

6. Probabilities: Markov chains and statistical model checking

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<https://fm-dcc.github.io/sv2425>



CISTER - Research Centre in
Real-Time & Embedded
Computing Systems

Where we are

- Introduction to model-checking
- CCS: a simple language for concurrency
 - Syntax
 - Semantics
 - Equivalence
 - mCRL2: modelling
- Dynamic logic
 - Syntax
 - Semantics
 - Relation with equivalence
 - mCRL2: verification
- Timed Automata
 - Syntax
 - Semantics (composition, Zeno)
 - Equivalence
 - UPPAAL: modelling
- Temporal logics (LTL/CTL)
 - Syntax
 - Semantics
 - UPPAAL: verification
- Probabilistic and stochastic systems
 - Going probabilistic
 - UPPAAL: monte-carlo

Going probabilistic

Systems can get very complex

- E.g., 5 components, 3 possible traces each
- No communication (pure interleaving)
- 5 traces (or 7 components) – becomes X

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- E.g., 5 components, 3 possible traces each
- No communication (pure interleaving)
- 5 traces (or 7 components) – becomes X
- Verifying deadlock freedom (and others) requires traversing all states
- **Approximation:**
 - traverse only part of the states
 - give more **priority** to some actions
 - return (statistically) likelihood of a given property

- $\alpha : S \rightarrow N \times S$ Moore machine
- $\alpha : S \rightarrow \text{Bool} \times S^N$ deterministic automata
- $\alpha : S \rightarrow \text{Bool} \times P(S)^N$ non-deterministic automata (reactive)
- $\alpha : S \rightarrow P(N \times S)$ non deterministic LTS (generative)
- $\alpha : S \rightarrow (S + 1)^N$ partial deterministic LTS
- $\alpha : S \rightarrow P(S)$ unlabelled TS
- $\alpha : S \rightarrow D(S)$ Markov chain

Markov chains

$$\alpha : S \rightarrow D(S)$$

where $D(S)$ is the set of all **discrete probability distributions** on set S

A Markov chain goes from a state s to a state s' with probability p if

$$\alpha(s) = \mu \quad \text{with} \quad \mu(s') = p > 0$$

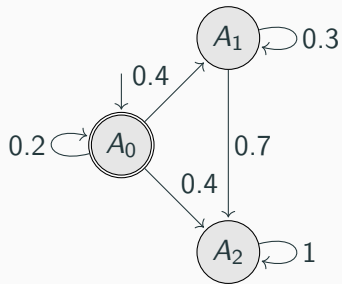
Recall

$\mu : S \rightarrow [0, 1]$ is a **discrete probability distribution** if

- $\{s \in S \mid \mu(s) > 0\}$, is finite (called the **support** of μ), and
- $\sum_{s \in S} \mu(s) = 1$

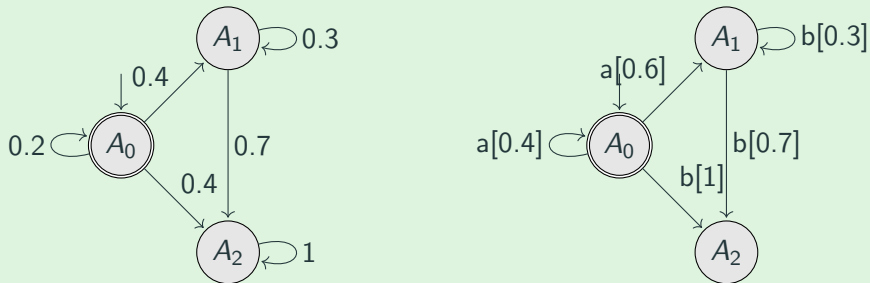
Examples

- **Dirac distribution:** $\mu_s^1 = \{s \rightarrow 1\}$
- **Product distribution:** $(\mu_1 \times \mu_2)\langle s, t \rangle = \mu_1(s) \times \mu_2(t)$



$$\alpha : S \rightarrow (D(S) + 1)^N$$

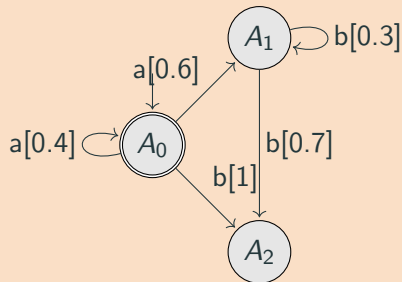
Ex. 6.1: Formalise the systems below as functions



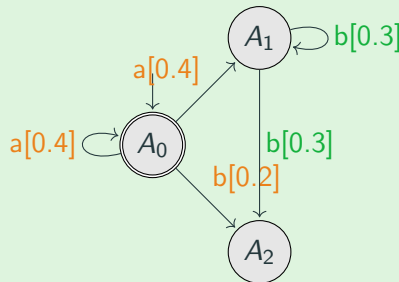
Notions of bisimulation arise naturally.

$$\alpha : S \rightarrow D((S \times N) + 1)$$

Before (reactive)

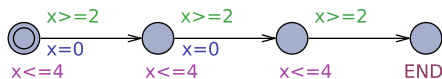


Ex. 6.2: Now (generative) – formalise it

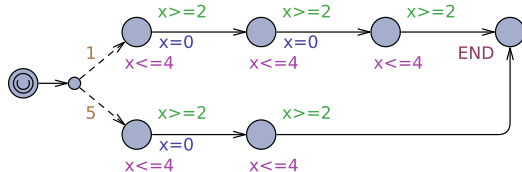


Probabilities in Uppaal

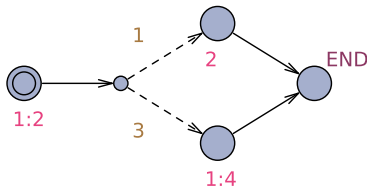
A1



A2



A3



$$\langle L, L_0, \text{Act}, C, \text{Tr}, \text{Inv} \rangle$$

where

- L is a set of **locations**, and $L_0 \subseteq L$ the set of **initial** locations
- Act is a set of **actions** and C a set of **clocks**
- $\text{Tr} \subseteq L \times \mathcal{C}(C) \times \text{Act} \times \mathcal{P}(C) \times \mathbb{N} \times L$ is the **transition relation**

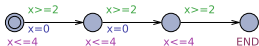
$$\ell_1 \xrightarrow{g, a, U, w} \ell_2$$

denotes a transition from location ℓ_1 to ℓ_2 , **labelled** by a , enabled if **guard** g is valid, which, when performed, **resets** the set U of **clocks**, **with a probability given by the weight** w

- $\text{Inv} : L \longrightarrow \mathcal{C}(C) \cup \text{rate}$ is the assignment of **invariants** or **rates** (of an **exponential distribution**) to locations

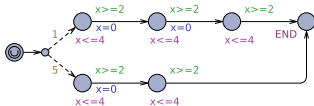
where $\mathcal{C}(C)$ denotes the set of clock constraints over a set C of clock variables

A1

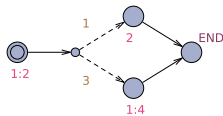


- Probability of $\langle A1_0, 0 \rangle \xrightarrow{0.5} \langle A1_0, 0.5 \rangle$?
- Probability of $\langle A2_0, 0 \rangle \xrightarrow{0.5} \langle A2_0, 0.5 \rangle$?

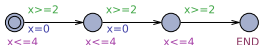
A2



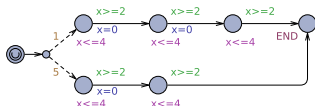
A3



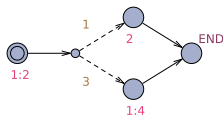
A1



A2

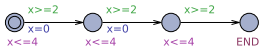


A3

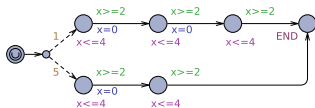


- Probability of $\langle A1_0, 0 \rangle \xrightarrow{0.5} \langle A1_0, 0.5 \rangle$?
- Probability of $\langle A2_0, 0 \rangle \xrightarrow{0.5} \langle A2_0, 0.5 \rangle$?
- Probability of $\langle A3_0, 0 \rangle \xrightarrow{0.5} \langle A3_0, 0.5 \rangle$?

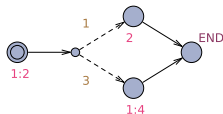
A1



A2

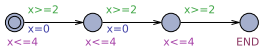


A3

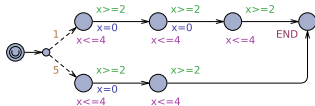


- Probability of $\langle A1_0, 0 \rangle \xrightarrow{0.5} \langle A1_0, 0.5 \rangle$?
- Probability of $\langle A2_0, 0 \rangle \xrightarrow{0.5} \langle A2_0, 0.5 \rangle$?
- Probability of $\langle A3_0, 0 \rangle \xrightarrow{0.5} \langle A3_0, 0.5 \rangle$?
- Probability of reaching $A1_1$?
- Probability of reaching $A2_1$?

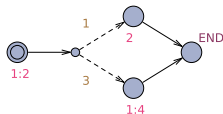
A1



A2



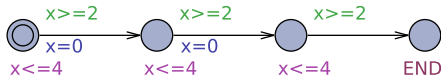
A3



- Probability of $\langle A1_0, 0 \rangle \xrightarrow{0.5} \langle A1_0, 0.5 \rangle$?
- Probability of $\langle A2_0, 0 \rangle \xrightarrow{0.5} \langle A2_0, 0.5 \rangle$?
- Probability of $\langle A3_0, 0 \rangle \xrightarrow{0.5} \langle A3_0, 0.5 \rangle$?
- Probability of reaching $A1_1$?
- Probability of reaching $A2_1$?
- Probability of reaching $A3_{END}$ in less than 4.3?
= ...

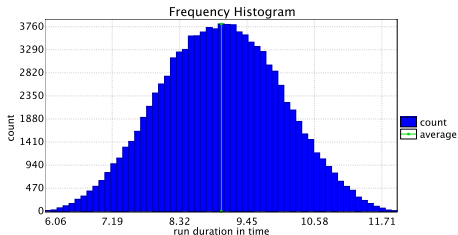
A1: When does it end?

A1



- Run 102000 times
- Histogram: how many times it took [9..9.1] seconds?
- ...

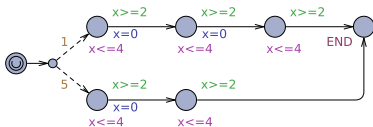
A1's histogram



Parameters: $\alpha=0.05$, $\epsilon=0.05$, bucket width=0.10002, bucket count=59
Runs: 102000 in total, 102000 (100%) displayed, 0 (0%) remaining
Span of displayed sample: [6.06618, 11.9675]
Mean estimate of displayed sample: 9.00732 ± 0.00614869 (95% CI)

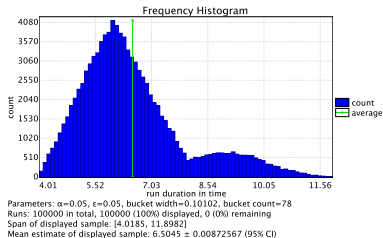
A2: When does it end?

A2

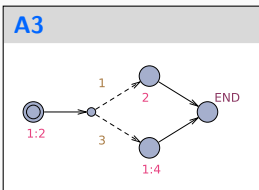


- Run 100000 times
- Histogram: how many times it took [9..9.1] seconds?
- ...

A2's histogram

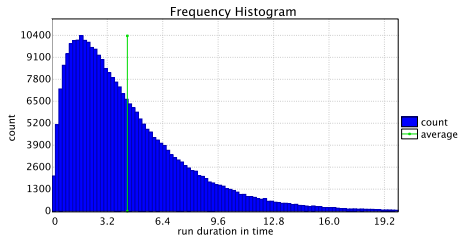


A3: When does it end?



- Run 300000 times
- Histogram: how many times it took [9..9.1] seconds?
- ...

A3's histogram

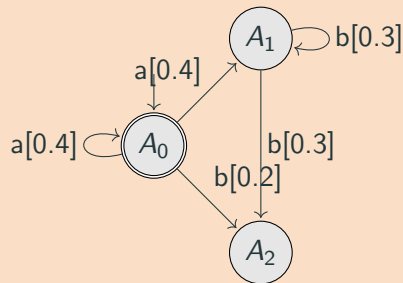


Parameters: $\alpha=0.05$, $\epsilon=0.05$, bucket width=0.19991, bucket count=100
Runs: 300000 in total, 299181 (99.727%) displayed, 819 (0.273%) remaining
Span of displayed sample: [0.0045298, 19.9958]
Mean estimate of displayed sample: 4.31514 ± 0.0118734 (95% CI)

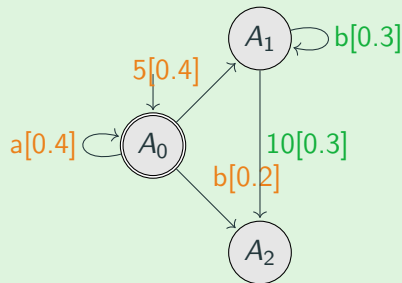
$$\alpha : S \rightarrow D((S \times N) + 1)$$

$$\alpha : S \rightarrow D(S \times (Act + R + 1))$$

Before (PTS)



Ex. 6.3: Now (Timed PTS) – formalise it



Probabilistic queries in Uppaal

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