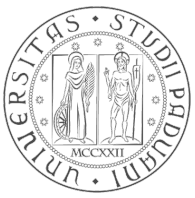

UNIVERSITÀ DEGLI STUDI DI PADOVA

SCHOOL OF ENGINEERING
DEPARTMENT OF INFORMATION ENGINEERING
SECOND CYCLE DEGREE IN AUTOMATION ENGINEERING

MASTER THESIS

LOCAL PATH PLANNING WITH MOVING OBSTACLE AVOIDANCE BASED ON ADAPTIVE MPC IN ATLASCAR2

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