Embedded Ada/SPARK Programming in 2022

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Scope: MCUs

- Micro-controllers
 - "Simple" devices
 - A few KiB sometimes MiB of RAM and ROM
 - No virtual memory
 - A lot of inputs/outputs
- No Operating System (bare-metal)

Ada/SPARK for embedded: Pros

- Benefits of high-level language
 - Contracts
 - Tagged types
 - Discriminated types
 - Arrays
 - Etc.
- Representation Clauses
- Interfacing with C
- Less debugging (debugging is hard in embedded)
- SPARK: formal proof
- Alire!
- Ravenscar Tasking

Ravenscar Tasking

A.K.A There's a mini-RTOS in my language¹

- Tasks (threads)
- Time handling
 - Clock
 - Delays
- Protected Objects:
 - Mutual exclusion
 - Synchronization between tasks
 - Interrupt handling

 $^{^{1}} blog. adacore. com/the res-a-mini-rtos-in-my-language \\$

Ada/SPARK for embedded: Cons

- Ravenscar Tasking
- Secondary Stack
- Toolchain availability
- Drivers/BSP availability
- Library ecosystem

What do you need?

What do you need?

- Board Support Package (BSP)
 - Run-time
 - Startup code
 - Linker scripts
 - Drivers
- Libraries
- Toolchain

Ada/SPARK Integration in Embbedded Projects

| Startup | Drivers | Functional | Libraries | |
|---------|---------|------------|-----------|--|
| Ada | Ada | Ada | Ada | |
| С | С | Ada | С | |
| С | Ada/C | Ada | C/Ada | |
| | | Ada | | |

Board Support Package

ARM Microcontroller Market

- Dozens of vendors (ST, Microchip, NXP, Nordic, Cypress, Infineon, nuvoTon, TI, Raspberry Pi, etc.)
- 8 variants (Cortex-M0/M0+/M1/M3/M4/M7/M23/M33)
- Thousands of individual parts (4000+):
 - STM32F446RET6
 - nRF51822-QFAA-R
 - APM32F103C6
 - ATSAME54N20A
 - HT32F22366
 - XMC1302-Q040x0032
 - EFM32GG280F1024
 - MB9AF155M
 - S6E2CC8H0A
 - MK60DN256xxx10
 - LM4F122H5QD
 - LPC1114FHN33/202TMPM3H2FWD116

How can we support so many devices?

Startup and run-time

The "generic" ZFP run-times

Zero-FootPrint run-times without parts that are specific to a given MCU or board

That means without:

- Linker script
- Startup code (crt0.S)

startup-gen

```
package Device_Configuration is
    for Cpu_Name use "ARM Cortex-M4F";
    for Memories use ("HSRAM", "FLASH");
    for Boot_Memory use "FLASH";
    for Mem_Kind ("FLASH") use "rom";
    for Address ("FLASH") use "0x08000000";
   for Size ("FLASH") use "0x80000";
    for Mem_Kind ("HSRAM") use "ram";
    for Address ("HSRAM") use "0x20000000";
    for Size ("HSRAM") use "0x30000";
end Device_Configuration;
```

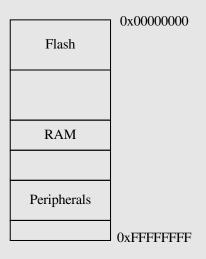
startup-gen

```
$ alr get/with startup_gen
```

\$ startup-gen -P samd51.gpr -l src/link.ld -s src/crt0.S

Peripheral Drivers

Memory Mapped Registers



Memory Mapped Registers

| 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|----------------|---|----------|---|---|---|---|---|
| Reserved Sense | | Reserved | | | | | |

Sense: Pin sensing mechanism

0: Disabled

2: Sense for high level

3: Sense for low level

```
#define SENSE_MASK
#define SENSE_POS
                     (4)
#define SENSE_DISABLED (0)
#define SENSE_HIGH (2)
#define SENSE_LOW (3)
uint8_t *register = 0x80000100;
// Clear Sense field
*register &= ~SENSE_MASK;
// Set sense value
*register |= SENSE_DISABLED << SENSE_POS;
```

```
-- High level view of the Sense field
type Pin_Sense is
  (Disabled,
   High,
  Low)
  with Size => 2;
    Hardware representation of the Sense field
for Pin_Sense use
  (Disabled \Rightarrow 0,
   High \Rightarrow 2,
   Low \Rightarrow 3);
```

```
-- High level view of the register
type IO_Register is record
  Reserved_A : UInt4;
  SENSE : Pin Sense;
  Reserved B : UInt2;
end record;
   Hardware representation of the register
for IO_Register use record
  Reserved_A at 0 range 0 .. 3;
  SENSE at 0 range 4 .. 5;
  Reserved_B at 0 range 6 .. 7;
end record;
```

```
Register : IO_Register
with Address => 16#8000_0100#;
```

```
Register.SENSE := Disabled;
```

Let's focus on one microcontroller

- STM32F446RET6
- 46 peripherals
- 881 memory mapped registers
- 6820 fields in the registers

Who wants to write all the representation clauses for that beast?

System View Description (SVD)

```
<field>
  <name>SENSE</name>
  <description>Pin sensing mechanism.</description>
  <lsb>4</lsb> <msb>5</msb>
  <enumeratedValues>
    <enumeratedValue>
      <name>Disabled</name>
      <description>Disabled.</description>
      <value>0x00</value>
    </enumeratedValue>
 [...]
```

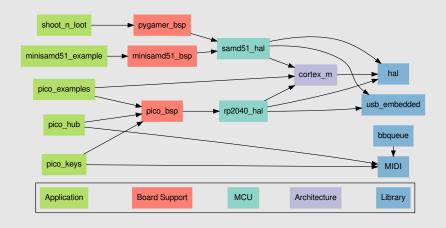
SVD2Ada

Generates Ada representation clauses from SVD file.

\$ alr get/with svd2ada

Libraries

Embedded projects with Alire



Available Toolchains







What about SPARK?

What about SPARK?

- All of the above apply
- Easier to do SPARK in embedded
- Easier to start with libraries

Questions?

Thank you!