

```
robot_interfaces::RobotDriver  
< robot_interfaces::NJointRobotTypes  
< N_JOINTS >::Action, robot_interfaces  
::NJointRobotTypes< N_JOINTS >::Observation >
```

```
blmc_robots::NJointBlmcRobot  
Driver< N_JOINTS, N_MOTOR  
_BOARDS >
```

