

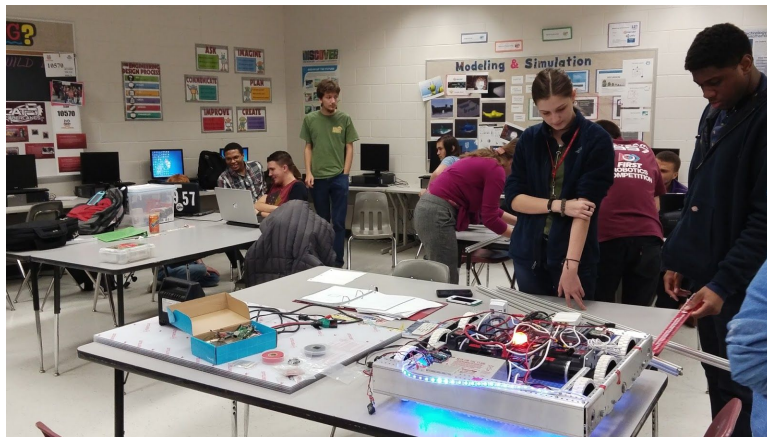
February 18, 2017

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Good afternoon everyone, and welcome to the sixth entry of *Plugged In*.

During the meeting on February 14th, the financial team continued to form the cost sheet for the team. The mechanical team started building the mechanisms that will be installed onto the robot, Okeechobee. The electrical team removed the electronics on the robot so mechanical could plan out the installment locations of the mechanisms. The programming team adjusted the program for the camera and attempted to combine the camera code and the program for the lift mechanism. The communications team. The drive team found the dimensions and angles of the game field.



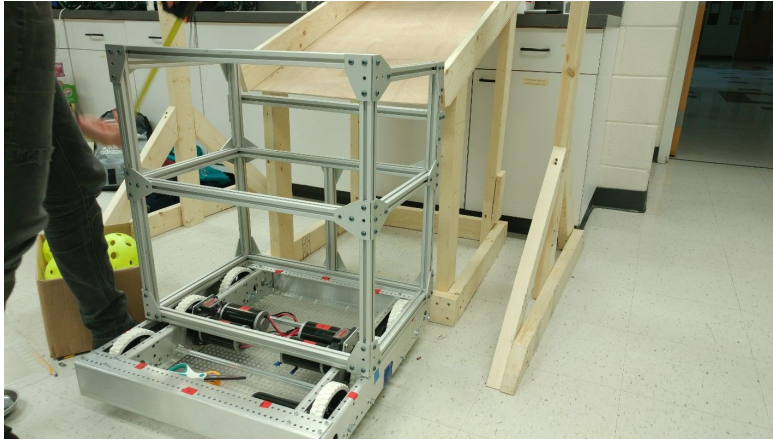
During the meeting on February 16th, the mechanical team started on building the frame that will be attached to the chassis. The electrical team mounted a window motor onto a metal bar, which will be used to construct the door mechanism. They also helped mechanical with building the frame. The drive team spent the meeting perfecting the strategy that will be used during the competition and helping mechanical and electrical. Since

Correspondent: Jalen Waye

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the mechanical, electrical, and drive teams were working on the robot, the programming team modified the existing code. The financial team started planning out ways to contact sponsors. The communications team composed a list of awards we will be striving to achieve.



During the meeting on February 18th, the electrical team continued construction on the door mechanism. The communications team compiled a list of possible locations we could outreach to the community. The mechanical team finished the frame and worked on the dump and coil. The drive team had no specific goal during the meeting, so they helped the other teams when they asked.

Since the programming team couldn't test the code on the robot since it was being worked on, they finished porting vision processing from RoboRio to PC. The financial team composed a list of possible companies we would want to sponsor us.