

# Fast Slerp Summary

David Eberly

Geometric Tools, LLC

<http://www.geometrictools.com/>

Copyright © 1998-2012. All Rights Reserved.

January 9, 2012

This is a brief summary of my paper: *A Fast and Accurate Algorithm for Computing Slerp*, Journal of Graphics, GPU, and Game Tools, vol. 15, no. 3, pages 161-176. (<http://www.tandfonline.com/loi/ujgt20>)

The SLERP of two unit-length quaternions  $q_0$  and  $q_1$  is

$$p = \left( \frac{\sin((1-t)\theta)}{\sin(\theta)} \right) q_0 + \left( \frac{\sin(t\theta)}{\sin(\theta)} \right) q_1$$

for  $t \in [0, 1]$ . Defining  $x = \cos(\theta)$  and  $f(x, t) = \sin(t\theta)/\sin(\theta)$ , the paper shows that

$$f(x, t) = \sum_{i=0}^{\infty} a_i(t)(x-1)^i$$

where

$$a_0(t) = t, \quad a_i(t) = \frac{t^2 - i^2}{i(2i+1)} a_{i-1}(t), \quad i \geq 1$$

It is clear that  $a_i(t)$  is a polynomial in  $t$  of degree  $2i+1$ . It is also clear that  $f(x, 0) = 0$  and  $f(x, 1) = 1$ .

The power series for  $f(x, t)$  may be truncated to obtain an approximation that always underestimates the true value. However, the error may be balanced (centered about zero, positive and negative errors can occur)

$$f(x, t) = \sum_{i=0}^n a_i(t)(x-1)^i + \mu_n a_n(t)(x-1)^n + \varepsilon_n(x, t)$$

for some positive constant  $\mu_n$  and where the last term  $\varepsilon_n(x, t)$  is the approximation error. A bound on the error is of the form

$$|\varepsilon_n(x, t)| = \left| f(x, t) - \left( \sum_{i=0}^n a_i(t)(x-1)^i + \mu_n a_n(t)(x-1)^n \right) \right| \leq e_n$$

The following table shows choices for  $n$  and the corresponding  $\mu_n$  and  $e_n$ .

$n$	$\mu_n$	$e_n$
1	0.62943436108234530	$5.745259 \star 10^{-3}$
2	0.73965850021313961	$1.092666 \star 10^{-3}$
3	0.79701067629566813	$2.809387 \star 10^{-4}$
4	0.83291820510335812	$8.409177 \star 10^{-5}$
5	0.85772477879039977	$2.763477 \star 10^{-5}$
6	0.87596835698904785	$9.678992 \star 10^{-6}$
7	0.88998444919711206	$3.551215 \star 10^{-6}$
8	0.90110745351730037	$1.349968 \star 10^{-6}$
9	0.91015881189952352	$5.277561 \star 10^{-7}$
10	0.91767344933047190	$2.110597 \star 10^{-7}$
11	0.92401541194159076	$8.600881 \star 10^{-8}$
12	0.92944142668012797	$3.560875 \star 10^{-8}$
13	0.93413793373091059	$1.494321 \star 10^{-8}$
14	0.93824371262559758	$6.344653 \star 10^{-9}$
15	0.94186426368404708	$2.721482 \star 10^{-9}$
16	0.94508125972497303	$1.177902 \star 10^{-9}$

An implementation of the approximation for a standard floating-point unit is shown next for  $n = 8$ . It must compute both  $f(x, t)$  and  $f(x, 1 - t)$  to produce  $p = f(x, 1 - t)q_0 + f(x, t)q_1$ .

```
// Precomputed constants.
const float opmu = 1.90110745351730037f;
const float u[8] = // 1/(2i+1) for i >= 1
{
    1.f/(1*3), 1.f/(2*5), 1.f/(3*7), 1.f/(4*9), 1.f/(5*11), 1.f/(6*13), 1.f/(7*15), opmu/(8*17)
};
const float v[8] = // i/(2i+1) for i >= 1
{
    1.f/3, 2.f/5, 3.f/7, 4.f/9, 5.f/11, 6.f/13, 7.f/15, opmu*8/17
};

FTuple4 SlerpFPU (float t, FTuple4 q0, FTuple4 q1)
{
    float x = q0.Dot(q1); // cos(theta)
    float sign = (x >= 0 ? 1 : (x = -x, -1));
    float xm1 = x - 1;

    float d = 1 - t, sqrT = t*t, sqrD = d*d;

    float bT[8], bD[8];
    for (int i = 7; i >= 0; --i)
    {
        bT[i] = (u[i]*sqrT - v[i])*xm1;
        bD[i] = (u[i]*sqrD - v[i])*xm1;
    }

    float cT = sign*t*(
        1 + bT[0]*(1 + bT[1]*(1 + bT[2]*(1 + bT[3]*(
        1 + bT[4]*(1 + bT[5]*(1 + bT[6]*(1 + bT[7])))))));

    float cD = d*(
        1 + bD[0]*(1 + bD[1]*(1 + bD[2]*(1 + bD[3]*(
        1 + bD[4]*(1 + bD[5]*(1 + bD[6]*(1 + bD[7])))))));

    FTuple4 slerp = q0*cD + q1*cT;
    return slerp;
}
```

The code uses the formula

$$b_i(x, t) = (x - 1) \frac{a_{i+1}(t)}{a_i(t)} = (x - 1) \left( \frac{t^2 - (i + 1)^2}{(i + 1)(2i + 3)} \right) = (x - 1)(u_i t^2 - v_i)$$

in order to reduce the operation count. The evaluation of  $f(x, t)$  becomes a nested sequence of multiplications and additions of 1. The  $u_i$  and  $v_i$  are constants known at compile time, so they are precomputed as shown in the code listing.

Source code is available online at <http://www.geometrictools.com/JGT/FastSlerp.cpp> and contains the FPU-based implementation and various Intel SSE2 implementations.