

COMP2003

Data Structures and Algorithms

Lecture 8: Binary Trees (二叉树), Binary Search Trees (二叉查找树)



Trees

- Linear access time of linked lists is prohibitive
 - ◆ Does there exist any simple data structure for which the running time of most operations (search, insert, delete) is $O(\log N)$?
- Trees
 - ◆ Basic concepts
 - ◆ Tree traversal
 - ◆ Binary tree
 - ◆ Binary search tree and its operations

Trees

- A tree is a collection of nodes
 - ◆ The collection can be empty
 - ◆ (recursive definition) If not empty, a tree consists of a distinguished node r (the *root*), and **zero or more** nonempty *subtrees* T_1, T_2, \dots, T_k , each of whose roots are connected by a directed *edge* from r

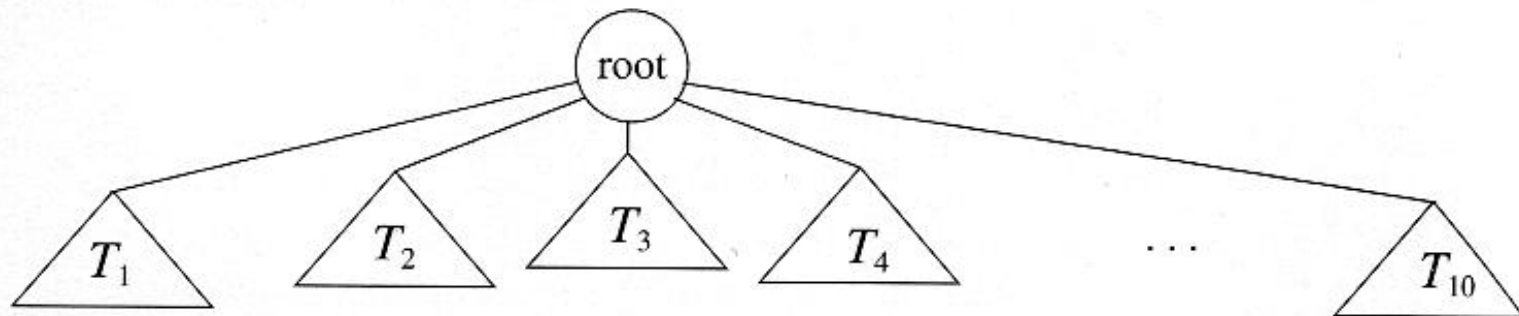


Figure 4.1 Generic tree

Some Terminologies

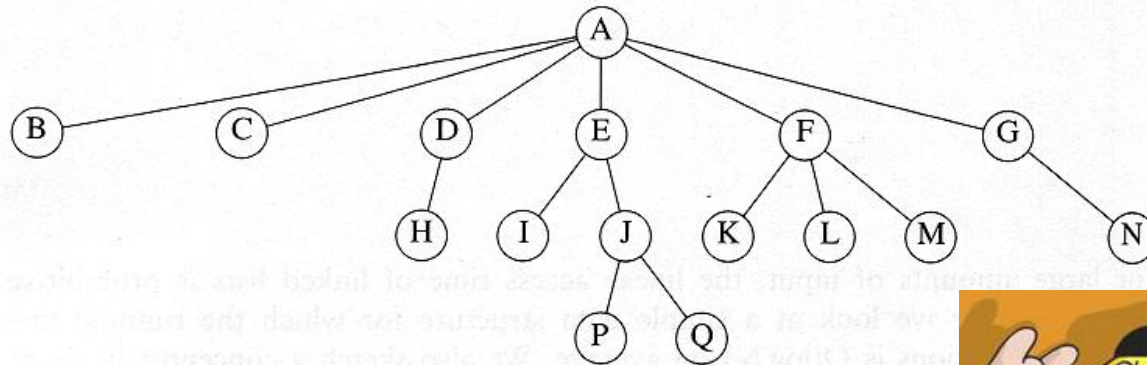


Figure 4.2 A tree

■ *Child* and *Parent*

- ◆ Every node except the **root** has one parent
- ◆ A node can have an zero or more children

■ *Leaves*

- ◆ Leaves are nodes with no children

■ *Sibling* (兄弟姐妹)

- ◆ nodes with same parent



More Terminologies

- *Path*
 - ◆ A sequence of edges
- *Length of a path*
 - ◆ number of edges on the path
- *Depth of a node*
 - ◆ length of the unique path from the root to that node
- *Height of a node*
 - ◆ length of the longest path from that node to a leaf
 - ◆ all leaves are at height 0
- *The height of a tree* = the height of the root
= the depth of the deepest leaf
- *Ancestor* and *descendant*
 - ◆ If there is a path from n_1 to n_2
 - ◆ n_1 is an ancestor of n_2 , n_2 is a descendant of n_1
 - ◆ *Proper ancestor* and *proper descendant*

Example: UNIX Directory

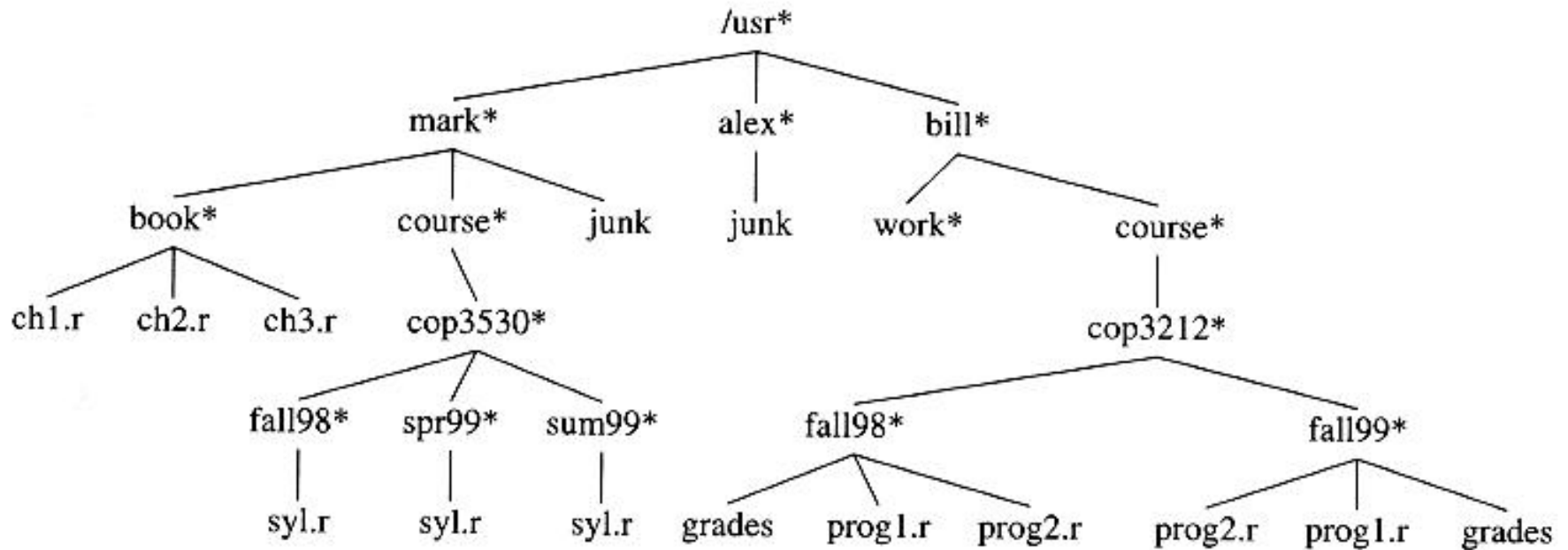


Figure 4.5 UNIX directory

Example: Expression Trees

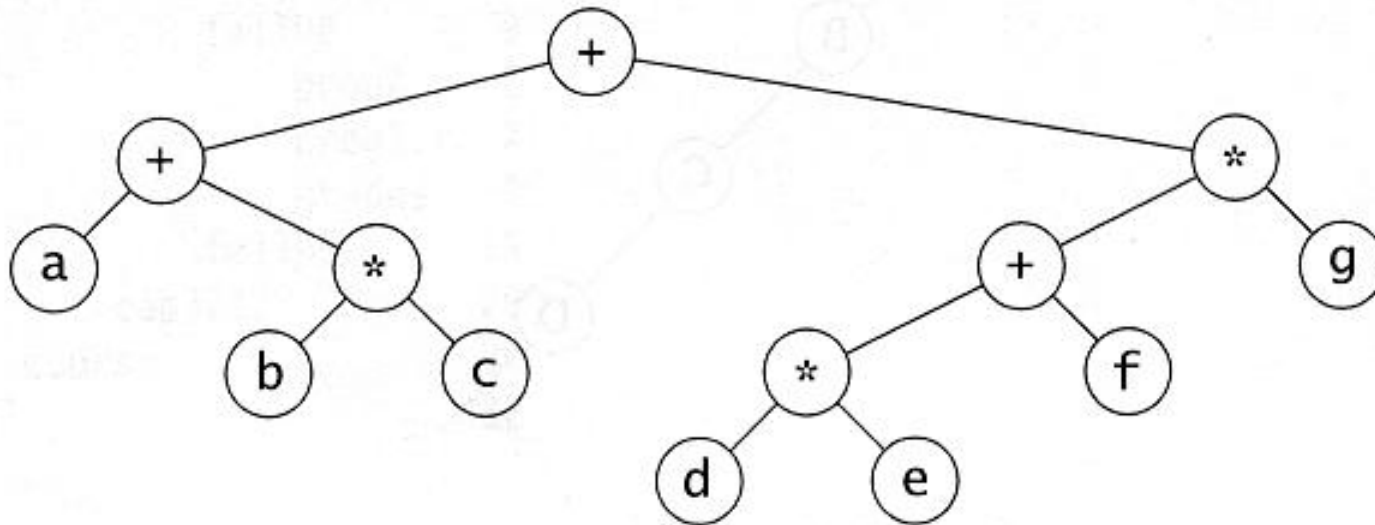
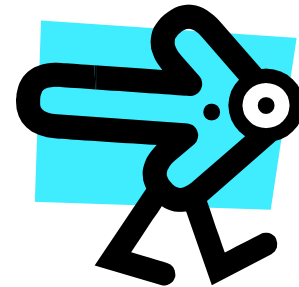
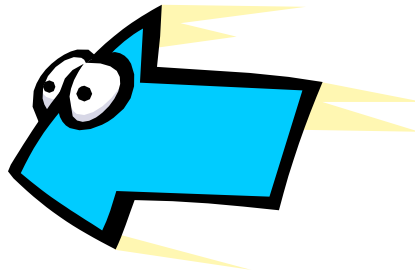
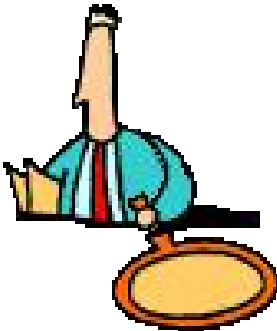


Figure 4.14 Expression tree for $(a + b * c) + ((d * e + f) * g)$

- Leaves are operands (运算数) (constants or variables)
- The internal nodes contain operators (运算符)
- Will not be a binary tree if some operators are not binary

Tree Traversal

- Used to print out the data in a tree in a certain order
- Pre-order traversal
 - ◆ Print the data at the **root**
 - ◆ **Recursively** print out all data in the **left subtree**
 - ◆ Recursively print out all data in the **right subtree**



Preorder, Postorder and Inorder

■ Preorder traversal

- ◆ Traversal order: **node, left, right**
- ◆ Example: **prefix** expression (前缀表达式)

$++a*bc*+*defg$

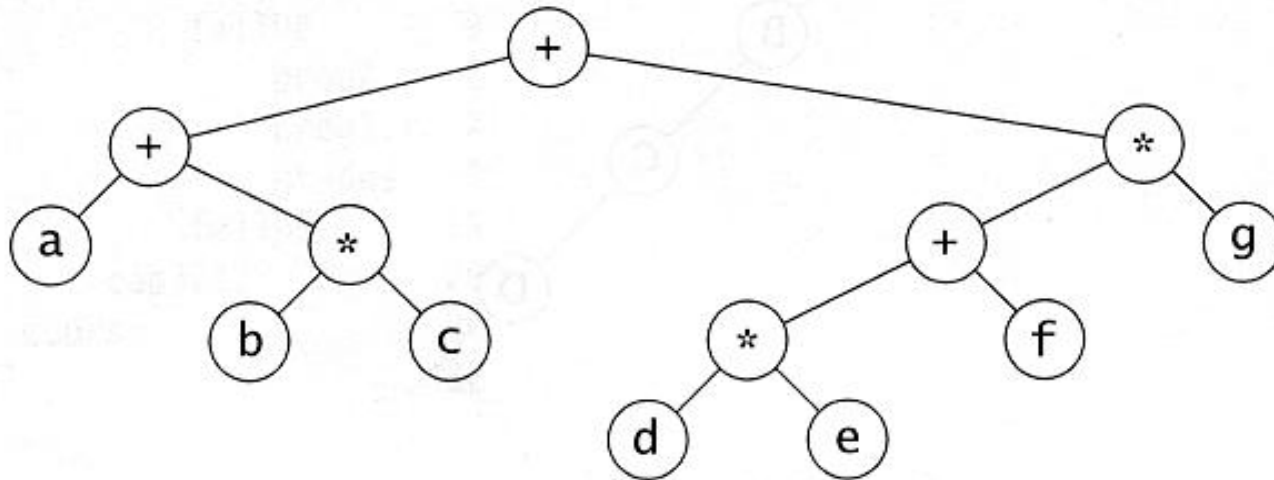


Figure 4.14 Expression tree for $(a + b * c) + ((d * e + f) * g)$

Preorder, Postorder and Inorder

■ Postorder traversal

◆ left, right, node

◆ postfix expression

$abc^*+de^*f+g^*+$

■ Inorder traversal

◆ left, node, right

◆ infix expression

$a+b^*c+d^*e+f^*g$

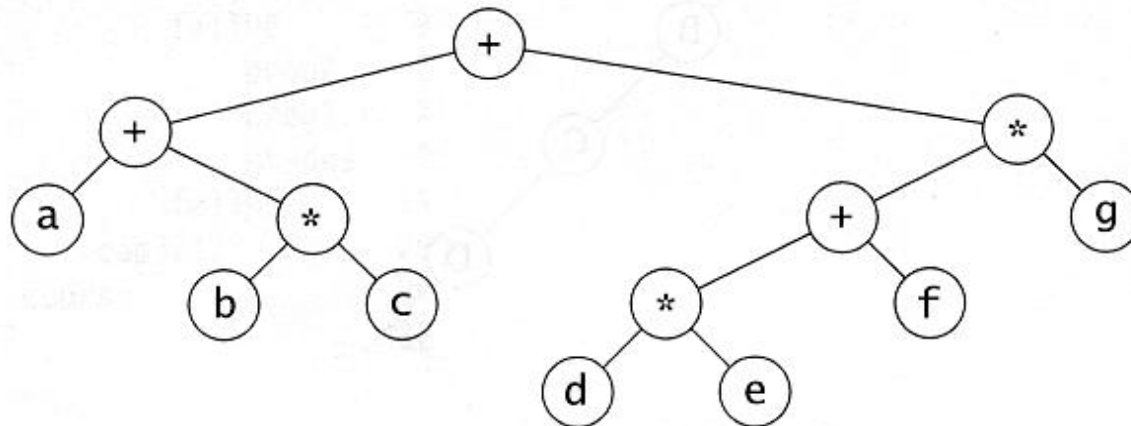


Figure 4.14 Expression tree for $(a + b * c) + ((d * e + f) * g)$

Example: Unix Directory Traversal

PreOrder

```
/usr
  mark
    book
      ch1.r
      ch2.r
      ch3.r
    course
      cop3530
        fall98
          syl.r
        spr99
          syl.r
        sum99
          syl.r
      junk
    alex
      junk
    bill
      work
      course
        cop3212
          fall98
            grades
            prog1.r
            prog2.r
          fall99
            prog2.r
            prog1.r
            grades
```

PostOrder

```
  ch1.r      3
  ch2.r      2
  ch3.r      4
  book      10
    syl.r     1
    fall98    2
    syl.r     5
    spr99     6
    syl.r     2
    sum99     3
  cop3530    12
  course     13
  junk       6
  mark      30
  junk       8
  alex       9
  work       1
    grades    3
    prog1.r   4
    prog2.r   1
  fall98     9
    prog2.r   2
    prog1.r   7
    grades    9
  fall99     19
  cop3212    29
  course     30
  bill       32
/usr        72
```

Preorder, Postorder and Inorder Pseudo Code

Algorithm *Preorder*(x)

Input: x is the root of a subtree.

1. **if** $x \neq \text{NULL}$
2. **then** output key(x);
3. *Preorder*(left(x));
4. *Preorder*(right(x));

Algorithm *Postorder*(x)

Input: x is the root of a subtree.

1. **if** $x \neq \text{NULL}$
2. **then** *Postorder*(left(x));
3. *Postorder*(right(x));
4. output key(x);

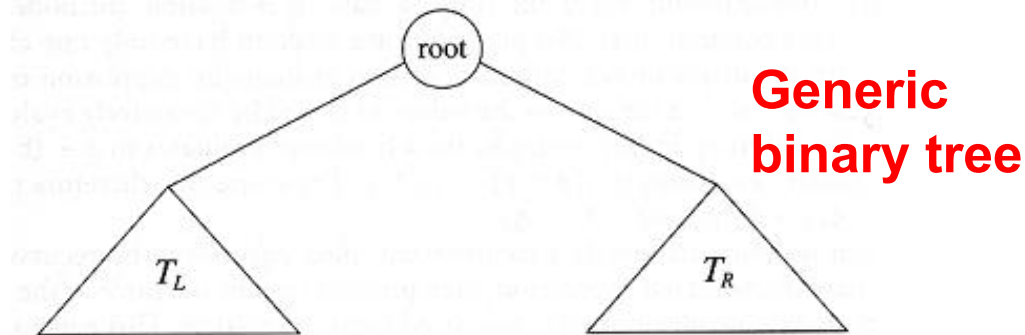
Algorithm *Inorder*(x)

Input: x is the root of a subtree.

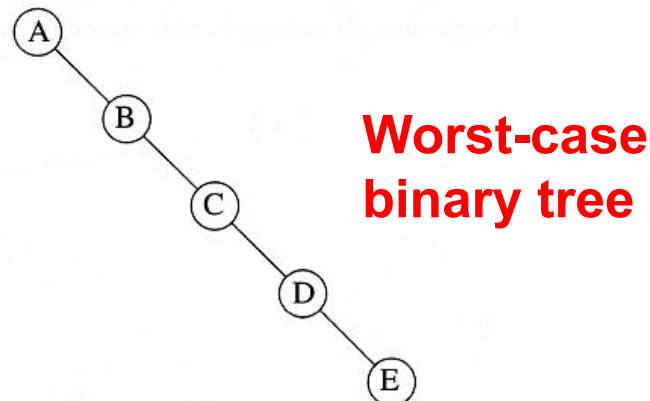
1. **if** $x \neq \text{NULL}$
2. **then** *Inorder*(left(x));
3. output key(x);
4. *Inorder*(right(x));

Binary Trees

- Binary tree is a tree in which **no node can have more than two children**



- The depth of an “average” binary tree is considerably smaller than N , even though in the worst case, the depth can be as large as $N - 1$.



Node Struct of Binary Tree

- Possible operations on the Binary Tree ADT
 - ◆ Parent, left_child, right_child, sibling, root, etc
- Implementation
 - ◆ Because a binary tree has at most two children, we can keep direct pointers to them

```
struct BinaryNode
{
    Object      element;           // The data in the node
    BinaryNode *left;              // Left child
    BinaryNode *right;             // Right child
};
```

Convert a Generic Tree to a Binary Tree

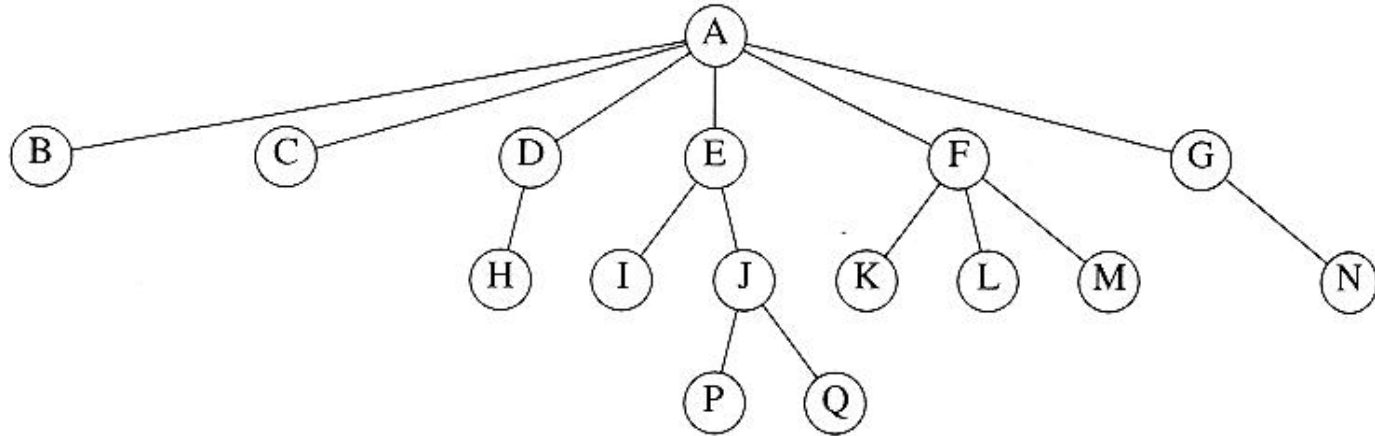


Figure 4.2 A tree

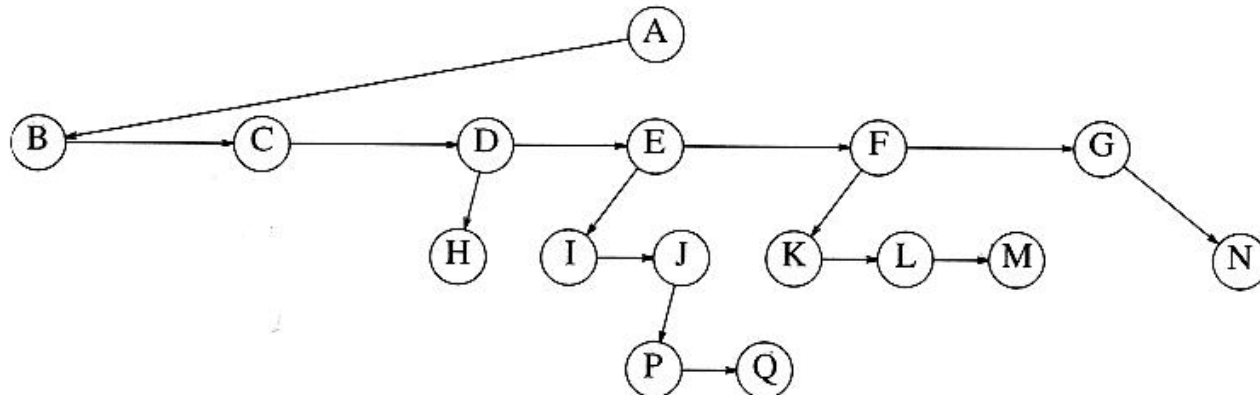
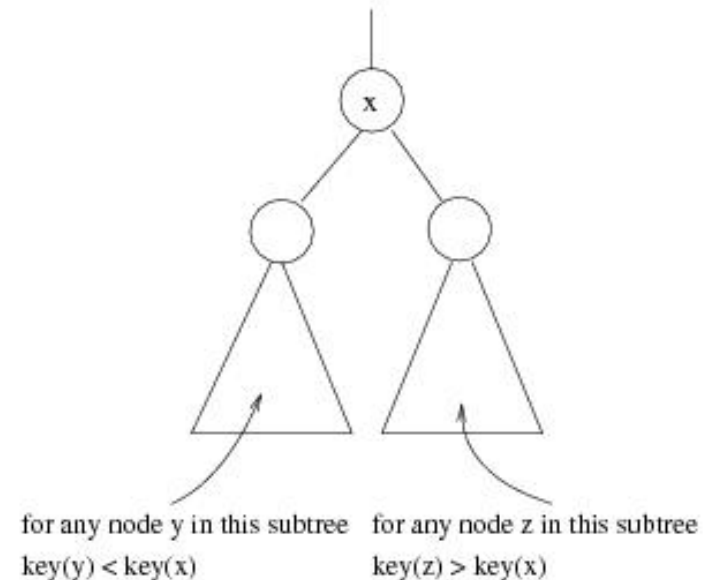


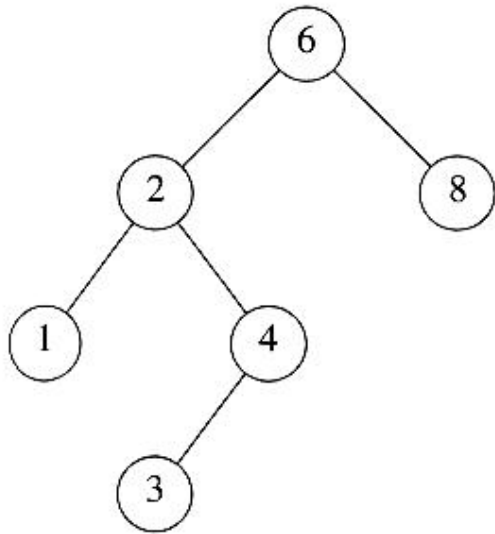
Figure 4.4 First child/next sibling representation of the tree shown in Figure 4.2

Binary Search Trees (BST)

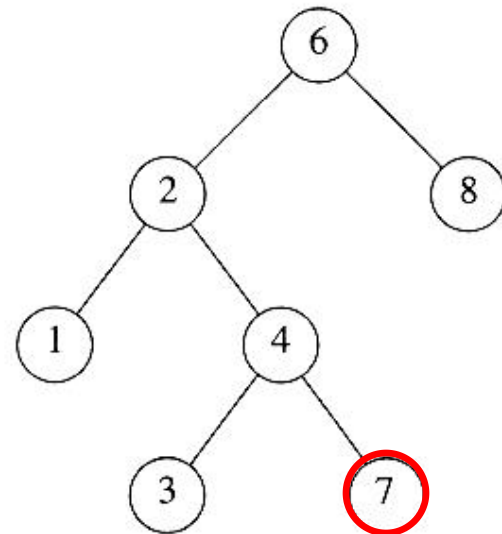
- A data structure for efficient searching, insertion and deletion
- Binary search tree property
 - ◆ For every node X
 - ◆ All the keys in its left subtree are smaller than the key value in X
 - ◆ All the keys in its right subtree are larger than the key value in X
- Here the key of node is the value in this node.



Binary Search Trees



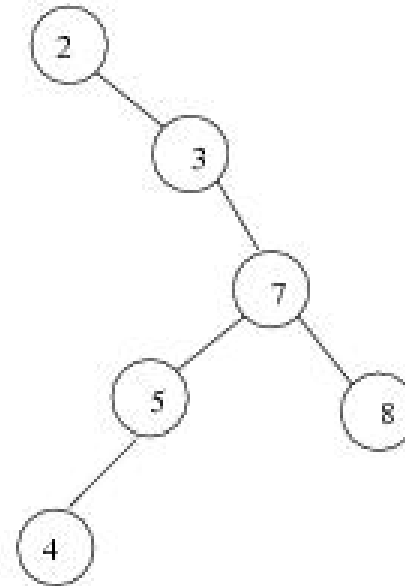
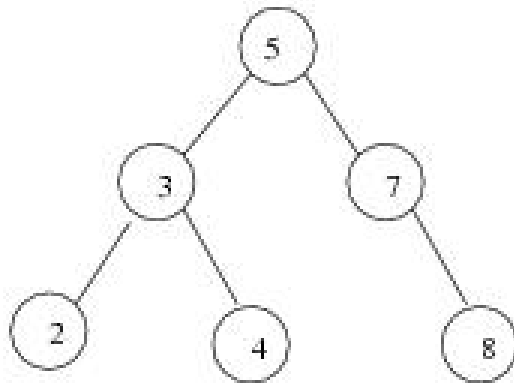
A binary search tree



Not a binary search tree

Binary Search Trees

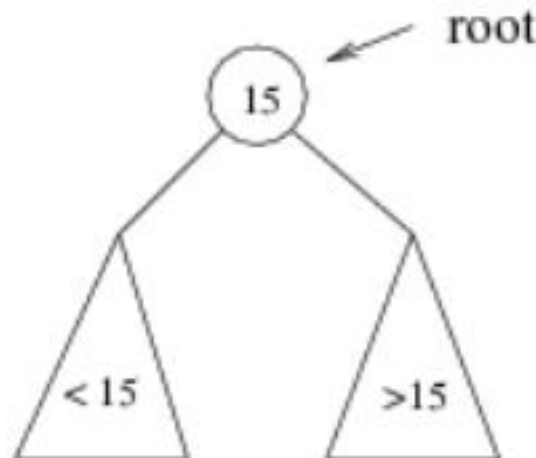
The same set of keys may have different BSTs



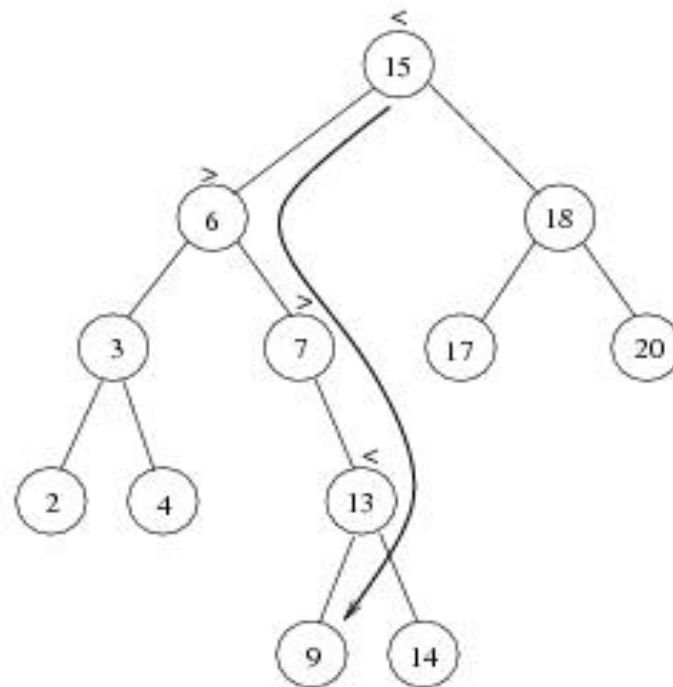
- Average depth of a node is $O(\log N)$
- Maximum depth of a node is $O(N)$

Searching BST

- If we are searching for 15, then we are done.
- If we are searching for a key < 15 , then we should search in the **left subtree**.
- If we are searching for a key > 15 , then we should search in the **right subtree**.



Example: Search for 9 ...



Search for 9:

1. compare 9:15(the root), go to left subtree;
2. compare 9:6, go to right subtree;
3. compare 9:7, go to right subtree;
4. compare 9:13, go to left subtree;
5. compare 9:9, found it!

Searching (Find)

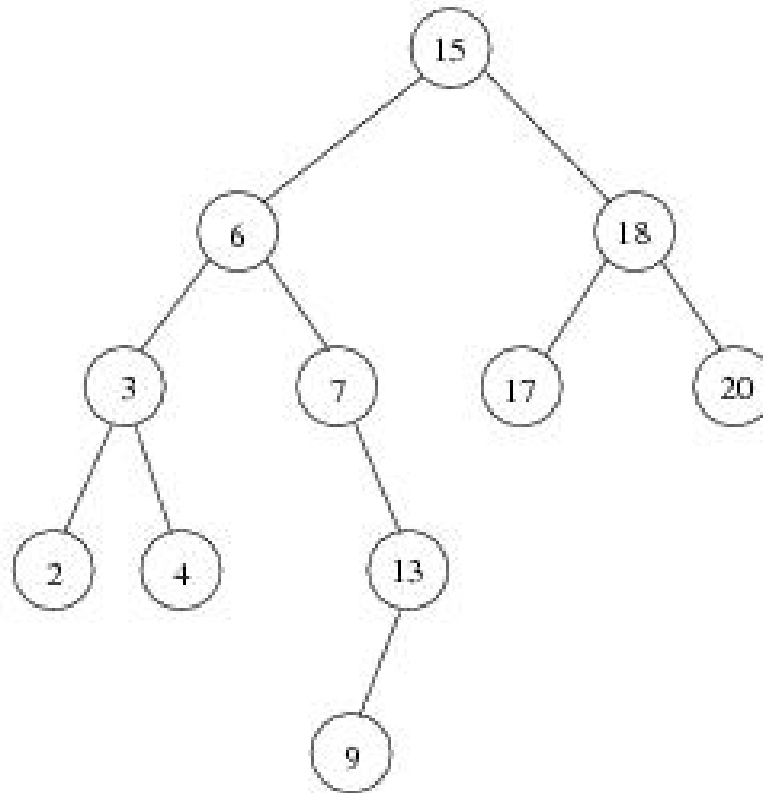
- Find X: return a pointer to the node that has key X, or NULL if there is no such node

```
BinaryNode * BinarySearchTree::Find(const float &x, BinaryNode *t) const
{
    if (t == NULL)
        return NULL;
    else if (x < t->element)
        return Find(x, t->left);
    else if (t->element < x)
        return Find(x, t->right);
    else
        return t;    // match
}
```

- Time complexity: $O(\text{height of the tree})$

Inorder Traversal of BST

- Inorder traversal of BST prints out all the keys in sorted order



Inorder: 2, 3, 4, 6, 7, 9, 13, 15, 17, 18, 20

findMin/ findMax

- **Goal:** return the node containing the **smallest (largest)** key in the tree
- **Algorithm:** Start at the root and **go left (right)** as long as there is a left (right) child. The stopping point is the smallest (largest) element

```
BinaryNode * BinarySearchTree::FindMin(BinaryNode *t) const
{
    if (t == NULL)
        return NULL;
    if (t->left == NULL)
        return t;
    return FindMin(t->left);
}
```

Binary Tree Height

- Given a binary tree, find its maximum depth.
- The maximum depth is the number of nodes along the longest path from the root node down to the farthest leaf node.
- **Note:** A leaf is a node with no children.

- **Example:**

Given binary tree [3,9,20,null,null,15,7],



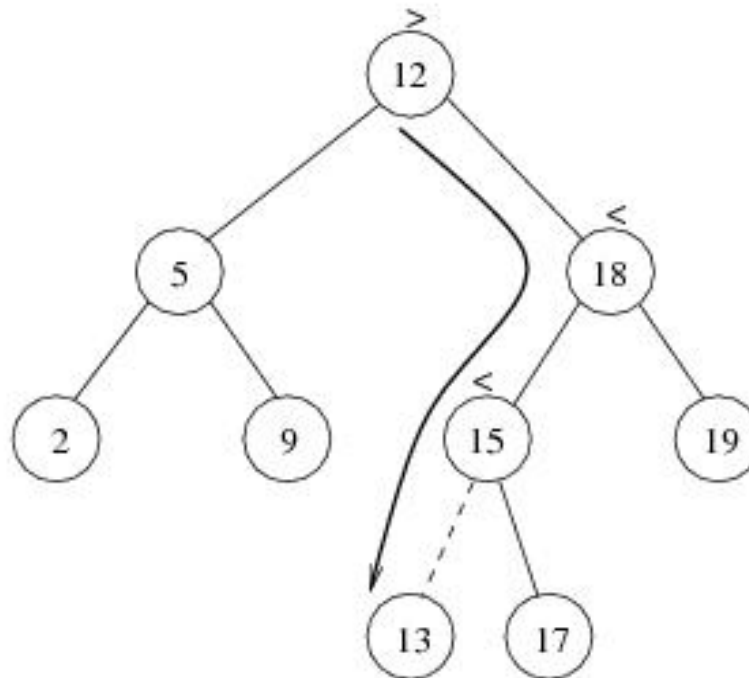
return its depth = 4

Binary Tree Height

```
int maxDepth(BinaryNode* root) {  
    if(root == NULL) return 0;  
    return max(maxDepth(root->left), maxDepth(root->right)) + 1;  
}
```

Insertion

- Proceed down the tree as you would with a find
- If X is found, do nothing (or update something)
- Otherwise, insert X at the last spot on the path traversed

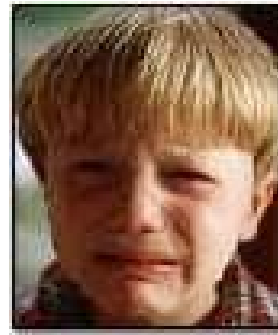


Insertion

```
node* insert(int x, node* t) {  
    if(t == NULL) {  
        t = new node;  
        t->data = x;  
        t->left = t->right = NULL;  
    }  
    else if(x < t->data)  
        t->left = insert(x, t->left);  
    else if(x > t->data)  
        t->right = insert(x, t->right);  
    return t;  
}
```

Deletion

- When we delete a node, we need to consider how we **take care of the children of the deleted node**.
 - ◆ This has to be done such that the **property of the search tree is maintained**.



Deletion under Different Cases

- Case 1: the node is a leaf
 - ◆ Delete it immediately
- Case 2: the node has one child
 - ◆ Adjust a pointer from the parent to bypass that node

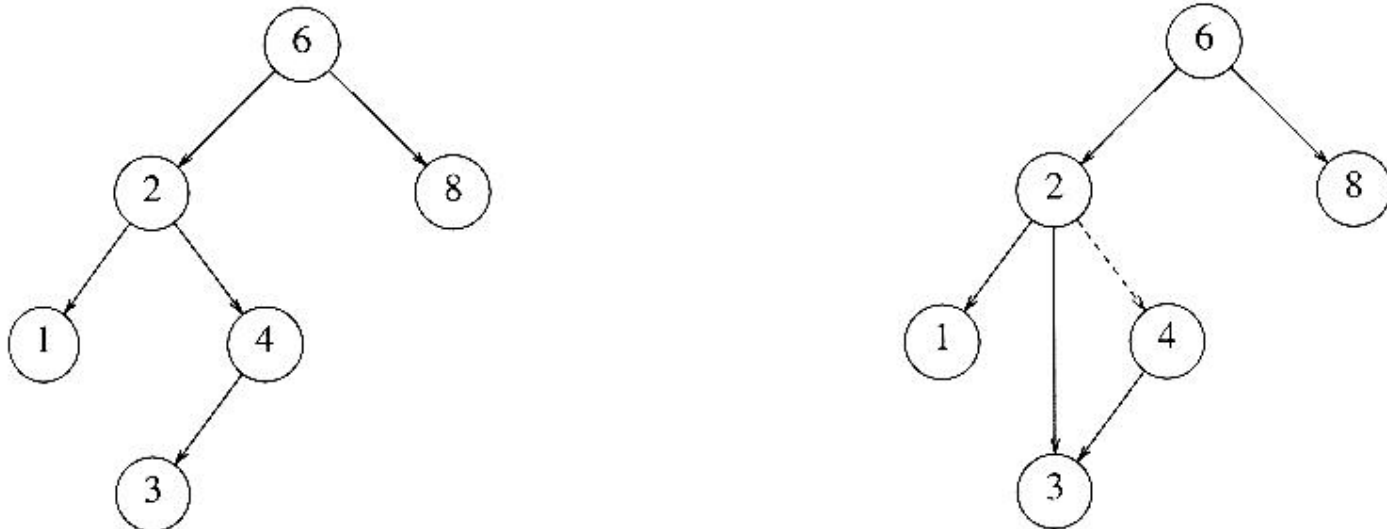


Figure 4.24 Deletion of a node (4) with one child, before and after

Deletion Case 3

■ Case 3: the node has 2 children

- ◆ Replace the key of that node with the **minimum element** at the **right subtree** (or Replace the key of that node with the **maximum element** at the **left subtree**)
- ◆ Delete that minimum element
 - Has either no child or only right child because if it has a left child, that left child would be smaller and would have been chosen. So invoke case 1 or 2.

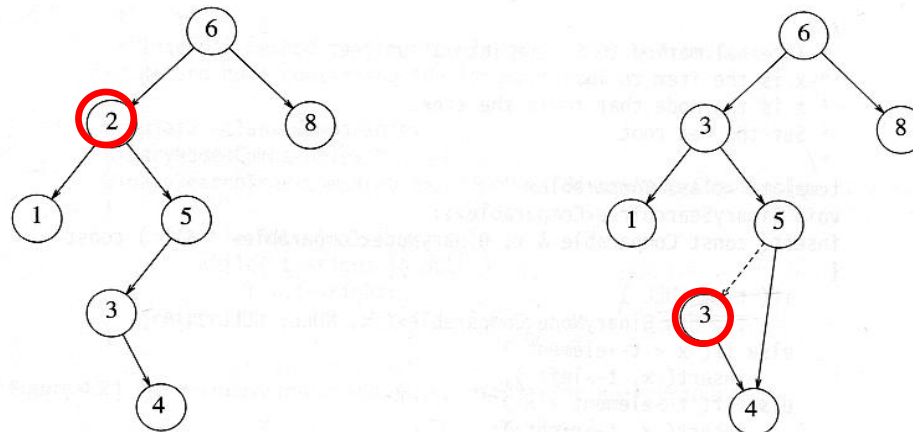


Figure 4.25 Deletion of a node (2) with two children, before and after

- Time complexity = $O(\text{height of the tree})$