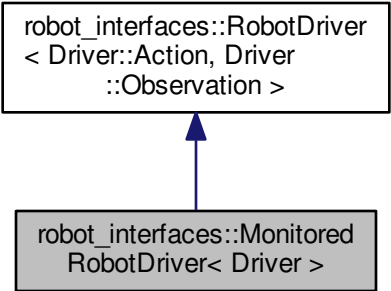


```
robot_interfaces::RobotDriver  
< Driver::Action, Driver  
  ::Observation >
```



```
robot_interfaces::Monitored  
RobotDriver< Driver >
```