

Incorporating Feature-Model Edits with Incremental d-DNNF Compilation

FOSD'25 | Chico Sundermann, Heiko Raab, Thomas Thüm | 28.03.2025

Motivation Product Lines



Your Selection

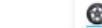
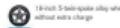
18-inch 5 twin-spoke alloy wheels
without extra charge



Motivation Product Lines



Your Selection



PC BUILDER

GET COMPATIBLE RECOMMENDATIONS

PICK YOUR IDEAL CORSAIR COMPONENTS



Motivation Product Lines



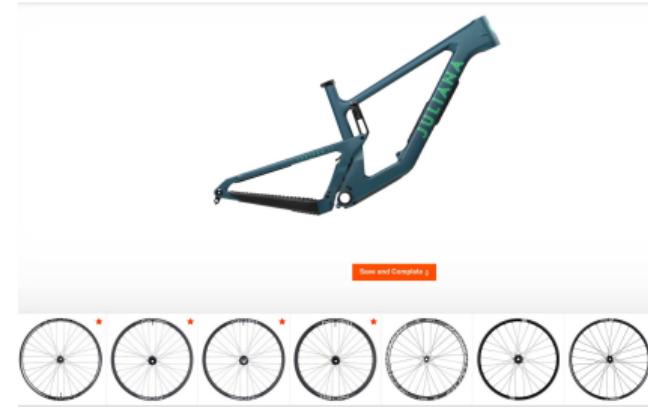
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PC BUILDER

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Show and Compatible ↗

Motivation Product Lines



Your Selection

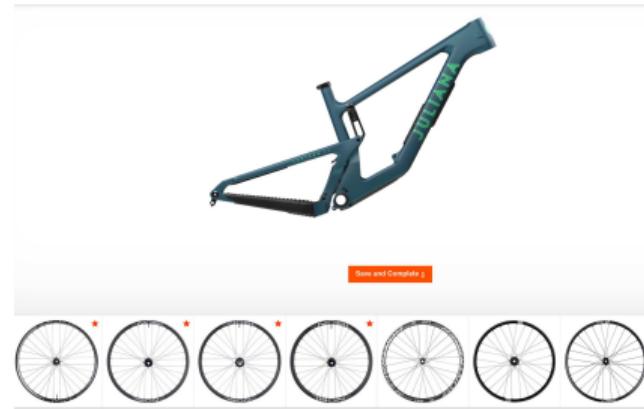


18-inch 5 twin-spoke alloy wheels
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PC BUILDER

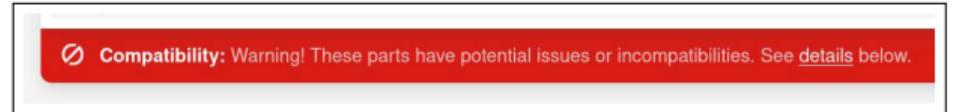
GET COMPATIBLE RECOMMENDATIONS
PICK YOUR IDEAL CORSAIR COMPONENTS



Motivation Feature Dependencies

GROUPSET 

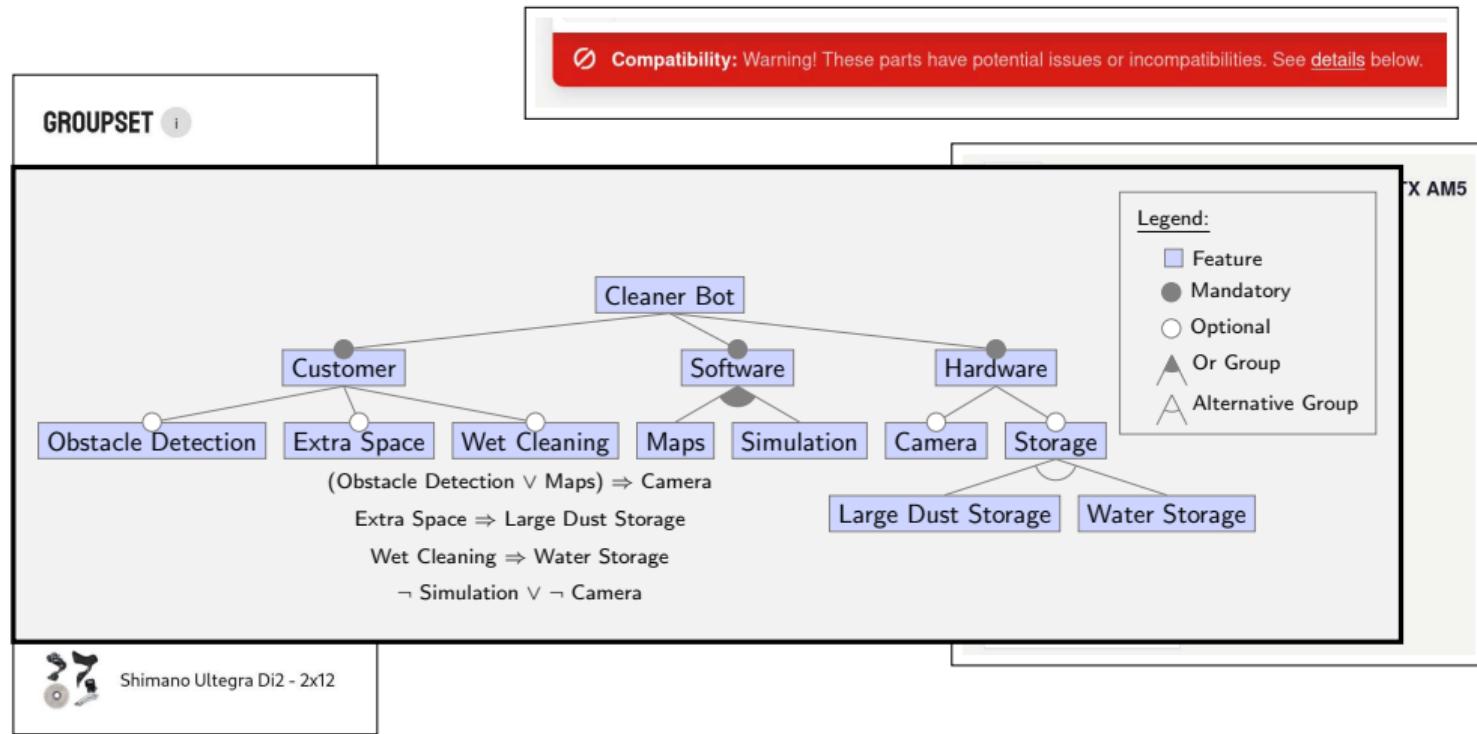
-  Shimano GRX600 2x12sp
-  Shimano 105 – 2x12
-  Sram Apex XPLR AXS 1x12
-  Shimano GRX800 2x12sp
-  SRAM Rival AXS XPLR – 1x12
-  Shimano 105 DI2 Disc 2x12
-  Shimano Ultegra Di2 - 2x12



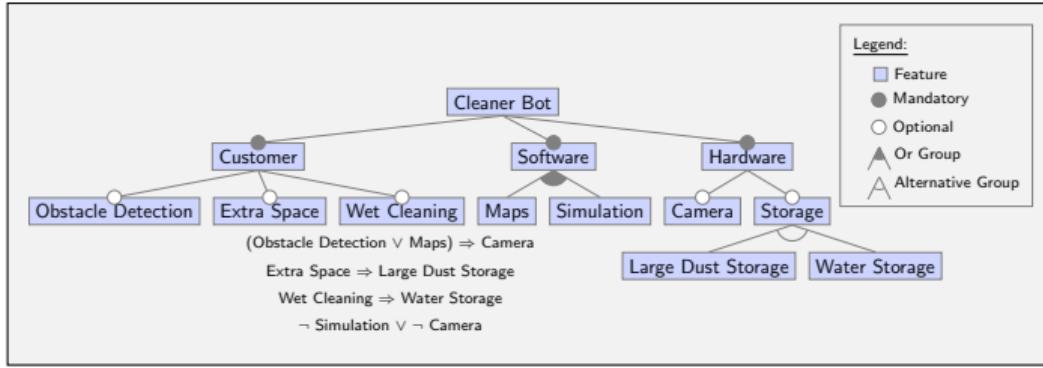
```
config SECURITY_INFINIBAND
    bool "Infiniband Security Hooks"
    depends on SECURITY && INFINIBAND
```



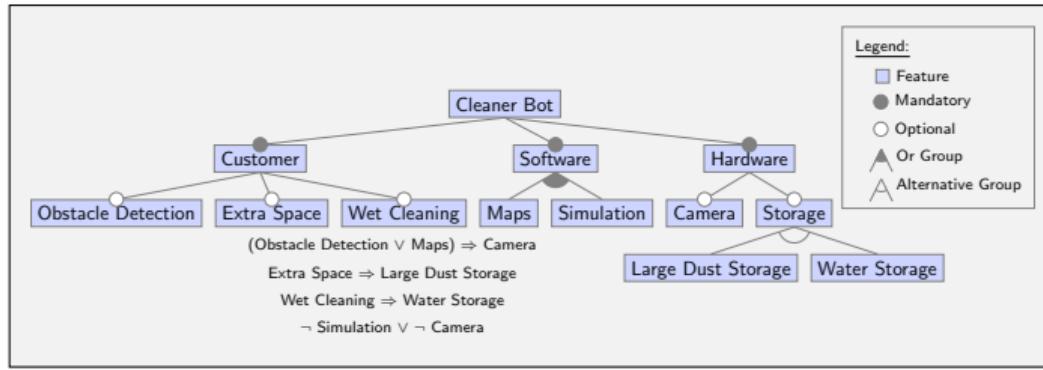
Motivation Feature Dependencies



Motivation Plenty Analyses

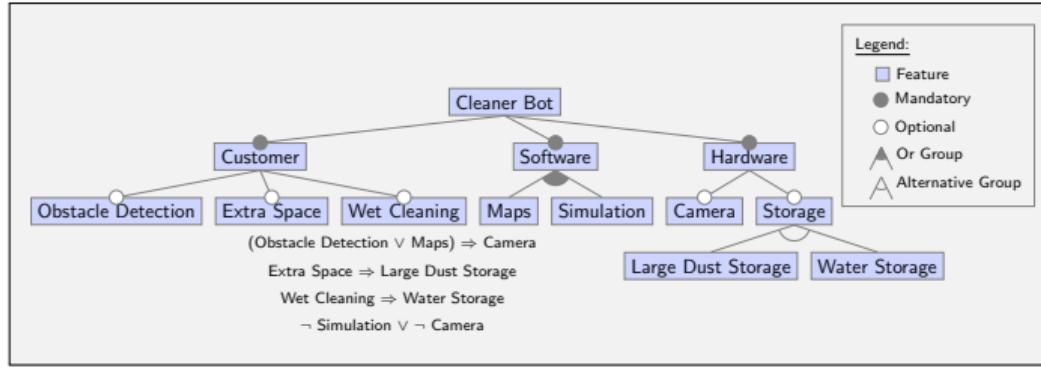


Motivation Plenty Analyses



Can we configure a robot?

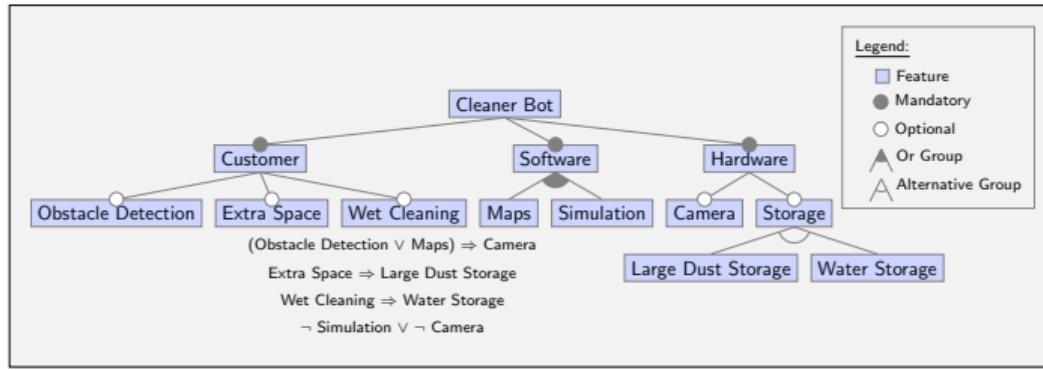
Motivation Plenty Analyses



Can we configure a robot?

Is there a robot with camera?

Motivation Plenty Analyses

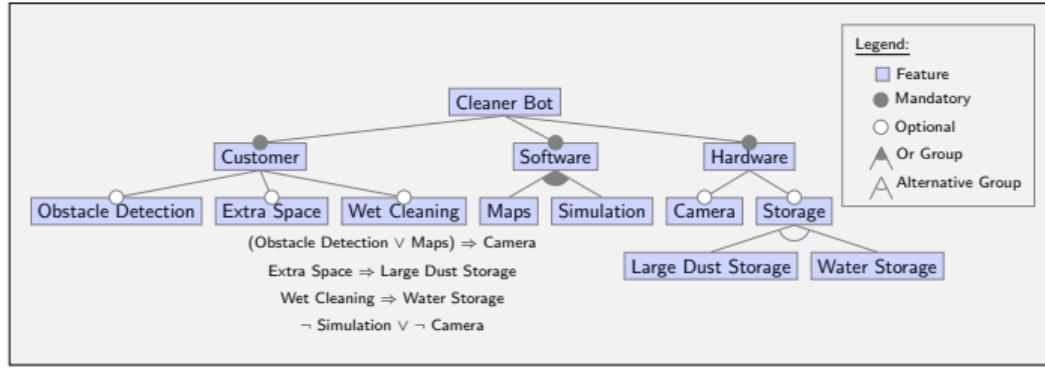


Can we configure a robot?

Is there a robot with camera?

How many robots?

Motivation Plenty Analyses



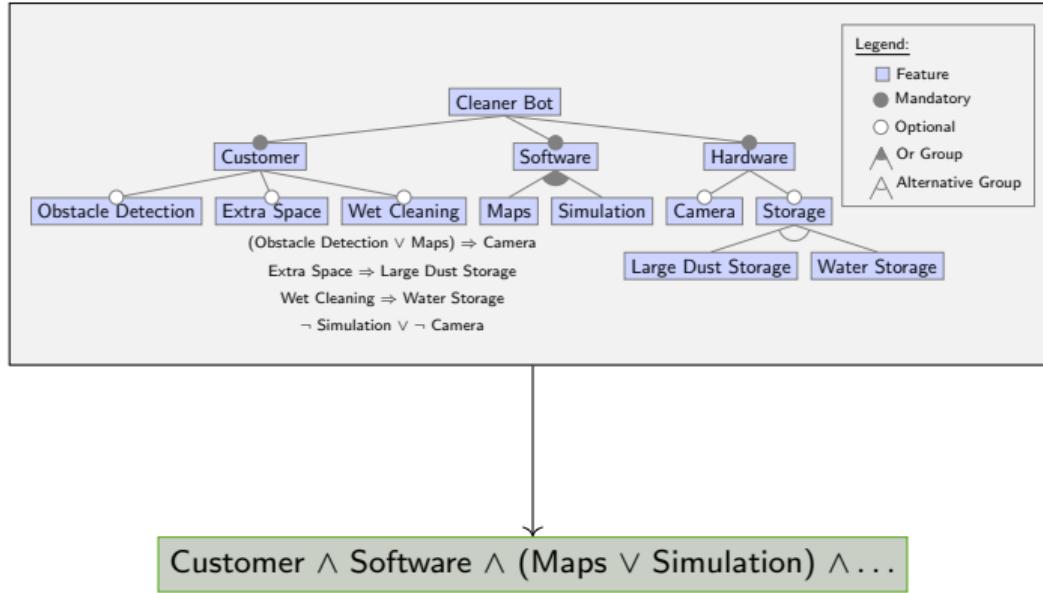
Can we configure a robot?

Is there a robot with camera?

How many robots?

Which robots to test?

Motivation Plenty Analyses



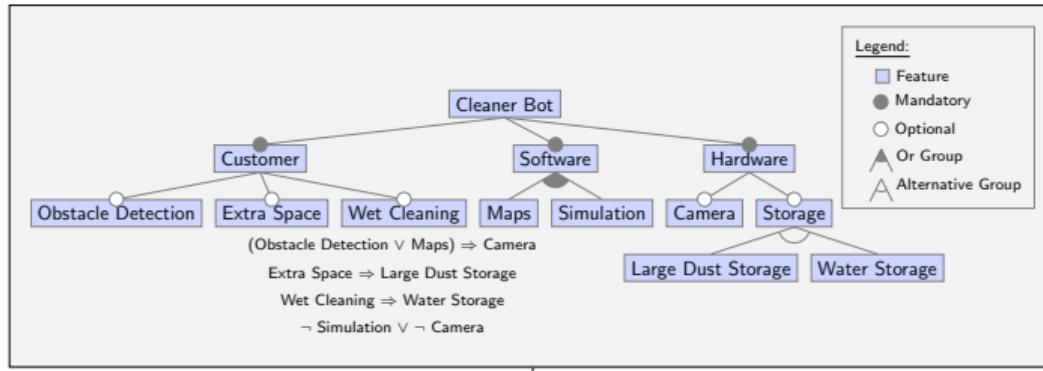
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Motivation Plenty Analyses



Can we configure a robot?

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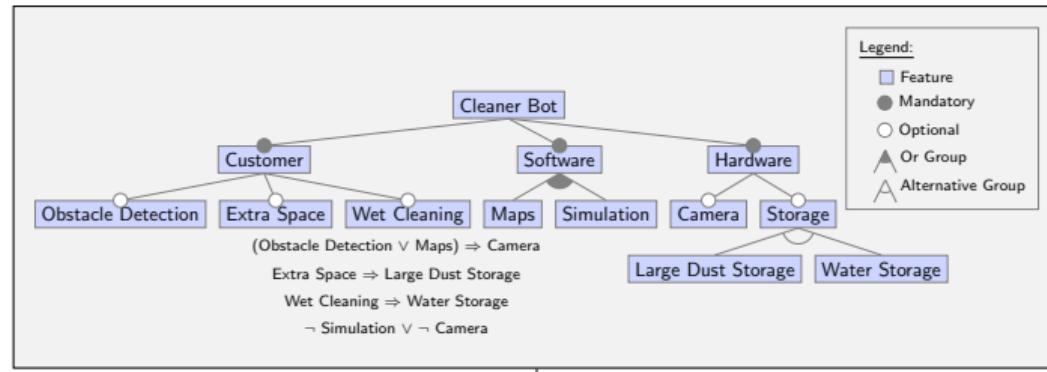
How many robots?

Which robots to test?

Customer \wedge Software \wedge (Maps \vee Simulation) $\wedge \dots$



Motivation Plenty Analyses



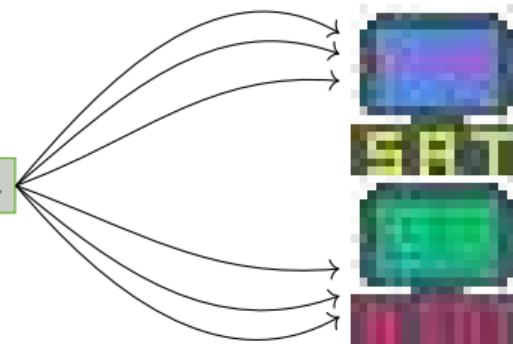
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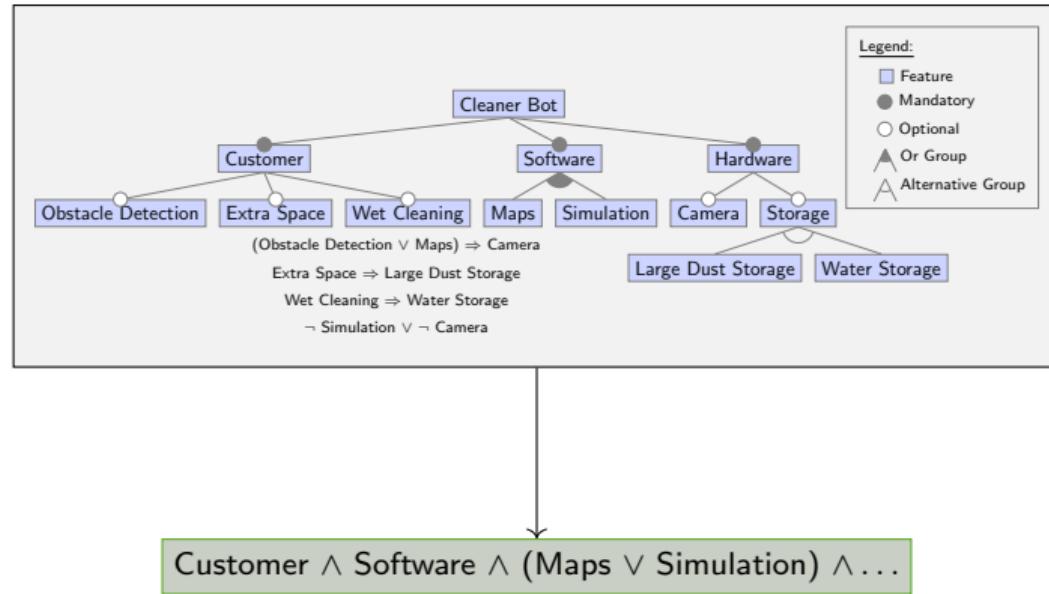
How many robots?

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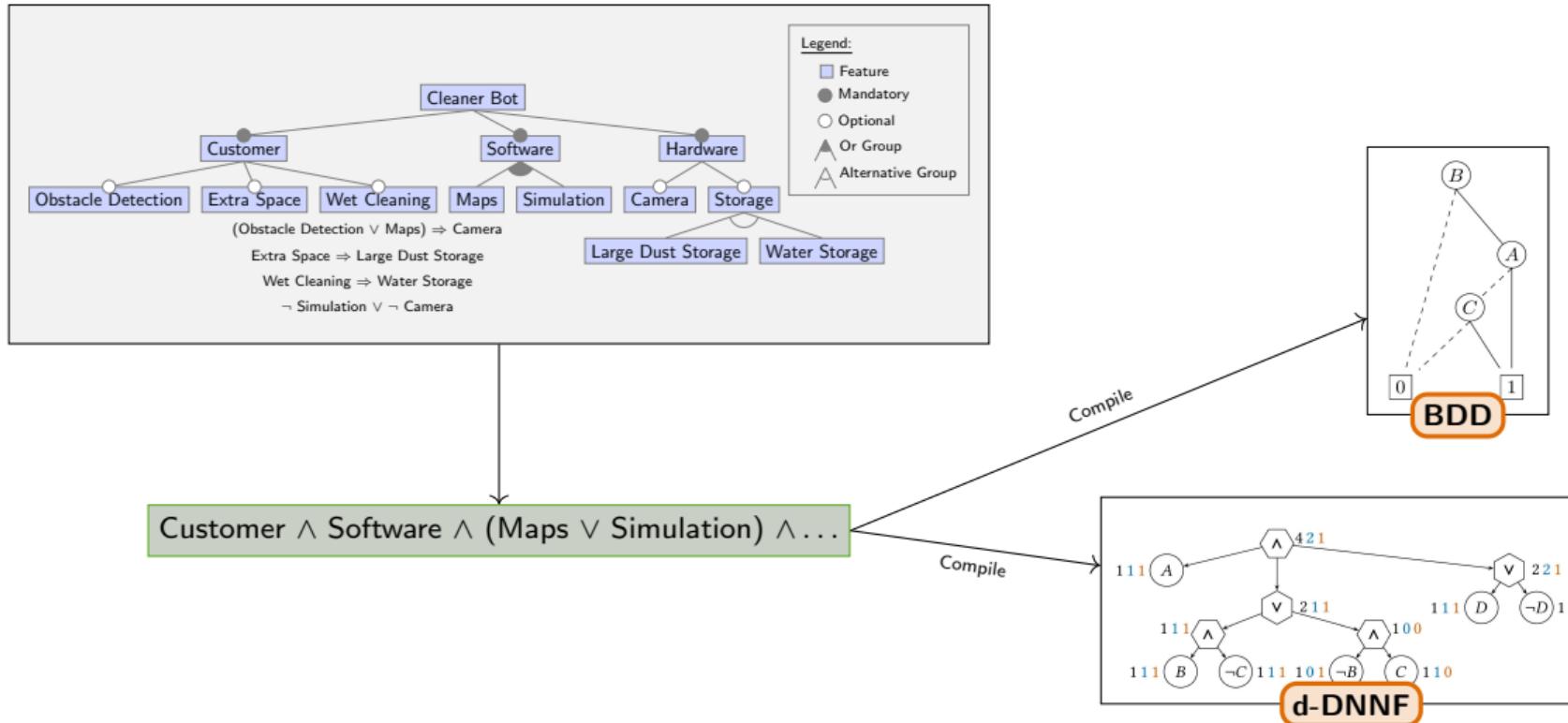
Customer \wedge Software \wedge (Maps \vee Simulation) $\wedge \dots$



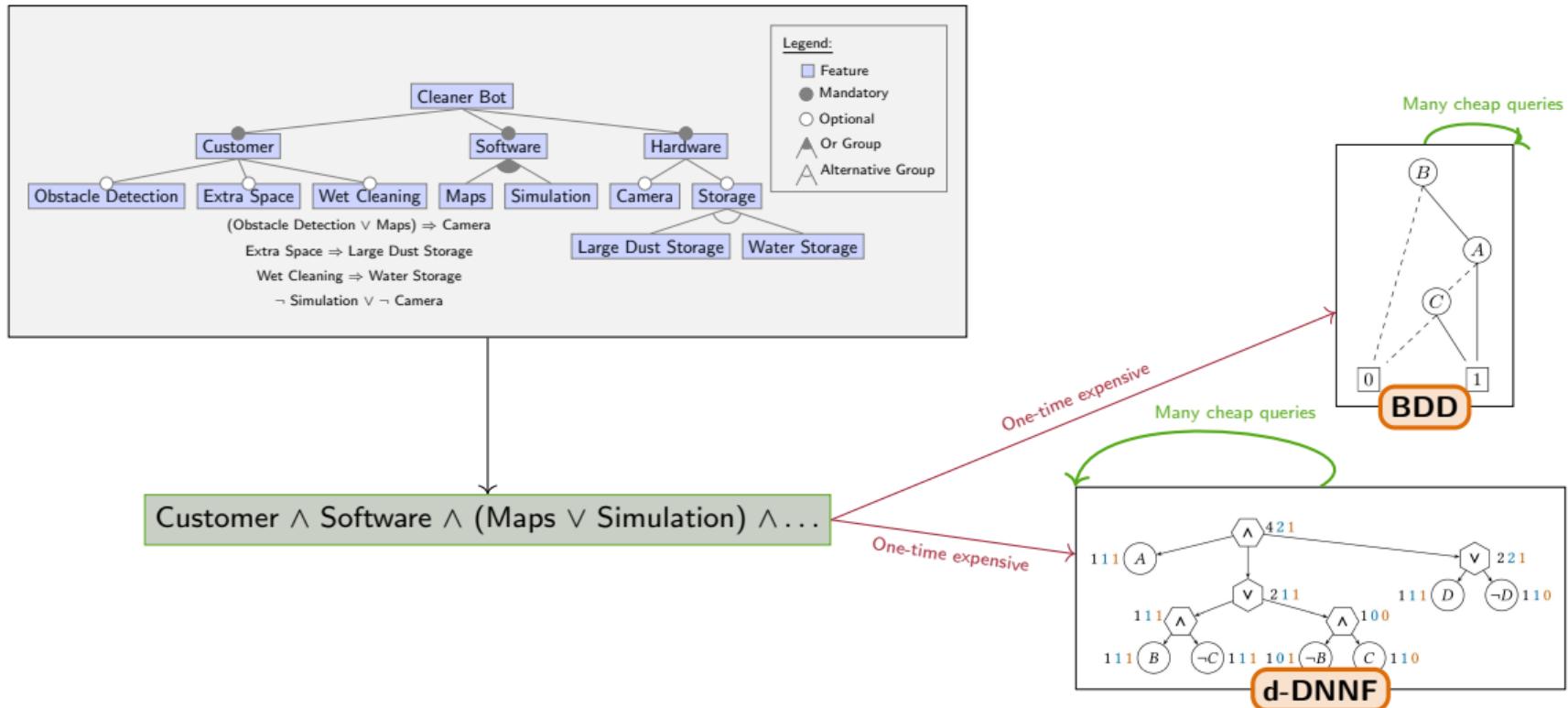
Motivation Knowledge Compilation



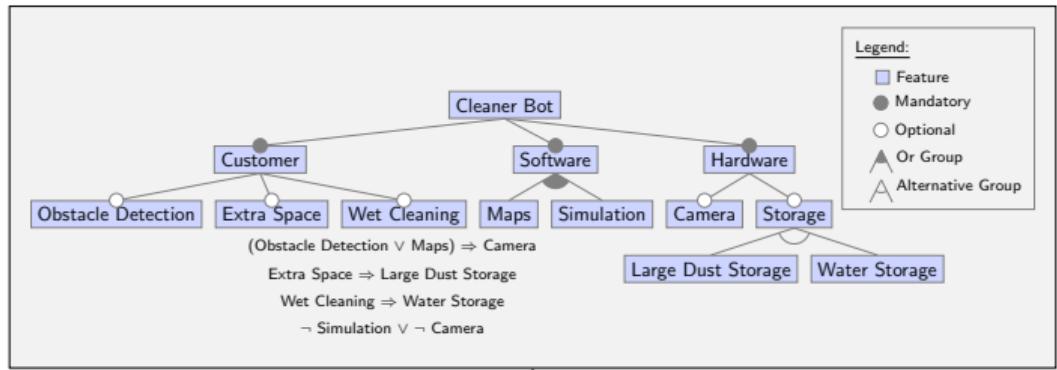
Motivation Knowledge Compilation



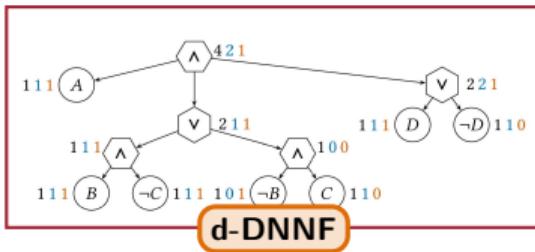
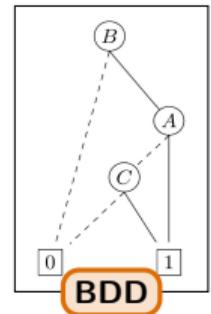
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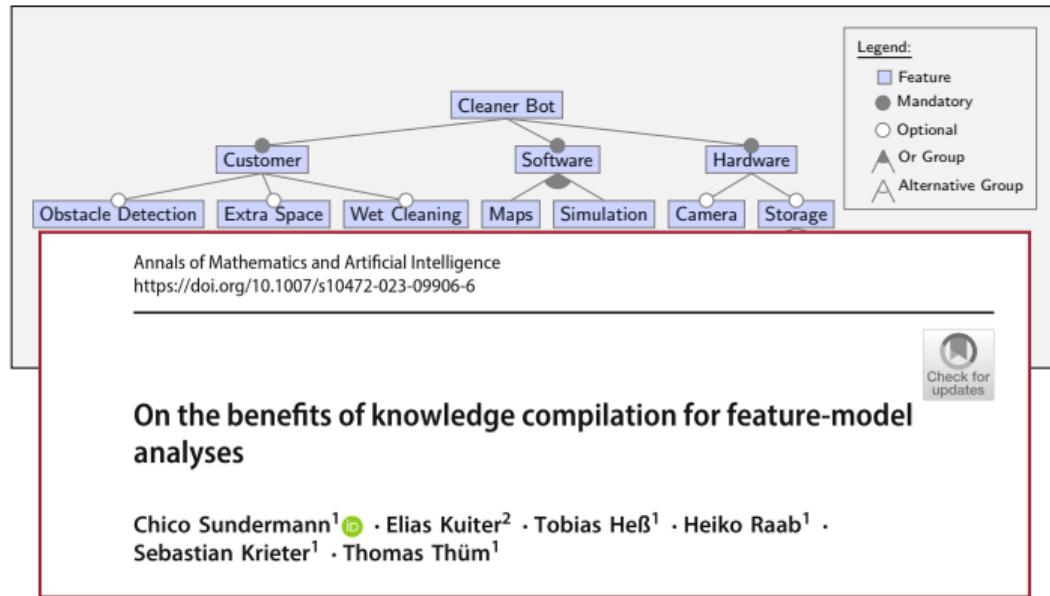
Motivation Knowledge Compilation



Customer \wedge Software \wedge (Maps \vee Simulation) \wedge ...

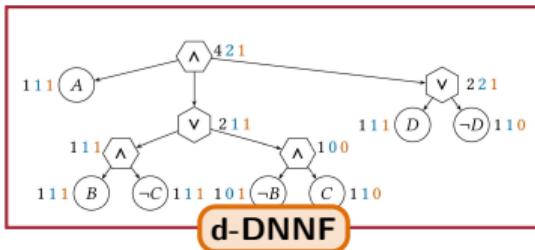
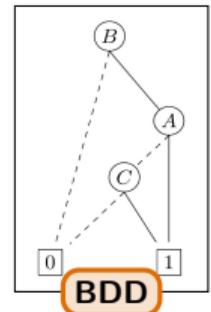


Motivation Knowledge Compilation

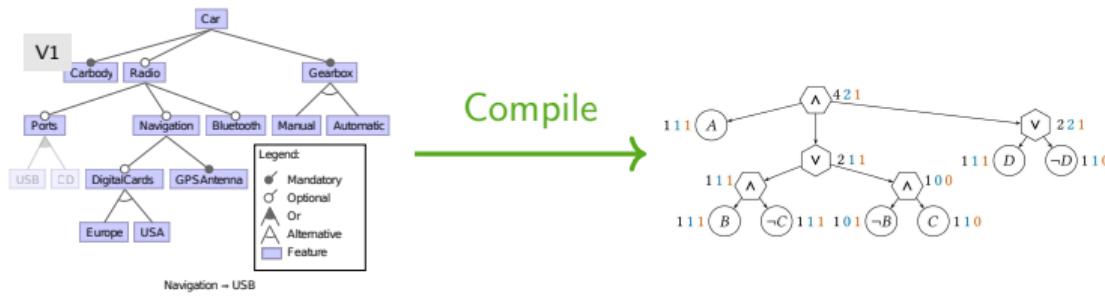


On the benefits of knowledge compilation for feature-model analyses

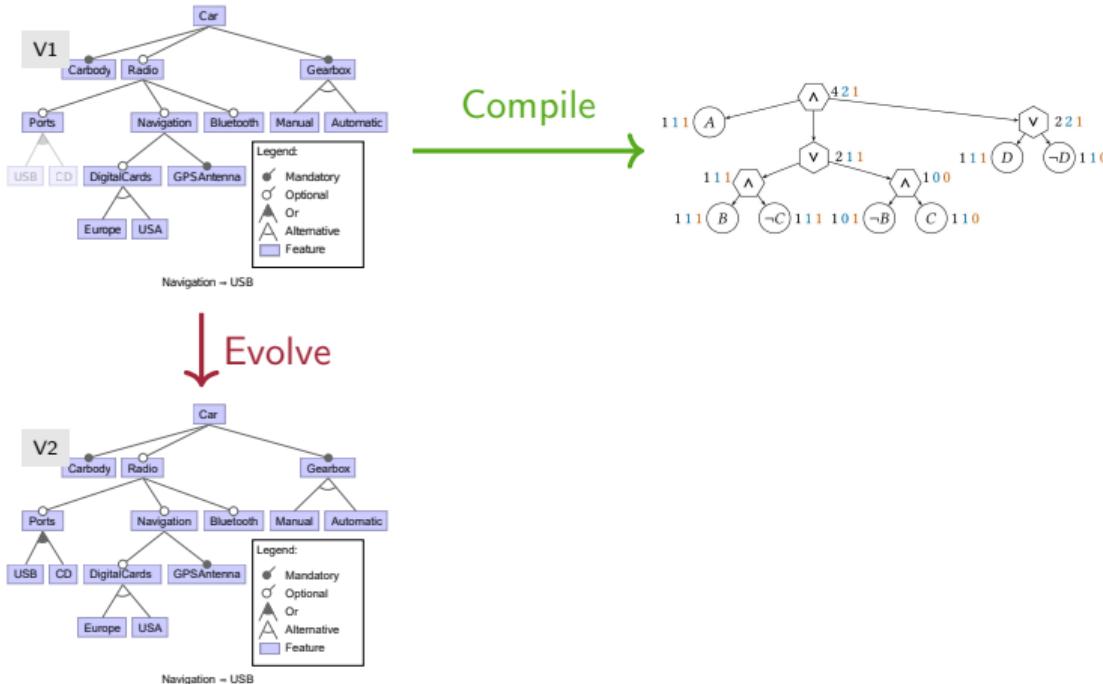
Chico Sundermann¹ · Elias Kuiter² · Tobias Heß¹ · Heiko Raab¹ ·
Sebastian Krieter¹ · Thomas Thüm¹



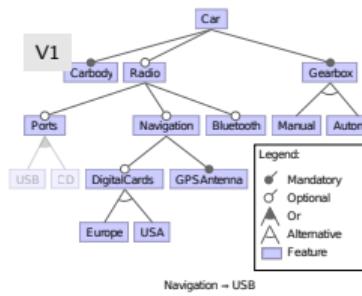
Incremental d-DNNF Compilation



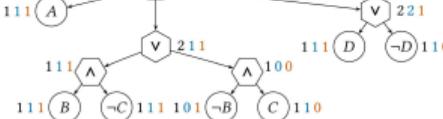
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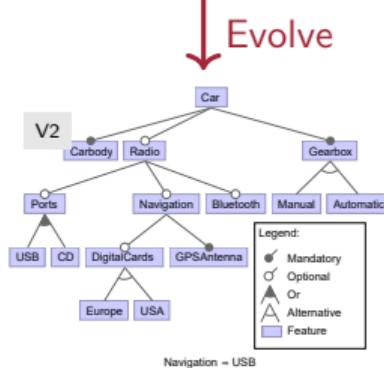
Incremental d-DNNF Compilation



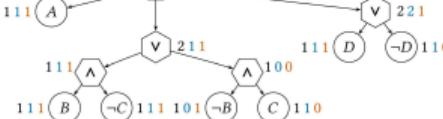
Compile →



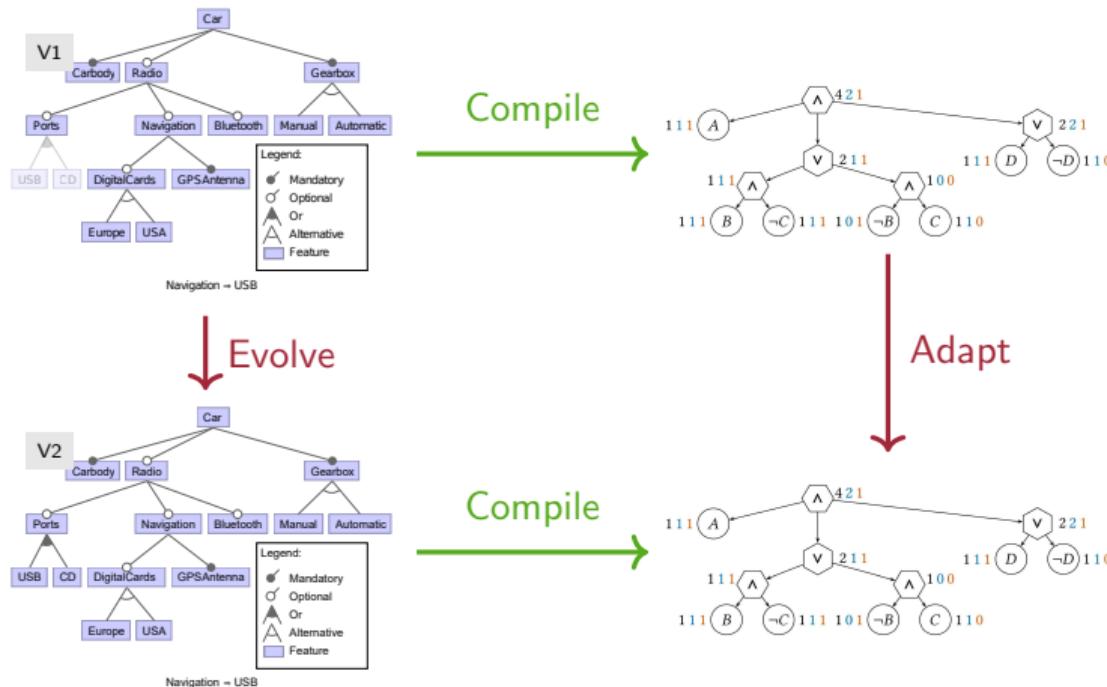
↓ Evolve



Compile →



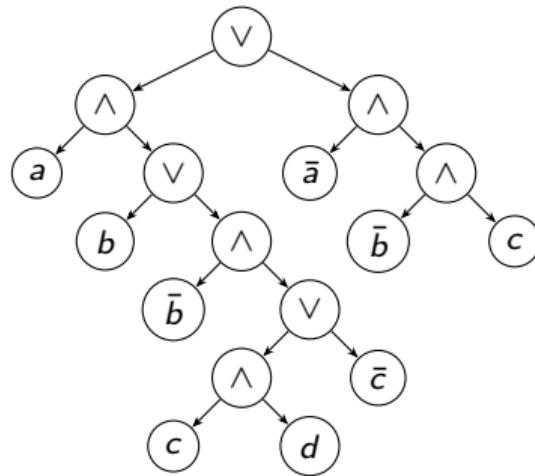
Incremental d-DNNF Compilation



Approach Identify Part Requiring Update

- Recurse d-DNNF to find parts sharing variables with clause
- Apply assumptions while recursing to skip parts unchanged by clause

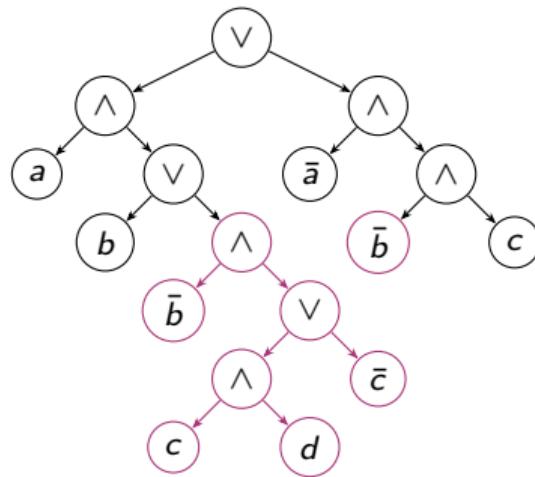
Change: $b \vee d$



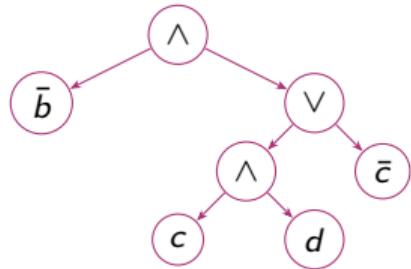
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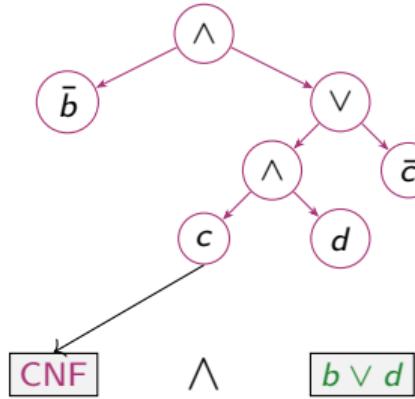
Change: $b \vee d$



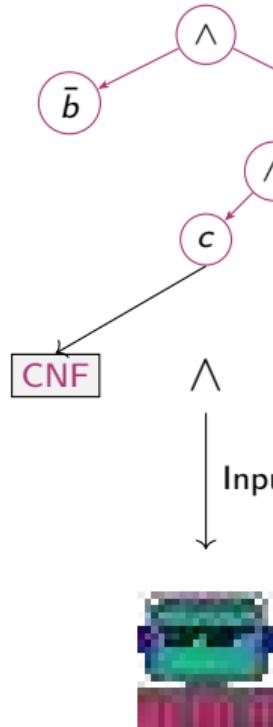
Approach Partially Recompile & Reattach



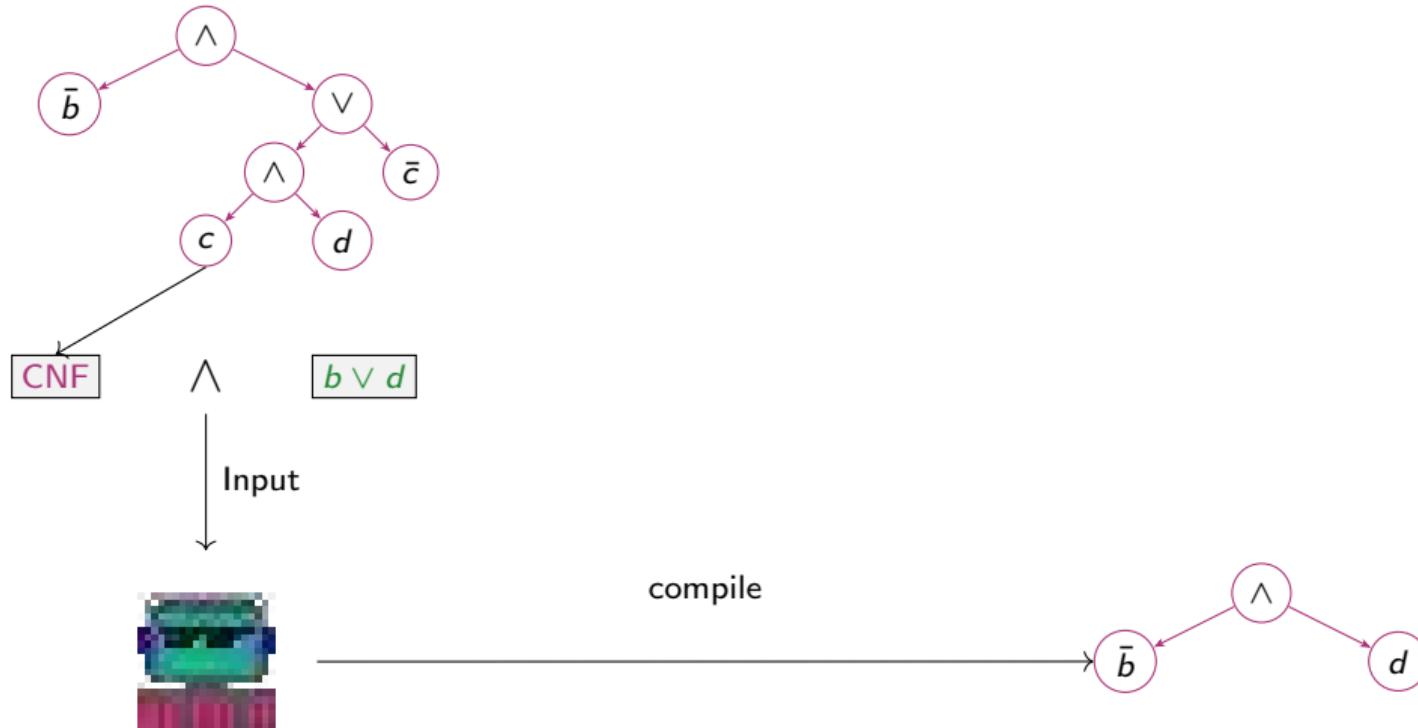
Approach Partially Recompile & Reattach



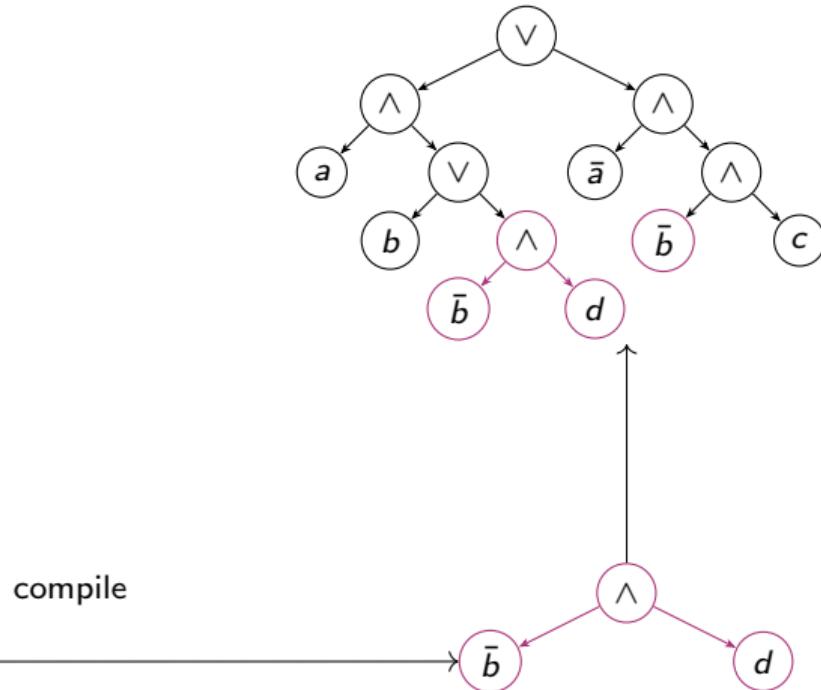
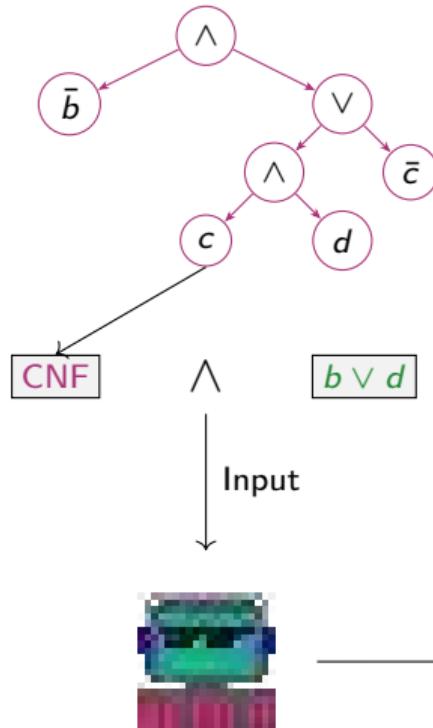
Approach Partially Recompile & Reattach



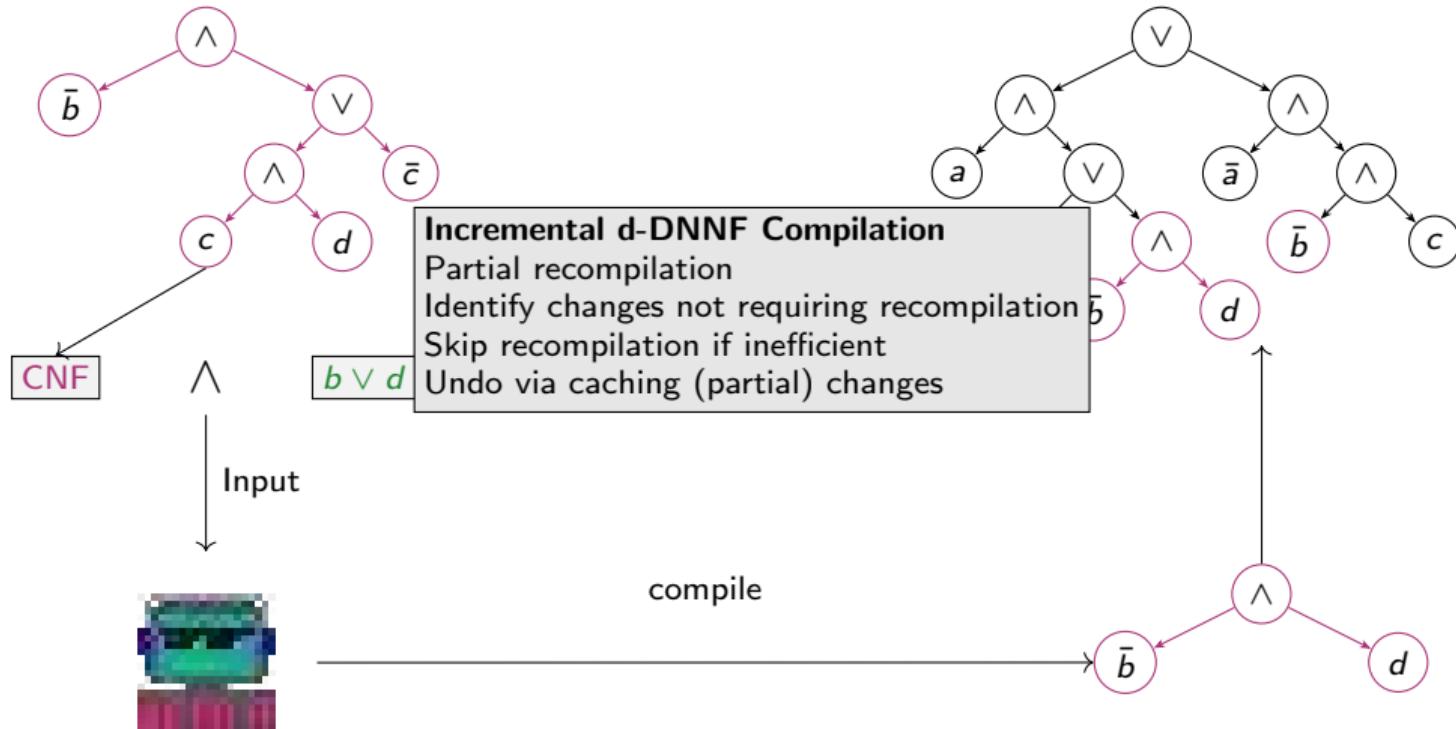
Approach Partially Recompile & Reattach



Approach Partially Recompile & Reattach



Approach Partially Recompile & Reattach



Evaluation Experiment Design

- Goal: Examine performance benefits

Domain	Models	Features	Clauses	Cardinality
automotive	2	2,513 – 18,616	10,311 – 350,149	$5.3^{210} – 1.7^{1534}$
business	1	1,920	61,362	2.0^{397}
cloud	1	106	156	5.4^{20}
database	1	117	417	3.2^1
deep-learning	2	3,296 – 6,867	8,004 – 17,431	$1.3^{185} – 2.8^{630}$
e-commerce	2	287 – 2,238	421 – 2,615	$2.3^{49} – 8.0^{558}$
finance	3	176 – 771	280 – 7,238	$9.7^{13} – 5.3^{31}$
games	1	144	769	4.2^{18}
hardware	2	172 – 377	309 – 1,356	$3.3^{21} – 2.3^{27}$
navigation	2	103 – 145	185 – 378	$3.2^{10} – 1.8^{12}$
security	1	158	457	1.2^{14}
systems software	14	96 – 1,580	183 – 15,692	$8.3^{11} – 4.1^{409}$
text	1	137	179	1.3^{23}

Evaluation Experiment Design

- Goal: Examine performance benefits
- Subject systems
 - Industrial feature Models
 - Various domains, sizes

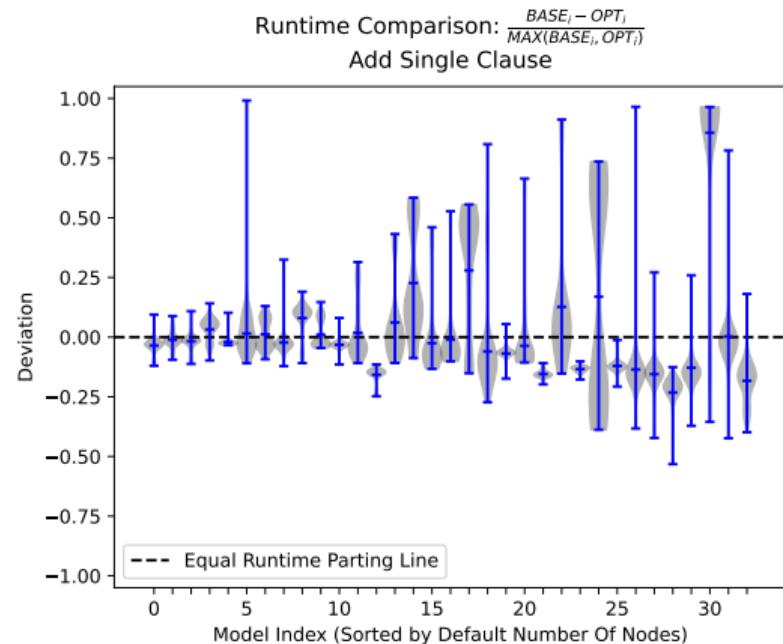
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Evaluation Experiment Design

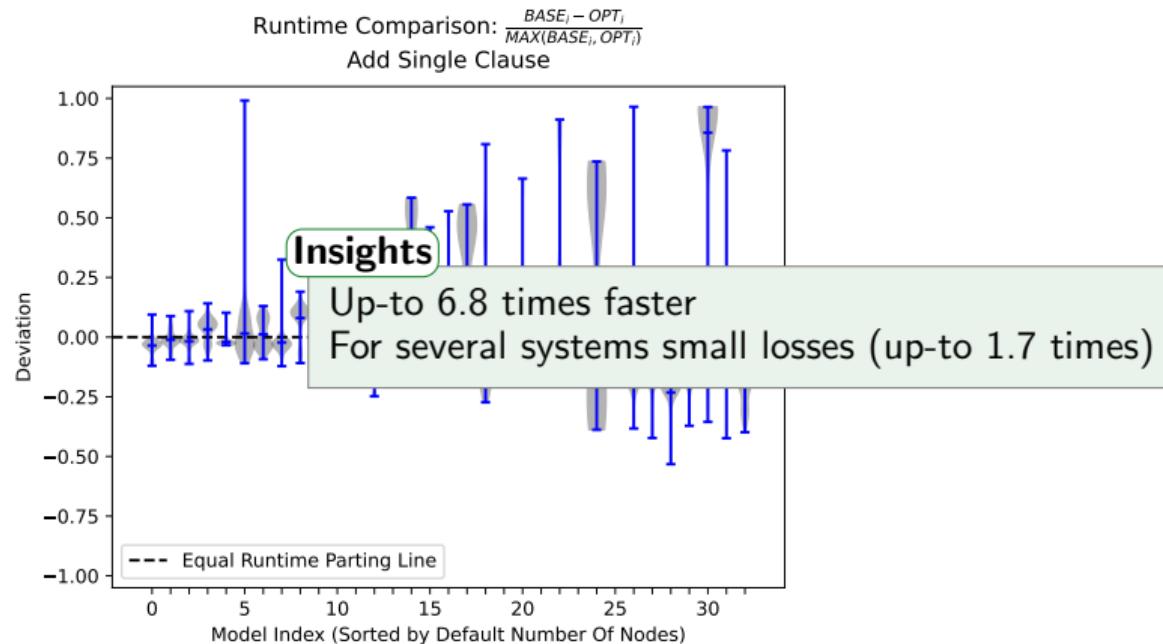
- Goal: Examine performance benefits
- Subject systems
 - Industrial feature Models
 - Various domains, sizes
- Emulate realistic changes
 - Remove one constraint → Compile without
→ Incrementally add removed
 - Apply typical edit patterns e.g.:
 - Add/remove feature
 - Change feature group
 - Move feature

Domain	Models	Features	Clauses	Cardinality
automotive	2	2,513 – 18,616	10,311 – 350,149	5.3 ²¹⁰ – 1.7 ¹⁵³⁴
business	1	1,920	61,362	2.0 ³⁹⁷
cloud	1	106	156	5.4 ²⁰
database	1	117	417	3.2 ¹
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e-commerce	2	287 – 2,238	421 – 2,615	2.3 ⁴⁹ – 8.0 ⁵⁵⁸
finance	3	176 – 771	280 – 7,238	9.7 ¹³ – 5.3 ³¹
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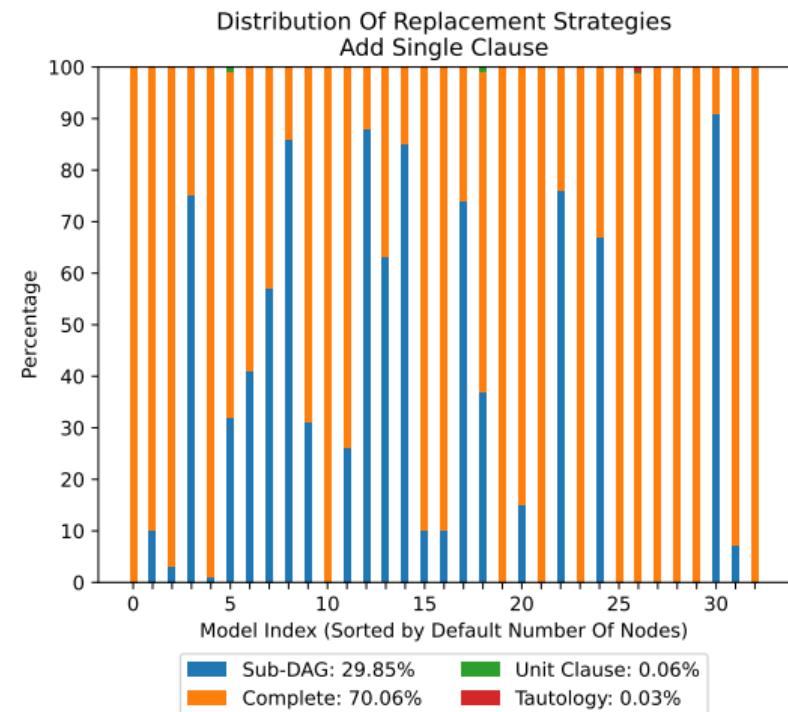
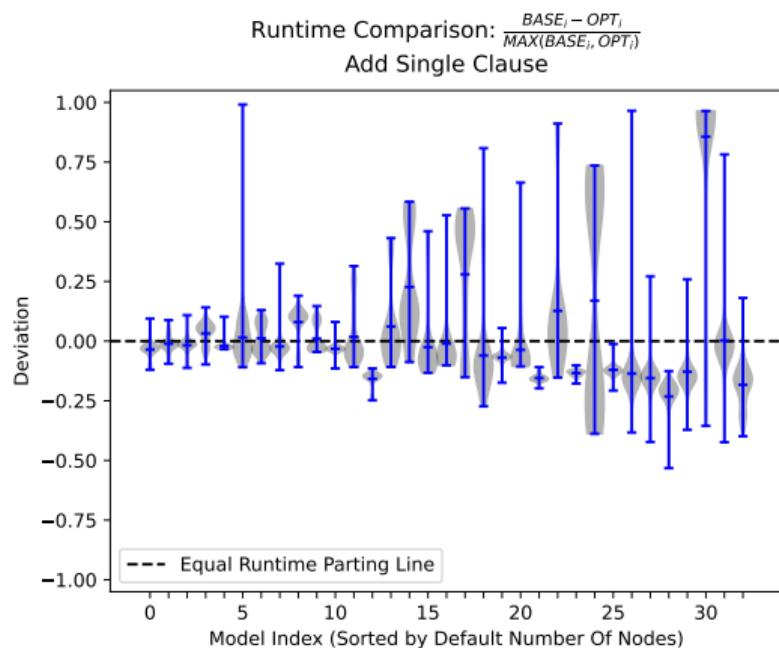
Evaluation Single Clause



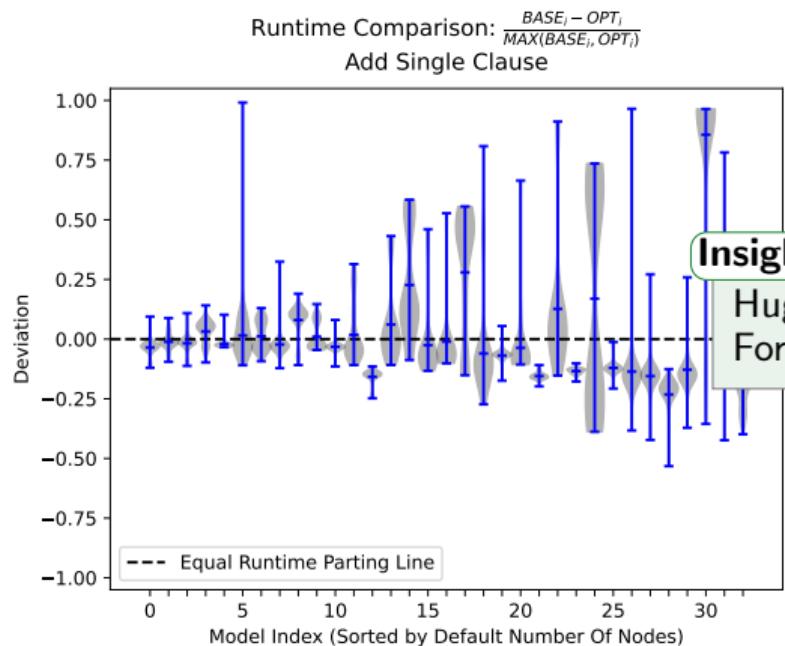
Evaluation Single Clause



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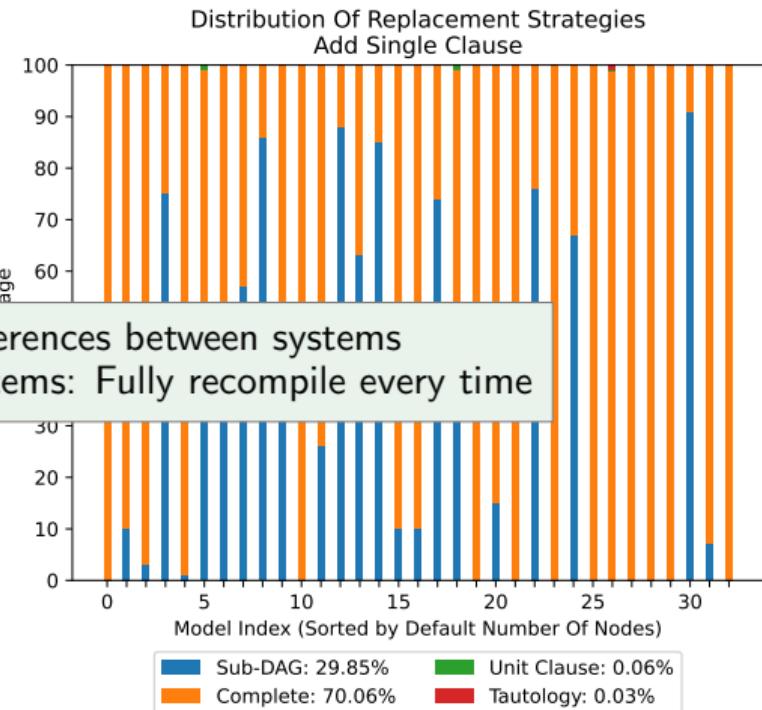


Evaluation Single Clause

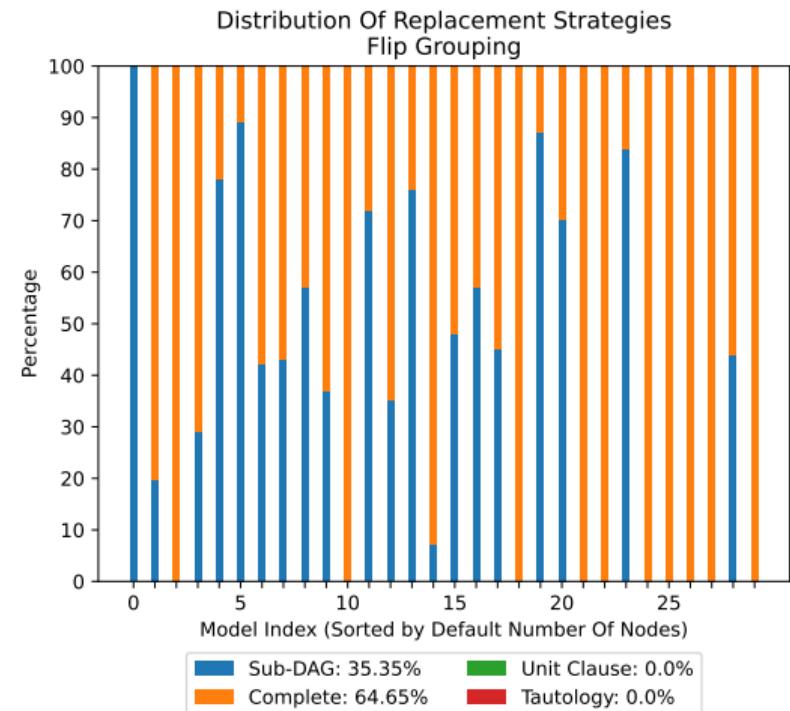
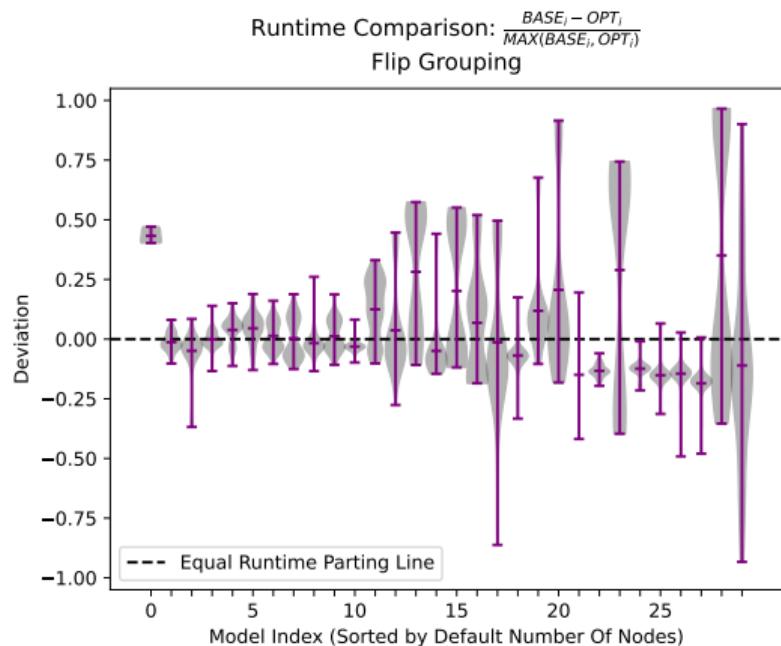


Insights

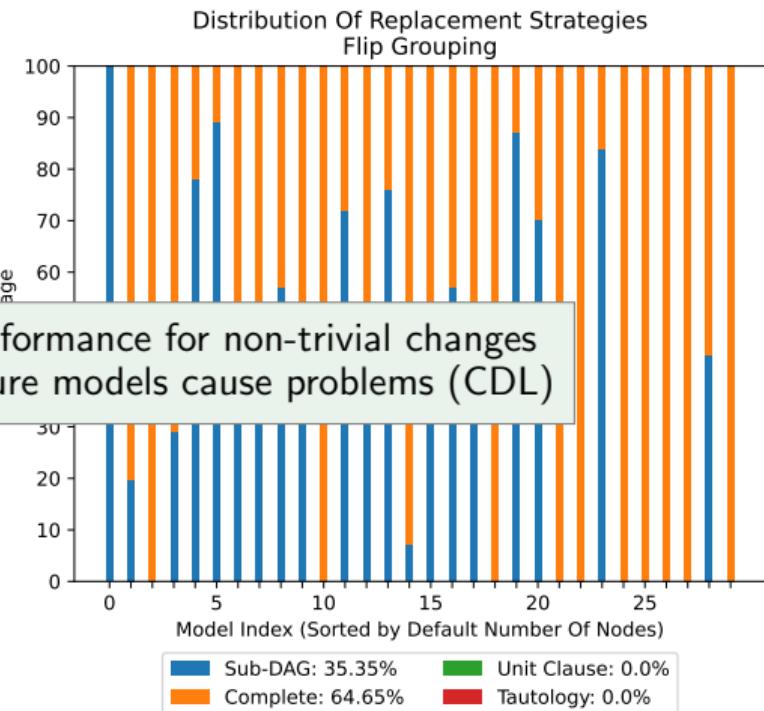
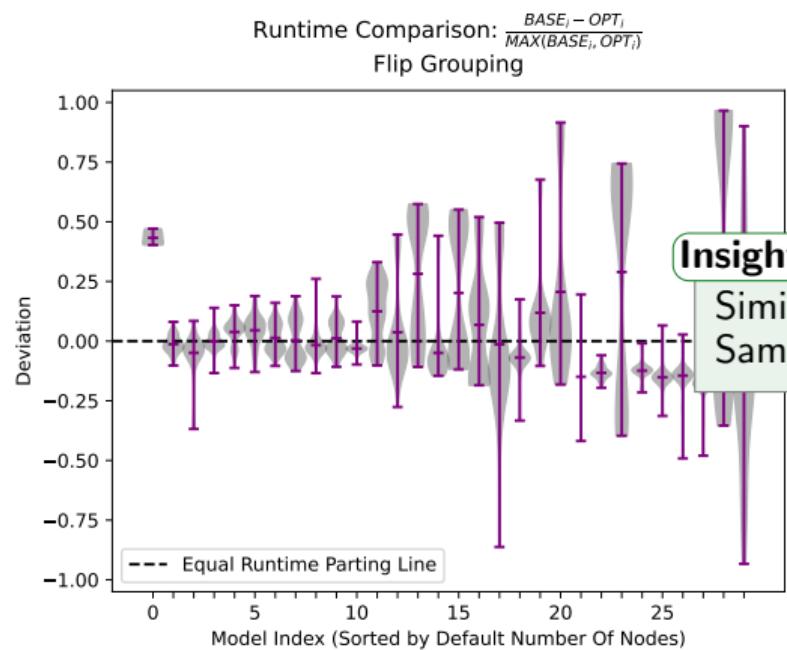
Huge differences between systems
For 6 systems: Fully recompile every time



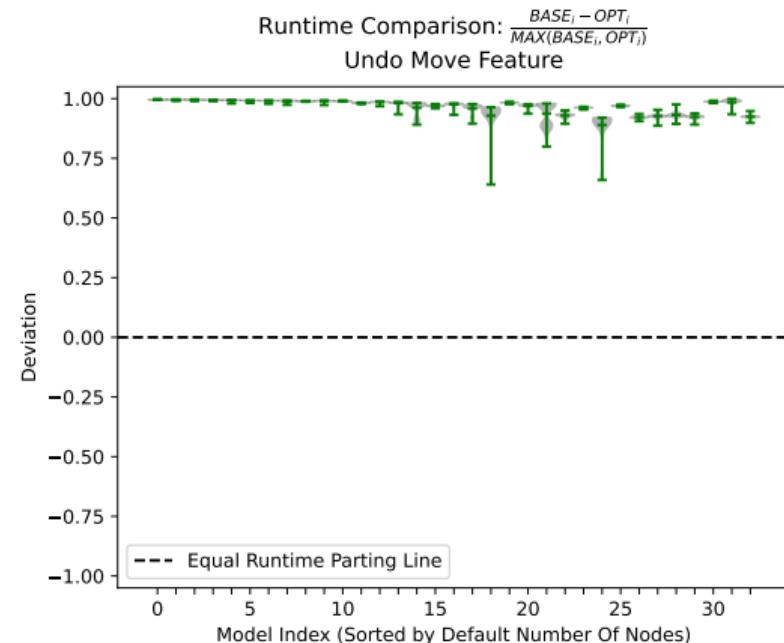
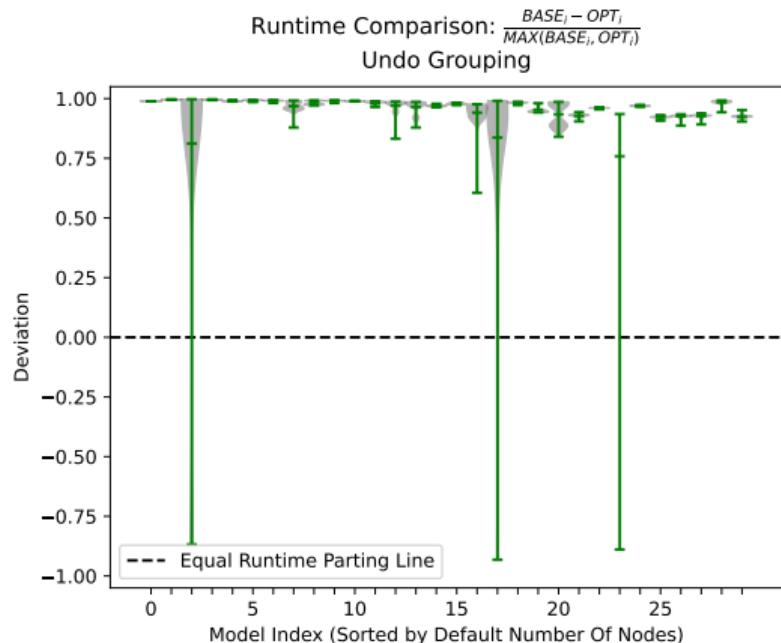
Evaluation Flip Group



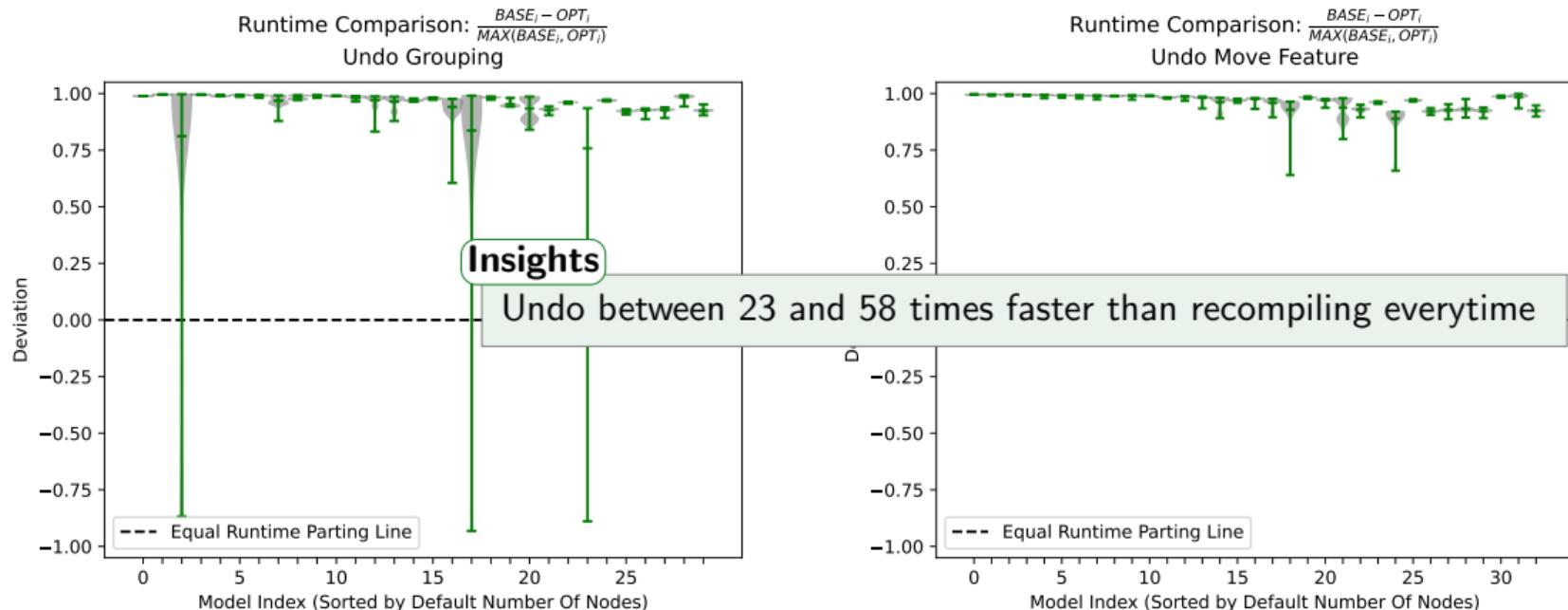
Evaluation Flip Group



Evaluation Undo



Evaluation Undo



Conclusion & Outlook

Insights

Substantial runtime improvements for some feature models
Undo by caching performs very well

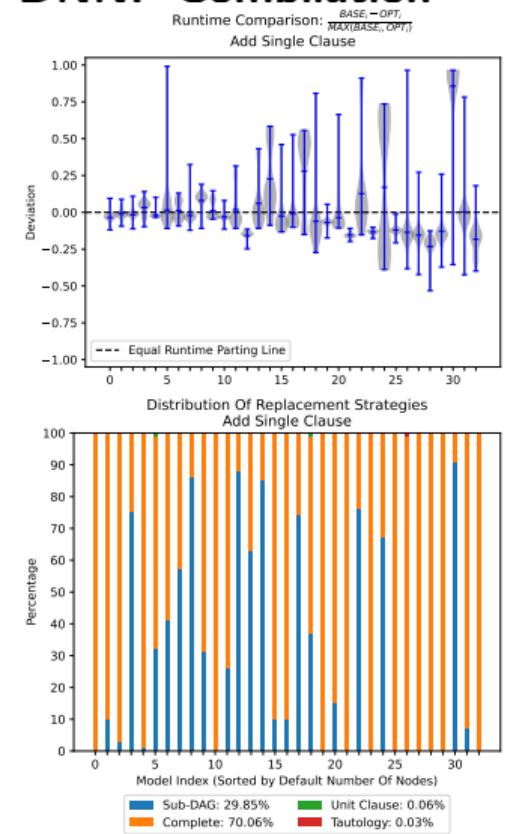
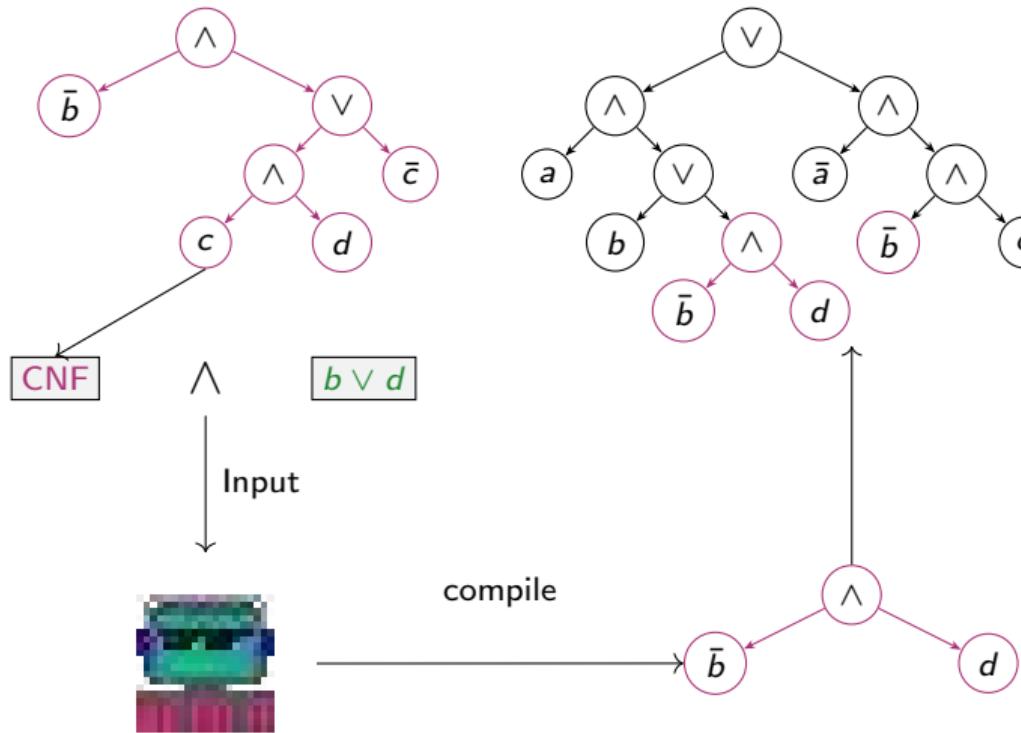
Limitations

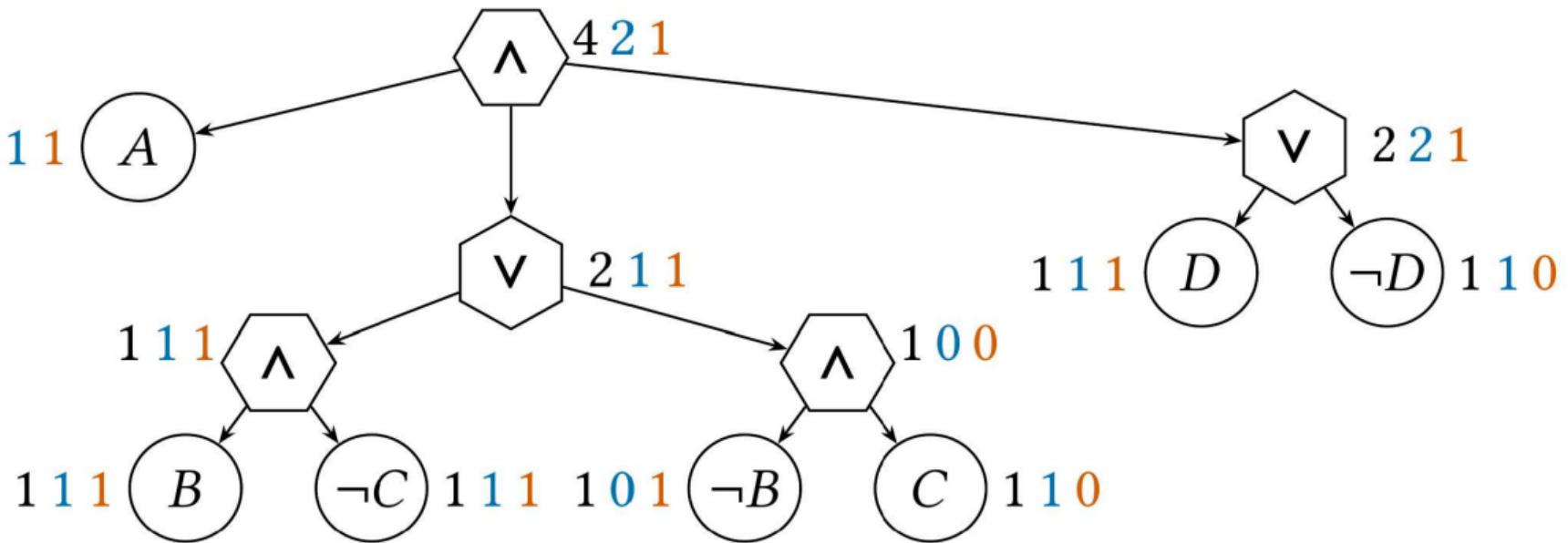
Performance highly depends on input model
Some models always need full recompilation

Future Work

How to improve for unfavourable d-DNNFs?
How to prepare the initial d-DNNF to be more favourable?
How to recognize hopeless d-DNNFs?

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Incorporating Feature-Model Edits with Incremental d-DNNF Compilation

1. Motivation

Product Lines
Feature Dependencies
Plenty Analyses

Knowledge
Compilation

2. Approach

3. Evaluation

Experiment Design
Single Clause
Flip Group
Undo

4. Conclusion & Outlook

5. Future Work
What's left to do?
Content Overview

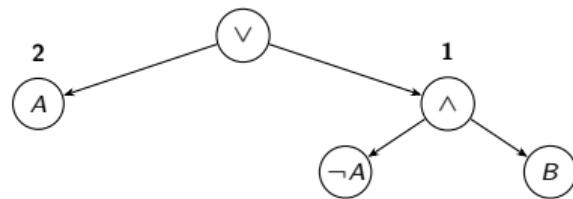
How does this even work?

d-DNNFs (Darwiche 2000)

deterministic
decomposable
negation
normal
form

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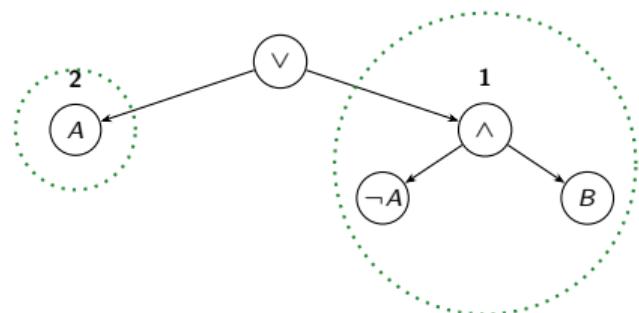
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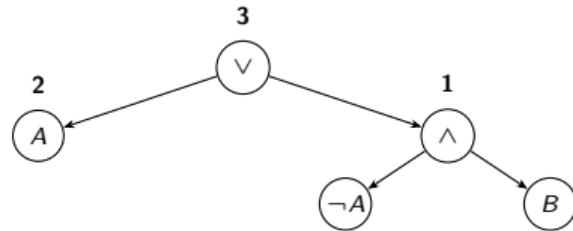


No shared solutions

deterministic
decomposable
negation
normal
form

How does this even work?

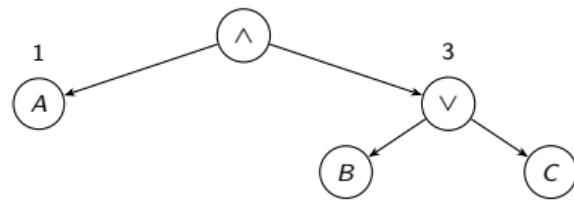
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deterministic (Sum for \vee)
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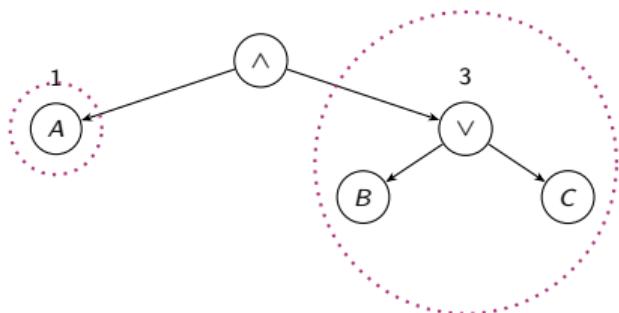
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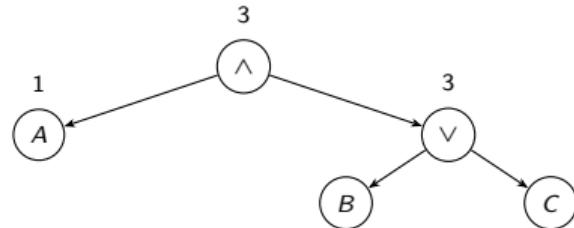


Independent
⇒ All pairs valid

deterministic (Sum for \vee)
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How does this even work?

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