

Report FYS4411 - Project 1

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$$\begin{aligned} E_{L2} &= \frac{1}{\Psi_T} \hat{\mathbf{H}} \Psi_T \\ &= \frac{1}{\Psi_T} \left(-\frac{\nabla_1^2}{2} - \frac{\nabla_2^2}{2} - \frac{Z}{r_1} - \frac{Z}{r_2} + \frac{1}{r_{12}} \right) \exp \left(-\alpha(r_1 + r_2) + \frac{r_{12}}{2(1 + \beta r_{12})} \right) \end{aligned}$$

We first do the derivative of the first half of the core of exponential

$$\begin{aligned} \frac{\nabla_1^2}{2} \left(-\alpha(r_1 + r_2) \right) &= \frac{1}{2} \frac{1}{r_1^2} \frac{\partial}{\partial r_1} \left[r_1^2 \frac{\partial}{\partial r_1} \left(-\alpha(r_1 + r_2) \right) \right] \\ &= \frac{1}{2r_1^2} \frac{\partial}{\partial r_1} [r_1^2 - \alpha] \\ &= \frac{1}{2r_1^2} (-2r_1\alpha) \\ &= -\frac{\alpha}{r_1} \end{aligned}$$

using the radial part of the Laplacian in spherical coordinates. We then do the derivative of the second part of the exponential with regards to r_1

$$\frac{\nabla_1^2}{2} \left(\frac{r_{12}}{2(1 + \beta r_{12})} \right) = \frac{1}{2} \frac{1}{r_1^2} \frac{\partial}{\partial r_1} \left[r_1^2 \frac{\partial}{\partial r_1} \left(\frac{r_{12}}{2(1 + \beta r_{12})} \right) \right]. \quad (1)$$

Now we focus on just the first derivative in the equation above

$$\begin{aligned} \frac{\partial}{\partial r_1} \left(\frac{r_{12}}{2(1 + \beta r_{12})} \right) &= \frac{\left(\frac{\partial}{\partial r_1} r_{12} \right) \cdot 2(1 + \beta r_{12}) - r_{12} \cdot 2\beta \left(\frac{\partial}{\partial r_1} r_{12} \right)}{4(1 + \beta r_{12})^2} \\ &= \frac{\left(\frac{\partial}{\partial r_1} r_{12} \right)}{2(1 + \beta r_{12})^2}, \end{aligned}$$

where $\frac{\partial}{\partial r_1} r_{12}$ is yet to be decided. We can then continue with the second derivative in (1)

$$\frac{\partial}{\partial r_1} \left[r_1^2 \frac{\partial}{\partial r_1} \left(\frac{r_{12}}{2(1 + \beta r_{12})} \right) \right] = \frac{\partial}{\partial r_1} \left[\frac{r_1^2 \left(\frac{\partial}{\partial r_1} r_{12} \right)}{2(1 + \beta r_{12})^2} \right]. \quad (2)$$

Now we see that we need the derivatives of the numerator and denominator, which we find separately as

$$\frac{\partial}{\partial r_1} \left[r_1^2 \left(\frac{\partial}{\partial r_1} r_{12} \right) \right] = 2r_1 \left(\frac{\partial}{\partial r_1} r_{12} \right) + r_1^2 \left(\frac{\partial^2}{\partial r_1^2} r_{12} \right),$$

and

$$\begin{aligned} \frac{\partial}{\partial r_1} 2(1 + \beta r_{12})^2 &= 4\beta \frac{\partial}{\partial r_1} r_{12} + 2\beta^2 \frac{\partial}{\partial r_1} r_{12}^2 \\ &= 4\beta \frac{\partial}{\partial r_1} r_{12} + 4\beta^2 r_{12} \frac{\partial}{\partial r_1} r_{12} \\ &= 4\beta \left(\frac{\partial}{\partial r_1} r_{12} \right) (1 + \beta r_{12}). \end{aligned}$$

Now we can put this all together to solve (2), yielding

$$\begin{aligned} & \frac{\left[2r_1 \left(\frac{\partial}{\partial r_1} r_{12} \right) + r_1^2 \left(\frac{\partial^2}{\partial r_1^2} r_{12} \right) \right] \cdot 2(1 + \beta r_{12})^2 - r_1^2 \left(\frac{\partial}{\partial r_1} r_{12} \right) \cdot 4\beta \left(\frac{\partial}{\partial r_1} r_{12} \right) (1 + \beta r_{12})}{4(1 + \beta r_{12})^4} \\ &= \frac{\left[r_1 \left(\frac{\partial}{\partial r_1} r_{12} \right) + \frac{r_1^2}{2} \left(\frac{\partial^2}{\partial r_1^2} r_{12} \right) \right] (1 + \beta r_{12}) - r_1^2 \left(\frac{\partial}{\partial r_1} r_{12} \right) \beta \left(\frac{\partial}{\partial r_1} r_{12} \right)}{(1 + \beta r_{12})^3} \end{aligned}$$

r -derivatives

$$\begin{aligned} \frac{\partial}{\partial r_1} r_{12} &= \frac{\partial}{\partial r_1} \sqrt{(x_1 - x_2)^2 + (y_1 - y_2)^2 + (z_1 - z_2)^2} \\ &= \frac{\partial}{\partial r_1} \sqrt{(r_1 \sin \theta_1 \cos \phi_1 - x_2)^2 + (r_1 \sin \theta_1 \sin \phi_1 - y_2)^2 + (r_1 \cos \theta_1 - z_2)^2} \\ &= \left(\frac{1}{2r_{12}} \right) \frac{\partial}{\partial r_1} \left[(r_1 \sin \theta_1 \cos \phi_1 - x_2)^2 + (r_1 \sin \theta_1 \sin \phi_1 - y_2)^2 + (r_1 \cos \theta_1 - z_2)^2 \right] \\ &= \frac{1}{2r_{12}} \left[2(x_1 - x_2)(\sin \theta_1 \cos \phi_1) + 2(y_1 - y_2)(\sin \theta_1 \sin \phi_1) + 2(z_1 - z_2)(\cos \theta_1) \right] \\ &= \frac{1}{r_{12}} \left[(x_1 - x_2) \frac{x_1}{r_1} + (y_1 - y_2) \frac{y_1}{r_1} + (z_1 - z_2) \frac{z_1}{r_1} \right] \\ &= \frac{1}{r_1 r_{12}} \left[r_1^2 - x_1 x_2 - y_1 y_2 - z_1 z_2 \right] \\ &= \frac{1}{r_1 r_{12}} \left[r_1^2 - \mathbf{r}_1 \mathbf{r}_2 \right] \end{aligned}$$

$$\frac{\partial^2}{\partial r_1^2} r_{12} = \frac{\partial}{\partial r_1} \left[\frac{1}{r_{12}} \left(r_1 - x_2 \frac{x_1}{r_1} - y_2 \frac{y_1}{r_1} - z_2 \frac{z_1}{r_1} \right) \right]$$

$$\begin{aligned}
\frac{\partial}{\partial r_1} \frac{1}{r_{12}} &= \frac{\partial}{\partial r_1} \left((x_1 - x_2)^2 + (y_1 - y_2)^2 + (z_1 - z_2)^2 \right)^{-1/2} \\
&= \left(-\frac{1}{2r_{12}} \right) \frac{\partial}{\partial r_1} \left((x_1 - x_2)^2 + (y_1 - y_2)^2 + (z_1 - z_2)^2 \right) \\
&= -\frac{1}{2r_{12}} \frac{\partial}{\partial r_1} \left((r_1 \sin \theta_1 \cos \phi_1 - x_2)^2 + (r_1 \sin \theta_1 \sin \phi_1 - y_2)^2 + (r_1 \cos \theta_1 - z_2)^2 \right)
\end{aligned}$$

θ -derivatives

$$\begin{aligned}
\frac{\partial}{\partial \theta_1} r_{12} &= \frac{\partial}{\partial \theta_1} \sqrt{(x_1 - x_2)^2 + (y_1 - y_2)^2 + (z_1 - z_2)^2} \\
&= \left(\frac{1}{2r_{12}} \right) \frac{\partial}{\partial \theta_1} \left[(r_1 \sin \theta_1 \cos \phi_1 - x_2)^2 + (r_1 \sin \theta_1 \sin \phi_1 - y_2)^2 + (r_1 \cos \theta_1 - z_2)^2 \right] \\
&= \frac{1}{2r_{12}} \left[2(x_1 - x_2)r_1 \cos \theta_1 \cos \phi_1 + 2(y_1 - y_2)r_1 \cos \theta_1 \sin \phi_1 - 2(z_1 - z_2)r_1 \sin \theta_1 \right] \\
&= \frac{r_1}{r_{12}} \left[(x_1 - x_2) \cos \theta_1 \cos \phi_1 + (y_1 - y_2) \cos \theta_1 \sin \phi_1 - (z_1 - z_2) \sin \theta_1 \right]
\end{aligned}$$

$$\begin{aligned}
\frac{\partial}{\partial \theta_1} \left(\sin \theta_1 \frac{\partial}{\partial \theta_1} r_{12} \right) &= \frac{\partial}{\partial \theta_1} \left(\sin \theta_1 \frac{r_1}{r_{12}} \left[(x_1 - x_2) \cos \theta_1 \cos \phi_1 + (y_1 - y_2) \cos \theta_1 \sin \phi_1 - (z_1 - z_2) \sin \theta_1 \right] \right) \\
&= \frac{\partial}{\partial \theta_1} \left[\frac{1}{r_{12}} \left((x_1 - x_2)x_1 \cos \theta_1 + (y_1 - y_2)y_1 \cos \theta_1 - (z_1 - z_2)r_1 \sin^2 \theta_1 \right) \right]
\end{aligned}$$

$$\begin{aligned}
\frac{\partial}{\partial \theta_1} \frac{1}{r_{12}} &= \frac{\partial}{\partial \theta_1} \left[(r_1 \sin \theta_1 \cos \phi_1 - x_2)^2 + (r_1 \sin \theta_1 \sin \phi_1 - y_2)^2 + (r_1 \cos \theta_1 - z_2)^2 \right]^{-1/2} \\
&= \left(-\frac{1}{2r_{12}^3} \right) \frac{\partial}{\partial \theta_1} \left[(r_1 \sin \theta_1 \cos \phi_1 - x_2)^2 + (r_1 \sin \theta_1 \sin \phi_1 - y_2)^2 + (r_1 \cos \theta_1 - z_2)^2 \right] \\
&= -\frac{1}{2r_{12}^3} \left[2(x_1 - x_2)r_1 \cos \theta_1 \cos \phi_1 + 2(y_1 - y_2)r_1 \cos \theta_1 \sin \phi_1 - 2(z_1 - z_2)r_1 \sin \theta_1 \right] \\
&= -\frac{r_1}{r_{12}^3} \left[(x_1 - x_2) \cos \theta_1 \cos \phi_1 + (y_1 - y_2) \cos \theta_1 \sin \phi_1 - (z_1 - z_2) \sin \theta_1 \right]
\end{aligned}$$

$$\frac{\partial}{\partial \theta_1} \left((x_1 - x_2)x_1 \cos \theta_1 + (y_1 - y_2)y_1 \cos \theta_1 - (z_1 - z_2)r_1 \sin^2 \theta_1 \right)$$

$$\begin{aligned}
\frac{\partial}{\partial \theta_1} (x_1 - x_2)x_1 \cos \theta_1 &= \frac{\partial}{\partial \theta_1} \left(x_1^2 \cos \theta_1 - x_1 x_2 \cos \theta_1 \right) \\
&= r_1^2 \cos^2 \phi_1 \frac{d}{d\theta_1} \sin^2 \theta_1 \cos \theta_1 - x_2 r_1 \cos \phi_1 \frac{d}{d\theta_1} \sin \theta_1 \cos \theta_1
\end{aligned}$$

$$\begin{aligned}
\frac{\partial}{\partial \theta_1}(y_1 - y_2)y_1 \cos \theta_1 &= \frac{\partial}{\partial \theta_1} \left(y_1^2 \cos \theta_1 - y_1 y_2 \cos \theta_1 \right) \\
&= r_1^2 \sin^2 \phi_1 \frac{d}{d\theta_1} \sin^2 \theta_1 \cos \theta_1 - y_2 r_1 \sin \phi_1 \frac{d}{d\theta_1} \sin \theta_1 \cos \theta_1
\end{aligned}$$

$$\begin{aligned}
&\frac{\partial}{\partial \theta_1}(x_1 - x_2)x_1 \cos \theta_1 + \frac{\partial}{\partial \theta_1}(y_1 - y_2)y_1 \cos \theta_1 \\
&= r_1^2 (\sin^2 \phi_1 + \cos^2 \phi_1) \frac{d}{d\theta_1} \sin^2 \theta_1 \cos \theta_1 - r_1 (x_2 \cos \phi_1 + y_2 \sin \phi_1) \frac{d}{d\theta_1} \sin \theta_1 \cos \theta_1 \\
&= r_1^2 \frac{d}{d\theta_1} \sin^2 \theta_1 \cos \theta_1 - r_1 (x_2 \cos \phi_1 + y_2 \sin \phi_1) \frac{d}{d\theta_1} \sin \theta_1 \cos \theta_1
\end{aligned}$$

$$\begin{aligned}
\frac{\partial}{\partial \theta_1}(z_1 - z_2)r_1 \sin^2 \theta_1 &= \frac{d}{d\theta_1} r_1 \cos \theta_1 r_1 \sin^2 \theta_1 - \frac{d}{d\theta_1} z_2 r_1 \sin^2 \theta_1 \\
&= r_1^2 \frac{d}{d\theta_1} \sin^2 \theta_1 \cos \theta_1 - r_1 z_2 \frac{d}{d\theta_1} \sin^2 \theta_1
\end{aligned}$$

$$\begin{aligned}
&\frac{\partial}{\partial \theta_1}(x_1 - x_2)x_1 \cos \theta_1 + \frac{\partial}{\partial \theta_1}(y_1 - y_2)y_1 \cos \theta_1 - \frac{\partial}{\partial \theta_1}(z_1 - z_2)r_1 \sin^2 \theta_1 \\
&= -r_1 (x_2 \cos \phi_1 + y_2 \sin \phi_1) \frac{d}{d\theta_1} \sin \theta_1 \cos \theta_1 - r_1 z_2 \frac{d}{d\theta_1} \sin^2 \theta_1 \\
&= -r_1 (x_2 \cos \phi_1 + y_2 \sin \phi_1) (\cos^2 \theta_1 - \sin^2 \theta_1) - z_2 r_1 2 \sin \theta_1 \cos \theta_1
\end{aligned}$$

ϕ -derivatives

$$\begin{aligned}
\frac{\partial}{\partial \phi_1} r_{12} &= \frac{\partial}{\partial \phi_1} \sqrt{(x_1 - x_2)^2 + (y_1 - y_2)^2 + (z_1 - z_2)^2} \\
&= \frac{\partial}{\partial \phi_1} \sqrt{(r_1 \sin \theta_1 \cos \phi_1 - x_2)^2 + (r_1 \sin \theta_1 \sin \phi_1 - y_2)^2 + (r_1 \cos \theta_1 - z_2)^2} \\
&= \left(\frac{1}{2r_{12}} \right) \frac{\partial}{\partial \phi_1} \left[(r_1 \sin \theta_1 \cos \phi_1 - x_2)^2 + (r_1 \sin \theta_1 \sin \phi_1 - y_2)^2 + (r_1 \cos \theta_1 - z_2)^2 \right] \\
&= \frac{1}{2r_{12}} \left[-2(x_1 - x_2)r_1 \sin \theta_1 \sin \phi_1 + 2(y_1 - y_2)r_1 \sin \theta_1 \cos \phi_1 \right] \\
&= \frac{1}{r_{12}} \left[-(x_1 - x_2)y_1 + (y_1 - y_2)x_1 \right]
\end{aligned}$$

$$\frac{\partial^2}{\partial \phi_1^2} r_{12} = \frac{\partial}{\partial \phi_1} \left[\frac{1}{r_{12}} \left(-(x_1 - x_2)y_1 + (y_1 - y_2)x_1 \right) \right]$$

$$\begin{aligned}
\frac{\partial}{\partial \phi_1}(x_1 - x_2)y_1 &= \frac{\partial}{\partial \phi_1}(x_1y_1 - x_2y_1) \\
&= \frac{\partial}{\partial \phi_1}(r_1^2 \sin \theta_1^2 \sin \phi_1 \cos \phi_1 - x_2r_1 \sin \theta_1 \sin \phi_1) \\
&= r_1^2 \sin \theta_1 \frac{d}{d\phi_1} \sin \phi_1 \cos \phi_1 - x_2r_1 \sin \theta_1 \cos \phi_1 \\
&= r_1^2 \sin \theta_1 \frac{d}{d\phi_1} \sin \phi_1 \cos \phi_1 - x_1x_2
\end{aligned}$$

$$\begin{aligned}
\frac{\partial}{\partial \phi_1}(y_1 - y_2)x_1 &= \frac{\partial}{\partial \phi_1}(y_1x_1 - y_2x_1) \\
&= \frac{\partial}{\partial \phi_1}(r_1^2 \sin^2 \theta_1 \sin \phi_1 \cos \phi_1 - y_2r_1 \sin \theta_1 \cos \phi_1) \\
&= r_1^2 \sin^2 \theta_1 \frac{d}{d\phi_1} \sin \phi_1 \cos \phi_1 + y_2r_1 \sin \theta_1 \sin \phi_1 \\
&= r_1^2 \sin^2 \theta_1 \frac{d}{d\phi_1} \sin \phi_1 \cos \phi_1 + y_1y_2
\end{aligned}$$

$$\frac{\partial}{\partial \phi_1}(-(x_1 - x_2)y_1 + (y_1 - y_2)x_1) = x_1x_2 + y_1y_2$$

$$\begin{aligned}
\frac{\partial}{\partial \phi_1} \frac{1}{r_{12}} &= \frac{\partial}{\partial \phi_1} \left[(r_1 \sin \theta_1 \cos \phi_1 - x_2)^2 + (r_1 \sin \theta_1 \sin \phi_1 - y_2)^2 + (r_1 \cos \theta_1 - z_2)^2 \right]^{-1/2} \\
&= \left(-\frac{1}{2r_{12}^3} \right) \frac{\partial}{\partial \phi_1} \left[(r_1 \sin \theta_1 \cos \phi_1 - x_2)^2 + (r_1 \sin \theta_1 \sin \phi_1 - y_2)^2 + (r_1 \cos \theta_1 - z_2)^2 \right] \\
&= -\frac{1}{2r_{12}^3} \left[-2(x_1 - x_2)r_1 \sin \theta_1 \sin \phi_1 + 2(y_1 - y_2)r_1 \sin \theta_1 \cos \phi_1 \right] \\
&= -\frac{1}{r_{12}^3} \left[-(x_1 - x_2)y_1 + (y_1 - y_2)x_1 \right]
\end{aligned}$$

$$\begin{aligned}
&\left(\frac{\partial}{\partial \phi_1} \frac{1}{r_{12}} \right) \cdot \left(-(x_1 - x_2)y_1 + (y_1 - y_2)x_1 \right) \\
&= -\frac{1}{r_{12}^3} \left(-(x_1 - x_2)y_1 + (y_1 - y_2)x_1 \right) \cdot \left(-(x_1 - x_2)y_1 + (y_1 - y_2)x_1 \right) \\
&= -\frac{1}{r_{12}^3} \left(-(x_1 - x_2)y_1 + (y_1 - y_2)x_1 \right)^2
\end{aligned}$$

$$\begin{aligned}
&\frac{1}{r_{12}} \cdot \frac{\partial}{\partial \phi_1} \left(-(x_1 - x_2)y_1 + (y_1 - y_2)x_1 \right) \\
&= \frac{1}{r_{12}} \cdot (x_1x_2 + y_1y_2)
\end{aligned}$$

$$\begin{aligned}
\frac{\partial^2}{\partial \phi_1^2} r_{12} &= \frac{1}{r_{12}} (x_1 x_2 + y_1 y_2) - \frac{1}{r_{12}^3} \left((y_1 - y_2)x_1 - (x_1 - x_2)y_1 \right)^2 \\
&= \frac{1}{r_{12}} (x_1 x_2 + y_1 y_2) - \frac{1}{r_{12}^3} (x_2 y_1 - x_1 y_2)^2
\end{aligned}$$

NEW STUFF

$$\frac{\partial}{\partial x_1} r_{12} = \frac{1}{r_{12}} (x_1 - x_2)$$

$$\begin{aligned}
\frac{\partial^2}{\partial x_1^2} r_{12} &= \frac{\partial}{\partial x_1} \frac{1}{r_{12}} (x_1 - x_2) \\
&= \frac{1}{r_{12}} - \frac{(x_1 - x_2)^2}{r_{12}^3}
\end{aligned}$$

$$\frac{\partial}{\partial x_1} \frac{1}{r_{12}} = -\frac{x_1 - x_2}{r_{12}^3}$$