# A Continuous-Time Dynamical System Describing both Rate Encoding and Spiking Neurons

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#### Introduction

- ► We investigated a two-dimensional nonlinear system, modeling a wide range of dynamic properties of spiking neurons.
- ▶ By altering key parameters of this system, its dynamics become identical to those of a time-continuous rate-encoding model.
- ▶ Differences of the dynamical properties of single units as well as of network structures under these two regimes can be treated within the same mathematical framework.

#### Neuron Model

► The model consists of a two-dimensional non-linear system given by

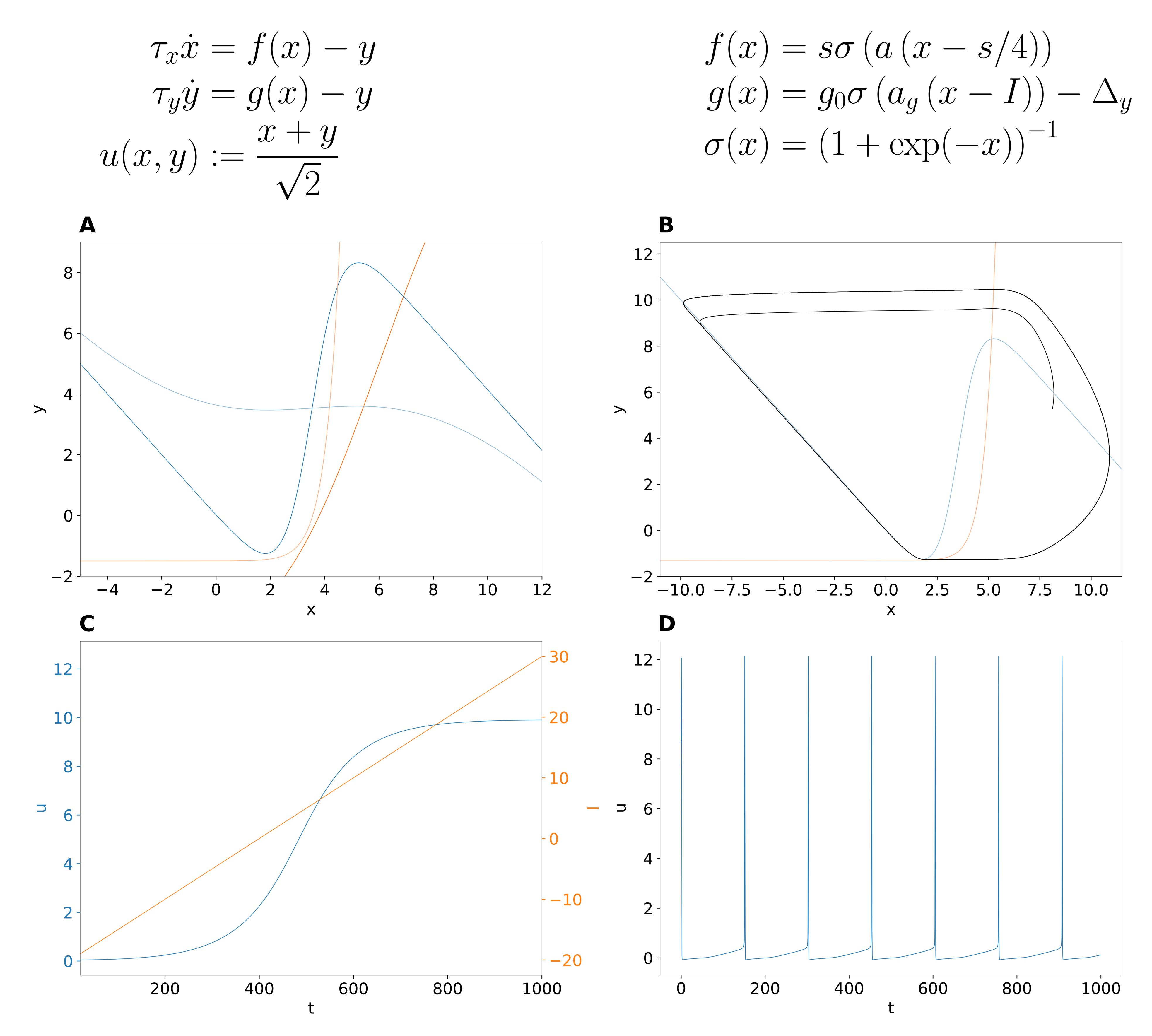


Figure 1: **A**: x/y-nullclines (blue/orange) of the dynamical system for parameter sets generating spiking/non spiking behavior. **B**: Phase plane trajectory for the spiking dynamics. **C**/**D**: Dynamics of readout variable u for the non-spiking/spiking case.

## Spiking Neuron Model

► A range of different types of spiking dynamics can be reproduced by this generic system.



#### Fitting Experimental Data

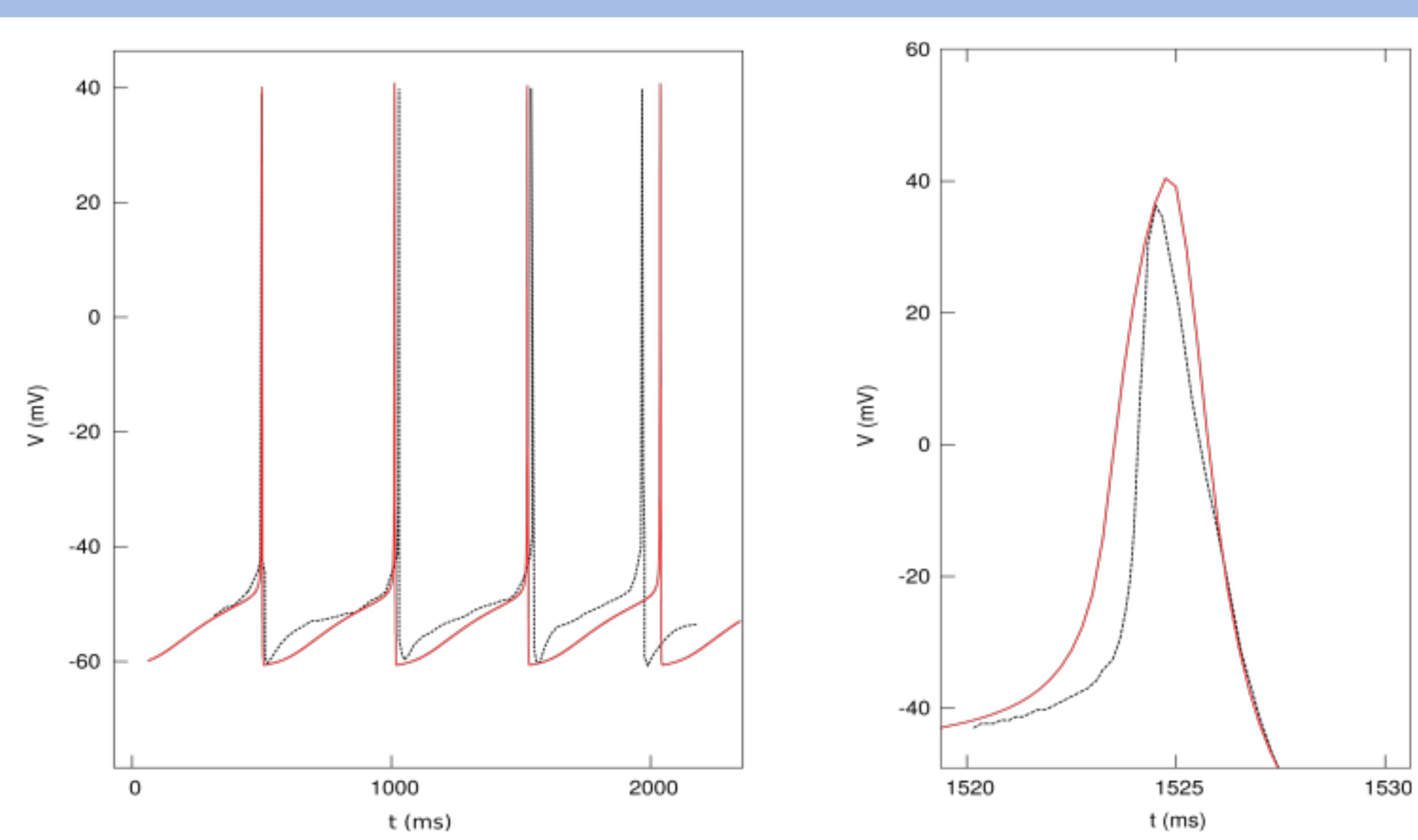


Figure 4: Fit of the dynamical system onto measurements of a dopaminergic neuron in the Substantia Nigra of a mouse brain [2].

► The parameters of the dynamical systems allow to easily control key features of the voltage trace, such as spike height, spike width and threshold potential.

$$u_{
m spikeheight} pprox s/\sqrt{2}$$
 $\Delta t_{
m spike} \propto g_O^{-1}$ 
 $u_{
m threshold} pprox 1/\sqrt{2}a$ 

## Rate Encoding Model

- ► The system's parameters can be tuned such that dynamics transition from a spiking behavior to a relaxation towards an input-dependent fixed point.
- $\blacktriangleright$  The projection of this fixed point onto u follows a sigmoidal as input increases, see Fig. 1C

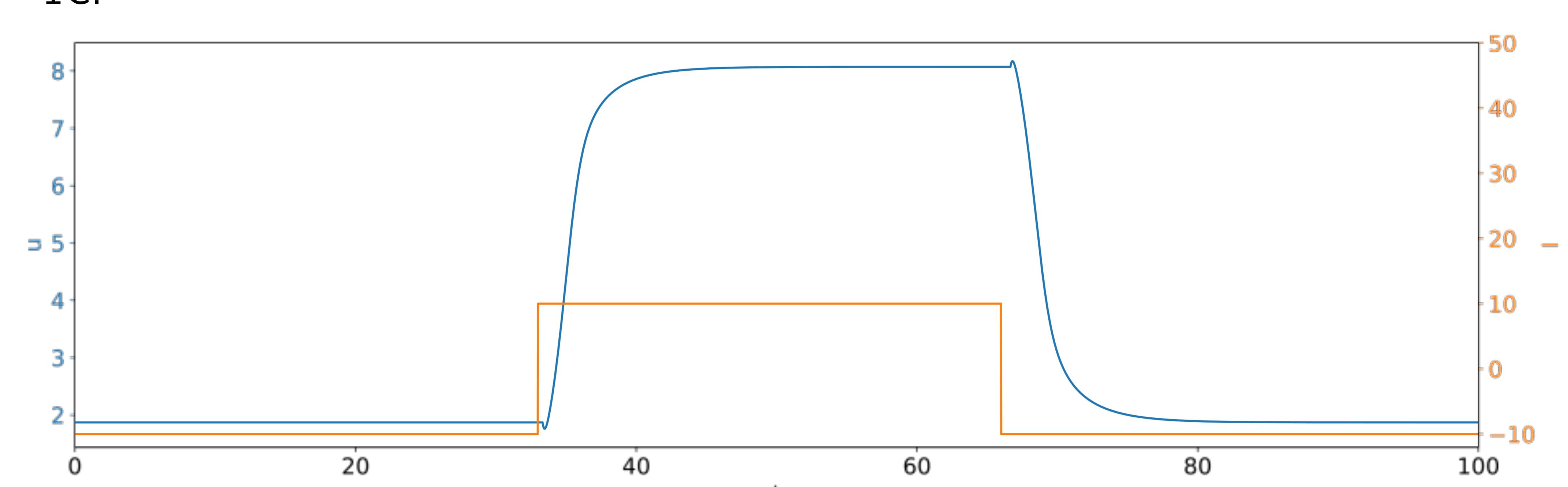


Figure 5: Rate-dynamics response of the readout variable u upon external step input.

The dynamics of u approximately follow those of 1d-system of the form  $\tau \dot{u} = -u + \frac{s}{\sqrt{2}}\sigma\left(c \cdot I\right)$ . The time constant  $\tau$  is then described by  $\tau = -\frac{1}{\langle \lambda \rangle}$ , where  $\langle \lambda \rangle$  is the mean of the eigenvalues of the fixed point's Jacobian