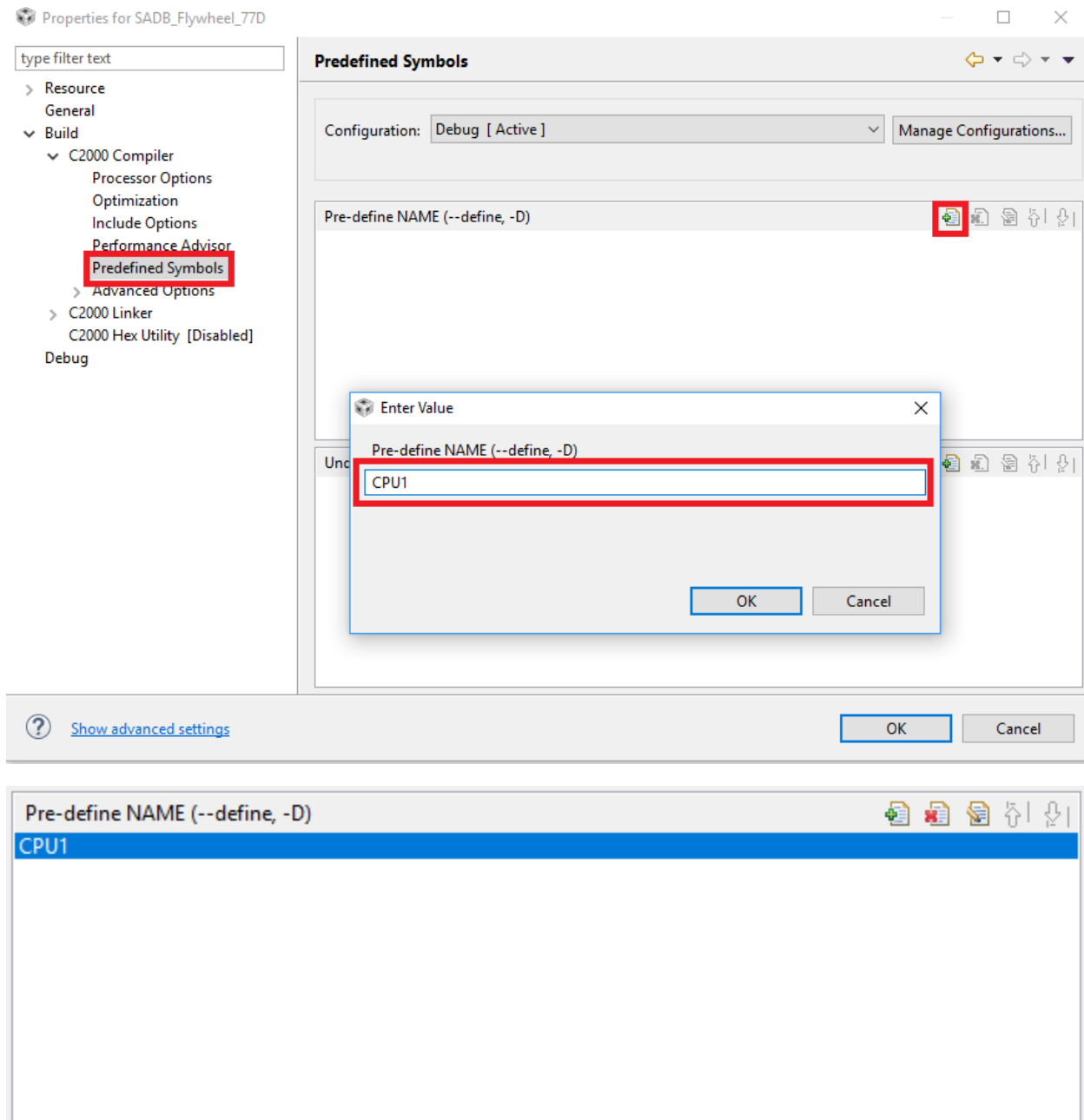
- In the left pane select “General”
 - o In the right pane under the tab main, click on the drop down menu by “Linker command file:”
 - At the top of this list select “<none>”



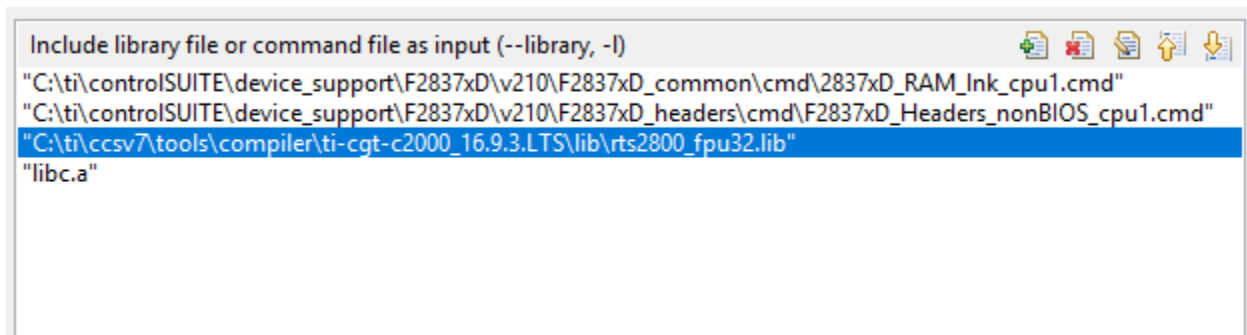
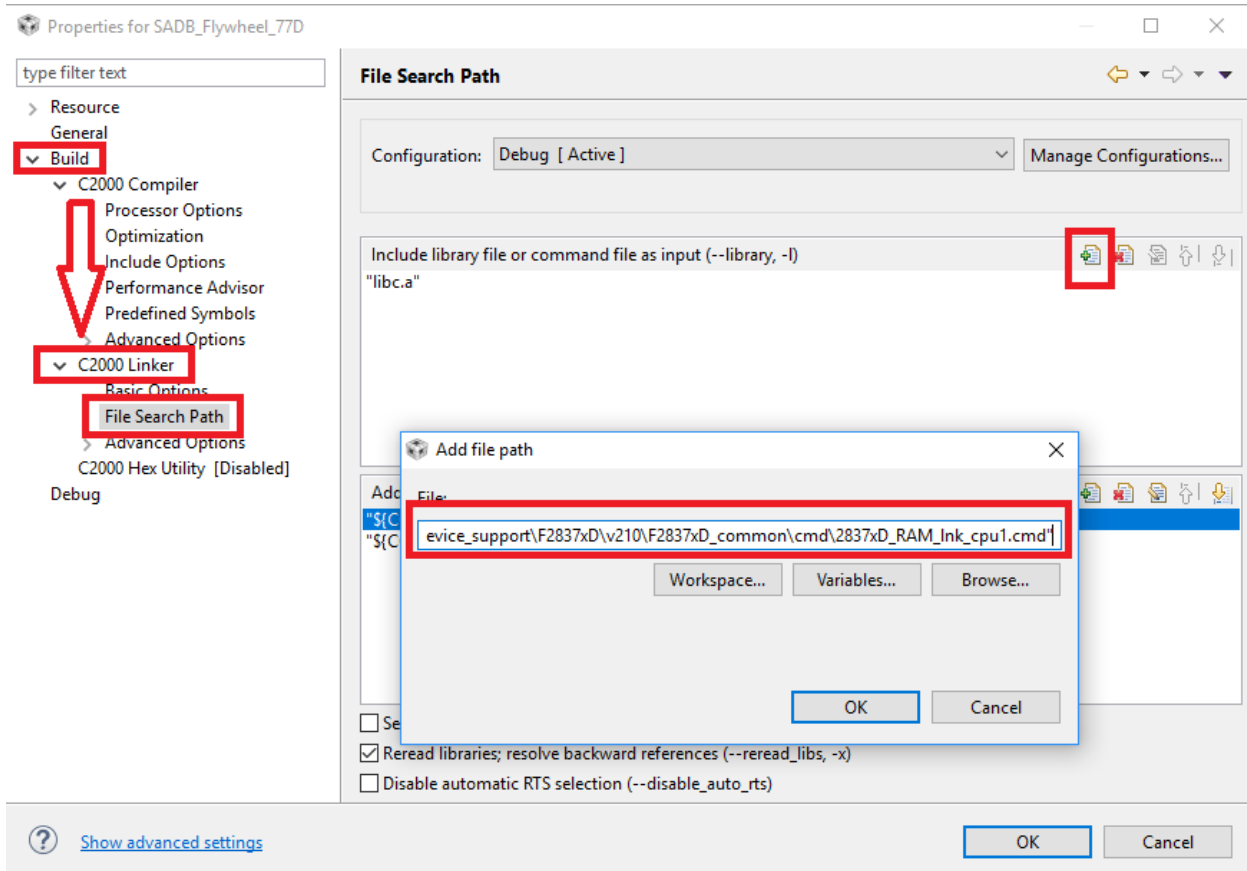
- Back in the left pane expand "Build" then under that expand "C2000 Compiler" then click on "Include Options"
 - o In the top right pane titled "Add dir to...", click the add to add these two paths separately
 - "C:\ti\controlSUITE\device_support\F2837xD\v210\F2837xD_common\include"
 - "C:\ti\controlSUITE\device_support\F2837xD\v210\F2837xD_headers\include"



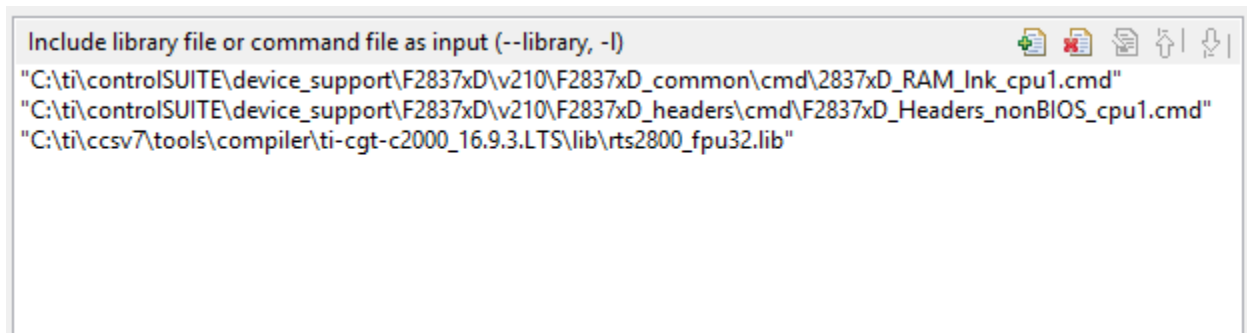
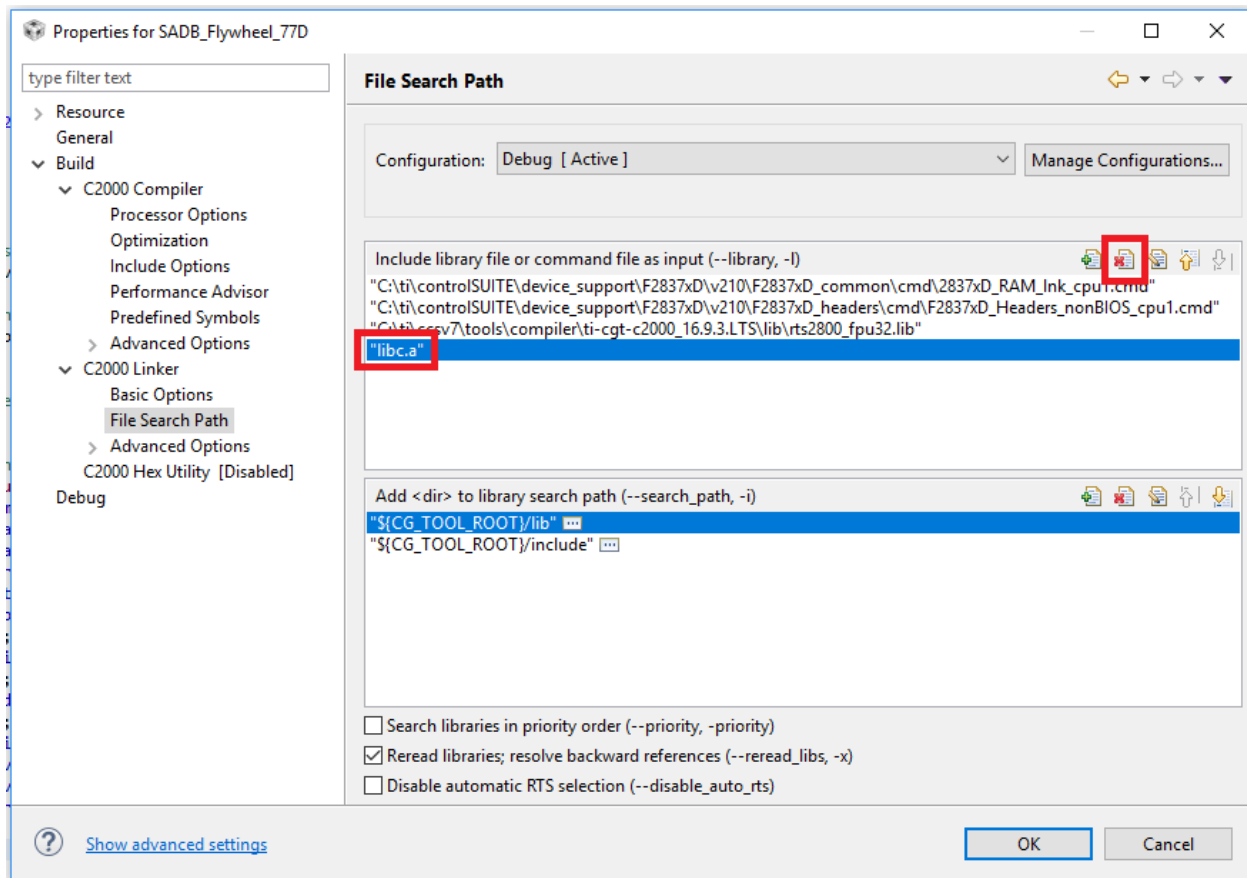
- Back in the left pane below “Include Options”, click on “Predefined Symbols”
 - o In the top right window titled “Pre-define NAM...”, click on the add to add this name
 - CPU1



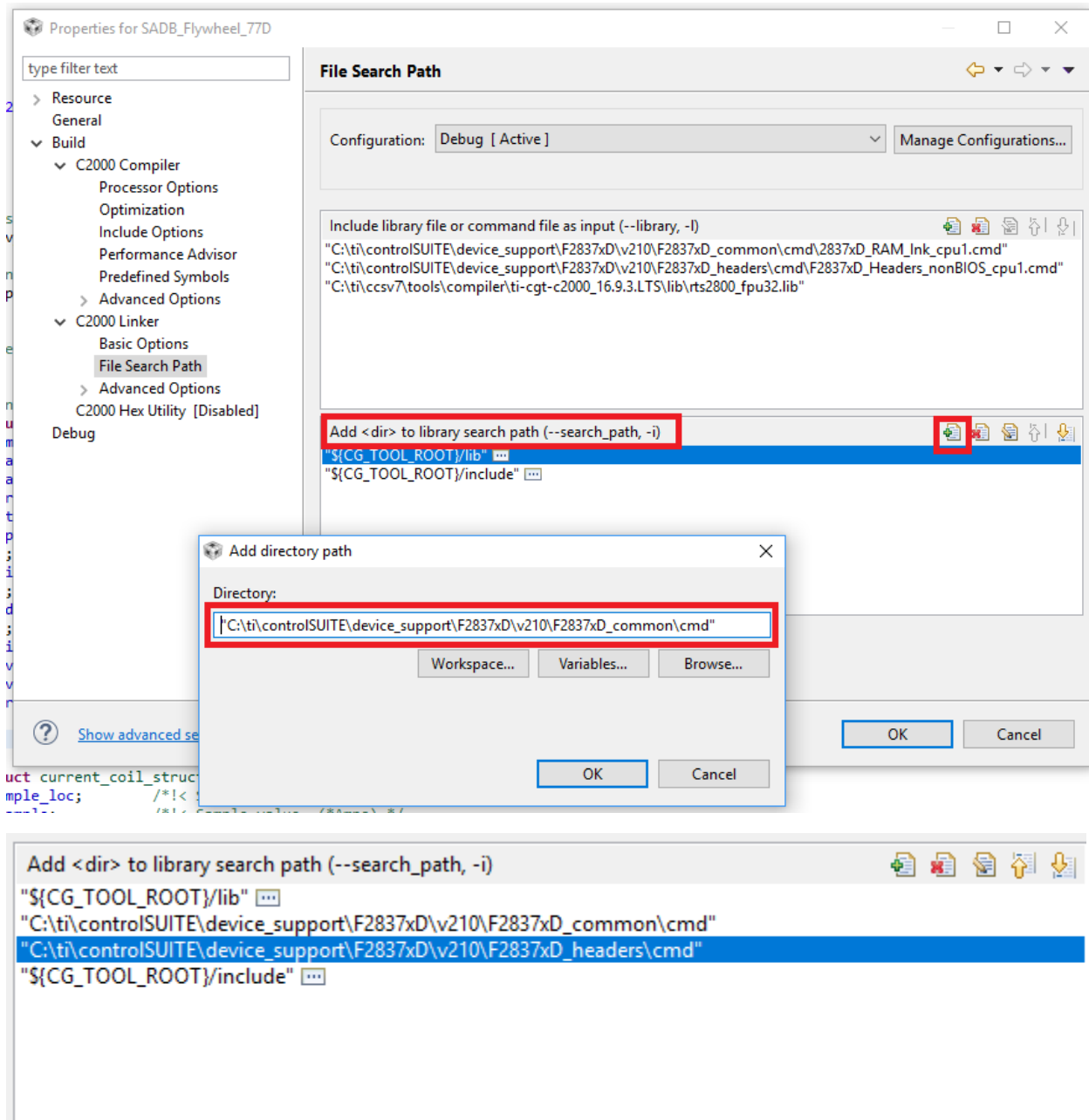
- Back in the left pane, in “Build”, below “C2000 Compiler”, expand “C2000 Linker”. Then select “File Search Path”
 - o In the top right pane titled “Include library file or...”, click on the add to add these three paths (*you will have to add them one at a time)
 - "C:\ti\controlSUITE\device_support\F2837xD\v210\F2837xD_common\cmd\2837xD_RAM_Ink_cpu1.cmd"
 - "C:\ti\controlSUITE\device_support\F2837xD\v210\F2837xD_headers\cmd\F2837xD-Headers_nonBIOS_cpu1.cmd"
 - "C:\ti\ccsv7\tools\compiler\ti-cgt-c2000_16.9.3.LTS\lib\rts2800_fpu32.lib"



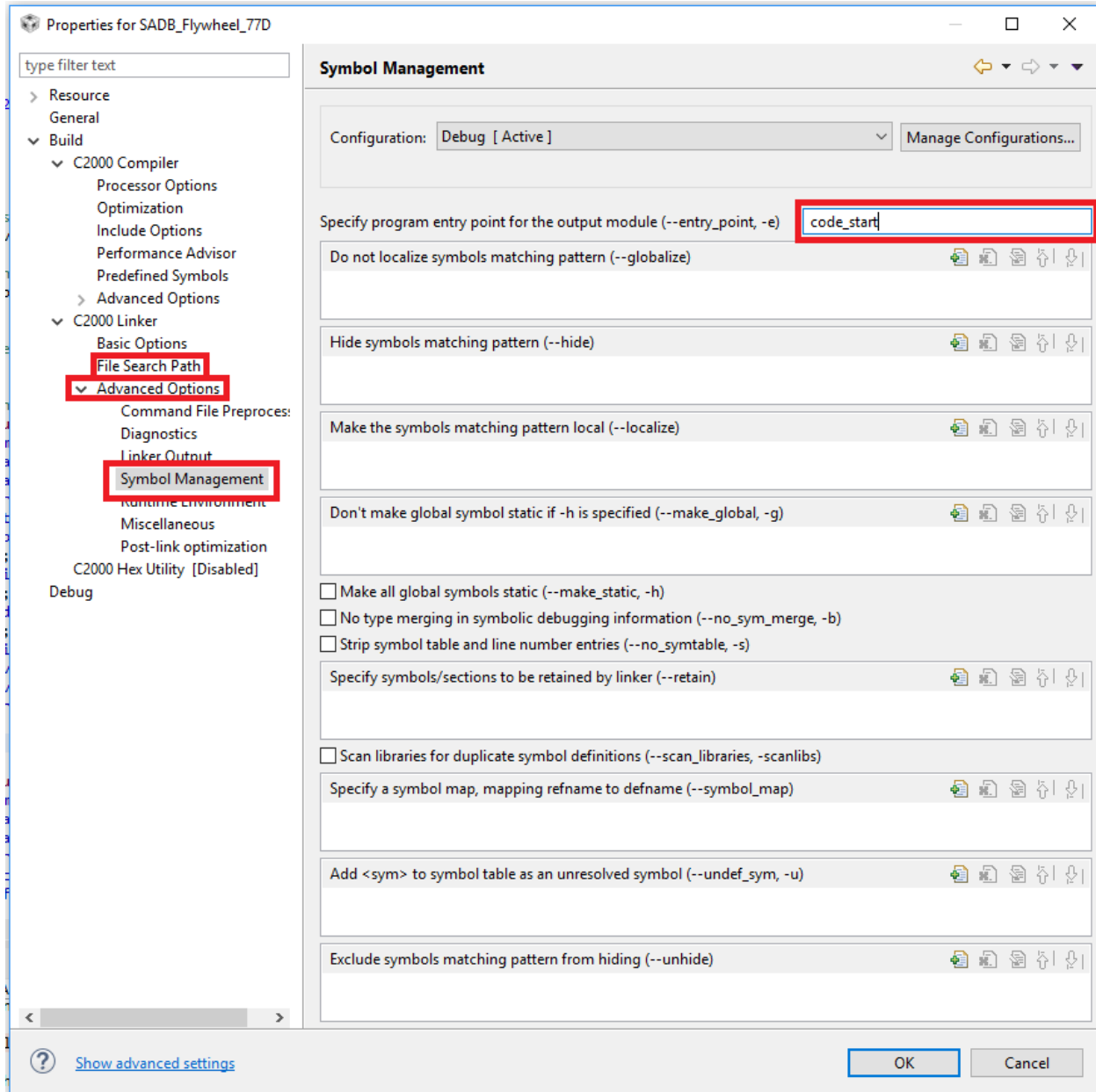
- In this same pane select the line "libc.a" and delete it with the red x in the top right



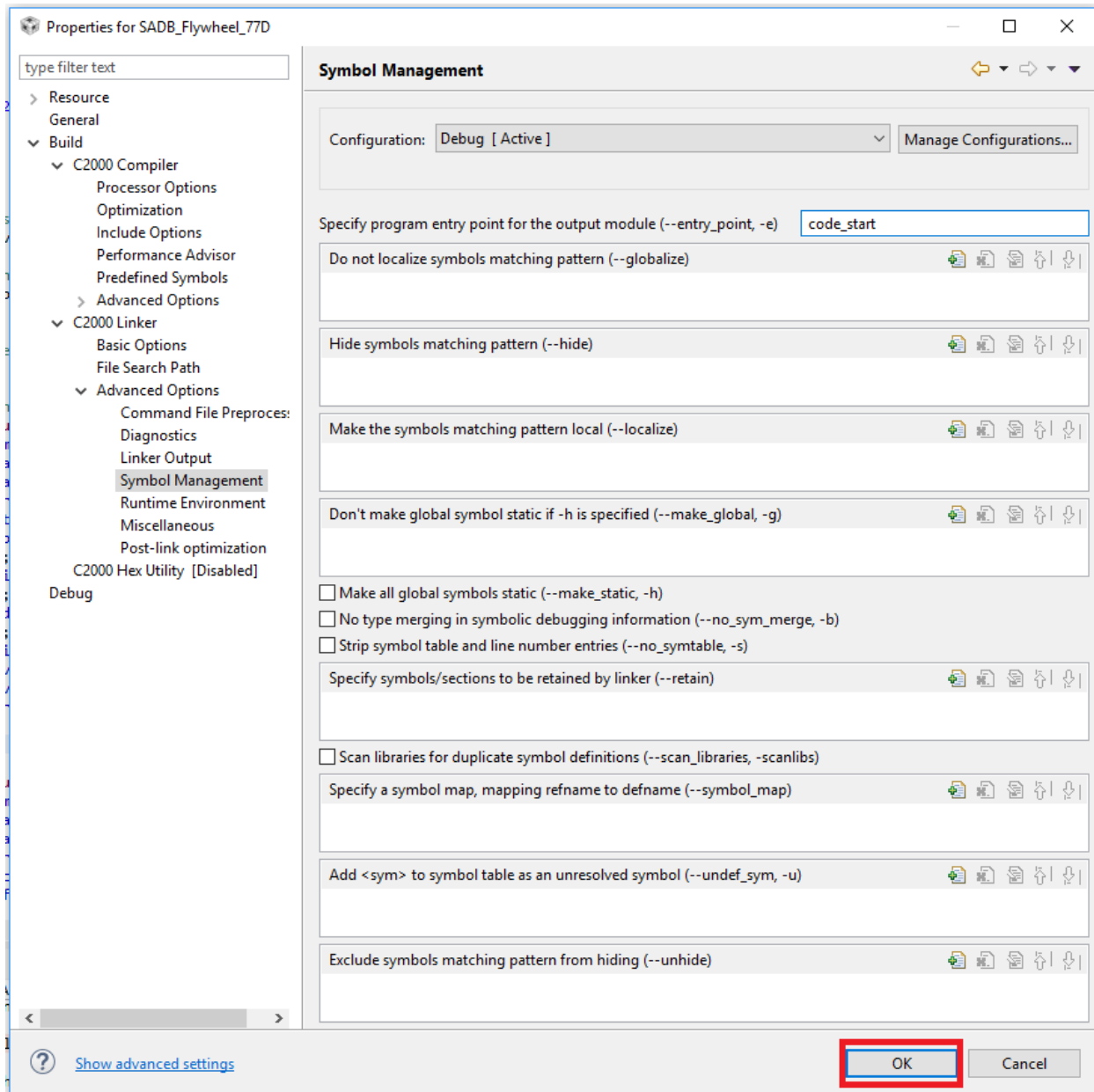
- In the lower right pane titled "Add <dir> to..." click on the add to add these paths
 - "C:\ti\controlSUITE\device_support\F2837xD\v210\F2837xD_common\cmd"
 - "C:\ti\controlSUITE\device_support\F2837xD\v210\F2837xD_headers\cmd"



- Back in the left pane below “File Search Path”, expand “Advanced Options” and click on “Symbol Management”
 - o Near the top of the right side of the window is a text entry box, in which type
 - code_start

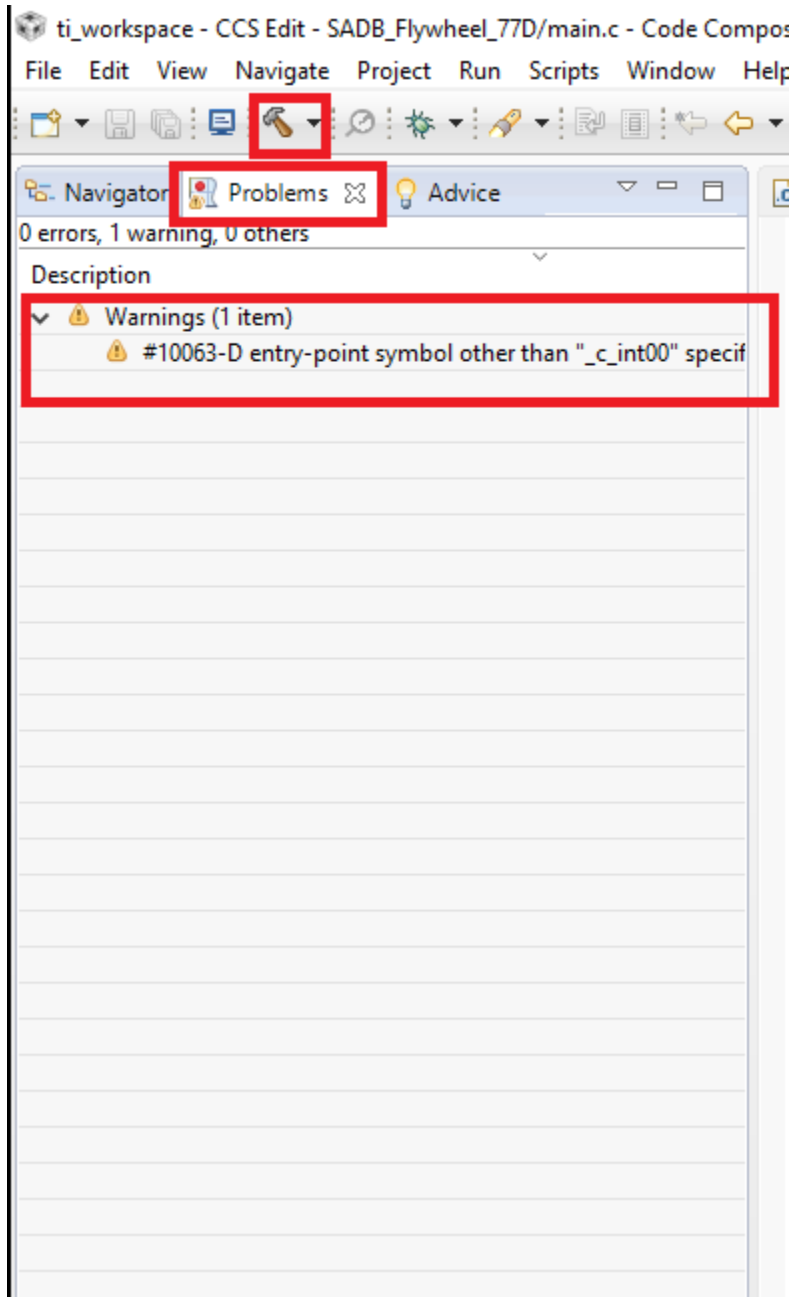


- At this point all the necessary changes have been made to the properties. Click the “OK” at the bottom of the window to close.

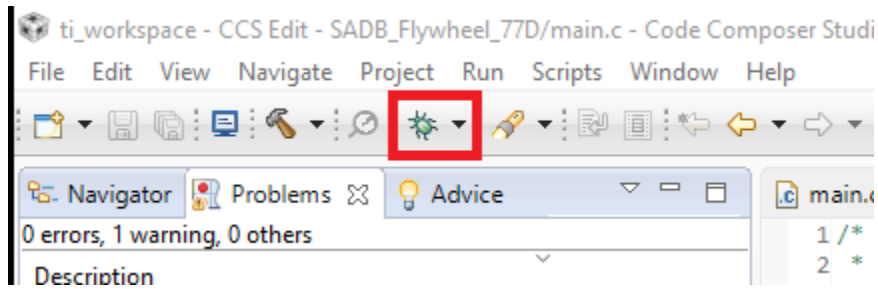


Running

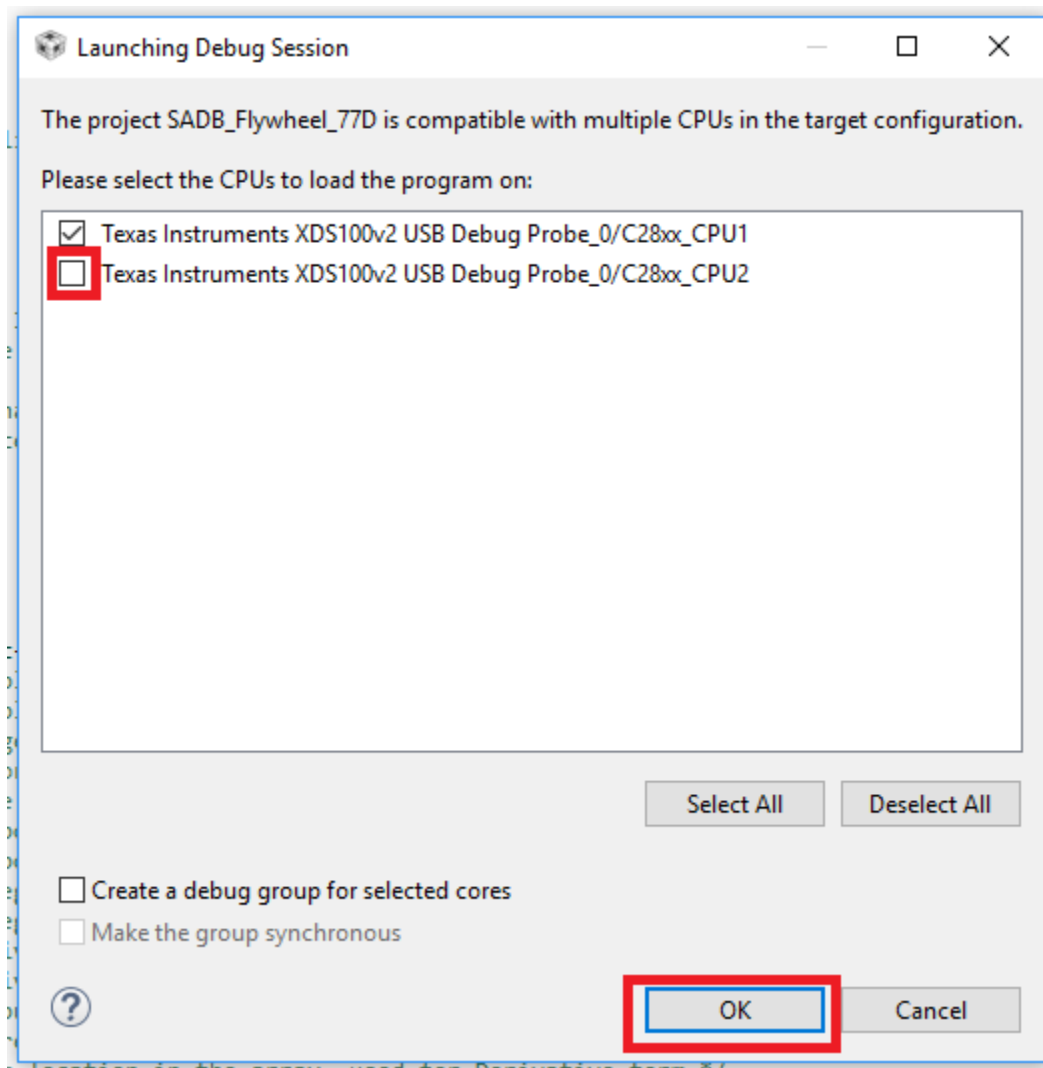
- At this point click on the image of the hammer to build
 - o There should only be one warning and no errors, and the one warning is fine



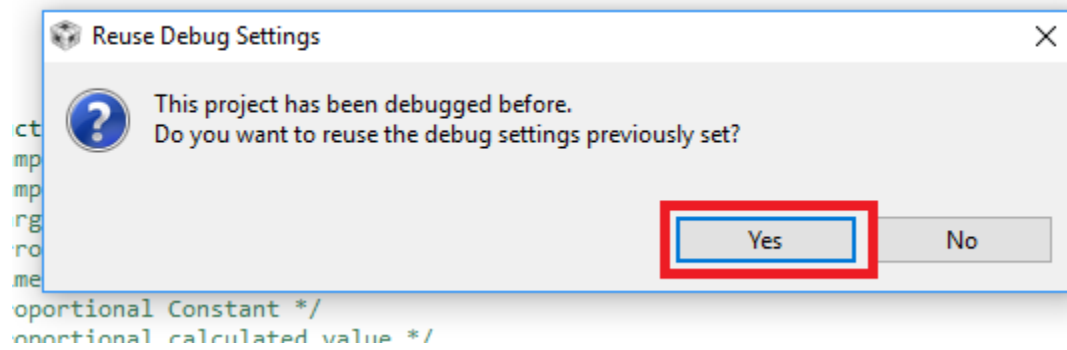
- Next click on the green bug to debug the program (same as running the program, but we get a few more options to change settings while the setup is running)



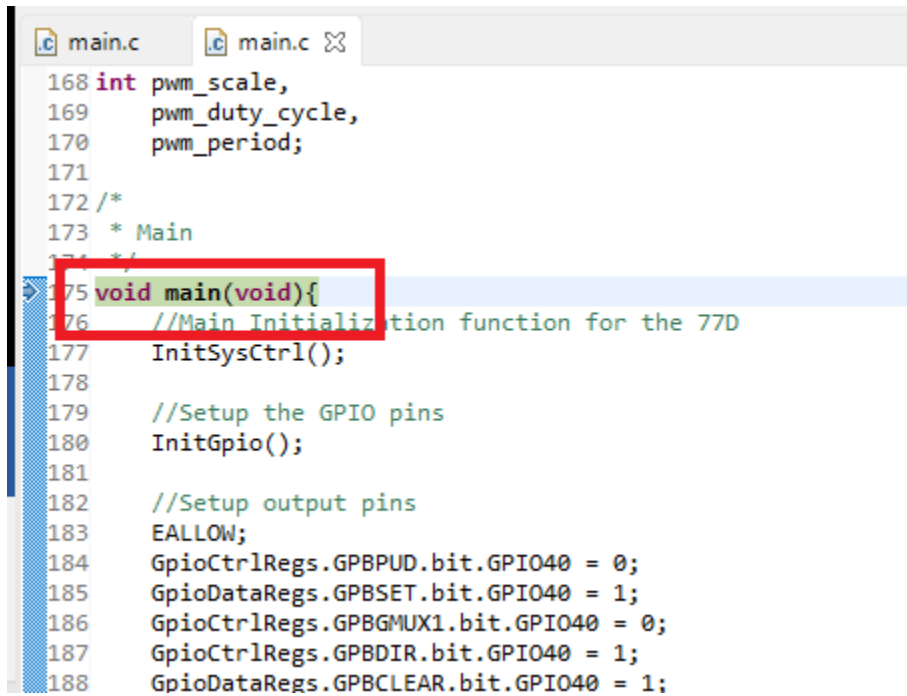
- After clicking on the debug button, a window will pop up
 - o Uncheck the box for CPU2 and press OK



- Another prompt will come up asking if you want to reuse the debug settings previously set, click yes

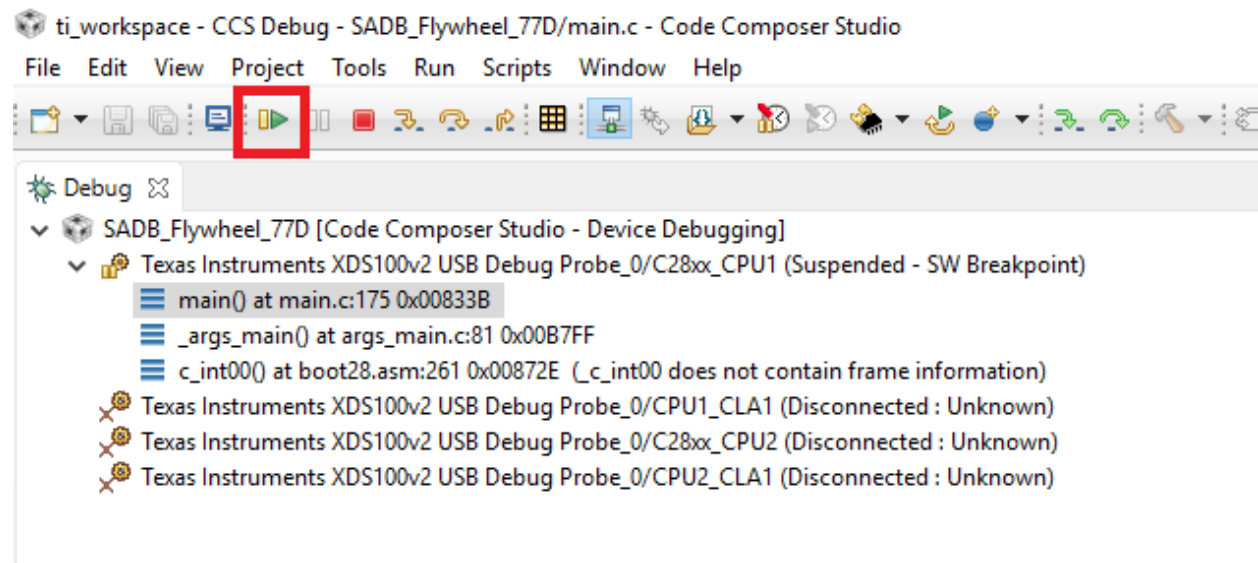


- Assuming all has gone well up until this point, a little arrow will appear next to the first line of the main() function, indicating that it is paused at this point in the code



```
main.c  main.c ✕
168 int pwm_scale,
169     pwm_duty_cycle,
170     pwm_period;
171
172 /*
173  * Main
174  */
175 void main(void){
176     //Main Initialization function for the 77D
177     InitSysCtrl();
178
179     //Setup the GPIO pins
180     InitGpio();
181
182     //Setup output pins
183     EALLOW;
184     GpioCtrlRegs.GPBPUD.bit.GPIO40 = 0;
185     GpioDataRegs.GPBSET.bit.GPIO40 = 1;
186     GpioCtrlRegs.GPBGMUX1.bit.GPIO40 = 0;
187     GpioCtrlRegs.GPBDIR.bit.GPIO40 = 1;
188     GpioDataRegs.GPBCLEAR.bit.GPIO40 = 1;
```

- From here we can begin the code by clicking on the green arrow to run



- While the code is running one can pause the code by pressing the yellow pause, or quit back to the code editing view by clicking on red square

