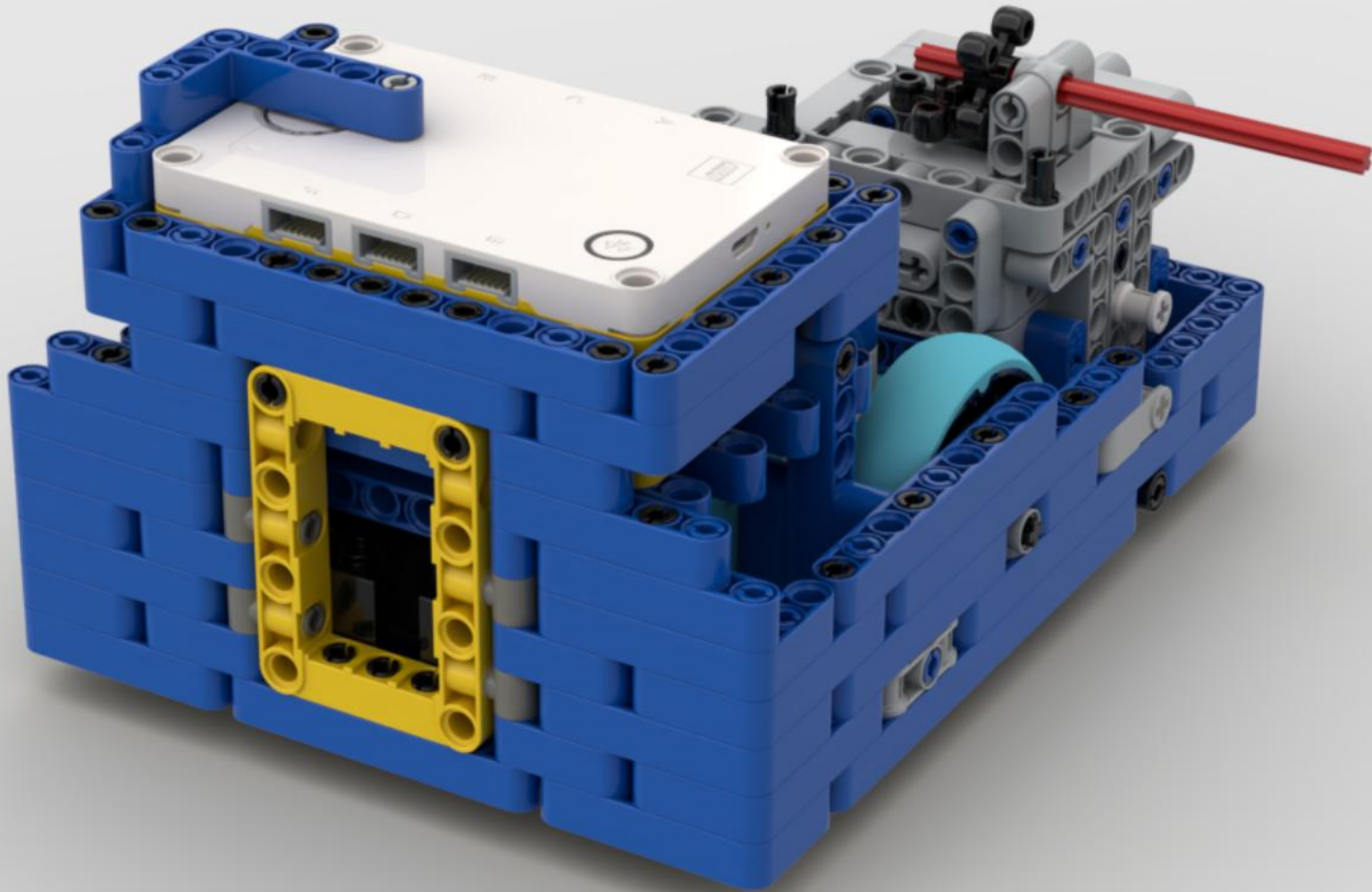
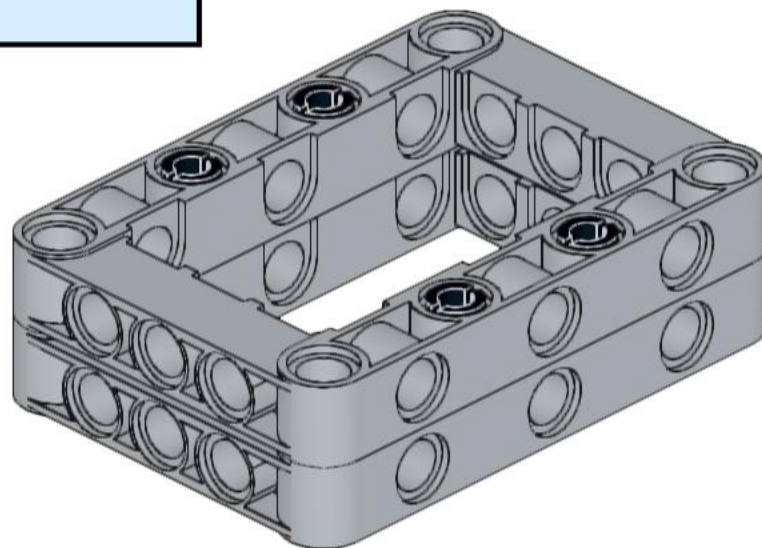
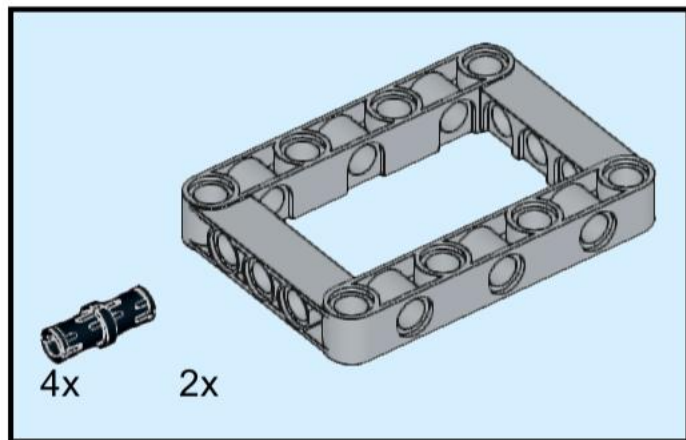


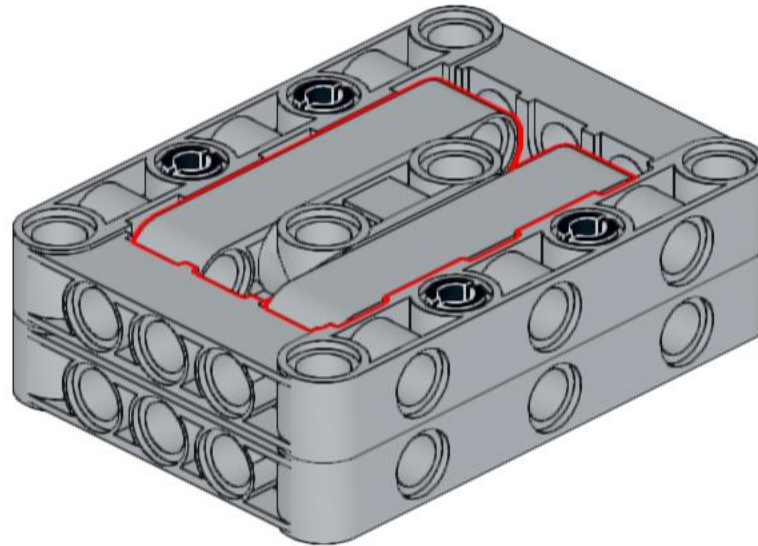
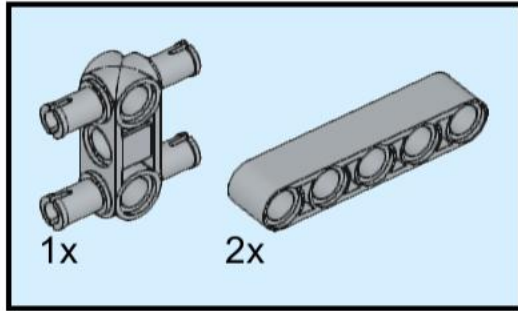
Axle extends out the
right side of the robot



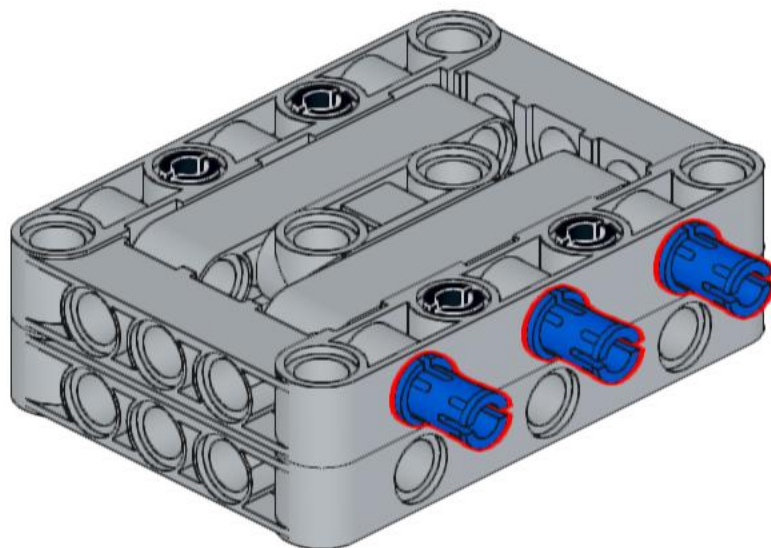
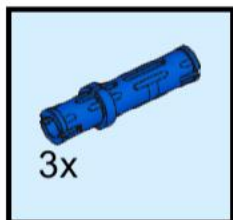
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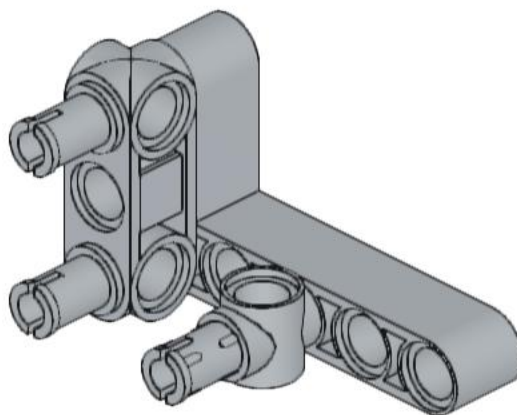
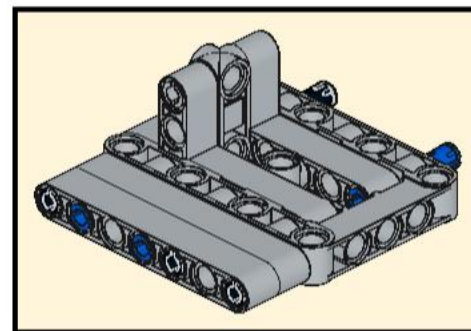
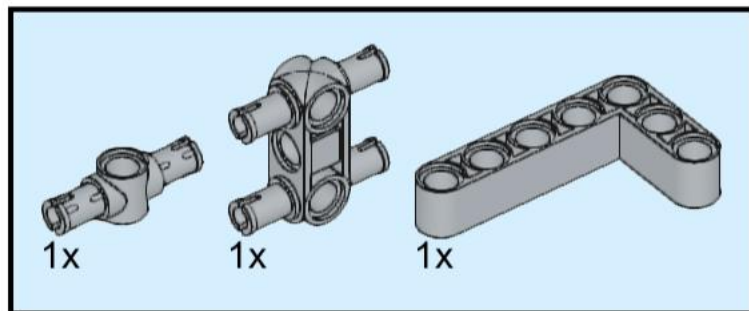
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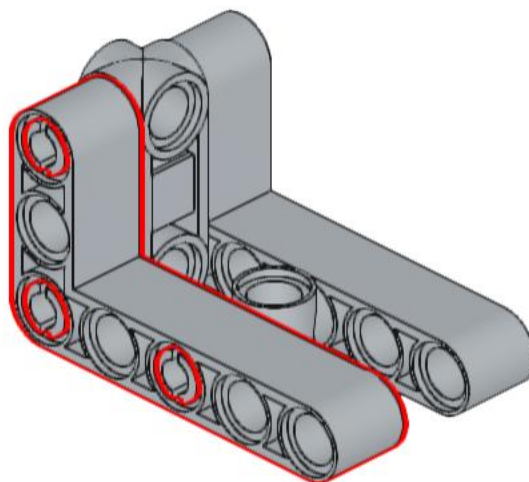
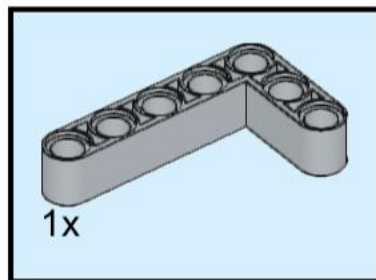
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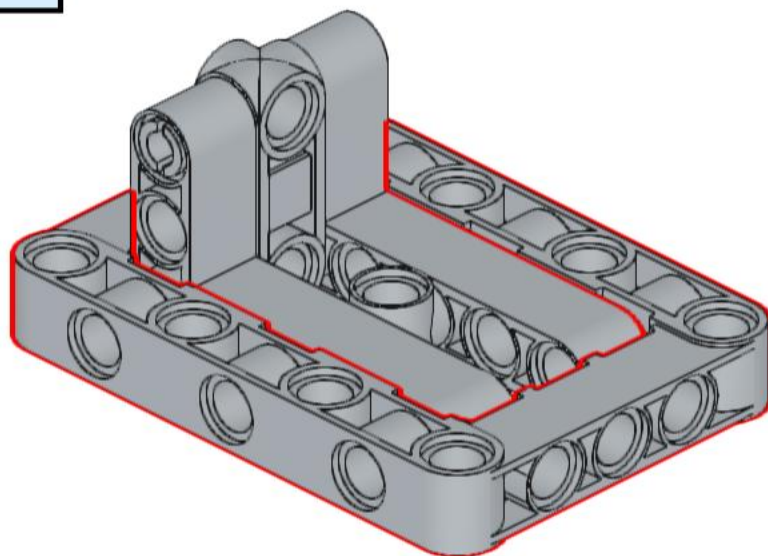
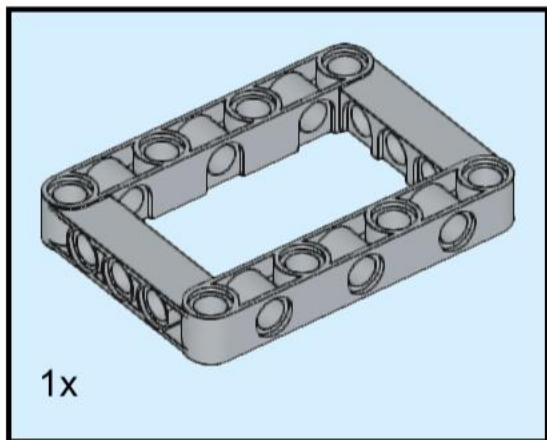
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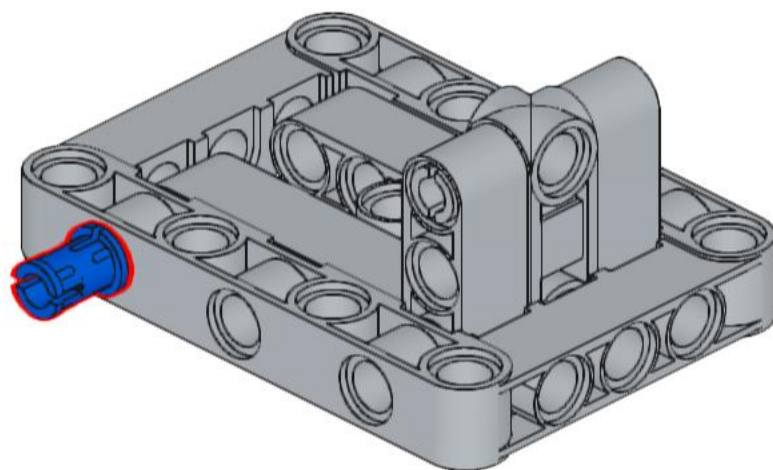
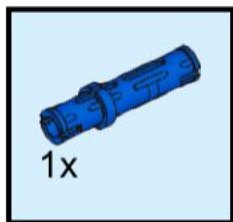
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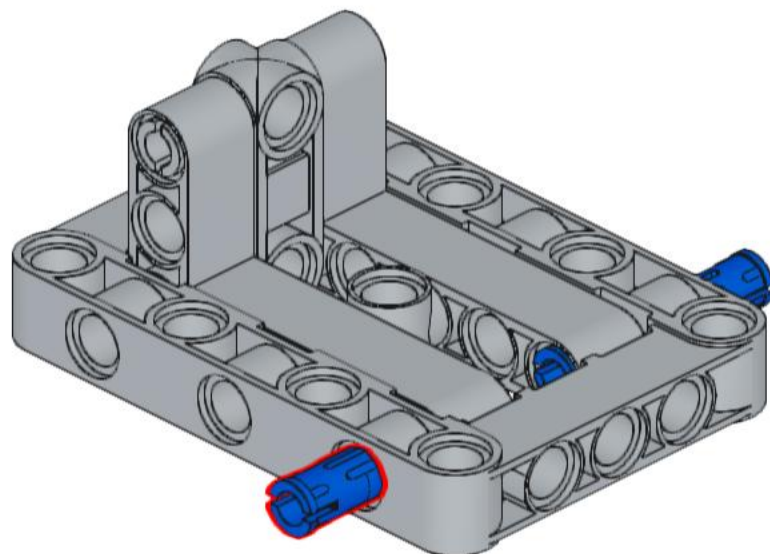
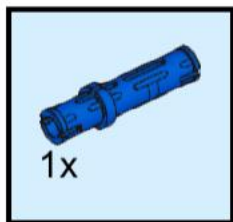
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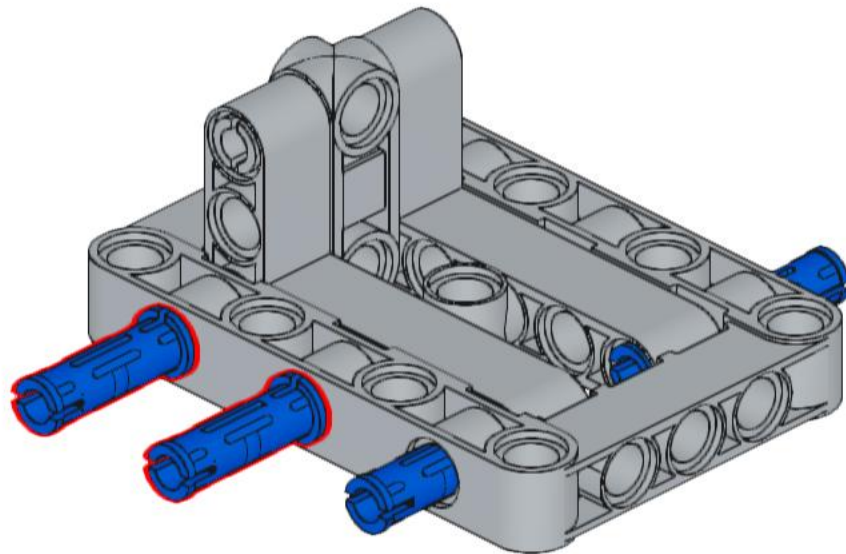
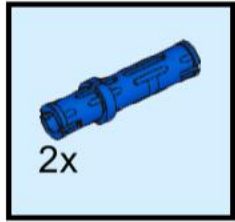
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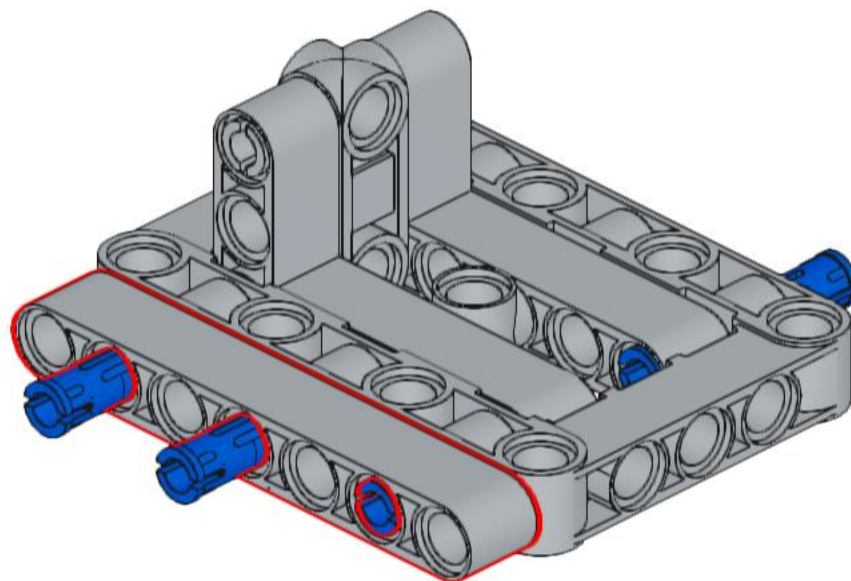
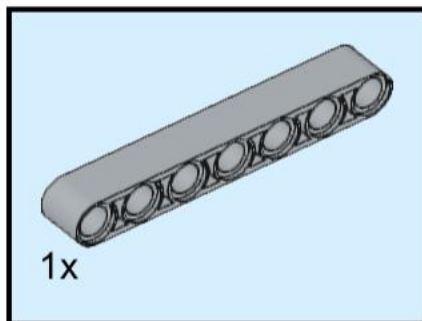
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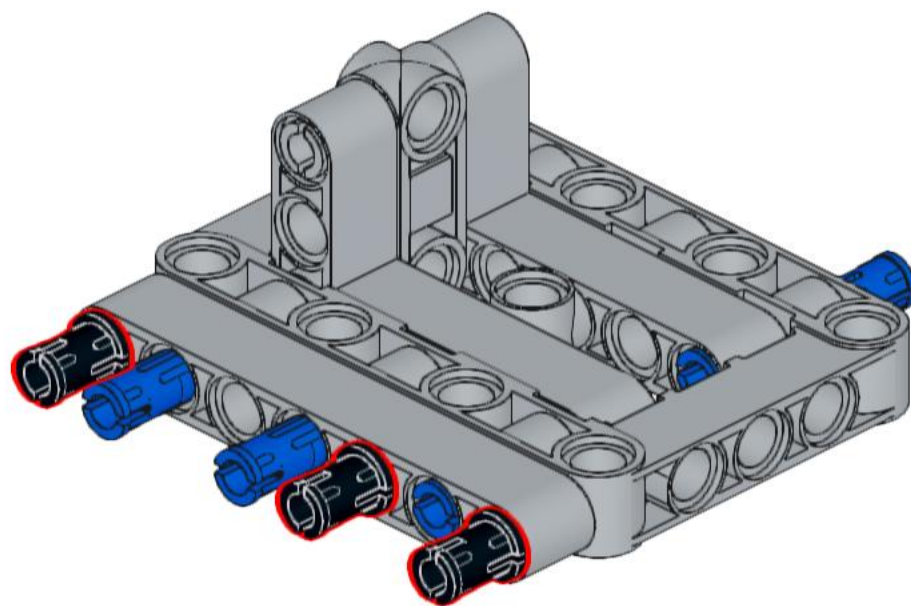
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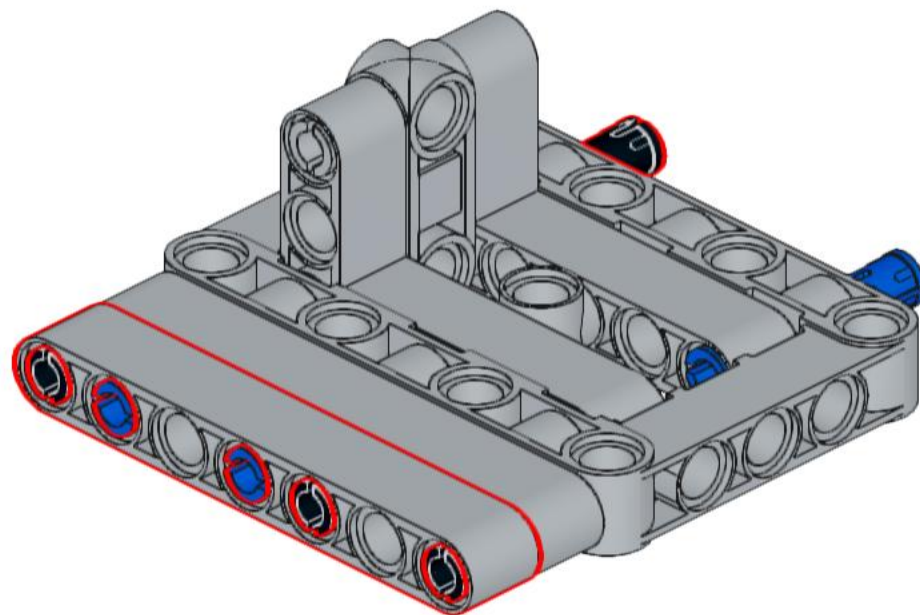
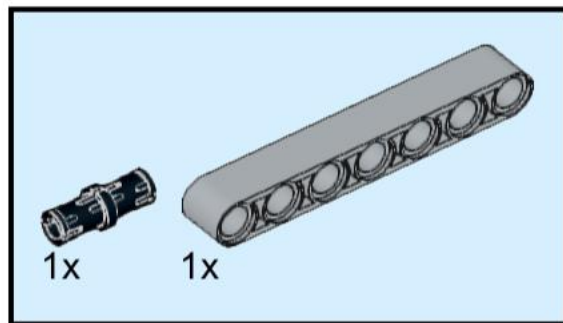
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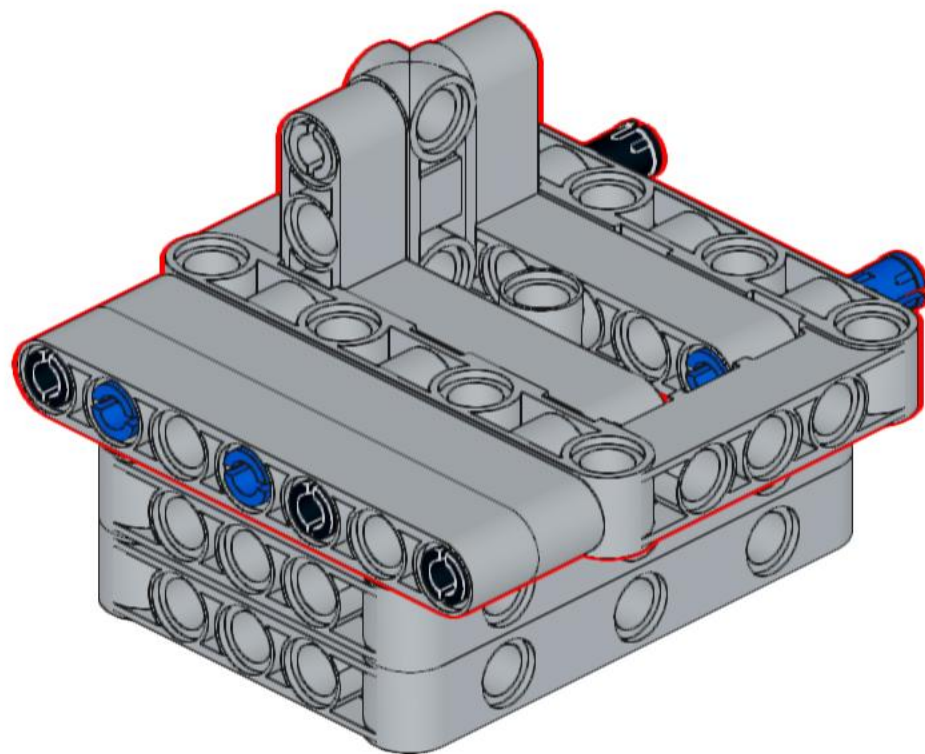
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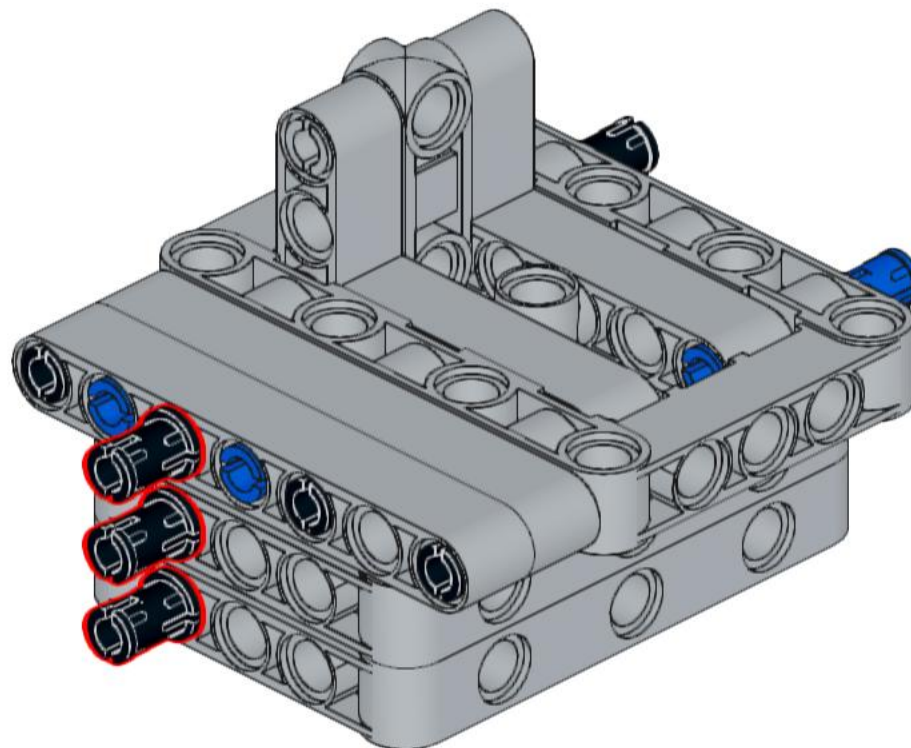
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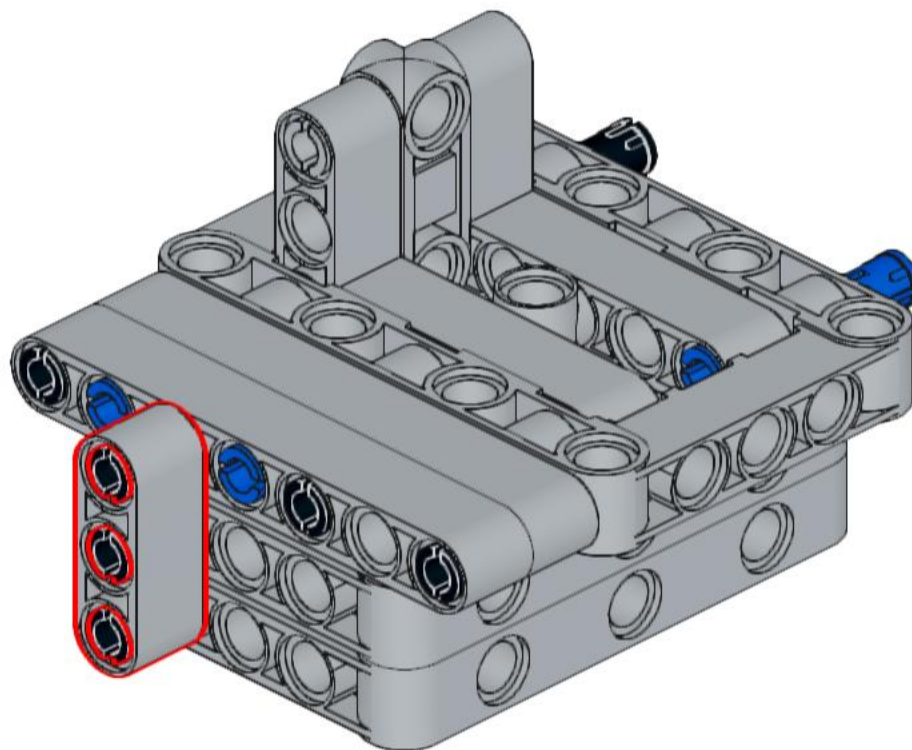
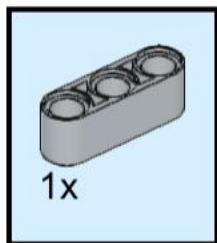
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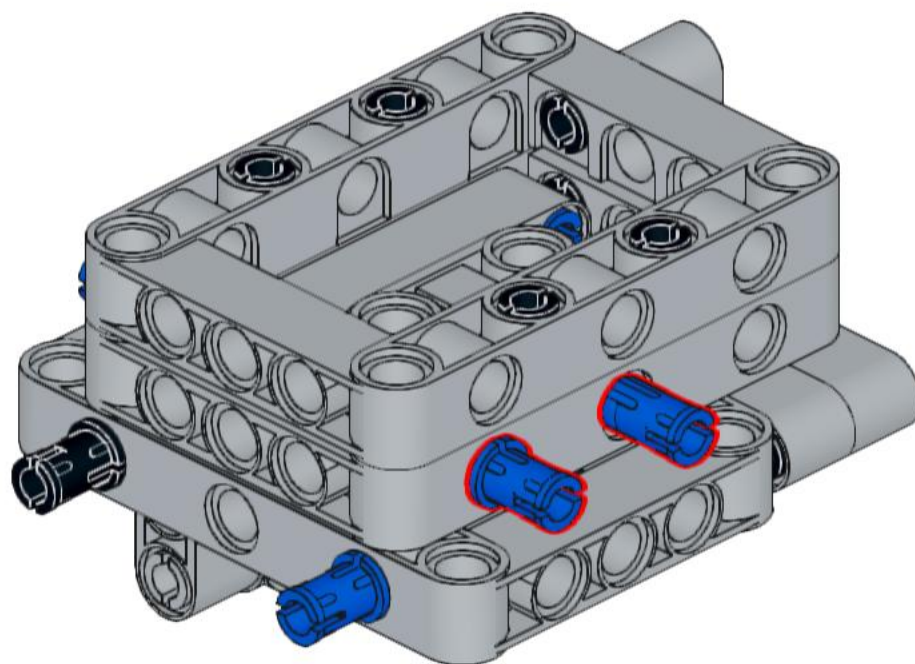
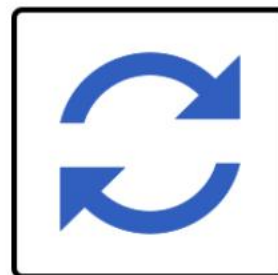
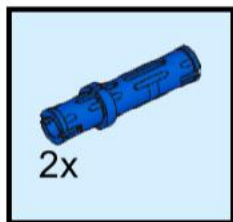
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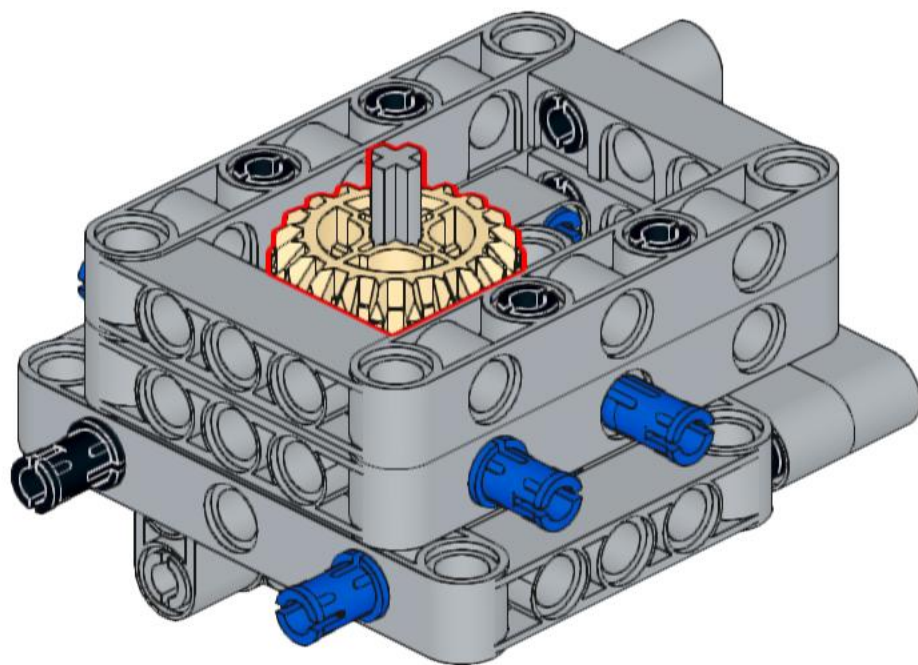
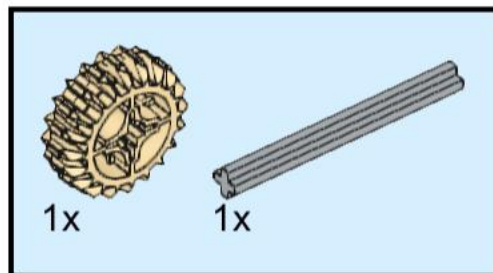
15



16



17



You have three gear options on the next steps. How will you decide which to choose? If you don't know, ask a coach or someone on the team.

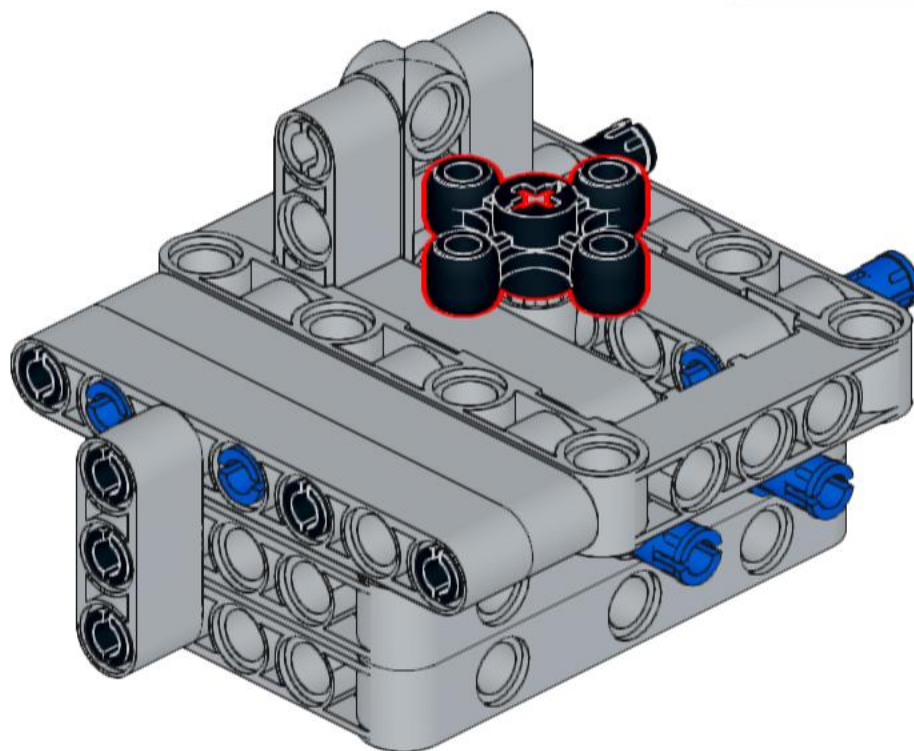
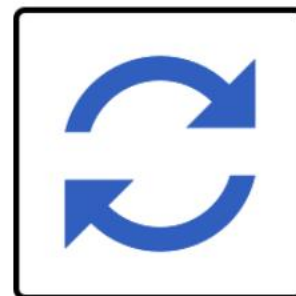
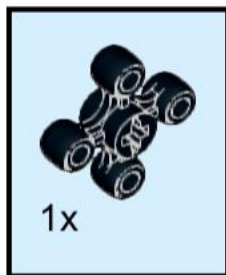
Which is fastest?

Which has the most power?

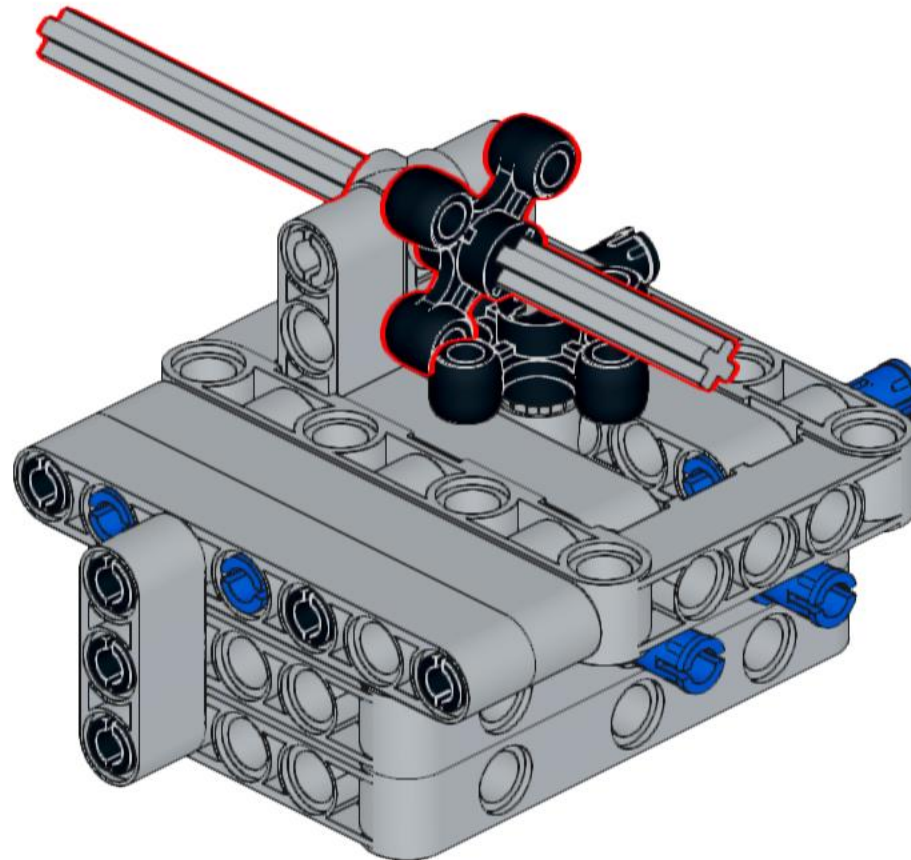
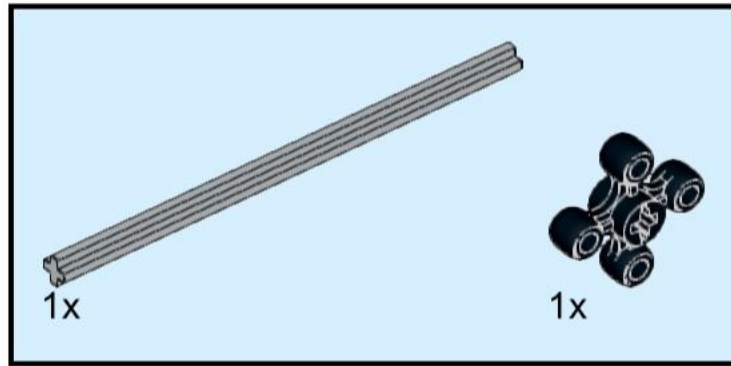
Which is least likely to slip if overloaded?



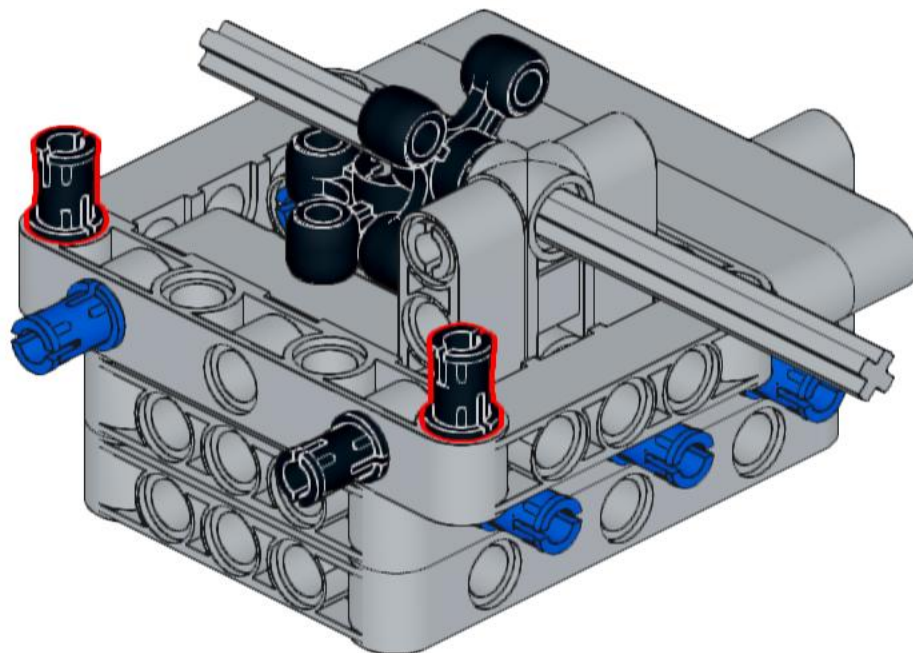
18



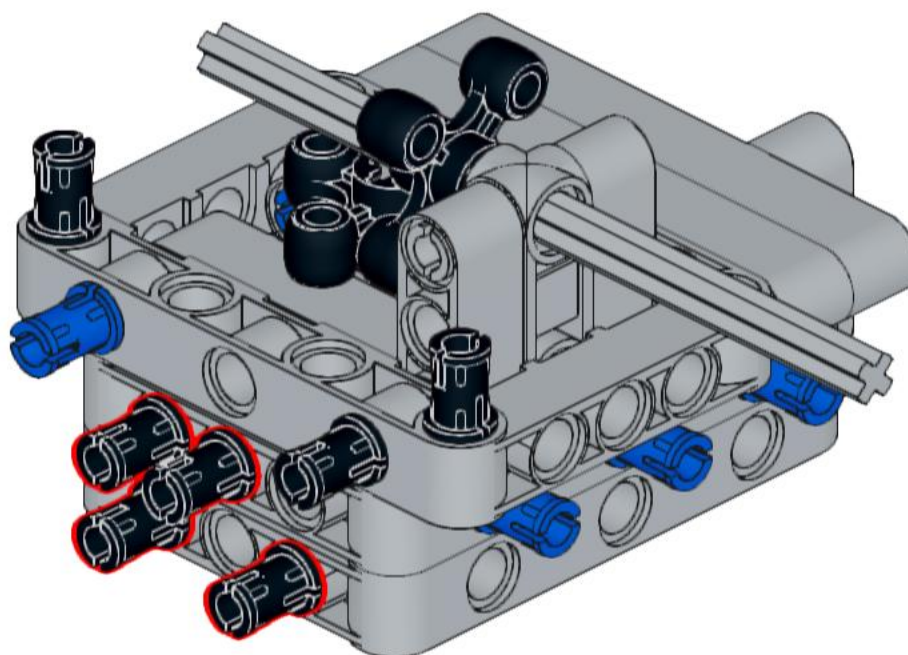
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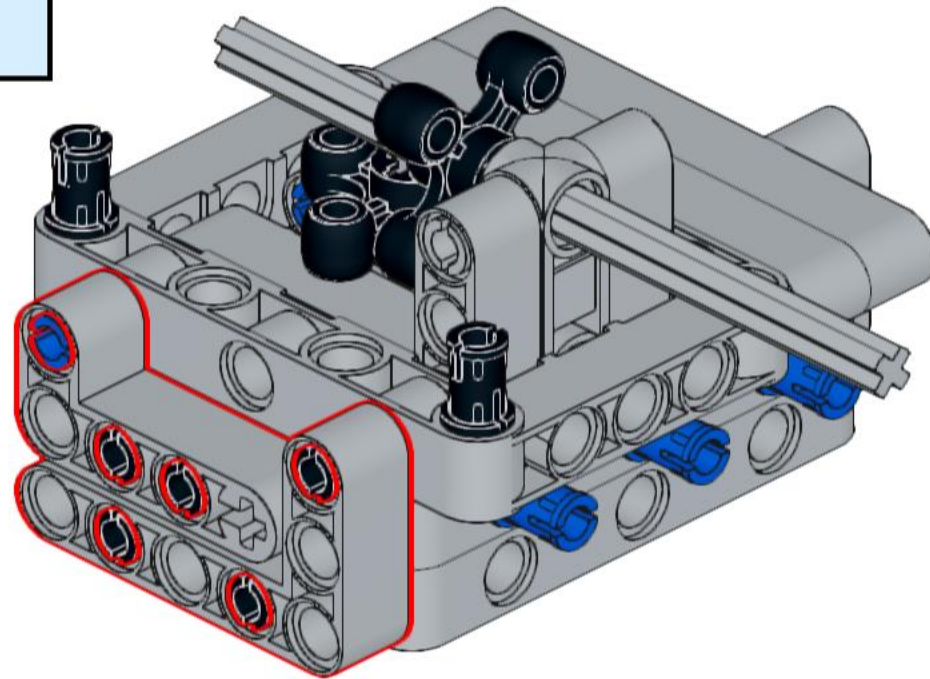
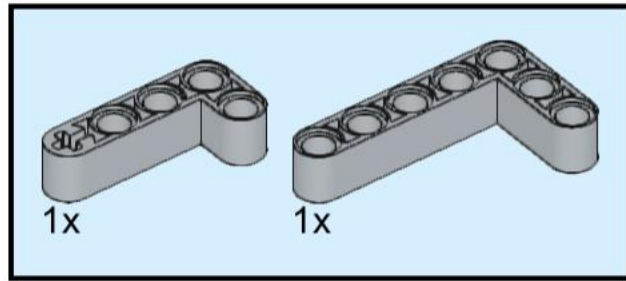
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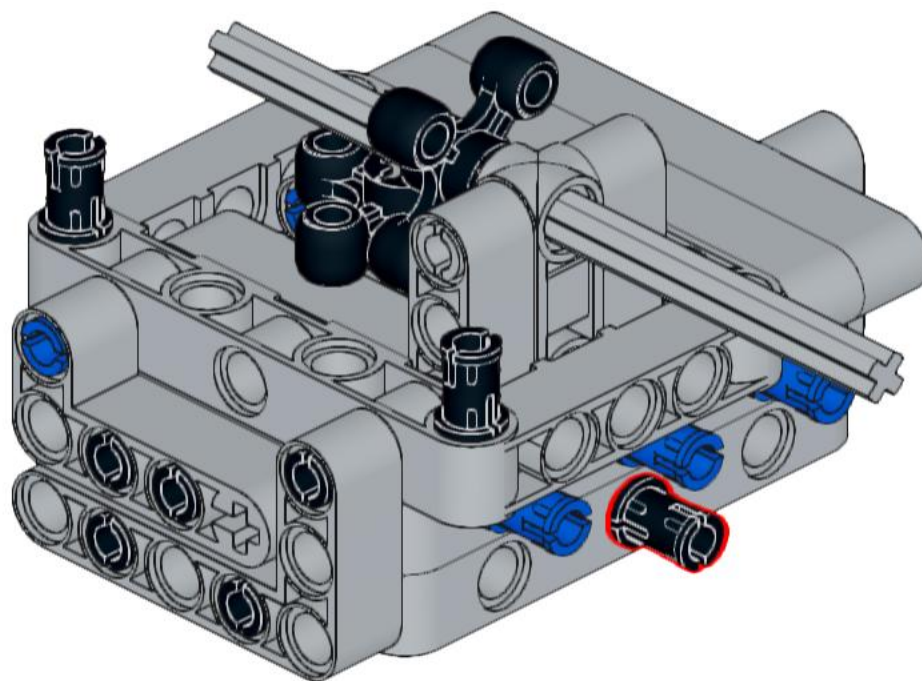
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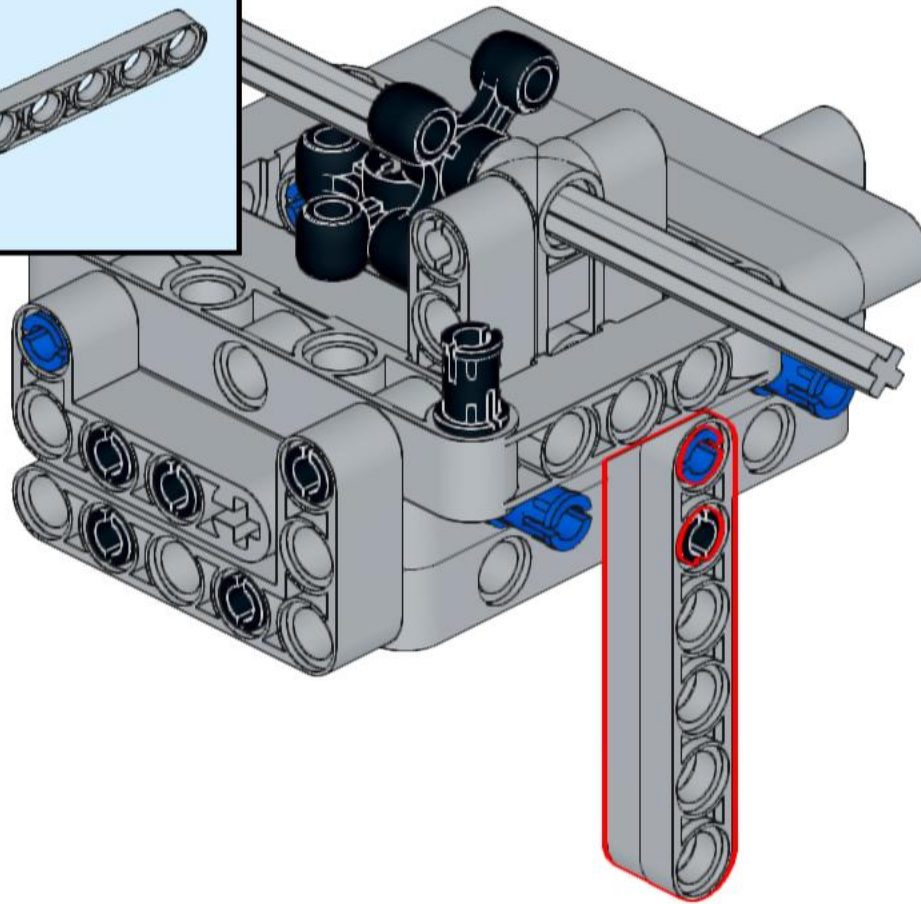
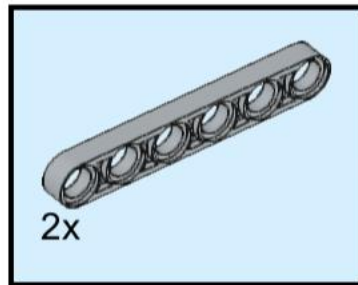
22



23



24



25

