Scilab Textbook Companion for Digital Signal Processing by R. Babu¹

Created by
Mohammad Faisal Siddiqui
B.Tech (pursuing)
Electronics Engineering
Jamia Milia Islamia
College Teacher
Dr. Sajad A. Loan, JMI, New D
Cross-Checked by
Santosh Kumar, IITB

March 8, 2017

¹Funded by a grant from the National Mission on Education through ICT, http://spoken-tutorial.org/NMEICT-Intro. This Textbook Companion and Scilab codes written in it can be downloaded from the "Textbook Companion Project" section at the website http://scilab.in

Book Description

Title: Digital Signal Processing

Author: R. Babu

Publisher: Scitech Publications

Edition: 4

Year: 2010

ISBN: 81-8371-081-7

Scilab numbering policy used in this document and the relation to the above book.

Exa Example (Solved example)

Eqn Equation (Particular equation of the above book)

AP Appendix to Example(Scilab Code that is an Appednix to a particular Example of the above book)

For example, Exa 3.51 means solved example 3.51 of this book. Sec 2.3 means a scilab code whose theory is explained in Section 2.3 of the book.

Contents

Lis	List of Scilab Codes		
1	DISCRETE TIME SIGNALS AND LINEAR SYSTEMS	6	
2	THE Z TRANSFORM	29	
3	THE DISCRETE FOURIER TRANSFORM	54	
4	THE FAST FOURIER TRANSFORM	7 4	
5	INFINITE IMPULSE RESPONSE FILTERS	85	
6	FINITE IMPULSE RESPONSE FILTERS	97	
7	FINITE WORD LENGTH EFFECTS IN DIGITAL FILTERS	134	
8	MULTIRATE SIGNAL PROCESSING	136	
9	STATISTICAL DIGITAL SIGNAL PROCESSING	138	
11	DIGITAL SIGNAL PROCESSORS	141	

List of Scilab Codes

Exa 1.1	Continuous Time Plot and Discrete Time Plot 6
Exa 1.2	Continuous Time Plot and Discrete Time Plot 8
Exa 1.3.a	Evaluate the Summations
Exa 1.3.b	Evaluate the Summations
Exa 1.4.a	Check for Energy or Power Signals
Exa 1.4.d	Check for Energy or Power Signals
Exa 1.5.a	Determining Periodicity of Signal
Exa 1.5.c	Determining Periodicity of Signal
Exa 1.5.d	Determining Periodicity of Signal
Exa 1.11	Stability of the System
Exa 1.12	Convolution Sum of Two Sequences
Exa 1.13	Convolution of Two Signals
Exa 1.18	Cross Correlation of Two Sequences
Exa 1.19	Determination of Input Sequence
Exa 1.32.a	Plot Magnitude and Phase Response
Exa 1.37	Sketch Magnitude and Phase Response
Exa 1.38	Plot Magnitude and Phase Response
Exa 1.45	Filter to Eliminate High Frequency Component 22
Exa 1.57.a	Discrete Convolution of Sequences
Exa 1.61	Fourier Transform
Exa 1.62	Fourier Transform
Exa 1.64.a	Frequency Response of LTI System
Exa 1.64.c	Frequency Response of LTI System
Exa 2.1	z Transform and ROC of Causal Sequence 29
Exa 2.2	z Transform and ROC of Anticausal Sequence 29
Exa 2.3	z Transform of the Sequence
Exa 2.4	z Transform and ROC of the Signal
Exa 2.5	z Transform and ROC of the Signal

Exa	2.6	Stability of the System
Exa	2.7	z Transform of the Signal
Exa	2.8.a	z Transform of the Signal
Exa	2.9	z Transform of the Sequence
Exa	2.10	z Transform Computation
Exa	2.11	z Transform of the Sequence
Exa	2.13.a	z Transform of Discrete Time Signals
Exa	2.13.b	z Transform of Discrete Time Signals
Exa	2.13.c	z Transform of Discrete Time Signals
Exa	2.13.d	z Transform of Discrete Time Signals
Exa	2.16	Impulse Response of the System
Exa	2.17	Pole Zero Plot of the Difference Equation
Exa	2.19	Frequency Response of the System
Exa	2.20.a	Inverse z Transform Computation
Exa	2.22	Inverse z Transform Computation 40
Exa	2.23	Causal Sequence Determination
Exa	2.34	Impulse Response of the System
Exa		Pole Zero Plot of the System
		Unit Sample Response of the System
		Determine Output Response
Exa		Input Sequence Computation
Exa	2.41.a	z Transform of the Signal
Exa	2.41.b	z Transform of the Signal
Exa	2.41.c	z Transform of the Signal
		Pole Zero Pattern of the System 50
		z Transform of the Sequence 50
Exa	2.53.b	z Transform of the Signal
Exa	2.53.c	z Transform of the Signal 51
Exa	2.53.d	z Transform of the Signal 51
Exa	2.54	z Transform of Cosine Signal
Exa	2.58	Impulse Response of the System
Exa	3.1	DFT and IDFT
Exa	3.2	DFT of the Sequence
Exa	3.3	8 Point DFT
Exa	3.4	IDFT of the given Sequence
Exa	3.7	Plot the Sequence
Exa	3.9	Remaining Samples
Exa	3.11	DFT Computation

Exa	3.13	Circular Convolution	
Exa	3.14	Circular Convolution 61	
Exa	3.15	Determine Sequence x3 62	
Exa	3.16	Circular Convolution	
Exa	3.17	Circular Convolution	
Exa	3.18	Output Response	
Exa	3.20	Output Response	
Exa	3.21	Linear Convolution	
Exa	3.23.a	N Point DFT Computation	
Exa	3.23.b	N Point DFT Computation	
Exa	3.23.c	N Point DFT Computation 67	
Exa	3.23.d	N Point DFT Computation 67	
		N Point DFT Computation 67	
		N Point DFT Computation	
Exa	3.24	DFT of the Sequence	
Exa	3.25	8 Point Circular Convolution	
Exa	3.26	Linear Convolution using DFT 69	
Exa	3.27.a	Circular Convolution Computation	
Exa	3.27.b	Circular Convolution Computation	
Exa	3.30	Calculate value of N	
Exa	3.32	Sketch Sequence	
Exa	3.36	Determine IDFT	
Exa	4.3	Shortest Sequence N Computation	
Exa	4.4	Twiddle Factor Exponents Calculation	
Exa	4.6	DFT using DIT Algorithm	
Exa	4.8	DFT using DIF Algorithm	
Exa	4.9	8 Point DFT of the Sequence	
Exa	4.10	4 Point DFT of the Sequence	
Exa	4.11	IDFT of the Sequence using DIT Algorithm 77	
Exa	4.12	8 Point DFT of the Sequence	
Exa	4.13	8 Point DFT of the Sequence	
Exa	4.14	DFT using DIT Algorithm	
	4.15	DFT using DIF Algorithm	
		8 Point DFT using DIT FFT	
Exa	4.16.b	8 Point DFT using DIT FFT 80	
Exa	4.17	IDFT using DIF Algorithm 80	
Exa	4.18	IDFT using DIT Algorithm 81	
Exa	4.19	FFT Computation of the Sequence 81	
6			

Exa	4.20	8 Point DFT by Radix 2 DIT FFT	31
Exa	4.21	DFT using DIT FFT Algorithm	32
Exa	4.22		32
Exa	4.23		3
Exa	4.24	8 Point DFT of the Sequence	3
Exa	5.1		35
Exa	5.2	Order of Low Pass Butterworth Filter	35
Exa	5.4	Analog Butterworth Filter Design	86
Exa	5.5	Analog Butterworth Filter Design	37
Exa	5.6		37
Exa	5.7		8
Exa	5.8		8
Exa	5.9		39
Exa	5.10		39
Exa	5.11	Impulse Invariant Method Filter Design	0
Exa	5.12		1
Exa	5.13		1
Exa	5.15	-)2
Exa	5.16	Bilinear Transformation Method Filter Design 9)2
Exa	5.17		93
Exa	5.18)4
Exa	5.19)4
Exa	5.29	Pole Zero IIR Filter into Lattice Ladder Structure 9	95
Exa	6.1	Group Delay and Phase Delay	7
Exa	6.5		9
Exa	6.6		9
Exa	6.7	BPF Magnitude Response	1
Exa	6.8	BRF Magnitude Response)3
Exa	6.9.a	HPF Magnitude Response using Hanning Window 10)5
Exa	6.9.b	HPF Magnitude Response using Hamming Window 10	7
Exa	6.10	Hanning Window Filter Design	9
Exa	6.11	LPF Filter Design using Kaiser Window	.1
Exa	6.12	BPF Filter Design using Kaiser Window	.3
		Digital Differentiator using Rectangular Window 11	
		Digital Differentiator using Hamming Window 11	
		Hilbert Transformer using Rectangular Window 11	
		Hilbert Transformer using Blackman Window 12	
		Filter Coefficients obtained by Sampling 12	

Exa	6.16	Coefficients of Linear phase FIR Filter
Exa	6.17	BPF Filter Design using Sampling Method 123
Exa	6.18.a	Frequency Sampling Method FIR LPF Filter 124
Exa	6.18.b	Frequency Sampling Method FIR LPF Filter 125
Exa	6.19	Filter Coefficients Determination
Exa	6.20	Filter Coefficients using Hamming Window 128
Exa	6.21	LPF Filter using Rectangular Window 130
Exa	6.28	Filter Coefficients for Direct Form Structure 132
Exa	6.29	Lattice Filter Coefficients Determination
Exa	7.2	Subtraction Computation
Exa	7.14	Variance of Output due to AD Conversion Process 134
Exa	8.9	Two Component Decomposition
Exa	8.10	Two Band Polyphase Decomposition
Exa	9.7.a	Frequency Resolution Determination
Exa	9.7.b	Record Length Determination
Exa	9.8.a	Smallest Record Length Computation 139
Exa	9.8.b	Quality Factor Computation
Exa	11.3	Program for Integer Multiplication 141
Exa	11.5	Function Value Calculation

List of Figures

1.1	Continuous Time Plot and Discrete Time Plot
1.2	Continuous Time Plot and Discrete Time Plot 8
1.3	Determining Periodicity of Signal
1.4	Determining Periodicity of Signal
1.5	Determining Periodicity of Signal
1.6	Plot Magnitude and Phase Response
1.7	Sketch Magnitude and Phase Response
1.8	Plot Magnitude and Phase Response
1.9	Filter to Eliminate High Frequency Component 23
1.10	Frequency Response of LTI System
1.11	Frequency Response of LTI System
2.1	Pole Zero Plot of the Difference Equation
2.2	Frequency Response of the System
2.3	Impulse Response of the System
2.4	Pole Zero Plot of the System
2.5	Unit Sample Response of the System
2.6	Determine Output Response
2.7	Pole Zero Pattern of the System
2.8	Impulse Response of the System
3.1	DFT of the Sequence
3.2	Plot the Sequence
3.3	Sketch Sequence
6.1	LPF Magnitude Response
6.2	HPF Magnitude Response
6.3	BPF Magnitude Response
6.4	BRF Magnitude Response

6.5	HPF Magnitude Response using Hanning Window	106
6.6	HPF Magnitude Response using Hamming Window	108
6.7	Hanning Window Filter Design	110
6.8	LPF Filter Design using Kaiser Window	112
6.9	BPF Filter Design using Kaiser Window	114
6.10	Digital Differentiator using Rectangular Window	116
6.11	Digital Differentiator using Hamming Window	118
6.12	Hilbert Transformer using Rectangular Window	120
6.13	Hilbert Transformer using Blackman Window	121
6.14	Frequency Sampling Method FIR LPF Filter	124
6.15	Frequency Sampling Method FIR LPF Filter	126
6.16	Filter Coefficients Determination	127
6.17	Filter Coefficients using Hamming Window	129
6.18	LPF Filter using Rectangular Window	131

Chapter 1

DISCRETE TIME SIGNALS AND LINEAR SYSTEMS

Scilab code Exa 1.1 Continuous Time Plot and Discrete Time Plot

```
1 / \text{Example } 1.1
2 //Sketch the continuous time signal x(t)=2*exp(-2t)
     and also its discrete time equivalent signal with
       a sampling period T = 0.2 sec
3 clear;
4 clc;
5 close;
6 t=0:0.01:2;
7 x1=2*exp(-2*t);
8 subplot(1,2,1);
9 plot(t,x1);
10 xlabel('t');
11 ylabel('x(t)');
12 title('CONTINUOUS TIME PLOT');
13 n=0:0.2:2;
14 x2=2*exp(-2*n);
15 subplot(1,2,2);
```

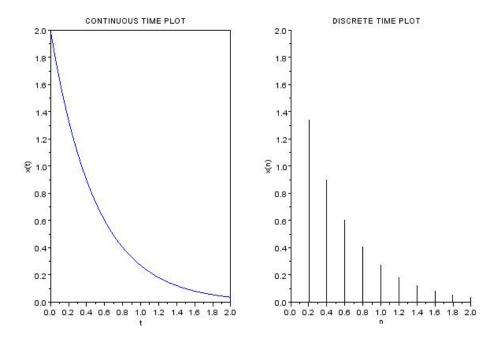


Figure 1.1: Continuous Time Plot and Discrete Time Plot

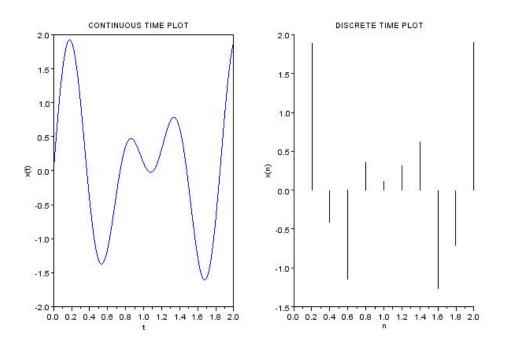


Figure 1.2: Continuous Time Plot and Discrete Time Plot

```
16 plot2d3(n,x2);
17 xlabel('n');
18 ylabel('x(n)');
19 title('DISCRETE TIME PLOT');
```

Scilab code Exa 1.2 Continuous Time Plot and Discrete Time Plot

```
3 clear;
4 clc;
5 close;
6 t=0:0.01:2;
7 x1=\sin(7*t)+\sin(10*t);
8 subplot(1,2,1);
9 plot(t,x1);
10 xlabel('t');
11 ylabel('x(t)');
12 title('CONTINUOUS TIME PLOT');
13 \quad n=0:0.2:2;
14 x2=\sin(7*n)+\sin(10*n);
15 subplot(1,2,2);
16 plot2d3(n,x2);
17 xlabel('n');
18 ylabel('x(n)');
19 title('DISCRETE TIME PLOT');
```

Scilab code Exa 1.3.a Evaluate the Summations

```
//Example 1.3 (a)
//MAXIMA SCILAB TOOLBOX REQUIRED FOR THIS PROGRAM
//Calculate Following Summations
clear;
clc;
sclc;
syms n;
X = symsum (sin(2*n),n,2,2);
//Display the result in command window
disp (X,"The Value of summation comes out to be:");
```

Scilab code Exa 1.3.b Evaluate the Summations

```
//Example 1.3 (b)
//MAXIMA SCILAB TOOLBOX REQUIRED FOR THIS PROGRAM
//Calculate Following Summations
clear;
clc;
sclc;
syms n;
X = symsum (%e^(2*n),n ,0, 0);
//Display the result in command window
disp (X,"The Value of summation comes out to be:");
```

Scilab code Exa 1.4.a Check for Energy or Power Signals

```
1 //Example 1.4 (a)
2 //MAXIMA SCILAB TOOLBOX REQUIRED FOR THIS PROGRAM
3 //Find Energy and Power of Given Signals
4 clear;
5 clc;
6 close;
7 syms n N;
8 x = (1/3)^n;
9 E= symsum (x^2, n, 0, %inf);
10 //Display the result in command window
11 disp (E, "Energy:");
12 p=(1/(2*N+1))*symsum (x^2,n,0,N);
13 P=limit(p,N,%inf);
14 disp (P, "Power:");
15 //The Energy is Finite and Power is 0. Therefore the
      given signal is an Energy Signal
```

Scilab code Exa 1.4.d Check for Energy or Power Signals

```
1 //Example 1.4 (d)
```

```
2 //MAXIMA SCILAB TOOLBOX REQUIRED FOR THIS PROGRAM
3 //Find Energy and Power of Given Signals
4 clear;
5 clc;
6 close;
7 syms n N;
8 x = %e^{(2*n)};
9 E = symsum (x^2, n, 0, %inf);
10 //Display the result in command window
11 disp (E, "Energy:");
12 p=(1/(2*N+1))*symsum (x^2,n,0,N);
13 P=limit(p,N,%inf);
14 disp (P, "Power:");
15 //The Energy and Power is infinite. Therefore the
     given signal is an neither Energy Signal nor
     Power Signal
```

Scilab code Exa 1.5.a Determining Periodicity of Signal

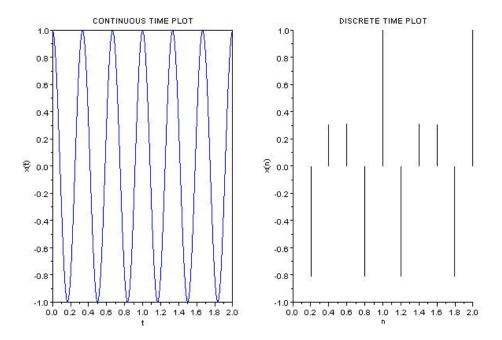


Figure 1.3: Determining Periodicity of Signal

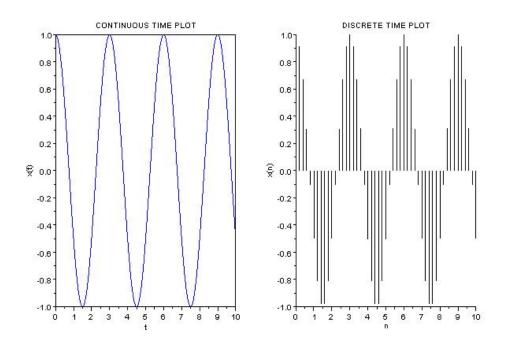


Figure 1.4: Determining Periodicity of Signal

```
14  x2=exp(%i*6*%pi*n);
15  subplot(1,2,2);
16  plot2d3(n,x2);
17  xlabel('n');
18  ylabel('x(n)');
19  title('DISCRETE TIME PLOT');
20  // Hence Given Signal is Periodic with N=1
```

Scilab code Exa 1.5.c Determining Periodicity of Signal

```
1 //Example 1.5 (c)
```

```
2 //To Determine Whether Given Signal is Periodic or
     not
3 clear;
4 clc;
5 close;
6 t=0:0.01:10;
7 x1 = \cos(2*\%pi*t/3);
8 subplot(1,2,1);
9 plot(t,x1);
10 xlabel('t');
11 ylabel('x(t)');
12 title('CONTINUOUS TIME PLOT');
13 n=0:0.2:10;
14 x2 = \cos(2*\%pi*n/3);
15 subplot(1,2,2);
16 plot2d3(n,x2);
17 xlabel('n');
18 ylabel('x(n)');
19 title('DISCRETE TIME PLOT');
20 //Hence Given Signal is Periodic with N=3
```

Scilab code Exa 1.5.d Determining Periodicity of Signal

```
1 //Example 1.5 (d)
2 //To Determine Whether Given Signal is Periodic or not
3 clear;
4 clc;
5 close;
6 t=0:0.01:50;
7 x1=cos(%pi*t/3)+cos(3*%pi*t/4);
8 subplot(1,2,1);
9 plot(t,x1);
```

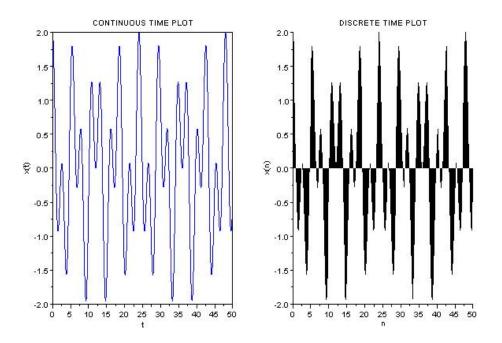


Figure 1.5: Determining Periodicity of Signal

Scilab code Exa 1.11 Stability of the System

```
//Example 1.11
//MAXIMA SCILAB TOOLBOX REQUIRED FOR THIS PROGRAM
//Testing Stability of Given System
clear;
clc;
close;
syms n;
x = (1/2)^n
X = symsum (x,n,0, %inf);
//Display the result in command window
disp (X, "Summation is:");
disp('Hence Summation < infinity. Given System is Stable');</pre>
```

Scilab code Exa 1.12 Convolution Sum of Two Sequences

```
1 //Example 1.12
2 //Program to Compute convolution of given sequences
3 //x(n)=[3 2 1 2], h(n)=[1 2 1 2];
```

```
4 clear;
5 clc;
6 close;
7 x=[3 2 1 2];
8 h=[1 2 1 2];
9 y=convol(x,h);
10 disp(y);
```

Scilab code Exa 1.13 Convolution of Two Signals

```
1 //Example 1.13
2 //Program to Compute convolution of given sequences
3 //x(n)=[1 2 1 1], h(n)=[1 -1 1 -1];
4 clear;
5 clc;
6 close;
7 x=[1 2 1 1];
8 h=[1 -1 1 -1];
9 y=convol(x,h);
10 disp(round(y));
```

Scilab code Exa 1.18 Cross Correlation of Two Sequences

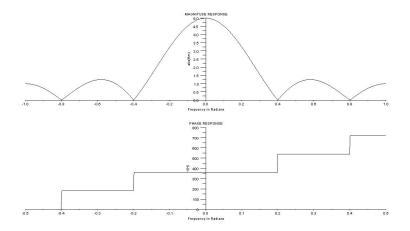


Figure 1.6: Plot Magnitude and Phase Response

```
10 y=convol(x,h1);
11 disp(round(y));
```

Scilab code Exa 1.19 Determination of Input Sequence

```
1 //Example 1.19
2 //To find input x(n)
3 //h(n)=[1 2 1], y(n)=[1 5 10 11 8 4 1]
4 clear;
5 clc;
6 close;
7 z=%z;
8 a=z^6+5*(z^(5))+10*(z^(4))+11*(z^(3))+8*(z^(2))+4*(z^(1))+1;
9 b=z^6+2*z^(5)+1*z^(4);
10 x =ldiv(a,b,5);
11 disp (x,"x(n)=");
```

Scilab code Exa 1.32.a Plot Magnitude and Phase Response

```
1 //Example 1.32
2 //Program to Plot Magnitude and Phase Responce
3 clear;
4 clc;
5 close;
6 \text{ w=-\%pi:0.01:\%pi;}
7 H=1+2*\cos(w)+2*\cos(2*w);
8 //caluculation of Phase and Magnitude of H
9 [phase_H,m]=phasemag(H);
10 Hm = abs (H);
11 a=gca();
12 subplot (2,1,1);
13 a.y_location="origin";
14 plot2d(w/%pi,Hm);
15 xlabel('Frequency in Radians')
16 ylabel('abs(Hm)');
17 title('MAGNITUDE RESPONSE');
18 subplot(2,1,2);
19 a=gca();
20 a.x_location="origin";
21 a.y_location="origin";
22 plot2d(w/(2*%pi),phase_H);
23 xlabel('Frequency in Radians');
24 ylabel('<(H)');
25 title('PHASE RESPONSE');
```

Scilab code Exa 1.37 Sketch Magnitude and Phase Response

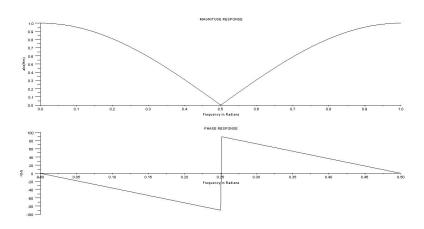


Figure 1.7: Sketch Magnitude and Phase Response

```
1 //Example 1.37
2 //Program to Plot Magnitude and Phase Responce
3 //y(n) = 1/2[x(n)+x(n-2)]
4 clear;
5 clc;
6 close;
7 w=0:0.01:\%pi;
8 H = (1 + \cos(2*w) - \%i * \sin(2*w))/2;
9 //caluculation of Phase and Magnitude of H
10 [phase_H,m]=phasemag(H);
11 Hm = abs(H);
12 a=gca();
13 subplot(2,1,1);
14 a.y_location="origin";
15 plot2d(w/%pi,Hm);
16 xlabel ('Frequency in Radians')
17 ylabel('abs(Hm)');
18 title('MAGNITUDE RESPONSE');
19 subplot(2,1,2);
20 a=gca();
21 a.x_location="origin";
22 a.y_location="origin";
23 plot2d(w/(2*%pi),phase_H);
```

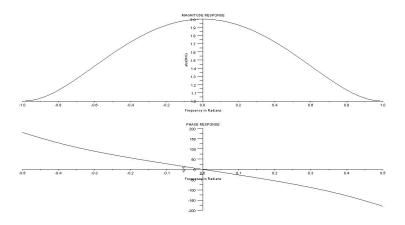


Figure 1.8: Plot Magnitude and Phase Response

```
24 xlabel('Frequency in Radians');
25 ylabel('<(H)');
26 title('PHASE RESPONSE');</pre>
```

Scilab code Exa 1.38 Plot Magnitude and Phase Response

```
//Example 1.38
//Program to Plot Magnitude and Phase Responce
//0.5 delta(n)+delta(n-1)+0.5 delta(n-2)

clear;
clc;
close;
w=-%pi:0.01:%pi;
H=0.5+exp(-%i*w)+0.5*exp(-%i*w);
//caluculation of Phase and Magnitude of H
[phase_H,m]=phasemag(H);
Hm=abs(H);
a=gca();
subplot(2,1,1);
```

```
14 a.y_location="origin";
15 plot2d(w/%pi,Hm);
16 xlabel('Frequency in Radians')
17 ylabel('abs(Hm)');
18 title('MAGNITUDE RESPONSE');
19 subplot(2,1,2);
20 a=gca();
21 a.x_location="origin";
22 a.y_location="origin";
23 plot2d(w/(2*%pi),phase_H);
24 xlabel('Frequency in Radians');
25 ylabel('<(H)');
26 title('PHASE RESPONSE');</pre>
```

Scilab code Exa 1.45 Filter to Eliminate High Frequency Component

```
1 //Example 1.45
2 / /
3 clear;
4 clc;
5 close;
6 t=0:0.01:10;
7 x=2*\cos(5*t)+\cos(300*t);
8 x1=2*cos(5*t);
9 b = [0.05 0.05];
10 a = [1 -0.9];
11 y=filter(b,a,x);
12 subplot (2,1,1);
13 plot(t,x);
14 xlabel('Time in Sec');
15 ylabel('Amplitude');
16 subplot (2,1,2);
17 plot(t,y);
```

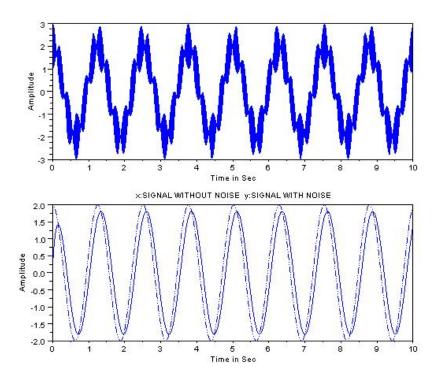


Figure 1.9: Filter to Eliminate High Frequency Component

```
18 subplot(2,1,2);
19 plot(t,x1,':');
20 title('x:SIGNAL WITHOUT NOISE y:SIGNAL WITH NOISE')
   ;
21 xlabel('Time in Sec');
22 ylabel('Amplitude');
```

Scilab code Exa 1.57.a Discrete Convolution of Sequences

Scilab code Exa 1.61 Fourier Transform

```
//Example 1.61
//MAXIMA SCILAB TOOLBOX REQUIRED FOR THIS PROGRAM
//Fourier transform of (3) n u(n)

clear;
clc;
close;
syms n;
x = (3) n;
X = symsum (x,n,0, %inf)
//Display the result in command window
```

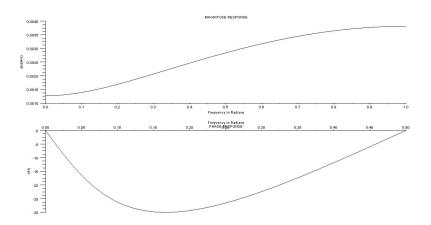


Figure 1.10: Frequency Response of LTI System

```
11 disp (X,"The Fourier Transform does not exit as x(n) is not absolutely summable and approaches infinity i.e.");
```

Scilab code Exa 1.62 Fourier Transform

```
//Example 1.62
//MAXIMA SCILAB TOOLBOX REQUIRED FOR THIS PROGRAM
//Fourier transform of (0.8) ^ |n| u(n)

clear;
clc;
close;
syms w n;
X = symsum ((0.8) ^ n*%e ^ (%i*w*n), n , 1, %inf ) + symsum ((0.8) ^ n*%e ^ (-%i*w*n), n , 0, %inf )
// Display the result in command window
disp (X, "The Fourier Transform comes out to be:");
```

Scilab code Exa 1.64.a Frequency Response of LTI System

```
1 //Example 1.64 (a)
2 //Program to Calculate Plot Magnitude and Phase
      Responce
3 clear;
4 clc;
5 close;
6 \text{ w=0:0.01:\%pi};
7 H=1/(1-0.5*\%e^{(-\%i*w)});
8 //caluculation of Phase and Magnitude of H
9 [phase_H,m]=phasemag(H);
10 Hm = abs(H);
11 a=gca();
12 subplot (2,1,1);
13 a.y_location="origin";
14 plot2d(w/%pi,Hm);
15 xlabel('Frequency in Radians')
16 ylabel('abs(Hm)');
17 title('MAGNITUDE RESPONSE');
18 subplot(2,1,2);
19 a=gca();
20 a.x_location="origin";
21 a.y_location="origin";
22 plot2d(w/(2*%pi),phase_H);
23 xlabel('Frequency in Radians');
24 \text{ ylabel}('<(H)');
25 title('PHASE RESPONSE');
```

Scilab code Exa 1.64.c Frequency Response of LTI System

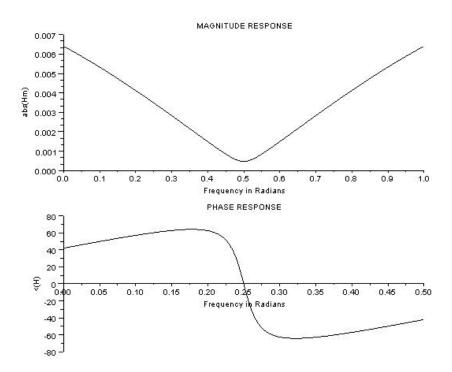


Figure 1.11: Frequency Response of LTI System

```
1 //Example 1.64 (c)
2 //Program to Calculate Plot Magnitude and Phase
      Responce
3 clear;
4 clc;
5 close;
6 \text{ w=0:0.01:\%pi};
7 H=1/(1-0.9*\%i*\%e^{-(-\%i*w)});
8 //caluculation of Phase and Magnitude of H
9 [phase_H,m]=phasemag(H);
10 Hm = abs (H);
11 a=gca();
12 subplot(2,1,1);
13 a.y_location="origin";
14 plot2d(w/%pi,Hm);
15 xlabel('Frequency in Radians')
16 ylabel('abs(Hm)');
17 title('MAGNITUDE RESPONSE');
18 subplot(2,1,2);
19 a=gca();
20 a.x_location="origin";
21 a.y_location="origin";
22 plot2d(w/(2*%pi),phase_H);
23 xlabel('Frequency in Radians');
24 \text{ ylabel}('<(H)');
25 title('PHASE RESPONSE');
```

Chapter 2

THE Z TRANSFORM

Scilab code Exa 2.1 z Transform and ROC of Causal Sequence

```
//Example 2.1
//Z- transform of [1 0 3 -1 2]
clear;
clc;
close;
function[za]=ztransfer(sequence,n)
z=poly(0,'z','r')
z=poly(0,'z','r')
z=sequence*(1/z)^n'
endfunction
x1=[1 0 3 -1 2];
n=0:length(x1)-1;
zz=ztransfer(x1,n);
//Display the result in command window
disp (zz,"Z-transform of sequence is:");
disp('ROC' is the entire plane except z = 0');
```

Scilab code Exa 2.2 z Transform and ROC of Anticausal Sequence

```
//Example 2.2
//Z- transform of [-3 -2 -1 0 1]
clear;
clc;
close;
function[za]=ztransfer(sequence,n)
z=poly(0,'z','r')
za=sequence*(1/z)^n'
endfunction
x1=[-3 -2 -1 0 1];
n=-(length(x1)-1):0;
zz=ztransfer(x1,n);
//Display the result in command window
disp (zz,"Z-transform of sequence is:");
disp('ROC is the entire plane except z = %inf');
```

Scilab code Exa 2.3 z Transform of the Sequence

```
1 / Example 2.3
2 //Z- transform of [2 -1 3 2 1 0 2 3 -1]
3 clear;
4 clc;
5 close;
6 function[za]=ztransfer(sequence,n)
7 z=poly(0, 'z', 'r')
8 za=sequence*(1/z)^n'
9 endfunction
10 x1 = [2 -1 3 2 1 0 2 3 -1];
11 n = -4:4;
12 zz=ztransfer(x1,n);
13 //Display the result in command window
14 disp (zz, "Z-transform of sequence is:");
15 disp('ROC is the entire plane except z = 0 and z =
     %inf');
```

Scilab code Exa 2.4 z Transform and ROC of the Signal

```
//Example 2.4
//MAXIMA SCILAB TOOLBOX REQUIRED FOR THIS PROGRAM
//Z- transform of a^n u(n)
clear;
clc;
close;
syms a n z;
x = a^n
X = symsum (x*(z^(-n)),n ,0, %inf);
//Display the result in command window
disp (X,"Z-transform of a^n u(n) with is:");
disp('ROC is the Region mod(z) > a')
```

Scilab code Exa 2.5 z Transform and ROC of the Signal

```
//Example 2.5
//MAXIMA SCILAB TOOLBOX REQUIRED FOR THIS PROGRAM
//Z- transform of -b^n u(-n-1)

clear;
clc;
close;
syms b n z;
x = b^n
X = symsum (x*(z^(-n)),n ,0, %inf);
//Display the result in command window
disp (X,"Z-transform of b^n u(n) with is:");
disp('ROC is the Region mod(z) < b')</pre>
```

Scilab code Exa 2.6 Stability of the System

```
//Example 2.6
//MAXIMA SCILAB TOOLBOX REQUIRED FOR THIS PROGRAM
//Z- transform of 2^n u(n)

clear;
clc;
close;
syms n z;
x = (2) ^n
X = symsum (x*(z^(-n)), n ,0, %inf);
//Display the result in command window
disp (X,"Z-transform of 2^n u(n) is:");
disp('ROC is the Region mod(z) > 2');
```

Scilab code Exa 2.7 z Transform of the Signal

```
//Example 2.7
//MAXIMA SCILAB TOOLBOX REQUIRED FOR THIS PROCRAM
//Z- transform of [3(3^n)-4(2)^n] u(n)

clear;
clc;
close;
syms n z;
x1 = (3) ^(n);
X1= symsum (3* x1 *(z^(-n)),n ,0, %inf);
x2 = (4) ^(n);
X2= symsum (4* x2 *(z^(-n)),n ,0, %inf);
X2 = (X1 -X2);
//Display the result in command window
disp (X,"Z-transform of [3(3^n)-4(2)^n] u(n) is:");
```

Scilab code Exa 2.8.a z Transform of the Signal

```
1 //Example 2.8 (a)
2 //MAXIMA SCILAB TOOLBOX REQUIRED FOR THIS PROGRAM
3 //Z transform of cos(Wo*n)
4 clc;
5 syms Wo n z;
6 x1=exp(sqrt(-1)*Wo*n);
7 X1=symsum(x1*(z^-n),n,0,%inf);
8 x2=exp(-sqrt(-1)*Wo*n);
9 X2=symsum(x2*(z^-n),n,0,%inf);
10 X=(X1+X2)/2;
11 disp(X,'X(z)=');
```

Scilab code Exa 2.9 z Transform of the Sequence

```
1 //Example 2.9
2 //MAXIMA SCILAB TOOLBOX REQUIRED FOR THIS PROGRAM
3 //Z- transform of (1/3) n u(n-1)
4 clear;
5 clc;
6 close;
7 syms n z;
8 x = (1/3) n;
9 X= (1/z)*symsum (x*(z^(-n)), n, 0, %inf);
10 //Display the result in command window
11 disp (X, "Z-transform of (1/3) n u(n-1) is:");
```

Scilab code Exa 2.10 z Transform Computation

```
1 //Example 2.10
2 //MAXIMA SCILAB TOOLBOX REQUIRED FOR THIS PROGRAM
3 //Z transform of r^n.cos(Wo*n)
4 clc;
5 syms r Wo n z;
```

```
6  x1=(r^n)*exp(sqrt(-1)*Wo*n);
7  X1=symsum(x1*(z^-n),n,0,%inf);
8  x2=(r^n)*exp(-sqrt(-1)*Wo*n);
9  X2=symsum(x2*(z^-n),n,0,%inf);
10  X=(X1+X2)/2;
11  disp(X,'X(z)=');
```

Scilab code Exa 2.11 z Transform of the Sequence

```
//Example 2.11
//MAXIMA SCILAB TOOLBOX REQUIRED FOR THIS PROGRAM
//Z- transform of n.a^n u(n)

clear;
clc;
close;
syms a n z;
x = (a) ^n;
X = symsum (x*(z^(-n)),n ,0, %inf)

Y = diff (X,z);
//Display the result in command window
disp (Y,"Z-transform of n.a^n u(n) is:");
```

Scilab code Exa 2.13.a z Transform of Discrete Time Signals

```
1 //Example 2.13 (a)
2 //MAXIMA SCILAB TOOLBOX REQUIRED FOR THIS PROGRAM
3 //Z- transform of (-1/5)^n u(n) + 5(1/2)^n (-n) u(-n-1)
4 clear;
5 clc;
6 close;
7 syms n z;
8 x1 = (-1/5)^n;
9 X1= symsum (x1 *(z^(-n)), n ,0, %inf);
```

Scilab code Exa 2.13.b z Transform of Discrete Time Signals

```
1 //Example 2.13 (b)
2 //MAXIMA SCILAB TOOLBOX REQUIRED FOR THIS PROGRAM
3 //Z transform
4 clc;
5 syms n z k;
6 x1=1;
7 X1=symsum(x1*z^(-n),n,0,0);
8 x2=1;
9 X2=symsum(x2*z^(-n),n,1,1);
10 x3=1;
11 X3=symsum(x3*z^(-n),n,2,2);
12 X=0.5*X1+X2-1/3*X3;
13 disp(X,'X(z)=');
```

Scilab code Exa 2.13.c z Transform of Discrete Time Signals

```
1 //Example 2.13 (c)
2 //MAXIMA SCILAB TOOLBOX REQUIRED FOR THIS PROGRAM
3 //Z- transform of u(n-2)
4 clear;
5 clc;
6 close;
7 syms n z;
8 x =1;
```

```
9 X = (1/(z^2)) * symsum (x*(z^(-n)), n ,0, %inf);
10 // Display the result in command window
11 disp (X,"Z-transform of u(n-2) is:");
```

Scilab code Exa 2.13.d z Transform of Discrete Time Signals

```
1  //Example 2.13 (d)
2  //MAXIMA SCILAB TOOLBOX REQUIRED FOR THIS PROGRAM
3  //Z- transform of (n+0.5)((1/3)^n)u(n)
4  clear;
5  clc;
6  close;
7  syms n z;
8  x1 = (1/3)^n;
9  X11= symsum (x1*(z^(-n)),n,0, %inf)
10  X1 = diff (X11,z);
11  x2 = (1/3)^(n);
12  X2= symsum (0.5* x2 *(z^(-n)),n,0, %inf);
13  X = (X1+X2);
14  //Display the result in command window
15  disp (X,"Z-transform of (n+0.5)((1/3)^n)u(n) is:");
```

Scilab code Exa 2.16 Impulse Response of the System

```
1 //Example 2.16
2 //To find input h(n)
3 //a=[1 2 -4 1], b=[1]
4 clear;
5 clc;
6 close;
7 z=%z;
8 a=z^3+2*(z^(2))-4*(z)+1;
9 b=z^3;
```

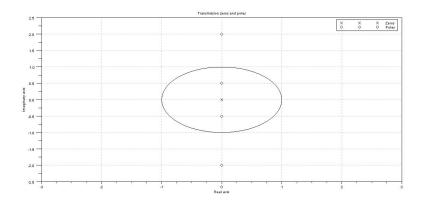


Figure 2.1: Pole Zero Plot of the Difference Equation

```
10 h = ldiv(a,b,4);
11 disp (h,"h(n)=");
```

Scilab code Exa 2.17 Pole Zero Plot of the Difference Equation

```
1 //Example 2.17
2 //To draw the pole-zero plot
3 clear;
4 clc;
5 close;
6 z=%z
7 H1Z=((z)*(z-1))/((z-0.25)*(z-0.5));
8 xset('window',1);
9 plzr(H1Z);
```

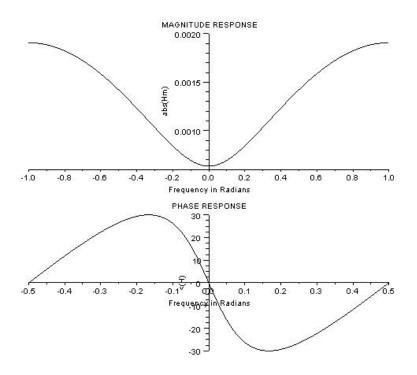


Figure 2.2: Frequency Response of the System

Scilab code Exa 2.19 Frequency Response of the System

```
1 //Example 2.19
2 //Program to Plot Magnitude and Phase Responce
3 clear;
4 clc;
5 close;
6 \text{ w=-\%pi:0.01:\%pi;}
7 H=1/(1-0.5*(\cos(w)-\%i*\sin(w)));
8 //caluculation of Phase and Magnitude of H
9 [phase_H,m]=phasemag(H);
10 Hm = abs(H);
11 a=gca();
12 subplot(2,1,1);
13 a.y_location="origin";
14 plot2d(w/%pi,Hm);
15 xlabel('Frequency in Radians');
16 ylabel('abs(Hm)');
17 title('MAGNITUDE RESPONSE');
18 subplot(2,1,2);
19 a=gca();
20 a.x_location="origin";
21 a.y_location="origin";
22 plot2d(w/(2*%pi),phase_H);
23 xlabel('Frequency in Radians');
24 \text{ ylabel}('<(H)');
25 title('PHASE RESPONSE');
```

Scilab code Exa 2.20.a Inverse z Transform Computation

```
1 //Example 2.10 (a)
2 //To find input h(n)
3 //X(z)=(z+0.2)/((z+0.5)(z-1);
4 clear;
5 clc;
```

```
6 close;
7 z=%z;
8 a=(z+0.5)*(z-1);
9 b=z+0.2;
10 h =ldiv(b,a,4);
11 disp (h,"h(n)=");
```

Scilab code Exa 2.22 Inverse z Transform Computation

```
1 //Example 2.22
2 //To find input x(n)
3 //X(z)=1/(2*z^(-2)+2*z^(-1)+1);
4 clear;
5 clc;
6 close;
7 z=%z;
8 a=(2+2*z+z^2);
9 b=z^2;
10 h =ldiv(b,a,6);
11 disp (h,"First six values of h(n)=");
```

Scilab code Exa 2.23 Causal Sequence Determination

```
1 //Example 2.23
2 //To find input x(n)
3 //X(z)=1/(1-2z^(-1))(1-z^(-1))^2;
4 clear;
5 clc;
6 close;
7 z=%z;
8 a=(z-2)*(z-1)^2;
9 b=z^3;
10 h =ldiv(b,a,6);
```

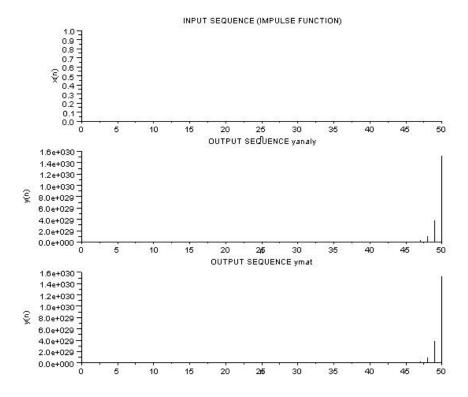


Figure 2.3: Impulse Response of the System

```
11 disp (h, "First six values of h(n)=");
```

Scilab code Exa 2.34 Impulse Response of the System

```
1 //Example 2.34
2 //To plot the impulse responce of the system
          analyically and using scilab
3 clear;
4 clc;
5 close;
6 n=0:1:50;
```

```
7 x = [1, zeros(1,50)];
8 b = [1 2];
9 a = [1 -3 -4];
10 yanaly=6/5*4.^n-1/5*(-1).^n;//Analytical Solution
11 ymat=filter(b,a,x);
12 subplot (3,1,1);
13 plot2d3(n,x);
14 xlabel('n');
15 ylabel('x(n)');
16 title('INPUT SEQUENCE (IMPULSE FUNCTION)');
17 subplot(3,1,2);
18 plot2d3(n, yanaly);
19 xlabel('n');
20 ylabel('y(n)');
21 title('OUTPUT SEQUENCE yanaly');
22 subplot(3,1,3);
23 plot2d3(n,ymat);
24 xlabel('n');
25 ylabel('y(n)');
26 title('OUTPUT SEQUENCE ymat');
27 //As the Analtical Plot matches the Scilab Plot
     hence it is the Responce of the system
```

Scilab code Exa 2.35.a Pole Zero Plot of the System

```
1 //Example 2.35 (a)
2 //To draw the pole-zero plot
3 clear;
4 clc;
5 close;
6 z=%z
7 H1Z=(z)/(z^2-z-1);
8 xset('window',1);
```

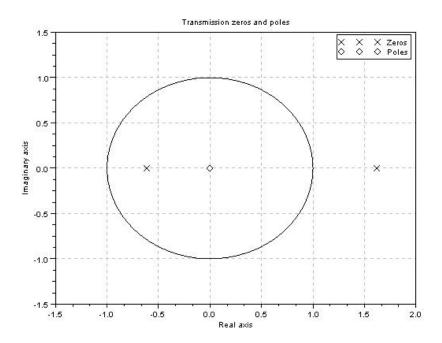


Figure 2.4: Pole Zero Plot of the System

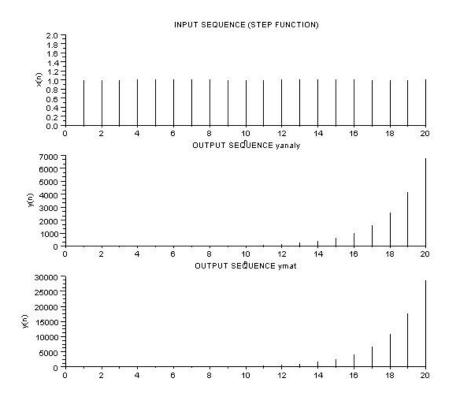


Figure 2.5: Unit Sample Response of the System

```
9 plzr(H1Z);
```

Scilab code Exa 2.35.b Unit Sample Response of the System

```
1 //Example 2.35 (b)
2 //To plot the responce of the system analyically and
      using scilab
3 clear;
4 clc;
5 close;
6 n=0:1:20;
```

```
7 x = ones(1,length(n));
8 b = [0 1];
9 a = [1 -1 -1];
10 yanaly=0.447*(1.618).^n-0.447*(-0.618).^n;//
      Analytical Solution
11 [ymat,zf]=filter(b, a, x);
12 subplot (3,1,1);
13 plot2d3(n,x);
14 xlabel('n');
15 ylabel('x(n)');
16 title('INPUT SEQUENCE (STEP FUNCTION)');
17 subplot(3,1,2);
18 plot2d3(n, yanaly);
19 xlabel('n');
20 ylabel('y(n)');
21 title('OUTPUT SEQUENCE yanaly');
22 subplot (3,1,3);
23 plot2d3(n,ymat,zf);
24 xlabel('n');
25 ylabel('y(n)');
26 title('OUTPUT SEQUENCE ymat');
27 //As the Analtical Plot matches the Scilab Plot
     hence it is the Responce of the system
```

Scilab code Exa 2.38 Determine Output Response

```
1 //Example 2.38
2 //To plot the responce of the system analyically and
      using scilab
3 clear;
4 clc;
5 close;
6 n=0:1:20;
```

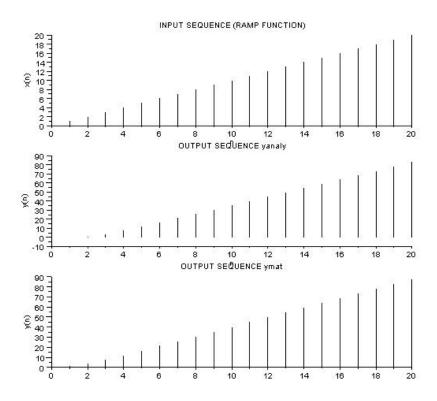


Figure 2.6: Determine Output Response

```
7 x=n;
8 b = [0 1 1];
9 a = [1 -0.7 0.12];
10 yanaly=38.89*(0.4).^n-26.53*(0.3).^n-12.36+4.76*n;
      Analytical Solution
11 ymat=filter(b,a,x);
12 subplot (3,1,1);
13 plot2d3(n,x);
14 xlabel('n');
15 ylabel('x(n)');
16 title('INPUT SEQUENCE (RAMP FUNCTION)');
17 subplot(3,1,2);
18 plot2d3(n, yanaly);
19 xlabel('n');
20 ylabel('y(n)');
21 title('OUTPUT SEQUENCE yanaly');
22 subplot (3,1,3);
23 plot2d3(n,ymat);
24 xlabel('n');
25 ylabel('y(n)');
26 title('OUTPUT SEQUENCE ymat');
27 //As the Analtical Plot matches the Scilab Plot
     hence it is the Responce of the system
```

Scilab code Exa 2.40 Input Sequence Computation

```
1 //Example 2.40
2 //To find input x(n)
3 //h(n)=1 2 3 2, y(n)=[1 3 7 10 10 7 2]
4 clear;
5 clc;
6 close;
7 z=%z;
8 a=z^6+3*(z^(5))+7*(z^(4))+10*(z^(3))+10*(z^(2))+7*(z^(1))+2;
```

```
9 b=z^6+2*z^(5)+3*z^(4)+2*z^(3);

10 x =ldiv(a,b,4);

11 disp (x,"x(n)=");
```

Scilab code Exa 2.41.a z Transform of the Signal

```
//Example 2.41 (a)
//MAXIMA SCILAB TOOLBOX REQUIRED FOR THIS PROGRAM
//Z- transform of n.(-1)^n u(n)

clear;
clc;
close;
syms a n z;
x = (-1) ^n;
X = symsum (x*(z^(-n)), n ,0, %inf)
Y = diff (X,z);
//Display the result in command window
disp (Y,"Z-transform of n.(-1)^n u(n) is:");
```

Scilab code Exa 2.41.b z Transform of the Signal

```
//Example 2.41 (b)
//MAXIMA SCILAB TOOLBOX REQUIRED FOR THIS PROGRAM
//Z- transform of n^2 u(n)
clear;
clc;
close;
syms n z;
x = 1;
X = symsum (x*(z^(-n)), n ,0, %inf)
Y = diff(diff (X,z),z);
//Display the result in command window
disp (Y,"Z-transform of n^2 u(n) is:");
```

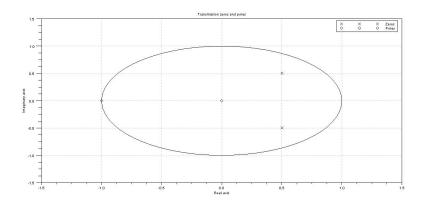


Figure 2.7: Pole Zero Pattern of the System

Scilab code Exa 2.41.c z Transform of the Signal

```
1 //Example 2.41 (c)
2 //MAXIMA SCILAB TOOLBOX REQUIRED FOR THIS PROGRAM
3 //Z transform of (-1)^n.cos(%pi/3*n)
4 clc;
5 syms n z;
6 Wo=%pi/3;
7 x1=exp(sqrt(-1)*Wo*n);
8 X1=(-1)^n*symsum(x1*(z^-n),n,0,%inf);
9 x2=exp(-sqrt(-1)*Wo*n);
10 X2=(-1)^n*symsum(x2*(z^-n),n,0,%inf);
11 X=(X1+X2)/2;
12 disp(X,'X(z)=');
```

Scilab code Exa 2.45 Pole Zero Pattern of the System

```
1 //Example 2.45
2 //To draw the pole-zero plot
3 clear;
4 clc;
5 close;
6 z=%z
7 H1Z=((z)*(z+1))/(z^2-z+0.5);
8 xset('window',1);
9 plzr(H1Z);
```

Scilab code Exa 2.53.a z Transform of the Sequence

```
1 //Example 2.53 (a)
2 //Z- transform of [3 1 2 5 7 0 1]
3 clear;
4 clc;
5 close;
6 function[za]=ztransfer(sequence,n)
7 z=poly(0,'z','r')
8 za=sequence*(1/z)^n'
9 endfunction
10 x1=[3 1 2 5 7 0 1];
11 n=-3:3;
12 zz=ztransfer(x1,n);
13 //Display the result in command window
14 disp (zz,"Z-transform of sequence is:");
```

Scilab code Exa 2.53.b z Transform of the Signal

```
1 //Example 2.53 (b)
2 //MAXIMA SCILAB TOOLBOX REQUIRED FOR THIS PROGRAM
```

```
3 //Z transform of delta(n)
4 clc;
5 syms n z;
6 x=1;
7 X=symsum(x*z^(-n),n,0,0);
8 disp(X,'X(z)=');
```

Scilab code Exa 2.53.c z Transform of the Signal

```
//Example 2.53 (c)
//MAXIMA SCILAB TOOLBOX REQUIRED FOR THIS PROGRAM
//Z transform of delta(n)

clc;
syms n z k;
x=1;
X=symsum(x*z^(-n),n,k,k);
disp(X,'X(z)=');
```

Scilab code Exa 2.53.d z Transform of the Signal

```
//Example 2.53 (d)
//Example 2.53 (d)
//MAXIMA SCILAB TOOLBOX REQUIRED FOR THIS PROGRAM
//Z transform of delta(n)
clc;
syms n z kc;
x=1;
X=symsum(x*z^(-n),n,-k,-k);
disp(X,'X(z)=');
```

Scilab code Exa 2.54 z Transform of Cosine Signal

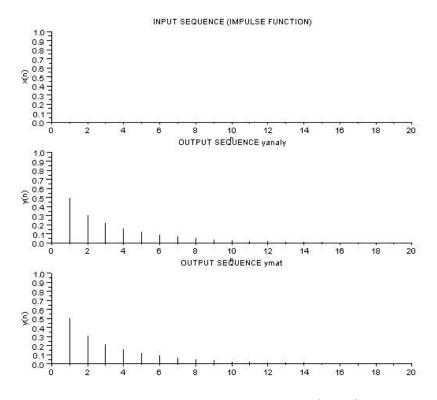


Figure 2.8: Impulse Response of the System

```
1 //Example 2.54
2 //MAXIMA SCILAB TOOLBOX REQUIRED FOR THIS PROGRAM
3 //Z transform of cos(Wo*n)
4 clc;
5 syms Wo n z;
6 x1=exp(sqrt(-1)*Wo*n);
7 X1=symsum(x1*(z^-n),n,0,%inf);
8 x2=exp(-sqrt(-1)*Wo*n);
9 X2=symsum(x2*(z^-n),n,0,%inf);
10 X=(X1+X2)/2;
11 disp(X, 'X(z)=');
```

Scilab code Exa 2.58 Impulse Response of the System

```
1 //Example 2.58
2 //To plot the response of the system analyically and
       using scilab
3 clear;
4 clc ;
5 close;
6 n=0:1:20;
7 x = [1 zeros(1,20)];
8 b = [1 -0.5];
9 a = [1 -1 3/16];
10 yanaly=0.5*(0.75).^n+0.5*(0.25).^n;//Analytical
      Solution
11 ymat=filter(b,a,x);
12 subplot(3,1,1);
13 plot2d3(n,x);
14 xlabel('n');
15 ylabel('x(n)');
16 title('INPUT SEQUENCE (IMPULSE FUNCTION)');
17 subplot(3,1,2);
18 plot2d3(n, yanaly);
19 xlabel('n');
20 ylabel('y(n)');
21 title('OUTPUT SEQUENCE yanaly');
22 subplot (3,1,3);
23 plot2d3(n,ymat);
24 xlabel('n');
25 ylabel('y(n)');
26 title('OUTPUT SEQUENCE ymat');
27 //As the Analtical Plot matches the Scilab Plot
     hence it is the Responce of the system
```

Chapter 3

THE DISCRETE FOURIER TRANSFORM

Scilab code Exa 3.1 DFT and IDFT

```
1 //Example 3.1
2 //Program to Compute the DFT of a Sequence x[n
     =[1,1,0,0]
3 //and IDFT of a Sequence Y[k] = [1, 0, 1, 0]
4 clear;
5 clc;
6 close;
7 x = [1,1,0,0];
8 //DFT Computation
9 X = fft (x, -1);
10 \quad Y = [1,0,1,0];
11 //IDFT Computation
12 y = fft (Y, 1);
13 // Display sequence X[k] and y[n] in command window
14 disp(X,"X[k]=");
15 disp(y, "y[n]=");
```

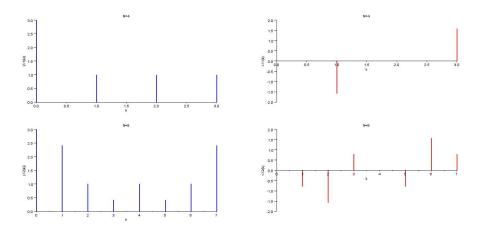


Figure 3.1: DFT of the Sequence

Scilab code Exa 3.2 DFT of the Sequence

```
1 //Example 3.2
2 //Program to Compute the DFT of a Sequence x[n]=1,
     0 \le n \le 2; and 0 otherwise
3 //for N=4 and N=8. Plot Magnitude and phase plots of
       each.
4 clear;
5 clc;
6 close;
7 / N=4
8 \times 1 = [1,1,1,0];
9 //DFT Computation
10 X1 = fft (x1, -1);
11 / N = 8
12 \times 2 = [1,1,1,0,0,0,0,0];
13 //DFT Computation
14 X2 = fft (x2, -1);
15 // Display sequence X1[k] and X2[k] in command window
16 disp(X1,"X1[k]=");
```

```
17 disp(X2,"X2[k]=");
18 // Plots for N=4
19 n1=0:1:3;
20 subplot (2,2,1);
21 \ a = gca \ ();
22 a.y_location = "origin";
23 a.x_location = "origin";
24 plot2d3(n1,abs(X1),2);
25 poly1=a.children(1).children(1);
26 poly1.thickness=2;
27 xtitle('N=4', 'k', '|X1(k)|');
28 subplot(2,2,2);
29 \ a = gca \ ();
30 a.y_location = "origin";
31 a.x_location = "origin";
32 plot2d3(n1,atan(imag(X1),real(X1)),5);
33 poly1=a.children(1).children(1);
34 poly1.thickness=2;
35 xtitle ('N=4', 'k', '<X1(k)');
\frac{36}{\text{Plots}} for N=8
37 \quad n2=0:1:7;
38 subplot (2,2,3);
39 \ a = gca \ ();
40 a.y_location = "origin";
41 a.x_location = "origin";
42 plot2d3(n2,abs(X2),2);
43 poly1=a.children(1).children(1);
44 poly1.thickness=2;
45 xtitle('N=8', 'k', '|X2(k)|');
46 subplot (2,2,4);
47 \ a = gca \ ();
48 a.y_location = "origin";
49 a.x_location = "origin";
50 plot2d3(n2, atan(imag(X2), real(X2)),5);
51 poly1=a.children(1).children(1);
52 poly1.thickness=2;
53 xtitle('N=8', 'k', '< X2(k)');
```

Scilab code Exa 3.3 8 Point DFT

```
1 //Example 3.3
2 //Program to Compute the 8-point DFT of the Sequence
        x[n]=[1,1,1,1,1,1,0,0]
3 clear;
4 clc;
5 close;
6 x = [1,1,1,1,1,1,0,0];
7 //DFT Computation
8 X = fft (x , -1);
9 //Display sequence X[k] in command window
10 disp(X,"X[k]=");
```

Scilab code Exa 3.4 IDFT of the given Sequence

```
1 //Example 3.4
2 //Program to Compute the IDFT of the Sequence X[k
        ]=[5,0,1-j,0,1,0,1+j,0]
3 clear;
4 clc;
5 close;
6 j=sqrt(-1);
7 X = [5,0,1-j,0,1,0,1+j,0]
8 //IDFT Computation
9 x = fft (X , 1);
10 //Display sequences x[n]in command window
11 disp(x,"x[n]=");
```

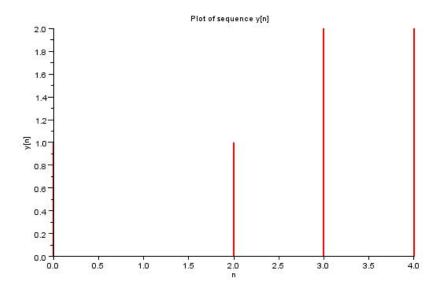


Figure 3.2: Plot the Sequence

Scilab code Exa 3.7 Plot the Sequence

```
1 //Example 3.7
2 //Program to Compute circular convolution of following sequences
3 //x[n]=[1,2,2,1,0]
4 //Y[k]=exp(-j*4*pi*k/5).X[k]
5 clear;
6 clc;
7 close;
8 x=[1,2,2,1,0];
9 X=fft(x,-1);
10 k=0:1:4;
11 j=sqrt(-1);
12 pi=22/7;
```

```
13 H=exp(-j*4*pi*k/5);
14 Y=H.*X;
15 //IDFT Computation
16 y=fft(Y,1);
17 // Display sequence y[n] in command window
18 disp(round(y),"y[n]=");
19 // Plots
20 n=0:1:4;
21 a = gca ();
22 a.y_location ="origin";
23 a.x_location ="origin";
24 plot2d3(n,round(y),5);
25 poly1=a.children(1).children(1);
26 poly1.thickness=2;
27 xtitle('Plot of sequence y[n]','n','y[n]');
```

Scilab code Exa 3.9 Remaining Samples

```
1 //Example 3.9
2 //Program to remaining samples of the sequence
3/X(0)=12,X(1)=-1+j3,X(2)=3+j4,X(3)=1-j5,X(4)=-2+j2
     X(5)=6+j3, X(6)=-2-j3, X(7)=10
4 clear;
5 clc;
6 close;
7 j=sqrt(-1);
8 z = 1;
9 X(0+z)=12, X(1+z)=-1+j*3, X(2+z)=3+j*4, X(3+z)=1-j*5, X(3+z)=1-j*5
      (4+z)=-2+j*2, X(5+z)=6+j*3, X(6+z)=-2-j*3, X(7+z)
      =10;
10 for a=9:1:14 do X(a)=conj(X(16-a)), end;
11 // Display the complete sequence X[k] in command
      window
12 disp(X,"X[k]=");
```

Scilab code Exa 3.11 DFT Computation

```
1 //Example 3.11
2 //Program to Compute the 8-point DFT of the
     following sequences
3/x1[n] = [1,0,0,0,0,1,1,1]
4 //x2[n] = [0,0,1,1,1,1,0,0]
5 clear;
6 clc;
7 close;
8 x1=[1,0,0,0,0,1,1,1];
9 x2 = [0,0,1,1,1,1,0,0];
10 //DFT Computation
11 X1 = fft (x1, -1);
12 X2 = fft (x2, -1);
13 //Display sequences X1[k] and X2[k] in command
     window
14 disp(X1, "X1[k]=");
15 disp(X2,"X2[k]=");
```

Scilab code Exa 3.13 Circular Convolution

```
1 //Example 3.13
2 //Program to Compute circular convolution of following sequences
3 //x1[n]=[1,-1,-2,3,-1]
4 //x2[n]=[1,2,3]
5 clear;
6 clc;
7 close;
8 x1=[1,-1,-2,3,-1];
9 x2=[1,2,3];
```

```
10 //Loop for zero padding the smaller sequence out of
      the two
11    n1=length(x1);
12 n2 = length(x2);
13 n3=n2-n1;
14 \text{ if } (n3 \ge 0) \text{ then}
    x1 = [x1, zeros(1, n3)];
15
16 else
17
    x2=[x2, zeros(1, -n3)];
18 end
19 //DFT Computation
20 X1 = fft(x1, -1);
21 \quad X2 = fft(x2, -1);
22 \quad Y = X1. * X2;
23 //IDFT Computation
24 y = fft(Y,1);
25 // Display sequence y[n] in command window
26 disp(y,"y[n]=");
```

Scilab code Exa 3.14 Circular Convolution

```
1 //Example 3.14
2 //Program to Compute circular convolution of following sequences
3 //x1[n]=[1,2,2,1]
4 //x2[n]=[1,2,3,1]
5 clear;
6 clc;
7 close;
8 x1=[1,2,2,1];
9 x2=[1,2,3,1];
10 //DFT Computation
11 X1=fft(x1,-1);
12 X2=fft(x2,-1);
13 Y=X1.*X2;
```

```
14 //IDFT Computation
15 y=fft(Y,1);
16 //Display sequence y[n] in command window
17 disp(y,"y[n]=");
```

Scilab code Exa 3.15 Determine Sequence x3

```
1 //Example 3.15
2 //Program to Compute x3[n] where X3[k]=X1[k].X2[k]
3 / x1 [n] = [1, 2, 3, 4]
4 / x2 [n] = [1, 1, 2, 2]
5 clear;
6 clc;
7 close;
8 x1 = [1,2,3,4];
9 	 x2 = [1, 1, 2, 2];
10 //DFT Computation
11 X1 = fft(x1, -1);
12 X2 = fft(x2, -1);
13 X3 = X1. * X2;
14 //IDFT Computation
15 x3 = fft(X3,1);
16 // Display sequence x3[n] in command window
17 disp(x3, "x3[n]=");
```

Scilab code Exa 3.16 Circular Convolution

```
1  //Example 3.16
2  //Program to Compute circular convolution of following sequences
3  //x1[n]=[1,1,2,1]
4  //x2[n]=[1,2,3,4]
5  clear;
```

```
6 clc;
7 close;
8 x1=[1,1,2,1];
9 x2=[1,2,3,4];
10 //DFT Computation
11 X1=fft(x1,-1);
12 X2=fft(x2,-1);
13 X3=X1.*X2;
14 //IDFT Computation
15 x3=fft(X3,1);
16 //Display sequence x3[n] in command window
17 disp(x3,"x3[n]=");
```

Scilab code Exa 3.17 Circular Convolution

```
1 //Example 3.17
2 //Program to Compute y[n] where Y[k]=X1[k].X2[k]
3 / x1 [n] = [0, 1, 2, 3, 4]
4 / x2 [n] = [0, 1, 0, 0, 0]
5 clear;
6 clc;
7 close;
8 x1 = [0,1,2,3,4];
9 	 x2 = [0,1,0,0,0];
10 //DFT Computation
11 X1 = fft(x1, -1);
12 X2 = fft(x2, -1);
13 Y = X1. * X2;
14 //IDFT Computation
15 y=round(fft(Y,1));
16 // Display sequence y[n] in command window
17 disp(y,"y[n]=");
```

Scilab code Exa 3.18 Output Response

```
1 //Example 3.18
2 //Program to Compute output response of following
      sequences
3 / x [n] = [1, 2, 3, 1]
4 / h[n] = [1, 1, 1]
5 //(1) Linear Convolution
6 //(2) Circular Convolution
7 //(3) Circular Convolution with zero padding
8 clear;
9 clc;
10 close;
11 x = [1, 2, 3, 1];
12 h = [1, 1, 1];
13 //(1) Linear Convolution Computation
14 ylinear=convol (x,h);
15 //Display Linear Convoluted Sequence y[n] in command
       window
16 disp(ylinear, "ylinear [n]=");
17 //(2) Circular Convolution Computation
18 //Now zero padding in h[n] sequence to make length
      of x[n] and h[n] equal
19 h1 = [h, zeros(1,1)];
20 //Now Performing Circular Convolution by DFT method
21 X = fft(x, -1);
22 \text{ H=} fft(h1,-1);
23 Y = X . * H;
24 ycircular=fft(Y,1);
25 // Display Circular Convoluted Sequence y[n] in
      command window
26 disp(ycircular, "ycircular[n]=");
27 //(3) Circular Convolution Computation with zero
      Padding
28 	 x2 = [x, zeros(1,2)];
29 h2=[h, zeros(1,3)];
30 //Now Performing Circular Convolution by DFT method
31 X2 = fft(x2, -1);
```

```
32 H2=fft(h2,-1);
33 Y2=X2.*H2;
34 ycircularp=fft(Y2,1);
35 //Display Circular Convoluted Sequence with zero
        Padding y[n] in command window
36 disp(ycircularp,"ycircularp[n]=");
```

Scilab code Exa 3.20 Output Response

Scilab code Exa 3.21 Linear Convolution

```
7 close;
8 x=[1,2,-1,2,3,-2,-3,-1,1,1,2,-1];
9 h=[1,2];
10 // Linear Convolution Computation
11 y=convol (x,h);
12 // Display Sequence y[n] in command window
13 disp(y,"y[n]=");
```

Scilab code Exa 3.23.a N Point DFT Computation

```
//Example 3.23 (a)
//MAXIMA SCILAB TOOLBOX REQUIRED FOR THIS PROGRAM
//N point DFT of delta(n)

clc;
syms n k N;
x=1;
X=symsum(x*exp(-%i*2*%pi*n*k/N),n,0,0);
disp(X,'X(k)=');
```

Scilab code Exa 3.23.b N Point DFT Computation

```
//Example 3.23 (b)
//MAXIMA SCILAB TOOLBOX REQUIRED FOR THIS PROGRAM
//N point DFT of delta(n-no)
clc;
syms n k N no;
x=1;
X=symsum(x*exp(-%i*2*%pi*n*k/N),n,-no,-no);
disp(X,'X(k)=');
```

Scilab code Exa 3.23.c N Point DFT Computation

```
//Example 3.23 (c)
//MAXIMA SCILAB TOOLBOX REQUIRED FOR THIS PROGRAM
//N point DFT of a^n
clc;
syms a n k N;
x=a^n;
X=symsum(x*exp(-%i*2*%pi*n*k/N),n,0,N-1);
disp(X,'X(k)=');
```

Scilab code Exa 3.23.d N Point DFT Computation

```
1  //Example 3.23 (d)
2  //MAXIMA SCILAB TOOLBOX REQUIRED FOR THIS PROGRAM
3  //N point DFT of x(n)=1, 0<=n<=N/2-1
4  clc;
5  syms n k N;
6  x=1;
7  X=symsum(x*exp(-%i*2*%pi*n*k/N),n,0,(N/2)-1);
8  disp(X,'X(k)=');</pre>
```

Scilab code Exa 3.23.e N Point DFT Computation

```
1  //Example 3.23 (e)
2  //MAXIMA SCILAB TOOLBOX REQUIRED FOR THIS PROGRAM
3  //N point DFT of x(n)=exp(%i*2*%pi*ko*n/N);
4  clc;
5  syms n k N ko;
6  x=exp(%i*2*%pi*ko*n/N);
7  X=symsum(x*exp(-%i*2*%pi*n*k/N),n,0,(N/2)-1);
8  disp(X,'X(k)=');
```

Scilab code Exa 3.23.f N Point DFT Computation

```
//Example 3.23 (f)
//MAXIMA SCILAB TOOLBOX REQUIRED FOR THIS PROGRAM
//N point DFT of x(n)=1, for n=even and 0, for n=odd
clc;
syms n k N;
x=1;//x(2n)=1, for all n
x=xymsum(x*exp(-%i*4*%pi*n*k/N),n,0,N/2-1);
disp(X,'X(k)=');
```

Scilab code Exa 3.24 DFT of the Sequence

Scilab code Exa 3.25 8 Point Circular Convolution

```
1 //Example 3.25
2 //Program to Compute the 8-point Circular
      Convolution of the Sequences
3 / x1 [n] = [1, 1, 1, 1, 0, 0, 0, 0]
4 / x2 [n] = sin (3*pi*n/8)
5 clear;
6 clc;
7 close;
8 x1=[1,1,1,1,0,0,0,0];
9 n=0:1:7;
10 pi=22/7;
11 x2=\sin(3*pi*n/8);
12 //DFT Computation
13 X1 = fft (x1, -1);
14 X2 = fft (x2, -1);
15 // Circular Convolution using DFT
16 \quad Y = X1. * X2;
17 //IDFT Computation
18 y = fft (Y,1);
19 // Display sequence y[n] in command window
20 disp(y,"y[n]=");
```

Scilab code Exa 3.26 Linear Convolution using DFT

```
1  //Example 3.26
2  //Program to Compute the Linear Convolution of the following Sequences
3  //x[n]=[1,-1,1]
4  //h[n]=[2,2,1]
5  clear;
6  clc;
7  close;
8  x=[1,-1,1];
9  h=[2,2,1];
10  //Convolution Computation
```

```
11 y= convol(x,h);
12 //Display sequence y[n] in command window
13 disp(y,"y[n]=");
```

Scilab code Exa 3.27.a Circular Convolution Computation

```
1 //Example 3.27 (a)
2 //Program to Compute the Convolution of the
      following Sequences
3 / x1 [n] = [1, 1, 1]
4 / x2 [n] = [2, -1, 2]
5 clear;
6 clc;
7 close;
8 x1 = [1,1,1];
9 x2 = [2, -1, 2];
10 // Convolution Computation
11 X1 = fft (x1, -1);
12 X2 = fft (x2, -1);
13 Y = X1. * X2;
14 y = fft (Y, 1);
15 // Display Sequence y[n] in command window
16 disp(y,"y[n]=");
```

Scilab code Exa 3.27.b Circular Convolution Computation

```
1  //Example 3.27 (b)
2  //Program to Compute the Convolution of the following Sequences
3  //x1[n]=[1,1,-1,-1,0]
4  //x2[n]=[1,0,-1,0,1]
5  clear;
6  clc ;
```

```
7 close;
8 x1=[1,1,-1,-1,0];
9 x2=[1,0,-1,0,1];
10 //Convolution Computation
11 X1=fft (x1,-1);
12 X2=fft (x2,-1);
13 Y=X1.*X2;
14 y= fft (Y,1);
15 //Display Sequence y[n] in command window
16 disp(y,"y[n]=");
```

Scilab code Exa 3.30 Calculate value of N

```
1 //Example 3.30
2 //Program to Calculate N from given data
3 / \text{fm} = 5000 \text{Hz}
4 //df = 50Hz
5 //t = 0.5 sec
6 clear;
7 clc;
8 close;
9 \text{ fm} = 5000 //\text{Hz}
10 df = 50
             //Hz
11 t=0.5
            //sec
12 N1=2*fm/df;
13 N = 2;
14 while N \le N1, N = N * 2, end
15 // Displaying the value of N in command window
16 disp(N,"N=");
```

Scilab code Exa 3.32 Sketch Sequence

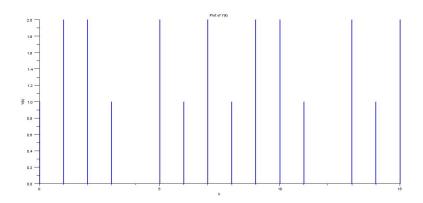


Figure 3.3: Sketch Sequence

```
1 //Example 3.32
2 //Program to plot the result of the given sequence
3 /X[k] = [1,2,2,1,0,2,1,2]
4 //y[n]=x[n/2] for n=even,0 for n=odd
5 clear;
6 clc;
7 close;
8 X = [1, 2, 2, 1, 0, 2, 1, 2];
9 x = fft (X, 1);
10 y = [x(1), 0, x(2), 0, x(3), 0, x(4), 0, x(5), 0, x(6), 0, x(7), 0,
      x(8),0];
11 Y = fft (y, -1);
12 //Display sequence Y[k] and in command window
13 disp(Y, "Y[k]=");
14 // Plotting the sequence Y[k]
15 k=0:1:15;
16 \ a = gca \ ();
17 a.y_location = "origin";
18 a.x_location = "origin";
19 plot2d3(k,Y,2);
20 poly1=a.children(1).children(1);
21 poly1.thickness=2;
22 xtitle('Plot of Y(k)', 'k', 'Y(k)');
```

Scilab code Exa 3.36 Determine IDFT

Chapter 4

THE FAST FOURIER TRANSFORM

Scilab code Exa 4.3 Shortest Sequence N Computation

```
1 / \text{Example } 4.3
2 //Program to calculate shortest sequence N such that
       algorithm B runs //faster than A
3 clear;
4 clc;
5 close;
6 i = 0;
7 N=32; //Given
8 // Calculation of Twiddle factor exponents for each
      stage
9 while 1==1
10 i = i + 1;
11
    N=2^i;
12 A=N^2;
13
   B=5*N*log2(N);
     if A>B then break;
14
15
       end;
16 \, \text{end}
17 disp(N, 'SHORTEST SEQUENCE N = ');
```

Scilab code Exa 4.4 Twiddle Factor Exponents Calculation

```
1 / Example 4.4
2 //Program to calculate Twiddle factor exponents for
      each stage
3 clear;
4 clc;
5 close;
6 N=32; //Given
7 // Calculation of Twiddle factor exponents for each
      stage
  for m=1:5
     disp(m, 'Stage: m = ');
     disp('k = ');
10
     for t=0:(2^{(m-1)}-1)
11
12
       k=N*t/2^m;
       disp(k);
13
14
     end
15 end
```

Scilab code Exa 4.6 DFT using DIT Algorithm

```
1 //Example 4.6
2 //Program to find the DFT of a Sequence x[n
        ]=[1,2,3,4,4,3,2,1]
3 //using DIT Algorithm.
4 clear;
5 clc;
6 close;
7 x = [1,2,3,4,4,3,2,1];
8 //FFT Computation
```

```
9 X = fft (x , -1);
10 disp(X, 'X(z) = ');
```

Scilab code Exa 4.8 DFT using DIF Algorithm

```
1 //Example 4.8
2 //Program to find the DFT of a Sequence x[n
        ]=[1,2,3,4,4,3,2,1]
3 //using DIF Algorithm.
4 clear;
5 clc;
6 close;
7 x = [1,2,3,4,4,3,2,1];
8 //FFT Computation
9 X = fft (x , -1);
10 disp(X, 'X(z) = ');
```

Scilab code Exa 4.9 8 Point DFT of the Sequence

Scilab code Exa 4.10 4 Point DFT of the Sequence

Scilab code Exa 4.11 IDFT of the Sequence using DIT Algorithm

Scilab code Exa 4.12 8 Point DFT of the Sequence

```
1 //Example 4.12
2 //Program to Compute the 8-point DFT of a Sequence
3 //x[n]=[0.5,0.5,0.5,0.5,0.0,0,0] using radix-2 DIT
        Algorithm.
4 clear;
5 clc;
6 close;
7 x=[0.5,0.5,0.5,0.5,0.0,0,0];
8 //FFT Computation
9 X = fft (x , -1);
10 disp(X, 'X(z) = ');
```

Scilab code Exa 4.13 8 Point DFT of the Sequence

```
1 //Example 4.13
2 //Program to Compute the 8-point DFT of a Sequence
3 //x[n]=[0.5,0.5,0.5,0.5,0.0,0,0] using radix-2 DIF
        Algorithm.
4 clear;
5 clc;
6 close;
7 x=[0.5,0.5,0.5,0.5,0,0,0,0];
8 //FFT Computation
9 X = fft (x , -1);
10 disp(X,'X(z) = ');
```

Scilab code Exa 4.14 DFT using DIT Algorithm

```
1 //Example 4.14
2 //Program to Compute the 4-point DFT of a Sequence x [n]=[1,-1,1,-1]
3 //using DIT Algorithm.
4 clear;
```

```
5 clc;
6 close;
7 x=[1,-1,1,-1];
8 //FFT Computation
9 X = fft (x , -1);
10 disp(X, 'X(z) = ');
```

Scilab code Exa 4.15 DFT using DIF Algorithm

Scilab code Exa 4.16.a 8 Point DFT using DIT FFT

```
10 disp(X1, 'X1(k) = ');
```

Scilab code Exa 4.16.b 8 Point DFT using DIT FFT

Scilab code Exa 4.17 IDFT using DIF Algorithm

Scilab code Exa 4.18 IDFT using DIT Algorithm

```
1 //Example 4.18
2 //Program to find the IDFT of the Sequence X[k]=
        [10,-2+j2,-2,-2-j2]
3 //using DIT Algorithm.
4 clear;
5 clc;
6 close;
7 j=sqrt(-1);
8 X = [10,-2+j*2,-2,-2-j*2];
9 //Inverse FFT Computation
10 x = fft (X , 1);
11 disp(x,'x(n) = ');
```

Scilab code Exa 4.19 FFT Computation of the Sequence

```
1 //Example 4.19
2 //Program to Compute the FFT of given Sequence x[n
        ]=[1,0,0,0,0,0,0].
3 clear;
4 clc;
5 close;
6 x = [1,0,0,0,0,0,0];
7 //FFT Computation
8 X = fft (x , -1);
9 disp(X, 'X(z) = ');
```

Scilab code Exa 4.20 8 Point DFT by Radix 2 DIT FFT

Scilab code Exa 4.21 DFT using DIT FFT Algorithm

```
1 //Example 4.21
2 //Program to Compute the DFT of given Sequence
3 //x[n]=[1,-1,-1,-1,1,1,1,-1] using DIT-FFT Algorithm
.
4 clear;
5 clc;
6 close;
7 x = [1,-1,-1,-1,1,1,1,-1];
8 //FFT Computation
9 X = fft (x , -1);
10 disp(X,'X(z) = ');
```

Scilab code Exa 4.22 Compute X using DIT FFT

```
1 //Example 4.22
2 //Program to Compute the DFT of given Sequence
3 //x[n]=2^n and N=8 using DIT-FFT Algorithm.
4 clear;
```

```
5 clc;
6 close;
7 N=8;
8 n=0:1:N-1;
9 x =2^n;
10 //FFT Computation
11 X = fft (x , -1);
12 disp(X, 'X(z) = ');
```

Scilab code Exa 4.23 DFT using DIF FFT Algorithm

```
1 //Example 4.23
2 //Program to Compute the DFT of given Sequence
3 //x[n]=cos(n*pi/2), and N=4 using DIF-FFT Algorithm.
4 clear;
5 clc;
6 close;
7 N=4;
8 pi=22/7;
9 n=0:1:N-1;
10 x = cos(n*pi/2);
11 //FFT Computation
12 X = fft (x , -1);
13 disp(X, 'X(z) = ');
```

Scilab code Exa 4.24 8 Point DFT of the Sequence

```
5 clc;
6 close;
7 x = [0,1,2,3,4,5,6,7];
8 //FFT Computation
9 X = fft (x , -1);
10 disp(X, 'X(z) = ');
```

Chapter 5

INFINITE IMPULSE RESPONSE FILTERS

Scilab code Exa 5.1 Order of the Filter Determination

```
//Example 5.1
//To Find out the order of the filter
clear;
clear;
close;
ap=1;//db
as=30;//db
op=200;//rad/sec
vs=600;//rad/sec
N=log(sqrt((10^(0.1*as)-1)/(10^(0.1*ap)-1)))/log(os/op);
disp(ceil(N),'Order of the filter, N =');
```

Scilab code Exa 5.2 Order of Low Pass Butterworth Filter

```
1 //Example 5.2
```

```
//To Find out the order of a Low Pass Butterworth
    Filter

clear;
close;
ap=3;//db
as=40;//db
fp=500;//Hz
fs=1000;//Hz
op=2*%pi*fp;
se=2*%pi*fs;
N=log(sqrt((10^(0.1*as)-1)/(10^(0.1*ap)-1)))/log(os/op);
disp(ceil(N), 'Order of the filter, N =');
```

Scilab code Exa 5.4 Analog Butterworth Filter Design

```
1 / Example 5.4
2 //To Design an Analog Butterworth Filter
3 clear;
4 clc;
5 close;
6 ap=2; //db
7 as=10; //db
8 op=20; // rad / sec
9 \text{ os=30;} //\text{rad/sec}
10 N = log(sqrt((10^(0.1*as)-1)/(10^(0.1*ap)-1)))/log(os/
11 disp(ceil(N), 'Order of the filter, N = ');
12 s = %s;
13 HS=1/((s^2+0.76537*s+1)*(s^2+1.8477*s+1)); // Transfer
       Function for N=4
14 oc=op/(10^{(0.1*ap)-1})^{(1/(2*ceil(N)))};
15 HS1=horner(HS,s/oc);
16 disp(HS1, 'Normalized Transfer Function, H(s) = ');
```

Scilab code Exa 5.5 Analog Butterworth Filter Design

```
1 / \text{Example } 5.5
2 //To Design an Analog Butterworth Filter
3 clear;
4 clc;
5 close;
6 op=0.2*%pi;
7 os=0.4*\%pi;
8 e1=0.9;
9 11=0.2;
10 epsilon=sqrt(1/(e1^2)-1);
11 lambda=sqrt(1/(11^2)-1);
12 N=log(lambda/epsilon)/log(os/op);
13 disp(ceil(N), 'Order of the filter, N = ');
14 s = %s;
15 HS=1/((s^2+0.76537*s+1)*(s^2+1.8477*s+1)); // Transfer
       Function for N=4
16 oc=op/epsilon^(1/ceil(N));
17 HS1=horner(HS,s/oc);
18 disp(HS1, 'Normalized Transfer Function, H(s) = ');
```

Scilab code Exa 5.6 Order of Chebyshev Filter

```
7 as=16;//db
8 fp=1000;//Hz
9 fs=2000;//Hz
10 op=2*%pi*fp;
11 os=2*%pi*fs;
12 N=acosh(sqrt((10^(0.1*as)-1)/(10^(0.1*ap)-1)))/acosh (os/op);
13 disp(ceil(N), 'Order of the filter, N =');
```

Scilab code Exa 5.7 Chebyshev Filter Design

```
1 / \text{Example } 5.7
2 //To Design an analog Chebyshev Filter with Given
      Specifications
3 clear;
4 clc;
5 close;
6 \text{ os} = 2;
7 \text{ op=1};
8 ap=3; //db
9 as=16; //db
10 e1=1/sqrt(2);
11 11=0.1;
12 epsilon=sqrt(1/(e1^2)-1);
13 lambda=sqrt(1/(l1^2)-1);
14 N=acosh(lambda/epsilon)/acosh(os/op);
15 disp(ceil(N), 'Order of the filter, N = ');
```

Scilab code Exa 5.8 Order of Type 1 Low Pass Chebyshev Filter

```
1 //Example 5.8
2 //To Find out the order of the poles of the Type 1
    Lowpass Chebyshev Filter
```

```
3 clear;
4 clc;
5 close;
6 ap=1;//dB
7 as=40;//dB
8 op=1000*%pi;
9 os=2000*%pi;
10 N=acosh(sqrt((10^(0.1*as)-1)/(10^(0.1*ap)-1)))/acosh (os/op);
11 disp(ceil(N), 'Order of the filter, N =');
```

Scilab code Exa 5.9 Chebyshev Filter Design

Scilab code Exa 5.10 HPF Filter Design with given Specifications

```
1 //Example 5.10
2 //To Design a H.P.F. with given specifications
3 clear;
4 clc;
```

```
5 close;
6 ap=3;//db
7 as=15;//db
8 op=500;//rad/sec
9 os=1000;//rad/sec
10 N=log(sqrt((10^(0.1*as)-1)/(10^(0.1*ap)-1)))/log(os/op);
11 disp(ceil(N), 'Order of the filter, N =');
12 s=%s;
13 HS=1/((s+1)*(s^2+s+1));//Transfer Function for N=3
14 oc=1000//rad/sec
15 HS1=horner(HS,oc/s);
16 disp(HS1, 'Normalized Transfer Function, H(s) =');
```

Scilab code Exa 5.11 Impulse Invariant Method Filter Design

```
1 //Example 5.11
2 //To Design the Filter using Impulse Invarient
      Method
3 clear;
4 clc;
5 close;
6 \text{ s=}\%\text{s};
7 T=1;
8 HS=(2)/(s^2+3*s+2);
9 elts=pfss(HS);
10 disp(elts, 'Factorized HS = ');
11 //The poles comes out to be at -2 and -1
12 p1 = -2;
13 p2 = -1;
14 z = %z;
15 HZ = (2/(1-%e^{(p2*T)*z^{(-1)}}) - (2/(1-%e^{(p1*T)*z^{(-1)}}))
16 \operatorname{disp}(HZ, 'HZ = ');
```

Scilab code Exa 5.12 Impulse Invariant Method Filter Design

Scilab code Exa 5.13 Impulse Invariant Method Filter Design

```
//Example 5.13
//MAXIMA SCILAB TOOLBOX REQUIRED FOR THIS PROGRAM
//To Design the 3rd Order Butterworth Filter using Impulse Invarient Method
clear;
clc;
clc;
close;
s=%s;
HS=1/((s+1)*(s^2+s+1));
pp=ilaplace(HS);//Inverse Laplace
syms n z;
t=1;
X= symsum (pp*(z^(-n)), n ,0, %inf );//Z Transform
```

```
13 disp(X, 'H(z) = ');
```

Scilab code Exa 5.15 Impulse Invariant Method Filter Design

```
1 //Example 5.15
2 //To Design the Filter using Impulse Invarient
      Method
3 clear;
4 clc;
5 close;
6 s = \%s;
7 T = 0.2;
8 HS=10/(s^2+7*s+10);
9 elts=pfss(HS);
10 disp(elts, 'Factorized HS = ');
11 //The poles comes out to be at -5 and -2
12 p1 = -5;
13 p2 = -2;
14 z = \%z;
15 HZ=T*((-3.33/(1-%e^(p1*T)*z^(-1)))+(3.33/(1-%e^(p2*T)))
      )*z^(-1))))
16 disp(HZ, 'HZ = ');
```

Scilab code Exa 5.16 Bilinear Transformation Method Filter Design

```
1  //Example 5.16
2  //To Find out Bilinear Transformation of HS=2/((s+1)
      *(s+2))
3  clear;
4  clc ;
5  close ;
6  s=%s;
7  z=%z;
```

```
8 HS=2/((s+1)*(s+2));

9 T=1;

10 HZ=horner(HS,(2/T)*(z-1)/(z+1));

11 disp(HZ,'H(z) =');
```

Scilab code Exa 5.17 HPF Design using Bilinear Transform

```
1 //Example 5.17
2 //To Design an H.P.F. monotonic in passband using
      Bilinear Transform
3 clear;
4 clc;
5 close;
6 ap=3; //db
7 as=10; //db
8 fp=1000; //Hz
9 fs=350; //Hz
10 f = 5000;
11 T=1/f;
12 \text{ wp=2*\%pi*fp;}
13 \text{ ws}=2*\%\text{pi}*\text{fs};
14 op=2/T*tan(wp*T/2);
15 os=2/T*tan(ws*T/2);
16 N = log(sqrt((10^(0.1*as)-1)/(10^(0.1*ap)-1)))/log(op/
17 disp(ceil(N), 'Order of the filter, N = ');
18 s = \%s;
19 HS=1/(s+1)/Transfer Function for N=1
20 \text{ oc=op}//\text{rad/sec}
21 HS1=horner(HS,oc/s);
22 disp(HS1, 'Normalized Transfer Function, H(s) = ');
23 z = \%z;
24 HZ=horner(HS,(2/T)*(z-1)/(z+1));
25 disp(HZ, 'H(z) =');
```

Scilab code Exa 5.18 Bilinear Transformation Method Filter Design

Scilab code Exa 5.19 Single Pole LPF into BPF Conversion

```
1 //Example 5.19
2 //To Convert a single Pole LPF into BPF
3 clear;
4 clc;
5 close;
6 s=%s;
7 z=%z;
8 HZ=(0.5*(1+z^(-1)))/(1-0.302*z^(-2));
9 T=1;
10 wu=3*%pi/4;
11 wl=%pi/4;
12 wp=%pi/6;
13 k=tan(wp/2)/tan((wu-wl)/2);
14 a=cos((wu+wl)/2)/cos((wu-wl)/2);
```

```
15 transf = -((((k-1)/(k+1))*(z^(-2))) - ((2*a*k/(k+1))*(z^(-1)))+1)/(z^(-2)-(2*a*k/(1+k)*z^(-1))+((k-1)/(k+1)));
16 HZ1 = horner(HZ, transf);
17 disp(HZ1, 'H(z) of B.P.F = ');
```

Scilab code Exa 5.29 Pole Zero IIR Filter into Lattice Ladder Structure

```
1 //Example 5.29
2 //Program to convert given IIR pole-zero Filter into
       Lattice Ladder Structure.
3 clear;
4 clc;
5 close;
                 //Zero Adjust
6 U=1;
7 a(3+U,0+U)=1;
8 a(3+U,1+U)=13/24;
9 a(3+U,2+U)=5/8;
10 a(3+U,3+U)=1/3;
11 a(2+U,0+U)=1; //a(m,0)=1
12 a(2+U,3+U)=1/3;
13 m=3, k=1;
14 a(m-1+U,k+U) = (a(m+U,k+U)-a(m+U,m+U)*a(m+U,m-k+U))
     /(1-a(m+U,m+U)*a(m+U,m+U));
15 m=3, k=2;
16 a(m-1+U,k+U) = (a(m+U,k+U)-a(m+U,m+U)*a(m+U,m-k+U))
     /(1-a(m+U,m+U)*a(m+U,m+U));
17 m=2, k=1;
18 a(m-1+U,k+U) = (a(m+U,k+U)-a(m+U,m+U)*a(m+U,m-k+U))
     /(1-a(m+U,m+U)*a(m+U,m+U));
19 disp('LATTICE COEFFICIENTS');
20 disp(a(1+U,1+U), 'k1');
21 disp(a(2+U,2+U), 'k2');
22 disp(a(3+U,3+U), 'k3');
23 b0=1;
```

```
24 b1=2;

25 b2=2;

26 b3=1;

27 c3=b3;

28 c2=b2-c3*a(3+U,1+U);

29 c1=b1-(c2*a(2+U,1+U)+c3*a(3+U,2+U));

30 c0=b0-(c1*a(1+U,1+U)+c2*a(2+U,2+U)+c3*a(3+U,3+U));

31 disp('LADDER COEFFICIENTS');

32 disp(c0,'c0 =');

33 disp(c1,'c1 =');

34 disp(c2,'c2 =');

35 disp(c3,'c3 =');
```

Chapter 6

FINITE IMPULSE RESPONSE FILTERS

Scilab code Exa 6.1 Group Delay and Phase Delay

```
//Example 6.1
//MAXIMA SCILAB TOOLBOX REQUIRED FOR THIS PROGRAM
//Program to Calculate Group Delay and Phase Delay
//y(n)=0.25x(n)+x(n-1)+0.25x(n-2)
clear;
close;
//w=poly(0,"w");
syms w;
syms w;
theeta=-w;
gd=-diff (theeta,w); //Group Delay
pd=-theeta/w; //Phase Delay
disp(gd,'GROUP DELAY =');
disp(pd,'PHASE DELAY =');
```

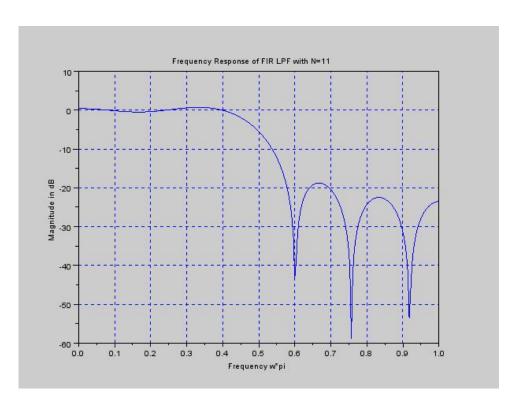


Figure 6.1: LPF Magnitude Response

Scilab code Exa 6.5 LPF Magnitude Response

```
1 / \text{Example } 6.5
2 //Program to Plot Magnitude Responce of ideal L.P.F.
       with wc=0.5*pi
3 / N = 11
4 clear;
5 clc;
6 close;
7 N = 11;
8 U=6;
9 for n=-5+U:1:5+U
10 \text{ if } n==6
11 hd(n)=0.5;
12 else
13 hd(n) = (sin(\%pi*(n-U)/2))/(\%pi*(n-U));
14 end
15 end
16 [hzm ,fr ] = frmag (hd ,256);
17 \text{ hzm\_dB} = 20* \frac{\log 10}{\log 10} \text{ (hzm)./ } \max \text{ (hzm);}
18 figure;
19 plot (2*fr , hzm_dB );
20 = gca ();
21 xlabel ('Frequency w*pi');
22 ylabel ('Magnitude in dB');
23 title ('Frequency Response of FIR LPF with N=11');
24 xgrid (2);
```

Scilab code Exa 6.6 HPF Magnitude Response

```
1 //Example 6.6
2 //Program to Plot Magnitude Responce of ideal H.P.F.
    with wc=0.25*pi
```

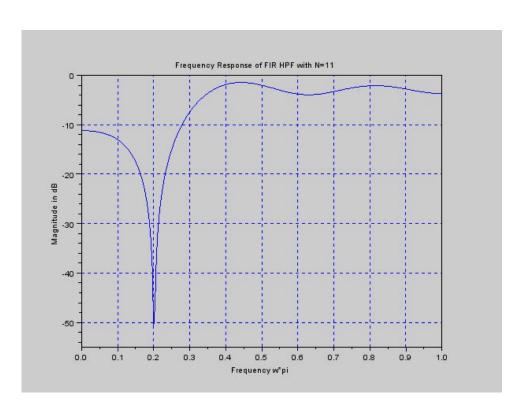


Figure 6.2: HPF Magnitude Response

```
3 / N = 11
4 clear;
5 clc;
6 close;
7 N = 11;
8 U=6;
9 for n=-5+U:1:5+U
10 \text{ if } n=6
11 hd(n) = 0.5;
12 else
13 hd(n) = (sin(\%pi*(n-U)) - sin(\%pi*(n-U)/4))/(\%pi*(n-U));
14 end
15 end
16 [hzm ,fr ] = frmag (hd ,256);
17 \text{ hzm\_dB} = 20* \frac{\log 10}{\log 10} \text{ (hzm)./ } \frac{\max}{\log 10} \text{ (hzm)};
18 figure
19 plot (2*fr , hzm_dB )
20 a = gca ();
21 xlabel ('Frequency w*pi');
22 ylabel ('Magnitude in dB');
23 title ('Frequency Response of FIR HPF with N=11');
24 xgrid (2);
```

Scilab code Exa 6.7 BPF Magnitude Response

```
1 //Example 6.7

2 //Program to Plot Magnitude Responce of ideal B.P.F. with

3 //wc1=0.25*pi and wc2=0.75*pi

4 //N=11

5 clear;

6 clc;

7 close;
```

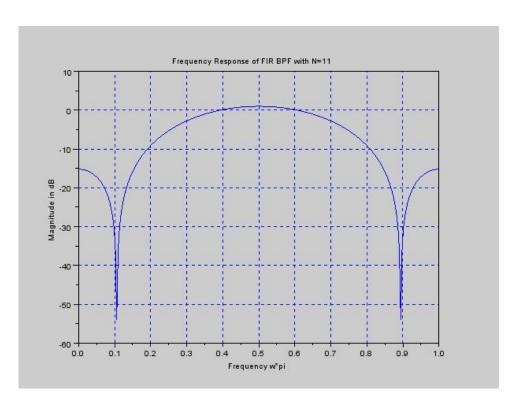


Figure 6.3: BPF Magnitude Response

```
8 N = 11;
9 U=6;
10 for n=-5+U:1:5+U
11 if n == 6
12 hd(n)=0.5;
13 else
14 hd(n) = \frac{\sin(\pi + 3*(n-U)/4) - \sin(\pi + (n-U)/4)}{(\pi + 3*(n-U)/4) - \sin(\pi + (n-U)/4)}
       U));
15 end
16 \text{ end}
17 [hzm ,fr ] = frmag (hd ,256);
18 \text{ hzm\_dB} = 20* \frac{\log 10}{\log 10} \text{ (hzm)./ max (hzm)};
19 figure
20 plot (2*fr , hzm_dB )
21 = gca ();
22 xlabel ('Frequency w*pi');
23 ylabel ('Magnitude in dB');
24 title ('Frequency Response of FIR BPF with N=11');
25 xgrid (2);
```

Scilab code Exa 6.8 BRF Magnitude Response

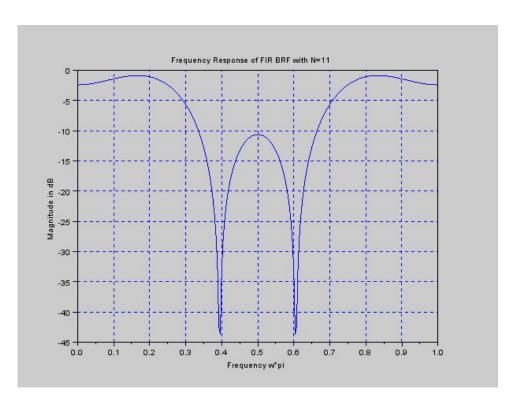


Figure 6.4: BRF Magnitude Response

```
11 if n = 6
12 hd(n)=0.5;
13 else
14 hd(n) = (\sin(\%pi*(n-U)) + \sin(\%pi*(n-U)/3) - \sin(\%pi*2*(n-U)/3)
      U)/3))/(%pi*(n-U));
15 end
16 \text{ end}
17 [hzm, fr] = frmag (hd, 256);
18 \text{ hzm\_dB} = 20* \frac{\log 10}{\log 10} \text{ (hzm)./ } \max \text{ (hzm);}
19 figure
20 plot (2*fr , hzm_dB )
21 a = gca ();
22 xlabel ('Frequency w*pi');
23 ylabel ('Magnitude in dB');
24 title ('Frequency Response of FIR BRF with N=11');
25 xgrid (2);
```

Scilab code Exa 6.9.a HPF Magnitude Response using Hanning Window

```
1  //Example 6.9a
2  //Program to Plot Magnitude Responce of ideal H.P.F.
3  //using Hanning Window
4  //wc1=0.25*pi
5  //N=11
6  clear;
7  clc ;
8  close ;
9  N=11;
10  U=6;
11  h_hann=window('hn',N);
12  for n=-5+U:1:5+U
13  if n==6
14  hd(n)=0.75;
```

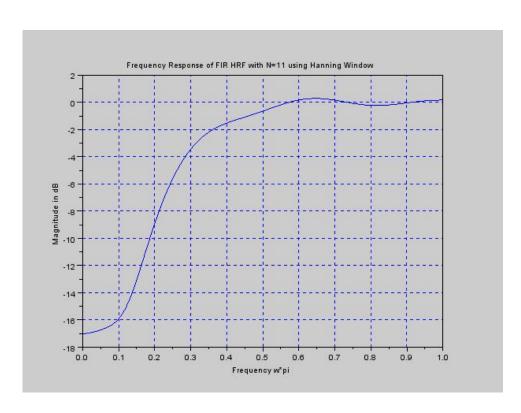


Figure 6.5: HPF Magnitude Response using Hanning Window

```
15 else
16 hd(n)=(sin(%pi*(n-U))-sin(%pi*(n-U)/4))/(%pi*(n-U));
17 end
18 h(n)=h_hann(n)*hd(n);
19 end
20 [hzm ,fr ]= frmag (h ,256);
21 hzm_dB = 20* log10 (hzm)./ max (hzm );
22 figure
23 plot (2*fr , hzm_dB )
24 a= gca ();
25 xlabel ('Frequency w*pi');
26 ylabel ('Magnitude in dB');
27 title ('Frequency Response of FIR HRF with N=11 using Hanning Window');
28 xgrid (2);
```

Scilab code Exa 6.9.b HPF Magnitude Response using Hamming Window

```
1 //Example 6.9b
2 //Program to Plot Magnitude Responce of ideal H.P.F.
3 //using Hamming Window
4 //wc1=0.25*pi
5 //N=11
6 clear;
7 clc;
8 close;
9 N=11;
10 U=6;
11 h_hamm=window('hm',N);
12 for n=-5+U:1:5+U
13 if n==6
14 hd(n)=0.75;
```

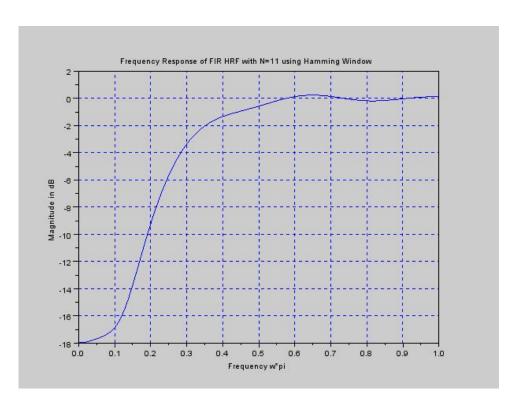


Figure 6.6: HPF Magnitude Response using Hamming Window

Scilab code Exa 6.10 Hanning Window Filter Design

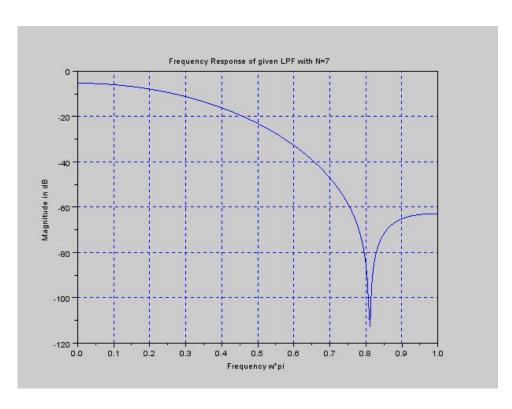


Figure 6.7: Hanning Window Filter Design

```
15 else
16 hd(n)=(sin(%pi*(n-U-alpha)/4))/(%pi*(n-U-alpha));
17 end
18 h(n)=hd(n)*h_hann(n);
19 end
20 [hzm ,fr ]= frmag (h ,256);
21 hzm_dB = 20* log10 (hzm)./ max (hzm );
22 figure
23 plot (2*fr , hzm_dB )
24 a= gca ();
25 xlabel ('Frequency w*pi');
26 ylabel ('Magnitude in dB');
27 title ('Frequency Response of given LPF with N=7');
28 xgrid (2);
```

Scilab code Exa 6.11 LPF Filter Design using Kaiser Window

```
1 //Example 6.11
2 //Program to Plot Magnitude Responce of given L.P.F.
        with specifications:
3 / \text{wp}=20 \text{rad/sec}, ws=30 \text{rad/sec}, wsf=100 \text{rad/sec}
4 // as = 44.0 dB, ap = 0.1 dB
5 //Using Kaiser Window
6 clear;
7 clc;
8 close;
9 wsf=100//rad/sec
10 ws=30; // \text{rad/sec}
11 wp=20; // rad / sec
12 as=44.0 / dB
13 ap=0.1/dB
14 B=ws-wp;
15 \text{ wc} = 0.5*(\text{ws} + \text{wp});
```

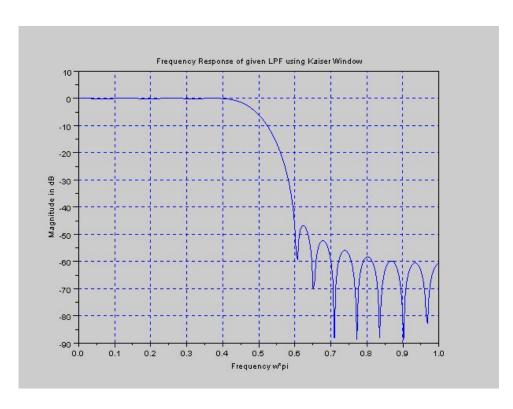


Figure 6.8: LPF Filter Design using Kaiser Window

```
16 \text{ wc1=wc*2*\%pi/wsf};
17 delta1=10^(-0.05*as);
18 delta2=(10^{(0.05*as)-1})/(10^{(0.05*as)+1});
19 delta=min(delta1, delta2);
20 alphas=-20*log10(delta);
21 alpha=0.5842*(alphas-21)^0.4+0.07886*(alphas-21)
22 D=(alphas-7.95)/14.36;
23 N1 = wsf*D/B+1;
24 \text{ N=ceil}(\text{N1});
25 \quad U=ceil(N/2);
26 win_l=window('kr',N,alpha);
27 for n = -floor(N/2) + U : 1 : floor(N/2) + U
28 if n = ceil(N/2);
29 \text{ hd}(n) = 0.5;
30 else
31 hd(n) = (sin(\%pi*(n-U)/2))/(\%pi*(n-U));
32 end
33 h(n)=hd(n)*win_l(n);
34 end
35 [hzm ,fr] = frmag (h ,256) ;
36 \text{ hzm\_dB} = 20* \frac{\log 10}{\log 10} \text{ (hzm)./ } \max \text{ (hzm);}
37 figure
38 plot (2*fr , hzm_dB )
39 \ a = gca \ ();
40 xlabel ('Frequency w*pi');
41 ylabel ('Magnitude in dB');
42 title ('Frequency Response of given LPF using Kaiser
       Window');
43 xgrid (2);
44 disp(h, "Filter Coefficients, h(n)=");
```

Scilab code Exa 6.12 BPF Filter Design using Kaiser Window

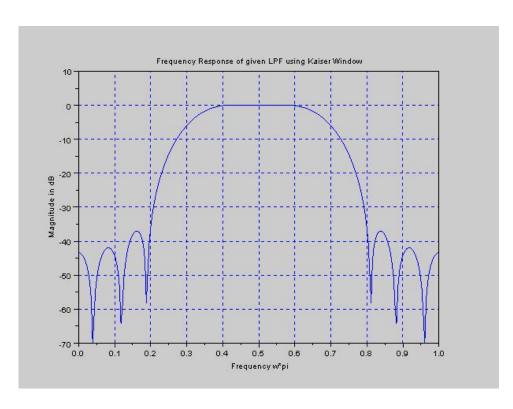


Figure 6.9: BPF Filter Design using Kaiser Window

```
1 //Example 6.12
2 //Program to Plot Magnitude Responce of given B.P.F.
         with specifications:
3 / \text{wp1}=40 \text{ pi rad/sec}, \text{wp2}=60 \text{ pi rad/sec}
4 //\text{ws}1=20 \text{pi rad/sec}, ws2=80 \text{pi rad/sec}
5 / as = 30dB, ap = 0.5dB
6 / F = 100 Hz
7 // Using Kaiser Window
8 clear;
9 clc;
10 close;
11 wsf = 200 * \%pi; // rad / sec
12 ws1=20*%pi; // rad / sec
13 ws2=80*%pi; // \text{rad} / \text{sec}
14 wp1=40*%pi; // rad / sec
15 wp2=60*%pi; // rad / sec
16 \text{ as} = 30 / / dB
17 ap=0.5/dB
18 B=\min(wp1-ws1,ws2-wp2);
19 wc1=wp1-B/2;
20 \text{ wc} 2 = \text{wp} 2 + B/2;
21 \text{ wc1=wc1*2*\%pi/wsf};
22 \text{ wc2=wc2*2*\%pi/wsf};
23 delta1=10^(-0.05*as);
24 delta2 = (10^{(0.05*as)-1})/(10^{(0.05*as)+1});
25 delta=min(delta1,delta2);
26 \text{ alphas} = -20 * \frac{10}{0} (\text{delta});
27 \text{ alpha} = 0.5842*(alphas - 21)^0.4+0.07886*(alphas - 21)
28 D = (alphas - 7.95) / 14.36;
29 N1 = wsf * D/B + 1;
30 \text{ N=ceil}(\text{N1});
31 U=ceil(N/2);
32 win_l=window('kr',N,alpha);
33 for n = -floor(N/2) + U : 1 : floor(N/2) + U
34 if n = ceil(N/2);
35 \text{ hd}(n) = 0.4;
36 else
37 hd(n) = \frac{\sin(0.7 * \%pi * (n-U)) - \sin(0.3 * \%pi * (n-U))}{(\%pi * (n-U))}
```

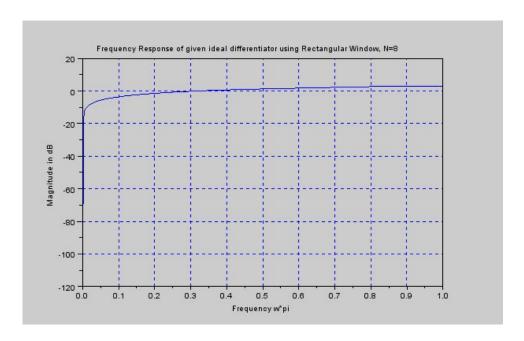


Figure 6.10: Digital Differentiator using Rectangular Window

```
n-U));
38 end
39 h(n)=hd(n)*win_l(n);
40 end
41 [hzm ,fr ]= frmag (h ,256);
42 hzm_dB = 20* log10 (hzm)./ max (hzm );
43 figure
44 plot (2*fr , hzm_dB )
45 a= gca ();
46 xlabel ('Frequency w*pi');
47 ylabel ('Magnitude in dB');
48 title ('Frequency Response of given LPF using Kaiser Window');
49 xgrid (2);
50 disp(h,"Filter Coefficients ,h(n)=");
```

Scilab code Exa 6.13.a Digital Differentiator using Rectangular Window

```
1 //Example 6.13a
2 //Program to Plot Magnitude Responce of ideal
      differentiator with specifications:
3 / N=8, w=pi
4 //using Rectangular window
5 clear;
6 clc;
7 close;
8 N = 8;
9 alpha=7/2;
10 U=1;
11 h_Rect=window('re',N);
12 \quad for \quad n=0+U:1:7+U
13 hd(n)=-(sin(\%pi*(n-U-alpha)))/(\%pi*(n-U-alpha)*(n-U-alpha)
      alpha));
14 h(n)=hd(n)*h_Rect(n);
15 end
16 [hzm, fr] = frmag (h, 256);
17 \text{ hzm\_dB} = 20* \frac{\log 10}{\log 10} \text{ (hzm)./ } \max \text{ (hzm);}
18 figure
19 plot (2*fr , hzm_dB )
20 a = gca ();
21 xlabel ('Frequency w*pi');
22 ylabel ('Magnitude in dB');
23 title ('Frequency Response of given ideal
      differentiator using Rectangular Window, N=8');
24 xgrid (2)
```

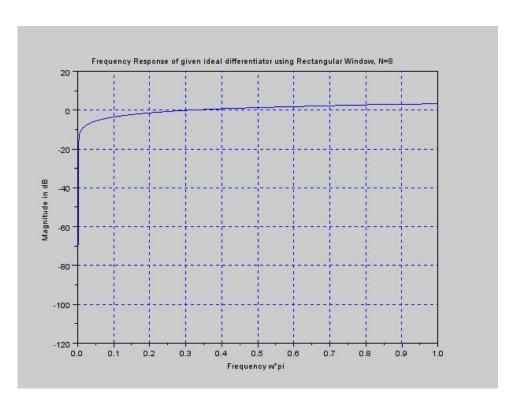


Figure 6.11: Digital Differentiator using Hamming Window

Scilab code Exa 6.13.b Digital Differentiator using Hamming Window

```
1 //Example 6.13b
2 //Program to Plot Magnitude Responce of ideal
      differentiator with specifications:
3 / N=8, w=pi
4 //using Hamming window
5 clear;
6 clc;
7 close;
8 N = 8;
9 alpha=7/2;
10 U=1;
               //Zero Adjust
11 h_hamm=window('hm',N);
12 \quad for \quad n=0+U:1:7+U
13 hd(n)=-(sin(\%pi*(n-U-alpha)))/(\%pi*(n-U-alpha)*(n-U-alpha)
      alpha));
14 h(n)=hd(n)*h_hamm(n);
15 end
16 [hzm ,fr ]= frmag (h ,256);
17 \text{ hzm_dB} = 20* \frac{\log 10}{\log 10} \text{ (hzm)./ } \frac{max}{\log 10} \text{ (hzm)};
18 figure
19 plot (2*fr , hzm_dB )
20 a = gca ();
21 xlabel ('Frequency w*pi');
22 ylabel ('Magnitude in dB');
23 title ('Frequency Response of given ideal
      differentiator using Hamming Window, N=8');
24 xgrid (2)
```

Scilab code Exa 6.14.a Hilbert Transformer using Rectangular Window

```
1 / Example 6.14a
```

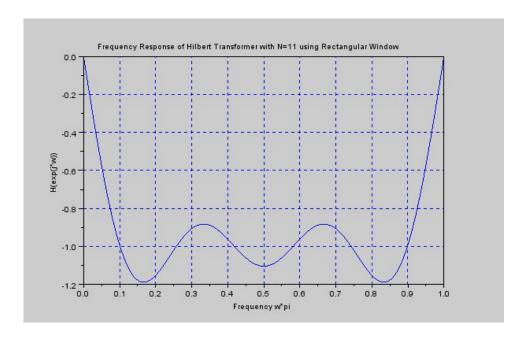


Figure 6.12: Hilbert Transformer using Rectangular Window

```
2 //Program to Plot Magnitude Responce of ideal
      Hilbert Transformer
3 //using Rectangular Window
4 / N = 11
5 clear;
6 clc;
7 close;
8 N = 11;
9 U=6;
10 h_Rect=window('re',N);
11 for n=-5+U:1:5+U
12 if n==6
13 hd(n)=0;
14 else
15 hd(n) = (1 - \cos(\%pi * (n-U)))/(\%pi * (n-U));
17 h(n)=hd(n)*h_Rect(n);
18 \text{ end}
19 [hzm ,fr] = frmag (h,256);
```

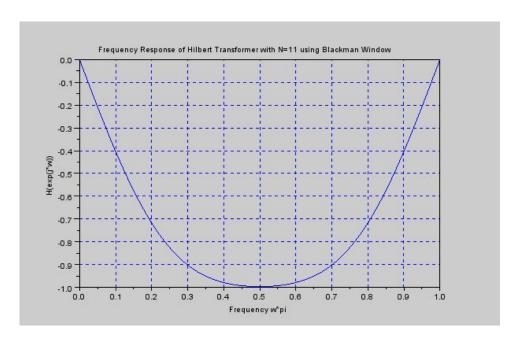


Figure 6.13: Hilbert Transformer using Blackman Window

```
20 figure
21 plot (2*fr ,-hzm);
22 a = gca ();
23 xlabel ('Frequency w*pi');
24 ylabel ('H(exp(j*w))');
25 title ('Frequency Response of Hilbert Transformer with N=11 using Rectangular Window');
26 xgrid (2);
```

Scilab code Exa 6.14.b Hilbert Transformer using Blackman Window

```
    1 //Example 6.14b
    2 //Program to Plot Magnitude Responce of ideal
Hilbert Transformer
```

```
3 //using Blackman Window
4 / N=11
5 clear;
6 clc;
7 close;
8 N = 11;
9 U=6;
10 for n=-5+U:1:5+U
11 h_balckmann(n) = 0.42+0.5*\cos(2*\%pi*(n-U)/(N-1))
      +0.08*\cos(4*\%pi*(n-U)/(N-1));
12 if n==6
13 hd(n)=0;
14 else
15 hd(n) = (1 - cos(\%pi*(n-U)))/(\%pi*(n-U));
17 h(n)=hd(n)*h_balckmann(n);
18 end
19 [hzm, fr] = frmag(h, 256);
20 figure
21 plot (2*fr ,-hzm);
22 \ a = gca \ ();
23 xlabel ('Frequency w*pi');
24 ylabel ('H(\exp(j*w))');
25 title ('Frequency Response of Hilbert Transformer
      with N=11 using Blackman Window');
26 xgrid (2);
```

Scilab code Exa 6.15 Filter Coefficients obtained by Sampling

```
1 //Example 6.15
2 //Program to determine filter coefficients obtained
            by sampling:
3 //N=7,w=pi/2
4 clear;
5 clc;
```

Scilab code Exa 6.16 Coefficients of Linear phase FIR Filter

Scilab code Exa 6.17 BPF Filter Design using Sampling Method

```
1 //Example 6.17
2 //Program to design bandpass filter with following specifications:
3 //N=7, fc1=1000Hz, fc2=3000Hz, F=8000Hz
4 clear;
5 clc;
```

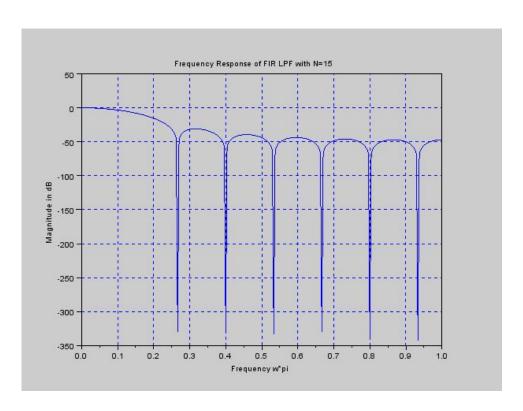


Figure 6.14: Frequency Sampling Method FIR LPF Filter

Scilab code Exa 6.18.a Frequency Sampling Method FIR LPF Filter

```
1 / Example 6.18a
```

```
2 //Program to design L.P.F. filter with following
      specifications:
3 / N = 15, \text{ wc} = \text{pi}/4
4 clear;
5 clc;
6 close;
7 N = 15;
8 U=1;
9 for n=0+U:1:N-1+U
10 h(n) = (1 + \cos(2*\%pi*(7-n)/N))/N;
11 end
12 [hzm ,fr ] = frmag (h ,256);
13 hzm_dB = 20* log10 (hzm)./ max (hzm);
14 figure;
15 plot (2*fr , hzm_dB );
16 a= gca ();
17 xlabel ('Frequency w*pi');
18 ylabel ('Magnitude in dB');
19 title ('Frequency Response of FIR LPF with N=15');
20 xgrid (2)
```

Scilab code Exa 6.18.b Frequency Sampling Method FIR LPF Filter

```
1 //Example 6.18b
2 //Program to design L.P.F. filter with following
         specifications:
3 //N=15, wc=pi/4
4 clear;
5 clc;
6 close;
7 N=15;
8 U=1;
9 for n=0+U:1:N-1+U
```

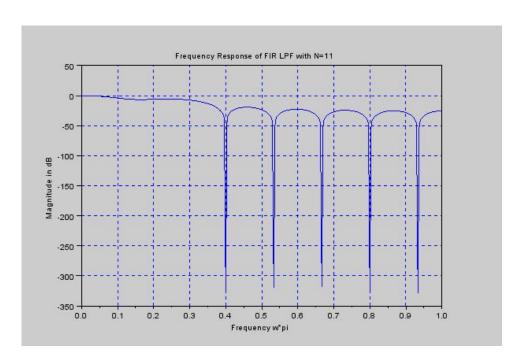


Figure 6.15: Frequency Sampling Method FIR LPF Filter

```
10 h(n)=(1+cos(2*%pi*(7-n)/N)+cos(4*%pi*(7-n)/N))/N;
11 end
12 [hzm ,fr ]= frmag (h ,256);
13 hzm_dB = 20* log10 (hzm)./ max (hzm );
14 figure;
15 plot (2*fr , hzm_dB );
16 a= gca ();
17 xlabel ('Frequency w*pi');
18 ylabel ('Magnitude in dB');
19 title ('Frequency Response of FIR LPF with N=11');
20 xgrid (2)
```

Scilab code Exa 6.19 Filter Coefficients Determination

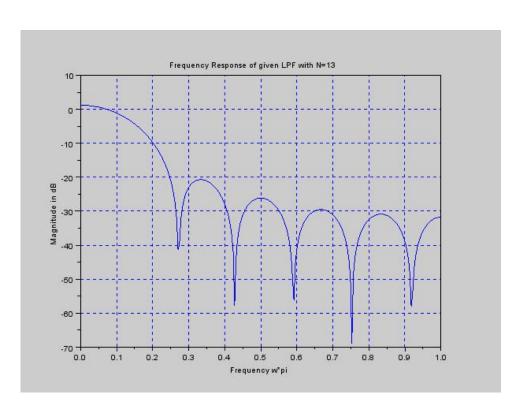


Figure 6.16: Filter Coefficients Determination

```
1 //Example 6.19
2 //Program to Plot Magnitude Responce of given L.P.F.
        with specifications:
3 / N = 13, w = pi / 6
4 clear;
5 clc;
6 close;
7 alpha=6;
8 U=1;
9 \text{ for } n=0+U:1:12+U
10 \text{ if } n == 7
11 hd(n) = 0.167;
12 else
13 hd(n) = (sin(\%pi*(n-U-alpha)/6))/(\%pi*(n-U-alpha));
14 end
15 end
16 [hzm ,fr] = frmag (hd ,256) ;
17 \text{ hzm\_dB} = 20* \frac{\log 10}{\log 10} \text{ (hzm)./ } \max \text{ (hzm);}
18 figure
19 plot (2*fr , hzm_dB )
20 \ a = gca \ ();
21 xlabel ('Frequency w*pi');
22 ylabel ('Magnitude in dB');
23 title ('Frequency Response of given LPF with N=13');
24 xgrid (2)
25 disp(hd, "Filter Coefficients, h(n)=");
```

Scilab code Exa 6.20 Filter Coefficients using Hamming Window

```
1 //Example 6.20
2 //Program to Plot Magnitude Responce of given L.P.F.
     with specifications:
3 //N=13,w=pi/6
```

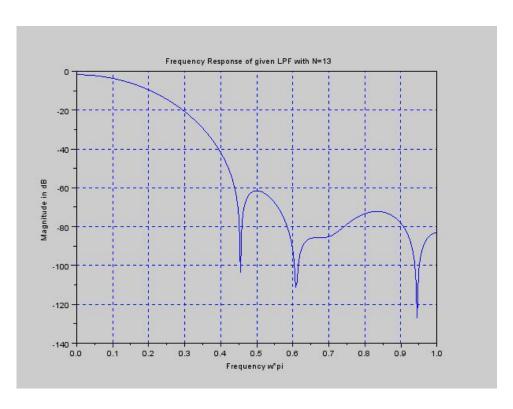


Figure 6.17: Filter Coefficients using Hamming Window

```
4 // Using Hamming Window
5 clear;
6 clc;
7 close;
8 N = 13;
9 \text{ alpha=6};
10 U=1;
11 h_hamm=window('hm',N);
12 for n=0+U:1:12+U
13 if n==7
14 hd(n)=0.167;
16 hd(n) = (\sin(\pi - U - alpha)/6))/(\pi + (n - U - alpha));
17 end
18 h(n) = hd(n) * h_hamm(n);
19 end
20 [hzm ,fr] = frmag (h ,256) ;
21 \text{ hzm_dB} = 20* \frac{\log 10}{\log 10} \text{ (hzm)./ max (hzm)};
22 figure
23 plot (2*fr , hzm_dB )
24 a = gca ();
25 xlabel ('Frequency w*pi');
26 ylabel ('Magnitude in dB');
27 title ('Frequency Response of given LPF with N=13');
28 xgrid (2)
29 disp(h, "Filter Coefficients, h(n)=");
30 disp(h, "Filter Coefficients, h(n)=");
```

Scilab code Exa 6.21 LPF Filter using Rectangular Window

```
1 //Example 6.21
2 //Program to Plot Magnitude Responce of given L.P.F.
    with specifications:
```

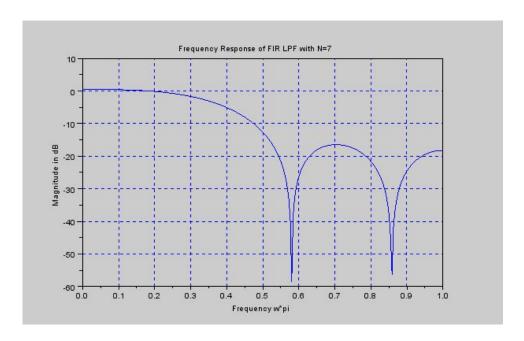


Figure 6.18: LPF Filter using Rectangular Window

```
3~//\mathrm{N}{=}7, f\,c\,{=}1000\mathrm{Hz}\,, F{=}5000\mathrm{Hz}
4 clear;
5 clc;
6 close;
7 N=7;
8 U=4;
9 h_Rect=window('re',N);
10 for n = -3 + U : 1 : 3 + U
11 \quad if \quad n==4
12 hd(n)=0.4;
13 else
14 hd(n) = (sin(2*\%pi*(n-U)/5))/(\%pi*(n-U));
15 end
16 h(n)=hd(n)*h_Rect(n);
17 \text{ end}
18 [hzm ,fr ] = frmag (h ,256);
19 hzm_dB = 20* log10 (hzm)./ max (hzm);
20 figure
21 plot (2*fr , hzm_dB )
```

```
22 a= gca ();
23 xlabel ('Frequency w*pi');
24 ylabel ('Magnitude in dB');
25 title ('Frequency Response of FIR LPF with N=7');
26 xgrid (2)
27 disp(h,"Filter Coefficients,h(n)=");
```

Scilab code Exa 6.28 Filter Coefficients for Direct Form Structure

```
1 //Example 6.28
2 //Program to calculate FIR Filter coefficients for
      the direct form structure
3 / k1 = 1/2, k2 = 1/3, k3 = 1/4
4 clear;
5 clc;
6 close;
7 U=1;
8 k1=1/2;
9 k2=1/3;
10 \text{ k3} = 1/4;
11 a(3+U,0+U)=1;
12 a(1+U,1+U)=k1;
13 a(2+U,2+U)=k2;
14 a(3+U,3+U)=k3;
15 m=2, k=1;
16 a(m+U,k+U)=a(m-1+U,k+U)+a(m+U,m+U)*a(m-1+U,m-k+U);
17 m=3, k=1;
18 a(m+U,k+U)=a(m-1+U,k+U)+a(m+U,m+U)*a(m-1+U,m-k+U);
19 m=3, k=2;
20 a(m+U,k+U)=a(m-1+U,k+U)+a(m+U,m+U)*a(m-1+U,m-k+U);
21 disp(a(3+U,0+U), 'a(3,0)');
22 disp(a(3+U,1+U), 'a(3,1)');
23 disp(a(3+U,2+U), 'a(3,2)');
24 disp(a(3+U,3+U), 'a(3,3)');
```

Scilab code Exa 6.29 Lattice Filter Coefficients Determination

```
1 //Example 6.29
2 //Program to calculate given FIR Filter's Lattice
     form coefficients.
3 clear;
4 clc;
5 close;
                  //Zero Adjust
6 U=1;
7 a(3+U,0+U)=1;
8 a(3+U,1+U)=2/5;
9 a(3+U,2+U)=3/4;
10 a(3+U,3+U)=1/3;
11 a(2+U,0+U)=1; //a(m,0)=1
12 a(2+U,3+U)=1/3;
13 m=3, k=1;
14 a(m-1+U,k+U) = (a(m+U,k+U)-a(m+U,m+U)*a(m+U,m-k+U))
      /(1-a(m+U,m+U)*a(m+U,m+U));
15 \text{ m=3, k=2};
16 a(m-1+U,k+U) = (a(m+U,k+U)-a(m+U,m+U)*a(m+U,m-k+U))
     /(1-a(m+U,m+U)*a(m+U,m+U));
17 m=2, k=1;
18 a(m-1+U,k+U) = (a(m+U,k+U)-a(m+U,m+U)*a(m+U,m-k+U))
     /(1-a(m+U,m+U)*a(m+U,m+U));
19 disp(a(1+U,1+U), 'k1');
20 disp(a(2+U,2+U), 'k2');
21 disp(a(3+U,3+U), 'k3');
```

Chapter 7

FINITE WORD LENGTH EFFECTS IN DIGITAL FILTERS

Scilab code Exa 7.2 Subtraction Computation

```
1 //Example 7.2
2 //To Compute Subtraction
3 //(a) 0.25 from 0.5
4 clear;
5 clc;
6 close;
7 a=0.5;
8 b=0.25;
9 c=a-b;
10 disp(c,'=',b,'-',a,'PART 1');
11 //(a) 0.5 from 0.25
12 d=b-a;
13 disp(d,'=',a,'-',b,'PART 2');
```

Scilab code Exa 7.14 Variance of Output due to AD Conversion Process

Chapter 8

MULTIRATE SIGNAL PROCESSING

Scilab code Exa 8.9 Two Component Decomposition

```
1 / \text{Example } 8.9
2 //MAXIMA SCILAB TOOLBOX REQUIRED FOR THIS PROGRAM
3 // Develop a two component decomposition for the
      transfer function
4 //and determine PO(z) and PI(z)
5 clear;
6 clc;
7 close;
8 syms z a n;
9 HZ=(z)/(z-a);
10 hn=a^n; //Inverse Z Transform of HZ
11 h2n=a^(2*n);
12 P0=symsum(h2n*z^{(-n)},n,0,%inf);
13 h2n1=a^(2*n+1);
14 P1=symsum(h2n1*z^(-n),n,0,%inf);
15 disp(P0, 'P0(Z) = ');
16 disp(P1, 'P1(Z) = ');
```

Scilab code Exa 8.10 Two Band Polyphase Decomposition

Chapter 9

STATISTICAL DIGITAL SIGNAL PROCESSING

Scilab code Exa 9.7.a Frequency Resolution Determination

```
1 //Example 9.7 (a)
2 //Program To Determine Frequency Resolution of
      Bartlett,
3 //Welch(50% Overlap) and Blackmann-Tukey Methods
4 clear;
5 clc;
6 close;
7 //Data
8 Q=10; // Quality Factor
9 N=1000; //Samples
10 //FREQUENCY RESOLUTION CALCULATION
11 K=Q;
12 rb=0.89*(2*\%pi*K/N);
13 rw=1.28*(2*\%pi*9*Q)/(16*N);
14 rbt=0.64*(2*\%pi*2*Q)/(3*N);
15 //Display the result in command window
16 disp(rb, "Resolution of Bartlett Method");
17 disp(rw, "Resolution of Welch(50% overlap) Method");
18 disp(rbt, "Resolution of Blackmann-Tukey Method");
```

Scilab code Exa 9.7.b Record Length Determination

```
1 //Example 9.7 (b)
2 //Program To Determine Record Length of Bartlett,
3 //Welch (50% Overlap) and Blackmann-Tukey Methods
4 clear;
5 clc;
6 close;
7 //Data
8 Q=10; // Quality Factor
9 N=1000; //Samples
10 //RECORD LENGTH CALCULATION
11 lb=N/Q;
12 lw=16*N/(9*Q);
13 lbt=3*N/(2*Q);
14 // Display the result in command window
15 disp(lb, "Record Length of Bartlett Method");
16 disp(lw, "Record Length of Welch(50% overlap) Method"
     );
17 disp(lbt, "Record Length of Blackmann-Tukey Method");
```

Scilab code Exa 9.8.a Smallest Record Length Computation

```
8 N=2400; //Samples
9 //RECORD LENGTH CALCULATION
10 lb=0.89/fr;
11 //Display the result in command window
12 disp(lb, "Record Length of Bartlett Method");
```

Scilab code Exa 9.8.b Quality Factor Computation

Chapter 11

DIGITAL SIGNAL PROCESSORS

Scilab code Exa 11.3 Program for Integer Multiplication

```
//Program 11.3
//Program To Calculate the value of the function
//Y=A*B
clear;
clc;
close;
//Input Data
A=input('Enter Integer Number A =');
B=input('Enter Integer Number B =');
//Multiplication Computation
Y=A*B;
//Display the result in command window
disp(Y,"Y = A*B = ");
```

Scilab code Exa 11.5 Function Value Calculation

```
1 //Program 11.5
2 //Program To Calculate the value of the function
3 / Y = A * X1 + B * X2 + C * X3
4 clear;
5 clc;
6 close;
7 //Data
8 \quad A = 1;
9 B=2;
10 C=3;
11 X1=4;
12 \quad X2=5;
13 X3 = 6;
14 //Compute the function
15 Y = A * X1 + B * X2 + C * X3;
16 // Display the result in command window
17 disp(Y, "Y = A*X1+B*X2+C*X3 = ");
```