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SUSHI++ COMPILER PROJECT REPORT [INF02049]

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Table des matières

1	Introduction							
2	Lan	nguage	1					
	2.1	General information	. 1					
	2.2	Type system	. 1					
		2.2.1 Arrays	. 1					
		2.2.2 Lists	. 2					
	2.3	Declarations	. 2					
		2.3.1 Functions	. 2					
		2.3.2 Variables	. 3					
	2.4	Expressions						
		2.4.1 Soy functions						
		2.4.2 Function calls						
		2.4.3 Operators						
	2.5	Statements						
		2.5.1 Loops						
		2.5.2 Conditionals						
		2.5.3 Switch						
		2.0.0 Switch	. 0					
3	Con	mpiler	5					
	3.1	General information	. 5					
	3.2	Lexical and syntax analysis						
	3.3	Semantic analysis						
		3.3.1 Scope checking						
		3.3.2 Termination checking						
		3.3.3 Type checking and inference						
		-JF						
4	Flav	ws and possible improvements	10					
	4.1	Code generation	. 10					
		4.1.1 Code generation	. 10					
		4.1.2 Code construction	. 10					
5		ntime	10					
	5.1	Garbage collector	. 10					
	a							
A	Sources 1							
В	Dia	agrams	10					

1 Introduction

In the context of the course INFO0085, we had to develop a compiler for a handmade programming language called **Sushi++**. This language is garbage-collected and halfway between a functional and an imperative language of which the keywords are inspired from the *sushi food* lexical field. The first part of the report describes both syntax and semantic of the language (section 2) and the second details the compiler organization and algorithms (section 3). The Section ?? presents the organization of the small runtime library handling the garbage collector. Finally, in the Section ??, the improvements that could be made are discussed.

2 Language

2.1 General information

2.2 Type system

The Sushi++ language is a strongly and statically typed language. Nevertheless, to alleviate the programmer's work, the type system is made as unobtrusive as possible and types are inferred during compilation. The only presence of types in the language is the *function parameters hinting* mechanism: the parameter type can be specified next to the parameter name in the a function declaration (see Section 2.3.1). The available types are:

ullet bool : true or false

• char: a character

• int : an integer $\in [-2147483648, 2147483647]$

• float: a single-precision floating point value $\in [-3.403 \times 10^{38}, 3.403 \times 10^{38}]$

• array : an array of elements (see Section 2.2.1)

• list: a list of elements (see Section 2.2.2)

• string: a string

• function : a function

• void: return type for function that doesn't return anything

2.2.1 Arrays

Idea The array type represents a sequence of elements having a given type T and that are stored sequentially in the memory. This structure has the same behaviour as a vector data structure in terms of complexity. The Sushi++ arrays cannot stored any type of data, T can only be one among: int, float, char, string, bool. The index of an array is an integer in the interval [0, array size]. Arrays are passed to function and returned by reference (they are never copied).

Syntax To construct an array, its elements must be listed between the array delimiters #[and]# and separated by commas :

```
• array of integers: #[ 1, 2, 3, 4 ]#
```

- array of strings : #["str1", "str2", "str3", "str4"]#
- assigning a variable : maki a = #[true, false]#

To access an element in the array, the C-like array-access operator [] can be used with a valid index.

```
maki first_element = array[0]
```

A set of built-in functions are provided to the programmer to handle arrays. They are listed as follows in a C-like format :

• int array_size_T(array A) : return the size of the array

- void array_clear_T(array A) : empty the array
- void array_push_T(array A, T element): push an element at the last position of the array
- T array_pop_T(array A) : pop the element at the last position of the array
- T array_get_T(array A, int i) : return the element at the position i of the array
- void array_set_T(array A, int i, T element): replace the element at the position i by element
- void array_insert_T(array A, int i, T element) : insert element at the position i

Memory Arrays are **heap-allocated** and their memory is managed at runtime with a garbage collector (see Section 5.1).

2.2.2 Lists

The construction of lists follows the same principles as the construction of array except that the delimiters are the curly brackets characters :

- array of integers : { 1, 2, 3, 4 }
- array of strings : { "str1", "str2", "str3", "str4" }
- assigning a variable : maki a = { true, false }

Lists *cannot* be accessed with the array-access operator. Nevertheless, a set of built-in functions are provided for interacting with them (inspired from standard C++ lists interface):

- int list_size(List 1) : return the size of the list
- bool list_empty(List 1): return true if the list is empty, false otherwise
- void list_clear(List 1) : clear the content of the list
- T list_front_T(List 1): return the element at the front of the list
- T list_back_T(List 1): return the element at the back of the list
- T list_pop_front_T(List 1) : remove and return the element at the front of the list
- T list_pop_back_T(List 1): remove and return the element at the back of the list
- void list_push_front_T(List 1): push an element at the front of the list
- void list_push_back_T(List 1): push an element at the back of the list
- T list_get_T(List 1, int pos) : get the element at the given position of the list
- void list_insert_T(List 1, int pos, T elem): insert an element at the given position of the list
- T list_remove_T(List 1, int pos): remover the element at the given position of the list

Memory Lists are **heap-allocated** and their memory is managed at runtime with a garbage collector (see Section 5.1).

2.3 Declarations

The Sushi++ language provides declaration syntax for both functions and variables. The declaration keyword maki is common to both declaration.

2.3.1 Functions

Idea The function declared with the maki keyword are called **named function** in opposition to anonymous function (or *soy functions*, see Section 2.4.1). As soon as it is declared, a function can be either called (see Section 2.4.2) or used as expression (passed as parameter). A declared named function is accessible in the scope in which it is declared and its nested scopes (including the function own scope).

Syntax The named function declaration syntax is the following:

```
maki function_name {parameter_name[< type >|} : function_body;;
```

The type element must be one of the types listed in the Section 2.2 except void.

2.3.2 Variables

Idea A variable must be assigned a value when it is declared. It is accessible in the scope in which it is declared and its nested scopes but **cannot be captured** in a function. A variable can only by reassigned a value having the same type as the one initially assigned.

Syntax Several variables can be declared with a single maki, the different declarations must be separated by commas:

```
maki variable_name = expression {, variable_name = expression }
```

2.4 Expressions

2.4.1 Soy functions

Idea Soy functions or anonymous functions are functions that are not bound to an identifier. They can either be used as value (passed as parameters), be called (see Section 2.4.2) or stored into a variable.

Syntax A soy function is declared by using the soy keyword:

```
(soy \{parameter[< type>]\} : function\_body)
```

Various usages:

- Storing an anonymous function in a variable: maki f = (soy x : nori x)
- Passing an anonymous function as parameter: call func (soy x : nori x) a
- Calling an anonymous function: call (soy x : nori x) 1

2.4.2 Function calls

Idea A function call is triggered with the call keyword followed by a function name or an expression that can be evaluated as a function. The keyword call is meant to prevent the ambiguity between a function call and a variable utilisation. A function call must be braced when its arguments are placed on several lines or if it is embedded into another expression.

Syntax The syntax for calling a function is the following:

```
call (function_name|soy_expression) { argument }
```

Various usages:

- Calling a function: call func param1 param2
- Calling an anonymous function: call (soy x : nori x) 1
- Embedded call: a = (call func c d)

2.4.3 Operators

The Sushi++ language provides a set of operators for expressing operations on flat types. These operators are listed in the Table 1 which describes their properties. The precedence and associativity was inspired from the C language. Therefore, in general, operators are left associative except for the assignment 1 and exponentiation. The precedence number given in the table decreases with the priority of the operator.

^{1.} so that they can be chained

	Arity	Assoc.	Prec.	Comment	Operand types	
Op.					Operand 1	Operand 2
op ++	1	/	1	Postfix increment	{int,float}	
op	1	/	1	Postfix decrement	{int,float}	
++ op	1		2	Prefix increment	{int,float}	
op	1	/	2	Prefix decrement	$\{\mathtt{int},\mathtt{float}\}$	
op1 ** op2	2	right	3	Exponent	{int,float}	int
op1 . op2	2	right	3	String concatenation	string	string
- op	1	/	4	Unary minus	{int, float}	
~ op	1	/	5	Bitwise not	int	
! op	1	/	5	Logical not	bool	
op1 * op2	2	left	6	Mutliplication	{int,float}	same as op1
op1 / op2	2	left	6	Division	{int,float}	same as op1
op1 % op2	2	left	6	Modulo	int	int
op1 + op2	2	left	7	Addition	{int,float}	same as op1
op1 - op2	2	left	7	Substraction	{int,float}	same as op1
op1 >> op2	2	left	8	Right shift	int	int
op1 << op2	2	left	8	Left shift	int	int
op1 < op2	2	left	9	Greater than	{int,float}	same as op1
op1 > op2	2	left	9	Equal to	{int,float}	same as op1
op1 <= op2	2	left	9	Less or equal to	{int,float}	same as op1
op1 >= op2	2	left	9	Greater or equal to	{int,float}	same as op1
op1!= op2	2	left	10	Not equal to	{int, float, bool}	same as op1
op1 == op2	2	left	10	Equal to	{int, float, bool}	same as op1
op1 & op2	2	left	11	Bitwise and	int	int
op1 ^ op2	2	left	12	Bitwise xor	int	int
op1 op2	2	left	13	Bitwise or	int	int
op1 && op2	2	left	14	Logical and	bool	bool
op1 op2	2	left	15	Logical or	bool	bool
op1 += op2	2	right	16	Addition assignment	{int,float}	same as op1
op1 -= op2	2	right	16	Substraction assignment	{int,float}	same as op1
op1 *= op2	2	right	16	Mutliplication assignment	{int,float}	same as op1
op1 /= op2	2	right	16	Division assignment	{int,float}	same as op1
op1 %= op2	2	right	16	Modulo assignment	int	int
op1 **= op2	2	right	16	Exponent assignment	$\{ \mathtt{int}, \mathtt{float} \}$	int
op1 .= op2	2	right	16	Concatenation assignment	string	string

Table 1 – Sushi++ operators

2.5 Statements

2.5.1 Loops

The Sushi++ language provides three kinds of loop.

Condition-controlled loop This loop is called roll and behaves like a C while loop. The scope containing this code fragment is delimited by the end of line following the condition and the scope delimiter;; The condition must be an expression of type bool, otherwise the compiler will return a type error. The syntax is the following:

```
roll condition
  roll scope
;;
```

Counter-controlled loop This loop is called for and behaves like a C for loop. Again, the condition must be an expression of type bool. Moreover, the initializer and update part must contain a modifying expressions (assignment or increment). The syntax is the following:

```
for init expression, condition, update expression
  for scope
;;
```

Collection-controlled loop This loop is called foreach and is made for iterating over lists. At the first iteration, the element at the front of the list is stored in the iteration variable. Then, at each iteration, the same goes for next value till the list was completely covered. The syntax is the following:

```
foreach list expression as variable
  foreach scope
;;
```

- 2.5.2 Conditionals
- 2.5.3 Switch
- 3 Compiler
- 3.1 General information
- 3.2 Lexical and syntax analysis
- 3.3 Semantic analysis
- 3.3.1 Scope checking
- 3.3.2 Termination checking
- 3.3.3 Type checking and inference

As the Sushi++ language is statically typed, the types must be checked at compile-time. This consists in checking the following properties:

- operands of an operators have valid types according to the Table 1.
- parameters of a function have the expected types
- function always returns an element of the same type, or it always returns nothing
- expressions used in statements have have a valid type (boolean for conditions or loop guardians for instance)

- variable can only be reassigned a value of the same type as the one initially assigned
- ...

As Sushi++ is free from type annotation, these checks cannot be performed directly and the types of expressions and identifiers have to be inferred.

Formally, the type inference problem can be as formulated as follows: given a set of types \mathcal{T} defined for the programming language, a set of expressions \mathcal{E} and a set of identifiers \mathcal{I} defined in a program, inferring the types consists in assigning a type $t \in \mathcal{T}$ for any identifier $i \in \mathcal{I}$ and expression $e \in \mathcal{E}$ used in the program (if the expression has no effect or if the identifier is not used in the program than knowing his type is not relevant). In the literature, a classical approach for assigning types is the Hindley-Milner (or Damas-Milner) algorithm. This algorithm assigns types to language constructs using a set of deduction rules and derivations. Unfortunately, this algorithm was designed for purely functional languages and is not directly applicable to the Sushi++ language.

Alternatively, the type inference can be seen as problem of **constraints generation and unification**. The types associated with the various program elements are represented by variables. Some constraints bringing in these variables are generated from some rules encoding the language type semantic and these constrains are unified to find the actual type of the program elements. Two sub-problems have therefore to be addressed to design the type inference algorithm: on the one hand, an unification algorithm has to be defined. On the other hand, for each Sushi++ construct, the type semantic has to be encoded into a rule defining the constraints to be generated.

Framework The algorithm associates a type variable, symbolized by a greek letters, to every language typed construct (including function parameters, return type and data structure elements' type). A variable is either resolved, meaning that it is associated with a valid type, or unresolved. A valid type is either a flat type (integer, float, char, string, bool or void) or a structured type of which the type parameters are valid types (array, list or function). A variable is also associated a set of types that it can be assigned and such a set is called *hints* (the hints of a variable α is noted \mathcal{H}_{α}). The hint system is a way to encode operator polymorphism and function parameter hinting. An unresolved type variable α can be resolved if \mathcal{H}_{α} contains only one flat type.

Unification The goal of the unification is to "find a substitution for all type variables that make the expressions identical" (taken from document [1a], slide 8). The algorithm used in the compiler is given in Listing 1 and uses the following function:

- is_unresolved(α): returns false if the variable is resolved, true otherwise
- is_function(α): returns true if the variable contains a function type, false otherwise
- count_parameters (α): given a variable containing a function type, return the number of parameters of this function
- get_return_type(α): given a variable containing a function type, return the type variable containing the return type of this function
- is_array(α): return true if the variable contains an array type, false otherwise
- is_list(α): return true if the variable contains an list type, false otherwise
- get_datastructure_type(α): given a variable containing an array or a list type, return the type variable containing the type of its elements

The worst-case complexity of the unification algorithm is $\Theta(n)$ where n is the number of parameters which intervenes in the types contained in α and β . This can be an issue when α and β both contains a function of which one of the parameters is a function taking itself as argument a function taking itself as argument a function, etc. Nonetheless, in the other cases, the complexity is $\mathcal{O}(1)$.

```
// Unification algorithm
unify ( \alpha, \beta )
  if is_unresolved(\alpha) || is_unresolved(\beta)
    if \mathcal{H}_{\alpha} \cap \mathcal{H}_{\beta} = \emptyset // check hints compatiblity
       throw error("incompatible hints")
    // update hints
    \mathcal{H}_{\beta} = \mathcal{H}_{\alpha} = \mathcal{H}_{\alpha} \cap \mathcal{H}_{\beta}
    // add indirection between the variables
    if is_unresolved(\alpha) { \alpha = \beta } else { \beta = \alpha }
    return
  }
  // both variables are resolved : the valid types must be compatibles
  if is_function(\alpha) && is_function(\beta) // variables are functions
  {
    if count_paramters(\alpha) != count_parameters(\beta)
      throw error ("function types should have the same number of parameters")
    for each parameters types variables \gamma of function \alpha and \delta of function \beta
      unify(\gamma, \delta)
    unify(get_return_type(\alpha), get_return_type(\beta))
  }
  // variables are both uniparameter types
  if ( is_array(\alpha) && is_array(\beta) ) || ( is_list(\alpha) && is_list(\beta) )
    \gamma = \text{get\_datastructure\_type}(\alpha)
    \delta = \text{get\_datastructure\_type}(\beta)
    unify(\gamma, \delta)
  // variables contains the same flat type
  if is_flat(\alpha) && is_flat(\beta) && \alpha = \beta
    return
  throw error("types cannot be unified")
```

Listing 1 – Unification algorithm

Constraints generation The constraints generation can be said to be syntax-directed. A set of type variables are passed to a node of the abstract syntax tree as inherited attributes. These variables contains the information about the types expected by the parent. Then, the node performs unification on these variables to signal the types it is expecting. It can also create new variables to pass to its children as inherited attributes.

Implementation The type inference is implemented in the ast/visitor/TypeInferenceVisitor.cpp file and uses the classes defined in the inference/ folder. The main idea is to store all variables and their associated type into a type symbol table. This table is implemented as a structure mapping a variable name to an object representing the type associated with this variable (of class TypeSymbol). The creation of variables consists in adding entries in this table and unification in updating it.

A key element of the table design is that, if two variables were unified, updating the type of one of them must be automatically reflected in the other. To achieve this, the elements mapped in the type symbol table are TypeLink objects introducing a level of indirection between a variable name and its actual type. The only attribute of a TypeLink is simply a pointer to another TypeSymbol. The class hierarchy of type symbols is described hereafter.

Type symbols The types symbols are objects designed to represents types. The base class TypeSymbol is derived into the classes TypeLink and TerminalTypeSymbol which represents respectively a link to a type symbol and an element that can be located at the end of a type link objects chain. The latter is then derived into the classes TypeVariable which represents a type variable (or an unresolved type) and Type which is the base type of any actual type class:

- FlatType: base class for any flat type (Int, Bool, Float, String, Char and Void).
- UniparameterType: base class for type having only one type parameter (Array and List). This class holds the type parameter which is represented by a type link object.
- Function: base class for any actual type. This class stores a vector of TypeLink objects to represent the type of the parameters and another one for the function return type.

The ShallowType is an enumeration representing possible types as integers. The hint sets are represented by TypeHints objects (class defined in inference/Types.hpp) which represents the set as a bitmask of ShallowTypes allowing efficient operations (intersection, union, removal and checking if a ShallowType belongs to it). Every TerminalTypeSymbol is assigned a hint set object.

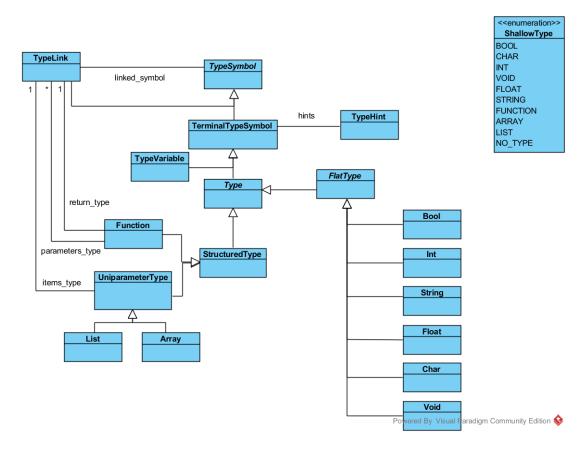


Figure 1 – Type symbols class diagram

Type symbol table The type symbol table inherits from an instantiation of the C++ standard hashtable template class, std::unordered_map<std::string,TypeLink>, and encapsulates the following operations:

- unification between two variables
- unification between a variable and a flat type
- update of the hints of a type variable
- creation of new variables
- construction of type symbol objects for variables, functions, arrays and lists
- construction of a type object for the code generation phase

• generation of unique type variable names

The table stores two kind of variables: the ones bounded to the program's identifiers (so-called *bounded* type variables) and the ones that are not (so-called *pure* type variables). As every variable has to be uniquely identified, the generation of variable names have to be done carefully:

- pure variable names are numbers generated with a counter and is therefore collision free as long as the counter does not overflow
- as a in a valid program, two identifiers of having the same name cannot be declared in the same scope, a unique name for bounded variables can be constructed from these two elements. An additional character, '@' is added between the identifier name and the scope id for the sake of readability mostly. The name of a bounded variable is therefore generated as follows:

identifier@scope_id

Syntax-directed type inference The type inference is implemented with another visitor in TypeInferenceVi Each node corresponds to a language construct of which the type semantic must be translated in the type symbol table. Moreover, a node can receive from its parent and pass to his children a set of variable (for instance, if an expression is expected to return a value of a given type, the corresponding type variable could be passed from the parent to the expression node). Therefore, designing the type inference for a node results in answering five questions:

- 1. **Inheritance**: which type variables are inherited from the parent node?
- 2. **Table insertion**: which variables must be created in the type symbol table and with which terminal type symbols have they to be associated?
- 3. **Unification**: which pairs of variables have to be unified? Does a variable have to be unified with a flat type?
- 4. **Hinting**: has the hints of a variable to be updated?
- 5. **Transmission**: which variables must be given to the children nodes?

As these elements must be defined for every node, the complete list is not detailed here. Nevertheless, three examples are given: the + operator, the if statement and the function declaration.

- Operator +: this node has two children, the two operands
 - Inheritance: α is the type that should be returned by the operation
 - Table insertion : no type variable insertion
 - *Unification* : no unification
 - *Hinting*: as '+' can only take integer or float operands, we have: $\mathcal{H}_{\alpha} = \mathcal{H}_{\alpha} \cap \{\text{int}, \text{float}\}\$
 - Transmission: as the type returned by the addition is the same as the type of the operands α is passed the both of them
- Statement if: this node has two children, the condition expression and the scope
 - Inheritance: α is the type that should be returned by a nori statement in the if scope
 - Table insertion : β is the type returned by the condition expression
 - Unification: as the condition expression must return a boolean value, the following unification must be performed: $unify(\beta, bool)$
 - *Hinting* : no hinting
 - Transmission: β is passed to the condition expression node and α to the scope node
- Function declaration: maki func_name $p_1 \dots p_n$: scope;; (for instance defined in the scope 1 and its scope having id 2)
 - *Inheritance* : no inheritance
 - Table insertion: func_name@1 is the type of the function, p_i @2 is the type of the i^{th} parameter and α is the return type

— *Unification*: the function name must be unified with the function type:

$$unify(func_name@1, p_1@2...p_n@2 \rightarrow \gamma)$$

- *Hinting* : each hinted parameter should be hinted. If the hint is a flat type, an unification can be performed instead
- $Transmission : \gamma$ to the scope node

The *almost* complete list of the nodes and their inference actions is given in the Inference.pdf document in the submitted archive.

4 Flaws and possible improvements

- 4.1 Code generation
- 4.1.1 Code generation
- 4.1.2 Code construction
- 5 Runtime
- 5.1 Garbage collector

A Sources

- 1. Type inference:
 - (a) Paul N. Hilfinger, "Lecture #22: Type Inference and Unification", https://goo.gl/RR8Eme, UC Berekeley, course CS164: Programming Languages and Compilers.

B Diagrams