

Camera pose

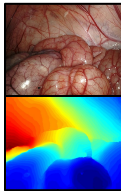
local dynamic
radiance fields

$[R|T]$



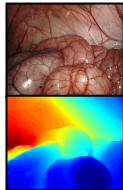
Pred_{rgb}

Pred_{Depth}



\mathcal{L}_{rgb}

\mathcal{L}_z



GT_{rgb}

RAFT_{Depth}

\mathcal{L}_f



RAFT_{Flow}

Forward Pass
Gradient Flow