

# 第一类拉格朗日方程的推导

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①: 首先对受理想约束非自由系统, 有约束方程

1) 完整:  $f_s(x_1, y_1, z_1, \dots, x_n, y_n, z_n, t) = 0 \quad (s=1, 2, \dots, l)$

2) 非完整:  $\sum_{i=1}^n (a_{ri} \dot{x}_i + b_{ri} \dot{y}_i + c_{ri} \dot{z}_i) + e_r = 0 \quad (r=1, 2, \dots, m)$

则: 对①求时间偏导:

$$\frac{\partial f_s}{\partial x_1} \dot{x}_1 + \frac{\partial f_s}{\partial y_1} \dot{y}_1 + \dots + \frac{\partial f_s}{\partial t} = 0$$

$$= \sum_{i=1}^n \left( \frac{\partial f_s}{\partial x_i} \dot{x}_i + \frac{\partial f_s}{\partial y_i} \dot{y}_i + \frac{\partial f_s}{\partial z_i} \dot{z}_i \right) + \frac{\partial f_s}{\partial t} = 0 \quad (s=1, 2, \dots, l)$$

写成变分方程的形式:

$$\begin{cases} a_{ri} \delta x_i + b_{ri} \delta y_i + c_{ri} \delta z_i = 0 \quad (r=1, 2, \dots, m) \\ \left( \frac{\partial f_s}{\partial x} \delta x_i + \frac{\partial f_s}{\partial y} \delta y_i + \frac{\partial f_s}{\partial z} \delta z_i \right) = 0 \end{cases}$$

代入动力学普遍方程

3)  $\lambda$  Lagrange 乘子  $\lambda_r, \mu_r$  并添加到  $\sum_{i=1}^n (F_i - m_i a_i) \delta r_i = 0$   
方程中, 则

$$m_i \ddot{x}_i \delta x_i = \left( F_{xi} - \sum_{r=1}^m \lambda_r a_{ri} - \sum_{r=1}^m \mu_r \frac{\partial f_s}{\partial x} \right) \delta x_i$$

故: 
$$\begin{cases} m_i \ddot{x}_i = F_{xi} - \sum_{r=1}^m \lambda_r a_{ri} - \sum_{r=1}^m \mu_r \frac{\partial f_s}{\partial x} \\ m_i \ddot{y}_i = F_{yi} - \sum_{r=1}^m \lambda_r b_{ri} - \sum_{r=1}^m \mu_r \frac{\partial f_s}{\partial y} \\ m_i \ddot{z}_i = F_{zi} - \sum_{r=1}^m \lambda_r c_{ri} - \sum_{r=1}^m \mu_r \frac{\partial f_s}{\partial z} \end{cases}$$