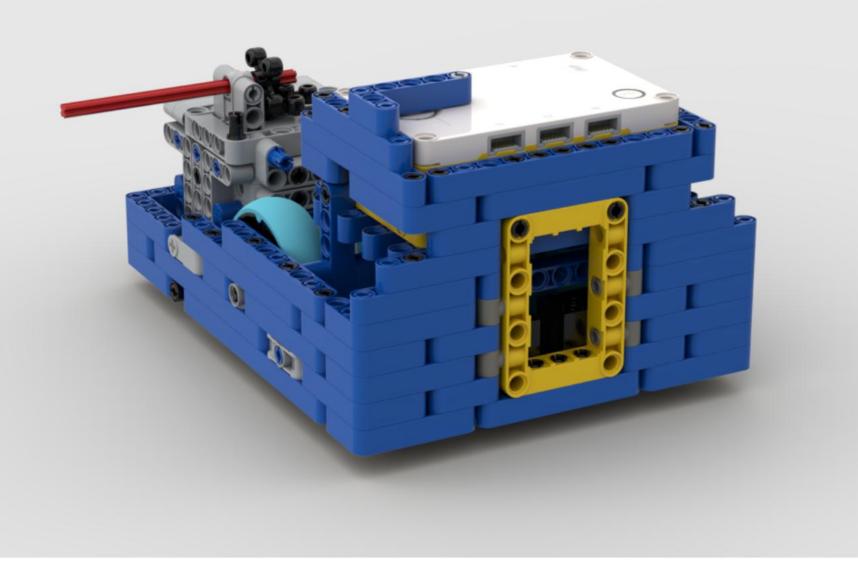
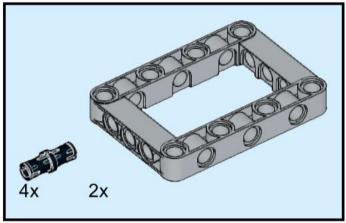
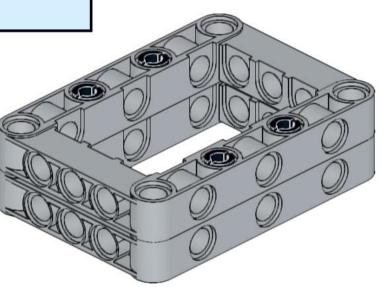
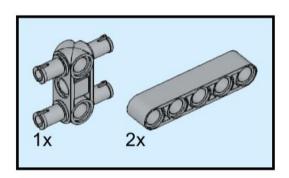
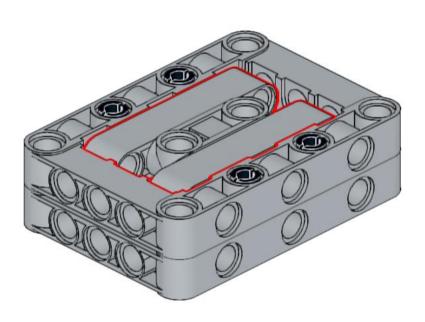
## Axle extends out the left side of the robot

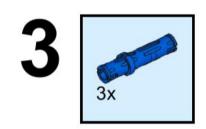


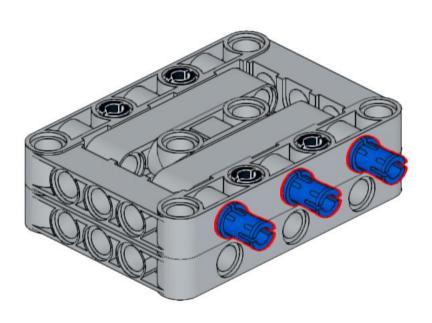


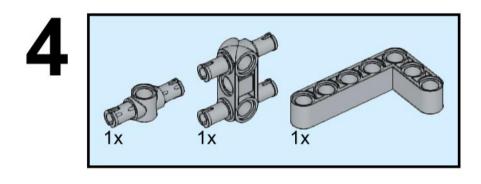


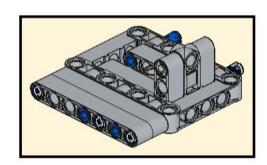


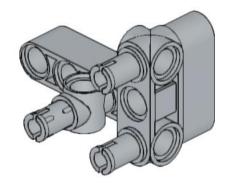


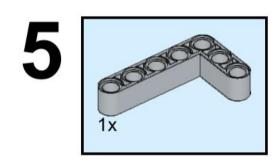


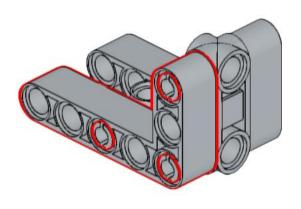


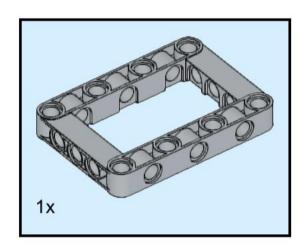


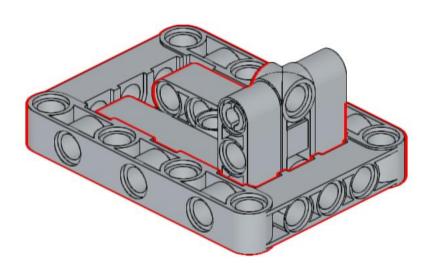


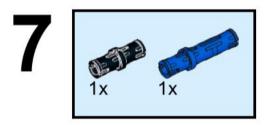


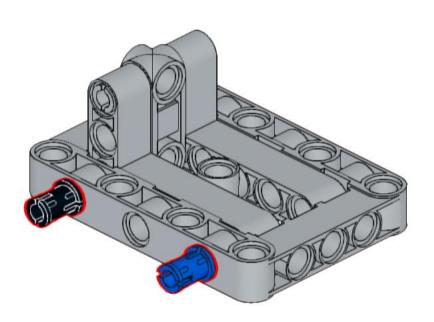


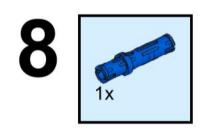


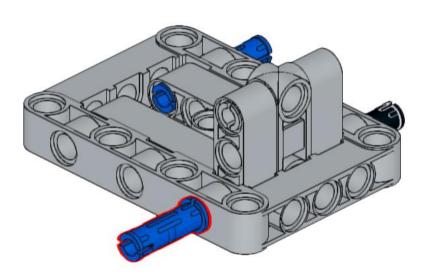


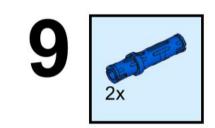


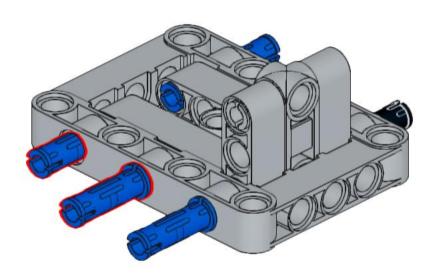


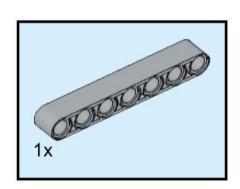


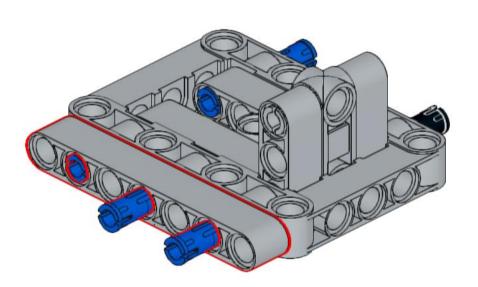




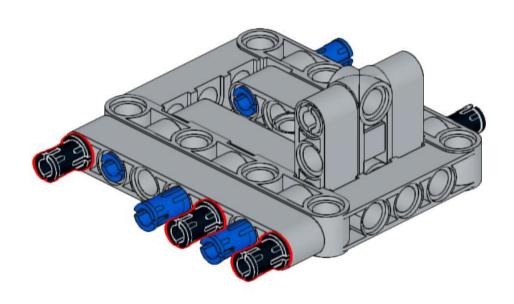


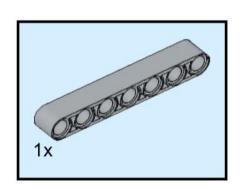


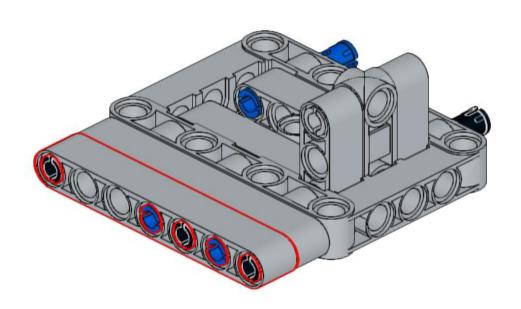


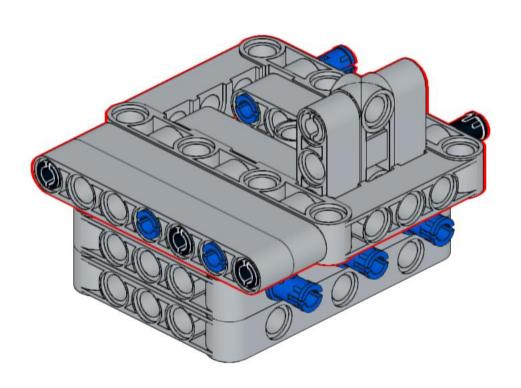


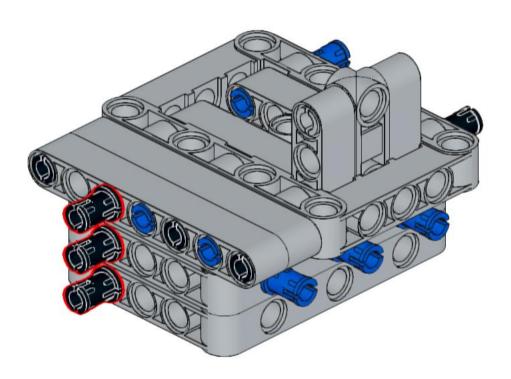
# 3x



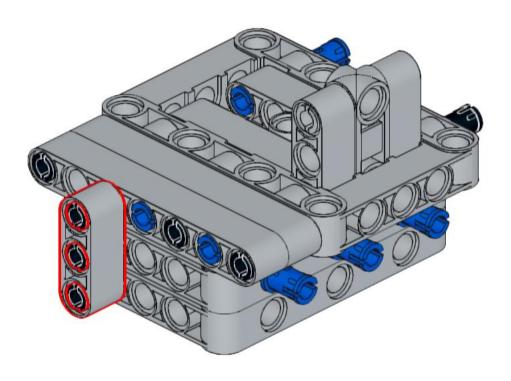




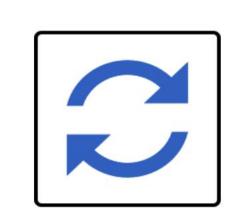


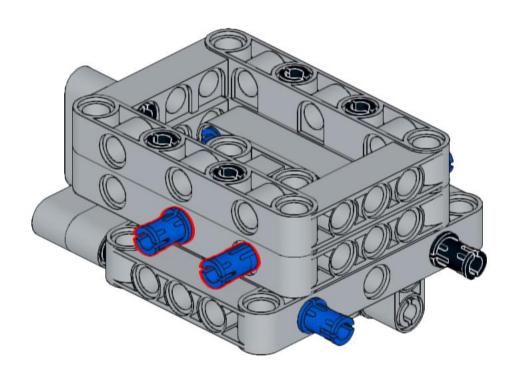


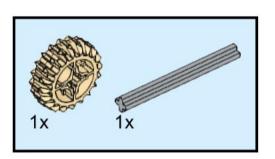
# 15 1x

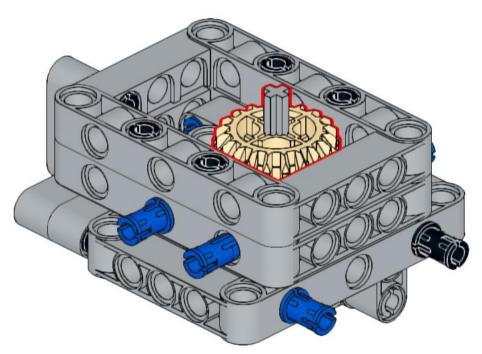


# 16 <sub>2x</sub>









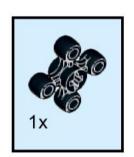
You have three gear options on the next steps. How will you decide which to choose? If you don't know, ask a coach or someone on the team.

Which is fastest?
Which has the most power?
Which is the least likely to slip if overloaded?

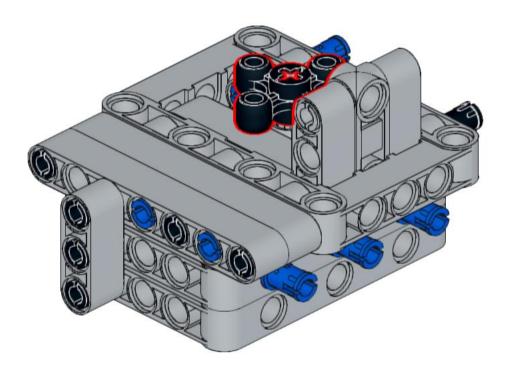


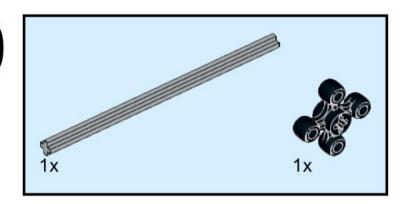


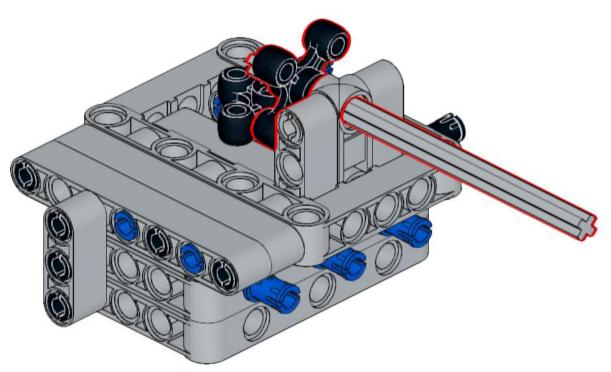


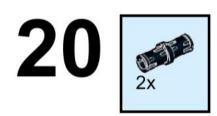


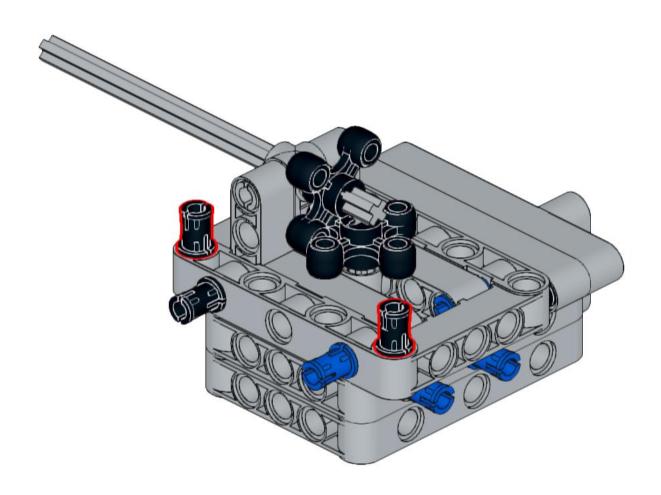




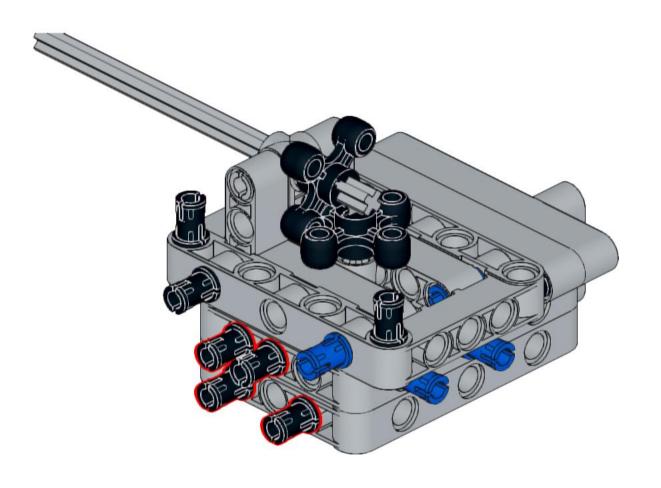


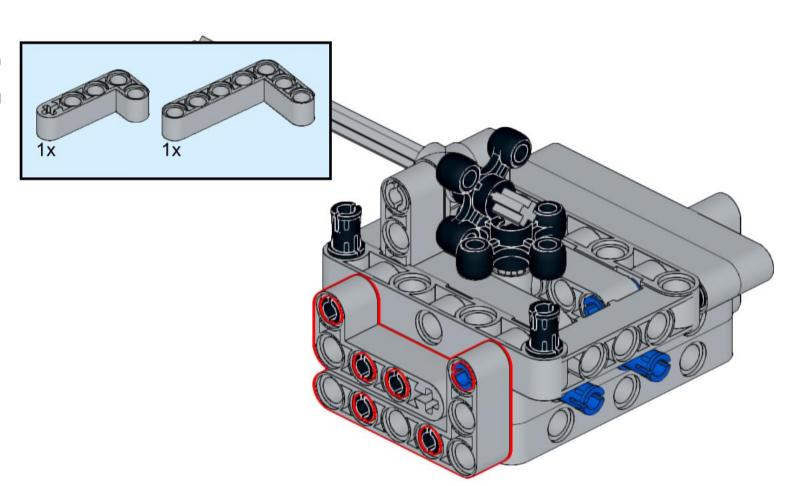












# 23 1x

