



Control System Training

MODULE 5 – Sequential Logic

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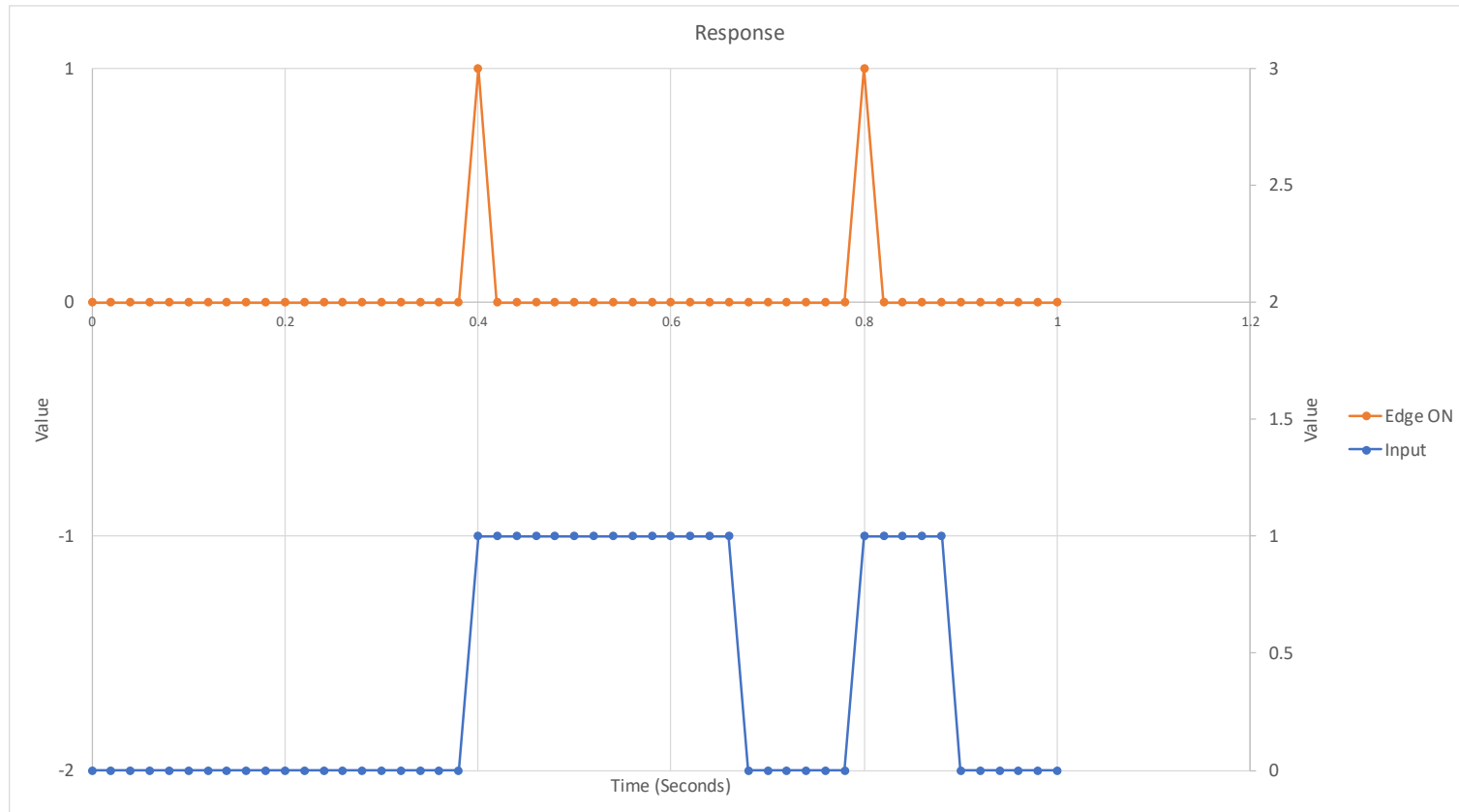
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Sequential Logic

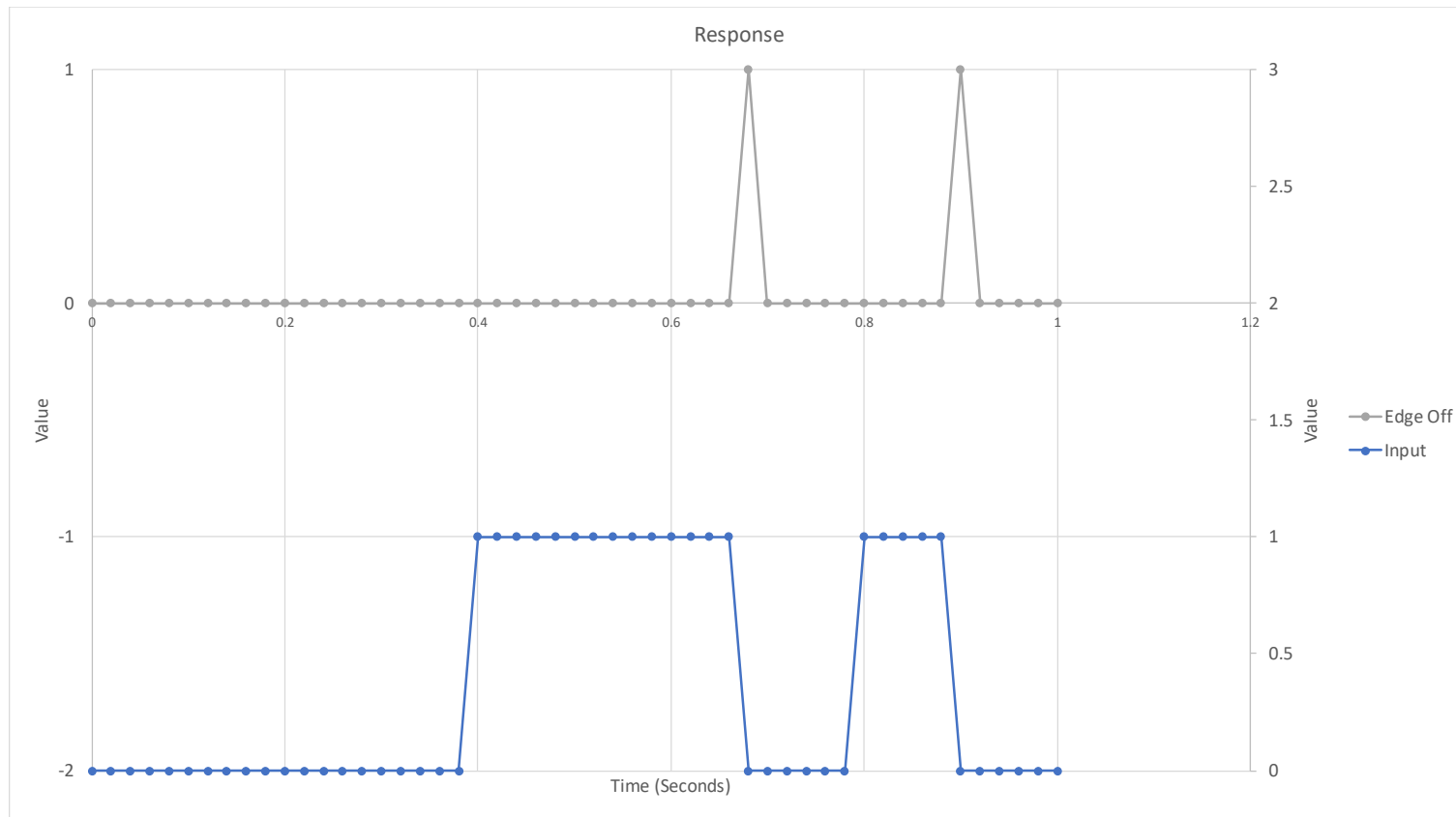
- **Output depends on both state of current inputs and previous input and output states.**

Edge Triggered – ON



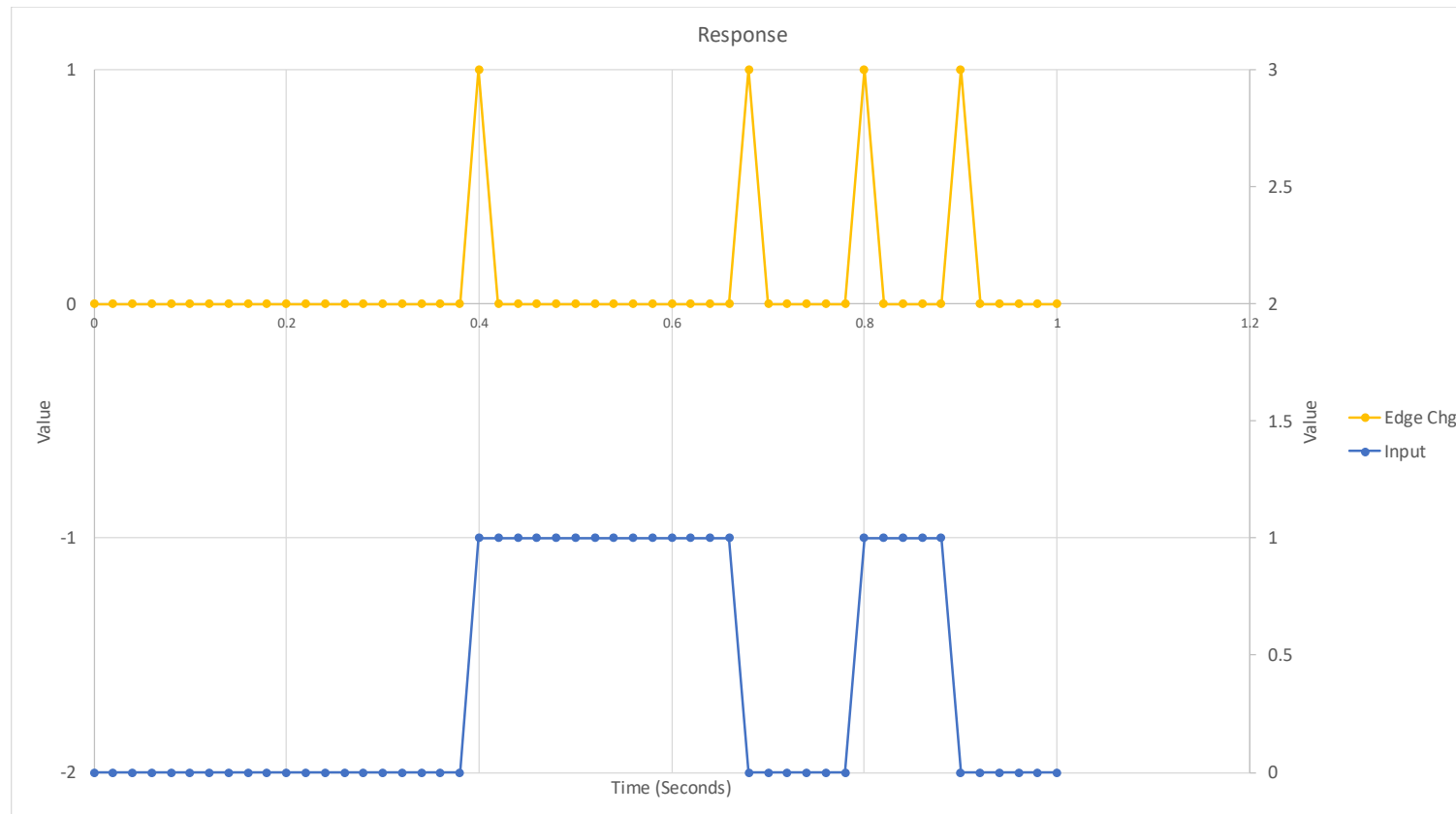
- Only true for a single scan.

Edge Triggered - OFF



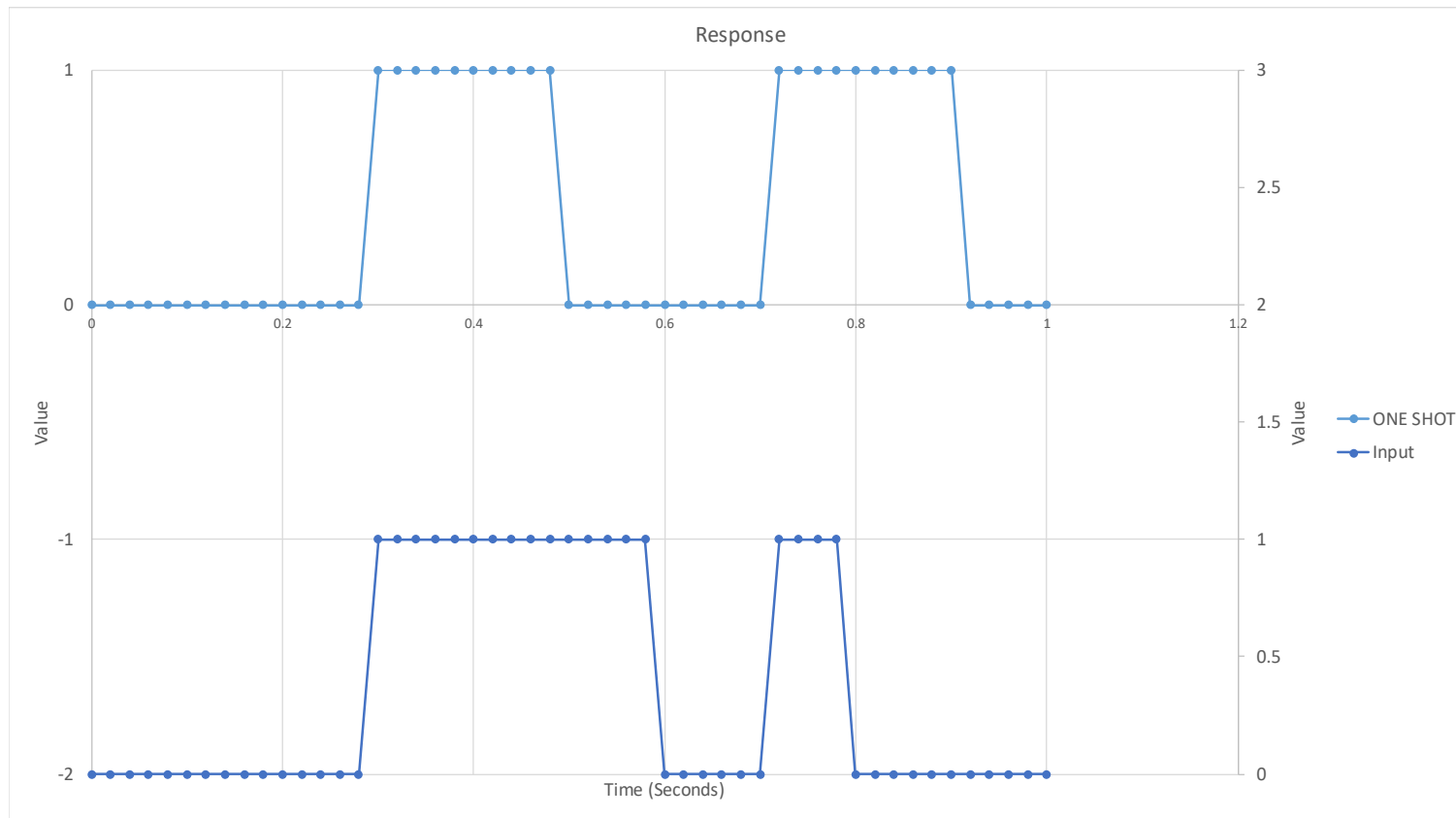
- Only true for a single scan

Edge Triggered - CHANGE



- Only true for a single scan

One Shot



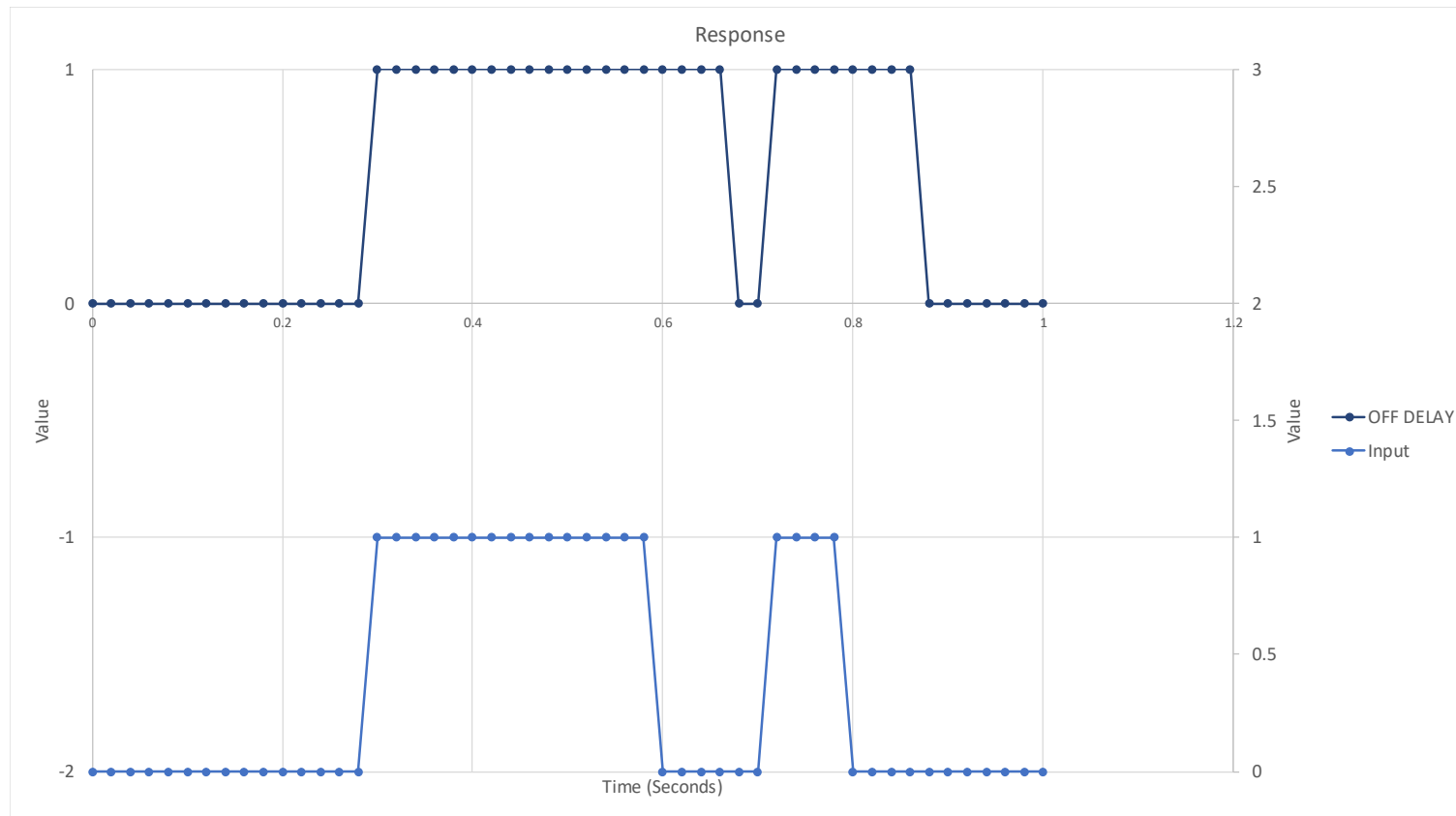
- Oneshot time is 0.200 seconds

On Delay



- **Delay is 0.200 Seconds**
- **If input goes false before delay expires, output is never true.**

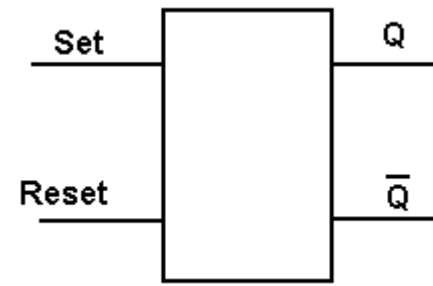
Off Delay



- Off delay time is 0.080 seconds.

Set / Reset Flip Flop

Set / Reset Flip Flop			
Input			
Set	Reset	Override	Output
1	0	N/A	1
0	1	N/A	0
0	0	N/A	Prev Output
1	1	Set	1
1	1	Reset	0



- Can think of this as “Boolean memory”. This is the building block of all computers.
- If both are true at the same time, one overrides the other. This is usually selectable.

Designing Sequential Logic 1/4

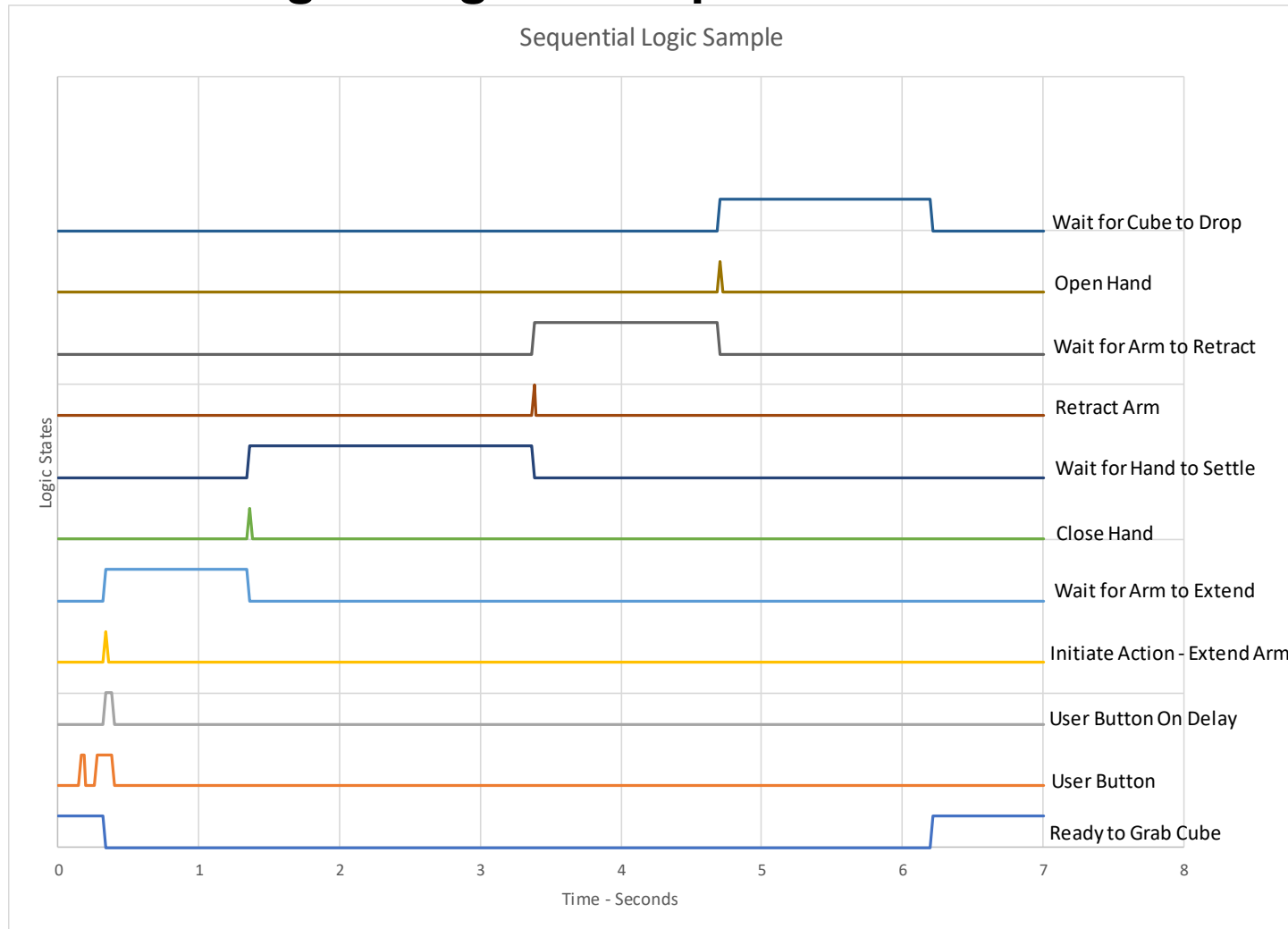
□ **Sample Problem – Cube Grab**

- Control system uses a 20 msec loop time
- System is ready when “hand” is opened and “arm” is retracted
- Users pushes button to initiate “cube grab”. Auto repeat of cube grab is not allowed.
- Ensure user pushed button for 60 msec
- Close “arm” extension solenoid. Wait 1 second for arm to extend.
- Close “hand” solenoid. Wait 2.0 seconds for “hand” to settle.
- Open “arm” extension solenoid. Wait 1.3 seconds for arm to retract.
- Open “hand” solenoid to release potential cube into bin. Wait 1.5 seconds for cube to drop before allowing next “grab” action.

□ **Enhancement – Add a cancel button**

Designing Sequential Logic 2/4

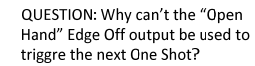
□ Draw the Logic Diagram Graph



Designing Sequential Logic 3/4

- **Start with inputs**
- **Determine relationships**
 - What inputs does an output relate to
- **Draw Logic Diagram**
- **Add intermediate Logic to Graph**
- **Repeat last two steps if needed to refine logic**

Final Logic Diagram



NOTE: The inputs to the FLIP/FLOPs can also be used to perform the solenoid output commands.

Exercise 5.1 - List Programming Objects

- **Create a list of potential objects from this chapter to program.**
 - List the inputs and outputs for each object.

Exercise 5.2 – Shoot frisbee

- **User pushes a button to shoot frisbee.**
- **Ensure user meant to push button. Button must be pressed for three cycles before initiating action. (Cycle time is 0.020 seconds).**
- **Can only shoot a frisbee if we have one. A limit switch indicates this. Also battery voltage must be > 11.5 volts. Can only shoot one frisbee at a time.**
- **Motors take 3 seconds to spin up to speed.**
- **Engage solenoid for 2 second to push frisbee into shooting wheel.**
- **Allow 2 more seconds for shooting to occur.**
- **After shooting is done, stop motor. (For now, don't allow continuous shooting.)**
- **Allow user to press a Cancel button. The cancel button must be pressed for at least 3 cycles before becoming active. After the Cancel, force a 5 second reset before allowing a new shot.**
- **It takes 5 seconds after shooting for a new frisbee to be in place ready to shoot.**
- **Design shooting logic. Also provide “ready to shoot” digital for dashboard display. Use ONLY the algorithms discussed in this module, and perhaps module 4.**