### Linear models I

Regression

### Supervised learning in practice

### Preprocessing Explore & prepare data

Data Visualization and Exploration

Identify patterns that can be leveraged for learning

- Missing data
- Noisy data
- Erroneous data

Data Cleaning

Scaling (Standardization)

Prepare data for use in scale-dependent algorithms.

Feature Extraction

Dimensionality reduction eliminates redundant information

#### **Model training**

Select models (hypotheses)

Select model options that may fit the data well. We'll call them "hypotheses".

Fit the model to training data

Pick the "best" hypothesis function of the options by choosing model parameters Iteratively fine tune evaluation

the model

Make a prediction on validation data

**Performance** 

**Metrics** 

Classification

Precision, Recall, F<sub>1</sub>, ROC Curves (Binary), Confusion Matrices (Multiclass)

Regression

MSE, explained variance, R<sup>2</sup>

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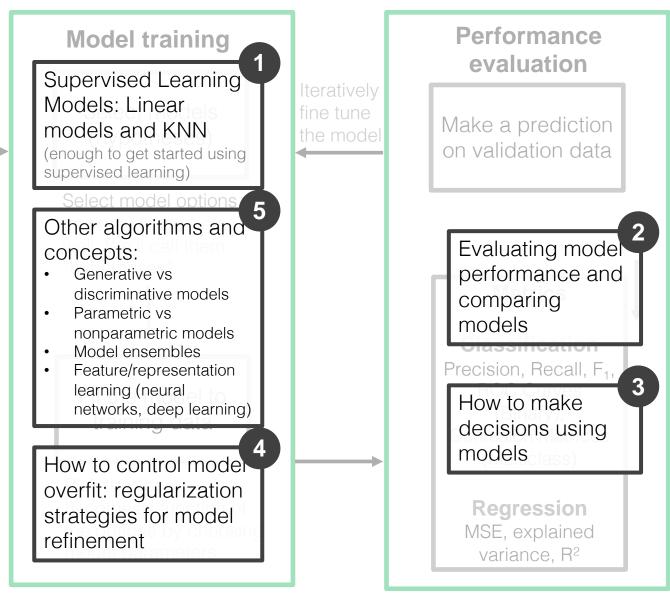
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### **Model Fitting / Training Process**

- 1. Choose a **hypothesis set of models** to train (e.g. linear regression with 4 predictor variables)
- 2. Identify a **cost function** to measure the model fit to the training data (e.g. mean square error)
- 3. Optimize model parameters to minimize cost (e.g. closed form solution using the normal equations for OLS)

\* We will use this procedure for ALL the parametric models we encounter Parametric models = models where the number of parameters are fixed and independent of the training data size

### How can we...

define what makes a model linear?

fit our model to our training data?

### What makes a model linear?

### Which of the following models are linear?

A 
$$y = w_0$$

$$y = w_0 + w_1 x_1$$

c 
$$y = w_0 + w_1 x_1 + x_2^{w_2}$$

$$y = w_0 + w_1 x_1^2 + w_2 x_2^{0.4}$$

$$= y = w_0 + w_1 x_1 + w_2 x_2 + w_3 x_1 x_2$$

$$y = w_0 + w_1 \int \sqrt[3]{x_1} dx_1 + w_2 g(x_2) + w_3 median(x_1, x_2, x_3)$$

Model parameters are  $w_i$ Target variable is yRemaining components are features

### Linear models are linear in the parameters

A linear combination is quantity where a set of terms are added together, each multiplied by a constant (parameter)

$$\boldsymbol{x} = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} \qquad \boldsymbol{y} = \begin{bmatrix} y_1 \\ y_2 \\ y_3 \end{bmatrix}$$

In other words, a linear combination is a sum of scalar multiples of vectors:

$$z = 2x + 99.9999y$$

$$z = 0.333x + (-42)y$$

$$z = 0x + \left(\frac{\pi^2}{e}\right)y$$

### Linear regression model

$$\mathbf{y}_i = \sum_{j=0}^p \mathbf{w}_j \mathbf{x}_{i,j} = \mathbf{w}^\mathsf{T} \mathbf{x}_i$$

Parameters 
$$w_j$$
Target  $y_i$ 
Features  $x_{i,j}$ 
Sample Feature

$$y_i = w_0 x_{i,0} + w_1 x_{i,1} + w_2 x_{i,2} + \dots + w_p x_{i,p}$$

Intercept/bias term:  $x_{i,0} \triangleq 1$ 

$$y_i = w_0 + w_1 x_{i,1} + w_2 x_{i,2} + \dots + w_p x_{i,p}$$

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$$y = w_0 + w_1 \int \sqrt[3]{x_1} dx_1 + w_2 g(x_2) + w_3 median(x_1, x_2, x_3)$$

Model parameters are  $w_i$ Target variable is yRemaining components are features

**ALL except** C are linear in the **parameters**, w

## We can rewrite these models in terms of transformed features

It becomes clear this is a linear model when we rewrite the features:

$$y = w_0 + w_1 z_1 + w_2 z_2 + w_3 z_3$$

Transformed features:

$$z_1 = \int \sqrt[3]{x_1} dx_1$$
  $z_2 = g(x_2)$ 

$$z_2 = median(x_1, x_2, x_3)$$

$$y = w_0 + w_1 \int \sqrt[3]{x_1} dx_1 + w_2 g(x_2) + w_3 median(x_1, x_2, x_3)$$

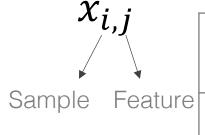
$$\mathbf{y}_i = \sum_{j=0}^p \mathbf{w}_j \mathbf{x}_{i,j} = \mathbf{w}^\mathsf{T} \mathbf{x}_i$$

### Linear regression assumptions

- 1. Linearity. Linear relationship between feature and target variables
- 2. Normality. Error is normally distributed
- 3. Independence. Assumes observations are independent from one another (no autocorrelation)
- 4. Homoscedascity. Variance of the error is constant
- 5. Little multicollinearity. Features are not correlated with one another

### **Notation**

#### **Number of features**



Number of samples

4	

Shorthand

$$\boldsymbol{x}_i = \begin{bmatrix} x_{i,0} \\ x_{i,1} \\ \vdots \\ x_{i,p} \end{bmatrix}$$

Assume 
$$x_{i,0} = 1$$

$$x_i = \begin{bmatrix} x_0 \\ x_1 \\ \vdots \\ x_p \end{bmatrix} = \begin{bmatrix} 1 \\ x_1 \\ \vdots \\ x_p \end{bmatrix}$$

Shorthand

$$N \qquad x = \begin{bmatrix} x_{1,j} \\ x_{2,j} \\ \vdots \\ x_{N,j} \end{bmatrix}$$

$$\boldsymbol{x} = \begin{bmatrix} x_{1,j} \\ x_{2,j} \\ \vdots \\ x_{N,j} \end{bmatrix}$$

Shorthand

$$\boldsymbol{x} = \begin{bmatrix} x_{1,j} \\ x_{2,j} \\ \vdots \\ x_{N,i} \end{bmatrix} \qquad \boldsymbol{x} = \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_N \end{bmatrix} \qquad \boldsymbol{X} = \begin{bmatrix} x_1 \\ x_2^T \\ \vdots \\ x_N^T \end{bmatrix} = \begin{bmatrix} x_{1,0} & x_{1,1} & \dots & x_{1,p} \\ x_{2,0} & x_{2,1} & \dots & x_{2,p} \\ \vdots & \vdots & \ddots & \vdots \\ x_{N,0} & x_{N,1} & \dots & x_{N,p} \end{bmatrix}$$

### **Types of Linear Regression**

	One feature variable	Two or more feature variables
One target variable	Simple Linear Regression $y_i = w_0 + w_1 x_{i,1}$	Multiple Linear Regression $y_i = \sum_{j=0}^p w_j x_{i,j} \text{ or } y_i = \mathbf{w}^\top \mathbf{x}_i$

### **Two or more** target variables

#### Multivariate (Multiple) Linear Regression

### Linear models: pros and cons

#### **Pros**

Simple/fast to implement and interpret

Excels if the relationship between features and targets is linear or can be expressed in terms of linear combinations of features

Often a good starting point or baseline model for many analyses

#### Cons

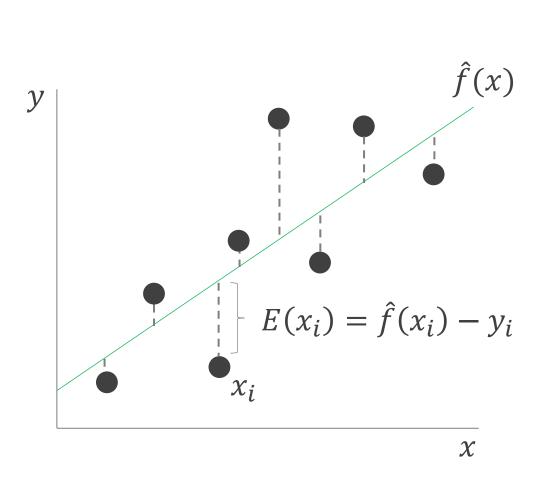
For many applications with complex feature-target relationships, underfits

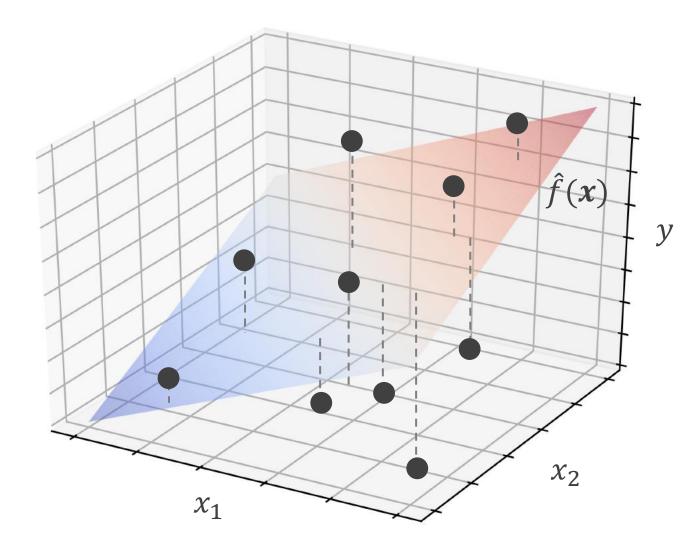
Requires feature engineering for capturing more complex feature-target relationships

### How do we fit the model to the training data?

A winding path to the least squares solution

### Linear models and error





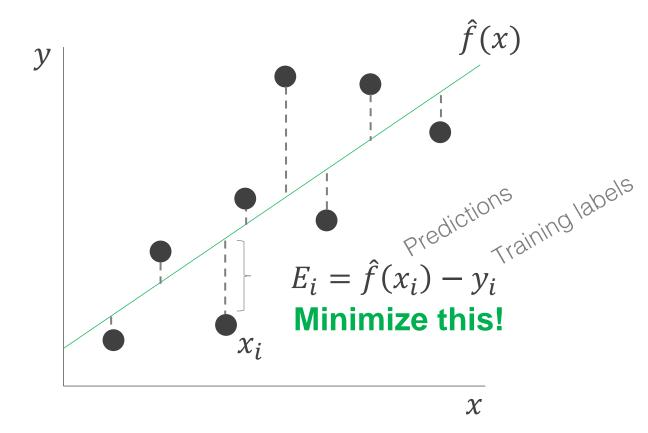
simple linear regression

multiple linear regression

### How do we fit a linear model to training data?

We want the error between our predictions and training data to be small

Training data:  $D = \{(x_1, y_1), (x_2, y_2), ..., (x_N, y_N)\}$ 



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### How do we measure error?

The error for one sample is:

$$E_i = \hat{f}(x_i) - y_i$$
  $\hat{y}_i = \hat{f}(x_i) = \sum_{i=0}^{p} w_i x_{i,j}$ 

We want to minimize the error across all our training data, so... we use mean squared error to quantify training (in-sample) error:

Training (in-sample) error: 
$$E_{in}(\hat{f}, D) = \frac{1}{N} \sum_{n=1}^{N} (\hat{f}(x_n) - y_n)^2$$

We call this our **Cost Function** (a.k.a. loss, error, or objective)

Cost Function: 
$$C(\hat{f}, D) = E_{in}(\hat{f}, D) = \frac{1}{N} \sum_{n=1}^{N} (\hat{f}(x_n) - y_n)^2$$

Training error is a function of our model and the training data

We can't change the data; we adjust our model to minimize cost

To adjust the model, we choose model parameters that minimize cost

This is an optimization problem

### How to fit our model to the training data?

Equivalently: how do we choose w to minimize cost (error)

$$E_{in}(\hat{f}, D) = \frac{1}{N} \sum_{n=1}^{N} (\hat{f}(\mathbf{x}_n) - y_n)^2$$

where 
$$\hat{f}(\mathbf{x}_n) = \mathbf{w}^T \mathbf{x}_n$$

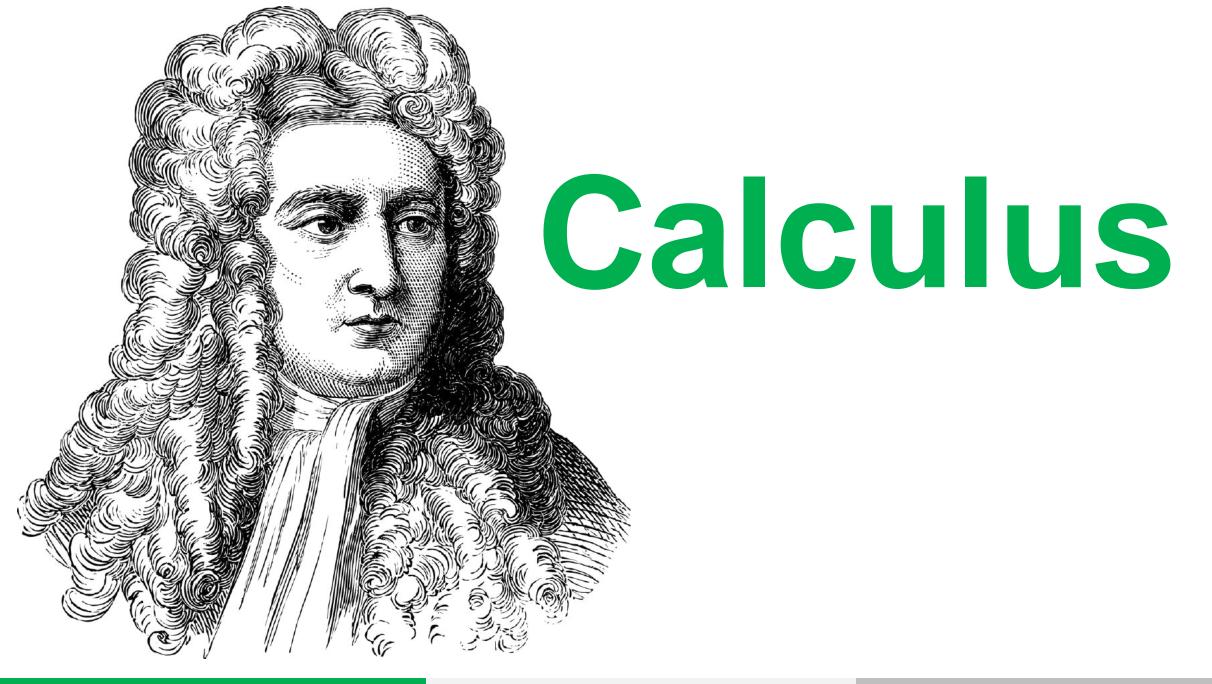
We want to minimize

...by varying w

How do we do that?

$$E_{in}(\mathbf{w}) = \frac{1}{N} \sum_{n=1}^{N} (\mathbf{w}^T \mathbf{x}_n - y_n)^2$$
Once we've determined

Once we've determined the form of the model and the training data, the model parameters w are the only parts we can adjust



### A moment of calculus

Function of one variable

$$f(x) = ax + bx^2$$

#### \_\_\_\_\_

#### Gradient

Function of multiple variables

 $f(x_1, x_2) = ax_1 + bx_2$ 

$$\frac{df}{dx} = a + 2bx$$

#### **Partial Derivative**

$$\frac{\partial f}{\partial x_1} = a$$

$$\frac{\partial f}{\partial x_2} = b$$

May also treat parameters as variables 
$$\frac{\partial f}{\partial b} = x$$
 and take their partial derivative

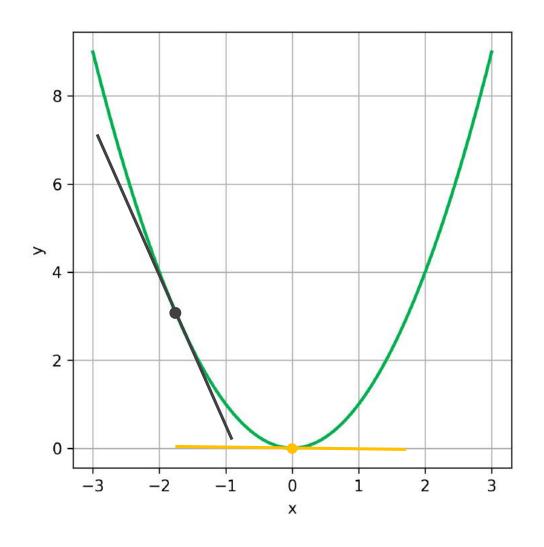
$$\nabla_{x} f = \begin{bmatrix} \frac{\partial f}{\partial x_{1}} \\ \frac{\partial f}{\partial x_{2}} \end{bmatrix}$$

$$=\begin{bmatrix} a \\ b \end{bmatrix}$$

### Why set the derivative to 0?

Remember the derivative (and gradient) is the direction and rate of fastest increase

For a continuous, convex function, the function is minimized when that derivative is zero



### How to fit our model to the training data?

Take the gradient with respect to w, set it to zero, and solve for w(think derivative)

$$abla_{w}E_{in}(w) = 
abla_{w} \left( \frac{1}{N} \sum_{n=1}^{N} (w^{T} x_{n} - y_{n})^{2} \right)$$
 $p = \text{number of predictors}$ 
 $N = \text{number of data points}$ 

$$abla_{w}E_{in}(\mathbf{w}) = \begin{bmatrix} \frac{\partial E_{in}}{\partial w_{0}} \\ \frac{\partial E_{in}}{\partial w_{1}} \\ \vdots \\ \frac{\partial E_{in}}{\partial w_{p}} \end{bmatrix} = \mathbf{0}$$
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Linear models

We will walk through the ordinary least squares (OLS) closed-form solution.

We could have used another optimization approach like gradient descent

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### How to fit our model to the training data?

Our cost function...

$$E_{in}(\mathbf{w}) = \frac{1}{N} \sum_{n=1}^{N} (\mathbf{w}^{T} \mathbf{x}_{n} - \mathbf{y}_{n})^{2}$$

$$\mathbf{w}^{T} \in \mathbb{R}^{1 \times p+1}$$
Scalar
$$\mathbf{x}_{n} \in \mathbb{R}^{p+1 \times 1}$$

...can be rewritten as:

$$E_{in}(\mathbf{w}) = \frac{1}{N} (\mathbf{X}\mathbf{w} - \mathbf{y})^T (\mathbf{X}\mathbf{w} - \mathbf{y})$$

Convenient definitions:

$$\mathbf{y} \in \mathbb{R}^{N \times 1}$$

$$\mathbf{X} = \begin{bmatrix} \mathbf{x}_{1}^{T} \\ \mathbf{x}_{2}^{T} \\ \vdots \\ \mathbf{x}_{N}^{T} \end{bmatrix} \in \mathbb{R}^{N \times p+1}$$

$$\mathbf{w} = \begin{bmatrix} \mathbf{w}_{0} \\ \mathbf{w}_{1} \\ \vdots \\ \mathbf{w}_{p} \end{bmatrix} \in \mathbb{R}^{p+1 \times 1}$$

p = number of predictors N = number of data points

Assume 
$$p = 2$$
 $N = 4$ 

$$\mathbf{w} = \begin{bmatrix} w_0 \\ w_1 \\ w_2 \end{bmatrix}$$

$$\mathbf{w} = \begin{bmatrix} w_0 \\ w_1 \\ w_2 \end{bmatrix} \qquad \mathbf{x}_i = \begin{bmatrix} x_{i,0} \\ x_{i,1} \\ x_{i,2} \end{bmatrix}$$

p = number of predictors N = number of data points

$$\mathbf{w}^{T} \mathbf{x}_{i} = \begin{bmatrix} w_{0} & w_{1} & w_{2} \end{bmatrix} \begin{bmatrix} x_{i,0} \\ x_{i,1} \\ x_{i,2} \end{bmatrix}$$
$$= w_{0} x_{i,0} + w_{1} x_{i,1} + w_{2} x_{i,2}$$

### Aside on algebraic manipulations

$$Xw = \begin{bmatrix} x_{1,0} & x_{1,1} & x_{1,2} \\ x_{2,0} & x_{2,1} & x_{2,2} \\ x_{3,0} & x_{3,1} & x_{3,2} \\ x_{4,0} & x_{4,1} & x_{4,2} \end{bmatrix} \begin{bmatrix} w_0 \\ w_1 \\ w_2 \end{bmatrix} = \begin{bmatrix} w^T x_1 \\ w^T x_2 \\ w^T x_3 \\ w^T x_4 \end{bmatrix}$$

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$$\begin{bmatrix} x_{1,0} & x_{1,1} & x_{1,2} \\ x_{2,2} & x_{2,1} & x_{2,2} \end{bmatrix}$$

$$x_{2,1}$$
  $x_{2,2}$   $x_{2,2}$ 

$$x_{3,1}$$
  $x_{3,2}$   $x_{4,1}$   $x_{4,2}$ 

$$Xw = \begin{bmatrix} x_{1,0} & x_{1,1} & x_{1,2} \\ x_{2,0} & x_{2,1} & x_{2,2} \\ x_{3,0} & x_{3,1} & x_{3,2} \\ x_{4,0} & x_{4,1} & x_{4,2} \end{bmatrix} \begin{bmatrix} w_0 \\ w_1 \\ w_2 \end{bmatrix} = \begin{bmatrix} \mathbf{w}^T \mathbf{x}_1 \\ \mathbf{w}^T \mathbf{x}_2 \\ \mathbf{w}^T \mathbf{x}_3 \\ \mathbf{w}^T \mathbf{x}_4 \end{bmatrix} \qquad Xw - \mathbf{y} = \begin{bmatrix} \mathbf{w}^T \mathbf{x}_1 - \mathbf{y}_1 \\ \mathbf{w}^T \mathbf{x}_2 - \mathbf{y}_2 \\ \mathbf{w}^T \mathbf{x}_3 - \mathbf{y}_3 \\ \mathbf{w}^T \mathbf{x}_4 - \mathbf{y}_4 \end{bmatrix}$$

$$(Xw - y)^{T}(Xw - y) = [w^{T}x_{1} - y_{1} \quad w^{T}x_{2} - y_{2} \quad w^{T}x_{3} - y_{3} \quad w^{T}x_{4} - y_{4}] \begin{bmatrix} w^{T}x_{1} - y_{1} \\ w^{T}x_{2} - y_{2} \\ w^{T}x_{3} - y_{3} \\ w^{T}x_{4} - y_{4} \end{bmatrix}$$

$$\mathbf{w}^T \mathbf{x}_2$$

$$y_2$$
 w

$$\mathbf{w}^T \mathbf{x}_3 - \mathbf{y}$$

$$\mathbf{w}^T \mathbf{x}_4 - \mathbf{y}_4$$

$$\mathbf{w}^T \mathbf{x}_4 - \mathbf{y}_4$$

## $=\sum_{n=1}^{N}(\mathbf{w}^{T}\mathbf{x}_{n}-\mathbf{y}_{n})^{2}$

### Aside on algebraic manipulations

### How to fit our model to the training data?

Our cost function...

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Convenient definitions:

$$\mathbf{y} \in \mathbb{R}^{N \times 1}$$

$$\mathbf{X} = \begin{bmatrix} \mathbf{x}_{1}^{T} \\ \mathbf{x}_{2}^{T} \\ \vdots \\ \mathbf{x}_{N}^{T} \end{bmatrix} \in \mathbb{R}^{N \times p+1}$$

$$\mathbf{w} = \begin{bmatrix} \mathbf{w}_{0} \\ \mathbf{w}_{1} \\ \vdots \\ \mathbf{w}_{p} \end{bmatrix} \in \mathbb{R}^{p+1 \times 1}$$

p = number of predictors N = number of data points

### How to fit our model to the training data?

$$E_{in}(\mathbf{w}) = \frac{1}{N} (\mathbf{X}\mathbf{w} - \mathbf{y})^T (\mathbf{X}\mathbf{w} - \mathbf{y})$$
 (take gradient, set to 0)

$$\nabla_{\mathbf{w}} E_{in}(\mathbf{w}) = \frac{2}{N} (\mathbf{X}^T \mathbf{X} \mathbf{w} - \mathbf{X}^T \mathbf{y}) = \mathbf{0}$$
 (solve for  $\mathbf{w}$ )

#### **Univariate analogy**:

$$f(w) = \frac{1}{N} (xw - y)^{2}$$

$$= \frac{1}{N} (x^{2}w^{2} - 2xyw + y^{2})$$

$$\frac{df(w)}{dw} = \frac{2}{N} (x^{2}w - xy)$$

$$X^TXw - X^Ty = 0$$

$$\boldsymbol{X}^T \boldsymbol{X} \boldsymbol{w} = \boldsymbol{X}^T \boldsymbol{y}$$
 (normal equation)

$$\boldsymbol{w}^* = (\boldsymbol{X}^T \boldsymbol{X})^{-1} \boldsymbol{X}^T \boldsymbol{y}$$

Pseudoinverse 
$$\mathbf{X}^{\dagger} = (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T$$

$$\boldsymbol{w}^* = \mathbf{X}^\dagger \boldsymbol{y}$$

### What is the pseudoinverse?

### Samples and features impact solutions

Features  $\begin{bmatrix}
N \times p \\
p \times 1
\end{bmatrix} = \begin{bmatrix}
N \times 1
\end{bmatrix}$ 

If N = p, then there are the same number of features as samples

(# equations = # unknowns)

If N > p, then the system of equations is **overdetermined**: more samples than features

(# equations > # unknowns)

Can't invert X – it's not square!

If N < p, then the system of equations is **underdetermined**: fewer samples than features

(# equations < # unknowns)

### Overdetermined systems

#### **Example 1**

#### Fully determined system

# equations = # unknowns

$$w_1 = 2$$

$$w_2 = 1$$

#### Overdetermined system

# equations > # unknowns

$$w_1 = 2$$

$$w_2 = 1$$

$$w_2 = 5$$

#### **Example 2**

#### Fully determined system

# equations = # unknowns

$$2w_1 + 3w_2 = 2$$

$$6w_1 + 1w_2 = 0.63$$

#### Overdetermined system

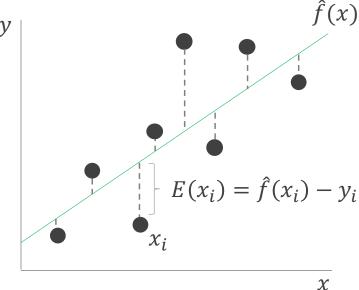
# equations > # unknowns

$$2w_1 + 3w_2 = 2$$

$$6w_1 + 1w_2 = 0.63$$

$$3w_1 + 2w_2 = 14$$

$$16w_1 - w_2 = 0.1$$



### Underdetermined systems

#### **Example 1**

#### Fully determined system

# equations = # unknowns

$$w_1 = 2$$
$$w_2 = 1$$

#### Underdetermined system

# equations > # unknowns

$$w_1 = w_2$$

#### **Example 2**

#### Fully determined system

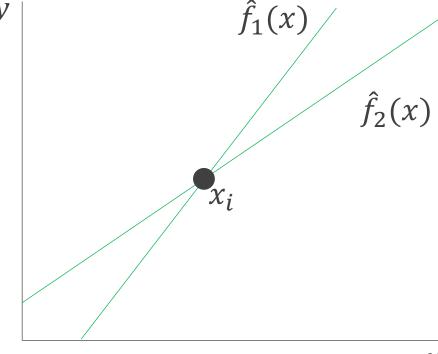
# equations = # unknowns

$$2w_1 + 3w_2 = 2$$
  
 $6w_1 + 1w_2 = 0.63$ 

#### Underdetermined system

# equations > # unknowns

$$2w_1 + 3w_2 = 2$$



### What is the pseudoinverse?

Consider the case when N = 3, p = 2 (Assume no bias term here)

Features

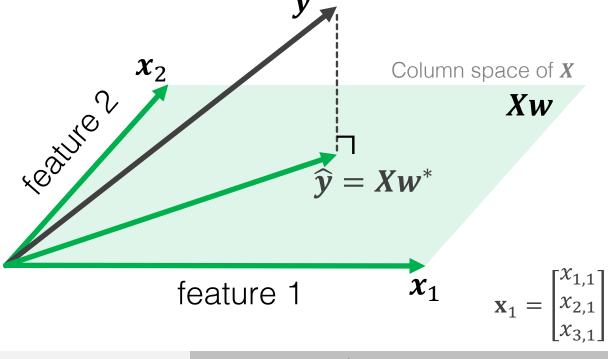
Feature vectors:  $oldsymbol{x}_1$ 

$$X \quad w \neq y$$

We CAN use  $X^{\dagger}$  to obtain  $w^{*}$ , the least squares solution:  $w^{*} = X^{\dagger}y$ 

 $\boldsymbol{x}_2$ 

The least squares solution is the best we can do given N > p



## Much of machine learning is optimizing a cost function

Least squares is one approach (when applicable), gradient descent is another, more generic method

### **Model Fitting / Training Process**

- 1. Choose a **hypothesis set of models** to train (e.g. linear regression with 4 predictor variables)
- 2. Identify a **cost function** to measure the model fit to the training data (e.g. mean square error)
- 3. Optimize model parameters to minimize cost (e.g. closed form solution using the normal equations for OLS)

# We now have our model parameters, we can make predictions on unseen test data!

The parameters learned from model fitting 
$$\hat{y}_i = \hat{f}(x_i) = \sum_{j=0}^p \overset{*}{w_j^*} x_{i,j}$$

### **Takeaways**

Linear models are linear in the weights

Model fitting/training process (valid beyond linear models):

- Choose a hypothesis set of models to train
- Identify a cost function
- Optimize the cost function by adjusting model parameters (This is the "learning" process)

Optimize cost functions for linear regression using least squares

- Least squares allows us to generate approximate solutions to overdetermined systems (more samples than features/parameters), which are common
- Alternative optimization strategies exist such as gradient descent