

sketching → randomized LA

nonparametric estimation → matrix  $\Rightarrow$  function

variance-reduced → specific choice of sketching

## 1. sketching

### 1.1 matrix sketching

suppose matrix  $B \in \mathbb{R}^{n_1 \times n_2}$  low-rank

① construct sketch  $B' = BS$ ,  $S \in \mathbb{R}^{n_2 \times k}$

$k \ll n_1, n_2$   
sketching matrix

$$\text{Range}(BS) = \text{Range}(B)$$

② orthogonalize

$$[Q, R] = qr(B') / [U, \Sigma, V] = svd(B)$$

$$\tilde{B} = Q Q^T B / \tilde{B} = U U^T B$$

$$\|\tilde{B} - B\| \rightarrow \text{small}$$

$$P = Q Q^T / U U^T$$

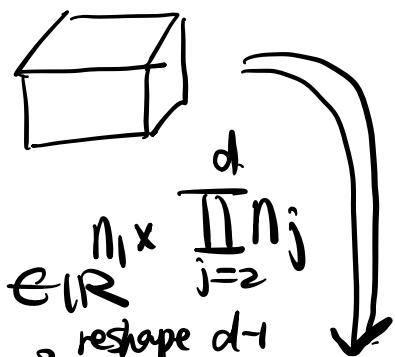
projection

How to get  $P$   
for continuous  
function?

## 1.2 tensor sketching

$$B \in \mathbb{R}_{\text{index}(i_1, \dots, i_d)}^{n_1 \times n_2 \times \dots \times n_d}$$

→ low-rank.



$$\text{Step 1: } B^{(1)} = B[i_1; i_2, i_3, \dots, i_d] \in \mathbb{R}^{n_1 \times \prod_{j=2}^d n_j}$$

use matrix sketching for  $B^{(1)}$

$$S_1 \in \mathbb{R}^{\prod_{j=2}^d n_j \times k_1}$$

$$\text{low-rank } Q_1 / U_1 \in \mathbb{R}^{n_1 \times k_1}$$

$$P_1 = Q_1 Q_1^T / P_1 = U_1 U_1^T \rightarrow \text{projection}$$

Step 2: repeat the procedure,  $\forall j = 1, \dots, d$

$$B^{(j)} = B[i_j; i_1, i_2, \dots, i_{j-1}, i_{j+1}, \dots, i_d]$$

permute

$$\stackrel{\text{reshape}}{=} B[i_j; i_1, i_2, \dots, i_{j-1}, i_{j+1}, \dots, i_d]$$

$$\in \mathbb{R}^{n_j \times \prod_{l \neq j} i_l}$$

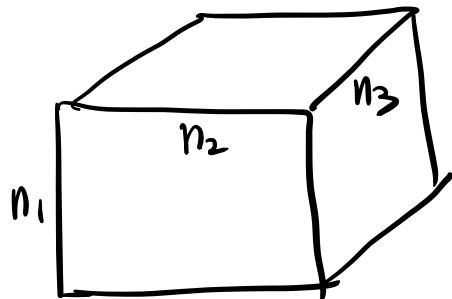
use matrix sketching for  $B^{(j)}$  with  $S_j$

$$\text{get } Q_j / U_j, \text{ projection } P_j = Q_j Q_j^T / U_j U_j^T$$

$$\text{Step 3: } \tilde{B} = B \times_1 P_1 \times_2 P_2 \times \dots \times_d P_d$$

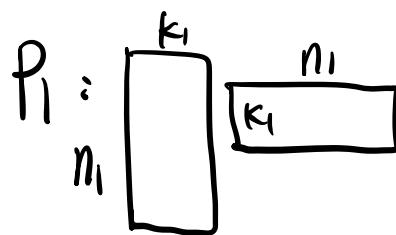
$$(B \times_1 P_1)(i_1, \dots, i_d) = \sum_j B(j, i_2, \dots, i_d) P_1(j, i_1)$$

$$B \in \mathbb{R}^{n_1 \times n_2 \times n_3}$$

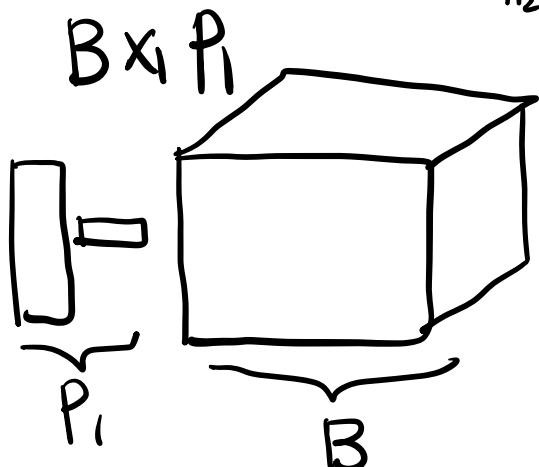
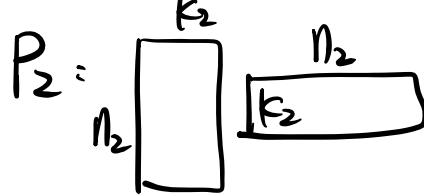


$$P_1 \in \mathbb{R}^{n_1 \times n_1}$$

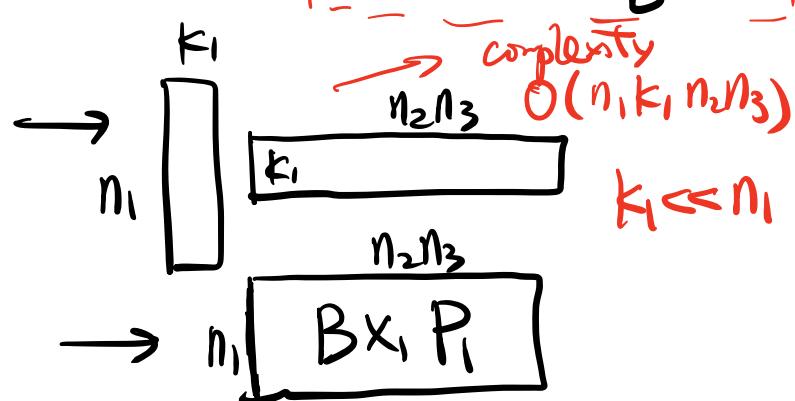
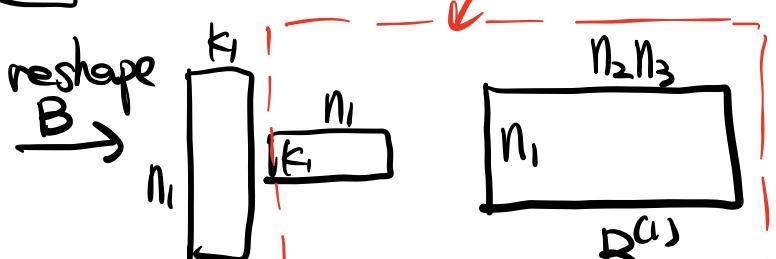
rank -  $k_1$

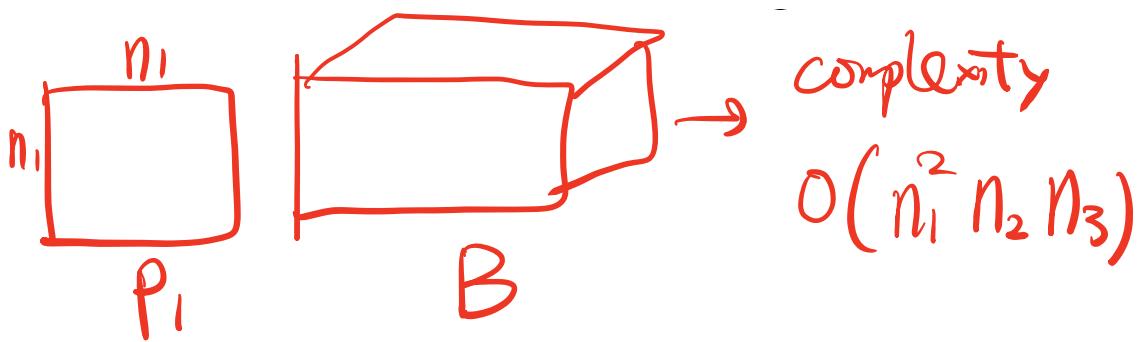


$$P_2 \in \mathbb{R}^{n_2 \times n_2}$$

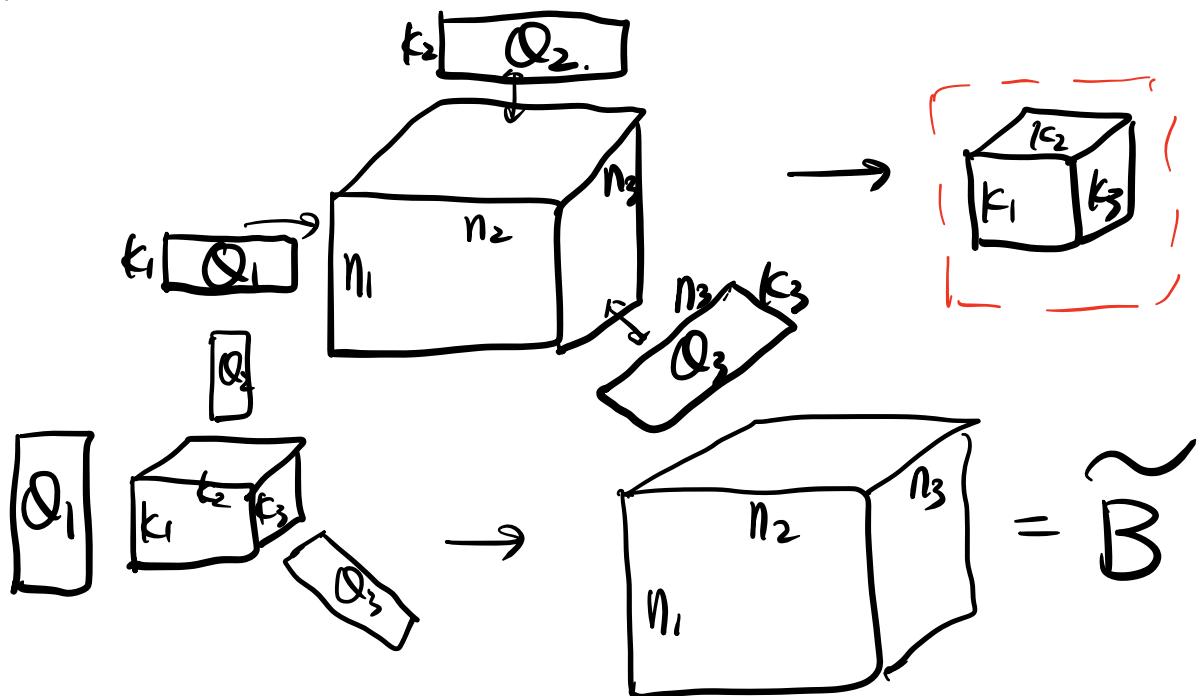


$P_3$ : complexity  $O(k_1 n_1 n_2 n_3)$





$$B \times_1 P_1 \times_2 P_2 \times_3 P_3$$



$B \in \mathbb{R}^{n \times n \times \dots \times n}$

$O(n^d)$

$k \ll n$

(low-rank approximation)  $\cdot O(dnk + k^d)$

## 2. Nonparametric estimation

### 2.1 Function representation

Basis

$f(x), x \in \mathbb{R}^1 \quad \{\phi_i(x)\}$  orthonormal basis functions

Result:

$$f(x) \approx \sum_{i=1}^m a_i \phi_i(x) \quad \text{if } m \rightarrow \infty,$$

$$\|f - \sum a_i \phi_i\| \rightarrow 0$$

$$a_i = \int f(x) \phi_i(x) dx \quad \text{Ex: } \{\phi_i\} \text{ : Legendre polynomial Fourier basis}$$

$f(x_1, x_2)$ , 2-dim function  $\{\phi_{i1}(x_1)\}, \{\phi_{i2}(x_2)\}$ .

$$f(x_1, x_2) \approx \sum_{i1, i2=1}^m A_{i1, i2} \phi_{i1}(x_1) \phi_{i2}(x_2).$$

$A \in \mathbb{R}^{m \times m}$  coefficient matrix (sketching  
↓  
low-rank approx)

$$\underline{A_{i1, i2}} = \iint f(x_1, x_2) \phi_{i1}(x_1) \phi_{i2}(x_2) dx_1 dx_2$$

$f(x_1, \dots, x_d)$  d-dim function  $\{\phi_{i1}(x_1)\}$   
 $\{\phi_{id}(x_d)\}$ .

$$f(x_1, \dots, x_d) \approx \sum_{i_1, \dots, i_d=1}^m A_{i_1, i_2, \dots, i_d} \phi_{i_1}(x_1) \cdots \phi_{i_d}(x_d)$$

$A \in \mathbb{R}^{m \times m \times \dots \times m}$   $\underbrace{m^d}_{\text{d-dim tensor}}$

$$A_{i_1, \dots, i_d} = \int \dots \int f(x_1, \dots, x_d) \phi_{i_1}(x_1) \cdots \phi_{i_d}(x_d) dx_1 \cdots dx_d$$

2.2 Density Estimation.  $f \xrightarrow{\text{prob density function}} p$  (pdf)

Given  $\{x_i\}_{i=1}^N$  i.i.d.  $p^*$ ,  $N$ : sample-size

Empirical density  $\hat{p}(x) = \frac{1}{N} \sum_{i=1}^N \delta_{x_i}(x)$   
 $\hat{p} \rightarrow$  a random function based on  $x_i$

$$\int \delta_{x_i}(x) dx = 1$$

Task: use some methods to

get approximation of  $p^*$  based on  $\hat{p}$

2.3 <sup>method</sup> kernel density estimation (KDE):

$$\hat{P}_h(x) = \frac{1}{N} \sum_{i=1}^N k_h(x - x_i) \leftarrow 1 \text{ d.}$$

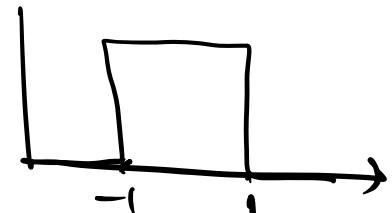
$k_h(\cdot) = \frac{1}{h} k\left(\frac{\cdot}{h}\right)$ ,  $k(\cdot)$  - kernel function.

$h$  - bandwidth.

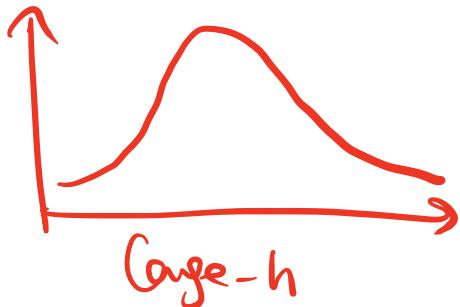
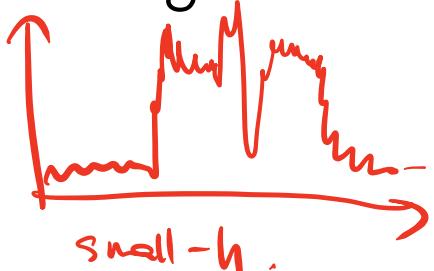
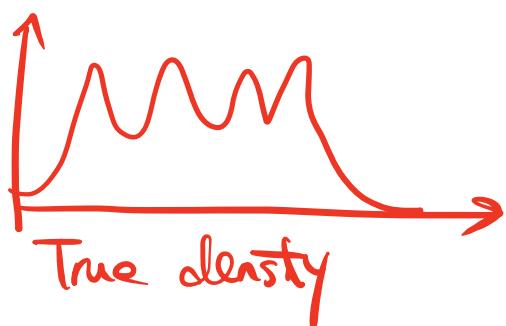
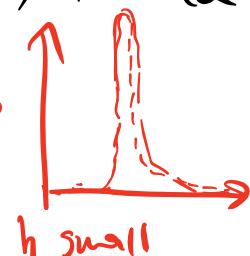
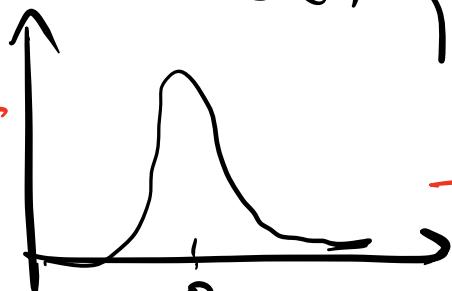
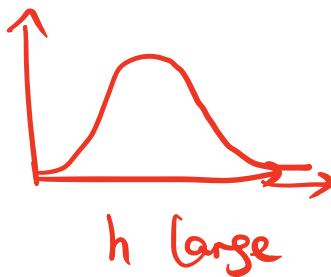
Ex: Step function  $k(x) = \frac{1}{2}I(x)$

Gaussian kernel:

$$k(x) = \frac{1}{\sqrt{2\pi}} \exp\left(-\frac{x^2}{2}\right)$$



$$I(x) = \begin{cases} 1, & x \in [-1, 1] \\ 0, & \text{else} \end{cases}$$



high-d

$$\hat{P}_h(x) = \frac{1}{N} \sum_{i=1}^N \frac{1}{h^a} k\left(\frac{\|x - x_i\|}{h}\right)$$

Error: bias error / variance error.

$$\| \mathbb{E}_{\underset{x}{\sim}} \hat{P}_h - p^* \|$$

$$\mathbb{E} \| \hat{P}_h - \mathbb{E} \hat{P}_h \|^2$$

suppose  $p^*$  belongs to Holder class.

$$\Sigma(\beta, L) = \left\{ g : \left| D^S g(x) - D^S g(y) \right| \leq L \|x-y\|, \text{ for all } S \text{ s.t. } |S| \leq \beta-1, \forall x, y \right\}$$

$$D^S = \frac{\partial^{S_1 + \dots + S_d}}{\partial x_1^{S_1} \dots \partial x_d^{S_d}}$$

$$\mathbb{E} \| \hat{P}_h - p^* \|^2 \leq \text{bias} + \text{Variance} \leq C h^\beta + \frac{C}{N h^d}$$

$$h \approx N^{-\frac{1}{2\beta+d}}$$

$$d \nearrow, \frac{2\beta}{2\beta+d} \rightarrow 0$$

curse of dimensionality

Tensor:  $\underline{n}^d$  < low-rank.

$$\text{keep error} \leq \varepsilon \quad \text{tolerance} \quad \left( \frac{1}{N} \right)^{\frac{2\beta}{2\beta+d}} \leq \varepsilon$$

$$\frac{1}{\varepsilon} \leq N^{\frac{2\beta}{2\beta+d}}$$

$$N \geq \left( \frac{1}{\varepsilon} \right)^{(1+\frac{d}{2\beta})}$$

$d \nearrow, N \rightarrow \exp \text{ in } d$ , for fixed  $\varepsilon$ .

3. Assumption 1:  $x \in \Omega_1 \subset \mathbb{R}^{d_1}, y \in \Omega_2 \subset \mathbb{R}^{d_2}$

(Let  $A^*(x, y) = \Omega_1 \times \Omega_2 \rightarrow \mathbb{R}$  be a generic population function with  $\|A^*\|_{L_2(\Omega_1 \times \Omega_2)} < \infty$ .

Assume  $A^*(x, y) = \sum_{p=1}^r g_p \Phi_p^*(x) \Psi_p^*(y)$

$r$  is const,  $g_1 \geq g_2 \geq \dots \geq g_r$

$\{\Phi_p^*(x)\}_{p=1}^r, \{\Psi_p^*(y)\}_{p=1}^r$  orthonormal function.

Ex: Mean-field model

$$P^*(x, y) = P_1^*(x) \cdot P_2^*(y)$$

$$P^*(z_1, \dots, z_d) = P_1^*(z_1) P_2^*(z_2) \cdot \dots \cdot P_d^*(z_d)$$

Extension: mixed mean-field

$$P^*(z_1, \dots, z_d) = \sum_{p=1}^r T_p P_{p,1}^*(z_1) P_{p,2}^*(z_2) \cdots P_{p,d}^*(z_d)$$

$$\text{Span}\{\Phi_p^*(x)\} = \text{Span}\{P_{p,1}^*(z_1)\}, \text{Span}\{\Psi_p^*(y)\} \\ = \text{Span}\{P_{p,2}^*(z_2) \cdots P_{p,d}^*(z_d)\}$$

Rank at most  $r$

How to get P? projection. Ex: Legendre poly  
sketching basis.

sketching: matrix  $S \rightarrow$  function space  $\{W_j(y)\}_{j=1}^{\dim(L)}$

$B \in S$  matrix multi  $\int_{\Omega_2} \hat{A}(x, y) W_j(y) dy$   $\int_{\Omega_1} \int_{\Omega_2}$   $\dim(L)$

space  $L = \text{Span}\{W_j(y)\}_{j=1}^{\dim(L)}$

① sketching stage:

a function solely depends on  $x$

$$[BS(:, 1), BS(:, 2), \dots, BS(:, k)]$$

② Estimation Stage: space  $M = \text{Span}\{V_{\mu}(x)\}_{\mu=1}^{\dim(M)}$

$$\tilde{f}_j(x) = \underset{f \in M}{\arg \min} \left\| \int_{\Omega_2} \hat{A}(x, y) W_j(y) dy - f(x) \right\|_{L_2(\Omega_1)}^2$$

$$\tilde{f}_j(x) = \sum_{\mu=1}^{\dim(M)} B_{\mu, j} V_{\mu}(x)$$

coefficient matrix  $B \in \mathbb{R}^{\dim(M) \times \dim(L)}$

$$B_{\mu, j} = \left\langle \int_{\Omega_2} \hat{A}(x, y) W_j(y) dy, V_{\mu}(x) \right\rangle$$

$$= \iint \hat{A}(x, y) V_{\mu}(x) W_j(y) dx dy$$

③ Orthogonalization do QR / SVD  $\rightarrow \underline{\underline{B}}$

$$[U, \Sigma, V] = \text{svd}(B)$$

$R^{\dim(M) \times r}$  (truncate at rank- $r$ ).

$$\hat{\Phi}_p(x) = \sum_{\mu=1}^{\dim(M)} V_{\mu}(x) U_{\mu,p}, \quad p=1, \dots, r$$

$$\text{projection operator } P_x(x, x') = \sum_{p=1}^r \hat{\Phi}_p(x) \hat{\Phi}_p(x')$$

$$\begin{matrix} UU^T \\ \Downarrow \\ U(x) U^T(x') \end{matrix}$$

Algorithm:

compute coefficient  $B$ :

$$B = \frac{1}{N} \sum_{i=1}^N V_{\mu}(x_i) W_{\mu}(y_i).$$

$$\text{when } \hat{A}(x, y) = \frac{1}{N} \sum_{i=1}^N \delta(x_i, y_i)(x, y)$$

Function estimation. (2-d function).

$$\boxed{\{ \hat{\Phi}_p(x) \}_{p=1}^r}$$

$$\dim(L_2) \rightarrow \frac{1}{G_r}.$$

$$\dim(M_2) \rightarrow$$

$$\text{sketching space } \{ W_j(x) \}_{j=1}^{\dim(L_2)}$$

$$\hat{A}(x, y) \rightarrow$$

$$\text{estimation space } \{ V_{\mu}(y) \}_{\mu=1}^{\dim(M_2)}$$

②

Algorithm

$$\boxed{\{ \hat{\Phi}_p(y) \}_{p=1}^r}$$

$\hat{A}$  is matrix

① projection: row  $U_1 U_1^T \hat{A}$

② projection: column  $\hat{A} U_2 U_2^T$

③ Together  $\hat{A} = U_1 U_1^T \hat{A} U_2 U_2^T$

③ coefficient core.

$$G_{P_1, P_2} = \iint \hat{A}(x, y) \hat{\Phi}_{P_1}^{(x)}(x) \hat{\Phi}_{P_2}^{(y)}(y) dx dy$$

$$\underset{EIR}{=} \underset{\substack{rxr \\ \text{density}}}{=} \frac{1}{N} \sum_{i=1}^N \hat{\Phi}_{P_1}^{(x)}(x_i) \hat{\Phi}_{P_2}^{(y)}(y_i)$$

Represent function

$$\hat{A}(x, y) = \sum_{P_1, P_2=1}^r G_{P_1, P_2} \hat{\Phi}_{P_1}^{(x)}(x) \hat{\Phi}_{P_2}^{(y)}(y).$$

$$\tilde{A} = \hat{A} \times_1 P_1 \times_2 P_2$$

Statistical analysis :  $x \in \mathbb{R}^{d_1}, y \in \mathbb{R}^{d_2}$

Assumption 2: Let  $M, L$  with  $\dim(M) = m^{d_1}$ ,  
 $\dim(L) = l^{d_2}$

$$\|A^* - A^* x \times P_M x^* P_L\|_{L_2}^2 = O(m^{-2\alpha} + l^{-2\alpha})$$

$\alpha$ : parameter of space (containing  $A^*$ )

Ex:  $A^*$  in Sobolev space: up to  $\alpha$  derivative is bounded in  $L_2^{\text{norm}}$

$$\|A^*\|_{W_2^\alpha}^2 = \left( \sum_{|S|=0}^{\alpha} \|D^S A^*\|_2^2 \right) < \infty \quad D^S = \frac{\partial^{S_1+...+S_d}}{\partial x_1^{S_1} \cdots \partial x_d^{S_d}}$$

Intuition: basis in  $M$ : polynomial:  $(S_1 + \dots + S_d = |S|) \times \mathbb{R}^d$

$\dim(M)$ : how many orthogonal polynomials  
 $\rightarrow$  degree of polynomial

to each dimensional order of polynomial ↑

$$\dim(M) = m^{d_1}, x \in \mathbb{R}^{d_1} \quad \text{Error } \downarrow$$

Ex:  $\alpha=2$

$$W_2^2, f \in W_2^2, \|f\|_{L_2} < \infty, \|f'\|_{L_2} < \infty, \\ \|f''\|_{L_2} < \infty \text{ for } \forall x$$

Assumption 3: for any test function  $u(x, y)$ ,

$$\begin{aligned} \textcircled{1} \quad & \underset{\text{samples}}{\mathbb{E}} \langle \hat{A}, u \rangle = \langle A^*, u \rangle \quad \textcircled{2} \quad \sup \text{Var}[\langle \hat{A}, u \rangle] \\ & \text{1st moment} \quad \|u\|_{L_2} \leq 1 \quad = O\left(\frac{1}{N}\right) \\ \left\{ \begin{array}{l} \langle \hat{A}, u \rangle = \iint \hat{A}(x, y) u(x, y) dx dy \\ \langle A^*, u \rangle = \iint A^*(x, y) u(x, y) dx dy \end{array} \right. & \begin{array}{l} \text{sample-size} \\ \text{2nd moment.} \end{array} \end{aligned}$$

$$\hat{A} = \frac{1}{N} \sum \delta_i, \quad \textcircled{3}: \sup |A^*(x, y)| < \infty$$

Theorem 1: suppose above assumptions hold,

$$\|\tilde{A} - A^*\|_{L_2}^2 = O\left(\frac{1}{N^{\frac{1}{2d+dl_1}}} + \frac{1}{N^{\frac{1}{2d+dl_2}}}\right) \quad \begin{array}{l} x \in \mathbb{R}^{d_1} \\ y \in \mathbb{R}^{d_2} \end{array}$$

with choice  $m_1 \approx N^{\frac{1}{2d+dl_1}}, m_2 \approx N^{\frac{1}{2d+dl_2}}$

sketching size  $\dim(M_1) \rightarrow$  variable  $x$  variable  $y$ .

$$l_1 = l_2 \approx C \sigma^{-\frac{1}{2}}$$

$\rightarrow$  r-th singular value of  $A^*$

$$\text{KDE: } O\left(N^{\frac{1}{2d+dl_1+dl_2}}\right)$$

bias-variance trade-off.

Remark: slightly improvement for 2-d function.  
huge improvement for high-d function

### 3.3 high-d function estimation

Assumption 4: (modification of low-rank..)

$$f^*(x_1, \dots, x_d) = \sum_{\rho=1}^{r_j} \theta_{j,\rho} \phi_{j,\rho}^*(x_j) \phi_{j,\rho}^*(x_1, \dots, x_{j-1}, x_{j+1}, \dots, x_d)$$

for  $j = 1, \dots, d$

sketching space: num of basis for  $x_j$

$$M_j = \text{span} \left\{ \phi_{j,\mu}(x_j) \right\}_{\mu=1}^m \quad \text{(d-1)}$$

$$L_j = \text{span} \left\{ \phi_{0,1}(x_1) \dots \phi_{0,j-1}(x_{j-1}) \phi_{0,j+1}(x_{j+1}) \dots \phi_{0,d}(x_d) \right\}_{j_1, \dots, j_d=1}^{j_j} \quad \dim(L_j) = j^{d-1}$$

$\left\{ \begin{array}{l} m \text{ could be large} \\ l_j \text{ small} \end{array} \right.$

$l_j \rightarrow$  sketching.

Thm2: (informal) Suppose above assumption holds,

choose  $m \approx N^{\frac{1}{2\alpha+1}}$ ,  $\ell_j = C G_j^{-\frac{1}{\alpha}} r_j$ ,

then

$$\|\tilde{A} - A^*\|_{L_2}^2 = O\left(\frac{1}{N^{\frac{2\alpha}{2\alpha+1}}}\right)$$

Remark1: intuitive:  $M_j \rightarrow x_j \in \mathbb{R}$ .

$d-1$  dimensions are sketched.

$$N^{\frac{1}{2\alpha/(2\alpha+1)}}$$

Remark2: we sketch  $d-1$  dimension

$$\dim(L_j) = l^{d-1}$$

image  $l$  is small when  $A^*$  is good.