とといって、後つとも、ウロノトもと、この
谐波平衡法(部分推导) Wednesday, June 4, 2025 7:36 PM
mx + cx + f(t) = F(t)
取duffing 系统方程:
$\ddot{x}+2 \xi \omega_0 \dot{x}+k_1 x+k_3 x^3=A \cos(\omega t)$
设×为;
X = affisin wt + b (t) as we
则x(t)= act)onwt+b(t)oswt
tact) w oswt-b(t) w sinut
> (act) -b(t) w) sin w t
+ (b(t) + a(t)w) oxwt
$\ddot{\chi}(t) = (\ddot{a}(t) - \dot{b}(t)) \omega - \dot{b}(t) \omega a(t) \omega$ sinut
$+(\dot{a}(t))W - \dot{b}(t)W^2 + \dot{b}(t) + \dot{a}(t)W)$ coswt
= $(\dot{a}(t)-2\dot{b}(t)w-\omega^2a(t))$ sinwt
+ (2à (4) w + b (4) - b(4) w2) as wt
我们认为, a,b为慢变时间参数(= a(t)
=6 Ct)=0
(1) ( - act) w 2 - 26 (t) w coswt
$+ [-b(t)w^2 + 2 a(t)w] sinwt$
7
7 +25 wox+k,x+k, x3= Acoswt,

1 sin ut = sin 2 wt oos ut - cos 2 wt sin ut



