## 2022-23 First Semester MATH1063 Linear Algebra II (1003)

Assignment 3 Suggested Solutions

1. Transition matrix V corresponding to a change of basis from  $\{v_1, v_2, v_3\}$  to  $\{e_1, e_2, e_3\}$ 

$$V = \begin{pmatrix} \mathbf{v_1} & \mathbf{v_2} & \mathbf{v_3} \end{pmatrix} = \begin{pmatrix} 1 & 1 & 0 \\ -1 & 2 & -2 \\ 1 & 0 & 1 \end{pmatrix}$$

then  $V^{-1}$  is a transition matrix corresponding to a change of basis from  $\{\mathbf{e_1}, \mathbf{e_2}, \mathbf{e_3}\}$  to  $\{\mathbf{v_1}, \mathbf{v_2}, \mathbf{v_3}\}$ 

$$V^{-1} = \begin{pmatrix} \mathbf{v_1} & \mathbf{v_2} & \mathbf{v_3} \end{pmatrix}^{-1} = \begin{pmatrix} 2 & -1 & -2 \\ -1 & 1 & 2 \\ -2 & 1 & 3 \end{pmatrix}$$

thus, the matrix B representing L with respect to  $\{v_1, v_2, v_3\}$  is

$$B = V^{-1}AV = \begin{pmatrix} 2 & -1 & -2 \\ -1 & 1 & 2 \\ -2 & 1 & 3 \end{pmatrix} \begin{pmatrix} 3 & -1 & -2 \\ 2 & 0 & -2 \\ 2 & -1 & 1 \end{pmatrix} \begin{pmatrix} 1 & 1 & 0 \\ -1 & 2 & -2 \\ 1 & 0 & 1 \end{pmatrix} = \begin{pmatrix} -4 & 0 & -4 \\ 6 & 1 & 4 \\ 8 & 0 & 7 \end{pmatrix}.$$

2. (a)  $||k\mathbf{v}||^2 = (k\mathbf{v})^T(k\mathbf{v}) = k^2(\mathbf{v}^T\mathbf{v}) = k^2||\mathbf{v}||^2$ . Take square roots of both sides; note that  $\sqrt{k^2} = |k|$ . Thus  $||k\mathbf{v}|| = |k|||\mathbf{v}||$ .

(b) 
$$\|\mathbf{u}\| = \underbrace{\left\|\frac{1}{\|\mathbf{v}\|}\mathbf{v}\right\|}_{\text{Based on (a)}} = 1$$
, as claimed.

3.

$$\mathbf{z}^T \mathbf{p} = \mathbf{x}^T \mathbf{p} - \mathbf{p}^T \mathbf{p} = \frac{(\mathbf{x}^T \mathbf{y})^2}{\mathbf{y}^T \mathbf{y}} - \left(\frac{\mathbf{x}^T \mathbf{y}}{\mathbf{y}^T \mathbf{y}}\right)^2 \mathbf{y}^T \mathbf{y} = 0.$$

- 4. No. For example, let  $\mathbf{x}_1 = \mathbf{e}_1$ ,  $\mathbf{x}_2 = \mathbf{e}_2$ ,  $\mathbf{x}_3 = 2\mathbf{e}_1$ , then  $\mathbf{x}_1 \perp \mathbf{x}_2$ ,  $\mathbf{x}_2 \perp \mathbf{x}_3$ , but  $\mathbf{x}_1$  is not orthogonal to  $\mathbf{x}_3$ .
- 5. By the plane equation, we know that a normal vector to the plane is  $\mathbf{n} = (6, 2, 3)^T$  and the point Q(1, 3, -2) lies in the plane. Then the distance from the point P(2, 1, -2) to the plane is the absolute value of the scalar projection of  $\overrightarrow{PQ} = (-1, 2, 0)^T$  onto  $\mathbf{n}$ .

$$d = \left| \frac{\overrightarrow{PQ} \cdot \mathbf{n}}{\|\mathbf{n}\|} \right| = \left| \frac{-2}{\sqrt{49}} \right| = \frac{2}{7}.$$

1

6. Let  $\mathbf{v} = (1,2)^T$ . To find the distance, we need to find the scalar projection of  $\mathbf{v}$  onto a normal vector to the line 4x - 3y = 0, say  $\mathbf{n} = (-4,3)^T$ :

$$\alpha = \frac{\mathbf{v}^T \mathbf{n}}{\|\mathbf{n}\|} = \frac{(1,2)(-4,3)^T}{5} = 0.4$$

7. Pick two points (0,2) and (2,6) on the line y=2x+2.

Let  $\mathbf{v} = \begin{pmatrix} 5 \\ 0 \end{pmatrix}$  be the vector from (0,2) to the point (5,2), and  $\mathbf{w} = \begin{pmatrix} 2 \\ 4 \end{pmatrix}$  be a vector along the line y = 2x + 2, then the vector projection of  $\mathbf{v}$  onto  $\mathbf{w}$  is

$$\vec{p} = \frac{\mathbf{v} \cdot \mathbf{w}}{\mathbf{w}^T \mathbf{w}} \mathbf{w} = \frac{(5,0)(2,4)^T}{(2,4)(2,4)^T} \begin{pmatrix} 2\\4 \end{pmatrix} = \begin{pmatrix} 1\\2 \end{pmatrix}.$$

Thus, the closest point to (5,2) on the line y=2x+2 should be the point  $(0,2)+\vec{p}=(1,4)$ .

8.  $Y^{\perp}$  is not empty since  $\mathbf{0} \in Y^{\perp}$ . If  $\mathbf{x} \in Y^{\perp}$  and  $\alpha \in \mathbb{R}$ , then for all  $\mathbf{y} \in Y$ ,

$$(\alpha \mathbf{x})^T \mathbf{y} = \alpha (\mathbf{x})^T \mathbf{y} = \alpha \cdot 0 = 0.$$

Therefore,  $\alpha \mathbf{x} \in Y^{\perp}$ . If  $\mathbf{x}_1$  and  $\mathbf{x}_2$  are in  $Y^{\perp}$ , then

$$(\mathbf{x}_1 + \mathbf{x}_2)^T \mathbf{y} = \mathbf{x}_1^T \mathbf{y} + \mathbf{x}_2^T \mathbf{y} = 0 + 0 = 0,$$

for each  $\mathbf{y} \in Y$ . Thus,  $\mathbf{x}_1 + \mathbf{x}_2 \in Y^{\perp}$ . Hence,  $Y^{\perp}$  is a subspace of  $\mathbb{R}^n$ .

9. (a)

$$Col(A) = span \{(1, 2)', (3, 4)'\}, \quad N(A) = span \{(2, -1, 1)'\}$$

$$Col(A^T) = span \{(1, 0, -2)', (0, 1, 1)'\}, \quad N(A^T) = span \{\mathbf{0}\}$$

Notice that  $Col(A^T) \oplus N(A) = \mathbb{R}^3$  and  $Col(A) \oplus N(A^T) = \mathbb{R}^2$ .

(b)

$$Col(A) = span \{(1, 2, 1)', (3, 4, 4)'\}, \quad N(A) = span \{(2, -1, 1)'\}$$

$$\mathrm{Col}(A^T) = \mathrm{span} \left\{ (1,0,-2)', (0,1,1)' \right\}, \quad \mathrm{N}(A^T) = \mathrm{span} \left\{ (-4,1,2)' \right\}$$

Notice that  $\operatorname{Col}(A^T) \oplus \operatorname{N}(A) = \mathbb{R}^3$  and  $\operatorname{Col}(A) \oplus \operatorname{N}(A^T) = \mathbb{R}^3$ .

10. Since V is the solution space of the linear system  $A\mathbf{x} = \mathbf{0}$ 

$$\begin{cases} x_1 + x_2 + x_3 + x_4 = 0 \\ x_1 + 2x_2 + 5x_3 + 4x_4 = 0 \end{cases} \rightarrow \begin{pmatrix} 1 & 1 & 1 & 1 \\ 1 & 2 & 5 & 4 \end{pmatrix} \mathbf{x} = \mathbf{0} \quad \text{i.e. } V = \mathcal{N}(A).$$

Then  $V^{\perp} = [N(A)]^{\perp} = \text{Col}(A^T) = \text{Row}(A)$ . Since (1, 1, 1, 1) and (1, 2, 5, 4) are linearly independent, they form a basis for Row(A).