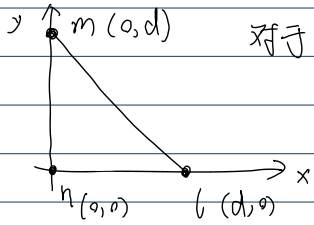


对于如图, 厚为 h 的等腰直角三角形, 直角边长 d ,
单元的直角边为 x, y 轴, 求其形状函数并建立
单元刚度矩阵,



解:

设如图的等腰三角形各个节点的位移为 $\{\delta\}^e$

设整个单元的位移函数为:

$$\{\delta\}^e = \begin{Bmatrix} u_l \\ v_l \\ u_m \\ v_m \\ u_n \\ v_n \end{Bmatrix}$$

$$\begin{cases} u = a_1 + a_2 x + a_3 y \\ v = a_4 + a_5 x + a_6 y \end{cases} \quad \text{则: } \{\delta\}^e = [A] \{a\}$$

$$\text{其中: } A = \begin{bmatrix} 1 & x_l & y_l & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & x_l & y_l \\ 1 & x_m & y_m & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & x_m & y_m \\ 1 & x_n & y_n & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & x_n & y_n \end{bmatrix}$$

$$\text{有: 对整个单元有: } \{\delta\} = \begin{bmatrix} 1 & x & y \\ 0 & 0 & 0 \\ 1 & x & y \end{bmatrix} \{a\} = [M] \{a\} = [M][A]^{-1} \{\delta\}^e$$

其中令 $[M][A]^{-1} = [N]$ 为形函数,

有:

$$N_l = \frac{a_6 + b_6 x + c_6 y}{2\Delta}$$

$$\text{并有 } \Delta = \begin{vmatrix} 1 & x_l & y_l \\ 1 & x_m & y_m \\ 1 & x_n & y_n \end{vmatrix} = \begin{vmatrix} 1 & d & 0 \\ 1 & 0 & d \\ 1 & 0 & 0 \end{vmatrix}$$

$$\text{有: } a_6 = 0, \quad b_6 = -\begin{vmatrix} 1 & d \\ 1 & 0 \end{vmatrix} = +d, \quad c_6 = \begin{vmatrix} 1 & 0 \\ 1 & 0 \end{vmatrix} = 0$$

$$\Delta = \frac{1}{2} \Delta = \frac{1}{2} \begin{vmatrix} 1 & d & 0 \\ 1 & 0 & d \\ 1 & 0 & 0 \end{vmatrix} = \frac{1}{2} d^2 = S_\Delta$$

$$\text{故有: } N_l = \frac{dx}{d^2} = \frac{x}{d}$$

$$N_m = \frac{a_5 + b_5 x + c_5 y}{2\Delta}, \quad a_5 = -\begin{vmatrix} d & 0 \\ 0 & 0 \end{vmatrix} = 0, \quad b_5 = \begin{vmatrix} 1 & 0 \\ 1 & 0 \end{vmatrix} = 0, \quad c_5 = -\begin{vmatrix} 1 & d \\ 1 & 0 \end{vmatrix} = d$$

$$= \frac{dy}{d^2} = \frac{y}{d}$$

$$N_n = \frac{a_4 + b_4 x + c_4 y}{2\Delta}, \quad a_4 = d^2, \quad b_4 = -\begin{vmatrix} 1 & 0 \\ 1 & d \end{vmatrix} = -d, \quad c_4 = \begin{vmatrix} 1 & d \\ 1 & 0 \end{vmatrix} = -d$$

$$= \frac{d^2 - dx - dy}{d^2} = \frac{d - x - y}{d} = 1 - \frac{1}{d}(x + y)$$

∴ 代入:

$$\{\delta\} = [N] \{\delta\}^e = \begin{bmatrix} \frac{x}{d} & \frac{y}{d} & 1 - \frac{x+y}{d} \\ \frac{x}{d} & \frac{y}{d} & 1 - \frac{x+y}{d} \end{bmatrix} \begin{Bmatrix} u_l \\ v_l \\ u_m \\ v_m \\ u_n \\ v_n \end{Bmatrix}$$

$$[d] = \begin{bmatrix} d & 0 & 0 \\ 0 & d & 0 \\ 0 & 0 & d \end{bmatrix} \begin{Bmatrix} v_m \\ v_n \\ v_n \end{Bmatrix}$$

$$N = \frac{1}{d} \begin{bmatrix} x & y & d-x-y \\ x & y & d-x-y \end{bmatrix}$$

对于平面应力问题, 可以得出应力矩阵为:

$$\sigma = \begin{bmatrix} \frac{\partial}{\partial x} \\ \frac{\partial}{\partial y} \\ \frac{\partial}{\partial y} \frac{\partial}{\partial x} \end{bmatrix} [u] \text{ 其中: } [u] = [N] \{ \delta^e \} \text{ 取 } [-] [N] = B,$$

$$[B] = \frac{1}{d} \begin{bmatrix} 1 & 0 & 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & 1 & 0 & -1 \\ 0 & 1 & 1 & 0 & -1 & -1 \end{bmatrix} = \frac{1}{d} \begin{bmatrix} 1 & 0 & 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & 1 & 0 & -1 \\ 0 & 1 & 1 & 0 & -1 & -1 \end{bmatrix}$$

刚度矩阵可通过公式求得, 有:

$$[k]^e = \begin{bmatrix} k_{11} & k_{1m} & k_{1n} \\ k_{m1} & k_{mm} & k_{mn} \\ k_{n1} & k_{nm} & k_{nn} \end{bmatrix} \text{ 其中 } [k_{rs}]^e = \frac{Eh}{2(1-\nu^2)d} \begin{bmatrix} b_r b_s + \frac{1-\nu}{2} c_r c_s & \mu b_r c_s + \frac{1-\nu}{2} c_r b_s \\ \mu b_s c_r + \frac{1-\nu}{2} c_s b_r & c_r c_s + \frac{1-\nu}{2} b_r b_s \end{bmatrix}$$

$$\text{有: } [b \ c] = \begin{bmatrix} d & 0 \\ 0 & d \\ -d & d \end{bmatrix} \text{ 代入: } [k_{rs}]^e = \frac{Eh}{2(1-\nu^2)d^2}$$

$$\frac{Eh}{2(1-\nu^2)d^2}$$

$$k_{13} = \begin{bmatrix} -d^2 & -\nu d^2 \\ \frac{1-\nu}{2} d^2 & \frac{1-\nu}{2} d^2 \end{bmatrix}$$

$$k_{23} = \begin{bmatrix} -\frac{1-\nu}{2} d^2 & -\frac{1-\nu}{2} d^2 \\ -\nu d^2 & -d^2 \end{bmatrix}$$

$$[k_{rs}]^e = \frac{Eh}{2(1-\nu^2)d^2} \begin{bmatrix} d^2 & 0 & 0 & \nu d^2 & -d^2 & -\nu d^2 \\ 0 & \frac{1-\nu}{2} d^2 & \frac{1-\nu}{2} d^2 & \frac{\nu}{2} d^2 & \frac{\nu}{2} d^2 & \frac{\nu}{2} d^2 \\ 0 & \frac{\nu}{2} d^2 & \frac{\nu}{2} d^2 & 0 & 0 & 0 \\ \frac{1-\nu}{2} d^2 & \frac{\nu}{2} d^2 & \frac{\nu}{2} d^2 & 0 & 0 & 0 \\ -d^2 & -\frac{\nu}{2} d^2 & -\frac{\nu}{2} d^2 & 0 & d^2 & -\nu d^2 \\ \frac{\nu}{2} d^2 & \frac{\nu}{2} d^2 & \frac{\nu}{2} d^2 & -\nu d^2 & -\nu d^2 & \frac{3-\nu}{2} d^2 \end{bmatrix}$$

即:

$$[K_{ss}]^e = \frac{Eh}{2(1-\nu^2)d^2} \begin{bmatrix} 1 & 0 & 0 & \nu & -1 & -\nu \\ 0 & 0 & \frac{1-\nu}{2} & \frac{1-\nu}{2} & \frac{\nu}{2} & \frac{\nu}{2} \\ 0 & \frac{1-\nu}{2} & 0 & 0 & \frac{\nu}{2} & \frac{\nu}{2} \\ \nu & \frac{1-\nu}{2} & 0 & d^2 & -\nu & -1 \\ -1 & \frac{\nu}{2} & \frac{\nu}{2} & -\nu & \frac{3-\nu}{2} & \frac{1-\nu}{2} \\ -\nu & \frac{\nu}{2} & \frac{\nu}{2} & -1 & \frac{1-\nu}{2} & \frac{3-\nu}{2} \end{bmatrix}$$

单元的刚度矩阵

附注: 实际上, 对于平面问题, 若材料物理性质相同, 则几何形状相似的元素都有相同的位移刚度矩阵。

我们在上述题图中, 可取: $\{ \delta \}^e = [1, 0, 0, 0, 0, 0]^T$, 则

$$[u] = \frac{1}{d} \begin{bmatrix} x & y & d-x-y \\ x & y & d-x-y \end{bmatrix}, \text{ 则 } \{ \delta \} = [N] \{ \delta^e \}$$

代入得:

$$u = \frac{x}{d}, \nu = 0,$$

$$\begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

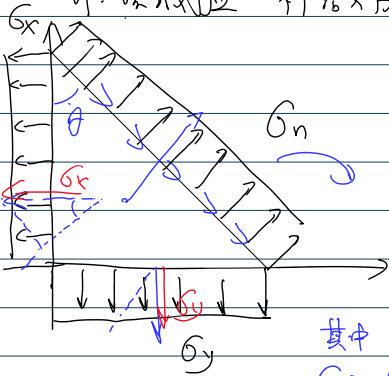
代入得:

$$u = \frac{x}{d}, \quad v = 0,$$

显然:

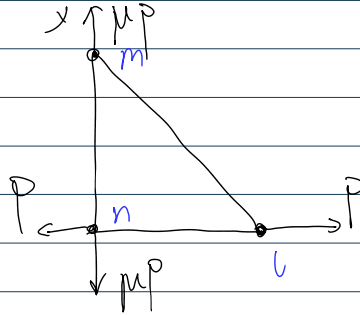
$$\varepsilon_x = \frac{\partial u}{\partial x} = \frac{1}{d}, \quad \varepsilon_y = 0,$$

即: 该式对应一种沿x方向的均匀拉伸状态;



其中

$$\begin{aligned} \sigma_n &= \sigma_x \cos^2 45^\circ \cos^2 45^\circ + \sigma_y \sin^2 45^\circ \cos^2 45^\circ \\ &= \frac{\sigma_x + \sigma_y}{2} \end{aligned}$$



我们可以令 $P = \frac{Eh}{2(1-\nu^2)d^2}$,

$$\text{则: } P_n = \begin{Bmatrix} P \\ 0 \end{Bmatrix}$$

$$P_m = \begin{Bmatrix} 0 \\ \nu P \end{Bmatrix} \quad P_l = \begin{Bmatrix} -P \\ -\nu P \end{Bmatrix}$$

如左图所示

利用应力矩阵

$$[S] = [D][\varepsilon] = \frac{E}{2\Delta(1-\mu^2)} \begin{bmatrix} b_i \mu C_i \\ \mu b_i C_i \\ \frac{1-\mu}{2} C_i \\ \frac{1-\mu}{2} b_i \end{bmatrix} \quad \text{其中 } [b_i C_i] = \begin{bmatrix} d & 0 \\ 0 & d \\ -d & -d \end{bmatrix}$$

故有:

$$[S] = \frac{E}{(1-\mu^2)d^2} \begin{bmatrix} d & 0 & 0 & \mu d & -\mu d & \mu \\ \mu d & 0 & 0 & d & -\mu d & -d \\ 0 & \frac{1-\mu}{2} d & \frac{1-\mu}{2} d & 0 & \frac{1-\mu}{2} d & \frac{1-\mu}{2} d \end{bmatrix} = \frac{E}{(1-\mu^2)d} \begin{bmatrix} 1 & 0 & 0 & \mu & -\mu & \mu \\ \mu & 0 & 0 & 1 & -\mu & -1 \\ 0 & \frac{1-\mu}{2} & \frac{1-\mu}{2} & 0 & \frac{1-\mu}{2} & \frac{1-\mu}{2} \end{bmatrix}$$

由: $[S] = [S]\{\varepsilon\}$, 代入有:

$$\begin{aligned} \sigma_x &= \sigma, \\ \sigma_y &= \mu\sigma, \quad \text{其中 } \sigma = \frac{E}{2(1-\mu^2)d} \\ \tau_{xy} &= 0 \end{aligned}$$

$$\text{故有: } \sigma_n = \frac{\sigma_x + \sigma_y}{2} = \frac{E(1+\mu)}{2(1-\mu^2)d} = \frac{E}{2(1-\mu)d}$$

$$\tau_n = \sigma_x \cos 45^\circ \sin 45^\circ - \sigma_y \sin 45^\circ \cos 45^\circ$$

$$= \frac{1}{2}(\sigma_x - \sigma_y) = \frac{E(1-\nu)}{2(1-\mu^2)d} \quad \text{则有}$$

$$\tau_n = \frac{E}{2(1+\mu)d} \quad \leftarrow \text{为应力分布}$$