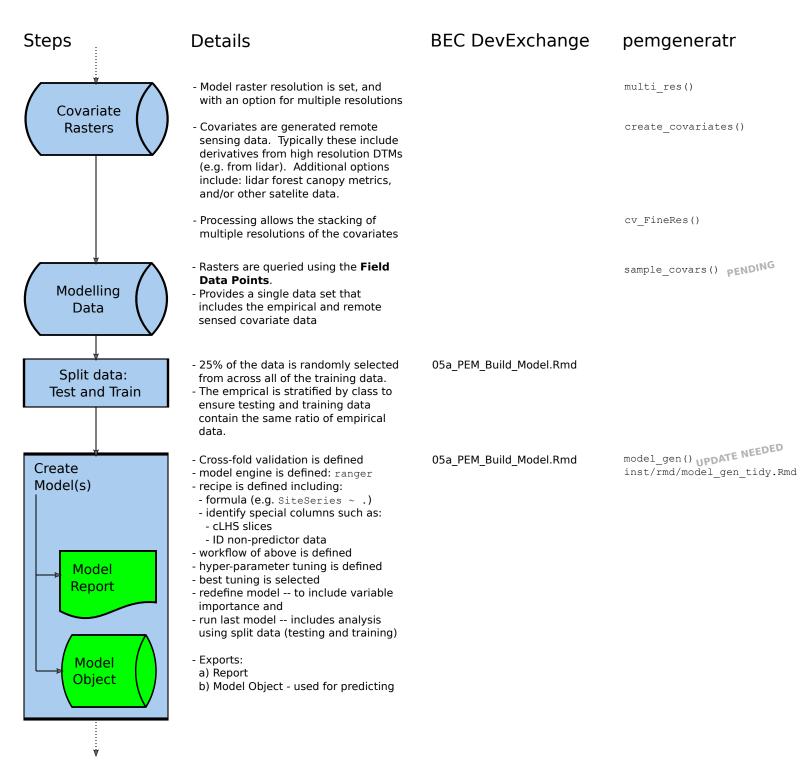
BC's Predictive Ecosystem Mapping Process

Part A: Field Sampling

Steps **Details** BEC DevExchange pemgeneratr - Digital Terrain Model (25m²) 00_folder_set_up.Rmd - Defined area of interest 01 BaseLayerConsolidate.Rmd aoi snap() Initial Data (snapped to 100m grid) plan get baselayers (ENDING - BEC Subzones - BCData sources: - Freshwater atlas (lakes, wetlands, and rivers) - roads - VRI: age class and conifer leading - Harvested Areas of BC - Forest Tenure Harvesting **Authority Polygons** - BC Major Cities Points - Fire Perimeters - Current - Fire Perimeters - Historical - TANTALIS - Surface Ownership PENDING 1. Generate sample plan covariates 01 raster BaseLayers.Rmd plan covariates() PENDING 2. Generate sample cost surface 03a_Stage1_SampleDesign.Rmd plan exclusion() plan_costsurface() pENDING Sample Plan (raster) plan_locatesampling (ENDING 3. Sliced Conditioned Latin Hyper-Cube PENDING sample points and associated survey plan transects() transects. - Using QGIS -- ATLAS module Manual Manual - 1:100.000 processing processing Sampling Map 1:2.500 Production - Export to ipad Avenza's 'PDF Map' as a 'map collection' - Sampling Schema set for project Manual Manual - Use high precision (sub-metre) GPS - Complete all fields as per the schema Field Data processing processing - Record track-log Collection - Record locations where Site Series changes. - Record site series you are entering. Looking ahead, not behind - Export as GPX and Shapefile - imports GPX and or Shapefile data 04a_TrainingPt_ r avenza() make lines() TransectImport&Clean.Rmd - Converts point data to lines Data Import 04a_AA_TrainingPt - converts lines to regularly sampled transect sample() TransectImport&Clean.Rmd points 04b TrainingPt Summary.Rmd - Spatial database of regular sample **Field Data** contains all empirical data for **Points** modelling - In the following steps this will be used C. Chisholm to extract covariate data

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Part B: Modelling



Note that the modelling framework started with the mlr package and is being converted to the tidymodels framework. This was done as mlr is no longer maintained, mlr3 is not yet released, and the tidymodels systems is very well documented. The main processing engine, ranger (used to process random forest models), remains the same.

BC's Predictive Ecosystem Mapping Process

Part C: Mapping and Map Accuracy

