

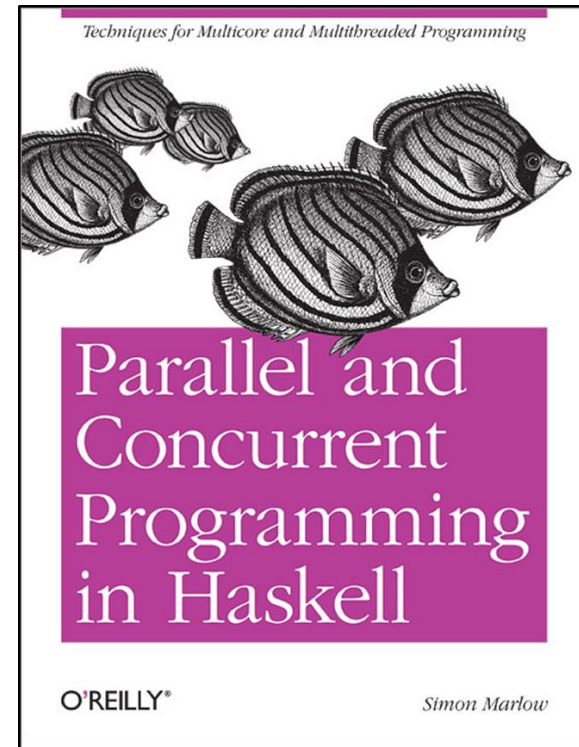
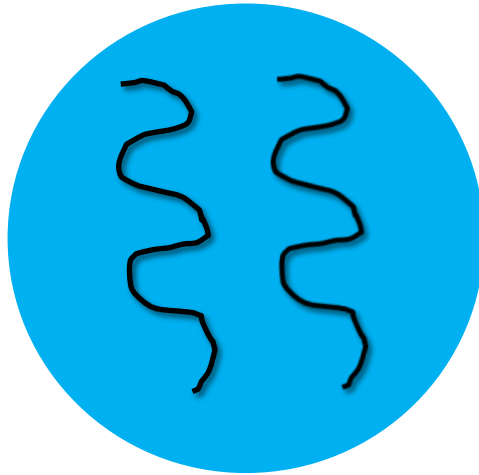
# IMPLEMENTAREA CONCURENTEI IN LIMBAJE DE PROGRAMARE

Concurenta

Threaduri

Memorie Partajata

Ioana Leustean

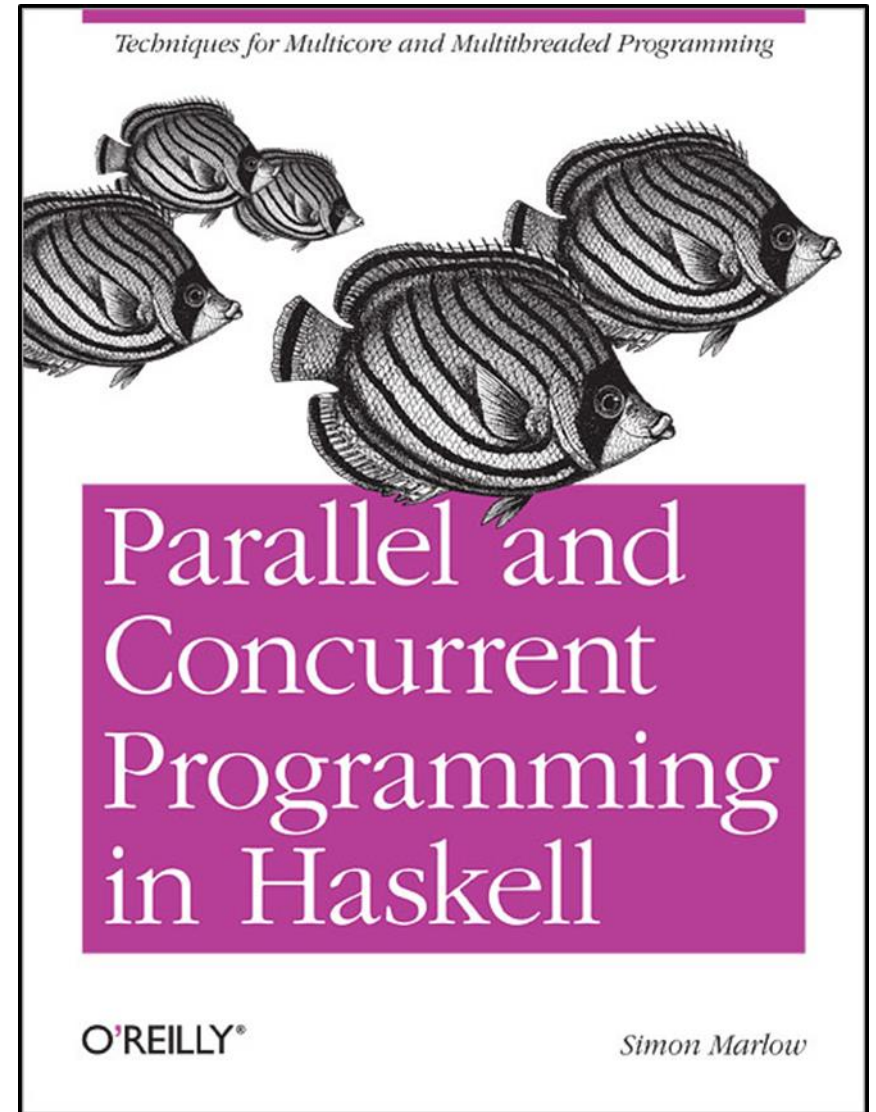


[Part II. Concurrent Haskell](#)  
Cap.7 & 8

"Haskell does not take a stance on which concurrent programming model is best: **actors, shared memory, and transactions** are all supported, for example."

"Haskell provides all of these concurrent programming models and more - but this flexibility is a double-edged sword. The advantage is that you can choose from a wide range of tools and pick the one best suited to the task at hand, but the disadvantage is that it can be hard to decide which tool is best for the job."

[S. Marlow](#)



## ➤ Thread-urile in Haskell:

Thread-urile au efecte si interactioneaza cu lumea exterioara.

Programarea concurenta in Haskell are loc in [monada IO](#).

La rulare, efectele thread-urilor sunt intercalate nedeterminist.

Thread-urile in Haskell sunt create si gestionate intern, fara a folosi facilitati specifice sistemului de operare.

Implementarea threadurilor asigura verificarea anumitor conditii de corectitudine ([fairness](#))



## ➤ Crearea thread-urilor

`forkIO :: IO () -> IO ThreadId`

```
Prelude> :m + Control.Concurrent
Prelude Control.Concurrent> :t forkIO
forkIO :: IO () -> IO ThreadId
```

```
import Control.Concurrent
import Control.Monad
```

```
main = do
    forkIO (replicateM_ 100 (putChar 'A')) -- child thread
    replicateM_ 100 (putChar 'B') -- main thread
    putStrLn " "
```

[replicateM](#)

```
Prelude> :m + Control.Monad
Prelude Control.Monad> :t replicateM_
replicateM_ :: Monad m => Int -> m a -> m ()
Prelude Control.Monad> replicateM_ 5 (putStrLn "A")
A
A
A
A
A
```



```
forkIO :: IO () -> IO ThreadId
```

```
import Control.Concurrent
import Control.Monad

main = do
    forkIO (replicateM_ 100 (putChar 'A')) -- child thread
    replicateM_ 100 (putChar 'B') -- main thread
    putStrLn " "
```

[illegible]

La rulari diferite se pot obtine rezultate diferite!



```
forkIO :: IO () -> IO ThreadId
```

```
import Control.Concurrent
import Control.Monad
```

```
main = do
    forkIO (replicateM_ 100 (putChar 'A')) -- child thread
    replicateM_ 100 (putChar 'B') -- main thread
    putStrLn " "
```

Daca fisierul se numeste *thread.hs* atunci el poate fi compilat si executat astfel

```
>ghc thread.hs -threaded
> ./thread
```

[illegible]

La rulari diferite se pot obtine rezultate diferite!



`forkIO :: IO () -> IO ThreadId`

```
import Control.Concurrent
import Control.Monad
```

```
main = do
    forkIO (replicateM_ 100 (myThreadId >=> print)) -- child thread
    replicateM_ 100 (myThreadId >=> print) -- main thread
    putStrLn " "
```

`myThreadId :: IO ThreadId`

`print x = putStrLn (show x)`

```
PS C:\Users\igleu\Documents\DIR\ICLP22\Curs-2022\Haskell22\pgh\haskell2022> ./threadID
ThreadId 3
ThreadId 4
ThreadId 3
ThreadId 4
ThreadId 3
ThreadId 4
ThreadId 3
ThreadId 4
ThreadId 3
ThreadId 4
ThreadId 3
ThreadId 4
```



"The computation passed to `forkIO` is executed in a new thread that runs concurrently with the other threads in the system. If the thread has effects, those effects will be interleaved in an indeterminate fashion with the effects from other threads."

*S. Marlow, PCPH*

"`forkIO` is asymmetrical: when a process executes a `forkIO` it spawns a child process that executes concurrently with the continued execution of the parent"

*SL Peyton Jones, A Gordon, S Finne, Concurrent Haskell*

**"GHC's runtime system treats the program's original thread of control differently from other threads.**

**When this thread finishes executing, the runtime system considers the program as a whole to have completed.**

**If any other threads are executing at the time, they are terminated."**

*B. O'Sullivan, D. Stewart, J. Goerzen, Real World Haskell*





## ➤ Interleaving

```
import Control.Concurrent
import Control.Monad

myread1 = do
    putStrLn "thread1"
    s<- getLine
    putStrLn $ "citit 1: " ++ s

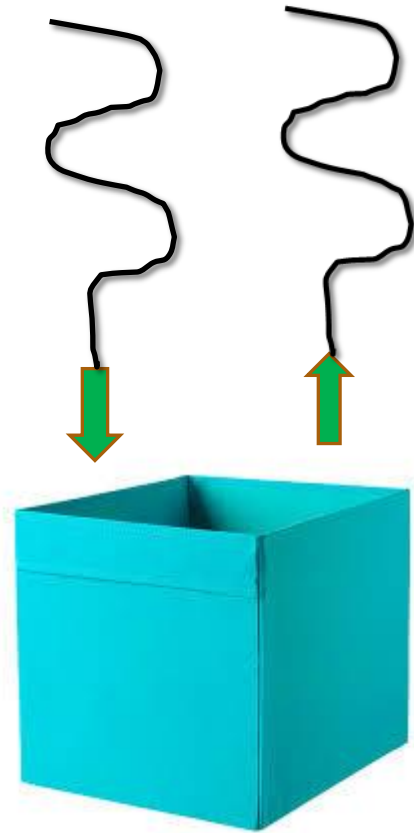
myread2 = do
    putStrLn "thread2"
    s<- getLine
    putStrLn $ "citit 2:" ++ s

main = do
    forkIO (replicateM_ 10 myread1)
    replicateM_ 10 myread2
```

```
*Main> main
thread1
thread2
e
citit 1: e
thread1
s
citit 2:s
thread2
r
citit 1: r
thread1
e
citit 2:e
thread2
f
citit 1: f
thread1
f
```



## ➤ Comunicarea thread-urilor



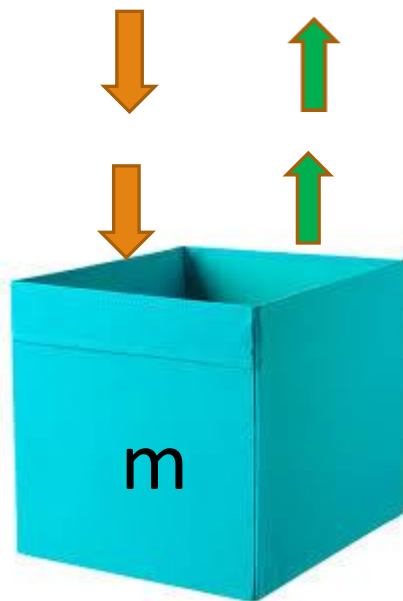
MVar

mutable variable

## ➤ Comunicarea folosind **MVar** se face in **monada IO**

### data **MVar** a

- o data de tipul **MVar** a reprezinta o locatie **mutabila** care poate fi goala sau
- poate contine o singura valoare de tip a
- thread-urile pot comunica prin intermediul datelor de tip **MVar**



**m :: MVar a**

poate fi vazuta ca:

- un semafor binar
- un monitor cu o variabila

## ➤ Comunicarea folosind **MVar** se face in **monada IO**

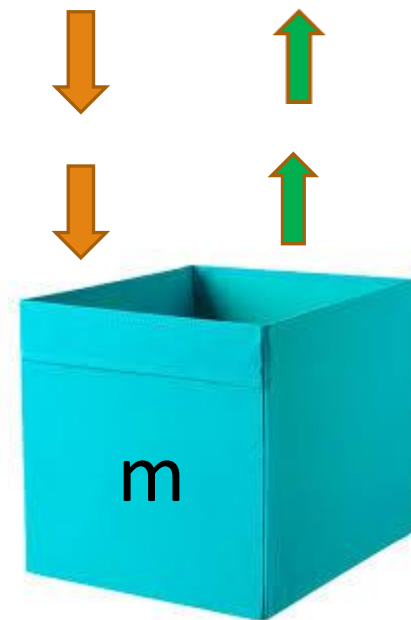
data MVar a

newEmptyMVar :: IO (MVar a) -- m <- newEmptyMVar  
-- m este o locatie goala

newMVar :: a -> IO (MVar a) -- m <- newMVar v  
-- m este o locatie care contine valoarea v

takeMVar :: MVar a -> IO a -- v <- takeMVar m  
-- intoarce in v valoarea din m si **goleste** m  
-- asteapta (blocheaza thread-ul) daca m este goala

putMVar :: MVar a -> a -> IO() -- putMVar m v  
-- pune in m valoarea v  
-- asteapta (blocheaza thread-ul) daca m este plina



- `takeMVar` este o operatie care blocheaza thread-urile
- `takeMVar` este *single-wakeup*:  
daca variabila MVar este goala, toate thread-urile care vor sa execute `takeMVar` sunt blocate; cand variabila devine plina, un singur thread este trezit si acesta va executa `takeMVar`
- daca mai multe thread-uri sunt blocate pe acelasi `MVar`, ele vor fi trezite in ordinea FIFO

<https://www.haskell.org/hoogle/?hoogle=MVar>



```
import Control.Concurrent
```

```
main = do
```

```
    m <- newEmptyMVar
```

```
    forkIO $ do
```

```
        putMVar m 'x'
```

```
        putMVar m 'y'
```

```
    x <- takeMVar m
```

```
    print x
```

```
    x <- takeMVar m
```

```
    print x
```

```
newEmptyMVar :: IO (MVar a)
```

```
putMVar :: MVar a -> a -> IO()
```

```
takeMVar :: MVar a -> IO a
```

```
*Main> main
```

```
'x'
```

```
'y'
```



```
import Control.Concurrent
```

```
main = do  
    m <- newEmptyMVar  
    takeMVar m
```

```
*Main> main
```

```
*** Exception: thread blocked indefinitely in an MVar operation
```



## ➤ takeMVar vs readMVar

### readMVar

Citeste atomic continutul unui `MVar`.

Daca variabile `MVar` este goala, thread-ul care apeleaza `readMVar` va astepta pana cand `MVar` primeste o valoare si va citi valoarea pusa de urmatoarea operatie `putMVar`.

`readMVar` este *multiple-wakeup*, deci toate threa-urile care asteapta sa citeasca din `MVar` vor fi trezite in acelasi timp.

Implementarea veche

```
readMVar :: MVar a -> IO a
readMVar m = do
    a <- takeMVar m
    putMVar m a
    return a
```

Implementarea actuala garanteaza ca `readMVar` este o operatie atomica.

<https://www.haskell.org/hoogle/?hoogle=MVar>

<https://www.haskell.org/hoogle/>





➤ MVar ca semafor binar

```
newLock = newMVar ()    -- MVar care contine ()  
acquireLock m = takeMVar m  
releaseLock m = putMVar m ()
```

act1 m = do

```
    acquireLock m  
    print "I have the lock"  
    releaseLock m
```

act2 m = do

```
    acquireLock m  
    print "Now I am have the lock"  
    releaseLock m
```

main = do

```
    m <- newLock  
    forkIO $ act1 m  
    forkIO $ act2 m  
    getLine
```



➤ MVar ca semafor binar

```
newLock = newMVar ()    -- MVar care contine ()  
acquireLock m = takeMVar m  
releaseLock m = putMVar m ()
```

```
main = do  
    m <- newLock  
    forkIO $ forever (act1 m)  
    forkIO $ forever (act2 m)  
    getLine
```

`forever` repeta o actiune monadica  
de un numar infinit de ori



➤ MVar ca semafor binar

```
newLock = newMVar ()    -- MVar care continue ()
acquireLock m = takeMVar m
releaseLock m = putMVar m ()
```

```
main = do
    m <- newLock
    forkIO $ forever (act1 m)
    forkIO $ forever (act2 m)
    getLine
```

[illegible]

- Sincronizare : doua thread-uri incrementeaza acelasi contor  
vrem sa citim valoarea contorului dupa ce ambele thread-uri au terminat

```
add m = replicateM_ 1000 $ do
    x <- takeMVar m
    putMVar m (x +1)

main = do
    m <- newMVar 0
    forkIO (add m )
    forkIO (add m )
    x <- takeMVar m
    print x
```



- Sincronizare : doua thread-uri incrementeaza acelasi contor  
vrem sa citim valoarea contorului dupa ce ambele thread-uri au terminat

```
add m = replicateM_ 1000 $ do
```

```
  x <- takeMVar m  
  putMVar m (x +1)
```

```
main = do
```

```
  m <- newMVar 0  
  forkIO (add m )  
  forkIO (add m )  
  x <- takeMVar m  
  print x
```

```
*Main> :l cont.hs  
[1 of 1] Compiling Main  
Ok, one module loaded.  
*Main> main  
0  
*Main> main  
0
```



- Sincronizare : doua thread-uri incrementeaza acelasi contor  
vrem sa citim valoarea contorului dupa ce ambele thread-uri au terminat

```
add m = replicateM_ 1000 $ do
```

```
    x <- takeMVar m  
    putMVar m (x +1)
```

```
main = do
```

```
    m <- newMVar 0  
    forkIO (add m )  
    forkIO (add m )  
    x <- takeMVar m  
    print x
```

```
*Main> :l cont.hs  
[1 of 1] Compiling Main  
Ok, one module loaded.  
*Main> main  
0  
*Main> main  
0
```

trebuie sa ne asiguram  
ca ambele thred-uri  
au terminat



## ➤ Sincronizare

```
main = do
```

```
  m <- newMVar 0
  ms1 <- newEmptyMVar
  ms2 <- newEmptyMVar
  forkIO (add m ms1)
  forkIO (add m ms2)
  takeMVar ms1
  takeMVar ms2
  x <- takeMVar m
  print x
```

```
add m ms1 = do
    replicateM_ 1000 $ do
        x <- takeMVar m
        putMVar mv (x + 1)
    putMVar ms1 "ok"
```

variabilele `ms1` si `ms2` actioneaza ca niste semafoare ;  
astfel ne asiguram ca ambele thread-uri au terminat



## ➤ Sincronizare

```
main = do
```

```
  m <- newMVar 0
  ms1 <- newEmptyMVar
  ms2 <- newEmptyMVar
  forkIO (add m ms1)
  forkIO (add m ms2)
  takeMVar ms1
  takeMVar ms2
  x <- takeMVar m
  print x
```

```
add m ms1 = do
    replicateM_ 1000 $ do
        x <- takeMVar m
        putMVar mv (x + 1)
    putMVar ms1 "ok"
```

```
*Main> main
2000
```

