The Ising model: the prototype model for a phase transition

In order to probe the properties of the critical region, it is common to appeal to simplified model systems whose behaviour parallels that of real materials. The sophistication of any particular model depends on the properties of the system it is supposed to represent. The simplest model to exhibit critical phenomena is the two-dimensional Ising model of a ferromagnet. Actual physical realizations of 2-d magnetic systems do exist in the form of layered ferromagnets such as K_2CoF_4 , so the 2-d Ising model is of more than just technical relevance.

The 2D Ising model

The 2-d spin- $\frac{1}{2}$ Ising model envisages a regular arrangement of magnetic moments or 'spins' on an infinite plane. Each spin can take two values, +1 ('up' spins) or -1 ('down' spins) and is assumed to interact with its nearest neighbours according to the Hamiltonian

$$H_I = -J \sum_{\langle ij \rangle} s_i s_j - H \sum_i s_i \tag{1}$$

where J > 0 measures the strength of the coupling between spins and the sum extends over nearest neighbour spins s_i and s_j , i.e it is a sum of the bonds of the lattice. H is a magnetic field term which can be positive or negative (although for the time being we will set it equal to zero). The order parameter is simply the average magnetisation:

$$m = \frac{1}{N} \langle \sum_{i} s_{i} \rangle ,$$

where $\langle \cdot \rangle$ means an average over typical configurations corresponding to the prescribed value of J/k_BT .

The fact that the Ising model displays a phase transition was argued in **?@sec-background**. Thus at low temperatures for which there is little thermal disorder, there is a preponderance of aligned spins and hence a net spontaneous magnetic moment (ie. the system is ferromagnetic).

As the temperature is raised, thermal disorder increases until at a certain temperature T_c , entropy drives the system through a continuous phase transition to a disordered spin arrangement with zero net magnetisation (ie. the system is paramagnetic). These trends are visible in configurational snapshots from computer simulations of the 2D Ising model (see Figure 1). Although each spin interacts only with its nearest neighbours, the phase transition occurs due to cooperative effects among a large number of spins.

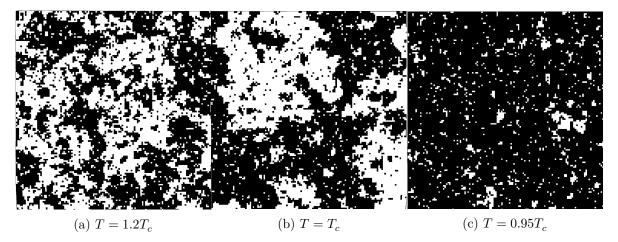


Figure 1: Configurations of the 2d Ising model. The patterns depict typical arrangements of the spins (white=+1, black=-1) generated in a computer simulation of the Ising model on a square lattice of N=512 sites, at temperatures (from left to right) of $T=1.2T_c$, $T=T_c$, and $T=0.95T_c$. In each case only a portion of the system containing 128 sites in shown. The typical island size is a measure of the correlation length ξ : the excess of black over white (below T_c is a measure of the order parameter.

An interactive Monte Carlo simulation of the Ising model demonstrates the phenomenology, By altering the temperature you will be able to observe for yourself how the typical spin arrangements change as one traverses the critical region. Pay particular attention to the configurations near the critical point. They have very interesting properties. We will return to them later!

Although the 2-d Ising model may appear at first sight to be an excessively simplistic portrayal of a real magnetic system, critical point universality implies that many physical observables such as critical exponents are not materially influenced by the actual nature of the microscopic interactions. The Ising model therefore provides a simple, yet quantitatively accurate representation of the critical properties of a whole range of real magnetic (and indeed fluid) systems. This universal feature of the model is largely responsible for its ubiquity in the field of critical phenomena. We shall explore these ideas in more detail later in the course.

Exact solutions: the one dimensional Ising chain

One might well ask why the 2D Ising model is the simplest model to exhibit a phase transition. What about the one-dimensional Ising model (ie. spins on a line)? In fact in one dimension, the Ising model can be solved exactly. It turns out that the system is paramagnetic for all T>0, so there is no phase transition at any finite temperature. To see this, consider the ground state of the system in zero external field. This will have all spins aligned the same way (say up), and hence be ferromagnetic. Now consider a configuration with a various "domain walls" dividing spin up and spin down regions:

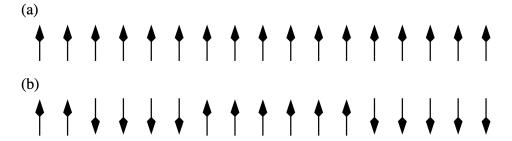


Figure 2: (a) Schematic of an Ising chain at T=0. (b) At a small finite temperature the chain is split into domains of spins ordered in the same direction. Domains are separated by notional domain "walls", which cost energy $\Delta=2J$. Periodic boundary conditions are assumed.

Instead of considering the underlying spin configurations, we shall describe the system in terms of the statistics of its domain walls. The energy cost of a wall is $\Delta = 2J$, independent of position. Domain walls can occupy the bonds of the lattice, of which there are N-1. Moreover, the walls are noninteracting, except that you cannot have two of them on the same bond. (Check through these ideas if you are unsure.)

In this representation, the partition function involves a count over all possible domain wall arrangements. Since the domain walls are non interacting (eg it doesn't cost energy for one to move along the chain) they can be treated as independent. Independent contributions to the partition function simply multiply. So we can calculate Z by considering the partition function associated with a single domain wall being present or absent on some given bond, and then simply raise to the power of the number of bonds:

$$Z = Z_1^{N-1}$$

where

$$Z_1 = e^{\beta J} + e^{\beta(J-\Delta)} = e^{\beta J} (1 + e^{-\beta \Delta})$$

is the domain wall partition function for a single bond and represent the sum over the two possible states: domain wall absent or present. Then the free energy per bond of the system is

$$\beta f \equiv \beta F/(N-1) = -\ln Z_1 = -\beta J - \ln(1 + e^{-\beta \Delta})$$

The first term on the RHS is simply the energy per spin of the ferromagnetic (ordered) phase, while the second term arises from the free energy of domain walls. Clearly for any finite temperature (ie. for $\beta < \infty$), this second term is finite and negative. Hence the free energy will always be lowered by having a finite concentration of domain walls in the system. Since these domain walls disorder the system, leading to a zero average magnetisation, the 1D system is paramagnetic for all finite temperatures. *Exercise*: Explain why this argument works only in 1D.

The animation below lets you see qualitatively how the typical number of domain walls varies with temperature. If you'd lke to explore more quantitatively, a python code performing a Monte Carlo simulation is available. You will learn about Monte Carlo simulation in the coursework and in later parts of the course.

```
#Monte Carlo simulation of the 1d Ising chain with periodic bounary conditions
import numpy as np
import matplotlib.pyplot as plt
from matplotlib.animation import FuncAnimation
from matplotlib.widgets import Slider
# Number of spins
N = 20
# Initialize spins (+1 or -1)
spins = np.random.choice([-1, 1], size=N)
# Initial temperature
T = 2.0
# Set up figure and axis for the spins
fig, ax = plt.subplots(figsize=(10, 2))
plt.subplots_adjust(bottom=0.25) # make room for slider
ax.set_xlim(-0.5, N - 0.5)
ax.set vlim(-1, 1)
ax.axis('off')
# Create text objects for each spin
texts = []
```

```
for i in range(N):
    arrow = '↑' if spins[i] == 1 else '↓'
    t = ax.text(i, 0, arrow, fontsize=24, ha='center', va='center')
   texts.append(t)
def update(frame):
    """Perform Metropolis updates over all spins, then refresh display."""
    global spins, T
    for _ in range(N):
        i = np.random.randint(N)
        left = spins[(i - 1) \% N]
        right = spins[(i + 1) \% N]
        deltaE = 2 * spins[i] * (left + right)
        # Metropolis criterion ensures configurations appear with the correct Boltzmann prob-
        if deltaE < 0 or np.random.rand() < np.exp(-deltaE / T):</pre>
            spins[i] *= -1
    # Update arrows on screen
    for idx, t in enumerate(texts):
        t.set_text('\tau' if spins[idx] == 1 else '\tau')
    return texts
# Create the animation with caching disabled and blit turned off
ani = FuncAnimation(
   fig,
   update,
    interval=200,
    blit=False,
    cache_frame_data=False
)
# Add a temperature slider
ax_T = plt.axes([0.2, 0.1, 0.6, 0.03], facecolor='lightgray')
slider_T = Slider(ax_T, 'Temperature T', 0.1, 5.0, valinit=T)
def on_T_change(val):
    """Callback to update T when the slider changes."""
    global T
    T = val
slider_T.on_changed(on_T_change)
# Show the plot (ani is kept in scope so it won't be deleted)
```

plt.show()

Temperature T =

2.0

More general 1D spins systems: transfer matrix method

Generally speaking one-dimensional systems lend themselves to a degree of analytic tractability not found in most higher dimensional models. Indeed for the case of a 1-d assembly of N spins each having m discrete energy states, and in the presence of a magnetic field, it is possible to reduce the evaluation of the partition function to the calculation of the eigenvalues of a matrix—the so called transfer matrix.

Let us start by assuming that the assembly has cyclic boundary conditions, then the total energy of configuration $\{s\}$ is

$$\begin{split} H(\{s\}) &= -\sum_{i=1}^{N} (Js_{i}s_{i+1} + Hs_{i}) \\ &= -\sum_{i=1}^{N} (Js_{i}s_{i+1} + H(s_{i} + s_{i+1})/2) \\ &= \sum_{i=1}^{N} E(s_{i}, s_{i+1}) \end{split}$$

where we have defined $E(s_i, s_{i+1}) = -Js_i s_{i+1} - H(s_i + s_{i+1})/2$.

Now the partition function may be written

$$\begin{split} Z_N &= \sum_{\{s\}} \exp\left(-\beta H(\{s\})\right) \\ &= \sum_{\{s\}} \exp\left(-\beta [E(s_1, s_2) + E(s_2, s_3) + E(s_N, s_1)]\right) \\ &= \sum_{\{s\}} \exp\left(-\beta E(s_1, s_2)\right) \exp\left(-\beta E(s_2, s_3)\right) \exp\left(-\beta E(s_N, s_1)\right) \\ &= \sum_{i,j,...,l=1}^m V_{ij} V_{jk} ... V_{li} \end{split}$$

where the $V_{ij} = \exp(-\beta E_{ij})$ are elements of an $m \times m$ matrix \mathbf{V} , known as the transfer matrix (i, j, k etc are dummy indices that run over the matrix elements). You should see that the

sum over the product of matrix elements picks up all the terms in the partition function and therefore Equation 2 is an alternative way of writing the partition function.

The reason it is useful to transform to a matrix representation is that it transpires that the sum over the product of matrix elements in Equation 2 is simply just the trace of \mathbf{V}^N (check this yourself for a short periodic chain), given by the sum of its eigenvalues:-

$$Z_N = \lambda_1^N + \lambda_2^N + ... \lambda_m^N$$

For very large N, this expression simplifies further because the largest eigenvalue λ_1 dominates the behaviour since $(\lambda_2/\lambda_1)^N$ vanishes as $N\to\infty$. Consequently in the thermodynamic limit one may put $Z_N=\lambda_1^N$ and the problem reduces to identifying the largest eigenvalue of the transfer matrix.

Specializing to the case of the simple Ising model in the presence of an applied field H, the transfer matrix takes the form

$$\mathbf{V}(H) = \left(\begin{array}{cc} e^{\beta(J+H)} & e^{-\beta J} \\ e^{-\beta J} & e^{\beta(J-H)} \end{array} \right)$$

This matrix has two eigenvalues which can be readily calculated in the usual fashion as the roots of the characteristic polynomial $|\mathbf{V} - \lambda \mathbf{I}|$. They are

$$\lambda_{\pm} = e^{\beta J} \cosh(\beta H) \pm \sqrt{e^{2\beta J} \sinh^2 \beta H + e^{-2\beta J}}.$$

Hence the free energy per spin $f = -k_B T \ln \lambda_+$ is

$$f = -k_B T \ln \left[e^{\beta J} \cosh(\beta H) + \sqrt{e^{2\beta J} \sinh^2 \beta H + e^{-2\beta J}} \right].$$

The Ising model in 2D can also be solved exactly, as was done by Lars Onsager in 1940. The solution is extremely complicated and is regarded as one of the pinnacles of statistical mechanics. In 3D no exact solution is known.