

# ROS Terminal

The ROS Terminal provides a space for visualizing what is going on in your environment. In the terminal, you can view the current master and whether or not it is live as well as see your own IP address. You can also change or start a master and open nodes. Clicking My Web and Master Web generate HTML pages that you can use to see what servers and topics are open and debug any problems. The three lists let you see nodes, logs, and servers. Dots next to logs indicate that the server is still running and Xs next to logs indicate an error. Clicking on an item in these lists allows you to further interact with the selection by seeing what is being sent back and forth as well as what items are on the queue. Items listed under elements are what is being passed back and forth in the queue. You can also use the terminal to close nodes and servers.

