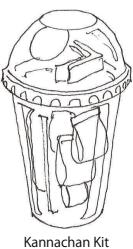


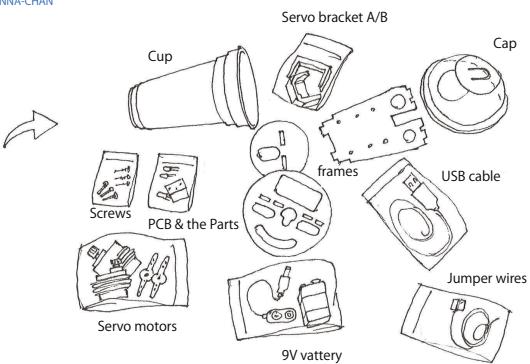
# ファブボット かんなちゃん

FABBOT KANNA-CHAN

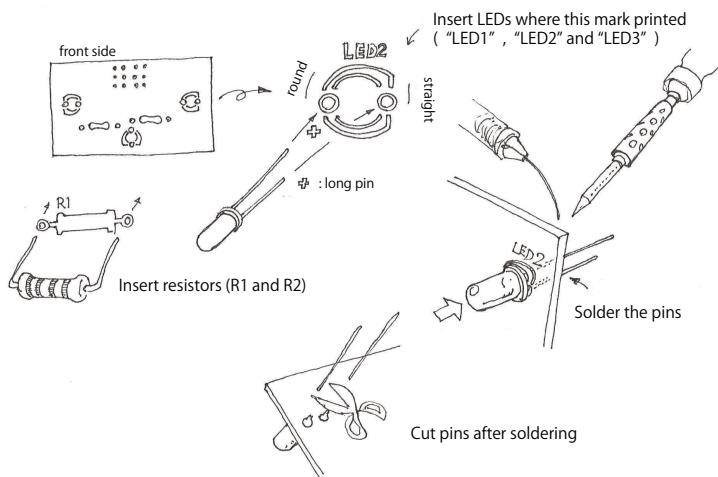
http://fabbot.com/kannachan



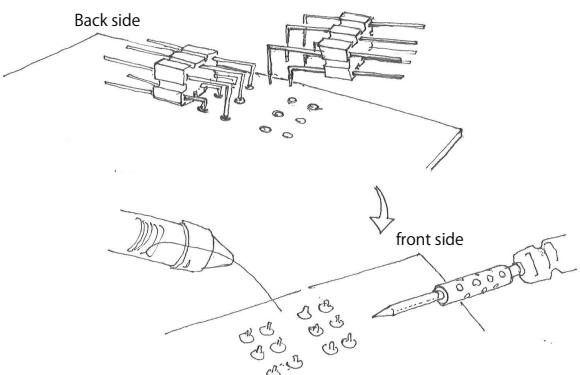
Kannachan Kit



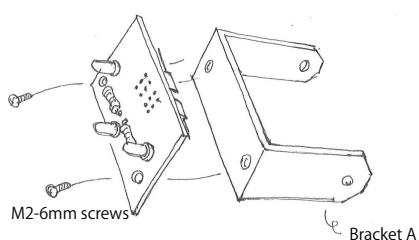
## 1 Solder LEDs and resistors on front side of PCB.



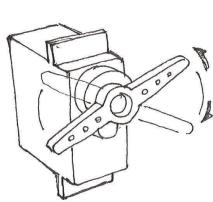
## 2 Solder pinheaders on back side of PCB.



## 3 Attach PCB to Bracket A.



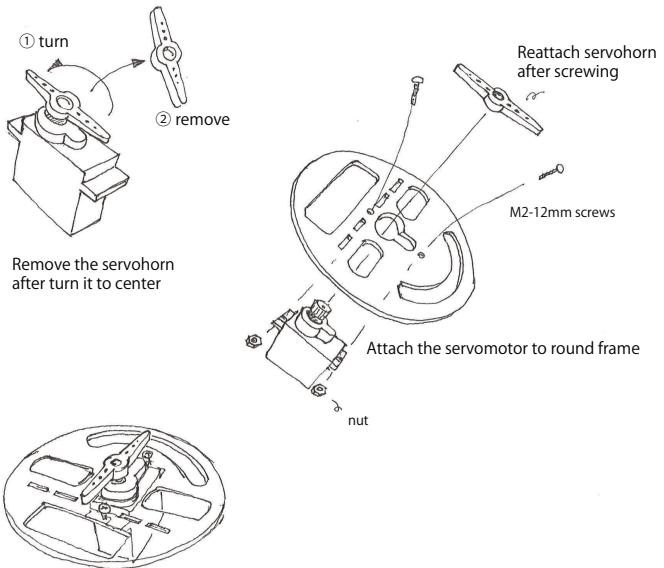
## 4 Adjust the position of Servomotor 1 (lower one).



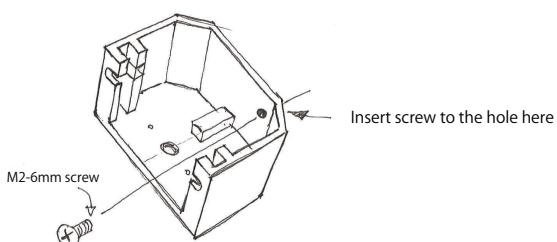
Attach a servohorn to a servomotor and try to turn it

Adjust insert position of servohorn to turn until right angle to both sides

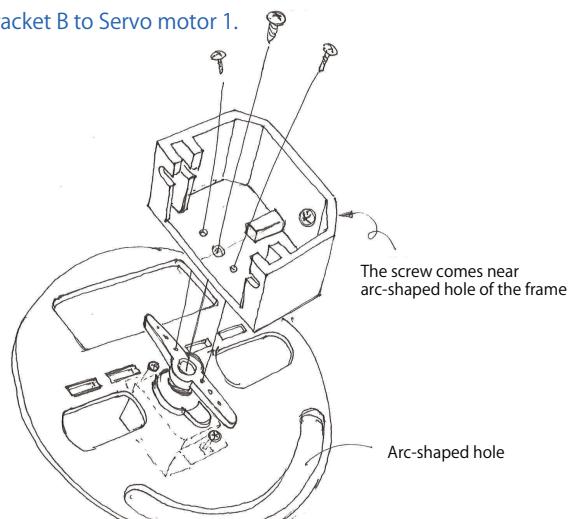
## 5 Attach Servo motor 1 to round frame.



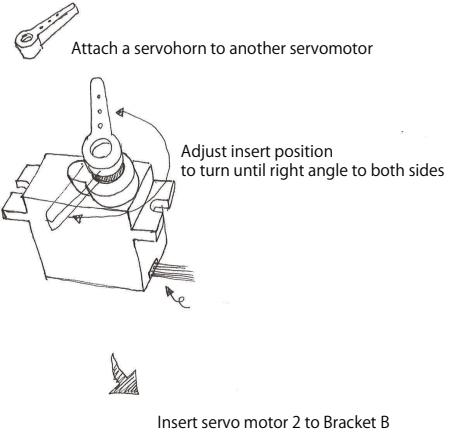
## 6 Prepare Bracket B.



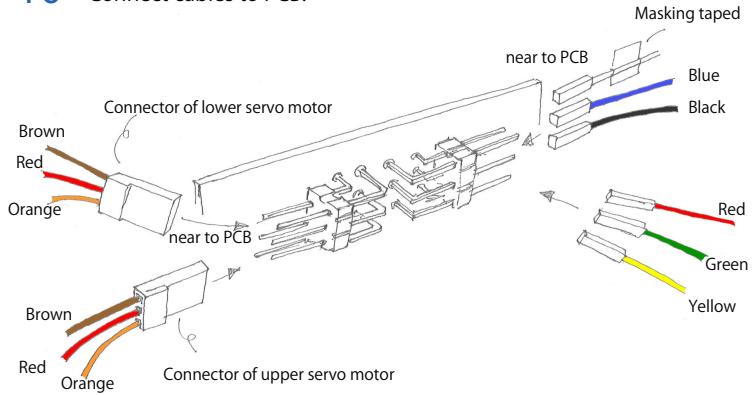
## 7 Attach Bracket B to Servo motor 1.



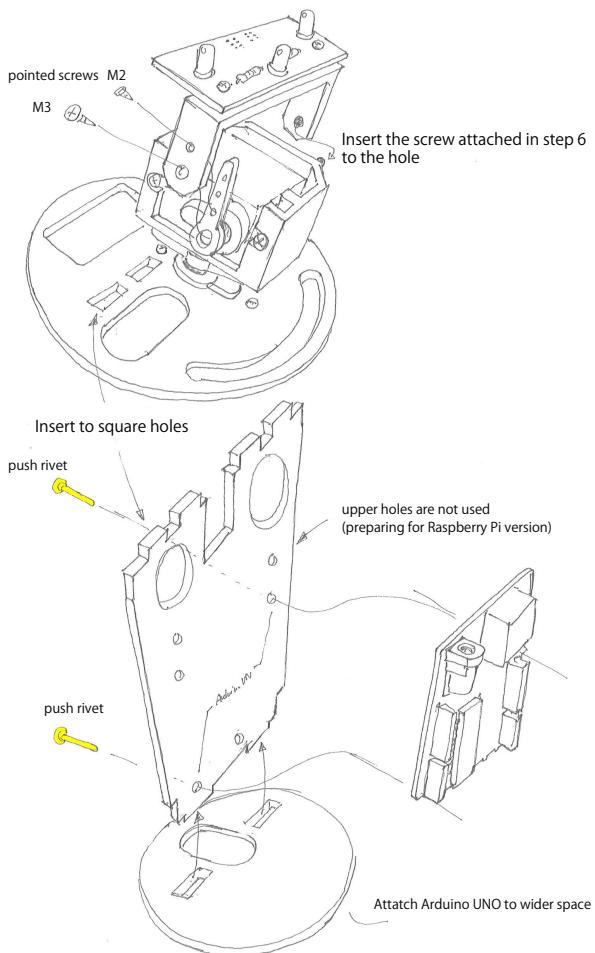
## 8 Adjust Servo motor 2 (upper one).



## 10 Connect cables to PCB.

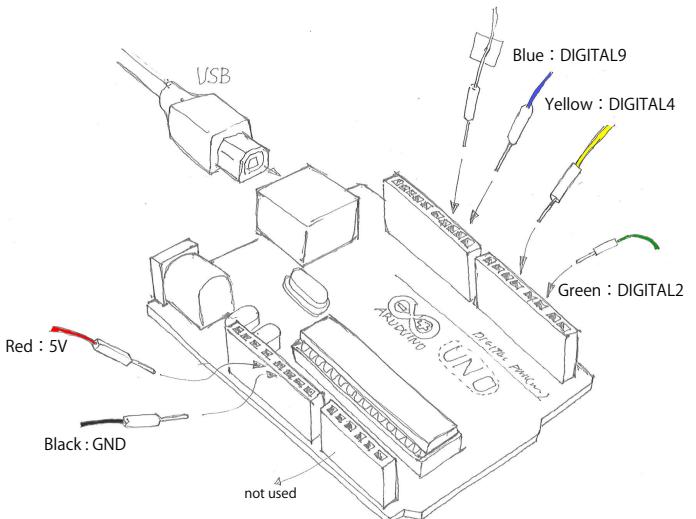


## 9 Assemble face and round frame.



## 11 Connect cables to Arduino.

Masking taped : DIGITAL11



## 12 Insert assembled frames into the cup and pick USB cable out through the hole of cap

