Linux Camera Tool

Leopard Imaging Inc 4/16/2019 Danyu



Functionality:

- 1. Video streaming for different type of USB3 cameras (YUV422, RAW10, RAW12) including debaying for RAW cameras
- 2. Gain and exposure control(ae enable, disable) (FIXME: experience split screen when updating values)
- 3. Software powered auto white balance
- 4. Software powered auto brightness and contrast (auto enhance ax+b)
- 5. Register read/write (both for sensor only or generic i2c slave)
- 6. Image capture (current resolution's bmp, raw images)
- 7. Software powered gamma correction
- 8. Triggering mode demo (same as windows camera tool)
- 9. Software powered black level correction
- 10. Resolution updates from command line arguments
- 11. Frame rate updates from command line arguments
- 12. Allocate buffer updates from command line arguments(FIXME: nbufs > 1 will experience split screen)

13. TODO:

- a. make video streaming faster -> use opencl/cuda to accelerate opencv etc
- b. test cross platform performance -> try it on TX2, enable cuda etc
- c. bug fixes of course

Datatype Definition for Data Stream:

BIT15	BIT14	BIT13	BIT12	BIT11	BIT10	ВІТ9	вітв	ВІТ7	ВІТ6	віт5	BIT4	ВІТЗ	BIT2	BIT1	віто
RAW12 Datatype:															
0	0	0	0	R0_11	R0_10	RO_ 9	R0_8	R0_7	R0_6	R0_5	R0_4	R0_3	R0_2	R0_1	R0_0
0	0	0	0	R1_11	R1_10	R1_9	R1_8	R1_7	R1_6	R1_5	R1_4	R1_3	R1_2	R1_1	R1_0
							! ! !								
RAW10 Datatype:															
0	0	0	0	0	0	R0_ 9	RO_8	R0_7	R0_6	R0_5	RO_4	RO_3	R0_2	RO_1	R0_0
0	0	0	0	0	0	R1_9	R1_8	R1_7	R1_6	R1_5	R1_4	R1_3	R1_2	R1_1	R1_0
YUV422 8-bit YUYV Datatype:															
Y0_7	Y0_6	Y0_5	Y0_4	Y0_3	Y0_2	Y0_1	Y0_0	U0_8	U0_7	U0_6	U0_5	U0_4	U0_3	U0_2	U0_1
Y1_7	Y1_6	Y1_5	Y1_4	Y1_3	Y1_2	Y1_1	Y1_0	V0_8	V0_7	V0_6	V0_5	V0_4	V0_3	V0_2	V0_1
Y2_7	Y2_6	Y2_5	Y2_4	Y2_3	Y2_2	Y2_1	Y2_0	U1_8	U1_7	U1_6	U1_5	U1_4	U1_3	U1_2	U1_1

3

Code Directory Structure

folders:

doc - something like this file will be at

includes - common libraries, macros, data structures (shortcuts.h)

pic - picture screenshots for README.md

src - project source file (cpp&h)

test - main.cpp ui control.cpp ui control.h

files:

CMakeLists.txt - cmake project compilation files

readme files on installation, compilation and running this software

leopard cam - the only executable for this linux camera tool

- makefile - makefile for building this software(alternative for CMakeLists.txt)

src/cam_property* - frame rate, gain, exposure, ae, ptz control

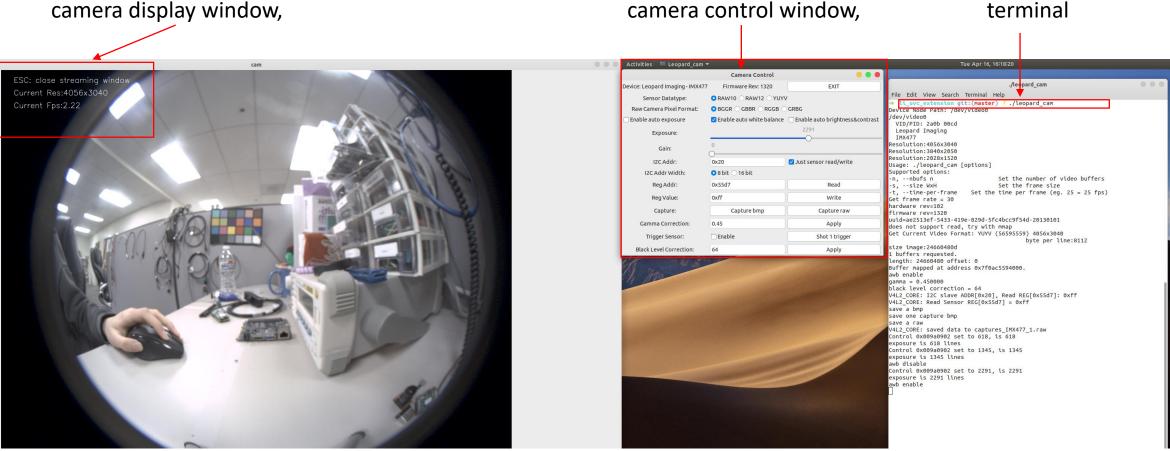
src/extend_cam_ctrl* - main backend code: gamma correction, awb, captures etc

src/uvc_extension_unit_ctrl* - all the uvc extension unit controls functionalities

src/v4l2 dev* - use udev for assigning right /dev/video#

Functionality Demo 1:

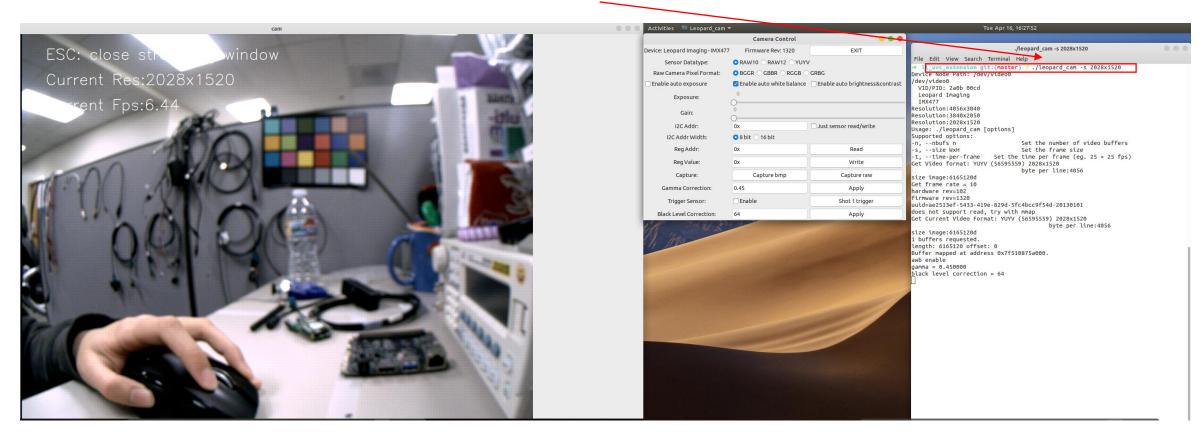
Tested on IMX477 RGGB RAW10 Cam Windows are divided into three: camera display window,



terminal

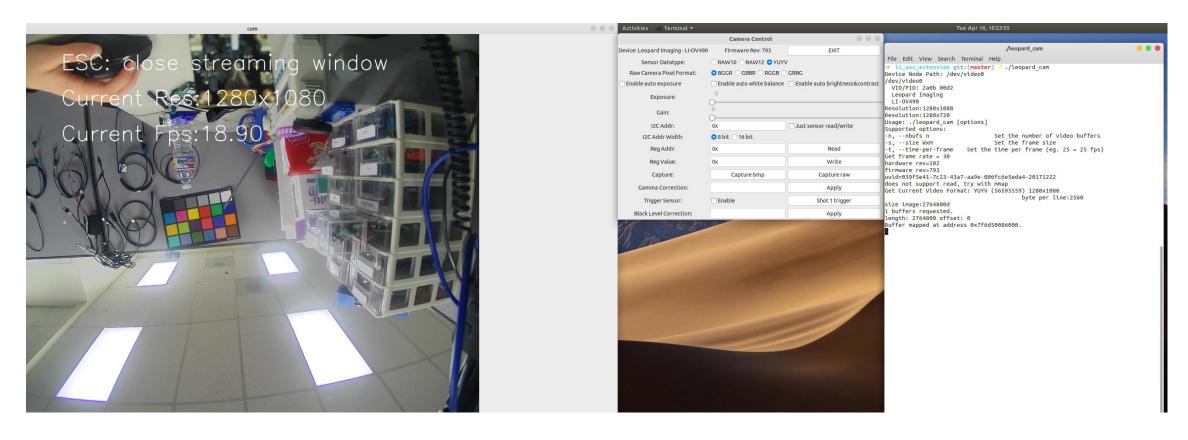
Functionality Demo 2:

Tested on IMX477 RGGB RAW10 Cam
To change resolution -> do a ./leopard_cam -s widthxheighth like so



Functionality Demo 3:

Tested on OV10640-OV490-YUV Cam



References:

- 1. http://git.ideasonboard.org/?p=yavta.git;a=summary (yavta)
- 2. https://sourceforge.net/p/guvcview/git-master/ci/master/tree/ (guvcview)
- 3. https://git.linuxtv.org/v4l-utils.git (v4l-utils)
- 4. https://stackoverflow.com/questions/24341114/simple-illumination-correction-in-images-opency-c (contrast limited adaptive histogram equalization algorithm)
- 5. https://gist.github.com/tomykaira/94472e9f4921ec2cf582 (auto white balance)
- 6. http://www.signal11.us/oss/udev/ (udev)