

# From Linear Optimization to Transmission Cost Allocation

F. Hofmann. T. Brown

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## Abstract

Maximizing the welfare of all market participants within a power system is a common approach in energy system modelling. It leads to perfectly scheduled operations of generators and ...

## Nomenclature

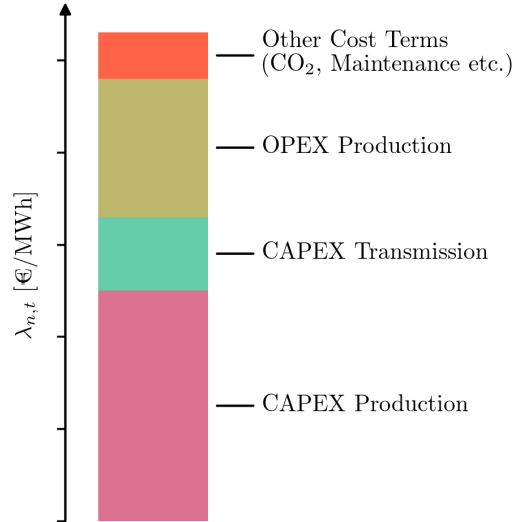
$\lambda_{n,t}$	Locational Market Price at bus $n$ and time step $t$ in €/MW
$d_{n,a,t}$	Electric demand per bus $n$ , demand type $a$ , time step $t$ in MW
$g_{n,s,t}$	Electric generation per bus $n$ , carrier $s$ , time step $t$ in MW
$f_{\ell,t}$	Active power flow on line $\ell$ , time step $t$ in MW
$o_{n,s}$	Operational cost (OPEX) in €/MW
$c_{n,s}$	Capital Expenditure (CAPEX) in €/MW
$c_{\ell}$	CAPEX per transmission line $\ell$ in €/MW
$G_{n,s}$	Generation capacity in MW
$F_{\ell}$	Transmission capacity in MW
$K_{n,\ell}$	Incidence matrix

any consumer  $a$  at bus  $n$ . It is given by the derivative of the total system cost  $\mathcal{TC}$  with respect to the local demand  $d_{n,a,t}$

$$\lambda_{n,t} = \frac{\partial \mathcal{TC}}{\partial d_{n,a,t}} \quad (2)$$

This leads to a nodal pricing where over the span of optimized timesteps  $t$ , the system costs are totally paid back by the consumers

$$\mathcal{TC} = \sum_{n,a,t} \lambda_{n,t} d_{n,a,t} \quad (3)$$



## 1 Economic Context

In long-term operation and investment planning models, the total costs  $\mathcal{TC}$  of a power system include all operational expenditures (OPEX)  $\mathcal{O}$  and capital expenditures (CAPEX)  $\mathcal{C}^G$  and  $\mathcal{C}^F$  for production and transmission respectively, thus

$$\mathcal{TC} = \mathcal{O} + \mathcal{C}^G + \mathcal{C}^F + \text{rest} \quad (1)$$

In a network design with minimal  $\mathcal{TC}$ , the Locational Market Price (LMP) describes the marginal price for an incremental increase of electricity demand  $d_{n,a,t}$  of

Figure 1: Schematic decomposition of the Locational Market Price  $\lambda_{n,t}$ . In power system model with optimal long-term operation and planning, the total system costs  $\mathcal{TC}$  split into different cost terms, *i.e.* OPEX and CAPEX for production and transmission and possibly other expenditures. As  $\mathcal{TC}$  is fully paid by the consumers, each LMP  $\lambda_{n,t}$  can be decomposed into cost terms compensating the different expenditures at timestep  $t$ .

As a direct consequence of Eqs. (1) to (3), the LMP splits into different cost terms assigned to OPEX and

CAPEX for production and transmission and eventual other expenditures. We schematically show this behaviour in Fig. 1. Extensive investigations of the LMP as done in [8] already showed this connection however leave the question open how the costs are allocated among the components. In the following we will show how the above presented cost decomposition is extended to full peer-to-peer (P2P) cost allocation including all network components.

## 2 Mathematical Theory

### 2.1 Power Transfer Distribution Factors and Flow Allocation

In linear power flow models, the Power Transfer Distribution Factors (PTDF)  $H_{\ell,n}$  determine the changes in the flow on line  $\ell$  for one unit (typically one MW) of net power production at bus  $n$ . Thus for a given production  $g_{n,s,t}$  and demand  $d_{n,a,t}$ , they directly link to the resulting flow on each line,

$$f_{\ell,t} = \sum_n H_{\ell,n} (g_{n,t} - d_{n,t}) \quad (4)$$

where  $g_{n,t} = \sum_s g_{n,s,t}$  and  $d_{n,t} = \sum_a d_{n,a,t}$  combine all generators  $s$  and all consumers  $a$  attached to  $n$ . The PTDF have a degree of freedom: The slack  $k_n$  denotes the contribution of bus  $n$  to balancing out total power excess or deficit in the system. It can be dedicated to one bus, a single “slackbus“, or to several or all buses. The choice of slack modifies the PTDF according to

$$H_{\ell,n}(k_m) = H_{\ell,n}^\circ - \sum_m H_{\ell,m}^\circ k_m \quad (5)$$

where  $H_{\ell,n}^\circ$  denote the PTDF with equally distributed slack. When bus  $n$  injects excess power, it has to flow to the slack; when bus  $n$  extract deficit power, it has to come from the slack. Summing over all ingoing and outgoing flow changes resulting from a positive injection at  $n$  yields again the slack

$$\sum_\ell K_{m,\ell} H_{\ell,n} = \delta_{m,n} - k_m \quad (6)$$

Note that  $\delta_{m,n}$  on the right hand side represents the positive injection at  $n$ . Established flow allocation schemes [cite] have used this degree of freedom in order to allocate power flows and exchanges to market participants. Under the assumption that consumers

account for all power flows in the grid, the slack is set to  $k_n^*$  such that

$$f_{\ell,t} = - \sum_n H_{\ell,n}(k_m^*) d_{n,t} \quad (7)$$

With such a choice the flow can be reproduced from the demand-side of the system only. Now each term in the sum on the right hand side stands for the individual contribution of consumers at node  $n$  to the network flow  $f_{\ell,t}$ . In other words, each nodal demand  $d_{n,t}$  induces a subflow originating from the slack  $k_n^*$  which all together add up to  $f_{\ell,t}$ . These subflows, in turn, can be further broken down to contributions for each bus  $m$  in the slack, such that we get the subflow of individual  $m \rightarrow n$  relations, that is

$$A_{m \rightarrow n, \ell, t} = (H_{\ell,m}^\circ - H_{\ell,n}^\circ) k_m^* d_{n,t} \quad (8)$$

It indicates the flow on line  $\ell$  coming from generators at  $m$  and supplying the demand  $d_{n,t}$ . When summing over all sources  $m$  it yields the total subflow induced by  $d_{n,t}$ , the same term as in the sum on the right hand side in Eq. (7); when summing over all sources and sinks, it yields again the power flow, thus

$$f_{\ell,t} = \sum_{m,n} A_{m \rightarrow n, \ell, t} \quad (9)$$

As mentioned before, the consumed power  $d_{n,t}$  has to come from the slack  $k_n^*$ . As proven in Appendix A.1, for each P2P relation  $m \rightarrow n$ , the “traded“ power  $A_{m \rightarrow n, t}$  amounts to

$$A_{m \rightarrow n, t} = k_m^* d_{n,t} \quad (10)$$

Finally, when summing over all sinks the P2P trades yield the nodal generation (see Appendix A.2)

$$\sum_n A_{m \rightarrow n, t} = g_{m,t} \quad (11)$$

and summing over all sources yields the nodal demand

$$\sum_m A_{m \rightarrow n, t} = d_{n,t} \quad (12)$$

which follows from the fact that  $\sum_n k_n^* = 1$ . Both allocation quantities  $A_{m \rightarrow n, t}$  and  $A_{m \rightarrow n, \ell, t}$  can be broken down to generators  $s$  or consumers  $a$  by multiplying with the nodal production share  $\omega_{n,s,t} = g_{n,s,t} / \sum_s g_{n,s,t}$  and the nodal consumer

share  $\omega_{n,a,t} = d_{n,a,t} / \sum_a d_{n,a,t}$  respectively.

The solution to  $k_n^*$  follows from combining Eqs. (10) and (11), which sets it to the share of the total production  $k_n^* = c g_{n,t}$  with  $c$  being defined as  $c = 1 / \sum_n g_{n,t}$ . That leads to the demand  $d_{n,a,t}$  of every single consumers  $a$  being supplied by all generators  $s$  in the network proportional to their gross production  $g_{n,s,t}$ . However as we will discuss in Section 4, the solution space can be extended to an individual slack for each node  $k_{m,n}^*$ .

## 2.2 Network Optimisation

We linearly cost-optimize the capacity and dispatch of a simple power system.

$$\min_{g_{n,s,t}, G_{n,s}, F_\ell} \left( \sum_{n,s} c_{n,s} G_{n,s} + \sum_{n,s,t} o_{n,s} g_{n,s,t} + \sum_{\ell} c_\ell F_\ell \right) \quad (13)$$

subject to following physical constraints.

The nodal balance constraint ensures that the amount of power that flows into a bus equals the power that flows out of a bus, thus reflects the Kirchhoff Current Law (KCL)

$$\sum_{\ell} K_{n,\ell} f_{\ell,t} - g_{n,t} + d_{n,t} = 0 \perp \lambda_{n,t} \quad \forall n, t \quad (14)$$

Its shadow price mirrors the Locational Marginal Prizes (LMP)  $\lambda_{n,t}$  per bus and time step. In a power market this is the €/MWh<sub>el</sub>-price which a consumer has to pay. Note that the flow  $f_{\ell,t}$  in Constr. (14) is a passive variable only, given by Eq. (4).

The generation  $g_{n,s,t}$  is constraint to its nominal capacity

$$g_{n,s,t} - \bar{g}_{n,s,t} G_{n,s} \leq 0 \perp \bar{\mu}_{n,s,t} \quad \forall n, s, t \quad (15)$$

$$-g_{n,s,t} \leq 0 \perp \underline{\mu}_{n,s,t} \quad \forall n, s, t \quad (16)$$

where  $\bar{g}_{n,s,t} \in [0, 1]$  is the capacity factor for renewable generators. The constraints yield the KKT variables  $\bar{\mu}_{n,s,t}$  and  $\underline{\mu}_{n,s,t}$  which due to complementary slackness,

$$\bar{\mu}_{n,s,t} (g_{n,s,t} - \bar{g}_{n,s,t} G_{n,s}) = 0 \quad \forall n, s, t \quad (17)$$

$$\underline{\mu}_{n,s,t} g_{n,s,t} = 0 \quad \forall n, s, t \quad (18)$$

are only non-zero if the corresponding constraint is binding.

The transmission capacity  $F_\ell$  limits the flow  $f_{\ell,t}$  in both directions, such that

$$f_{\ell,t} - F_\ell \leq 0 \perp \bar{\mu}_{\ell,t} \quad \forall \ell, t \quad (19)$$

$$-f_{\ell,t} - F_\ell \leq 0 \perp \underline{\mu}_{\ell,t} \quad \forall \ell, t \quad (20)$$

The yielding KKT variables  $\bar{\mu}_{\ell,t}$  and  $\underline{\mu}_{\ell,t}$  are only non-zero if  $f_{\ell,t}$  is limited by the transmission capacity in positive or negative direction, i.e. Constr. (19) or Constr. (20) are binding. The complementary slackness

$$\bar{\mu}_{\ell,t} (f_{\ell,t} - F_\ell) = 0 \quad \forall \ell, t \quad (21)$$

$$\underline{\mu}_{\ell,t} (-f_{\ell,t} - F_\ell) = 0 \quad \forall \ell, t \quad (22)$$

set the respective KKT for flows staying below the thermal limit to zero.

## 2.3 Allocating Nodal Payments

$$\begin{aligned} \mathcal{L}(g_{n,s,t}, f_{\ell,t}, G_{n,s}, F_\ell, \boldsymbol{\lambda}, \boldsymbol{\mu}) = & \sum_{n,s} c_{n,s} G_{n,s} + \sum_{n,s,t} o_{n,s} g_{n,s,t} + \sum_{\ell} c_\ell F_\ell \\ & + \sum_{n,t} \lambda_{n,t} \left( \sum_{\ell} K_{n,\ell} f_{\ell,t} - \sum_s g_{n,s,t} + \sum_a d_{n,a,t} \right) \\ & + \sum_{\ell,c,t} \lambda_{c,t} C_{\ell,c} x_\ell f_{\ell,t} \\ & + \sum_{n,s,t} \bar{\mu}_{n,s,t} (g_{n,s,t} - \bar{g}_{n,s,t} G_{n,s}) - \sum_{n,s,t} \underline{\mu}_{n,s,t} g_{n,s,t} \\ & + \sum_{\ell,t} \bar{\mu}_{\ell,t} (f_{\ell,t} - F_\ell) - \sum_{\ell,t} \underline{\mu}_{\ell,t} (-f_{\ell,t} - F_\ell) \end{aligned} \quad (23)$$

where  $\boldsymbol{\lambda} = \{\lambda_{n,t}, \lambda_{c,t}\}$  and  $\boldsymbol{\mu} = \{\bar{\mu}_{n,s,t}, \underline{\mu}_{n,s,t}, \bar{\mu}_{\ell,t}, \underline{\mu}_{\ell,t}\}$  denote the set of related KKT variables. The global maximum of the Lagrangian requires stationarity with respect to all variables. The stationarity of the generation capacity variable leads to

$$\frac{\partial \mathcal{L}}{\partial G_{n,s}} = 0 \rightarrow c_{n,s} = \sum_t \bar{\mu}_{n,s,t} \bar{g}_{n,s,t} \quad \forall n, s \quad (24)$$

the stationarity of the transmission capacity to

$$\frac{\partial \mathcal{L}}{\partial F_\ell} = 0 \rightarrow c_\ell = \sum_t (\bar{\mu}_{\ell,t} - \underline{\mu}_{\ell,t}) \quad \forall \ell \quad (25)$$

and the stationarity of the generation to

$$\frac{\partial \mathcal{L}}{\partial g_{n,s,t}} = 0 \rightarrow o_{n,s} = \lambda_{n,t} - \bar{\mu}_{n,s,t} + \underline{\mu}_{n,s,t} \quad \forall n, s \quad (26)$$

Solving Eq. (26) for the  $\lambda_{n,t}$ , leads to our first representation for Locational Market Price, which we will refer to as the “Island Solution“,

$$\lambda_{n,t} = o_{n,s} + \bar{\mu}_{n,s,t} - \underline{\mu}_{n,s,t} \quad \forall n, s, t \quad (27)$$

It connects the LMP directly with the local operational price and prices for the generation capacity constraint. However, we can derive a second representation for  $\lambda_{n,t}$ . Starting from the stationarity of the flow

$$0 = \frac{\partial \mathcal{L}}{\partial f_{\ell,t}} \quad (28)$$

$$0 = \sum_{m,\ell,t} \lambda_{m,t} K_{m,\ell} + \sum_{\ell} (\bar{\mu}_{\ell,t} - \underline{\mu}_{\ell,t}) + \sum_{\ell,c,t} \lambda_{c,t} C_{\ell,c} x_{\ell} \quad (29)$$

and multiplying each term with the Power Transfer Distribution Factor  $H_{\ell,n}$  leaves us with

$$0 = \lambda_{n,t} - \sum_m \lambda_{m,t} k_m + \sum_{\ell} (\bar{\mu}_{\ell,t} - \underline{\mu}_{\ell,t}) H_{\ell,n} \quad (30)$$

According to Eq. (6), the first term splits into the LMP at  $n$  and the LMP weighted with the slack. The final term disappears as the  $C_{\ell,c} x_{\ell}$  is the kernel of the PTDF  $H_{\ell,n}$ , so  $\sum_l C_{\ell,c} x_{\ell} H_{\ell,n} = 0$ . Solving Eq. (30) for  $\lambda_{n,t}$  and replacing  $\lambda_{m,t}$  of the right hand side with the expression of the Island Solution in Eq. (27) leads to

$$\lambda_{n,t} = \sum_m o_{m,s} k_m + \sum_m (\bar{\mu}_{m,s,t} - \underline{\mu}_{m,s,t}) k_m - \sum_{\ell} (\bar{\mu}_{\ell,t} - \underline{\mu}_{\ell,t}) H_{\ell,n} \quad \forall n, s, t \quad (31)$$

In contrast to the Island Solution in Eq. (27), this representation connects  $\lambda_{n,t}$  with all other prices in the system. Moreover, it must hold for any choice of  $k_m$  and correspondingly decomposes the LMP to operational prices  $o_{m,s}$  and prices for capacity bounds for generators and transmission lines. When setting the slack to  $k_m^* = c g_{m,s,t}$ , the LMP decomposes to

prices of generators proportional to their production plus an extra term for the transmission usage. This directly links to the flow allocation presented above. Multiplied with the nodal demand  $d_{n,t}$  the left hand side of Eq. (31) turns into the total payment of  $n$  and the right hand side into the different payment allocations,

$$\lambda_{n,t} d_{n,t} = \mathcal{O}_{n,t} + \mathcal{C}_{n,t}^G + \mathcal{C}_{n,t}^F \quad \forall n, t \quad (32)$$

which we define as

$$\mathcal{O}_{n,t} = \sum_{m,s} o_{m,s} \omega_{m,s,t} A_{m \rightarrow n,t} \quad (33)$$

$$\mathcal{C}_{n,t}^G = \sum_{m,s} \bar{\mu}_{m,s,t} \omega_{m,s,t} A_{m \rightarrow n,t} \quad (34)$$

$$\mathcal{C}_{n,t}^F = \sum_{m,\ell} (\bar{\mu}_{\ell,t} - \underline{\mu}_{\ell,t}) A_{m \rightarrow n,\ell,t} \quad (35)$$

Equation (33) denotes the payments for generators' OPEX, Eq. (34) for generators' CAPEX and Eq. (35) for the transmission system's CAPEX respectively. All those payment allocation build up on the physically allocated flows presented in Eqs. (8) and (10). Thus with the right choice of slack the power flow allocations directly translate into a cost allocation. Further, the allocated payments can be considered on a more detailed level as

$$\mathcal{O}_{n \rightarrow (m,s),t} = o_{m,s} \omega_{m,s,t} A_{m \rightarrow n,t} \quad (36)$$

$$\mathcal{C}_{n \rightarrow (m,s),t}^G = \bar{\mu}_{m,s,t} \omega_{m,s,t} A_{m \rightarrow n,t} \quad (37)$$

$$\mathcal{C}_{n \rightarrow \ell,t}^F = (\bar{\mu}_{\ell,t} - \underline{\mu}_{\ell,t}) \sum_m A_{m \rightarrow n,\ell,t} \quad (38)$$

Let's have a look at the allocated OPEX in Eqs. (33) and (36) first. Consumers at bus  $n$  retrieve power from different generators  $(m, s)$  and accordingly compensate their operational costs. The OPEX allocation behaves like P2P tradings between producers and consumers with fixed production prices. In this way, the generator  $(m, s)$  retrieves the exact amount of money from consumers that it spends on the operation. In other words, all OPEX payments to generator  $(m, s)$  sum up to the total OPEX spent at  $(m, s)$ , thus

$$\sum_n \mathcal{O}_{n \rightarrow (m,s),t} = o_{n,s} g_{n,s,t} \quad (39)$$

The CAPEX allocation for generators  $\mathcal{C}_{n,t}^G$  defined in Eqs. (34) and (37), reveals a similar relation. Ac-

cording to the polluter pays principle, it differentiates between consumers who are ‘responsible’ for investments and those who are not. If  $\bar{\mu}_{n,s,t}$  (in literature often denoted as the Quality of Supply) is bigger than zero, the upper Capacity Constr. (15) is binding. Thus it is these time steps which push investments in  $G_{n,s}$ . If  $\bar{\mu}_{n,s,t} = 0$ , the generation  $g_{n,s,t}$  is not bound and investments are not necessary. When summing over all CAPEX payments to generator  $(m, s)$  each generator retrieves exactly the cost that were spent to build the capacity  $G_{n,s}$ ,

$$\sum_{n,t} \mathcal{C}_{n \rightarrow (m,s),t}^G = c_{n,s} G_{n,s} \quad (40)$$

where we used Eqs. (17) and (24). So in total, throughout all time steps each generator  $(m, s)$  receives the money it spends for investments and operation, reflecting the zero-profit rule.

The allocation of CAPEX for the transmission system  $\mathcal{C}_{n,t}^F$ , defined in Eqs. (35) and (38), builds up on the KKT variables  $\bar{\mu}_{\ell,t}$  and  $\underline{\mu}_{\ell,t}$ . Again the latter translate to the necessity of transmission investments at  $\ell$  at time  $t$ . Consumers which retrieve power flowing on congested lines, yielding a bound Constr. (19) or (20), pay compensations for the resulting investments. Again the sum of all CAPEX payments to line  $\ell$  equal the total CAPEX spent, thus

$$\sum_{n,t} \mathcal{C}_{n \rightarrow \ell,t}^F = c_{\ell} F_{\ell} \quad (41)$$

where we used the complementary slackness Eqs. (21) and (22) and the fact that summing over all sources  $m$  and sinks  $n$  the allocation equals the actual power flow as stated in Eq. (9).

## 2.4 Adding Further Constraints

### CO<sub>2</sub> Constraint

Imposing an additional CO<sub>2</sub> constraint limiting the total emission to  $K$ ,

$$\sum_{n,s,t} e_{n,s} g_{n,s,t} \leq K \perp \mu_{\text{CO}_2} \quad (42)$$

with  $e_{n,s}$  being the emission factor in tonne-CO<sub>2</sub> per MWh<sub>el</sub>, returns an effective CO<sub>2</sub> price  $\mu_{\text{CO}_2}$  in €/tonne-CO<sub>2</sub>. As shown in ... the constraint can be

translated in a dual price which shift the operational price per generator

$$o_{n,s} \rightarrow o_{n,s} + e_{n,s} \mu_{\text{CO}_2} \quad (43)$$

This leads to allocated CO<sub>2</sub> cost compensation of node  $n$  of

$$\mathcal{E}_{n,t} = \mu_{\text{CO}_2} \sum_{m,s} e_{m,s} \omega_{m,s,t} A_{m \rightarrow n,t} \quad \forall n, t \quad (44)$$

which expands the allocation of the electricity cost in Eq. (32) to

$$\lambda_{n,t} d_{n,t} = \mathcal{C}_{n,t}^F + \mathcal{O}_{n,t} + \mathcal{C}_{n,t}^G + \mathcal{E}_{n,t} \quad \forall n, t \quad (45)$$

## Lower and Upper Capacity Limits

Constraining the capacities  $G_{n,s}$  for a subset  $S$  of generators to lower or upper limits in the form of

$$G_{n,s} \geq \underline{G}_{n,s} \quad \forall n, s \in S \quad (46)$$

$$G_{n,s} \leq \bar{G}_{n,s} \quad \forall n, s \in S \quad (47)$$

or doing likewise with a subset  $L$  of transmission lines,

$$F_{\ell} \geq \underline{F}_{\ell} \quad \forall \ell \in L \quad (48)$$

$$F_{\ell} \leq \bar{F}_{\ell} \quad \forall \ell \in L \quad (49)$$

does not have any effect on the above presented allocation in Eq. (32). The additional cost directly translate to the Quality of Supply  $\bar{\mu}_{n,s,t}$  for production and  $\bar{\mu}_{\ell,t} - \underline{\mu}_{\ell,t}$  for transmission respectively. This also counts for limiting the overall production capacity  $\sum_{n,s} G_{n,s}$  or transmission capacity  $\sum_{\ell} F_{\ell}$ . However it will distort the no profit rule for generators Eq. (40) and transmission Eq. (41) respectively. As shown in [3]

## 3 Numerical Example

The P2P cost allocation suits for any type of topology and network setup. In the following we showcase a two bus system with one optimized time step and its resulting allocated payments, illustrated in Fig. 2.

The two buses are connected via one transmission line, each has one generator. Whereas the generator at bus 1 has an operational price of 50 €/MWh<sub>el</sub>, the generator at bus 2 has a higher operational price of 200 €/MWh<sub>el</sub>. For both the CAPEX rate is set to 500 €/MW and the maximal capacity is limited to

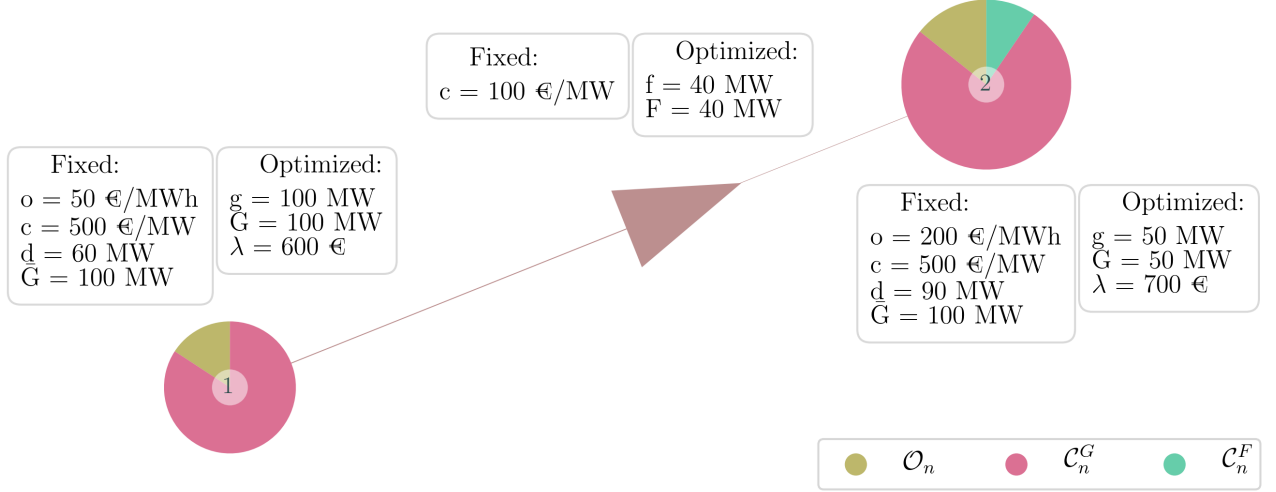


Figure 2: Illustrative example of a 2-bus network with one optimized time step. Fixed prices and constraining values are given in the left box for each bus and the transmission line. Optimized values are given in the right boxes. Bus 1 has a cheaper operational price  $o$ , capital prices are the same for both. As both generator capacities are constraint to 100 MW, the optimization also deploys the generator at bus 2. The resulting electricity prices  $\lambda$  are then a composition of all prices for operation and capital investments.

$\bar{G}_{n,s} = 100$  MW. The transmission line has a CAPEX rate of 100 €/MW and no upper capacity limit. With a demand of 60 MW at bus 1 and 90 MW at bus 2, the optimization expands the cheaper generator at bus 1 to its full limit of 100 MW. The 40 MW excess power not consumed at bus 1, flow to bus 2 where the generator is built with only 50 MW.

Figure 3 shows the allocated transactions for both buses 1 & 2 separately. The resulting P2P payments are given in Fig. 4. The upper graph Fig. 3a shows that  $A_{1,1} = 40$  MW at bus 1 are self-sustained. Consumers at bus 1 consequently pay 2k € OPEX and 22k € CAPEX to the generator at bus 1. The remaining 20 MW come from bus 2 and induce a sub-flow on line 1 of  $A_{2 \rightarrow 1,1} = -20$ . As this flow is in contrary direction to the total flow, it is relieving the transmission system. This translates to a congestion reward for consumers at bus 1 of  $c_{\ell=1} A_{2 \rightarrow 1,1} = 2$  k € which is exactly the cost that had to be spent on the transmission system if bus 1 didn't induce a relieving flow, see again Fig. 4.

The lower graph Fig. 3b illustrates the impact of consumption at bus 2. As  $d_2$  is higher than  $d_1$  the retrievments from both generators are proportionately increased as well as the OPEX and CAPEX allocations to the generators. But instead of a relieving flow, consumers at bus 2 drive the burdening flow in direction of congestion. Hence the payoff to

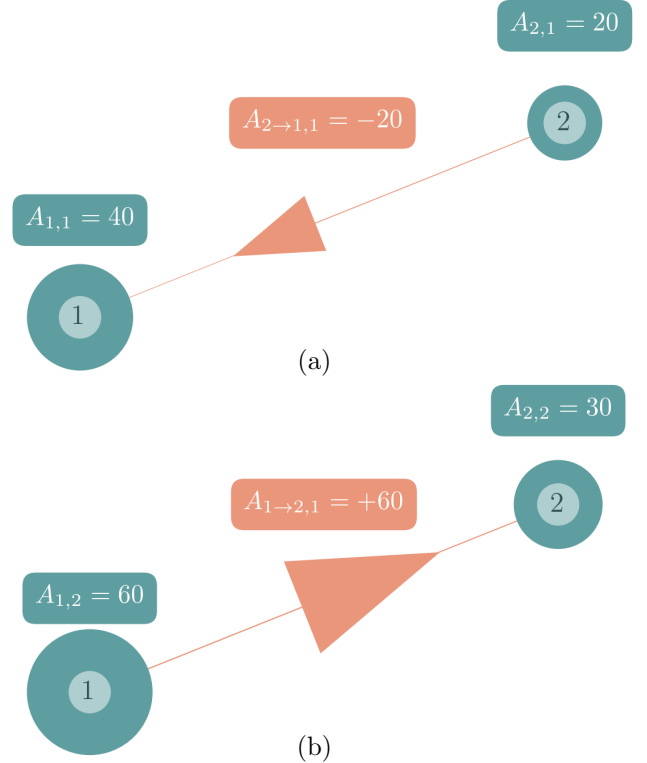


Figure 3: Power allocations for bus 1 (a) and bus 2 (b) of the example network in Fig. 2. Bus 1 retrieves 40 MW from itself and 20 MW from bus 2. The latter in turn retrieves 60 MW from bus 1 and self supplies 30 MW. The sum of both net flows equals the resulting flow of  $f = 40$  MW.



	$\mathcal{O}_n$		$\mathcal{C}_n^G$		$\mathcal{C}_n^F$
1	2k €	4k €	22k €	10k €	-2k €
2	3k €	6k €	33k €	15k €	6k €
	1	2	1	2	1
	m		m		$\ell$

Figure 4: Full P2P cost allocation for the example setup shown in Fig. 2. The payments are derived on the basis of Eqs. (36) to (38). Consumers at bus  $n$  have to pay each generator proportional to their consumption. As we only consider one time step the proportionality applies for OPEX  $\mathcal{O}_n$  and CAPEX  $\mathcal{C}_n$ . As bus 1 induces a relieving flow on line 1 and therefore “prevents” further transmission expansion, it is rewarded proportional to the relief.

the transmission system is positive and much higher than for bus 1.

The sum of all rows in the payoff matrix in Fig. 4 yields the revenues of the assets  $m, \ell$ . These values match their overall spendings, *e.g.* the total revenue of the transmission line is 4k € which equals the cost for investments  $c_1 F_1$ . The sum of all columns yields the total payment of consumers at bus  $n$ . For example the sum of payments of consumers at bus 1 is 36k €. This is exactly the electricity price of 600 €/MW times the consumption of 60 MW,  $\lambda_1 d_1$ .

The fact that OPEX and CAPEX allocations are proportional to the total consumption at a bus results from optimizing one time step only. In larger optimization problems with multiple time steps the CAPEX allocation takes effect only for time steps in which capacity constraints limit the operation of assets, *i.e.* one or more of Constrs. (15), (19) and (20) is binding.

## 4 Localizing Allocations

We recap the fundamental constraint for the solution space  $k_m^*$  which is given by

$$g_{m,t} = \sum_n k_m^* d_{n,t} \quad (50)$$

and results from Eqs. (10) and (11) in Section 2. The summation over  $n$  allows for extending  $k_m^*$  to a set of individual solution for each bus  $n$

$$k_m^* \rightarrow k_{m,n}^* \quad (51)$$

which fulfills Eq. (50). In the following we link the solution space  $k_{m,n}^*$  to established flow allocation methods. Principally two options exist *what* is allocated

1. gross power injections
2. net power injections

Further it is important *what assumptions* define the allocation, *i.e.* what method is used to define the pairs of sources and sinks. The three suitable approaches we present here are

- a. Equivalent Bilateral Exchanges (EBE) [4] which assumes that every producer supplies every consumer proportional to its share in the total consumption.
- b. Average Participation (AP) [1][2] which traces the flow from producer to consumer following the law of proportional sharing.
- c. Flow Based Market Coupling (FBMC) which uses zonal PTDF for allocating power within predefined regions. The interregional exchange is only allocating net power deficit or excess of the regions.

The solution presented in Section 2.1 and used throughout the example in Section 3 corresponds to type 1a, allocating gross power injections according to the EBE principle. Appendix A.3 derives the distributed slack  $k_{m,n}^*$  for net injections following the EBE principal (type 2a). It leads to less P2P trades as power from a bus  $n$  with  $g_{n,t} \leq d_{n,t}$  is not assigned to other buses, only to  $n$ .

However, literature has often pointed out that the EBE principal does not suit for large networks where remote buses would interconnect in the same way as buses in close vicinity[5]. The AP based choice of slack  $k_{m,n}^*$  formulated in Appendices A.4 and A.5 tackles this problem by restricting P2P trades to those which are traceable when applying the proportional sharing principal. Therefore  $A_{m \rightarrow n,t}$  denotes that part of power produced by bus  $m$  which, when only following in the direction of  $f_{\ell,t}$ , ends up at bus  $n$ . This leads to intuitive and spatially justifiable P2P allocations. Note however that the subflows  $A_{m \rightarrow n,\ell,t}$  do not

## 5 Application Case



## A Appendix

### A.1 Proof Equation (10)

Equation (10) follows from summing  $A_{m \rightarrow n, \ell, t}$  over all incoming flows to  $n$  and taking into account the power that  $n$  provides by itself,  $k_n^* d_{n, t}$ , which leads us to

$$\begin{aligned} A_{m \rightarrow n, t} &= k_n^* d_{n, t} - \sum_{\ell} K_{n, \ell} A_{m \rightarrow n, \ell, t} \\ &= k_n^* d_{n, t} - \sum_{\ell} K_{n, \ell} (H_{\ell, m}^{\circ} - H_{\ell, n}^{\circ}) k_m^* d_{n, t} \\ &= k_n^* d_{n, t} - \left( \delta_{n, m} - \frac{1}{N} - \delta_{n, n} + \frac{1}{N} \right) k_m^* d_{n, t} \\ &= k_n^* d_{n, t} - (\delta_{n, m} - 1) k_m^* d_{n, t} \\ &= k_m^* d_{n, t} \end{aligned}$$

where we used Eq. (6) and the fact that the equally distributed slack amounts to  $1/N$  for all  $N$  nodes in the network.

### A.2 Proof of Equation (11)

The relation follows from multiplying Eq. (7) with  $\sum_m K_{m, \ell}$ , and solving for  $A_{m \rightarrow n, t}$

$$\begin{aligned} \sum_m K_{m, \ell} f_{\ell, t} &= - \sum_{m, n} K_{m, \ell} H_{\ell, n} d_{n, t} \\ g_{m, t} - d_{m, t} &= -\delta_{m, n} d_{n, t} + k_m^* d_{n, t} \\ A_{m \rightarrow n, t} &= g_{m, t} - d_{m, t} + \delta_{m, n} d_{n, t} \\ \sum_n A_{m \rightarrow n, t} &= g_{m, t} \end{aligned}$$

### A.3 Allocating Net Injections with EBE

Allocating net power injections using the EBE methods leads to the same result as the Marginal Participation (MP) [7] algorithm when allocating to consumers only, see [6] for further insight. We calculate it by setting

$$k_{m, n}^* = \frac{\delta_{m, n} p_{m, t}^{\circ} + \gamma_t p_{n, t}^- p_{m, t}^+}{d_{n, t}} \quad (52)$$

where

- $p_{n, t}^+ = \min(g_{n, t} - d_{n, t}, 0)$  denotes the nodal net production
- $p_{n, t}^- = \min(d_{n, t} - g_{n, t}, 0)$  denotes the nodal net consumption

- $p_{n, t}^{\circ} = \min(p_{n, t}^+, p_{n, t}^-)$  the denotes nodal self-consumption. That is the power generated and at the same time consumed at node  $n$  and
- $\gamma_t = \frac{1}{\sum_n p_{n, t}^+} = \frac{1}{\sum_n p_{n, t}^-}$  is the inverse of the total injected/extracted power at time  $t$ .

### A.4 Allocating Net Power using AP

Allocating net injections using the AP method is derived from [1]. In a lossless network the downstream and upstream formulations result in the same P2P allocation which is why we restrict ourselves to the downstream formulation only. In a first step we define a time-dependent auxiliary matrix  $\mathcal{J}_t$  which is the inverse of the  $N \times N$  with directed power flow  $m \rightarrow n$  at entry  $(m, n)$  for  $m \neq n$  and the total flow passing node  $m$  at entry  $(m, m)$  at time step  $t$ . Mathematically this translates to

$$\mathcal{J}_t = (\text{diag}(p^+) + \mathcal{K}^- \text{diag}(f) K)_t^{-1} \quad (53)$$

where  $\mathcal{K}^-$  is the negative part of the directed Incidence matrix  $\mathcal{K}_{n, \ell} = \text{sign}(f_{\ell, t}) K_{n, \ell}$ . Then the distributed slack for time step  $t$  is given by

$$k_{m, n} = \mathcal{J}_{m, n, t} p_{m, t}^+ \quad (54)$$

### A.5 Allocating Gross Power using AP

We use the same allocation as in Appendix A.4 but replace the net nodal production  $p_{n, t}^+$  by the gross nodal production  $g_{n, t}$  which leads to

$$\mathcal{J}_t = (\text{diag}(g) + \mathcal{K}^- \text{diag}(f) K)_t^{-1} \quad (55)$$

The distributed slack is for time step  $t$  is then given by

$$k_{m, n} = \mathcal{J}_{m, n} g_{m, t} \quad (56)$$

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