

The error vector dynamic matrix

$$\text{Dynamic Matrix : } \mathbf{J}_{\delta\theta}^{\mathbf{R} \oplus \delta\theta} = \begin{cases} \mathbf{J}_r(\delta\theta) & \text{for } \mathbf{R} \\ \frac{1}{2}\Xi(\delta\theta) & \text{for } q \end{cases}$$

