

## SLIM Curve

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## Chapter 1

# SLIM-curve package for exponential curve fitting of spectral lifetime data.

SLIM Curve is a curve fitting library used for Fluorescent Lifetime Imaging or FLIM and Spectral Lifetime Imaging or SLIM. It is based on code developed by Paul Barber and the Advanced Technology Group at the Gray Institute for Radiation Oncology & Biology, University of Oxford, and used for FLIM functionality in his TRI2 (Time Resolved Imaging) software. It is also used in the LOCI SLIM Plugin project.

For exponential lifetime fitting there are two core algorithms within SLIM Curve: The first is a triple integral method that does a very fast estimate of a single exponential lifetime component. The second is a Levenberg-Marquardt algorithm or LMA that uses an iterative, least-squares-minimization approach to generate a fit. This works with single, double and triple exponential models, as well as stretched exponential. There is also code to perform 'global' analysis over a number of signals simultaneously (e.g. over an image), where the lifetimes can be considered constant across the data set, but the amplitudes are allowed to vary for each signal. There is also a completely generic global analysis function. A third algorithm is available to perform phasor analysis.

In addition there is a non-negative linear least squares algorithm that is useful for spectral unmixing in SLIM.

The code is written in C89 compatible C and is thread safe for fitting multiple pixels concurrently. Several files are provided as wrappers to call this library from Java code: `EcfWrapper.c` and `.h` provide a subset of function calls used by SLIM Plugin, these may be invoked directly from Java using JNA. In addition there is a Java CurveFitter project that provides a wrapper to the SLIM Curve code. This invokes the C code using JNI, with `loci_curvefitter_SLIM-CurveFitter.c` and `.h`.

For further details, see: <http://loci.wisc.edu/software/slim-curve>

If you are familiar with the program TRI2, that uses SLIM Curve, this screenshot may help you to understand the meaning of the parameters.

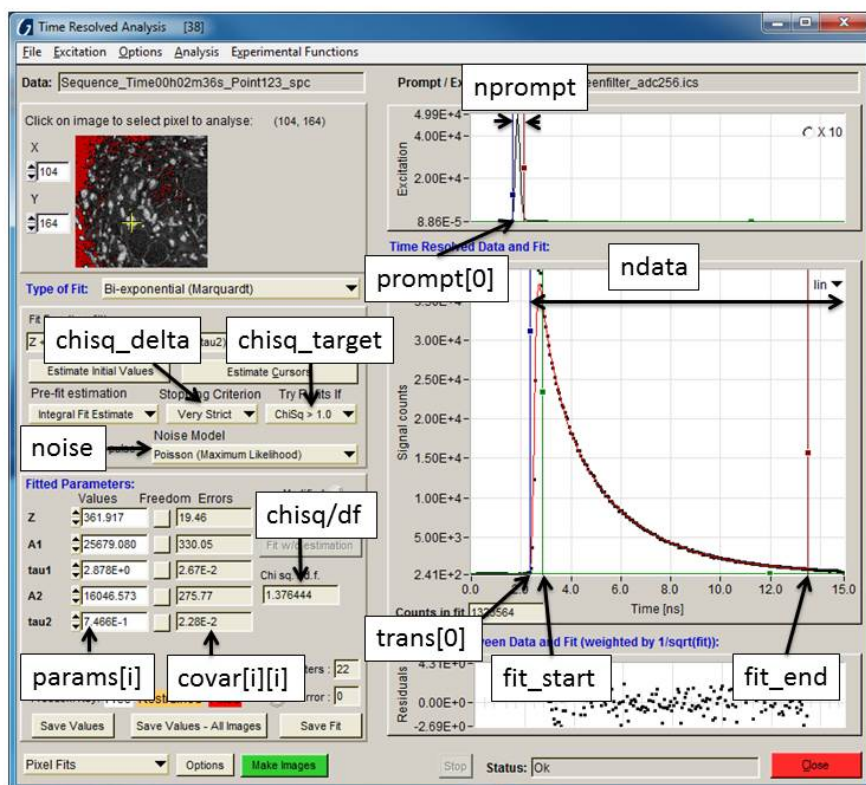


Figure 1.1: How some SLIM-Curve paramters are used in TRI2.

## Library Contents:

Directory	Contents
src	source files
src/main/c	The source files for the SLIM Curve library
src/slim-curve-cmd/c	The source files for the stand alone executable wrapper for the library
test_files	dat and ini settings file for testing
src/main/c/doc	API documentation (Doxygen output)

## To Build the Stand Alone Program using CMake and gcc under Linux:

Create a build folder, and cd to it

```
mkdir build
cd build
```

Run CMake

```
cmake ../CMakeLists.txt
```

Run make

```
make
```

## To Run the Stand Alone Executable

Copy the executable to the test\_files folder for convenience

```
cp slim-curve-cmd ../test_files
```

Run the program with the test files

```
cd ../test_files  
./slim-curve-cmd test.ini transient.dat
```

### Author

Paul Barber

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## Chapter 2

# File Index

### 2.1 File List

Here is a list of all documented files with brief descriptions:

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## Chapter 3

# File Documentation

### 3.1 Ecf.h File Reference

SLIM Curve - Exponential Curve Fitting Header.

#### Enumerations

- enum [noise\\_type](#) {  
    **NOISE\_CONST**, **NOISE\_GIVEN**, **NOISE\_POISSON\_DATA**, **NOISE\_POISSON\_FIT**,  
    **NOISE\_GAUSSIAN\_FIT**, **NOISE\_MLE** }

*Noise Type.*

- enum [fit\\_type](#) { **FIT\_GLOBAL\_MULTIEXP**, **FIT\_GLOBAL\_STRETCHEDEXP** }

*Fit Type for optimised exponential global analysis.*

- enum [restrain\\_type](#) { **ECF\_RESTRAIN\_DEFAULT**, **ECF\_RESTRAIN\_USER** }

*Restrain Type.*

#### Functions

- int [GCI\\_triple\\_integral\\_fitting\\_engine](#) (float xincr, float y[], int fit\_start, int fit\_end, float instr[], int ninstr, [noise\\_type](#) noise, float sig[], float \*Z, float \*A, float \*tau, float \*fitted, float \*residuals, float \*chisq, float chisq\_target)

*The main entry point for Triple Integral or Rapid Lifetime Determination (RLD).*

- int [GCI\\_marquardt\\_fitting\\_engine](#) (float xincr, float \*trans, int ndata, int fit\_start, int fit\_end, float prompt[], int nprompt, [noise\\_type](#) noise, float sig[], float param[], int paramfree[], int nparam, [restrain\\_type](#) restrain, void(\*fitfunc)(float, float[], float \*, float[], int), float \*fitted, float \*residuals, float \*chisq, float \*\*covar, float \*\*alpha, float \*\*erraxes, float chisq\_target, float chisq\_delta, int chisq\_percent)

*The main entry point for LM and MLE fitting.*

- int **GCI\_triple\_integral** (float xincr, float y[], int fit\_start, int fit\_end, [noise\\_type](#) noise, float sig[], float \*Z, float \*A, float \*tau, float \*fitted, float \*residuals, float \*chisq, int division)
- int **GCI\_triple\_integral\_instr** (float xincr, float y[], int fit\_start, int fit\_end, float instr[], int ninstr, [noise\\_type](#) noise, float sig[], float \*Z, float \*A, float \*tau, float \*fitted, float \*residuals, float \*chisq, int division)
- int **GCI\_marquardt** (float x[], float y[], int ndata, [noise\\_type](#) noise, float sig[], float param[], int paramfree[], int nparam, [restrain\\_type](#) restrain, void(\*fitfunc)(float, float[], float \*, float[], int), float \*fitted, float \*residuals, float \*\*covar, float \*\*alpha, float \*chisq, float chisq\_delta, float chisq\_percent, float \*\*erraxes)
- int **GCI\_marquardt\_instr** (float xincr, float y[], int ndata, int fit\_start, int fit\_end, float instr[], int ninstr, [noise\\_type](#) noise, float sig[], float param[], int paramfree[], int nparam, [restrain\\_type](#) restrain, void(\*fitfunc)(float, float[], float \*, float[], int), float \*fitted, float \*residuals, float \*\*covar, float \*\*alpha, float \*chisq, float chisq\_delta, float chisq\_percent, float \*\*erraxes)
- void **GCI\_marquardt\_cleanup** (void)

- int [GCI\\_marquardt\\_global\\_exps\\_instr](#) (float xincr, float \*\*trans, int ndata, int ntrans, int fit\_start, int fit\_end, float instr[], int ninstr, [noise\\_type](#) noise, float sig[], int ftype, float \*\*param, int paramfree[], int nparam, [restrain\\_type](#) restrain, float chisq\_delta, float \*\*fitted, float \*\*residuals, float chisq\_trans[], float \*chisq\_global, int \*df, int drop\_bad\_transients)

*Global analysis analysis function for exponential functions.*

- int [GCI\\_marquardt\\_global\\_generic\\_instr](#) (float xincr, float \*\*trans, int ndata, int ntrans, int fit\_start, int fit\_end, float instr[], int ninstr, [noise\\_type](#) noise, float sig[], float \*\*param, int paramfree[], int nparam, int gparam[], [restrain\\_type](#) restrain, float chisq\_delta, void(\*fitfunc)(float, float[], float \*, float[], int), float \*\*fitted, float \*\*residuals, float chisq\_trans[], float \*chisq\_global, int \*df)

*Global analysis analysis function for generic functions.*

- int [GCI\\_SPA\\_1D\\_marquardt](#) (float x[], float y[], int ndata, [noise\\_type](#) noise, float sig[], float param[], int paramfree[], int nparam, [restrain\\_type](#) restrain, float chisq\_delta, void(\*fitfunc)(float, float[], float \*, float[], int), int spa\_param, int spa\_nvalues, float spa\_low, float spa\_high, float chisq[], void(\*progressfunc)(float))

*Support plane analysis.*

- int [GCI\\_SPA\\_2D\\_marquardt](#) (float x[], float y[], int ndata, [noise\\_type](#) noise, float sig[], float param[], int paramfree[], int nparam, [restrain\\_type](#) restrain, float chisq\_delta, void(\*fitfunc)(float, float[], float \*, float[], int), int spa\_param1, int spa\_nvalues1, float spa\_low1, float spa\_high1, int spa\_param2, int spa\_nvalues2, float spa\_low2, float spa\_high2, float \*\*chisq, void(\*progressfunc)(float))

*Support plane analysis for 2 parameters.*

- int [GCI\\_SPA\\_1D\\_marquardt\\_instr](#) (float xincr, float y[], int ndata, int fit\_start, int fit\_end, float instr[], int ninstr, [noise\\_type](#) noise, float sig[], float param[], int paramfree[], int nparam, [restrain\\_type](#) restrain, float chisq\_delta, void(\*fitfunc)(float, float[], float \*, float[], int), int spa\_param, int spa\_nvalues, float spa\_low, float spa\_high, float chisq[], float chisq\_target, void(\*progressfunc)(float))

*Support plane analysis with instrument response (prompt or IRF).*

- int [GCI\\_SPA\\_2D\\_marquardt\\_instr](#) (float xincr, float y[], int ndata, int fit\_start, int fit\_end, float instr[], int ninstr, [noise\\_type](#) noise, float sig[], float param[], int paramfree[], int nparam, [restrain\\_type](#) restrain, float chisq\_delta, void(\*fitfunc)(float, float[], float \*, float[], int), int spa\_param1, int spa\_nvalues1, float spa\_low1, float spa\_high1, int spa\_param2, int spa\_nvalues2, float spa\_low2, float spa\_high2, float \*\*chisq, float chisq\_target, void(\*progressfunc)(float))

*Support plane analysis for 2 parameters with instrument response (prompt or IRF).*

- int [GCI\\_SPA\\_1D\\_marquardt\\_global\\_exps\\_instr](#) (float xincr, float \*\*trans, int ndata, int ntrans, int fit\_start, int fit\_end, float instr[], int ninstr, [noise\\_type](#) noise, float sig[], int ftype, float \*\*param, int paramfree[], int nparam, [restrain\\_type](#) restrain, float chisq\_delta, int drop\_bad\_transients, int spa\_param, int spa\_nvalues, float spa\_low, float spa\_high, float chisq\_global[], int df[], void(\*progressfunc)(float))

*Support plane analysis for exponential global analysis with instrument response (prompt or IRF).*

- int [GCI\\_SPA\\_2D\\_marquardt\\_global\\_exps\\_instr](#) (float xincr, float \*\*trans, int ndata, int ntrans, int fit\_start, int fit\_end, float instr[], int ninstr, [noise\\_type](#) noise, float sig[], int ftype, float \*\*param, int paramfree[], int nparam, [restrain\\_type](#) restrain, float chisq\_delta, int drop\_bad\_transients, int spa\_param1, int spa\_nvalues1, float spa\_low1, float spa\_high1, int spa\_param2, int spa\_nvalues2, float spa\_low2, float spa\_high2, float \*\*chisq\_global, int \*\*df, void(\*progressfunc)(float))

*Support plane analysis for exponential global with 2 parameters with instrument response (prompt or IRF).*

- int [GCI\\_SPA\\_1D\\_marquardt\\_global\\_generic\\_instr](#) (float xincr, float \*\*trans, int ndata, int ntrans, int fit\_start, int fit\_end, float instr[], int ninstr, [noise\\_type](#) noise, float sig[], float \*\*param, int paramfree[], int nparam, int gparam[], [restrain\\_type](#) restrain, float chisq\_delta, void(\*fitfunc)(float, float[], float \*, float[], int), int spa\_param, int spa\_nvalues, float spa\_low, float spa\_high, float chisq\_global[], int df[], void(\*progressfunc)(float))

*Support plane analysis for generic global analysis with instrument response (prompt or IRF).*

- int [GCI\\_SPA\\_2D\\_marquardt\\_global\\_generic\\_instr](#) (float xincr, float \*\*trans, int ndata, int ntrans, int fit\_start, int fit\_end, float instr[], int ninstr, [noise\\_type](#) noise, float sig[], float \*\*param, int paramfree[], int nparam, int gparam[], [restrain\\_type](#) restrain, float chisq\_delta, void(\*fitfunc)(float, float[], float \*, float[], int), int spa\_param1, int spa\_nvalues1, float spa\_low1, float spa\_high1, int spa\_param2, int spa\_nvalues2, float spa\_low2, float spa\_high2, float \*\*chisq\_global, int \*\*df, void(\*progressfunc)(float))

*Support plane analysis for generic global with 2 parameters with instrument response (prompt or IRF).*

- int [GCI\\_set\\_restrain\\_limits](#) (int nparam, int restrain[], float minval[], float maxval[])

*Setting restraints.*

- void [GCI\\_multiexp\\_lambda](#) (float x, float param[], float \*y, float dy\_dparam[], int nparam)

- multi-exp predefined fitting model based on decay rates (lambdas).*
- void [GCI\\_multiexp\\_tau](#) (float x, float param[], float \*y, float dy\_dparam[], int nparam)
- multi-exp predefined fitting model based on lifetimes (taus).*
- void [GCI\\_stretchedexp](#) (float x, float param[], float \*y, float dy\_dparam[], int nparam)
- stretched-exp predefined fitting model.*
- float \*\* [GCI\\_ecf\\_matrix](#) (long nrows, long ncols)
- Allocate a 2d matrix for ecf fitting.*
- void [GCI\\_ecf\\_free\\_matrix](#) (float \*\*m)
- Free a 2d matrix.*
- void [ECF\\_ExportParams\\_start](#) (char path[])
- Start exporting fit details to a file for each fit.*
- void [ECF\\_ExportParams\\_stop](#) (void)
- Stop exporting fit details to a file for each fit.*

### 3.1.1 Detailed Description

SLIM Curve - Exponential Curve Fitting Header.

Definition in file [Ecf.h](#).

### 3.1.2 Enumeration Type Documentation

#### 3.1.2.1 enum fit\_type

Fit Type for optimised exponential global analysis.

Chooses between a multi-exponential fit (FIT\_GLOBAL\_MULTIEXP) and the special 'stretched' exponential (FIT\_GLOBAL\_STRETCHEDEXP).

Definition at line 51 of file Ecf.h.

#### 3.1.2.2 enum noise\_type

Noise Type.

'NOISE\_CONST' - every data point is assumed to have the same supplied variance.

'NOISE\_GIVEN' - every data point can have an individual variance, given via a data array.

'NOISE\_GAUSSIAN\_FIT' - Variance for Gaussian distribution is used at all data points Variants based on the data or the fit.

'NOISE\_POISSON\_DATA and NOISE\_POISSON\_FIT' - Variance for Gaussian distribution is used with a lower limit of 15, this being the point where the Gaussian approximation begins to break down with Poissonian data. Variants based on the data or the fit.

'NOISE\_MLE' - Maximum Likelihood Estimation through the use of the Poisson equation (Laurence and Chromy 2010).

Definition at line 45 of file Ecf.h.

#### 3.1.2.3 enum restrain\_type

Restrain Type.

Chooses the restrain type, either the default with very wide sensible limits (ECF\_RESTRAIN\_DEFAULT) or 'user' defined limits (ECF\_RESTRAIN\_USER). See [GCI\\_set\\_restrain\\_limits](#).

Definition at line 56 of file Ecf.h.

### 3.1.3 Function Documentation

#### 3.1.3.1 void ECF\_ExportParams\_start ( char *path*[] )

Start exporting fit details to a file for each fit.

##### Parameters

in	<i>path</i>	The path of the file to use to save fit details.
----	-------------	--

#### 3.1.3.2 void ECF\_ExportParams\_stop ( void )

Stop exporting fit details to a file for each fit.

#### 3.1.3.3 void GCI\_ecf\_free\_matrix ( float \*\* *m* )

Free a 2d matrix.

#### 3.1.3.4 float\*\* GCI\_ecf\_matrix ( long *nrows*, long *ncols* )

Allocate a 2d matrix for ecf fitting.

#### 3.1.3.5 int GCI\_marquardt\_fitting\_engine ( float *xincr*, float \* *trans*, int *ndata*, int *fit\_start*, int *fit\_end*, float *prompt*[], int *nprompt*, noise\_type *noise*, float *sig*[], float *param*[], int *paramfree*[], int *nparam*, restrain\_type *restrain*, void(\*) (float, float[], float \*, float[], int) *fitfunc*, float \* *fitted*, float \* *residuals*, float \* *chisq*, float \*\* *covar*, float \*\* *alpha*, float \*\* *erraxes*, float *chisq\_target*, float *chisq\_delta*, int *chisq\_percent* )

The main entry point for LM and MLE fitting.

Uses GCI\_marquardt\_instr() to fit repeatedly until *chisq\_target* is met or a maximum number of iterations are used. This can be used to fit any function through the 'fitfunc', but is primarily used for single, multi and stretched exponential fits. Predefined fitting models GCI\_multiexp\_tau and GCI\_stretchedexp are provided elsewhere in the library.

##### Parameters

in	<i>xincr</i>	The time increment in between the values in the y array.
in	<i>trans</i>	The transient (time resolved) signal to be analysed, the 'data'.
in	<i>ndata</i>	The number of data points.
in	<i>fit_start</i>	The index into the y array marking the start to the data to be used in the fit. Some data before this start index is required for convolution with the prompt.
in	<i>fit_end</i>	The index into the y array marking the end of the data to be used in the fit.
in	<i>prompt</i>	The instrument response (IRF) or prompt signal to be used (optional, can pass NULL).
in	<i>nprompt</i>	The number of data points in the prompt (ignored if prompt = NULL).
in	<i>noise</i>	The <a href="#">noise_type</a> to be used.
in	<i>sig</i>	The standard deviation at each data point in y if <a href="#">noise_type</a> NOISE_GIVEN is used (optional, can pass NULL).
in, out	<i>param</i>	An array of parameters, the order of which must match fitfunc. Provide parameter estimates, these are overridden with the fitted values.

in	<i>paramfree</i>	An array indicating which parameters are free (1), fixed (0)
in	<i>nparam</i>	The number of parameters.
in	<i>restrain</i>	Parameter <a href="#">restrain_type</a> . Normally use ECF_RESTRAIN_DEFAULT. Use ECF_RESTRAIN_USER if restraining parameters has been setup via GCI_set_restrain_limits.
in	<i>fitfunc</i>	Encodes the function to fit to the data, e.g. <a href="#">GCI_multiexp_tau</a> .
out	<i>fitted</i>	An array containing values fitted to the data, the 'fit'. Fit points are coincident in time with the data points.
out	<i>residuals</i>	An array containing the difference between the data and the fit.
out	<i>chisq</i>	The resulting raw chi squared value of the fit. To get the reduced chisq, divide by the degrees of freedom (fit_start - fit_end - nparam)
out	<i>covar</i>	The covariance matrix. Allocate with a square matrix with <a href="#">GCI_ecf_matrix</a> (nparam, nparam).
out	<i>alpha</i>	The alpha matrix. Allocate with a square matrix with <a href="#">GCI_ecf_matrix</a> (nparam, nparam).
out	<i>erraxes</i>	The dimensions of the confidence ellipsoid of the chisq. See chisq_percent below. Allocate with a square matrix with <a href="#">GCI_ecf_matrix</a> (nparam, nparam).
in	<i>chisq_target</i>	A raw chi squared value to aim for. If this value is reached fitting will stop. If you want to aim for a reduced chisq (say 1.1 or 1.0) you must multiply by the degree of freedom. (TRI2: "Try refits")
in	<i>chisq_delta</i>	An individual fit will continue if the chisq value changes by more then this amount. Try 1E-5. (TRI2: "Stopping Criterion")
in	<i>chisq_percent</i>	Defines the confidence interval when calculating the error axes, e.g. 95 %.

### Returns

An error code, 0 = success.

```
3.1.3.6 int GCI_marquardt_global_exps_instr ( float xincr, float ** trans, int ndata, int ntrans, int fit_start, int fit_end,
float instr[], int ninstr, noise_type noise, float sig[], int ftype, float ** param, int paramfree[], int nparam,
restrain_type restrain, float chisq_delta, float ** fitted, float ** residuals, float chisq_trans[], float * chisq_global,
int * df, int drop_bad_transients )
```

Global analysis analysis function for exponential functions.

The main entry point for Global analysis with exponential functions. This assumes global exponential params (lifetimes) and local amplitudes.

### Parameters

in	<i>xincr</i>	The time increment inbetween the values in the y array.
in	<i>trans</i>	A pointer to a matrix of transient (time resolved) signals to be analysed, the 'data'. Allocate with <a href="#">GCI_ecf_matrix</a> .
in	<i>ndata</i>	The number of data points in each transient.
in	<i>ntrans</i>	The number of transient signals (pixels in a time resolved image).
in	<i>fit_start</i>	The index into the y array marking the start to the data to be used in the fit. Some data before this start index is required for convolution with the prompt.
in	<i>fit_end</i>	The index into the y array marking the end of the data to be used in the fit.
in	<i>instr</i>	The instrument reponse (IRF) or prompt signal to be used (optional, can pass NULL).
in	<i>ninstr</i>	The number of data points in the prompt (ignored if prompt = NULL).
in	<i>noise</i>	The <a href="#">noise_type</a> to be used.

in	<i>sig</i>	The standard deviation at each data point in y if <a href="#">noise_type</a> NOISE_GIVEN is used (optional, can pass NULL).
in	<i>ftype</i>	The type of function to fit can be multi-exponential (FIT_GLOBAL_MULTIEXP) or stretched exponential (FIT_GLOBAL_STRETCHEDEXP). For other fitting functions use the global generic function.
in,out	<i>param</i>	A pointer to an array of parameter arrays, the order of which must match fitfunc.
in	<i>paramfree</i>	An array indicating which parameters are free (1), fixed (0).
in	<i>nparam</i>	The number of parameters per fit.
in	<i>restrain</i>	Parameter <a href="#">restrain_type</a> . Normally use ECF_RESTRAIN_DEFAULT. Use ECF_RESTRAIN_USER if restraining parameters has been setup via GCI_set_restrain_limits.
in	<i>chisq_delta</i>	An individual fit will continue if the chisq value changes by more then this amount. Try 1E-5. (TRI2: "Stopping Criterion")
out	<i>fitted</i>	A pointer to a matrix containing values fitted to the data, the 'fit'. Fit points are coincident in time with the data points. Only the first row is used. Allocate with <a href="#">GCI_ecf_matrix</a> with nrows=1.
out	<i>residuals</i>	A matrix containing the difference between the data and the fit. Only the first row is used. Allocate with <a href="#">GCI_ecf_matrix</a> with nrows=1.
out	<i>chisq_trans</i>	An array of the resulting raw chi squared values of the fits. To get the reduced chisq, divide by the degrees of freedom (fit_start - fit_end - nparam).
out	<i>chisq_global</i>	The resulting raw chi squared value of the total global fit. To get the reduced chisq, divide by the degrees of freedom df.
out	<i>df</i>	The degrees of freedom.
in	<i>drop_bad_transients</i>	Remove individual transients from the fit that have a -ve return value from GCI_marquardt_global_exps_do_fit_single (default = 1)

### Returns

An error code, 0 = success.

### See Also

[GCI\\_marquardt\\_global\\_generic\\_instr](#)

```
3.1.3.7 int GCI_marquardt_global_generic_instr ( float xincr, float ** trans, int ndata, int ntrans, int fit_start, int fit_end,
float instr[], int ninstr, noise_type noise, float sig[], float ** param, int paramfree[], int nparam, int gparam[],
restrain_type restrain, float chisq_delta, void(*) (float, float[], float *, float[], int) fitfunc, float ** fitted, float **
residuals, float chisq_trans[], float * chisq_global, int * df )
```

Global analysis analysis function for generic functions.

The main entry point for Global analysis with generic functions.

### Parameters

in	<i>xincr</i>	The time increment inbetween the values in the y array.
in	<i>trans</i>	A pointer to a matrix of transient (time resolved) signals to be analysed, the 'data'. Allocate with <a href="#">GCI_ecf_matrix</a> .
in	<i>ndata</i>	The number of data points in each transient.
in	<i>ntrans</i>	The number of transient signals (pixels in a time resolved image).
in	<i>fit_start</i>	The index into the y array marking the start to the data to be used in the fit. Some data before this start index is required for convolution with the prompt.



in	<i>fit_end</i>	The index into the y array marking the end of the data to be used in the fit.
in	<i>instr</i>	The instrument reponse (IRF) or prompt signal to be used (optional, can pass NULL).
in	<i>ninstr</i>	The number of data points in the prompt (ignored if prompt = NULL).
in	<i>noise</i>	The <a href="#">noise_type</a> to be used.
in	<i>sig</i>	The standard deviation at each data point in y if <a href="#">noise_type</a> NOISE_GIVEN is used (optional, can pass NULL).
in, out	<i>param</i>	A pointer to an array of parameter arrays, the order of which must match fitfunc. Allocate with <a href="#">GCI_ecf_matrix</a> (ntrans, nparam). The global params will be the same for every transient.
in	<i>paramfree</i>	An array indicating which parameters are free (1), fixed (0).
in	<i>nparam</i>	The number of parameters per fit.
in	<i>gparam</i>	An array marking which parameters are to be globally determined.
in	<i>restrain</i>	Parameter <a href="#">restrain_type</a> . Normally use ECF_RESTRAIN_DEFAULT. Use ECF_RESTRAIN_USER if restraining parameters has been setup via GCI_set_restrain_limits.
in	<i>chisq_delta</i>	An individual fit will continue if the chisq value changes by more then this amount. Try 1E-5. (TRI2: "Stopping Criterion")
in	<i>fitfunc</i>	Encodes the function to fit to the data, e.g. <a href="#">GCI_multiexp_tau</a> .
out	<i>fitted</i>	A pointer to a matrix containing values fitted to the data, the 'fit'. Fit points are coincident in time with the data points. Only the first row is used. Allocate with <a href="#">GCI_ecf_matrix</a> with nrows=1.
out	<i>residuals</i>	A matrix containing the difference between the data and the fit. Only the first row is used. Allocate with <a href="#">GCI_ecf_matrix</a> with nrows=1.
out	<i>chisq_trans</i>	An array of the resulting raw chi squared values of the fits. To get the reduced chisq, divide by the degrees of freedom (fit_start - fit_end - nparam).
out	<i>chisq_global</i>	The resulting raw chi squared value of the total global fit. To get the reduced chisq, divide by the degrees of freedom df.
out	<i>df</i>	The degrees of freedom.

**Returns**

An error code, 0 = success.

**See Also**

[GCI\\_marquardt\\_global\\_exps\\_instr](#)

### 3.1.3.8 void GCI\_multiexp\_lambda ( float x, float param[], float \* y, float dy\_dparam[], int nparam )

multi-exp predefined fitting model based on decay rates (lambdas).

**Parameters**

in	<i>x</i>	The x value to evaluate the function at.
in	<i>param[]</i>	Array containing the parameters to use in the evaluation.
out	<i>y</i>	The value of the function at the x value.
out	<i>dy_dparam</i>	Array of dy/dparam values at this point
in	<i>nparam</i>	The number of parameters (may not be used if model has a fixed parameter number)

### 3.1.3.9 void GCI\_multiexp\_tau ( float x, float param[], float \* y, float dy\_dparam[], int nparam )

multi-exp predefined fitting model based on lifetimes (taus).

**Parameters**

in	<i>x</i>	The x value to evaluate the function at.
in	<i>param[]</i>	Array containing the parameters to use in the evaluation.
out	<i>y</i>	The value of the function at the x value.
out	<i>dy_dparam</i>	Array of dy/dparam values at this point
in	<i>nparam</i>	The number of parameters (may not be used if model has a fixed parameter number)

### 3.1.3.10 int GCI\_set\_restrain\_limits ( int *nparam*, int *restrain[]*, float *minval[]*, float *maxval[]* )

Setting restraints.

**Parameters**

in	<i>nparam</i>	The number of parameters.
in	<i>restrain</i>	Array indicating which parameters to restrain (set non-zero to restrain).
in	<i>minval</i>	Array of minimum values for each parameter (only those for the restrained parameters set by the restrain array are used).
in	<i>maxval</i>	Array of maximum values for each parameter (only those for the restrained parameters set by the restrain array are used).

**Returns**

An error code, 0 = success.

### 3.1.3.11 int GCI\_SPA\_1D\_marquardt ( float *x[]*, float *y[]*, int *ndata*, **noise\_type** *noise*, float *sig[]*, float *param[]*, int *paramfree[]*, int *nparam*, **restrain\_type** *restrain*, float *chisq\_delta*, void(\*) (float, float[], float \*, float[], int) *fitfunc*, int *spa\_param*, int *spa\_nvalues*, float *spa\_low*, float *spa\_high*, float *chisq[]*, void(\*) (float) *progressfunc* )

Support plane analysis.

This function will perform a number of fits with one fixed parameter that varies between the *spa\_low* and *spa\_high* values. The array of *chisq* values is returned that forms the 'support plane'.

**Parameters**

in	<i>x</i>	The x or time values at which the y data points are provided.
in	<i>y</i>	The transient (time resolved) signal to be analysed, the 'data'.
in	<i>ndata</i>	The number of data points.
in	<i>noise</i>	The <b>noise_type</b> to be used.
in	<i>sig</i>	The standard deviation at each data point in y if <b>noise_type</b> NOISE_GIVEN is used (optional, can pass NULL).
in, out	<i>param</i>	An array of parameters, the order of which must match <i>fitfunc</i> . Provide parameter estimates, these are overridden with the fitted values.
in	<i>paramfree</i>	An array indicating which parameters are free (1), fixed (0).
in	<i>nparam</i>	The number of parameters.
in	<i>restrain</i>	Parameter <b>restrain_type</b> . Normally use ECF_RESTRAIN_DEFAULT. Use ECF_RESTRAIN_USER if restraining parameters has been setup via GCI_set_restrain_limits.

in	<i>chisq_delta</i>	An individual fit will continue if the chisq value changes by more then this amount. Try 1E-5. (TR12: "Stopping Criterion")
in	<i>fitfunc</i>	Encodes the function to fit to the data, e.g. <a href="#">GCI_multiexp_tau</a> .
in	<i>spa_param</i>	The index to the param we are analysing with spa.
in	<i>spa_nvalues</i>	The number of values of the parameter we are to calculate the chisq value for.
in	<i>spa_low</i>	The lowest parameter value to use.
in	<i>spa_high</i>	The highest parameter value to use.
out	<i>chisq</i>	An array of resulting raw chi squared values. To get the reduced chisq, divide by the degrees of freedom (fit_start - fit_end - nparam)
in	<i>progressfunc</i>	A pointer to a function that may provide some feedback to the user on progress. A number between 0 and 1 is sent to this function after each iteration. (optional: may be NULL)

#### Returns

An error code, 0 = success.

#### See Also

[GCI\\_SPA\\_2D\\_marquardt](#)  
[GCI\\_SPA\\_1D\\_marquardt\\_instr](#)  
[GCI\\_SPA\\_2D\\_marquardt\\_instr](#)

3.1.3.12 `int GCI_SPA_1D_marquardt_global_exps_instr ( float xincr, float ** trans, int ndata, int ntrans, int fit_start, int fit_end, float instr[], int ninstr, noise_type noise, float sig[], int ftype, float ** param, int paramfree[], int nparam, restrain_type restrain, float chisq_delta, int drop_bad_transients, int spa_param, int spa_nvalues, float spa_low, float spa_high, float chisq_global[], int df[], void(*) (float) progressfunc )`

Support plane analysis for exponential global analysis with instrument response (prompt or IRF).

This function will perform a number of fits with one fixed parameter that varies between the spa\_low and spa\_high values. The array of chisq values is returned that forms the 'support plane'.

#### Parameters

in	<i>xincr</i>	The time increment in between the values in the y array.
in	<i>trans</i>	A pointer to a matrix of transient (time resolved) signals to be analysed, the 'data'. Allocate with <a href="#">GCI_ecf_matrix</a> .
in	<i>ndata</i>	The number of data points.
in	<i>ntrans</i>	The number of transient signals (pixels in a time resolved image).
in	<i>fit_start</i>	The index into the y array marking the start to the data to be used in the fit. Some data before this start index is required for convolution with the prompt.
in	<i>fit_end</i>	The index into the y array marking the end of the data to be used in the fit.
in	<i>instr</i>	The instrument response (IRF) or prompt signal to be used (optional, can pass NULL).
in	<i>ninstr</i>	The number of data points in the prompt (ignored if prompt = NULL).
in	<i>noise</i>	The <a href="#">noise_type</a> to be used.
in	<i>sig</i>	The standard deviation at each data point in y if <a href="#">noise_type</a> NOISE_GIVEN is used (optional, can pass NULL).
in	<i>ftype</i>	The type of function to fit can be multi-exponential (FIT_GLOBAL_MULTIEXP) or stretched exponential (FIT_GLOBAL_STRETCHEDEXP). For other fitting functions use the global generic function.

in, out	<i>param</i>	A pointer to an array of parameter arrays, the order of which must match fitfunc.
in	<i>paramfree</i>	An array indicating which parameters are free (1), fixed (0).
in	<i>nparam</i>	The number of parameters.
in	<i>restrain</i>	Parameter <a href="#">restrain_type</a> . Normally use ECF_RESTRAIN_DEFAULT. Use ECF_RESTRAIN_USER if restraining parameters has been setup via GCI_set_restrain_limits.
in	<i>chisq_delta</i>	An individual fit will continue if the chisq value changes by more then this amount. Try 1E-5. (TRI2: "Stopping Criterion")
in	<i>drop_bad_transients</i>	Remove individual transients from the fit that have a -ve return value from GCI_marquardt_global_exps_do_fit_single (default = 1)
in	<i>spa_param</i>	The index to the param we are analysing with spa.
in	<i>spa_nvalues</i>	The number of values of the parameter we are to calculate the chisq value for.
in	<i>spa_low</i>	The lowest parameter value to use.
in	<i>spa_high</i>	The highest parameter value to use.
out	<i>chisq_global</i>	The resulting array of raw chi squared values of the total global fit. To get the reduced chisq, divide by the degrees of freedom df.
out	<i>df</i>	The degrees of freedom.
in	<i>progressfunc</i>	A pointer to a function that may provide some feedback to the user on progress. A number between 0 and 1 is sent to this function after each iteration. (optional: may be NULL)

### Returns

An error code, 0 = success.

### See Also

[GCI\\_SPA\\_2D\\_marquardt\\_global\\_exps\\_instr](#)  
[GCI\\_SPA\\_1D\\_marquardt\\_global\\_generic\\_instr](#)  
[GCI\\_SPA\\_2D\\_marquardt\\_global\\_generic\\_instr](#)

**3.1.3.13** `int GCI_SPA_1D_marquardt_global_generic_instr ( float xincr, float ** trans, int ndata, int ntrans, int fit_start, int fit_end, float instr[], int ninstr, noise_type noise, float sig[], float ** param, int paramfree[], int nparam, int gparam[], restrain_type restrain, float chisq_delta, void(*) (float, float[], float *, float[], int) fitfunc, int spa_param, int spa_nvalues, float spa_low, float spa_high, float chisq_global[], int df[], void(*) (float) progressfunc )`

Support plane analysis for generic global analysis with instrument response (prompt or IRF).

This function will perform a number of fits with one fixed parameter that varies between the spa\_low and spa\_high values. The array of chisq values is returned that forms the 'support plane'.

### Parameters

in	<i>xincr</i>	The time increment in between the values in the y array.
in	<i>trans</i>	A pointer to a matrix of transient (time resolved) signals to be analysed, the 'data'. Allocate with <a href="#">GCI_ecf_matrix</a> .
in	<i>ndata</i>	The number of data points.
in	<i>ntrans</i>	The number of transient signals (pixels in a time resolved image).
in	<i>fit_start</i>	The index into the y array marking the start to the data to be used in the fit. Some data before this start index is required for convolution with the prompt.
in	<i>fit_end</i>	The index into the y array marking the end of the data to be used in the fit.
in	<i>instr</i>	The instrument response (IRF) or prompt signal to be used (optional, can pass NULL).

in	<i>ninstr</i>	The number of data points in the prompt (ignored if prompt = NULL).
in	<i>noise</i>	The <a href="#">noise_type</a> to be used.
in	<i>sig</i>	The standard deviation at each data point in y if <a href="#">noise_type</a> NOISE_GIVEN is used (optional, can pass NULL).
in, out	<i>param</i>	A pointer to an array of parameter arrays, the order of which must match fitfunc.
in	<i>paramfree</i>	An array indicating which parameters are free (1), fixed (0).
in	<i>nparam</i>	The number of parameters.
in	<i>gparam</i>	An array marking which parameters are to be globally determined.
in	<i>restrain</i>	Parameter <a href="#">restrain_type</a> . Normally use ECF_RESTRAIN_DEFAULT. Use ECF_RESTRAIN_USER if restraining parameters has been setup via GCI_set_restrain_limits.
in	<i>chisq_delta</i>	An individual fit will continue if the chisq value changes by more then this amount. Try 1E-5. (TR12: "Stopping Criterion")
in	<i>fitfunc</i>	Encodes the function to fit to the data, e.g. <a href="#">GCI_multiexp_tau</a> .
in	<i>spa_param</i>	The index to the param we are analysing with spa.
in	<i>spa_nvalues</i>	The number of values of the parameter we are to calculate the chisq value for.
in	<i>spa_low</i>	The lowest parameter value to use.
in	<i>spa_high</i>	The highest parameter value to use.
out	<i>chisq_global</i>	The resulting array of raw chi squared values of the total global fit. To get the reduced chisq, divide by the degrees of freedom df.
out	<i>df</i>	The degrees of freedom.
in	<i>progressfunc</i>	A pointer to a function that may provide some feedback to the user on progress. A number between 0 and 1 is sent to this function after each iteration. (optional: may be NULL)

#### Returns

An error code, 0 = success.

#### See Also

[GCI\\_SPA\\_1D\\_marquardt\\_global\\_exps\\_instr](#)  
[GCI\\_SPA\\_2D\\_marquardt\\_global\\_exps\\_instr](#)  
[GCI\\_SPA\\_2D\\_marquardt\\_global\\_generic\\_instr](#)

**3.1.3.14** int GCI\_SPA\_1D\_marquardt\_instr ( float *xincr*, float *y*[], int *ndata*, int *fit\_start*, int *fit\_end*, float *instr*[], int *ninstr*, [noise\\_type](#) *noise*, float *sig*[], float *param*[], int *paramfree*[], int *nparam*, [restrain\\_type](#) *restrain*, float *chisq\_delta*, void(\*) (float, float[], float \*, float[], int) *fitfunc*, int *spa\_param*, int *spa\_nvalues*, float *spa\_low*, float *spa\_high*, float *chisq*[], float *chisq\_target*, void(\*) (float) *progressfunc* )

Support plane analysis with instrument response (prompt or IRF).

This function will perform a number of fits with one fixed parameter that varies between the *spa\_low* and *spa\_high* values. The array of *chisq* values is returned that forms the 'support plane'.

#### Parameters

in	<i>xincr</i>	The time increment in between the values in the y array.
in	<i>y</i>	The transient (time resolved) signal to be analysed, the 'data'.
in	<i>ndata</i>	The number of data points.
in	<i>fit_start</i>	The index into the y array marking the start to the data to be used in the fit. Some data before this start index is required for convolution with the prompt.

in	<i>fit_end</i>	The index into the y array marking the end of the data to be used in the fit.
in	<i>instr</i>	The instrument response (IRF) or prompt signal to be used (optional, can pass NULL).
in	<i>ninstr</i>	The number of data points in the prompt (ignored if prompt = NULL).
in	<i>noise</i>	The <a href="#">noise_type</a> to be used.
in	<i>sig</i>	The standard deviation at each data point in y if <a href="#">noise_type</a> NOISE_GIVEN is used (optional, can pass NULL).
in, out	<i>param</i>	An array of parameters, the order of which must match fitfunc. Provide parameter estimates, these are overridden with the fitted values.
in	<i>paramfree</i>	An array indicating which parameters are free (1), fixed (0).
in	<i>nparam</i>	The number of parameters.
in	<i>restrain</i>	Parameter <a href="#">restrain_type</a> . Normally use ECF_RESTRAIN_DEFAULT. Use ECF_RESTRAIN_USER if restraining parameters has been setup via GCI_set_restrain_limits.
in	<i>chisq_delta</i>	An individual fit will continue if the chisq value changes by more then this amount. Try 1E-5. (TRI2: "Stopping Criterion")
in	<i>fitfunc</i>	Encodes the function to fit to the data, e.g. <a href="#">GCI_multiexp_tau</a> .
in	<i>spa_param</i>	The index to the param we are analysing with spa.
in	<i>spa_nvalues</i>	The number of values of the parameter we are to calculate the chisq value for.
in	<i>spa_low</i>	The lowest parameter value to use.
in	<i>spa_high</i>	The highest parameter value to use.
out	<i>chisq</i>	An array of resulting raw chi squared values. To get the reduced chisq, divide by the degrees of freedom (fit_start - fit_end - nparam)
in	<i>chisq_target</i>	A raw chi squared value to aim for. If this value is reached fitting will stop. If you want to aim for a reduced chisq (say 1.1 or 1.0) you must multiply by the degree of freedom. (TRI2: "Try refits")
in	<i>progressfunc</i>	A pointer to a function that may provide some feedback to the user on progress. A number between 0 and 1 is sent to this function after each iteration. (optional: may be NULL)

#### Returns

An error code, 0 = success.

#### See Also

[GCI\\_SPA\\_1D\\_marquardt](#)  
[GCI\\_SPA\\_2D\\_marquardt](#)  
[GCI\\_SPA\\_2D\\_marquardt\\_instr](#)

```
3.1.3.15 int GCI_SPA_2D_marquardt ( float x[], float y[], int ndata, noise_type noise, float sig[], float param[], int
paramfree[], int nparam, restrain_type restrain, float chisq_delta, void(*) (float, float[], float *, float[], int) fitfunc,
int spa_param1, int spa_nvalues1, float spa_low1, float spa_high1, int spa_param2, int spa_nvalues2, float spa_low2,
float spa_high2, float ** chisq, void(*) (float) progressfunc )
```

Support plane analysis for 2 parameters.

This function will perform a number of fits with two fixed parameters that vary between the spa\_low and spa\_high values. The array of chisq values is returned that forms the 'support plane'.

#### Parameters

in	<i>x</i>	The x or time values at which the y data points are provided.
----	----------	---

in	<i>y</i>	The transient (time resolved) signal to be analysed, the 'data'.
in	<i>ndata</i>	The number of data points.
in	<i>noise</i>	The <a href="#">noise_type</a> to be used.
in	<i>sig</i>	The standard deviation at each data point in y if <a href="#">noise_type</a> NOISE_GIVEN is used (optional, can pass NULL).
in, out	<i>param</i>	An array of parameters, the order of which must match fitfunc. Provide parameter estimates, these are overridden with the fitted values.
in	<i>paramfree</i>	An array indicating which parameters are free (1), fixed (0).
in	<i>nparam</i>	The number of parameters.
in	<i>restrain</i>	Parameter <a href="#">restrain_type</a> . Normally use ECF_RESTRAIN_DEFAULT. Use ECF_RESTRAIN_USER if restraining parameters has been setup via GCI_set_restrain_limits.
in	<i>chisq_delta</i>	An individual fit will continue if the chisq value changes by more then this amount. Try 1E-5. (TRI2: "Stopping Criterion")
in	<i>fitfunc</i>	Encodes the function to fit to the data, e.g. <a href="#">GCI_multiexp_tau</a> .
in	<i>spa_param1</i>	The index to first param we are analysing with spa.
in	<i>spa_nvalues1</i>	The number of values of first parameter we are to calculate the chisq value for.
in	<i>spa_low1</i>	The lowest first parameter value to use.
in	<i>spa_high1</i>	The highest first parameter value to use.
in	<i>spa_param2</i>	The index to second param we are analysing with spa.
in	<i>spa_nvalues2</i>	The number of values of second parameter we are to calculate the chisq value for.
in	<i>spa_low2</i>	The lowest second parameter value to use.
in	<i>spa_high2</i>	The highest second parameter value to use.
out	<i>chisq</i>	An matrix of resulting raw chi squared values. To get the reduced chisq, divide by the degrees of freedom (fit_start - fit_end - nparam), Allocate with chisq = (float **)malloc
in	<i>progressfunc</i>	A pointer to a function that may provide some feedback to the user on progress. A number between 0 and 1 is sent to this function after each iteration. (optional: may by NULL)

#### Returns

An error code, 0 = success.

#### See Also

[GCI\\_SPA\\_1D\\_marquardt](#)  
[GCI\\_SPA\\_1D\\_marquardt\\_instr](#)  
[GCI\\_SPA\\_2D\\_marquardt\\_instr](#)

```
3.1.3.16 int GCI_SPA_2D_marquardt_global_exps_instr( float xincr, float ** trans, int ndata, int ntrans, int fit_start, int fit_end, float instr[], int ninstr, noise_type noise, float sig[], int ftype, float ** param, int paramfree[], int nparam, restrain_type restrain, float chisq_delta, int drop_bad_transients, int spa_param1, int spa_nvalues1, float spa_low1, float spa_high1, int spa_param2, int spa_nvalues2, float spa_low2, float spa_high2, float ** chisq_global, int ** df, void (*)(float) progressfunc )
```

Support plane analysis for exponential global with 2 parameters with instrument response (prompt or IRF).

This function will perform a number of fits with two fixed parameters that vary between the spa\_low and spa\_high values. The array of chisq values is returned that forms the 'support plane'.

## Parameters

in	<i>xincr</i>	The time increment in between the values in the y array.
in	<i>trans</i>	A pointer to a matrix of transient (time resolved) signals to be analysed, the 'data'. Allocate with <a href="#">GCI_ecf_matrix</a> .
in	<i>ndata</i>	The number of data points.
in	<i>ntrans</i>	The number of transient signals (pixels in a time resolved image).
in	<i>fit_start</i>	The index into the y array marking the start to the data to be used in the fit. Some data before this start index is required for convolution with the prompt.
in	<i>fit_end</i>	The index into the y array marking the end of the data to be used in the fit.
in	<i>instr</i>	The instrument response (IRF) or prompt signal to be used (optional, can pass NULL).
in	<i>ninstr</i>	The number of data points in the prompt (ignored if prompt = NULL).
in	<i>noise</i>	The <a href="#">noise_type</a> to be used.
in	<i>sig</i>	The standard deviation at each data point in y if <a href="#">noise_type</a> NOISE_GIVEN is used (optional, can pass NULL).
in	<i>ftype</i>	The type of function to fit can be multi-exponential (FIT_GLOBAL_MULTIEXP) or stretched exponential (FIT_GLOBAL_STRETCHEDEXP). For other fitting functions use the global generic function.
in, out	<i>param</i>	A pointer to an array of parameter arrays, the order of which must match fitfunc.
in	<i>paramfree</i>	An array indicating which parameters are free (1), fixed (0).
in	<i>nparam</i>	The number of parameters.
in	<i>restrain</i>	Parameter <a href="#">restrain_type</a> . Normally use ECF_RESTRAIN_DEFAULT. Use ECF_RESTRAIN_USER if restraining parameters has been setup via <a href="#">GCI_set_restrain_limits</a> .
in	<i>chisq_delta</i>	An individual fit will continue if the chisq value changes by more then this amount. Try 1E-5. (TRI2: "Stopping Criterion")
in	<i>drop_bad_transients</i>	Remove individual transients from the fit that have a -ve return value from <a href="#">GCI_marquardt_global_exps_do_fit_single</a> (default = 1)
in	<i>spa_param1</i>	The index to first param we are analysing with spa.
in	<i>spa_nvalues1</i>	The number of values of first parameter we are to calculate the chisq value for.
in	<i>spa_low1</i>	The lowest first parameter value to use.
in	<i>spa_high1</i>	The highest first parameter value to use.
in	<i>spa_param2</i>	The index to second param we are analysing with spa.
in	<i>spa_nvalues2</i>	The number of values of second parameter we are to calculate the chisq value for.
in	<i>spa_low2</i>	The lowest second parameter value to use.
in	<i>spa_high2</i>	The highest second parameter value to use.
out	<i>chisq_global</i>	The resulting array of raw chi squared values of the total global fit. To get the reduced chisq, divide by the degrees of freedom df.
out	<i>df</i>	The degrees of freedom.
in	<i>progressfunc</i>	A pointer to a function that may provide some feedback to the user on progress. A number between 0 and 1 is sent to this function after each iteration. (optional: may be NULL)

## Returns

An error code, 0 = success.

## See Also

[GCI\\_SPA\\_1D\\_marquardt\\_global\\_exps\\_instr](#)  
[GCI\\_SPA\\_1D\\_marquardt\\_global\\_generic\\_instr](#)  
[GCI\\_SPA\\_2D\\_marquardt\\_global\\_generic\\_instr](#)



**3.1.3.17** `int GCI_SPA_2D_marquardt_global_generic_instr ( float xincr, float ** trans, int ndata, int ntrans, int fit_start, int fit_end, float instr[], int ninstr, noise_type noise, float sig[], float ** param, int paramfree[], int nparam, int gparam[], restrain_type restrain, float chisq_delta, void(*) (float, float[], float *, float[], int) fitfunc, int spa_param1, int spa_nvalues1, float spa_low1, float spa_high1, int spa_param2, int spa_nvalues2, float spa_low2, float spa_high2, float ** chisq_global, int ** df, void(*) (float) progressfunc )`

Support plane analysis for generic global with 2 parameters with instrument response (prompt or IRF).

This function will perform a number of fits with two fixed parameters that vary between the `spa_low` and `spa_high` values. The array of `chisq` values is returned that forms the 'support plane'.

#### Parameters

in	<i>xincr</i>	The time increment in between the values in the y array.
in	<i>trans</i>	A pointer to a matrix of transient (time resolved) signals to be analysed, the 'data'. Allocate with <a href="#">GCI_ecf_matrix</a> .
in	<i>ndata</i>	The number of data points.
in	<i>ntrans</i>	The number of transient signals (pixels in a time resolved image).
in	<i>fit_start</i>	The index into the y array marking the start to the data to be used in the fit. Some data before this start index is required for convolution with the prompt.
in	<i>fit_end</i>	The index into the y array marking the end of the data to be used in the fit.
in	<i>instr</i>	The instrument response (IRF) or prompt signal to be used (optional, can pass NULL).
in	<i>ninstr</i>	The number of data points in the prompt (ignored if prompt = NULL).
in	<i>noise</i>	The <a href="#">noise_type</a> to be used.
in	<i>sig</i>	The standard deviation at each data point in y if <a href="#">noise_type</a> NOISE_GIVEN is used (optional, can pass NULL).
in, out	<i>param</i>	A pointer to an array of parameter arrays, the order of which must match <i>fitfunc</i> .
in	<i>paramfree</i>	An array indicating which parameters are free (1), fixed (0).
in	<i>nparam</i>	The number of parameters.
in	<i>gparam</i>	An array marking which parameters are to be globally determined.
in	<i>restrain</i>	Parameter <a href="#">restrain_type</a> . Normally use ECF_RESTRAIN_DEFAULT. Use ECF_RESTRAIN_USER if restraining parameters has been setup via <code>GCI_set_restrain_limits</code> .
in	<i>chisq_delta</i>	An individual fit will continue if the <code>chisq</code> value changes by more than this amount. Try 1E-5. (TRI2: "Stopping Criterion")
in	<i>fitfunc</i>	Encodes the function to fit to the data, e.g. <a href="#">GCI_multiexp_tau</a> .
in	<i>spa_param1</i>	The index to first param we are analysing with spa.
in	<i>spa_nvalues1</i>	The number of values of first parameter we are to calculate the <code>chisq</code> value for.
in	<i>spa_low1</i>	The lowest first parameter value to use.
in	<i>spa_high1</i>	The highest first parameter value to use.
in	<i>spa_param2</i>	The index to second param we are analysing with spa.
in	<i>spa_nvalues2</i>	The number of values of second parameter we are to calculate the <code>chisq</code> value for.
in	<i>spa_low2</i>	The lowest second parameter value to use.
in	<i>spa_high2</i>	The highest second parameter value to use.
out	<i>chisq_global</i>	The resulting array of raw chi squared values of the total global fit. To get the reduced <code>chisq</code> , divide by the degrees of freedom <i>df</i> .
out	<i>df</i>	The degrees of freedom.
in	<i>progressfunc</i>	A pointer to a function that may provide some feedback to the user on progress. A number between 0 and 1 is sent to this function after each iteration. (optional: may be NULL)

#### Returns

An error code, 0 = success.

## See Also

[GCI\\_SPA\\_1D\\_marquardt\\_global\\_exps\\_instr](#)  
[GCI\\_SPA\\_2D\\_marquardt\\_global\\_exps\\_instr](#)  
[GCI\\_SPA\\_1D\\_marquardt\\_global\\_generic\\_instr](#)

3.1.3.18 `int GCI_SPA_2D_marquardt_instr ( float xincr, float y[], int ndata, int fit_start, int fit_end, float instr[], int ninstr, noise_type noise, float sig[], float param[], int paramfree[], int nparam, restrain_type restrain, float chisq_delta, void(*)(float, float[], float *, float[], int) fitfunc, int spa_param1, int spa_nvalues1, float spa_low1, float spa_high1, int spa_param2, int spa_nvalues2, float spa_low2, float spa_high2, float ** chisq, float chisq_target, void(*)(float) progressfunc )`

Support plane analysis for 2 parameters with instrument response (prompt or IRF).

This function will perform a number of fits with two fixed parameters that vary between the `spa_low` and `spa_high` values. The array of `chisq` values is returned that forms the 'support plane'.

## Parameters

in	<i>xincr</i>	The time increment in between the values in the y array.
in	<i>y</i>	The transient (time resolved) signal to be analysed, the 'data'.
in	<i>ndata</i>	The number of data points.
in	<i>fit_start</i>	The index into the y array marking the start to the data to be used in the fit. Some data before this start index is required for convolution with the prompt.
in	<i>fit_end</i>	The index into the y array marking the end of the data to be used in the fit.
in	<i>instr</i>	The instrument response (IRF) or prompt signal to be used (optional, can pass NULL).
in	<i>ninstr</i>	The number of data points in the prompt (ignored if prompt = NULL).
in	<i>noise</i>	The <a href="#">noise_type</a> to be used.
in	<i>sig</i>	The standard deviation at each data point in y if <a href="#">noise_type</a> NOISE_GIVEN is used (optional, can pass NULL).
in, out	<i>param</i>	An array of parameters, the order of which must match <code>fitfunc</code> . Provide parameter estimates, these are overridden with the fitted values.
in	<i>paramfree</i>	An array indicating which parameters are free (1), fixed (0).
in	<i>nparam</i>	The number of parameters.
in	<i>restrain</i>	Parameter <a href="#">restrain_type</a> . Normally use <code>ECF_RESTRAIN_DEFAULT</code> . Use <code>ECF_RESTRAIN_USER</code> if restraining parameters has been setup via <code>GCI_set_restrain_limits</code> .
in	<i>chisq_delta</i>	An individual fit will continue if the <code>chisq</code> value changes by more then this amount. Try 1E-5. (TR12: "Stopping Criterion")
in	<i>fitfunc</i>	Encodes the function to fit to the data, e.g. <a href="#">GCI_multiexp_tau</a> .
in	<i>spa_param1</i>	The index to first param we are analysing with spa.
in	<i>spa_nvalues1</i>	The number of values of first parameter we are to calculate the <code>chisq</code> value for.
in	<i>spa_low1</i>	The lowest first parameter value to use.
in	<i>spa_high1</i>	The highest first parameter value to use.
in	<i>spa_param2</i>	The index to second param we are analysing with spa.
in	<i>spa_nvalues2</i>	The number of values of second parameter we are to calculate the <code>chisq</code> value for.
in	<i>spa_low2</i>	The lowest second parameter value to use.
in	<i>spa_high2</i>	The highest second parameter value to use.
out	<i>chisq</i>	An matrix of resulting raw chi squared values. To get the reduced <code>chisq</code> , divide by the degrees of freedom ( <code>fit_start - fit_end - nparam</code> ), Allocate with <code>chisq = (float **)malloc</code>
in	<i>chisq_target</i>	A raw chi squared value to aim for. If this value is reached fitting will stop. If you want to aim for a reduced <code>chisq</code> (say 1.1 or 1.0) you must multiply by the degree of freedom. (TR12: "Try refits")
in	<i>progressfunc</i>	A pointer to a function that may provide some feedback to the user on progress. A number between 0 and 1 is sent to this function after each iteration. (optional: may be NULL)

## Returns

An error code, 0 = success.

## See Also

[GCI\\_SPA\\_1D\\_marquardt](#)  
[GCI\\_SPA\\_2D\\_marquardt](#)  
[GCI\\_SPA\\_1D\\_marquardt\\_instr](#)

**3.1.3.19** void GCI\_stretchedexp ( float x, float *param*[], float \* y, float *dy\_dparam*[], int *nparam* )

stretched-exp predefined fitting model.

## Parameters

in	x	The x value to evaluate the function at.
in	<i>param</i> []	Array containing the parameters to use in the evaluation.
out	y	The value of the function at the x value.
out	<i>dy_dparam</i>	Array of dy/dparam values at this point
in	<i>nparam</i>	The number of parameters (may not be used if model has a fixed parameter number)

**3.1.3.20** int GCI\_triple\_integral\_fitting\_engine ( float *xincr*, float *y*[], int *fit\_start*, int *fit\_end*, float *instr*[], int *ninstr*, *noise\_type* *noise*, float *sig*[], float \* *Z*, float \* *A*, float \* *tau*, float \* *fitted*, float \* *residuals*, float \* *chisq*, float *chisq\_target* )

The main entry point for Triple Integral or Rapid Lifetime Determination (RLD).

Uses GCI\_triple\_integral\_\*() to fit repeatedly with different integration periods until *chisq\_target* is met or a maximum number of iterations are used.

## Parameters

in	<i>xincr</i>	The time increment inbetween the values in the y array.
in	y	The transient (time resolved) signal to be analysed, the 'data'.
in	<i>fit_start</i>	The index into the y array marking the start to the data to be used in the fit.
in	<i>fit_end</i>	The index into the y array marking the end of the data to be used in the fit.
in	<i>instr</i>	The instrument reponse (IRF) or prompt signal to be used (optional, can pass NULL).
in	<i>ninstr</i>	The number of data points in the prompt (ignored if prompt = NULL).
in	<i>noise</i>	The <a href="#">noise_type</a> to be used.
in	<i>sig</i>	The standard deviation at each data point in y if <a href="#">noise_type</a> NOISE_GIVEN is used (optional, can pass NULL).
out	<i>Z</i>	The returned background value from the fit.
out	<i>A</i>	The returned amplitude value from the fit.
out	<i>tau</i>	The returned lifetime value from the fit.
out	<i>fitted</i>	An array containing values fitted to the data, the 'fit'. Fit points are coincident in time with the data points.
out	<i>residuals</i>	An array containing the difference between the data and the fit.
out	<i>chisq</i>	The resulting raw chi squared value of the fit. To get the reduced chisq, divide by the degrees of freedom (fit_start - fit_end - nparam)

in	<i>chisq_target</i>	A raw chi squared value to aim for. If this value is reached fitting will stop. If you want to aim for a reduced chisq (say 1.1 or 1.0) you must multiply by the degree of freedom. (TRI2: "Try refits")
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#### Returns

An error code, 0 = success.

## 3.2 GCI\_Lsqnonneg.h File Reference

SLIM Curve - Non-negative Least Squares Header.

### Functions

- int [GCI\\_Lsqnonneg](#) (double \*\*A, double \*b, double \*x, int m, int n, int preserve, double \*rnorm, double \*lambda)

*This function solves the non-negative least squares problem.*

#### 3.2.1 Detailed Description

SLIM Curve - Non-negative Least Squares Header.

Definition in file [GCI\\_Lsqnonneg.h](#).

#### 3.2.2 Function Documentation

**3.2.2.1** int [GCI\\_Lsqnonneg](#) ( double \*\* A, double \* b, double \* x, int m, int n, int preserve, double \* rnorm, double \* lambda )

This function solves the non-negative least squares problem.

Minimise  $|Ax-b|$  subject to  $x \geq 0$  (where  $|v|$  is the 2-norm of the vector v). !!! NB: A and B will both be modified unless preserve is non-zero (see below).

#### Parameters

in	<i>A</i>	An m x n matrix, in the form double A[n][m], so the columns of A are A[0], A[1], ..., A[n-1]
in	<i>b</i>	The m-vector
out	<i>x</i>	The solution
in	<i>m</i>	The size of the 'm' dimensions of A
in	<i>n</i>	The size of the 'n' dimensions of A
in	<i>preserve</i>	Copy A and b before solving the problem so they are not modified
out	<i>rnorm</i>	The value of $ Ax-b $ with the determined x if the function was successful or if the iteration count was exceeded. This can be NULL.
out	<i>lambda</i>	An n-vector which will contain the dual vector on completion (that is, the Lagrange multipliers). This can be NULL.

#### Returns

The return value will be 0 on success, and negative if a problem occurred:

- -1:  $m > \text{MAX\_EQNS}$  or  $m \leq 0$
- -2:  $n > \text{MAX\_VARS}$  or  $n \leq 0$
- -3: iteration count exceeded: more than  $3*n$  iterations performed
- -4: memory allocation problems

### 3.3 GCI\_Phazor.h File Reference

SLIM Curve - Phazor analysis Header.

#### Functions

- int [GCI\\_Phazor](#) (float xincr, float y[], int fit\_start, int fit\_end, float \*Z, float \*u, float \*v, float \*taup, float \*taum, float \*tau, float \*fitted, float \*residuals, float \*chisq)  
*Take transient data and perform phazor analysis, returning u, v, and estimated lifetime.*
- double [GCI\\_Phazor\\_getPeriod](#) ()  
*Get the phazor period that was calculated and used in the last call to GCI\_Phazor.*

#### 3.3.1 Detailed Description

SLIM Curve - Phazor analysis Header. Classic Phazor or Polar approach to FLIM. See Clayton 2004 or Leray 2008.  
Definition in file [GCI\\_Phazor.h](#).

#### 3.3.2 Function Documentation

**3.3.2.1** int [GCI\\_Phazor](#) ( float xincr, float y[], int fit\_start, int fit\_end, float \* Z, float \* u, float \* v, float \* taup, float \* taum, float \* tau, float \* fitted, float \* residuals, float \* chisq )

Take transient data and perform phazor analysis, returning u, v, and estimated lifetime.

$u = \text{integral}(\text{data}(t) * \cos(wt)) \, dt / \text{integral}(\text{data}(t)) \, dt$   $v = \text{integral}(\text{data}(t) * \sin(wt)) \, dt / \text{integral}(\text{data}(t)) \, dt$

$\tau \phi = \tau_{\text{up}} = 1/w * (v/u)$   $\tau \text{ mod} = \tau_{\text{um}} = 1/w * \sqrt{1/(u^2 + v^2) - 1}$   $\tau \text{ average} = \tau = (\tau_{\text{up}} + \tau_{\text{um}}) / 2$

##### Parameters

in	xincr	The time increment inbetween the values in the y array.
in	y	The transient (time resolved) signal to be analysed, the 'data'.
in	fit_start	The index into the y array marking the start to the data to be used in the fit.
in	fit_end	The index into the y array marking the end of the data to be used in the fit.
out	Z	must have been estimated previously so that it can be subtracted from the data here.
out	u	The 'horizontal' phazor coordinate.
out	v	The 'vertical' phazor coordinate.
out	taup	The lifetime calculated from the phase change.
out	taum	The lifetime calculated from the amplitude change (the demodulation).
out	tau	The average of the other taus.
out	fitted	An array containing values fitted to the data, the 'fit'. Fit points are coincident in time with the data points.
out	residuals	An array containing the difference between the data and the fit.
out	chisq	The resulting reduced chi squared value of the fit.

##### Returns

An error code, 0 = success.

**3.3.2.2** double [GCI\\_Phazor\\_getPeriod](#) ( )

Get the phazor period that was calculated and used in the last call to GCI\_Phazor.

## Returns

The period in the time units of xinc.

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