Frederick Wachter

3601 Powelton Avenue, Unit B6
Philadelphia, PA 19104

✉ wachterfreddy@gmail.com   📞 +1 (610) 517-0948   🖥 fwachter.github.io   ⊙ github.com/FWachter

Professional Profile

I am a Mechanical Engineer with primary interest in robotics, embedded systems, and software development. The majority of my work and project experience has involved combining software and hardware for developing robotic platforms along with developing software for various applications. I also have experience with full-cycle design, integration, and testing of robotic platforms. I have taken multiple leadership roles in teams ranging from 4 to 100 student and professional members, and have additional experience with project management, product development, sponsorship, and website development.

Education

Master's and Bachelor's of Science in Mechanical Engineering
Drexel University, Pennoni Honors College | Graduated: June 2018
Cumulative GPA: 3.93

Engineering Work Experience

Lockheed Martin Robotics and Intelligent Systems Group – *Robotics Intern*
Cherry Hill, New Jersey | March 2017 to December 2017 | *Advanced Technologies Lab*
- Robotic platform developer for autonomous maritime and aerial vehicles
- Performed full system design, development, and integration
- Developed vehicle autonomy framework, software and controls in ROS framework

Autonomous Systems Laboratory – *Intern*
Zürich, Switzerland | March 2016 to September 2016 | *Swiss Fed. Inst. of Tech. (ETHZ)*
- Interfaced ABB YuMi robot with the MoveIt! dynamics and control software in ROS
- Integrated the Leap Motion and VI sensor with YuMi for interactive manipulation
- Developed a stand and a new attachment for YuMi to integrate a VI sensor
- Presented work to the President of ABB Switzerland and his colleagues

Production Technology West – *Research Engineering Intern*
Trollhättan, Sweden | September 2014 to March 2015 | *University West*
- Developed algorithms to determine robustness of weld defect detection from an IR camera with various light sources
- Built a GUI in MATLAB to interface with algorithms to display defect locations to user
- Developed tests to image defects on welds using an IR camera with various light sources in order to benchmark the defect detection algorithms
- Designed and built a borescope for an IR camera to image welds inside of vanes

Engineering and Leadership Experience

Swerve Robotic Platform – *Project Manager, Software & Robotics Head, Webmaster*
Drexel University | July 2017 to May 2018
- Worked with two mechanical one computer engineer to design a highly nimble, high speed, ROS-enabled robot targeted for manufacturing and entertainment industries
- Developed full physics simulation of platform with simulated sensors in Gazebo
- Implemented software and hardware to perform state estimation
- Built software architecture within ROS framework
- Ranked #1 senior design capstone project in Drexel University College of Engineering out of over 100 teams from 8 departments

ASME Student Design Competition – *Project Manager and Hardware/Software Head*
Drexel University | October 2017 to April 2018
- Major tasks include selecting hardware, making electrical layout, designing and implementing software, set up and execute meetings, and raising funds
- Team placed 3rd out of 54 teams from around the world

Drexel Hyperloop Team – *Project Manager, Sponsorship Head, Steering Committee*
Drexel University | June 2015 to January 2017
- Interfaced between subsystem teams, university advisors, university staff, and sponsors in order to manage team resources and keep the project on schedule
- Developed organizational structure, grew team of 5 to over 100 students
- Raised over $65,000 as sponsorship head for developing a scaled pod prototype

Citizenship

US Citizen

Skills

Robotics
ROS (Robot Operating System)
Embedded Systems
Software Development
UNIX
ABB Industrial Robots

Programming
MATLAB
C++11
Python 3
HTML/CSS
JavaScript
RAPID
Bash
LaTeX

Software
ProE/Creo
SolidWorks
Microsoft Office

Manufacturing
3D Printing
Lathe
Milling
Power and Hand Tools

Electrical
Wiring (soldering, crimping, etc.)

Languages
English (Native)
French (Working Proficiency)

Standards and Practices

Programming
Google C++ Style Guide
ROS C++ Style Guide

Non-required Coursework

Graduate
Advanced Programming Techniques

Undergraduate
Micro-Based Control Systems
Computer Programming I
Basic Robotic Simulation