

robot_interfaces::Loggable

```
classDiagram
    class Loggable["robot_interfaces::Loggable"]
    class NJoint["robot_interfaces::NJoint"]
    class Observation["RobotTypes< N >::Observation"]
    NJoint --|> Loggable
    Observation --|> Loggable
```

robot_interfaces::NJoint
RobotTypes< N >::Observation