



UNIVERSITÀ DEGLI STUDI DI PADOVA

SCHOOL OF ENGINEERING

DEPARTMENT OF INFORMATION ENGINEERING

SECOND CYCLE DEGREE IN AUTOMATION ENGINEERING

MASTER THESIS

LOCAL PATH PLANNING WITH
MOVING OBSTACLE AVOIDANCE
BASED ON ADAPTIVE MPC IN ATLASCAR2

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Contents

Contents	i
List of Figures	iii
List of Tables	v
1 Introduction	1
1.1 ATLAS Project	1
1.2 Context of the Problem and Motivation	1
1.3 Proposed Approach	1
1.4 Thesis Outline and Contributions	1
2 Literature Review	3
3 Model Predictive Control	5
4 Moving Obstacle Avoidance	7
4.1 Problem Formulation	7
4.2 Design of Adaptive MPC	7
4.3 Simulations Results	7
5 Lane Following	9
5.1 Problem Formulation	9
5.2 Design of Adaptive MPC	9
5.3 Simulation Results	9
6 Chapter 6	11
Conclusions and Future Work	13
Bibliography	15

List of Figures

List of Tables

Chapter 1

Introduction

ATLAS Project

Context of the Problem and Motivation

Proposed Approach

Thesis Outline and Contributions

Chapter 2

Literature Review

Model Predictive Control

Moving Obstacle Avoidance

Problem Formulation

Design of Adaptive MPC

Simulation Results

Lane Following

Problem Formulation

Design of Adaptive MPC

Simulation Results

Chapter 6

Conclusions and Future Work

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