



# PERFORMANCE AND DEBUGGING TOOLS

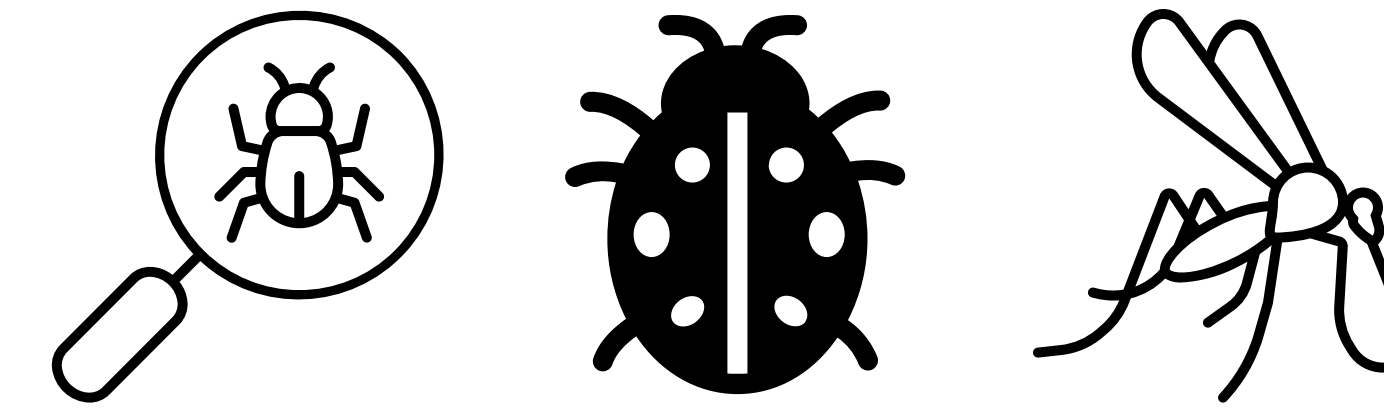
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# GOALS FOR THIS SESSION

Why you should use tools, and what they do

- All code has bugs. The more code, the more bugs.
- Different classes of „bugs“
  - Crashes, undefined behavior, deadlocks, correctness issues, ...
  - Time to solution, parallel efficiency, energy efficiency
- Treat performance issues as bugs, especially at scale



- Manual debugging: Mimic program execution, print state, time code regions
- Tool-assisted debugging: Automate „tedious“ part
  - More information, less effort
  - Otherwise unavailable information (hardware counters!)
- Fixing bugs not (yet ☺) automated: Tools simplify and enable analysis
- Introduce workflow and representative tools, focus on distributed GPU applications

# DEBUGGING CORRECTNESS: BEST PRACTICES

Before you start

- Crashes are „nice“ - the stacktrace often points to the bug
- Prerequisite: Compile flags
  - While developing, always use `-g -lineinfo`
  - Use `-g -G` for manual debugging
  - Specific flags for compilers/lanugages (e.g. gfortran): `-fcheck=bounds`
- Memory corruption: Out-of-bounds accesses may or may not crash
  - *compute-sanitizer*: Automate finding these errors
- Other issues: Manual debugging
  - *cuda-gdb*: Command-line debugger, GPU extensions

## NVCC compile flags for debugging

<code>-g</code>	Embed symbol info for <i>host</i> code
<code>-lineinfo</code>	Generate line correlation info for <i>device</i> code
<code>-G</code>	Device debug - <b>slow</b>

# COMPUTE-SANITIZER

Functional correctness checking suite for GPU

- `compute-sanitizer` is a collection of tools
- `memcheck` (default) tool comparable to [Valgrind's memcheck](#).
- Other tools include
  - `racecheck`: shared memory data access hazard detector
  - `initcheck`: uninitialized device global memory access detector
  - `synccheck`: identify whether a CUDA application is correctly using synchronization primitives
- Example run:

```
srun -n 4 compute-sanitizer \  
--log-file jacobi.%q{SLURM_PROCID}.log \  
--save jacobi.%q{SLURM_PROCID}.compute-sanitizer \  
./jacobi -niter 10
```
- Stores (potentially very long) text output in \*.log file, raw data separately, once per process.
- One file per MPI rank - more on %q{ } later

# COMPUTE-SANITIZER

## Anatomy of an error

- Look into log file, or use `compute-sanitizer --read <save file>`
- Actual output can be very long, if many GPU threads produce (similar) errors.

```
===== COMPUTE-SANITIZER
[....]
===== Invalid __global__ write of size 4 bytes
=====      at 0x6d0 in mpi/jacobi_kernels.cu:60:initialize_boundaries(float*, float*, float,
                                                                    int, int, int, int)

=====      by thread (1,0,0) in block (32,0,0)
=====      Address 0x14fb88020000 is out of bounds
=====      Saved host backtrace up to driver entry point at kernel launch time
=====      Host Frame: [0x20d6ea]
=====                      in libcuda.so.1
=====      Host Frame: [0x115ab]
[....]
=====
===== ERROR SUMMARY: 10 errors
```

- We introduced an off-by-one error in line 60 ourselves:

```
a_new[iy * nx + (nx - 1) + 1] = y0;
```



# APPROACHES FOR MULTI-PROCESS TOOLS

- Tools usually run on a single process - adapt for highly distributed applications?
  - Bugs in parallel programs are often serial bugs in disguise
- Common MPI paradigm: Workload distributed; bug classes/performance similar for all processes
  - Not: Load imbalance, parallel race conditions; require parallel tools
- Ergo: Run tool N times in parallel, have N output files, only look at 1 (or 2, ...)
- `%q{ENV_VAR}` supported by all the NVIDIA tools discussed here, embed environment variable in file name
  - `ENV_VAR` should be one set by the process launcher, unique ID
  - Evaluated only once tool starts running (on compute node) - not when launching job
- Other tools: Use a launcher script, for late evaluation

## OpenMPI:

```
OMPI_COMM_WORLD_RANK  
OMPI_COMM_WORLD_LOCAL_RANK
```

## MVAPICH2:

```
MV2_COMM_WORLD_RANK  
MV2_COMM_WORLD_LOCAL_RANK
```

## Slurm:

```
SLURM_PROCID  
SLURM_LOCALID
```

<https://www.open-mpi.org/faq/?category=running#mpi-environmental-variables>

<http://mvapich.cse.ohio-state.edu/static/media/mvapich/mvapich2-2.2-userguide.html#x1-32100013>

[https://slurm.schedmd.com/srun.html#SECTION\\_OUTPUT-ENVIRONMENT-VARIABLES](https://slurm.schedmd.com/srun.html#SECTION_OUTPUT-ENVIRONMENT-VARIABLES)

# USING CUDA-GDB WITH MPI

- Launcher (mpirun/srun/...) complicates starting process inside debugger
- Workaround: Attach later

```
#include <unistd.h>
if (rank == 0) {
    char name[255]; gethostname(name, sizeof(name)); bool attached;
    printf("rank %d: pid %d on %s ready to attach\n", rank, getpid(), name);
    while (!attached) { sleep(5); }
}
```

- Launch process, sleep on particular rank

```
$ srun -n 4 ./jacobi -niter 10
rank 0: pid 28920 on jwb0001.juwels ready to attach
```

- Then attach from another terminal (may need more flags)

```
[jwlogin]$ JOBID=$(squeue -ho %i --me) # obtain job ID of user's first job
[jwlogin]$ srun -n 1 --jobid ${JOBID} --pty bash -i # launch interactive shell on job's node
[jwb0001]$ cuda-gdb --attach 28920
```

- Wake up sleeping process and continue debugging normally

```
(cuda-gdb) set var attached=true
```

JSC system shortcut:  
sgoto --help

# USING CUDA-GDB WITH MPI

## Environment variables for easier debugging

- Automatically wait for attach on exception without code changes:

```
$ CUDA_DEVICE_WAITS_ON_EXCEPTION=1 srun ./jacobi -niter 10
Single GPU jacobi relaxation: 10 iterations on 16384 x 16384 mesh with norm check every 1
iterations
jwb0129.juwels: The application encountered a device error and CUDA_DEVICE_WAITS_ON_EXCEPTION is
set. You can now attach a debugger to the application (PID 31562) for inspection.
```

- Same as before, go to node (see previous slide), then attach cuda-gdb:

```
$ cuda-gdb --pid 31562
CUDA Exception: Warp Illegal Address
The exception was triggered at PC 0x508ca70 (jacobi_kernels.cu:88)

Thread 1 "jacobi" received signal CUDA_EXCEPTION_14, Warp Illegal Address.
[Switching focus to CUDA kernel 0, grid 4, block (0,0,0), thread (0,20,0), device 0, sm 0, warp 21,
lane 0]
0x00000000508ca80 in jacobi_kernel<32, 32><<<(512,512,1), (32,32,1)>>> (/*...*/) at jacobi_kernels.c
u:88
88          real foo = *((real*)nullptr);
```



# DEBUGGING MPI+CUDA APPLICATIONS

More environment variables for offline debugging

- With `CUDA_ENABLE_COREDUMP_ON_EXCEPTION=1` core dumps are generated in case of an exception
  - `CUDA_ENABLE_LIGHTWEIGHT_COREDUMP=1` does not dump application memory - faster
  - Can be used for post-mortem debugging
  - Helpful if live debugging is not possible
- Enable/Disable CPU part of core dump (enabled by default)
  - `CUDA_ENABLE_CPU_COREDUMP_ON_EXCEPTION`
- Specify name of core dump file with `CUDA_COREDUMP_FILE`
- Open GPU
  - `(cuda-gdb) target cudacore core.cuda`
- Open CPU+GPU
  - `(cuda-gdb) target core core.cpu core.cuda`

<https://docs.nvidia.com/cuda/cuda-gdb/index.html#gpu-coredump>



# EXAMPLE: OPENING A CORE DUMP

- Running and generating the core file

```
$ CUDA_ENABLE_COREDUMP_ON_EXCEPTION=1 CUDA_ENABLE_LIGHTWEIGHT_COREDUMP=1 srun ./jacobi -niter 10
Single GPU jacobi relaxation: 10 iterations on 16384 x 16384 mesh with norm check every 1 iterations
srun: error: jwb0021: tasks 0-3: Aborted (core dumped)

$ ls core*
core.jwb0021.juwels.23959  core_1633801834_jwb0021.juwels_23959.nvcudmp ...
```

- And opening the core dump in cuda-gdb

```
(cuda-gdb) target cudacore core_1633801834_jwb0021.juwels_23959.nvcudmp
Opening GPU coredump: core_1633801834_jwb0021.juwels_23959.nvcudmp

[New Thread 23979]

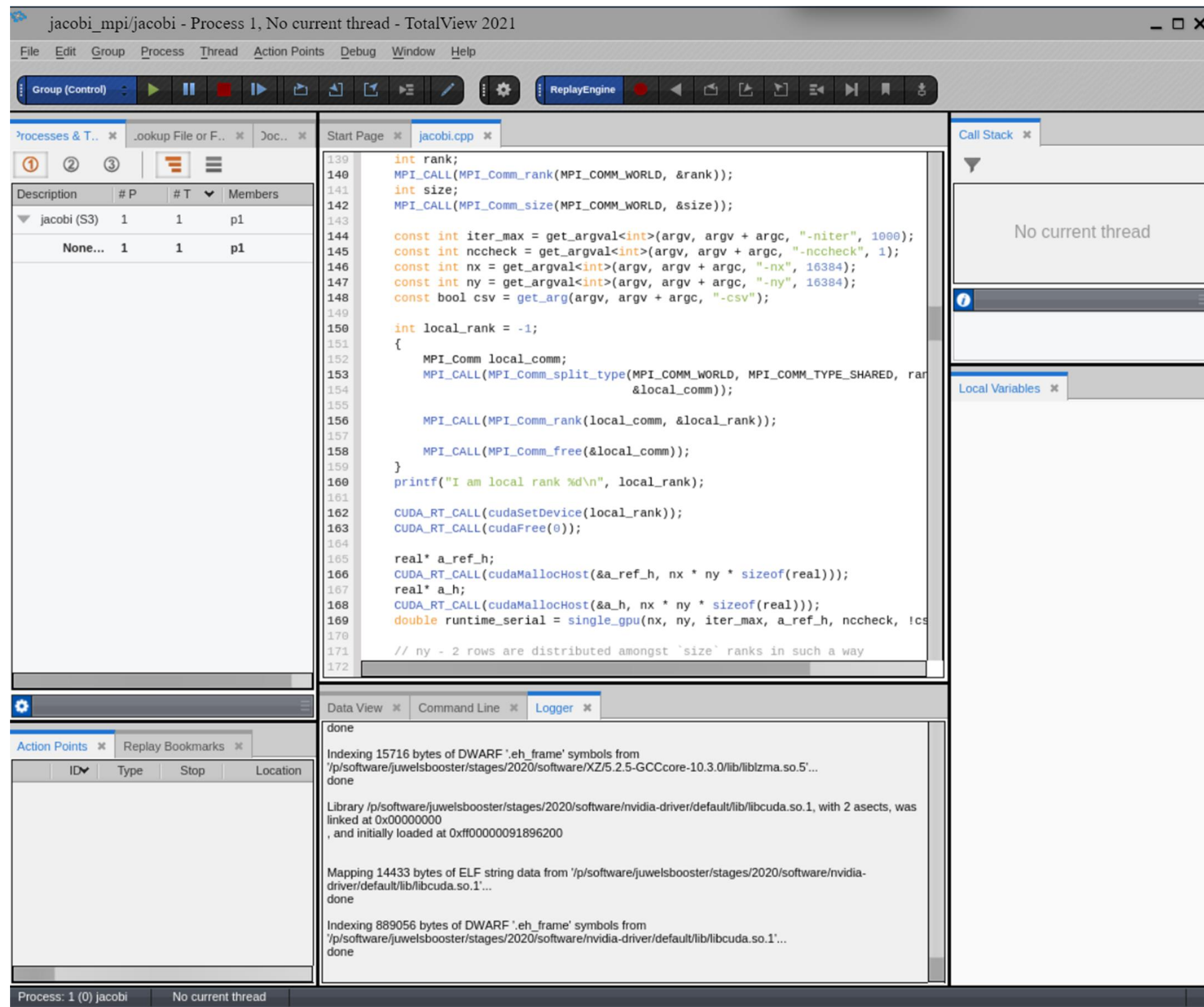
warning: No exception was found on the device

[Current focus set to CUDA kernel 0, grid 4, block (0,0,0), thread (0,2,0), device 0, sm 0, warp 0, lane 0]
#0  0x00000000057e1ae0 in void jacobi_kernel<32, 32>(float*, float const*, float*, int, int, int, bool)
    <<<(512,512,1), (32,32,1)>>> ()
    at /p/project/cexalab/hrywniak1/code/multi-gpu-programming-models/mpi/jacobi_kernels.cu:87
87      real foo = *((real*)nullptr);

(cuda-gdb)
```



# SPECIALIZED PARALLEL DEBUGGERS



- `cuda-gdb` can debug multiple processes (`add-inferior`), although...
- For truly parallel bugs (e.g. multi-node, multi-process race conditions), third-party tools offer more convenience
  - Or enable „live“ analysis in the first place
- ARM DDT
- Perforce TotalView (screenshot)
  - Available as module on JSC systems



# WRITE DEBUGGABLE SOFTWARE

A case for modularity, and proper test cases

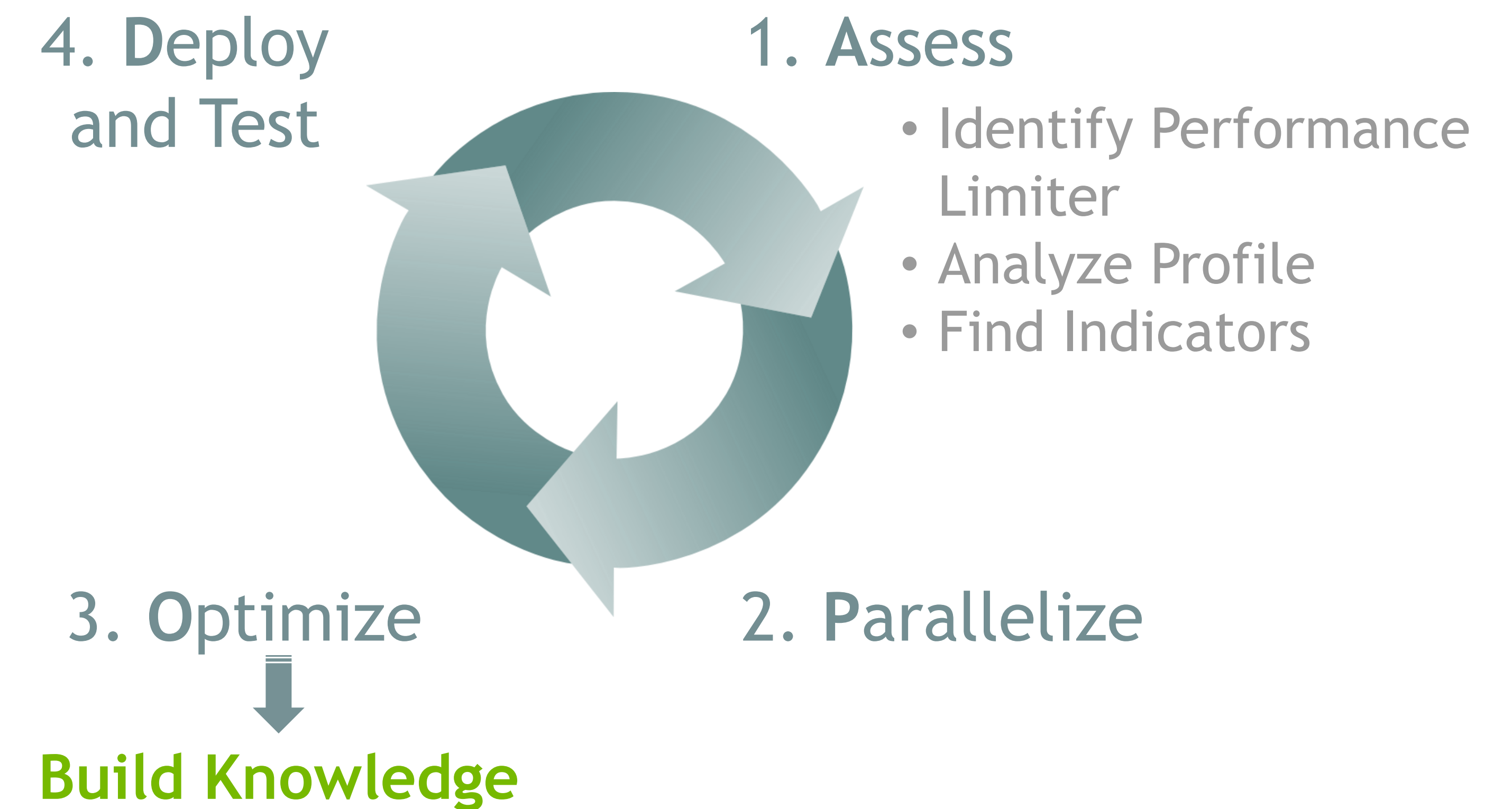
- Think about interfaces in your code: Which parts must depend on each other, etc.
  - Example: BLAS, linear algebra routines
- Think about structure and architecture („the big picture“)
- Don't go overboard: „I read this book, we need 100% test coverage“, etc.
  - For many research codes that would be overkill
- **“Everything should be made as simple as possible, but no simpler.”**
- Badly structured legacy code slows you down as well, as it resists change
  - Today's code is tomorrow's legacy
  - Strike a balance, avoid full rewrites. Code encapsulates hard-earned bug fixes and knowledge
- Representative test cases
  - Contain the correct science, walk the code paths
  - But run quickly, best on a single process, should run on a single node
  - Some (but not all) tests at full scale



# DEBUGGING PERFORMANCE

Why you *must* use profilers

- Paraphrasing [Donald Knuth](#):
  - Don't overoptimize, but meta-optimize your own time by using tools to focus on relevant parts
- Do not trust your gut instinct - very often *very* misleading
  - Easy to waste a lot of time chasing the "perceived" issue
- Getting the same information, you end up reimplementing your own profiler
- Iterative workflow
- Different kinds of measurement tools, different tradeoffs
  - Instrumenting/Sampling
  - Profiling/Tracing
  - multi-process, single-process, kernel-level
- Here: Focus on GPU and system-level: Nsight Systems





# THE NSIGHT SUITE COMPONENTS

How the pieces fit together



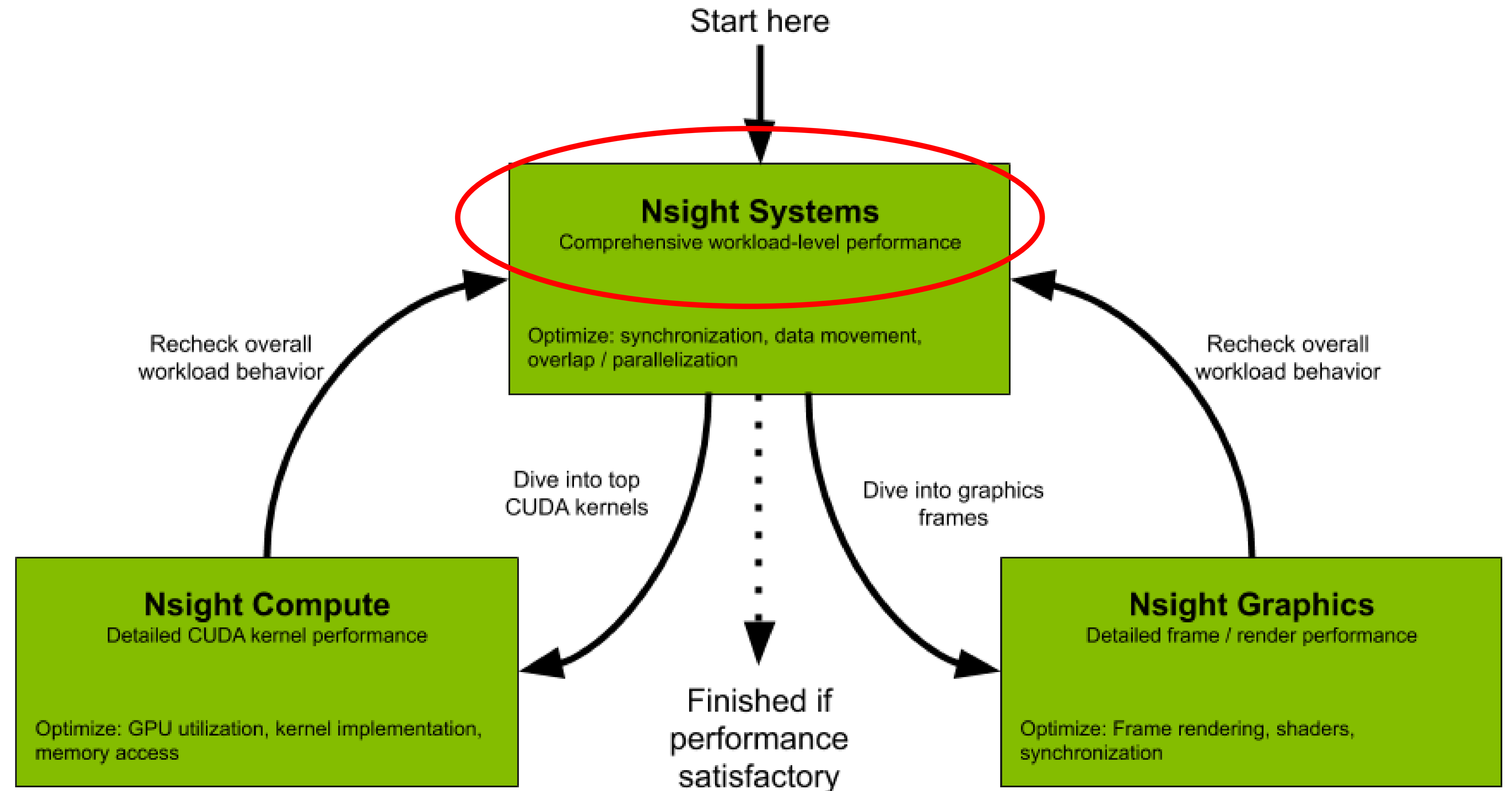
- Nsight **Systems**: Coarse-grained, whole-application



- Nsight **Compute**: Fine-grained, kernel-level

- NVTX: Support and structure across tools

- Main purpose: Performance optimization
  - But at their core, advanced *measurement* tools





# A FIRST (I)NSIGHT

## Recording with the CLI

- Use the command line
  - `srun nsys profile --trace=cuda,nvtx,mpi --output=my_report.%q{SLURM_PROCID} ./jacobi -niter 10`
- Inspect results: Open the report file in the GUI
  - Also possible to get details on command line
  - Either add `--stats` to profile command line, or: `nsys stats --help`
- Runs set of reports on command line, customizable (sqlite + Python):
  - Useful to check validity of profile, identify important kernels

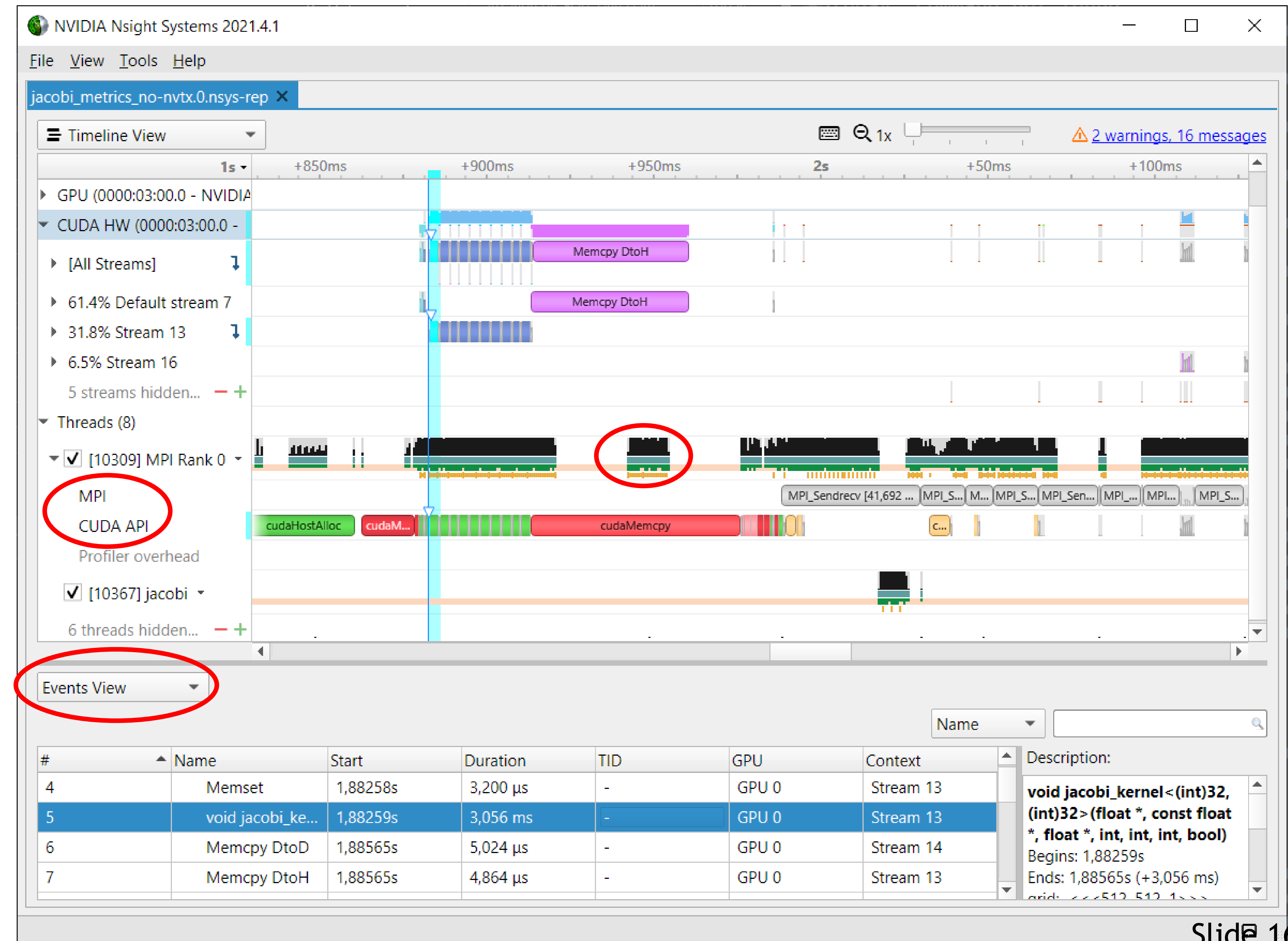
Running [.../reports/**gpukernsum.py** jacobi\_metrics\_more-nvtx.0.**sqlite**]...

Time(%)	Total Time (ns)	Instances	Avg (ns)	Med (ns)	Min (ns)	Max (ns)	StdDev (ns)	Name
99.9	36750359	20	1837518.0	1838466.5	622945	3055044	1245121.7	void jacobi_kernel
0.1	22816	2	11408.0	11408.0	7520	15296	5498.5	initialize_boundaries



# SYSTEM-LEVEL PROFILING WITH NSIGHT SYSTEMS

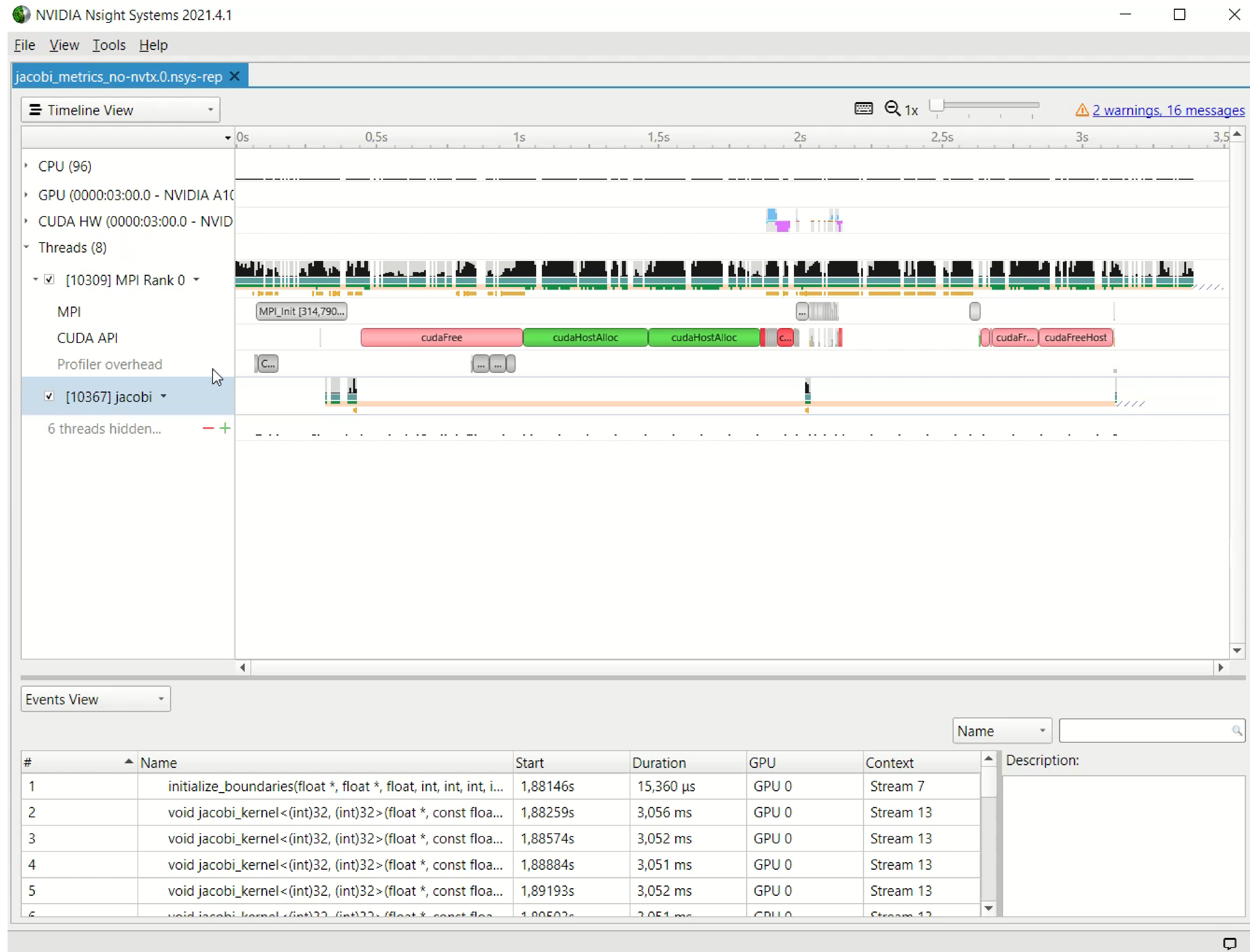
- Global timeline view
  - CUDA HW: streams, kernels, memory
- Different traces, e.g. CUDA, MPI
  - correlations API <-> HW
- Stack samples
  - bottom-up, top-down for CPU code
- GPU metrics
- Events View
  - Expert Systems
- looks at single process (tree)
  - correlate multi-process reports in single timeline





# NSIGHT SYSTEMS BASIC WORKFLOW

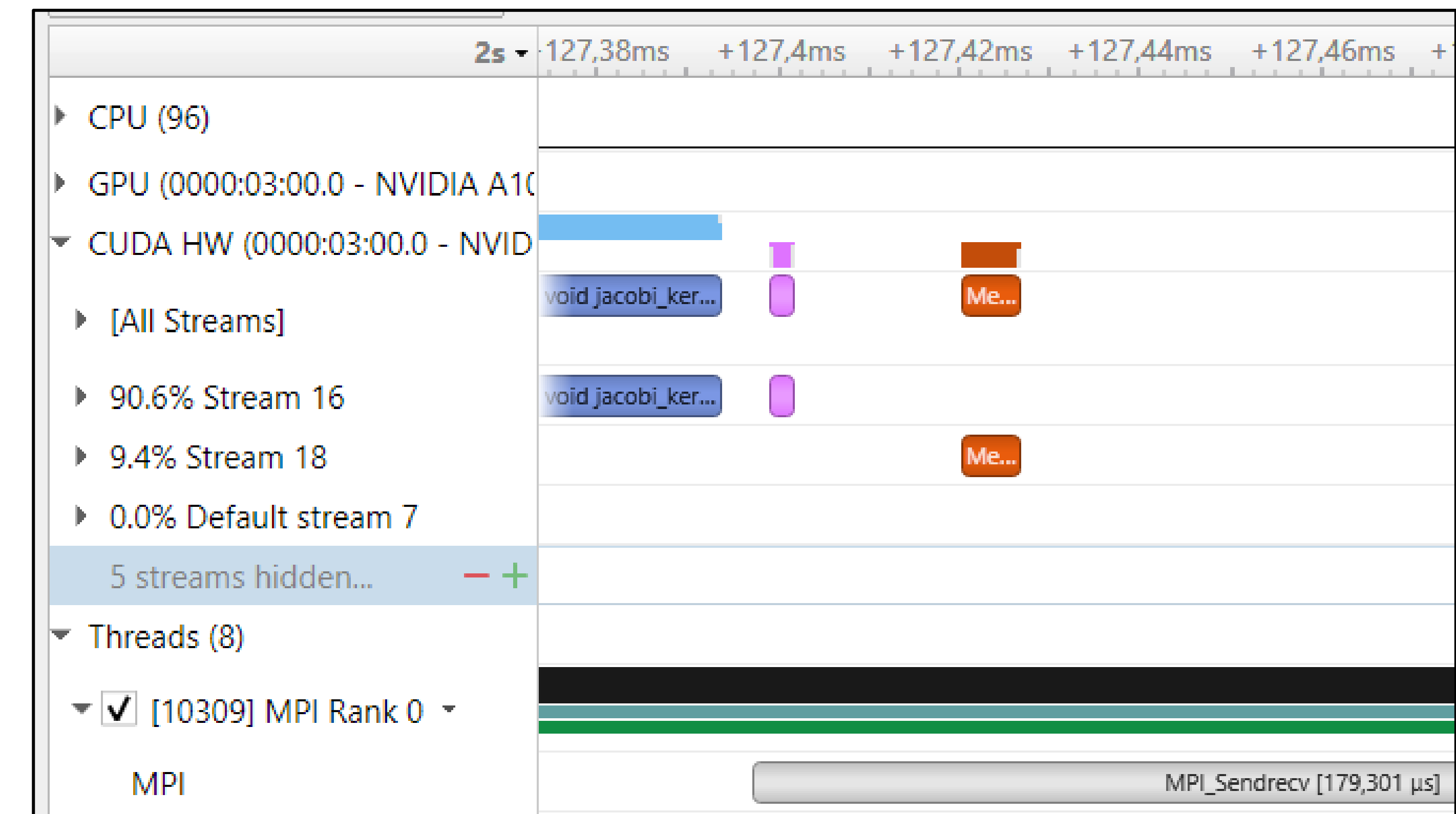
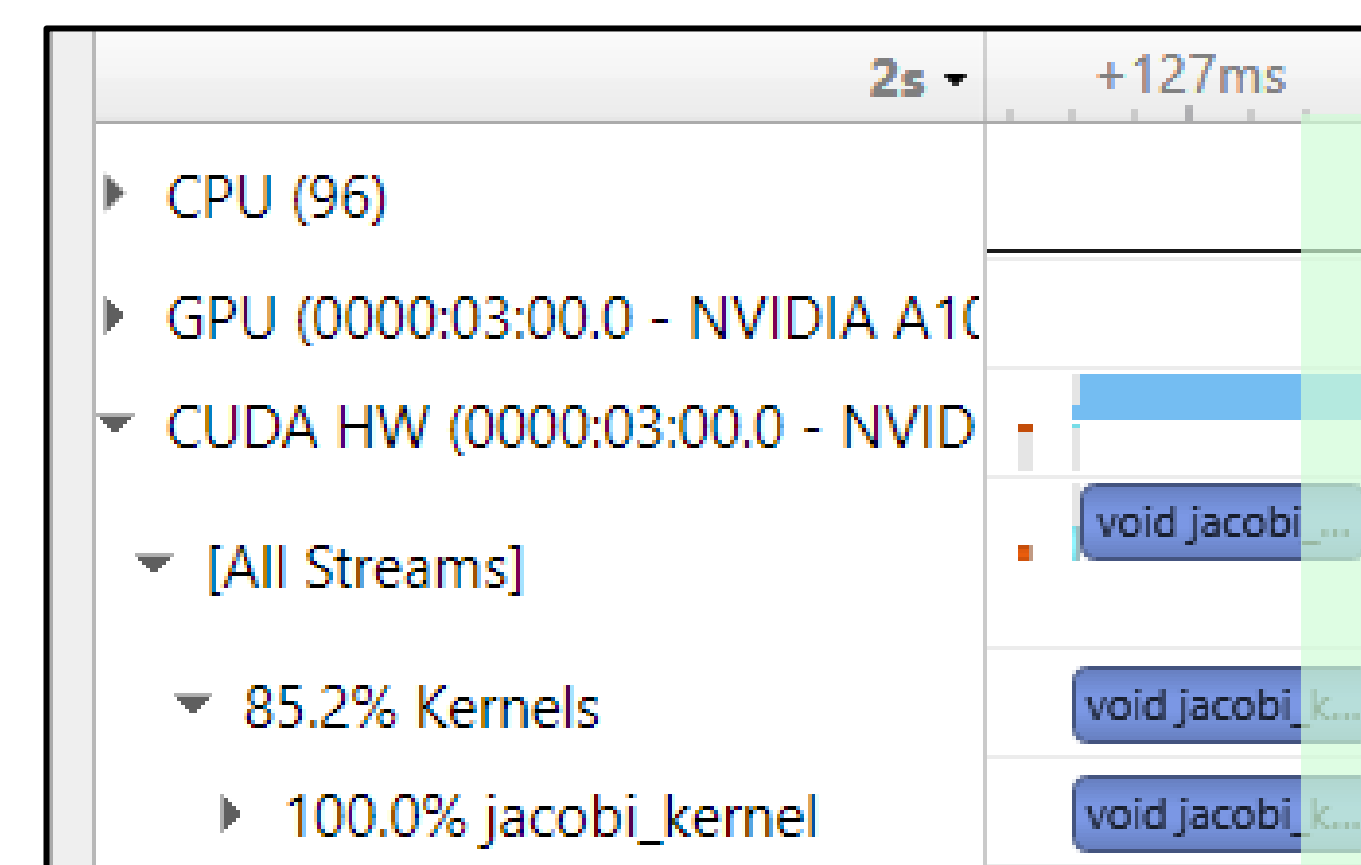
Navigating the timeline and finding interesting areas





# DISCOVERING OPTIMIZATION POTENTIAL

- Using our Jacobi example (see exercise)
- Spot kernels - lots of whitespace
  - Which part is „bad“?
  - Enhance!
- MPI calls
  - Memory copies
  - We know: This is CUDA-aware MPI
- Even without knowing source, insight
- Too complicated for repeated/reliable usage
  - How to simplify navigating and comparing reports?

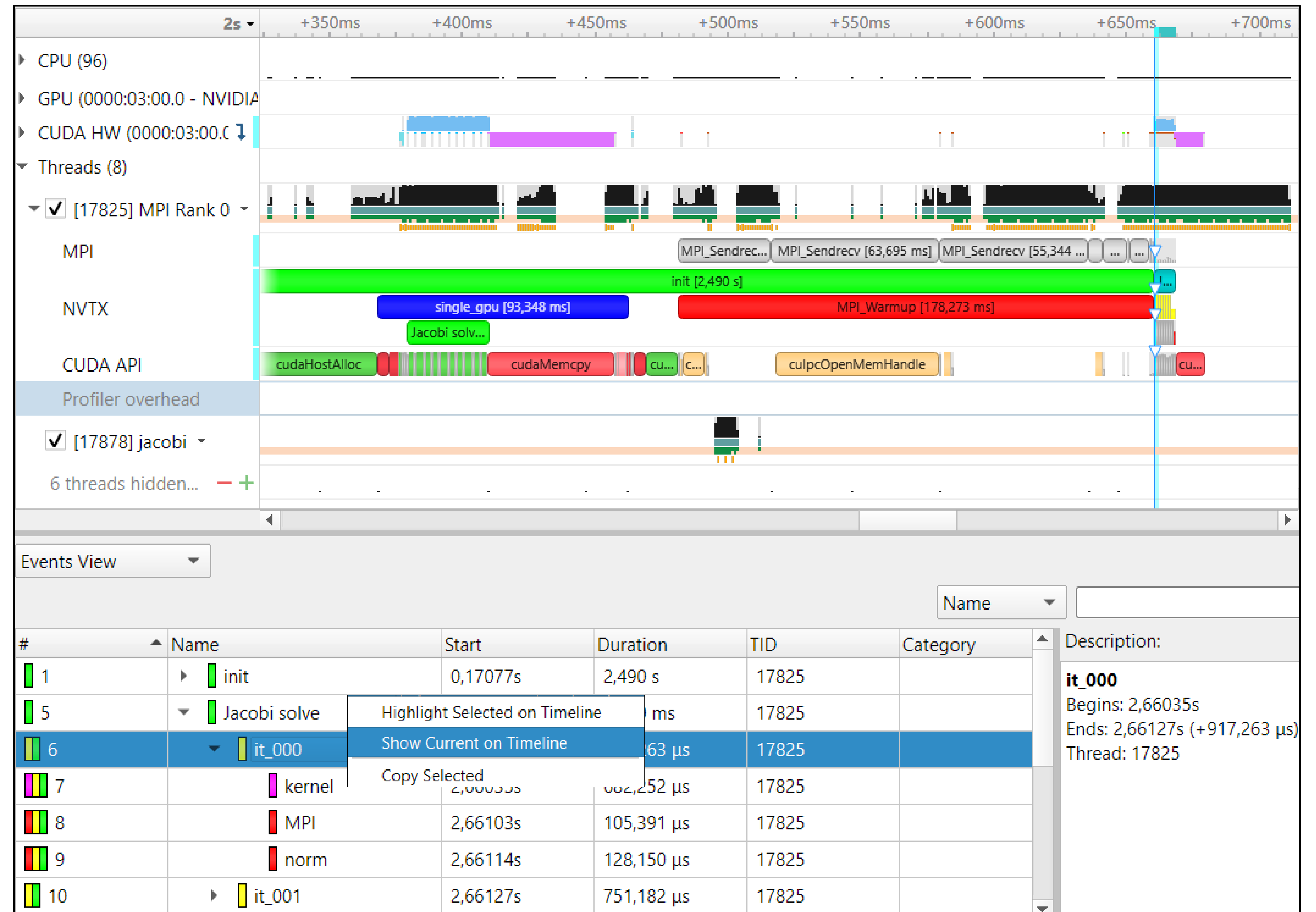




# ADDING SOME COLOR

Code annotation with NVTX

- Same section of timeline as before
  - Events view: Quick navigation
- Like manual timing, only less work
- Nesting
- Correlation, filtering



# ADDING NVTX

## Simple range-based API

- `#include "nvtx3/nvToolsExt.h"`
  - NVTX v3 is header-only, needs just `-ldl`
  - C++ and Python APIs
- Fortran: [NVHPC compilers include module](#)
  - Just use `nvtx` and `-lnvhpcwrapnvtx`
  - Other compilers: See blog posts linked below
- Definitely: Include `PUSH/POP` macros (see links below)  
`PUSH_RANGE(name, color_idx)`
- Sprinkle them strategically through code
  - Use hierarchically: Nest ranges
- Not shown: Advanced usage (domains, ...)
- Similar range-based annotations exist for other tools
  - e.g. [SCOREP\\_USER\\_REGION\\_BEGIN](#)

```
int main(int argc, char** argv) {
    PUSH_RANGE("main", 0)
    PUSH_RANGE("init", 1)
    do_initialization();
    POP_RANGE
    /* ... */
    PUSH_RANGE("computation", 2)
    jacobi_kernel<<< /* ... */, compute_stream>>>(...);
    cudaStreamSynchronize(compute_stream);
    POP_RANGE
    /* ... */
    POP_RANGE
}
```

<https://github.com/NVIDIA/NVTX> and <https://nvidia.github.io/NVTX/#how-do-i-use-nvtx-in-my-code>

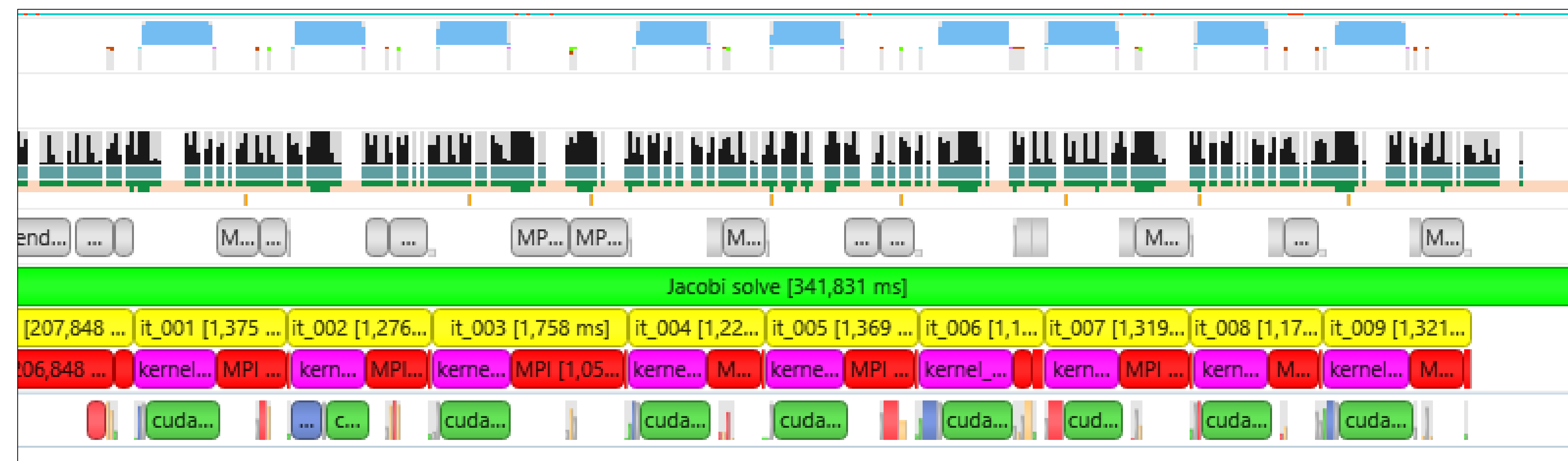
<https://developer.nvidia.com/blog/cuda-pro-tip-generate-custom-application-profile-timelines-nvtx/>  
<https://developer.nvidia.com/blog/customize-cuda-fortran-profiling-nvtx/>



# MINIMIZING PROFILE SIZE

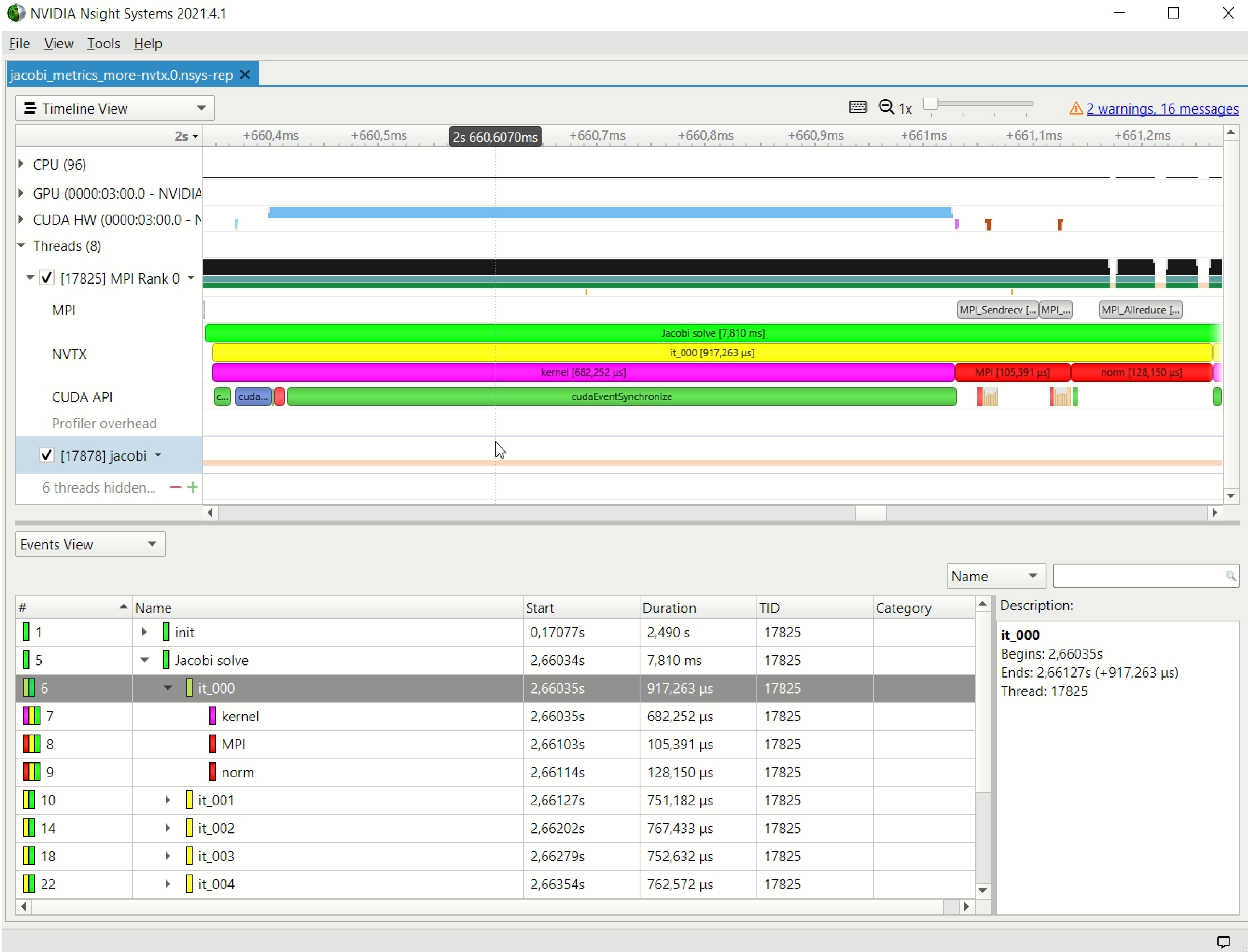
Shorter time, smaller files = quicker progress

- Only profile what you need - all profilers have some overhead
  - Example: Event that occurs after long-running setup phase
- Bonus: lower number of events leads to smaller file size
- Add to nsys command line:
  - `--capture-range=nvtx --nvtx-capture=any_nvtx_marker_name \`  
`--env-var=NSYS_NVTX_PROFILER_REGISTER_ONLY=0 --kill none`
- **Alternatively:** `cudaProfilerStart()` and `-Stop()`
  - `--capture-range=cudaProfilerApi`



# NSIGHT SYSTEMS WORKFLOW WITH NVTX

Repeating the analysis

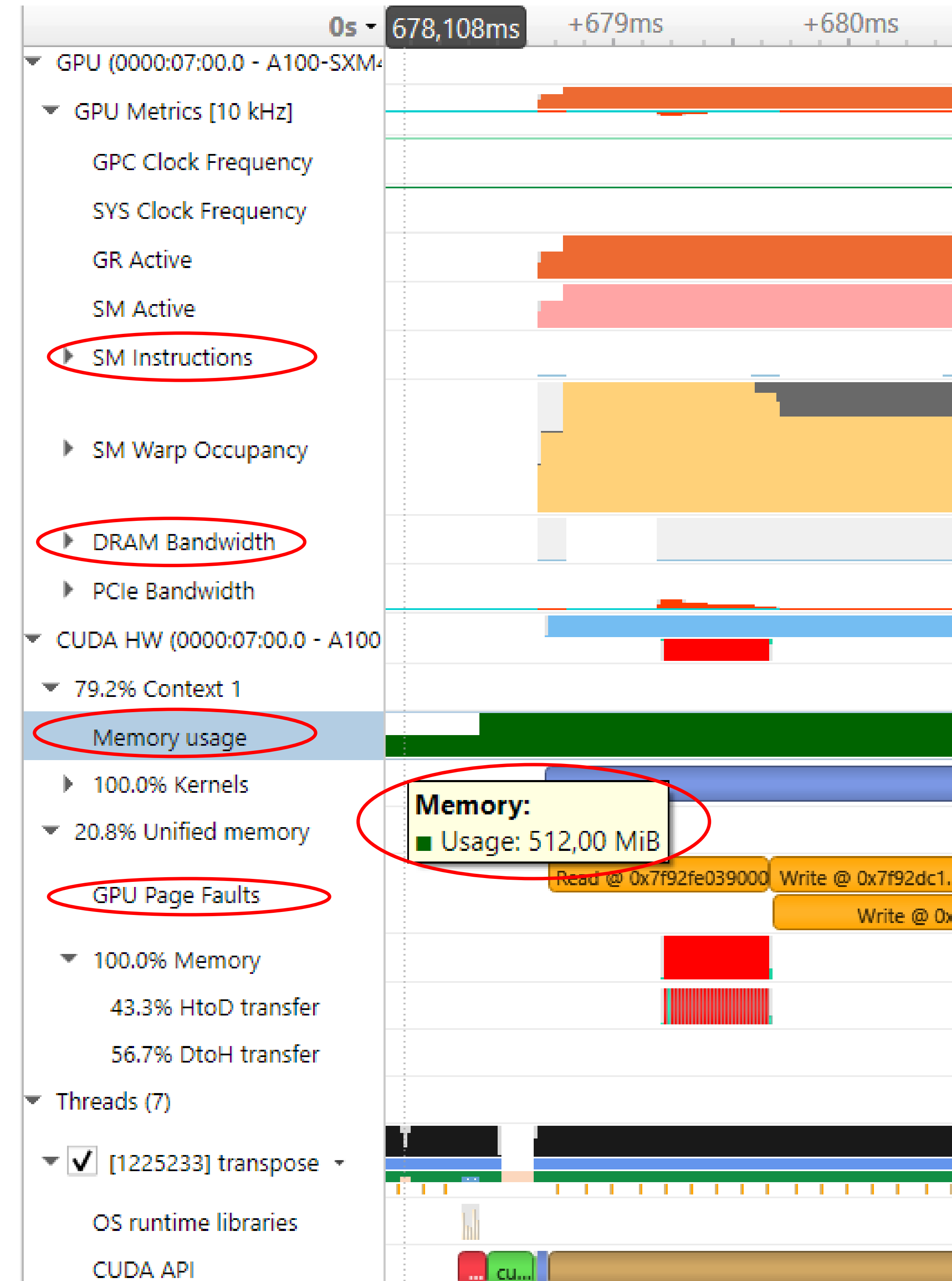




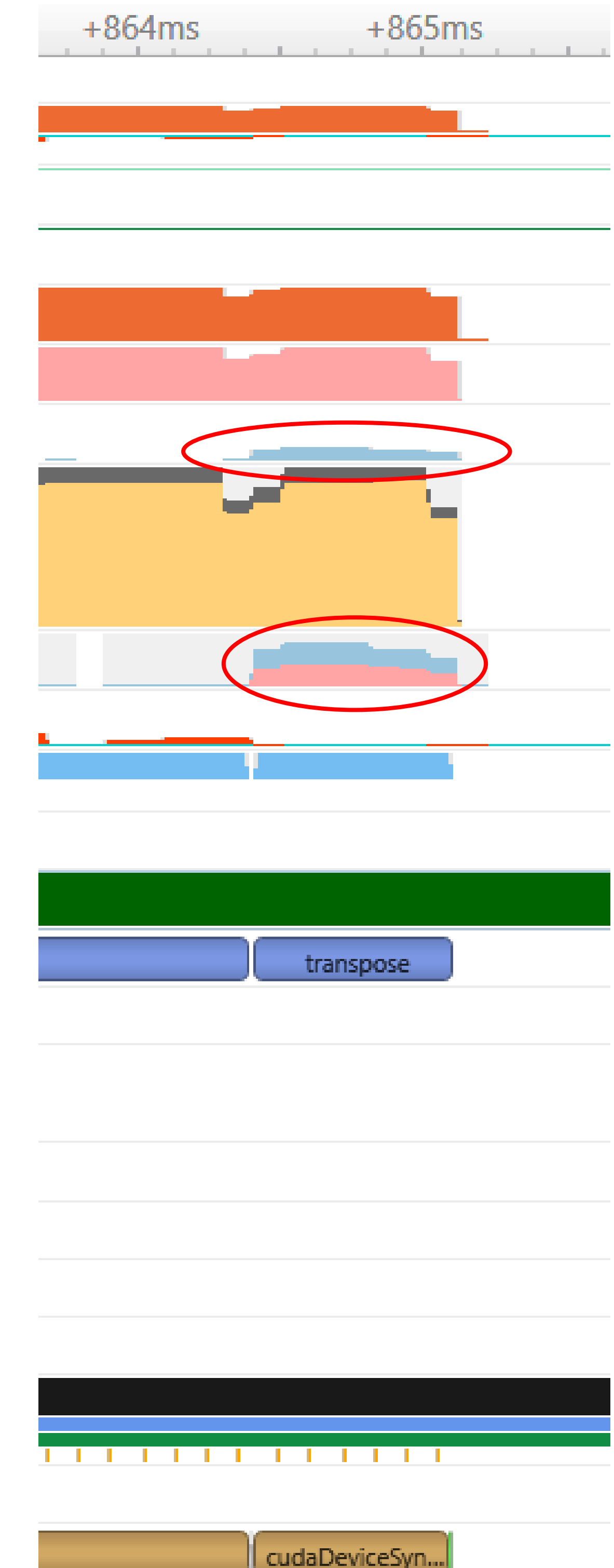
# GPU METRICS IN NSIGHT SYSTEMS

...and other traces you can activate

- Valuable low-overhead insight into HW usage:
  - SM instructions
  - DRAM Bandwidth, PCIe Bandwidth (GPUDirect)
- Also: Memory usage, Page Faults (higher overhead)
  - CUDA Programming guide: [Unified Memory Programming](#)
- Can save kernel-level profiling effort!
- `nsys profile`
  - `--gpu-metrics-device=0`
  - `--cuda-memory-usage=true`
  - `--cuda-um-cpu-page-faults=true`
  - `--cuda-um-gpu-page-faults=true``./app`



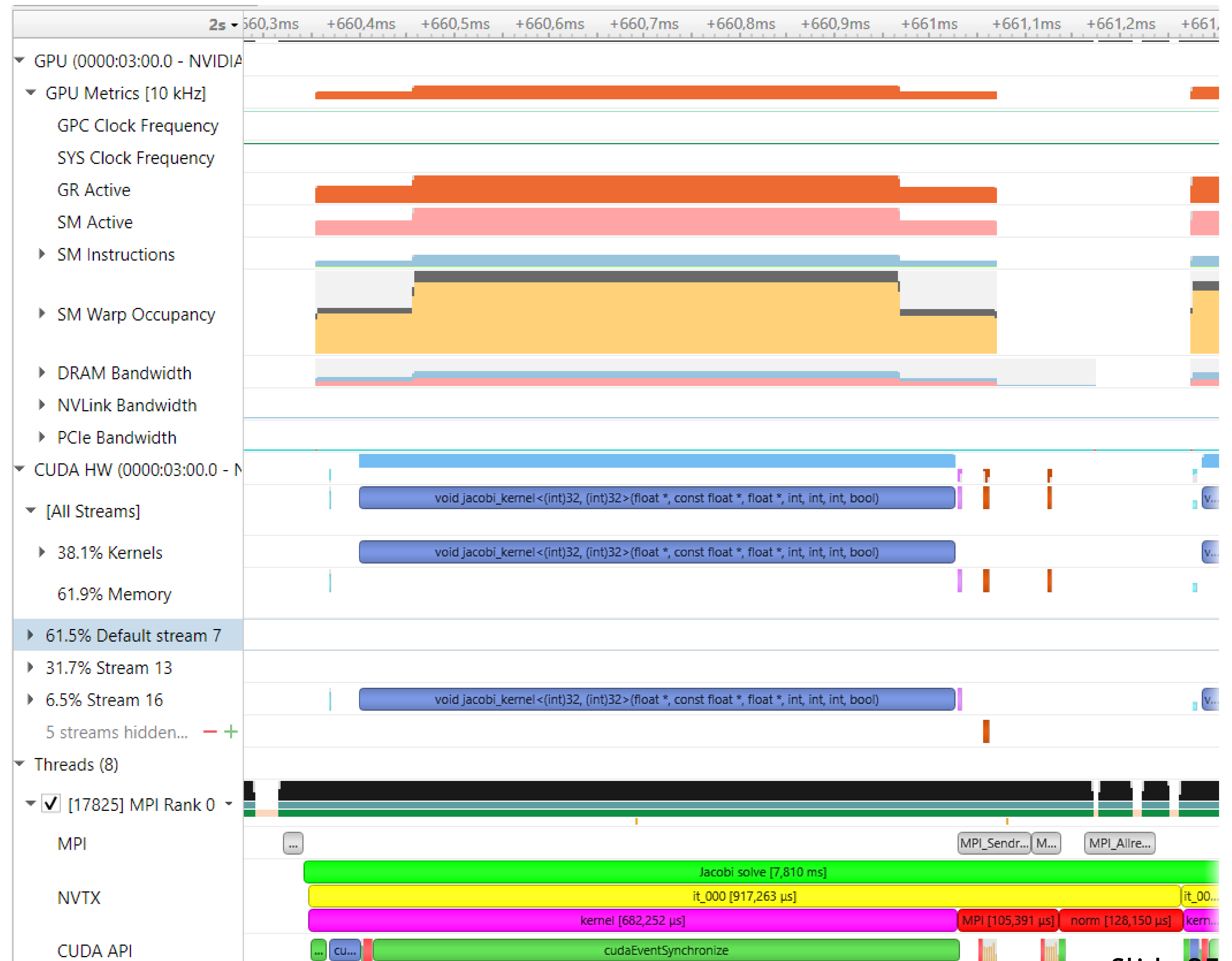
...



# FOCUSING THE ANALYSIS

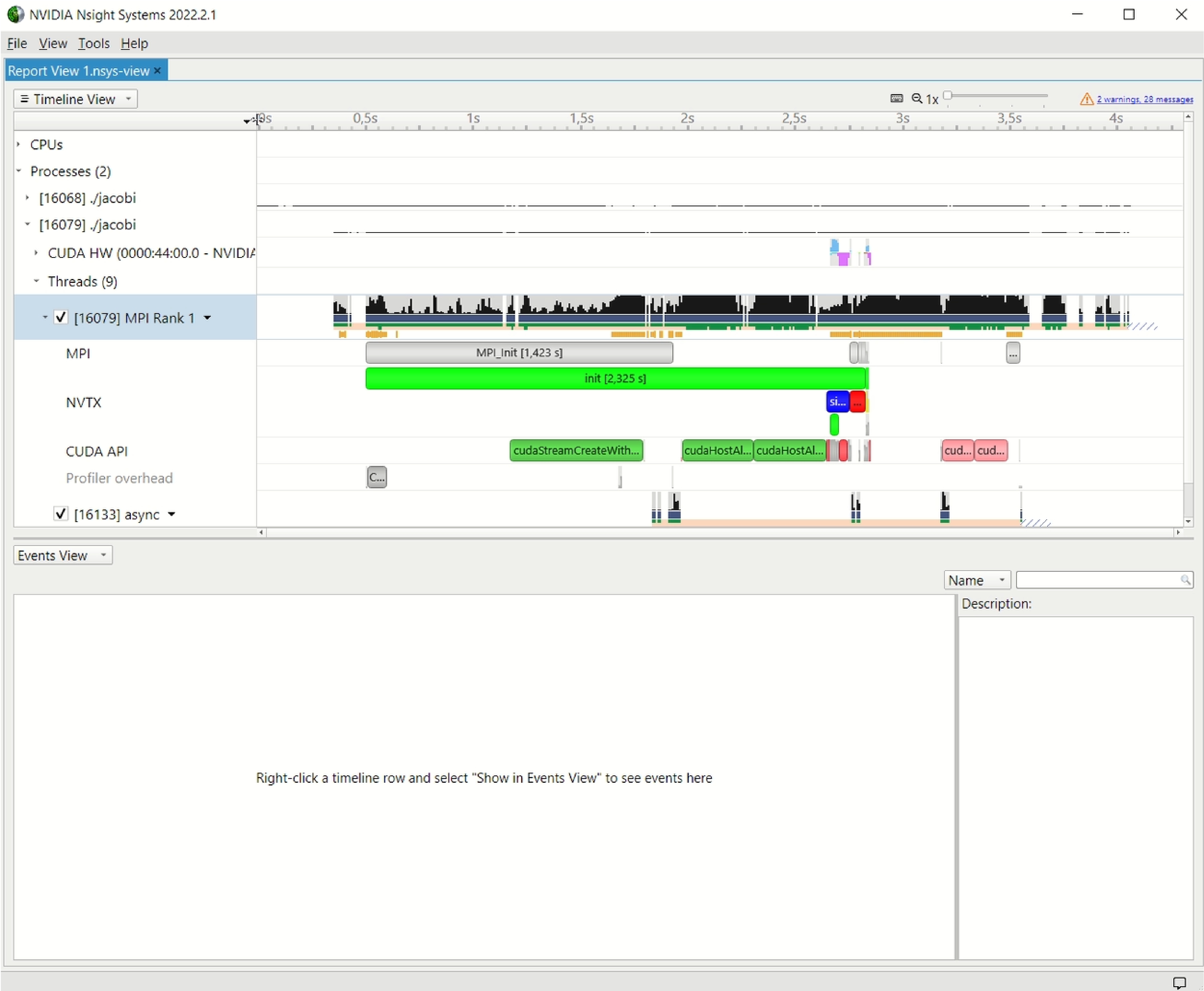
## Introducing GPU metrics sampling

- Discover the „unit cell“ of performance
  - in our case: single iteration
- Other blank spots during setup can be ignored (amortized, many more iterations)
- Maybe: Too small for proper comms profiling
- Kernel itself adequately using GPU
  - Remaning blank spots?
- Norm calculation
  - Can be turned off
- But still: Overlap potential? Can we run kernel during MPI?
  - later lectures



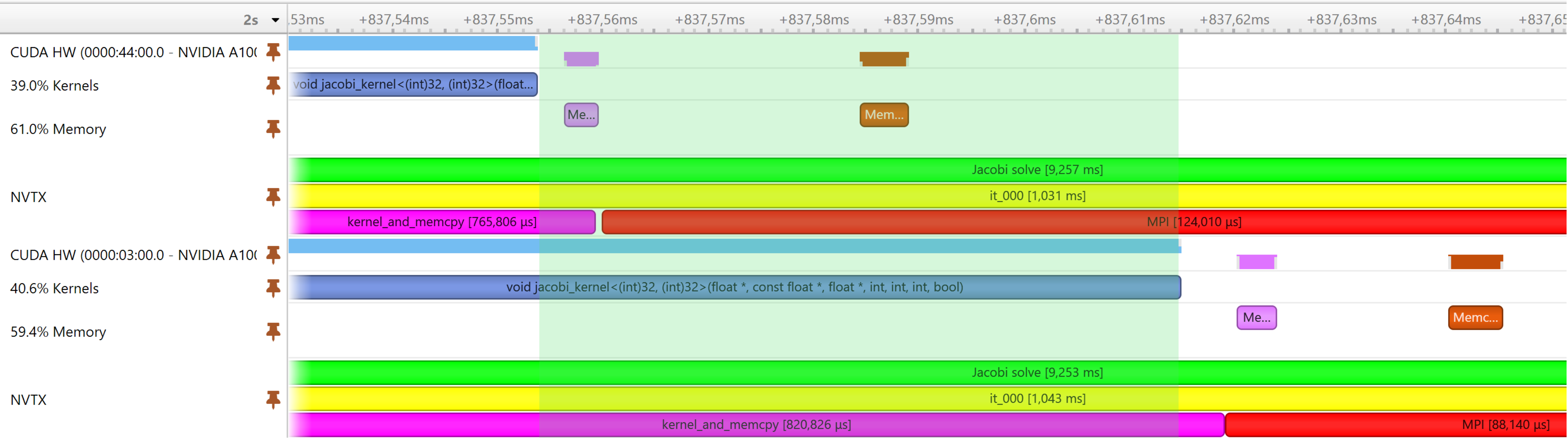


# USING MULTIPLE REPORTS IN NSIGHT SYSTEMS



# MULTI-PROCESS GPU ANALYSIS

- Load multiple reports into timeline
  - analyze differences in execution, GPU utilization
- Pin rows for comparison
- Example: End time of kernel execution





# COMMUNITY PROFILING TOOLS

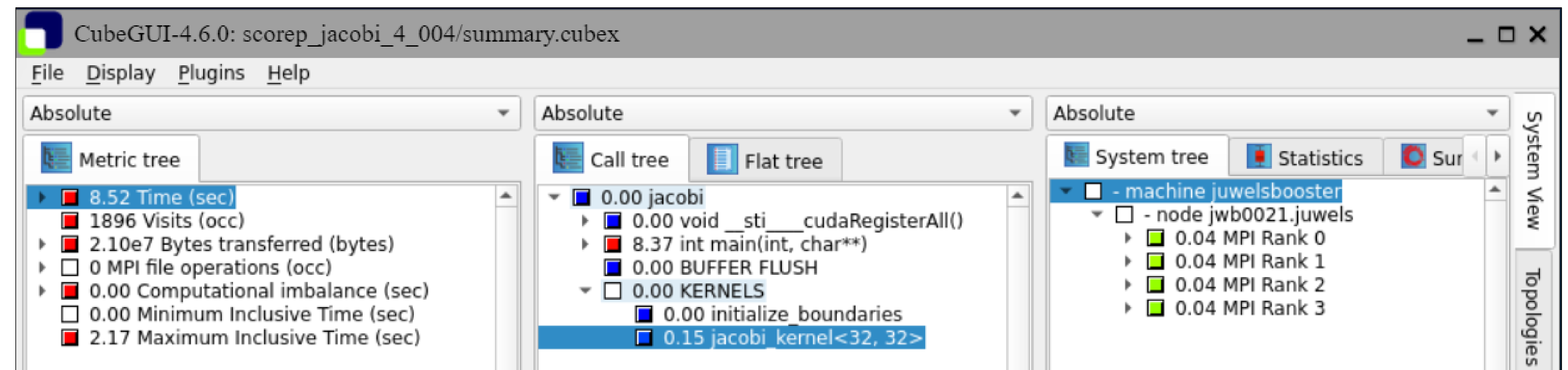
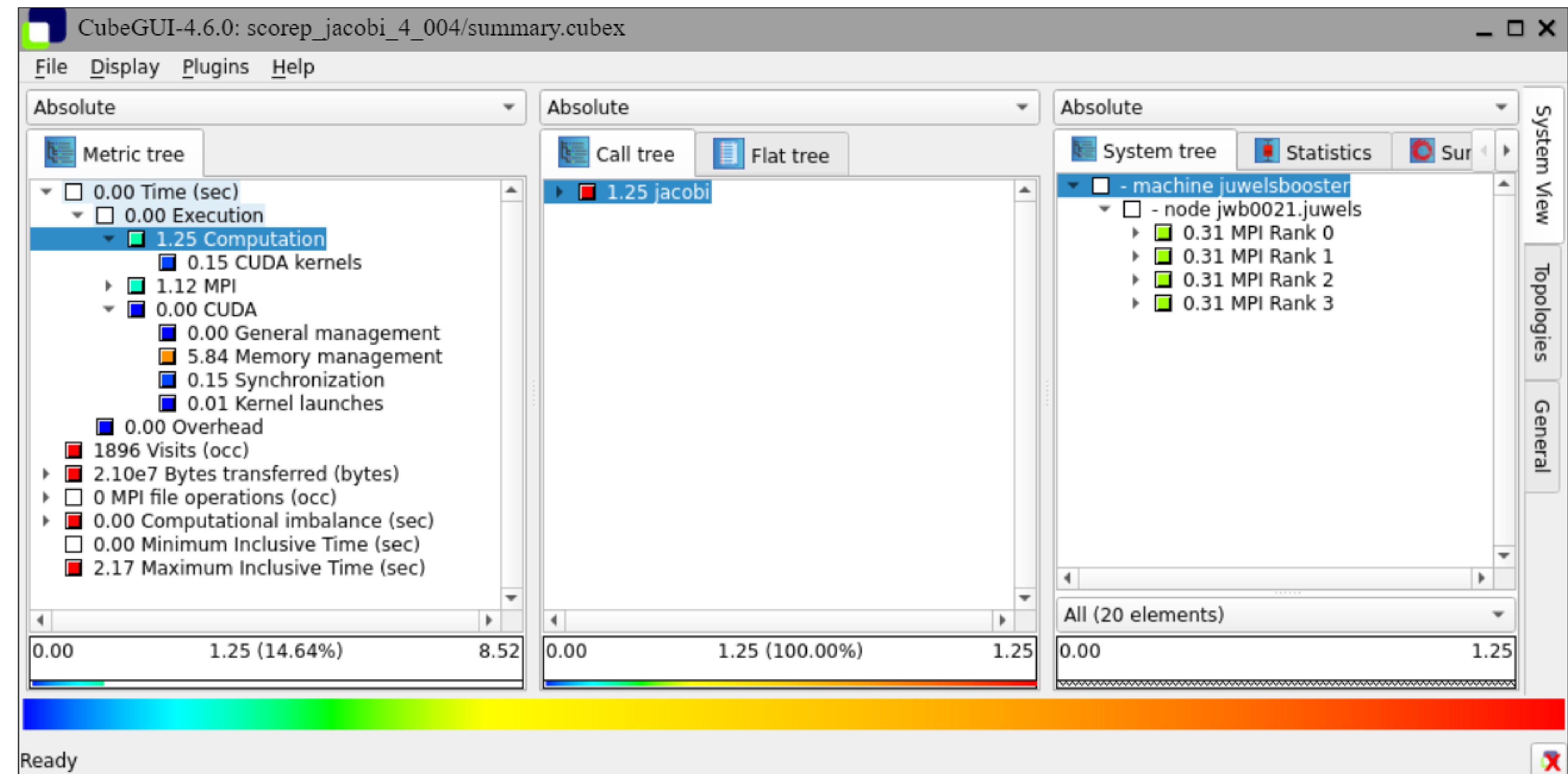
Specialized for large-scale distributed analysis

- Detecting issues at scale of thousands of GPUs (and processes)
  - Need to slice and dice data, too much to make sense of raw data
- Common measurement/instrumentation infrastructure: *Score-P*
  - Prefix all compilation/linker commands with `scorep -cuda`
- GPU data integration
  - CUDA profiling tools interface (CUPTI)
- Run the application to collect...
  - profiling data, for Scalasca
  - tracing data, for Vampir
  - (selection of tools not exhaustive)
- Tracing in particular: Careful tuning to keep overhead low (filtering)



# SCALASCA / CUBE

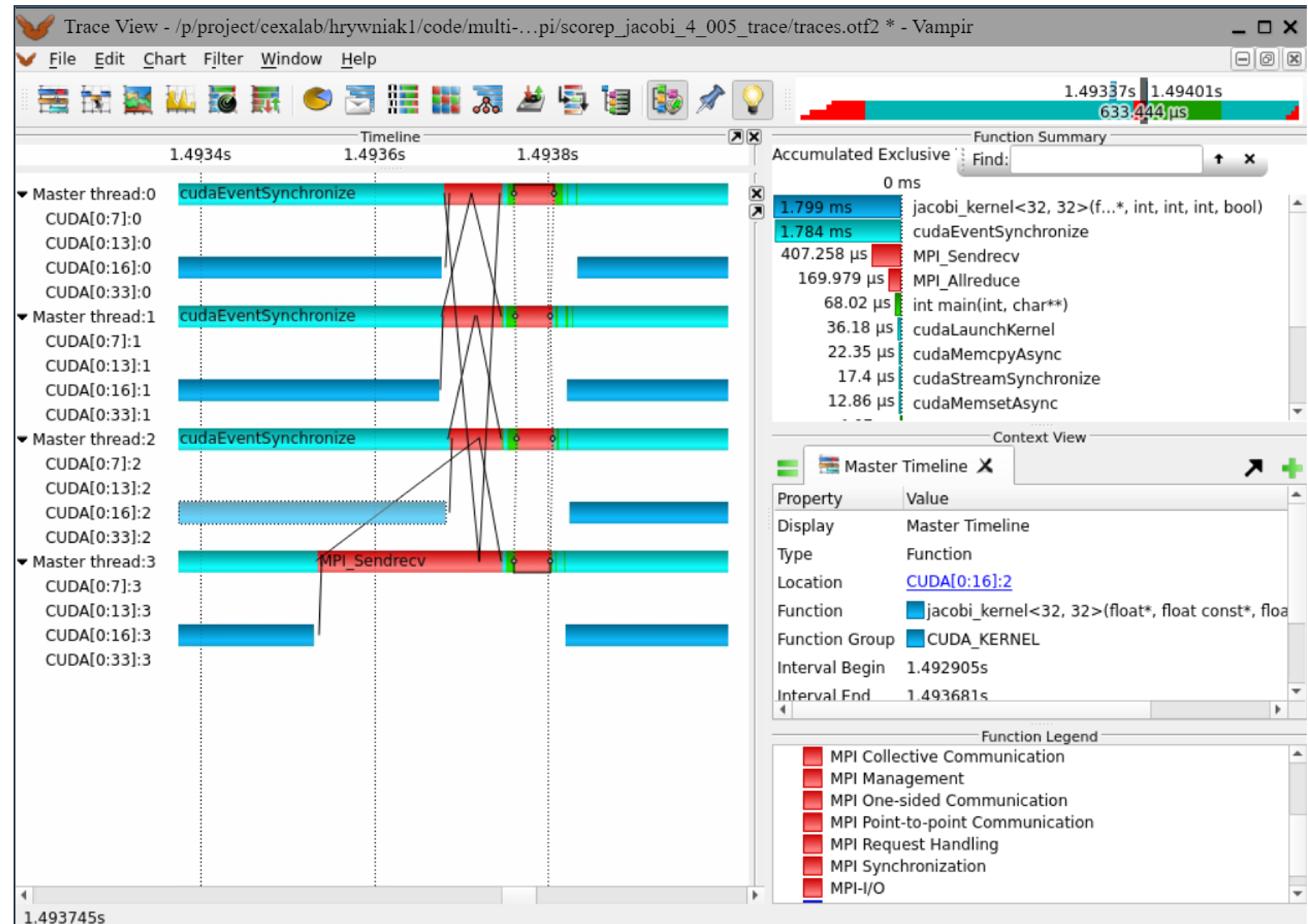
- Breakdown of different metrics across functions and processes
- Left-to-right: Selection influences breakdown
- Expanding changes inclusive/exclusive
- Example analysis:
  - Detect computational imbalance
- <https://scalasca.org/>





# VAMPIR TRACE

- Analyze multi-process patterns
- What you can see in screenshot
  - Main timeline
  - Function summary
- Example analysis: Pinpoint MPI message relationships
  - e.g. late sender issues
- <https://vampir.eu/>



# SUMMARY

- Looked at a wide selection of different tools
  - compute-sanitizer
  - cuda-gdb
  - Nsight-Systems
  - Score-P: Scalasca, Vampir, ...
  - and don't forget compiler flags and checks
- Correctness is paramount, but so is optimal resource usage
- Pick right tool for the job - and take the time to learn it thoroughly
  - Do not trust your gut when analyzing performance, easy to be misled
  - How to adapt serial (or small-scale) tooling to highly distributed applications
- Meant as guideline, not gospel
  - Especially performance issues often require creativity to solve
- Workflow is equally important



# FURTHER MATERIAL

- GTC on-demand talks
  - [What, Where, and Why? Use CUDA Developer Tools to Detect, Locate, and Explain Bugs and Bottlenecks \(s41493, GTC 2022\)](#)
  - [Tuning GPU Network and Memory Usage in Apache Spark \(s31566, GTC 2022\)](#)
- Documentation for [cuda-gdb](#), [compute-sanitizer](#) and [Nsight Systems](#)
- GTC labs from Nsight teams: <https://github.com/NVIDIA/nsight-training>
- GPU bootcamp material, e.g., [https://github.com/gpuhackathons-org/gpubootcamp/tree/master/hpc/multi\\_gpu\\_nways](https://github.com/gpuhackathons-org/gpubootcamp/tree/master/hpc/multi_gpu_nways)



