



# Programação concorrente

## 10 – Threads

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# Bibliography

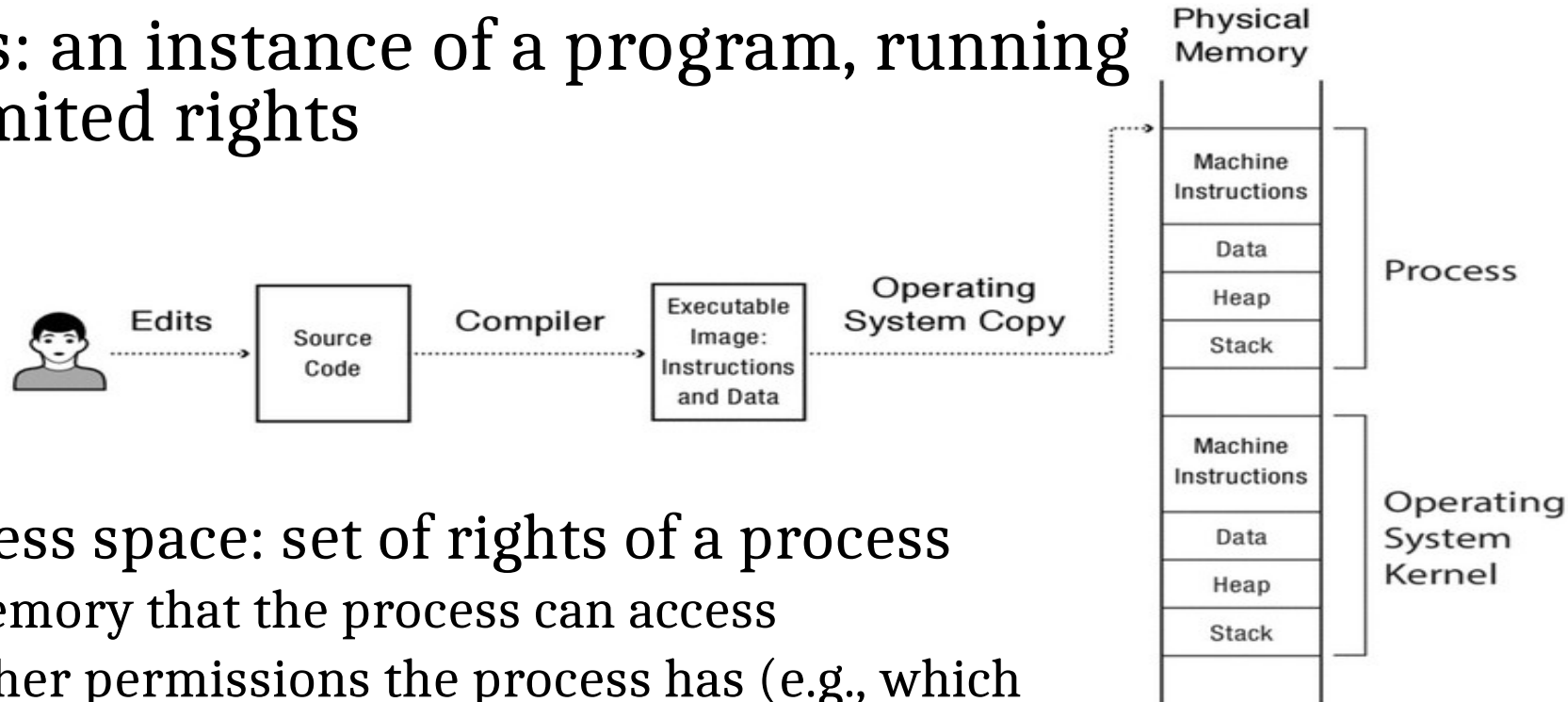
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- The Linux Programming Interface, Michael Kerrisk,
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  - Chapters 1 and 2

# Parallelism/concurrency

- OS need to support concurrency
  - Multiple tasks running at the same time
- Simplest abstractions
  - Process
  - Thread
- On multiprocessors
  - Processes and threads allow parallelism

# Process Abstraction


- Process: an instance of a program, running with limited rights



- Address space: set of rights of a process
  - Memory that the process can access
  - Other permissions the process has (e.g., which system calls it can make, what files it can access)




# Processes

- Distributed-memory multi-computers
    - Process fits perfectly
    - Independent memory nodes
      - Independent memory for processes
  - Parallel programming models
    - Tasks and Channels
    - Message passing
    - Data Parallelism
- 



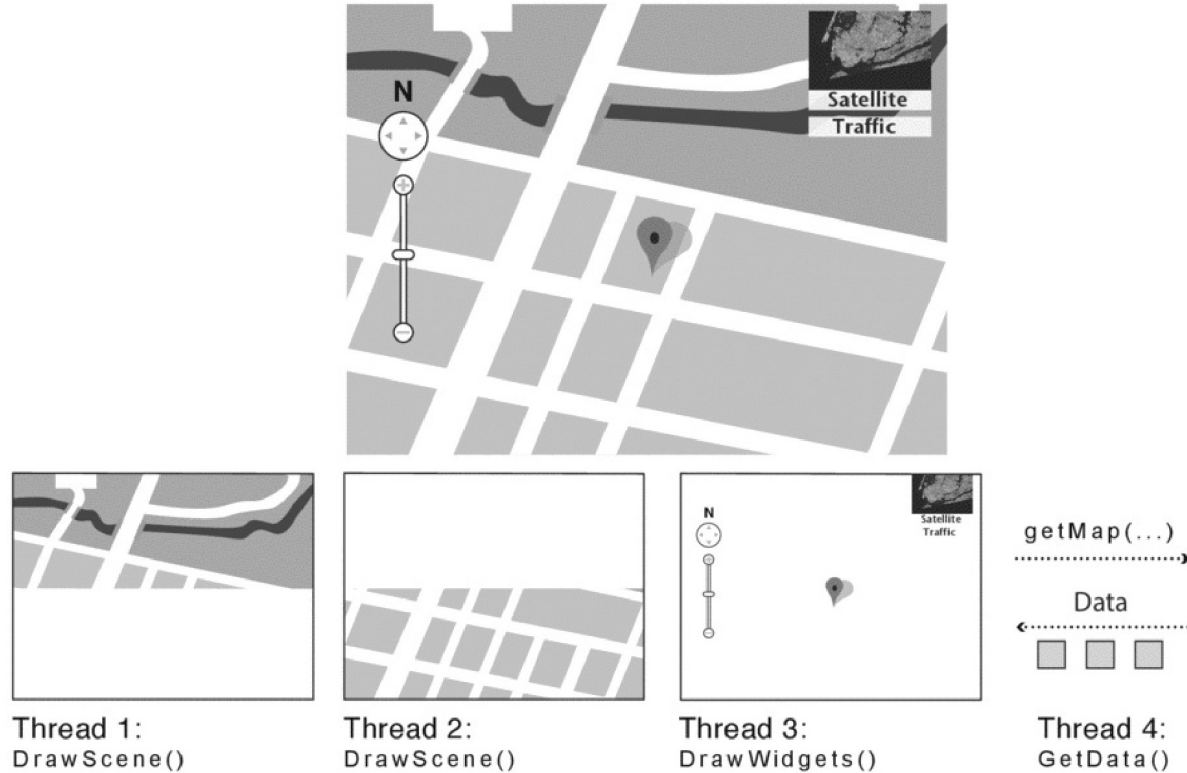
# Processes

- Shared-memory multi-computers
    - Processes are isolated entities
    - Shared memory is complex
  - Requires Middle-ware
    - Launch of processes
    - Explicit communication
- 

# Threads

- A Thread is an independent stream of instructions that can be schedule to run as such by the OS
  - Concurrent procedure inside a process
  - Runs independently from its main program.
- A Thread exists within a process and uses the process resources.

# Thread



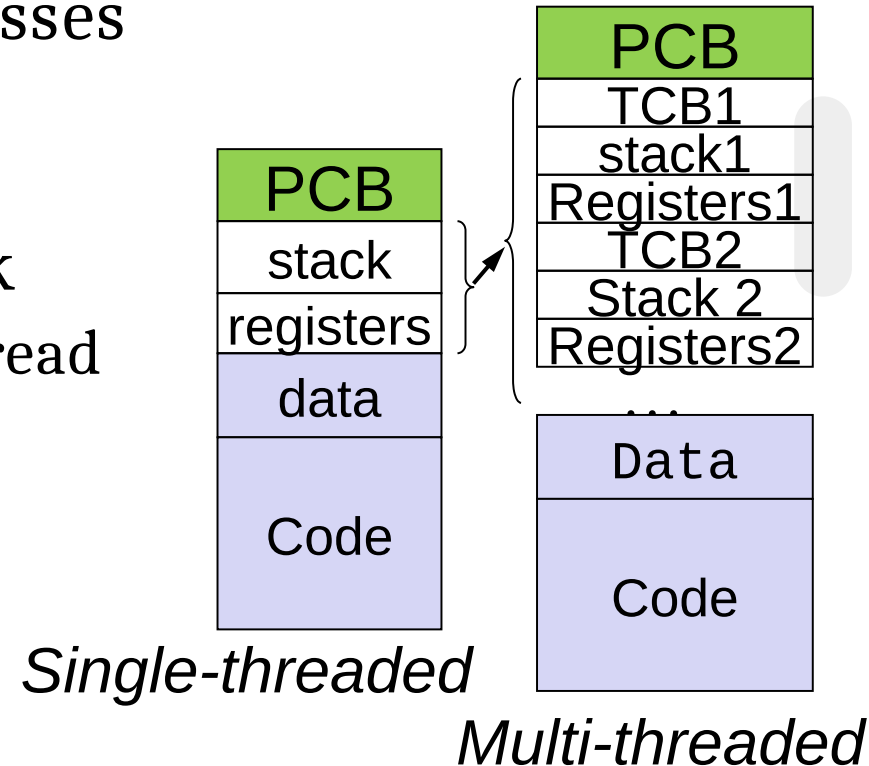


# Threads resources

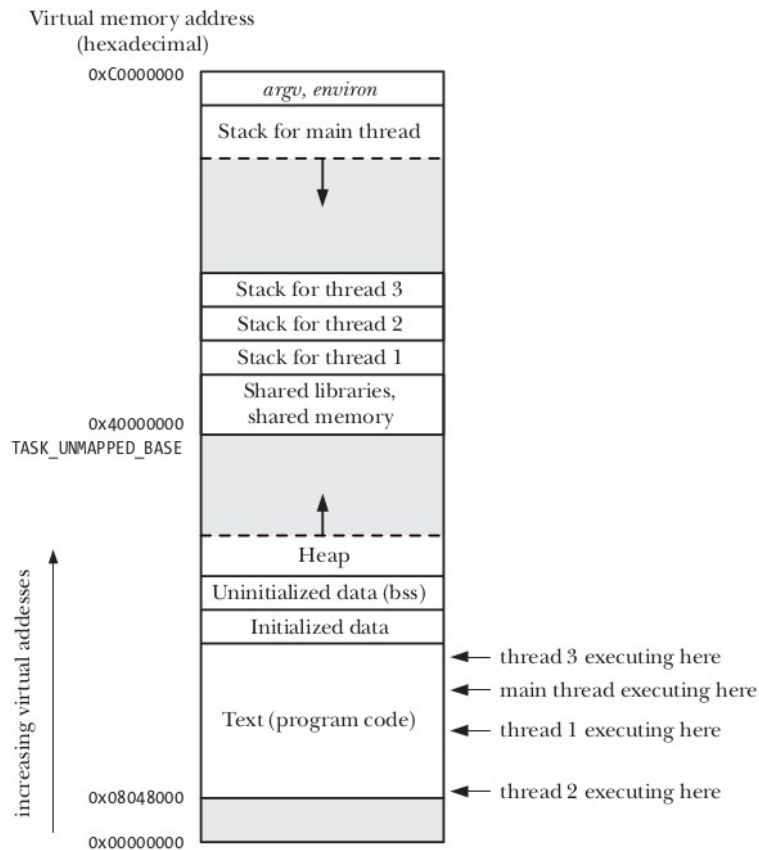
- Threads only duplicate the essential resources
  - necessary to be independently scheduled
- A thread will die if the parent process dies.
- A thread is “lightweight”
  - most of the overhead has already been accomplished through the creation of the process.
- Private
  - Processor register
  - Stack
- Shared
  - Memory
  - Resources (files, ...)

# Process structure

- Threads require changes on processes
  - Each thread has a local TCB
    - Thread Control Block.
- Each thread contains its own stack
  - Local variables are local to each thread
- Threads share
  - Code
  - Global variables
  - Resources (FILES, IPC)




# Threads inside processes



Shared	Not Shared
PID / PPID	Thread ID
Terminal	Signal mask
Open files	Thread specific Data
Timers	Alternative signal stack
Resource limits	Errno
	CPU affinity
	Stack



# Thread API

- There are several APIs
    - Win32 threads.
    - C-Threads (user level)
    - Pthreads
      - POSIX IEEE 1003.1c, published in 1995
- 

# Simple Threads API

- **void thread\_create (thread, func, arg)**
  - Create a new thread, storing information about it in thread.
  - Concurrently with the calling thread
    - thread executes the function func with the argument arg.
- **void thread\_yield ()**
  - The calling thread voluntarily gives up the processor to let some other thread(s) run.
  - The scheduler can resume running the calling thread whenever it chooses to do so.

# Simple Threads API

- **int thread\_join (thread)**
  - Wait for thread to finish if it has not already done so;
    - then return the value passed to thread\_exit by that thread.
  - thread\_join may be called only once for each thread.
- **void thread\_exit(ret)**
  - Finish the current thread.
  - Store the value ret in the current thread's data structure.
  - If another thread is already waiting in a call to thread\_join, resume it.

# POSIX Thread API

- POSIX defines functions for the management of threads
  - Functions/data started with the prefix `pthread_`
- Definitions available in the `pthread.h` file
- Code should be linked with the pthread library
  - `-lpthread`

# POSIX Thread creation

- The `main()` method comprises
  - a single, default thread.
- **`pthread_create()`**
  - creates a new thread and makes it executable.
- The maximum number of threads that may be created by a process is implementation dependent.
- Once created, threads are peers, and may create other threads.



# Thread creation

```
int pthread_create(  
    pthread_t *thread, pthread_attr_t *attr,  
    void *(*start_routine) (void *), void *arg);
```

- 1st parameter - Pointer to thread identifier (out)
- 2nd parameter - Pointer to thread attributes (IN)
  - Can be NULL.
- 3rd parameter - Pointer to function containing the thread code
  - Function should be: void \* (func\*) (void \* arg).
- 4th parameter - Pointer to thread arguments (IN)
  - Pointer to array, structure, int, .... (can be NULL)
- Returns 0 if successful
-

# Thread termination

- Several ways to terminate a thread:
  - The thread function is complete and **returns**
  - The `pthread_exit()` method is called
- The **`exit()`** method is called and terminates all threads
- **`void pthread_exit(void *retval);`**
  - terminates calling thread
  - **`Retval`** points to value accessible using `pthread_join`

# Thread termination

- If the main thread finishes with **pthread\_exit**
  - the other threads will continue to exist
- The **pthread\_exit** does not close files
  - any files opened inside the thread will remain open
- The **pthread\_exit** does not free memory
  - All allocated memory remains

# Thread joining

- A thread terminates itself by calling
  - `int pthread_exit(void *ret)` or `return ret_val`
  - The 1<sup>st</sup> parameter is a pointer to any data type
    - Memory location should be accessible outside (either global variable or malloc)
- After `pthread_exit` some resources are maintained
  - Until corresponding `pthread_join()`.
- Any other thread can retrieve returned data
  - `int pthread_join(pthread_t thread, void **retval);`

# Wait for a thread

- A thread waits for another thread executing `pthread_join`
  - To release resources
  - To fetch returned data
  - **`int pthread_join(pthread_t thread, void **retval);`**
    - 1st parameter - thread identifier.
    - 2nd parameter - Pointer to location of returned value
- function waits for the thread specified by thread to terminate.
- If that thread has already terminated, then `pthread_join()` returns immediately.
- Only one thread can wait/join another thread

# in/out Data transfer

- Data can be transmitted to the thread in several ways
  - Global variables
    - Accessible by all threads (synchronization should be applied)
  - 4<sup>th</sup> parameter of `pthread_create`
    - This parameter points to any data structure the programmer defines
    - Not use same memory location to multiple threads
      - Coherency not guaranteed
- Out data follows similar pattern

# Data Transfer patterns

- Each thread need to do its work
  - Independent
  - Complementary
- Each thread requires
  - Shared data
  - Private data
  - Individual data
    - Supplied at creation time
    - 4<sup>th</sup> argument of `pthread_create` / function argument

# Data transfer into threads

- Thread accepts a (void \*)
  - void \* - 8 bytes
  - int, float - 4 bytes
  - long, double - 8 bytes
  - Char - 1 byte

```
void * thread_func(void * arg){  
    int val = (int) arg;
```

- pthread\_create accepts scalars

```
for (int i = 0; i < 4; i++){  
    pthread_create(&t_id[0], NULL,  
                  thread_func, i);  
}
```



# Data transfer into threads

- Thread accepts a (void \*)
  - void \* - 8 bytes
  - All pointers – 8 bytes

- pthread\_create accepts scalars

```
for (int i = 0; i < 4; i++)  
    pthread_create(&tid[i], NULL,  
                  thread_func, &i);  
}
```

**BAD! BAD! BAD!**

# Data transfer into threads

- Thread accepts a (void \*)
  - void \* - 8 bytes
  - All pointers – 8 bytes
- pthread\_create accepts scalars

```
void * thread_func(void * arg){  
    int val = *((int*) arg);  
}
```

# Data transfer into threads

```
for (int i = 0; i < 4; i++){  
    int * int_p = malloc(sizeof(int));  
    *int_p = i;  
    pthread_create(&t_id[0], NULL, thread_func, int_p)  
}
```

# Data transfer out of threads

- Threads return a (void \*)
  - Can return a scalar

```
void * thread_func(void * arg){  
    int val = .....;  
    return val;  
}  
    void * ptr_ret;  
    pthread_join(t_id[0], &ptr_ret);  
    printf("thread return %d\n", (int)ptr_ret);
```

# Data transfer out of threads

- Threads return a (void \*)

- Can return a pointer

```
void * thread_func(void * arg){
```

```
    int val = .....;
```

```
    return & val;
```

```
}  
    void * ptr_ret;  
    pthread_join(t_id[0], &ptr_ret);  
    printf("thread return %d\n", *(int*)ptr_ret);
```

# Data transfer out of threads

```
void * thread_func(void * arg){
    int val = .....;
    int * ptr_ret = malloc(sizeof(int));
    *ptr_ret = val;
    return ptr_ret;
}

void * ptr_ret;
pthread_join(t_id[i], &ptr_ret);
printf("thread return %u\n" * (int *)ptr_ret);
free(ptr_ret);
```

# Access to shared data....

- Concurrency
  - e.g. multiple threads increment same variable

- Random sleeps

- Small loops

```
void * thread_func(void * arg){  
    for (int i = 0; i < 10000; i++){  
        usleep(random()%500000);  
        n++;  
    }
```

```
void * thread_func(void * arg){  
    for (int i = 0; i < 10; i++){  
        n++;  
    }
```

LUCKY SHOTS!!!

# Access to shared data....

- Isolate each thread
  - Arrays or local variables
  - Processing after the join

```
void * thread_func(void * arg){  
    int n_thread = (int)arg;  
    n_array[n_thread] = 0;  
    for (int i=0; i<LENGTH; i++)  
        n_array[n_thread]++;  
}
```

```
void * thread_func(void * arg){  
    int n = 0;  
    for (int i = 0; i < LENGTH; i++)  
        n++;  
    return n;  
}
```