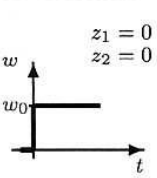
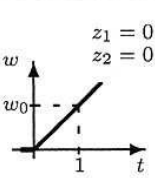
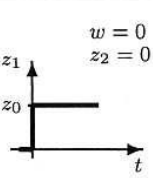
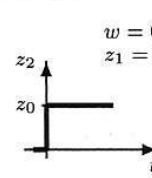
Regler $G_R(s)$		Regelstrecke $G_S(s)$	bleibende Regeldifferenz e_∞ für			
						
P	K_P	P-Typ	$\frac{1}{1+K_P \cdot K_S} \cdot w_0$	∞	$\frac{-K_S}{1+K_P \cdot K_S} \cdot z_0$	$\frac{-1}{1+K_P \cdot K_S} \cdot z_0$
I	$\frac{K_I}{s}$	entsprechend	0	$\frac{1}{K_I \cdot K_S} \cdot w_0$	0	0
PI	$K_P + \frac{K_I}{s}$		0	$\frac{1}{K_I \cdot K_S} \cdot w_0$	0	0
I_2	$\frac{K_I}{s^2}$	$K_S \cdot \frac{1+\ \ldots}{1+\ \ldots}$	0	0	0	0
P	K_P	I-Typ	0	$\frac{1}{K_S \cdot K_P} \cdot w_0$	$\frac{-1}{K_P} \cdot z_0$	0
I	$\frac{K_I}{s}$	entsprechend	0	0	0	0
PI	$K_P + \frac{K_I}{s}$	$\frac{K_S}{s} \cdot \frac{1+\ \ldots}{1+\ \ldots}$	0	0	0	0