

* Title : Binary Search Trees

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* Section : 2

* Assignment : 2

* Description : Questions 1 & 3

Question 1 – 15 points

A) [5 points] What are the preorder, inorder, and postorder traversals of the binary tree below:

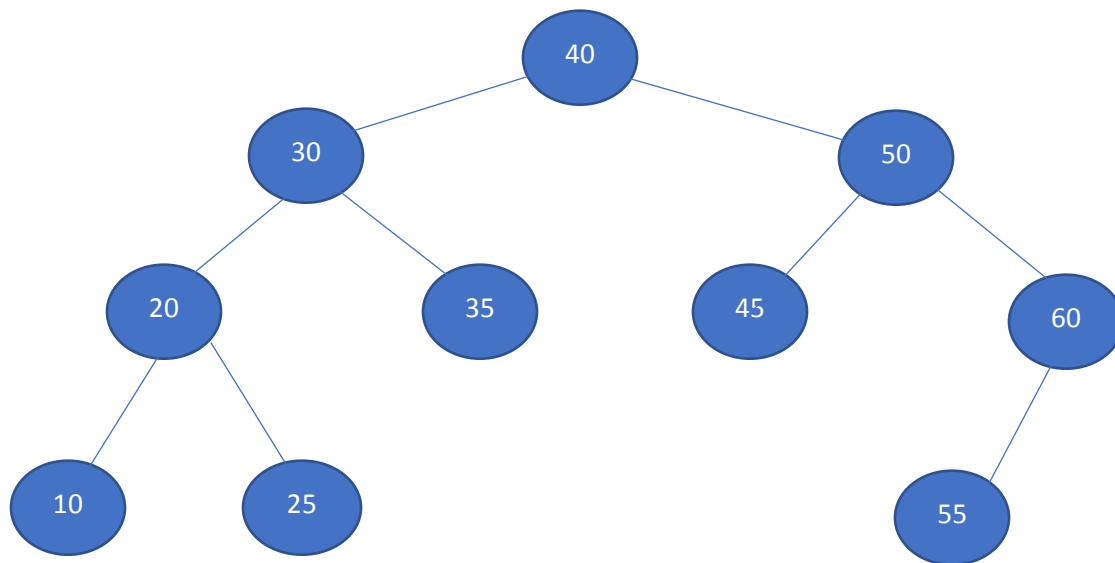
Preorder: RGLAOHITM

Inorder: ALGORITHM

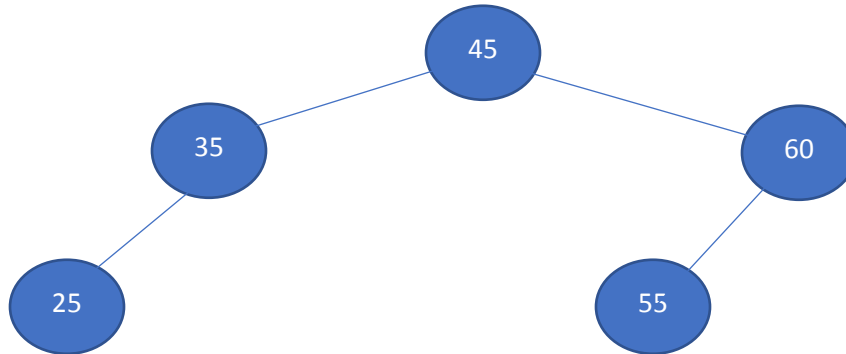
Postorder: ALOGTIMHR

B) [5 points] Insert 40, 50, 45, 30, 60, 55, 20, 35, 10, 25 to an empty Binary Search Tree. Then delete 10, 40, 50, 20, 30.

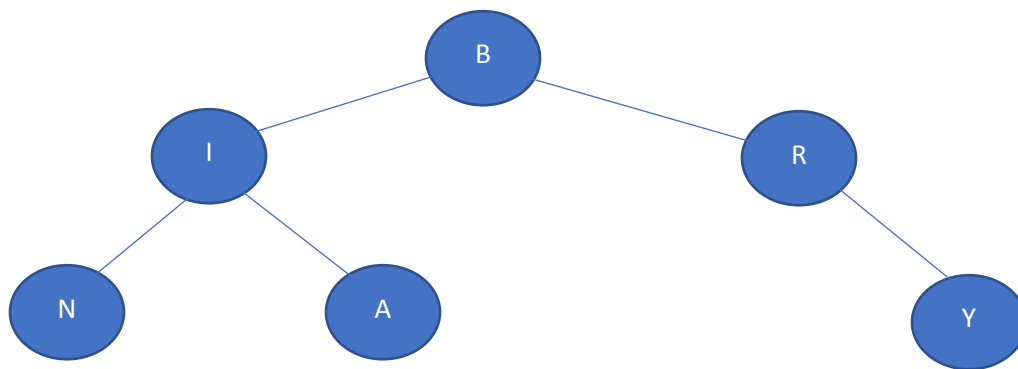
After all insertions: 40, 50, 45, 30, 60, 55, 20, 35, 10, 25



After all deletions: 10, 40, 50, 20, 30.

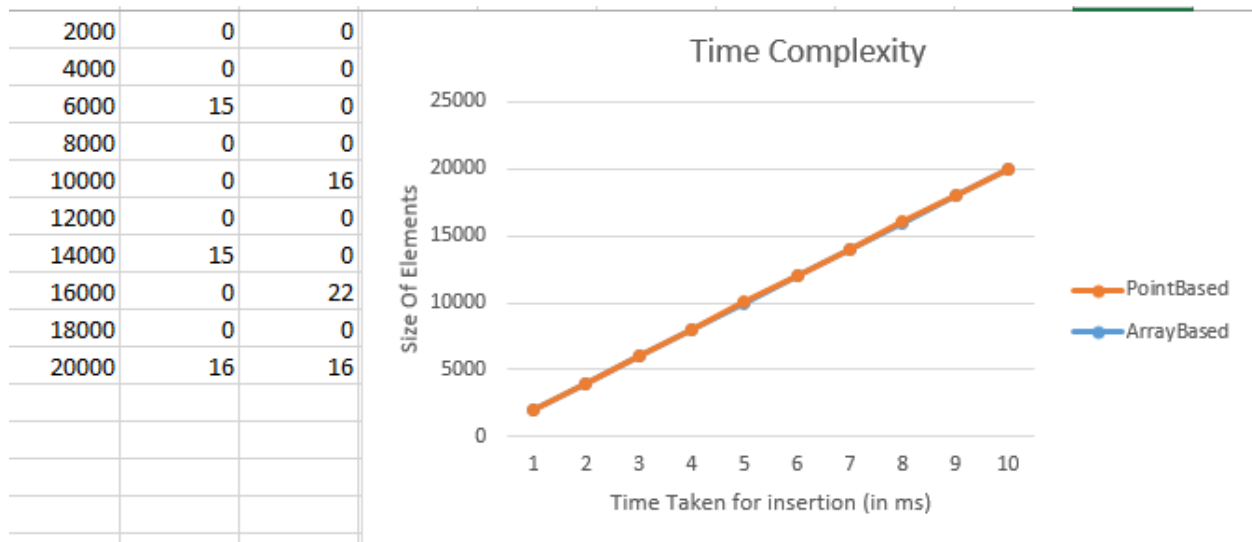


(c) [5 points] A binary tree has a pre-order traversal of B, I, N, A, R, Y and postorder traversal of N, A, I, Y, R, B. What is its inorder traversal? Reconstruct the tree from those traversals and draw it.

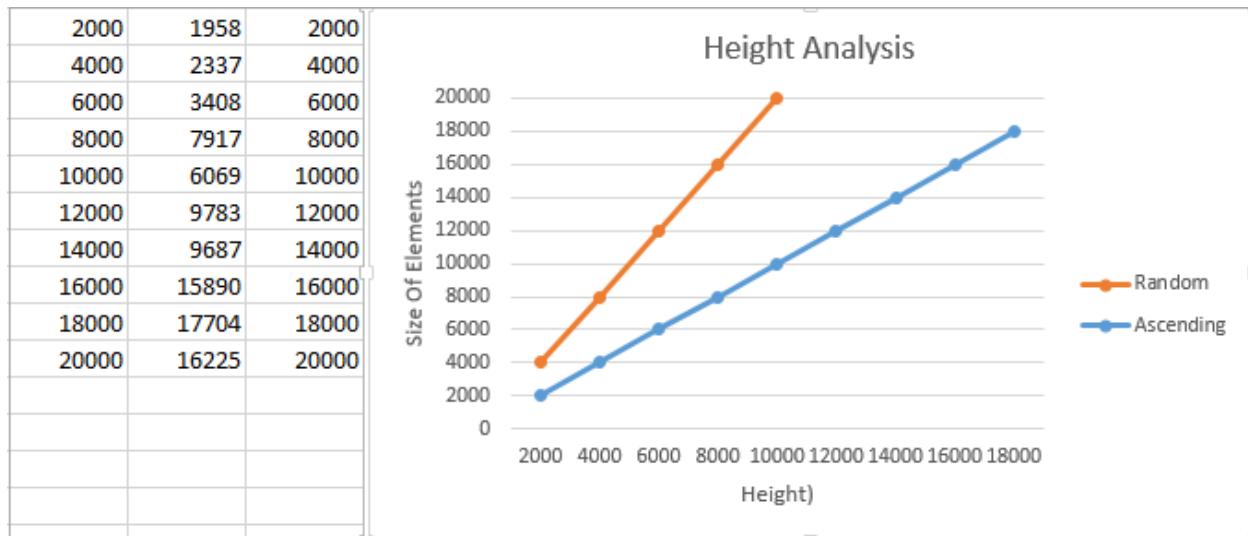


Inorder Traversal: NIABRY

Question 3 – 15 points



Although invisible, the two graphs are on top of each other as they are hardly any different in insertion time complexity. To conclude my results are very accurate when compared to the real ones. Theoretical and practical results are almost the same. The difference in speed of the implementation is more or less the same when it comes to insertion however the Array is a little faster than pointers. Also the pointer based implementation takes up a lot of space. But array isn't a good choice for this because of the size problem where you have to keep changing it. So this reason makes the pointer based linked list a better choice for implementing binary search tree.



For this the average height for ascending random integers seemed to be nearly $n/2$ which we can break down to simply $O(N)$. In the ascending case, it is the worst possible thing that could happen for Bst insertions and all nodes will be found on the right side leaving us with a linear data and a height as the same size as the whole array. In order to make sure the worst case doesn't happen we should try to keep balanced trees. So that insertion and other traversal processes don't take as long as $O(N)$