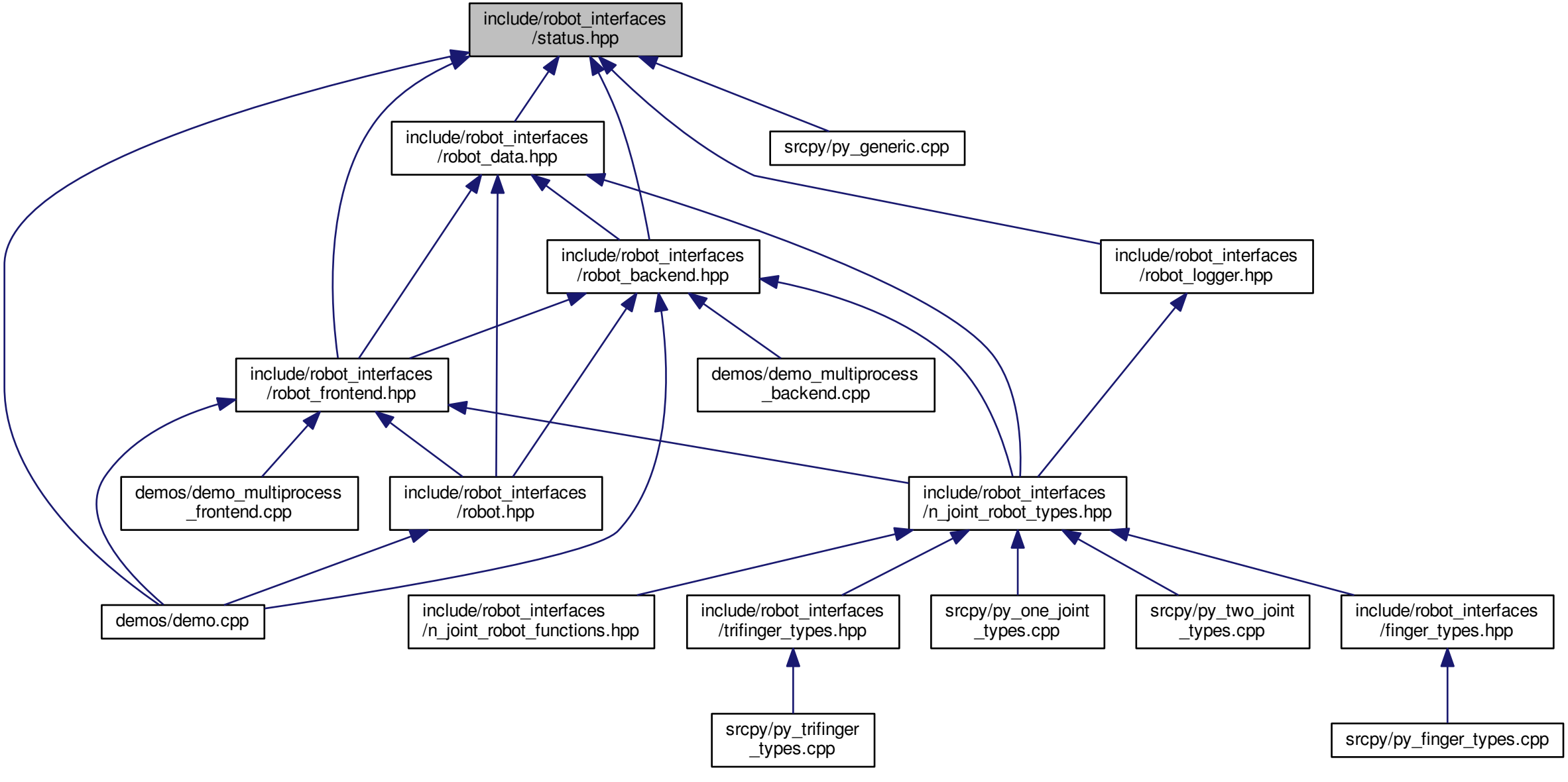
include/robot_interfaces/status.hpp
include/robot_interfaces/robot_data.hpp
srcpy/py_generic.cpp
include/robot_interfaces/robot_backend.hpp
include/robot_interfaces/robot_logger.hpp
include/robot_interfaces/robot_frontend.hpp
demos/demo_multiprocess_backend.cpp
demos/demo_multiprocess_frontend.cpp
include/robot_interfaces/robot.hpp
include/robot_interfaces/n_joint_robot_types.hpp
demos/demo.cpp
include/robot_interfaces/n_joint_robot_functions.hpp
include/robot_interfaces/trifinger_types.hpp
srcpy/py_one_joint_types.cpp
srcpy/py_two_joint_types.cpp
include/robot_interfaces/finger_types.hpp
srcpy/py_trifinger_types.cpp
srcpy/py_finger_types.cpp