NFA TO DFA

NFAs accept the Regular Languages

Equivalence of Machines

Definition for Automata:

Machine

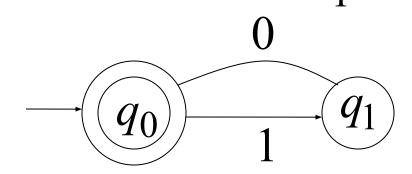
 M_{1} is equivalent to machine

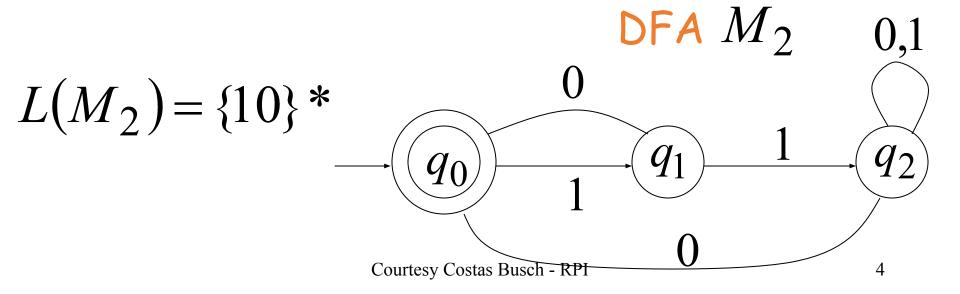
$$M_2$$

$$^{\mathsf{if}} L(M_1) = L(M_2)$$

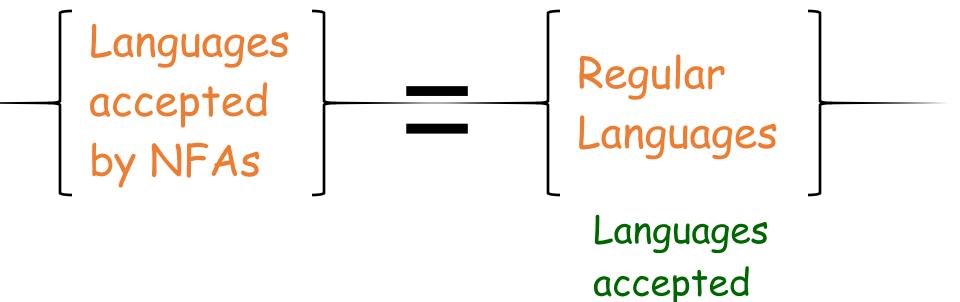
Example of equivalent machines $_{{\sf FA}}\,\,M_1$

$$L(M_1) = \{10\} *$$





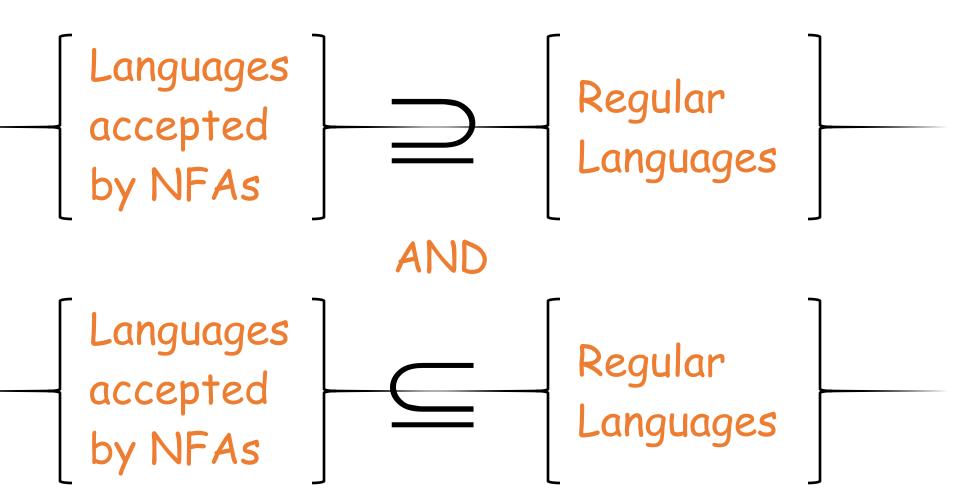
We will prove:



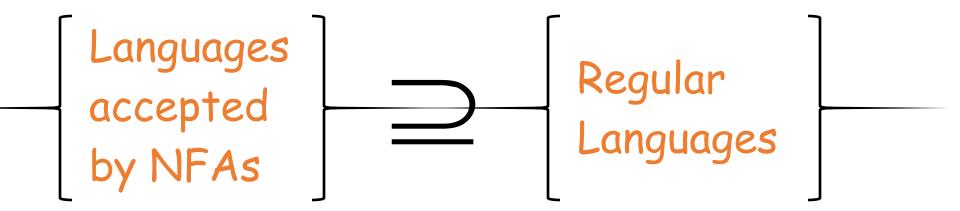
by DFAs

NFAs and DFAs have the same computation power

Proof: we only need to show



Step 1

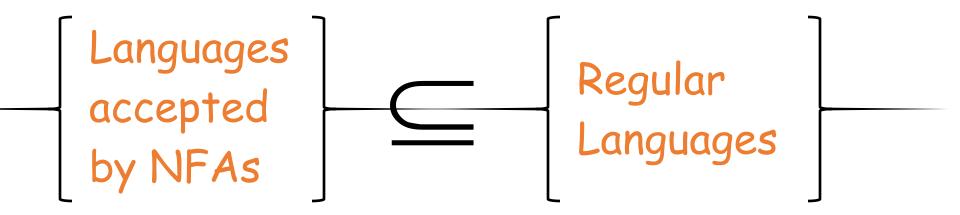


Proof: Every DFA is trivially an NFA



Any language $\,L\,$ accepted by a DFA is also accepted by an NFA

Step 2



Proof: Any NFA can be converted to an equivalent DFA

Any language L accepted by an NFA is also accepted by a DFA $_8$

Non Deterministic Features of NFA

There are three main cases of non-determinism in NFAs:

- 1. Transition to a state without consuming any input.
- 2. Multiple transitions on the same input symbol.
- 3. No transition on an input symbol.

To convert NFAs to DFAs we need to get rid of non-determinism from NFAs.

Using Subset construction method to convert NFA to DFA involves the following steps:

- For every state in the NFA, determine all reachable states for every input symbol.
- The set of reachable states constitute a *single state* in the converted DFA (Each state in the DFA corresponds to a subset of states in the NFA).
- Find *reachable states* for each new DFA state, until no more new states can be found.

Fig1. NFA without λ -transitions

Fig1. NFA without λ -transitions

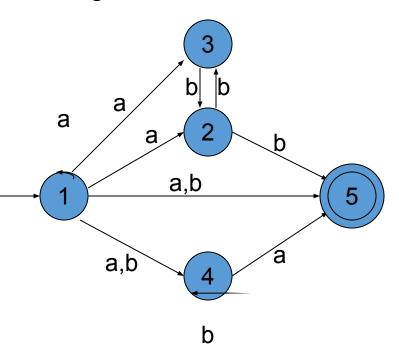
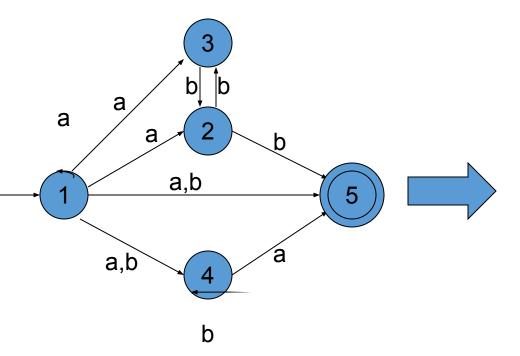


Fig1. NFA without λ -transitions



Step1

Construct a transition table showing all reachable states for every state for every input signal.

Fig1. NFA without λ -transitions

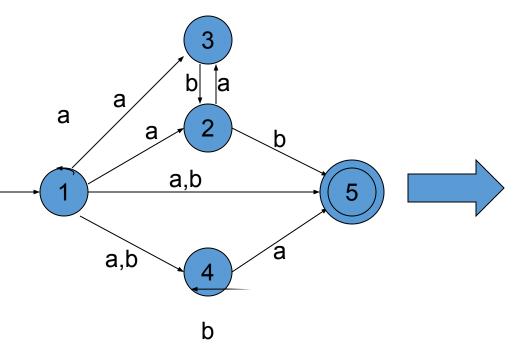


Fig2. Transition table

Fig1. NFA without λ -transitions

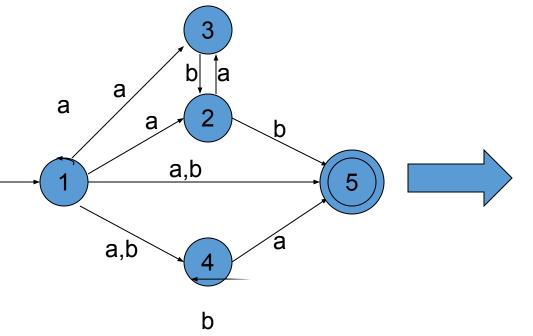


Fig2. Transition table

q	<i>δ</i> (q,a)	$\delta(q,b)$
1	{1,2,3,4,5}	{4,5}
2	{3}	{5}
3	Ø	{2}
4	{5}	{4}
5	Ø	Ø

with input b input a Fig1. NFA without λ -transitions $\delta(q,a)$ $\delta(q,b)$ b a Starts here {1,2,3,4,5} {4,5} a a 2 {3} {5} a,b 3 {2} \varnothing {5} {4} 4 a,b 5 \varnothing \varnothing b

Transition from state q with

Transition from state q

Fig2. Transition table		
q	δ (q,a)	$\delta(q,b)$
1	{1,2,3,4,5}	{4,5}
2	{3}	{5}
3	Ø	{2}
4	{5}	{4}
5	Ø	Ø

Step2



The set of states resulting from every transition function constitutes a new state. Calculate all reachable states for every such state for every input signal.

Fig2. Transition table

 q
 δ (q,a)
 δ (q,b)

 1
 $\{1,2,3,4,5\}$ $\{4,5\}$

 2
 $\{3\}$ $\{5\}$

 3
 \emptyset $\{2\}$

 4
 $\{5\}$ $\{4\}$

 5
 \emptyset \emptyset

Fig3. Subset Construction table

Starts with

Initial state

q	δ (q,a)	δ (q,b)
1	{1,2,3,4,5}	{4,5}

Fig2. Transition table

q	<i>δ</i> (q,a)	$\delta(q,b)$
1	{1,2,3,4,5}	{4,5}
2	{3}	{5}
3	Ø	{2}
4	{5}	{4}
5	Ø	Ø

Fig3. Subset Construction table

Starts with Initial state

q	δ (q,a)	$\delta(q,b)$
1	{1 2,3,4,5}	{4,5}
{1,2,3,4,5}		
{4,5}		

Fig2. Transition table

q	<i>δ</i> (q,a)	$\delta(q,b)$
1	{1,2,3,4,5}	{4,5}
2	{3}	{5}
3	Ø	{2}
4	{5}	{4}
5	Ø	Ø

Fig3. Subset Construction table

Starts with Initial state

q	δ(q,a)	δ (q,b)
1	{1 2,3,4,5}	{4,5}
{1,2,3,4,5}		
{4,5}		

Step3

Repeat this process(step2) until no more new states are reachable.

Fig2. Transition table

q	<i>δ</i> (q,a)	δ (q,b)
1	{1,2,3,4,5}	{4,5}
2	{3}	{5}
3	Ø	{2}
4	{5}	{4}
5	Ø	Ø

Fig3. Subset Construction table

<u> </u>		
q	δ (q,a)	$\delta(q,b)$
1	{1,2,3,4,5}	{4,5}
{1,2,3,4,5}	{1,2,3,4,5}	{2,4,5}
{4,5}		
{2,4,5}		

Fig2. Transition table

q	δ(q,a)	δ (q,b)
1	{1,2,3,4,5}	{4,5}
2	{3}	{5}
3	Ø	{2}
4	{5}	{4}
5	Ø	Ø

Fig3. Subset Construction table

q	δ(q,a)	$\delta(q,b)$
1	{1,2,3,4,5}	{4,5}
{1,2,3,4,5}	{1,2,3,4,5}	{2,4,5}
{4,5}	5	4
{2,4,5}		
5		
4		

Fig2. Transition table

q	δ(q,a)	δ (q,b)
1	{1,2,3,4,5}	{4,5}
2	{3}	{5}
3	Ø	{2}
4	{5}	{4}
5	Ø	Ø

Fig3. Subset Construction table

q	<i>δ</i> (q,a)	δ (q,b)
1	{1,2,3,4,5}	{4,5}
{1,2,3,4,5}	{1,2,3,4,5}	{2,4,5}
{4,5}	5	4
{2,4,5}	{3,5}	{4, 5}
5		
4		
{3,5}		

Fig2. Transition table

q	δ(q,a)	δ (q,b)
1	{1,2,3,4,5}	{4,5}
2	{3}	{5}
3	Ø	{2}
4	{5}	{4}
5	Ø	Ø

Fig3. Subset Construction table

q	δ (q,a)	$\delta(q,b)$
1	{1,2,3,4,5}	{4,5}
{1,2,3,4,5}	{1,2,3,4,5}	{2,4,5}
{4,5}	5	4
{2,4,5}	{3,5}	{4,5}
5	Ø	9
4		
{3,5}		
Ø		

Fig2. Transition table

q	<i>δ</i> (q,a)	$\delta(q,b)$
1	{1,2,3,4,5}	{4,5}
2	{3}	{5}
3	Ø	{2}
4	{5}	{4}
5	Ø	Ø



We already got 4 and 5.
So we don't add them again.

Fig3. Subset Construction table

q	δ (q,a)	δ (q,b)
1	{1,2,3,4,5}	{4,5}
{1,2,3,4,5}	{1,2,3,4,5}	{2,4,5}
{4,5}	5	4
{2,4,5}	{3,5}	{4,5}
5	Ø	Ø
4	5	4
{3,5}		

Fig2. Transition table

q	δ(q,a)	$\delta(q,b)$
1	{1,2,3,4,5}	{4,5}
2	{3}	{5}
3	Ø	{2}
4	{5}	{4}
5	Ø	Ø

Fig3. Subset Construction table

		_
q	δ (q,a)	δ (q,b)
1	{1,2,3,4,5}	{4,5}
{1,2,3,4,5}	{1,2,3,4,5}	{2,4,5}
{4,5}	5	4
{2,4,5}	{3,5}	{4,5}
5	Ø	Ø
4	5	4
{3,5}	Ø	2
Ø		
2		

Fig2. Transition table

q	δ(q,a)	$\delta(q,b)$
1	{1,2,3,4,5}	{4,5}
2	{3}	{5}
3	Ø	{2}
4	{5}	{4}
5	Ø	Ø

Fig3. Subset Construction table

q	δ(q,a)	δ (q,b)
1	{1,2,3,4,5}	{4,5}
{1,2,3,4,5}	{1,2,3,4,5}	{2,4,5}
{4,5}	5	4
{2,4,5}	{3,5}	{4,5}
5	Ø	Ø
4	5	4
{3,5}	Ø	2
Ø	Ø	Ø
2		

Fig2. Transition table

q	δ(q,a)	$\delta(q,b)$
1	{1,2,3,4,5}	{4,5}
2	{3}	{5}
3	Ø	{2}
4	{5}	{4}
5	Ø	Ø

Fig3. Subset Construction table

q	<i>δ</i> (q,a)	δ (q,b)
1	{1,2,3,4,5}	{4,5}
{1,2,3,4,5}	{1,2,3,4,5}	{2,4,5}
{4,5}	5	4
{2,4,5}	{3,5}	{4,5}
5	Ø	Ø
4	5	4
{3,5}	Ø	2
Ø	Ø	Ø
2	3	5
3		

Fig2. Transition table

q	δ(q,a)	δ (q,b)
1	{1,2,3,4,5}	{4,5}
2	{3}	{5}
3	Ø	{2}
4	{5}	{4}
5	Ø	Ø

Fig3. Subset Construction table

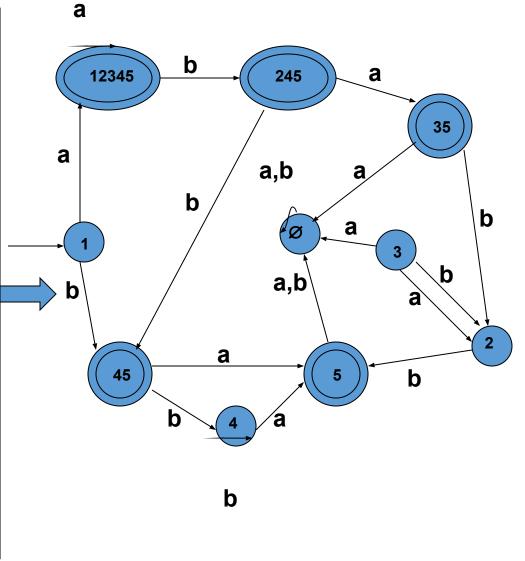
1 190: Gaboct Gottott action table			
q	δ (q,a)	$\delta(q,b)$	
1	{1,2,3,4,5}	{4,5}	
{1,2,3,4,5}	{1,2,3,4,5}	{2,4,5}	
{4,5}	5	4	
{2,4,5}	{3,5}	{4,5}	
5	Ø	Ø	
4	5	4	
{3,5}	Ø	2	
Ø	Ø	Ø	
2	3	5	
3	Ø	2	

Stops here as there are no more reachable states

Fig3. Subset Construction table

 $\delta(\mathbf{q},\mathbf{a})$ {1,2,3,4,5} {4,5} {1,2,3,4,5} {1,2,3,4,5} {2,4,5} {4,5} 5 {3,5} {4,5} {2,4,5} 5 \varnothing \varnothing 4 5 4 2 {3,5} \varnothing \varnothing \varnothing \varnothing 2 3 5 3 2 \varnothing

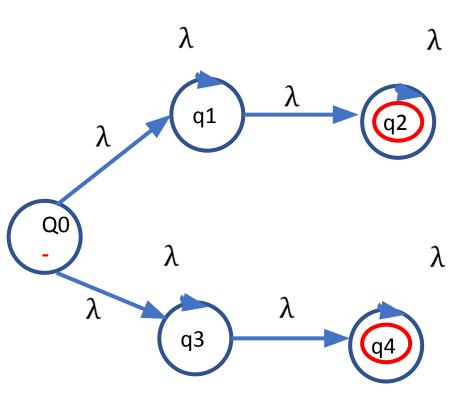
Fig4. Resulting FA after applying Subset Construction to fig1

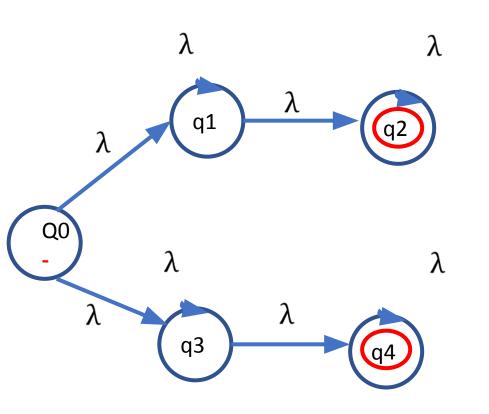


E-NIA to DIA

Teachers

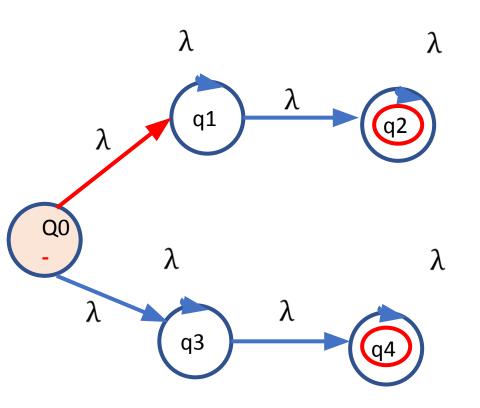
Mr. Musawar and Ms. Bakhtawar





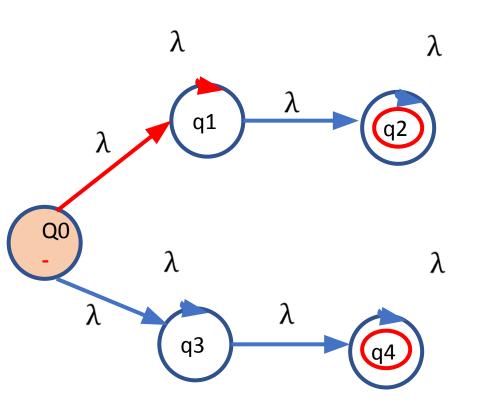
Transition Table

States	a	b



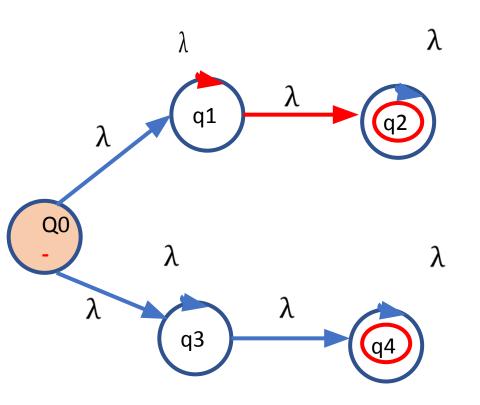
Transition Table

States	a	b
q_o		



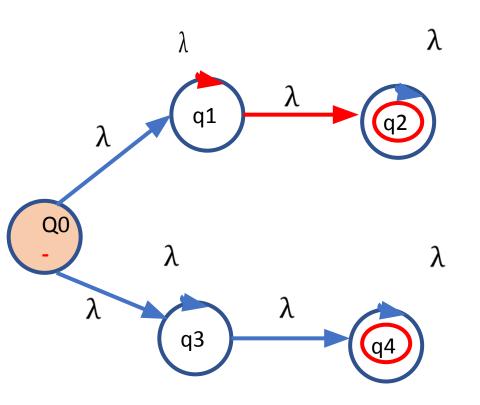
Transition Table

States	a	b
q_o	$\{q_1\}$	



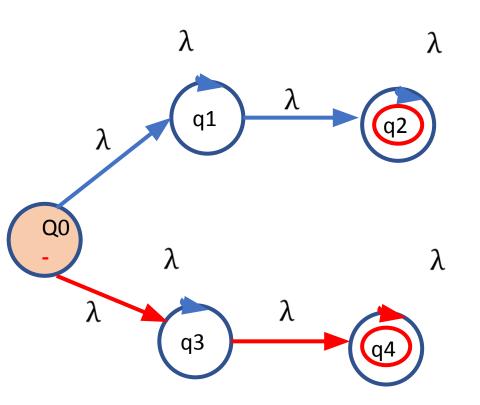
Transition Table

States	a	b
q_o	$\{q_1,\}$	



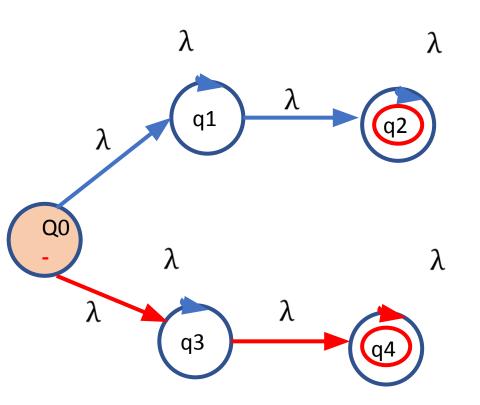
Transition Table

States	a	b
q_o	$\{q_1,q_2\}$	



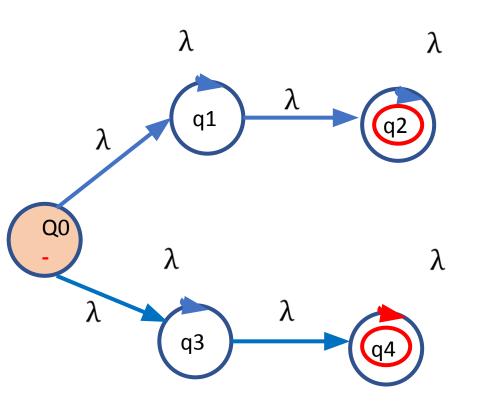
Transition Table

States	a	b
q_o	$\{q_1, q_{2,}q_4\}$	



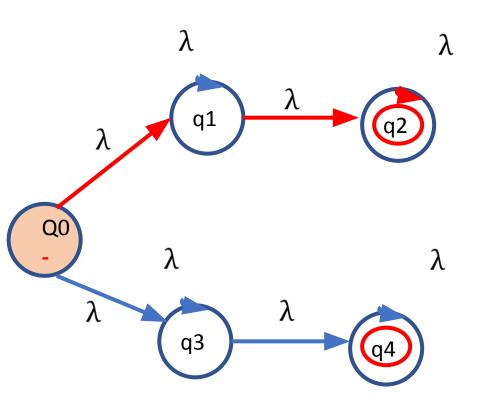
Transition Table

States	a	b
q_o	$\{q_1, q_{2,}q_4\}$	



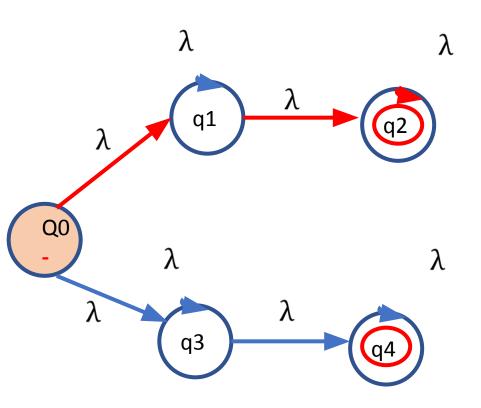
Transition Table

States	a	b
q_o	$\{q_1, q_2, q_4\}$	



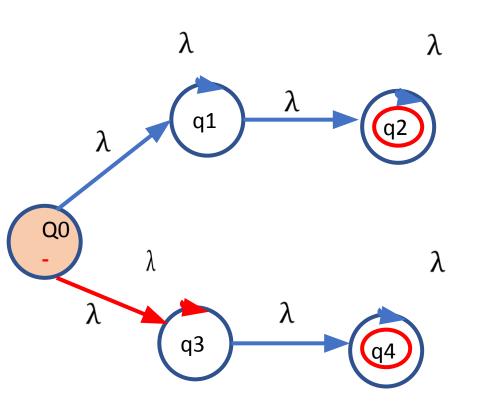
Transition Table

States	a	b
q_o	$\{q_1, q_{2,}q_4\}$	



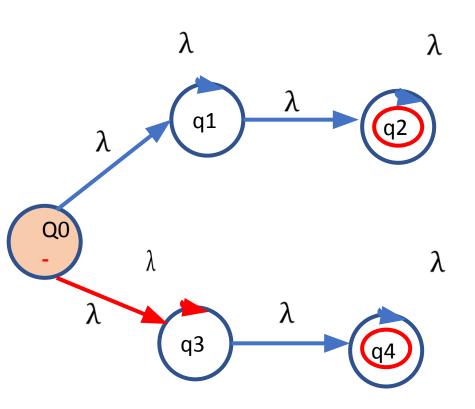
Transition Table

States	a	b
q_o	$\{q_1, q_2, q_4\}$	$\{q_2$



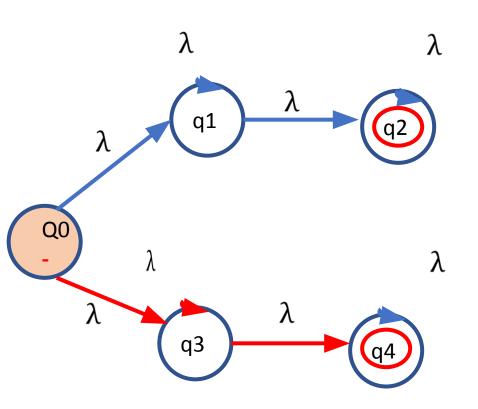
Transition Table

States	a	b
q_o	$\{q_1, q_{2,}q_4\}$	$\{q_{2,}$



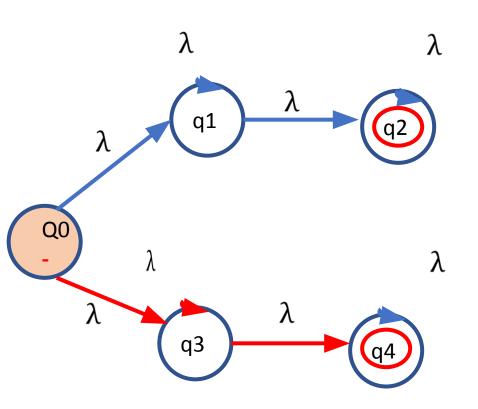
Transition Table

States	a	b
q_o	$\{q_1, q_2, q_4\}$	$\{q_2,q_3$



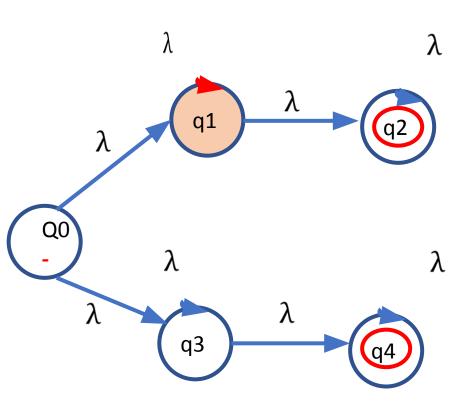
Transition Table

States	a	b
q_o	$\{q_1, q_2, q_4\}$	$\{q_2,q_3$



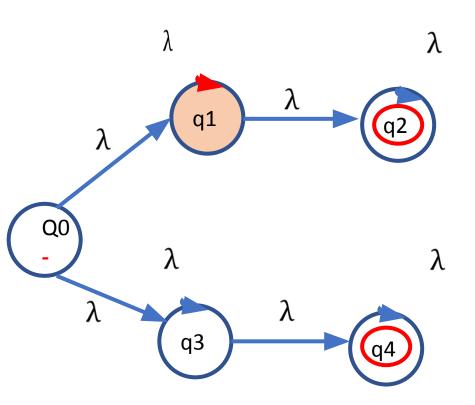
Transition Table

States	a	b
q_o	$\{q_1, q_2, q_4\}$	$\{q_2,q_3,q_4\}$



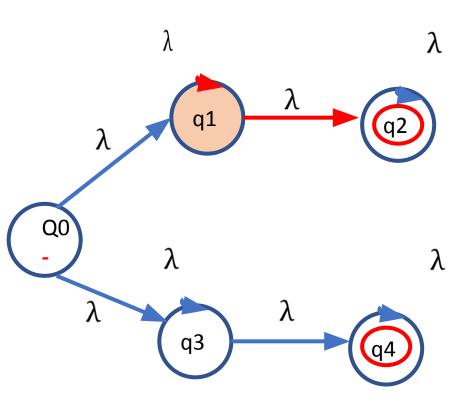
Transition Table

States	a	b
q_o	$\{q_1, q_2, q_4\}$	$\{q_2,q_3,q_4\}$
q_1		



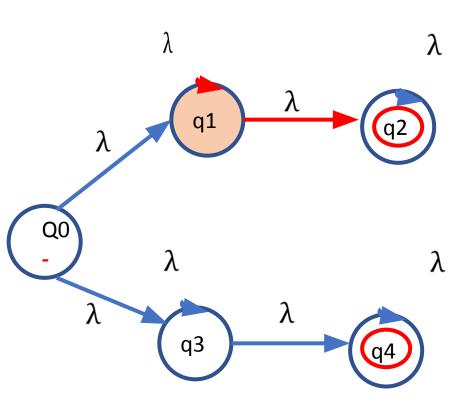
Transition Table

States	a	b
q_o	$\{q_1, q_2, q_4\}$	$\{q_2,q_3,q_4\}$
q_1	$\{q_1$	



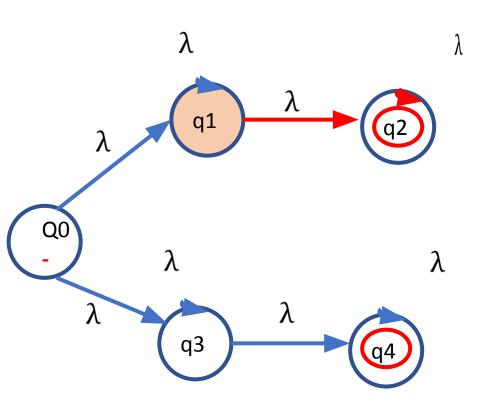
Transition Table

States	a	b
q_o	$\{q_1, q_{2,}q_4\}$	$\{q_2,q_3,q_4\}$
q_1	{ <i>q</i> ₁ ,}	



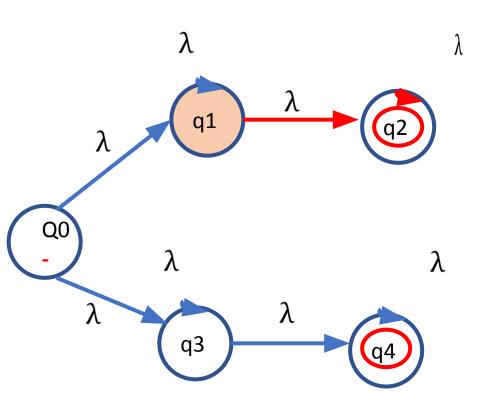
Transition Table

States	a	b
q_o	$\{q_1, q_2, q_4\}$	$\{q_2,q_3,q_4\}$
q_1	$\{q_1,q_2\}$	



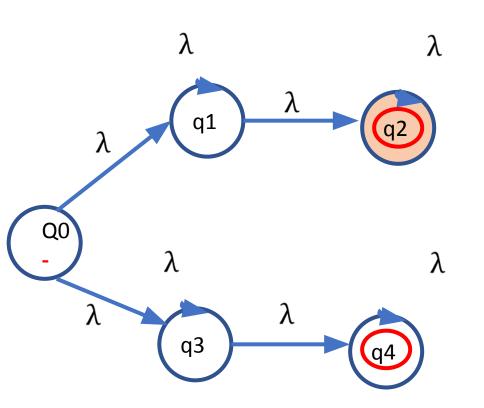
Transition Table

States	a	b
q_o	$\{q_1, q_2, q_4\}$	$\{q_2,q_3,q_4\}$
q_1	$\{q_1,q_2\}$	



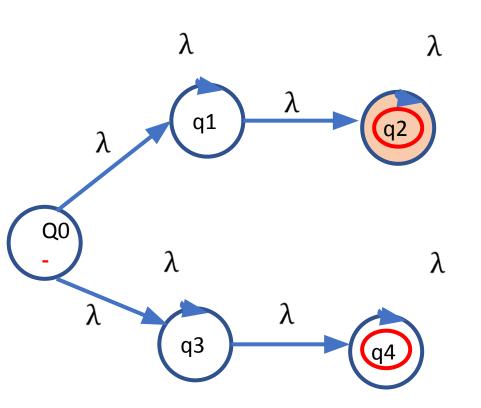
Transition Table

States	a	b
q_o	$\{q_1, q_2, q_4\}$	$\{q_2,q_3,q_4\}$
q_1	$\{q_1,q_2\}$	$\{q_{2}\}$



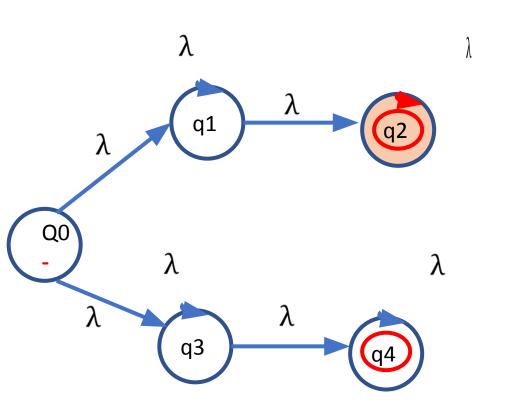
Transition Table

States	a	ь
q_o	$\{q_1, q_{2,}q_4\}$	$\{q_2,q_3,q_4\}$
q_1	$\{q_1,q_2\}$	$\{q_2\}$
q_2		



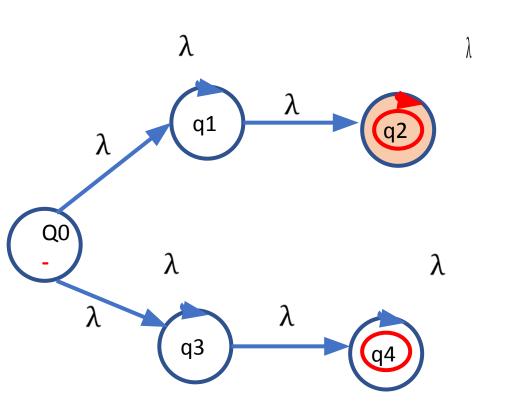
Transition Table

States	a	b
q_o	$\{q_1, q_{2,}q_4\}$	$\{q_2,q_3,q_4\}$
q_1	$\{q_1,q_2\}$	$\{q_2\}$
q_2	Ø	

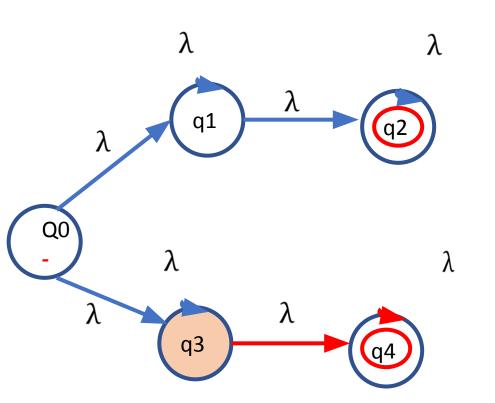


Transition Table

States	a	b
q_o	$\{q_1, q_{2,}q_4\}$	$\{q_2,q_3,q_4\}$
q_1	$\{q_1,q_2\}$	$\{q_2\}$
q_2	Ø	

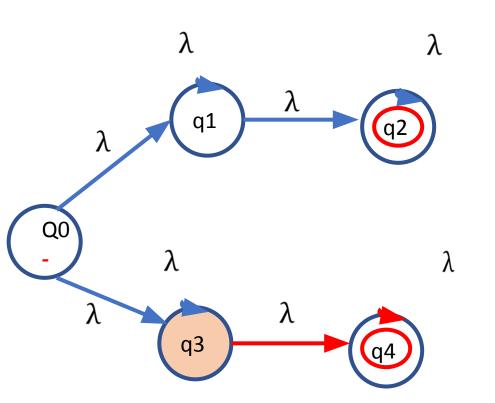


States	a	b
q_o	$\{q_1, q_{2,}q_4\}$	$\{q_2,q_3,\mathbf{q}_4\}$
q_1	$\{q_1,q_2\}$	$\{q_2\}$
q_2	Ø	{q ₂ }



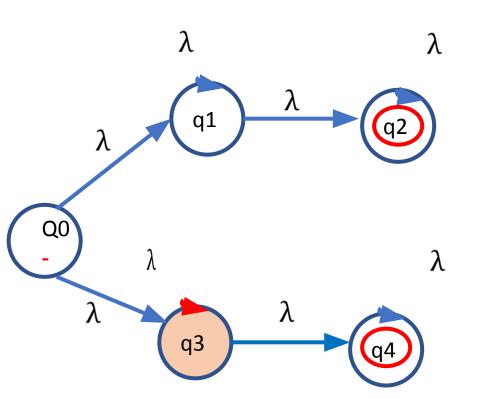
Transition Table

States	a	b
q_o	$\{q_1, q_{2,}q_4\}$	$\{q_2,q_3,q_4\}$
q_1	$\{q_1,q_2\}$	$\{q_{2}\}$
q_2	Ø	$\{q_{2}\}$
q_3		



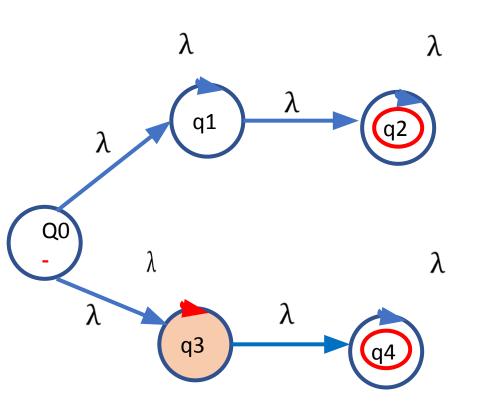
Transition Table

States	a	b
q_o	$\{q_1, q_{2,}q_4\}$	$\{q_2,q_3,q_4\}$
q_1	$\{q_1,q_2\}$	$\{q_{2}\}$
q_2	Ø	$\{q_2\}$
q_3	$\{q_4\}$	



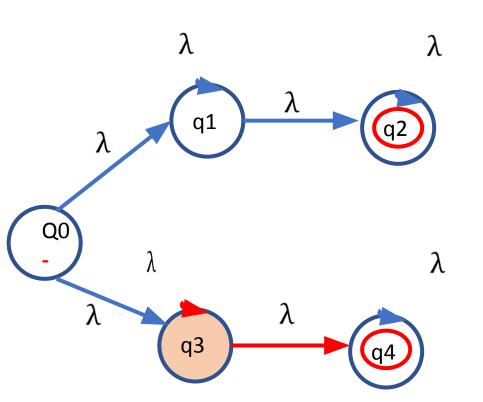
Transition Table

States	a	b
q_o	$\{q_1, q_{2,}q_4\}$	$\{q_2,q_3,q_4\}$
q_1	$\{q_1,q_2\}$	$\{q_{2}\}$
q_2	Ø	$\{q_{2}\}$
q_3	$\{q_4\}$	



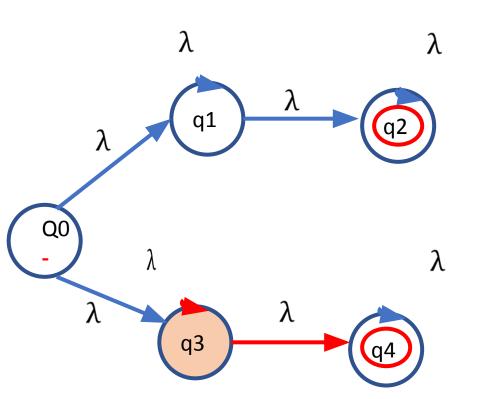
Transition Table

States	a	b
q_o	$\{q_1, q_{2,}q_4\}$	$\{q_2,q_3,q_4\}$
q_1	$\{q_1,q_2\}$	$\{q_{2}\}$
q_2	Ø	$\{q_{2}\}$
q_3	$\{q_4\}$	$\{q_3$



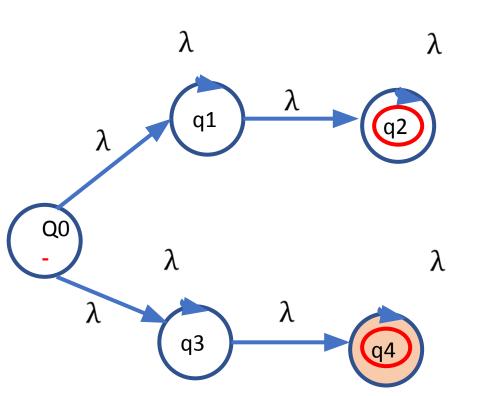
Transition Table

States	a	b
q_o	$\{q_1, q_{2,}q_4\}$	$\{q_2,q_3,q_4\}$
q_1	$\{q_1,q_2\}$	$\{q_{2}\}$
q_2	Ø	$\{q_{2}\}$
q_3	$\{q_4\}$	{ <i>q</i> ₃ ,}



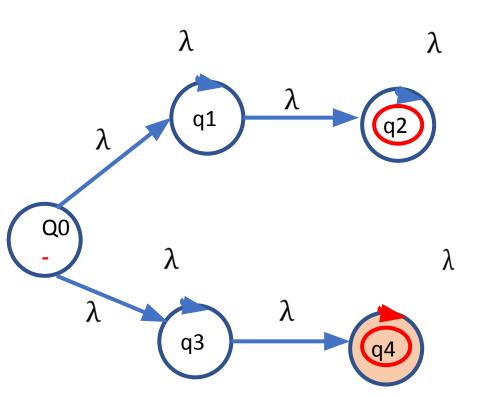
Transition Table

States	a	b
q_o	$\{q_1, q_{2,}q_4\}$	$\{q_2,q_3,q_4\}$
q_1	$\{q_1,q_2\}$	$\{q_2\}$
q_2	Ø	$\{q_{2}\}$
q_3	$\{q_4\}$	$\{q_3,q_4\}$



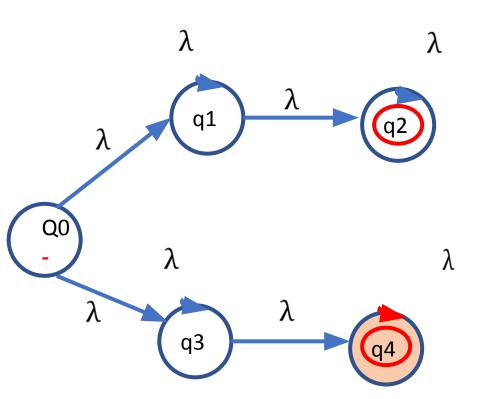
Transition Table

States	a	b
q_o	$\{q_1, q_{2,}q_4\}$	$\{q_2,q_3,q_4\}$
q_1	$\{q_1,q_2\}$	$\{q_{2}\}$
q_2	Ø	$\{q_{2}\}$
q_3	$\{q_4\}$	$\{q_3,q_4\}$
q_4		

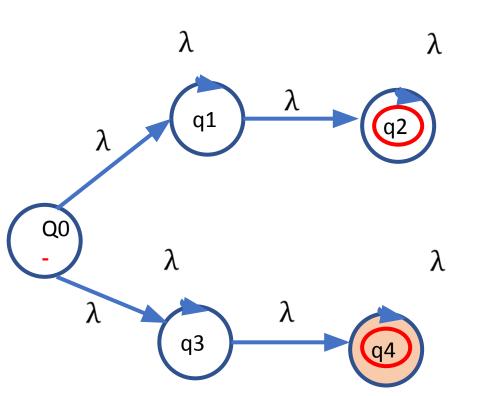


Transition Table

States	a	b
q_o	$\{q_1, q_{2,}q_4\}$	$\{q_2,q_3,q_4\}$
q_1	$\{q_1,q_2\}$	$\{q_2\}$
q_2	Ø	$\{q_2\}$
q_3	$\{q_4\}$	$\{q_3, q_4\}$
q_4		



States	a	b
q_o	$\{q_1, q_2, q_4\}$	$\{q_2,q_3,q_4\}$
q_1	$\{q_1,q_2\}$	$\{q_{2}\}$
q_2	Ø	$\{q_2\}$
q_3	$\{q_4\}$	$\{q_3,q_4\}$
q_4	$\{q_4\}$	



Transition Table

States	a	b
-q _o	$\{q_1, q_{2,}q_4\}$	$\{q_2,q_3,q_4\}$
q_1	$\{q_1,q_2\}$	$\{q_2\}$
q_2	Ø	$\{q_2\}$
+q3	$\{q_4\}$	$\{q_3, q_4\}$
$+q_4$	$\{q_4\}$	Ø

States	a	b
$-q_o$	$\{q_1, q_{2,}q_4\}$	$\{q_2,q_3,q_4\}$
q_1	$\{q_1,q_2\}$	{q ₂ }
q_2	Ø	{q ₂ }
+q3	$\{q_4\}$	$\{q_3, q_4\}$
+q4	$\{q_4\}$	Ø

States	a	В
$-q_o$	$\{q_1, q_2, q_4\}$	$\{q_2, q_3, q_4\}$

States	a	b
$-q_o$	$\{q_1, q_{2,}q_4\}$	$\{q_2,q_3,q_4\}$
q_1	$\{q_1,q_2\}$	{q ₂ }
q_2	Ø	$\{q_2\}$
+q ₃	$\{q_4\}$	$\{q_3,q_4\}$
+q4	$\{q_4\}$	Ø

States	a	В
$-q_o$	$\{q_1, q_2, q_4\}$	$\{q_2,q_3,q_4\}$
$\{q_1,q_2,q_4\}$	$\{q_1,q_2,q_4\}$	$\{q_2\}$

States	a	b
$-q_o$	$\{q_1, q_{2,}q_4\}$	$\{q_2,q_3,q_4\}$
q_1	$\{q_1,q_2\}$	$\{q_2\}$
q_2	Ø	$\{q_2\}$
+q3	$\{q_4\}$	$\{q_3,q_4\}$
+q4	$\{q_4\}$	Ø

States	a	В
$-q_o$	$\{q_1, q_2, q_4\}$	$\{q_2,q_3,q_4\}$
$\{q_1, q_2, q_4\}$	$\{q_1, q_2, q_4\}$	$\{q_{2}\}$

States	a	b
$-q_o$	$\{q_1, q_{2,}q_4\}$	$\{q_2,q_3,q_4\}$
q_1	$\{q_1,q_2\}$	$\{q_2\}$
q_2	Ø	$\{q_2\}$
+q3	$\{q_4\}$	$\{q_3,q_4\}$
+q4	$\{q_4\}$	Ø

States	a	В
$-q_o$	$\{q_1, q_2, q_4\}$	$\{q_2,q_3,q_4\}$
$\{q_1,q_2,q_4\}$	$\{q_1, q_2, q_4\}$	$\{q_{2}\}$
$\{q_2, q_3, q_4\}$	$\{q_4\}$	$\{q_2, q_3, q_4\}$

States	a	b
$-q_o$	$\{q_1, q_{2,}q_4\}$	$\{q_2,q_3,q_4\}$
q_1	$\{q_1,q_2\}$	$\{q_2\}$
q_2	Ø	{q ₂ }
+q3	$\{q_4\}$	$\{q_3,q_4\}$
+q4	$\{q_4\}$	Ø

States	a	В
$-q_o$	$\{q_1, q_{2,q_4}\}$	$\{q_2,q_3,q_4\}$
$\{q_1,q_2,q_4\}$	$\{q_1,q_2,q_4\}$	$\{q_2\}$
$\{q_2,q_3,q_4\}$	$\{q_4\}$	$\{q_2, q_3, q_4\}$
{q ₂ }	Ø	$\{q_{2}\}$

States	a	b
$-q_o$	$\{q_1, q_{2,}q_4\}$	$\{q_2,q_3,q_4\}$
q_1	$\{q_1,q_2\}$	$\{q_2\}$
q_2	Ø	$\{q_2\}$
+q ₃	$\{q_4\}$	$\{q_3,q_4\}$
+q4	$\{q_4\}$	Ø

States	a	В
$-q_o$	$\{q_1, q_2, q_4\}$	$\{q_2, q_3, q_4\}$
$\{q_1, q_2, q_4\}$	$\{q_1, q_2, q_4\}$	{q ₂ }
$\{q_2, q_3, q_4\}$	$\{q_4\}$	$\{q_2, q_3, q_4\}$
{q ₂ }	Ø	{q ₂ }

States	a	ь
$-q_o$	$\{q_1, q_{2,}q_4\}$	$\{q_2,q_3,q_4\}$
q_1	$\{q_1,q_2\}$	$\{q_2\}$
q_2	Ø	$\{q_2\}$
+q3	$\{q_4\}$	$\{q_3,q_4\}$
+q4	$\{q_4\}$	Ø

States	a	В
$-q_o$	$\{q_1, q_{2,q_4}\}$	$\{q_2,q_3,q_4\}$
$\{q_1,q_2,q_4\}$	$\{q_1,q_2,q_4\}$	$\{q_2\}$
$\{q_2,q_3,q_4\}$	$\{q_4\}$	$\{q_2, q_3, q_4\}$
{q ₂ }	Ø	{q ₂ }
$\{q_4\}$	$\{q_4\}$	Ø

States	a	b
$-q_o$	$\{q_1, q_{2,}q_4\}$	$\{q_2,q_3,q_4\}$
q_1	$\{q_1,q_2\}$	$\{q_2\}$
q_2	Ø	$\{q_2\}$
+q3	$\{q_4\}$	$\{q_3,q_4\}$
+q4	$\{q_4\}$	Ø

States	a	В
$-q_o$	$\{q_1, q_{2,q_4}\}$	$\{q_2,q_3,q_4\}$
$\{q_1,q_2,q_4\}$	$\{q_1,q_2,q_4\}$	$\{q_2\}$
$\{q_2, q_3, q_4\}$	$\{q_4\}$	$\{q_2, q_3, q_4\}$
{q ₂ }	Ø	$\{q_{2}\}$
$\{q_4\}$	$\{q_4\}$	Ø

States	a	b
$-q_o$	$\{q_1, q_{2,}q_4\}$	$\{q_2,q_3,q_4\}$
q_1	$\{q_1,q_2\}$	{q ₂ }
q_2	Ø	{q ₂ }
+q3	$\{q_4\}$	$\{q_3,q_4\}$
+q4	$\{q_4\}$	Ø

States	a	В
$-q_o$	$\{q_1, q_{2,q_4}\}$	$\{q_2,q_3,q_4\}$
$\{q_1,q_2,q_4\}$	$\{q_1,q_2,q_4\}$	$\{q_2\}$
$\{q_2,q_3,q_4\}$	$\{q_4\}$	$\{q_2, q_3, q_4\}$
$\{q_2\}$	Ø	$\{q_2\}$
$\{q_4\}$	$\{q_4\}$	Ø
Ø	Ø	Ø