

Formal Methods Project for System Verification Project

A dynamic server allocation for energy efficiency



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Introduction



Power consumption in data centres receive a huge concern by data centre providers.

- ▶ Find a trade-off between performance cost and saving energy;
- ▶ Model a (high/low) policy to control dynamically the powering on and off of the servers.

The system can basically be regarded as a multi-server queue.

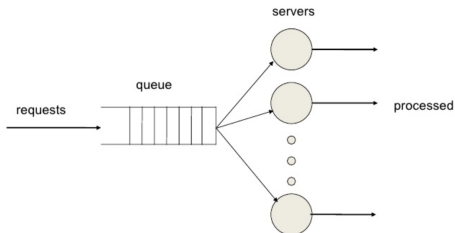


Figure: Multi server queue

- ▶ N servers of which $M < N$ static servers (always on);
- ▶ Alternating high/low job arrival rate.

Components and Activities of the System



- ▶ Q_i : Queue's current state, with $0 \leq i \leq n$, which represents the number of jobs in the system at the time i ;
- ▶ $Arrival_{high}$, $Arrival_{low}$: Represent the two possible jobs' arrival stream states (high or low);

- ▶ All the possible server's state are represented by:
 - ▶ *Server_{on}*: State in which the server is either active or idle;
 - ▶ *ServerPowering_{on}*: State in which the server is turning on;
 - ▶ *Server_{off}*: State in which the server is fully turned off;
 - ▶ *ServerPowering_{off}*: State in which the server is turning off;
 - ▶ *Server_{failOn}*: State in which the server encountered an error performing the power-up activity;
 - ▶ *Server_{failOff}*: State in which the server encountered an error performing the shutdown activity;
 - ▶ *Server_{static}*: State representing a server that is always active (M servers).

The set of possible actions that the *queue* component can perform are:

- ▶ **Service:** When a request is successfully elaborated and the job leaves the system (at a fixed rate of μ);
- ▶ **arrivalH:** When the arrival into the system occurs at high rate λ ;
- ▶ **arrivalL:** When the arrival into the system occurs at low rate ϵ .

The activities of the *arrival stream*, identified by the components $Arrival_{high}$ and $Arrival_{low}$, are modeled by the previously defined queue activities, i.e. **arrivalH** and **arrivalL**, and also by the switching actions between the high and low rate defined through the activities:

- ▶ **highPeriodEnd** at rate β ;
- ▶ **lowPeriodEnd** at rate γ .

The activities of the server are modeled by the previously defined activities **highPeriodEnd**, **lowPeriodEnd**, **service** and by new ones, such as:

- ▶ **powerup**: Used to turn on a server (η rate);
- ▶ **poweroff**: Used to turn off a server (ξ rate);
- ▶ **repair**: Used to fix the server in case of error/fault (σ rate);

- ▶ **Queue** will accept the incoming jobs, regardless the type of arrival, up until the queue is full ($i \leq n$), plus every time a job is served the queue index counter is decreased by 1;
- ▶ **Arrival Stream** will be in charge of detecting and switching accordingly to the appropriate arrival rate stream situation (high or low);
- ▶ **Server** will power-up or down accordingly to the high or low jobs arrival. To keep in mind that we have considered also M static servers.

PEPA Components of the System



$$Q_0 \stackrel{\text{def}}{=} (\text{arrival}H, \lambda).Q_1 + (\text{arrival}L, \epsilon).Q_1$$

$$Q_1 \stackrel{\text{def}}{=} (\text{arrival}H, \lambda).Q_2 + (\text{arrival}L, \epsilon).Q_2 + (\text{service}, \mu).Q_1$$

$$\vdots$$

$$Q_i \stackrel{\text{def}}{=} (\text{arrival}H, \lambda).Q_{i+1} + (\text{arrival}L, \epsilon).Q_{i+1} + (\text{service}, \mu).Q_{i-1}$$

$$\vdots$$

$$Q_n \stackrel{\text{def}}{=} (\text{service}, \mu).Q_{n-1}$$

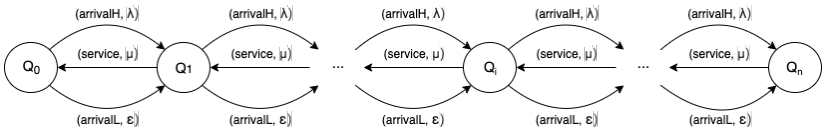


Figure: Queue PEPA derivation graph



$$\begin{aligned} \textit{Arrival}_{high} &\stackrel{\text{def}}{=} (\textit{arrival}H, \lambda). \textit{Arrival}_{high} + (\textit{highPeriodEnd}, \beta). \textit{Arrival}_{low} \\ \textit{Arrival}_{low} &\stackrel{\text{def}}{=} (\textit{arrival}L, \epsilon). \textit{Arrival}_{low} + (\textit{lowPeriodEnd}, \gamma). \textit{Arrival}_{high} \end{aligned}$$

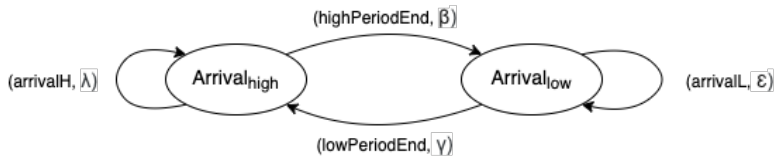


Figure: Arrival Stream PEPA derivation graph

$$\begin{aligned}
 \text{ServerPowering}_{on} &\stackrel{\text{def}}{=} (\text{powerup}, \eta * (1 - \rho)).\text{Server}_{on} + (\text{powerup}, \eta * \rho).\text{Server}_{failOn} \\
 \text{Server}_{on} &\stackrel{\text{def}}{=} (\text{service}, \mu).\text{Server}_{on} + (\text{highPeriodEnd}, \beta).\text{ServerPowering}_{off} \\
 \text{ServerPowering}_{off} &\stackrel{\text{def}}{=} (\text{poweroff}, \xi * (1 - \rho)).\text{Server}_{off} + (\text{poweroff}, \xi * \rho).\text{Server}_{failOff} \\
 \text{Server}_{off} &\stackrel{\text{def}}{=} (\text{lowPeriodEnd}, \gamma).\text{ServerPowering}_{on} \\
 \\
 \text{Server}_{static} &\stackrel{\text{def}}{=} (\text{service}, \mu).\text{Server}_{static} \\
 \text{Server}_{failOn} &\stackrel{\text{def}}{=} (\text{repair}, \sigma).\text{Server}_{on} \\
 \text{Server}_{failOff} &\stackrel{\text{def}}{=} (\text{repair}, \sigma).\text{Server}_{off}
 \end{aligned}$$

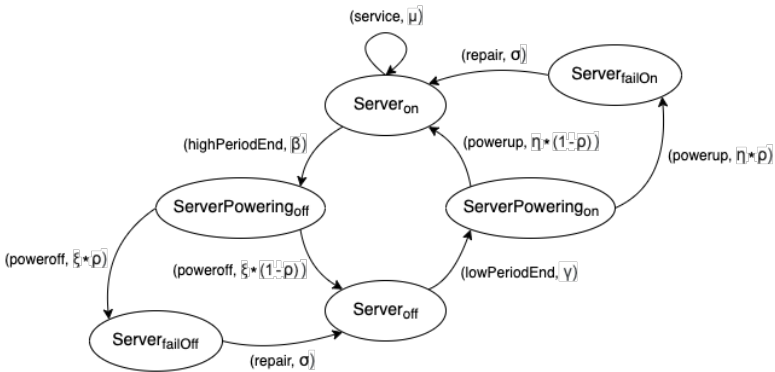


Figure: Server PEPA derivation graph

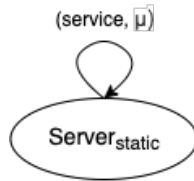


Figure: Static server PEPA derivation graph

Entire System Expressed in PEPA



$$System \stackrel{\text{def}}{=} ((Arrival_{high} \boxtimes_K Server_{on} \boxtimes_K \dots \boxtimes_K Server_{on}) \boxtimes_Z Server_{static}[M]) \boxtimes_L Q_0$$

Where respectively the sets K, Z, L are defined as follows:

- ▶ $K = \{highPeriodEnd\};$
- ▶ $Z = \emptyset;$
- ▶ $L = \emptyset.$

Derivation Graph of the System



$$Arrival_{high} \bowtie_{\{highPeriodEnd\}} Server_{on}$$

12 states			
1	Arrival_high	Server_on	0.7511560761484473
2	Arrival_low	ServerPowering_off	0.03755780380742236
3	Arrival_high	ServerPowering_off	0.037557803807422366
4	Arrival_low	Server_off	0.017839956808525625
5	Arrival_low	Server_failOff	0.0018778901903711179
6	Arrival_high	Server_off	0.0572756508063191
7	Arrival_high	Server_failOff	0.005633670571113353
8	Arrival_low	ServerPowering_on	0.00891997840426281
9	Arrival_high	ServerPowering_on	0.0661956292105819
10	Arrival_low	Server_on	0.00847397948404967
11	Arrival_low	Server_failOn	4.459989202131406E-4
12	Arrival_high	Server_failOn	0.007065561841271393

Figure: Space State View for the system equation - PEPA Eclipse plug-in

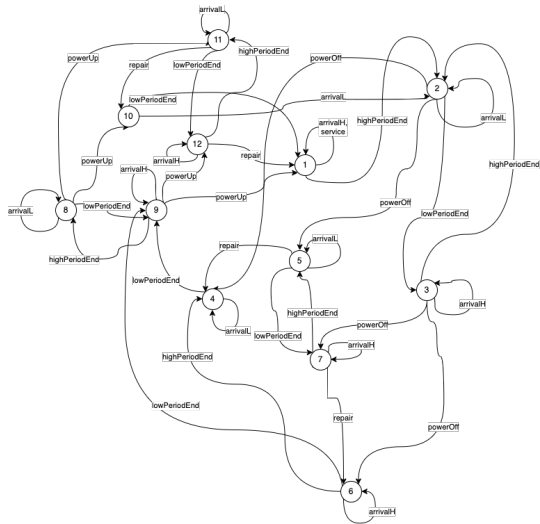


Figure: System derivation graph

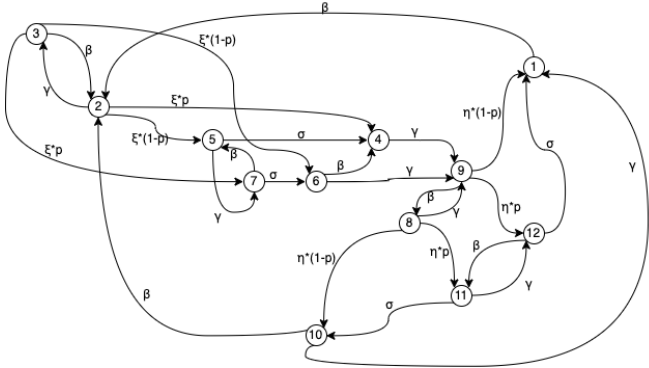


Figure: CTMC representation - State transition diagram



Evaluation



Different types of performance measures can be derived from the steady state distribution of a Markov Process:

- ▶ State-based measures : correspond to the probability that a model is in a state (e.g. utilisation);
- ▶ Rate-based measures : those which correspond to the predicted rate at which some event occur (e.g. throughput);
- ▶ Response-time.

When the model is in steady state we have:

- ▶ the total probability flux out of each state is equal to the total probability flux into the state;
- ▶ π_i is the probability that the model is in state x_i
- ▶ $\sum_{x_i \in S} \pi_i = 1$ for π_i is a probability distribution.

The collection of the equations expressing the steady state condition for each state x_i of the model is resumed in the Global Balance equation:

$$\pi Q = 0$$

where Q is the Infinitesimal Generator matrix.



$$\left\{ \begin{array}{l} \pi_1 \cdot \beta = \pi_9 \cdot (\eta \cdot (1 - \rho)) + \pi_{10} \cdot \gamma + \pi_{12} \cdot \sigma \\ \pi_2 \cdot (\gamma + \xi) = \pi_1 \cdot \beta + \pi_3 \cdot \beta + \pi_{10} \cdot \beta \\ \pi_3 \cdot (\beta + \xi) = \pi_2 \cdot \gamma \\ \pi_4 \cdot \gamma = \pi_2 \cdot (\xi \cdot (1 - \rho)) + \pi_5 \cdot \sigma + \pi_6 \cdot \beta \\ \pi_5 \cdot (\sigma + \gamma) = \pi_2 \cdot (\xi \cdot \rho) + \pi_7 \cdot \beta \\ \pi_6 \cdot (\beta + \gamma) = \pi_3 \cdot (\xi \cdot (1 - \rho)) + \pi_7 \cdot \sigma \\ \pi_7 \cdot (\beta + \sigma) = \pi_3 \cdot (\xi \cdot \rho) + \pi_5 \cdot \gamma \\ \pi_8 \cdot (\gamma + \eta) = \pi_9 \cdot \beta \\ \pi_9 \cdot (\beta + \eta) = \pi_4 \cdot \gamma + \pi_6 \cdot \gamma + \pi_8 \cdot \gamma \\ \pi_{10} \cdot (\beta + \gamma) = \pi_8 \cdot (\xi \cdot (1 - \rho)) + \pi_{11} \cdot \sigma \\ \pi_{11} \cdot (\sigma + \gamma) = \pi_8 \cdot (\xi \cdot \rho) + \pi_{12} \cdot \beta \\ \pi_{12} \cdot (\sigma + \beta) = \pi_9 \cdot (\xi \cdot \rho) + \pi_{11} \cdot \gamma \\ \pi_1 + \pi_2 + \pi_3 + \pi_4 + \pi_5 + \pi_6 + \pi_7 + \pi_8 + \pi_9 + \pi_{10} + \pi_{11} + \pi_{12} = 1 \end{array} \right.$$

Figure: Global balance system equations



$$Q = \begin{bmatrix} -\beta & \beta & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & -(\gamma + \xi) & \gamma & \xi * (1 - \rho) & \xi * \rho & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & \beta & -(\beta + \xi) & 0 & 0 & \xi * (1 - \rho) & \xi * \rho & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & -\gamma & 0 & 0 & 0 & 0 & \gamma & 0 & 0 & 0 \\ 0 & 0 & 0 & \sigma & -(\sigma + \gamma) & 0 & \gamma & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & \beta & 0 & -(\beta + \gamma) & 0 & 0 & \gamma & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & \beta & \sigma & -(\beta + \sigma) & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & -(\gamma + \eta) & \gamma & \eta * (1 - \rho) & \eta * \rho & 0 \\ \eta * (1 - \rho) & 0 & 0 & 0 & 0 & 0 & 0 & \beta & -(\beta + \eta) & 0 & 0 & \eta * \rho \\ \gamma & \beta & 0 & 0 & 0 & 0 & 0 & 0 & 0 & -(\beta + \gamma) & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & \sigma & -(\sigma + \gamma) & \gamma \\ \sigma & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & \beta & -(\sigma + \beta) \end{bmatrix}$$

Figure: Infinitesimal generator matrix

Exit rate and sojourn time are two related measures:

- ▶ Exit rate: $q_i = \sum_{x_j \in S, j \neq i} q_{ij}$
- ▶ Sojourn time: $1/q_i$.

The Sojourn time in a state x_i is exponentially distributed with parameter q_i

$$q(1) = \beta$$

$$q(2) = \gamma + \xi$$

$$q(3) = \beta + \xi$$

$$q(4) = \gamma$$

$$q(5) = \sigma + \gamma$$

$$q(6) = \beta + \gamma$$

$$q(7) = \beta + \sigma$$

$$q(8) = \sigma + \eta$$

$$q(9) = \beta + \eta$$

$$q(10) = \beta + \gamma$$

$$q(11) = \sigma + \gamma$$

$$q(12) = \sigma + \beta$$

Figure: Exit rates



$$ST(1) = \frac{1}{\beta}$$

$$ST(2) = \frac{1}{\gamma + \xi}$$

$$ST(3) = \frac{1}{\beta + \xi}$$

$$ST(4) = \frac{1}{\gamma}$$

$$ST(5) = \frac{1}{\sigma + \gamma}$$

$$ST(6) = \frac{1}{\beta + \gamma}$$

$$ST(7) = \frac{1}{\beta + \sigma}$$

$$ST(8) = \frac{1}{\sigma + \eta}$$

$$ST(9) = \frac{1}{\beta + \eta}$$

$$ST(10) = \frac{1}{\beta + \gamma}$$

$$ST(11) = \frac{1}{\sigma + \gamma}$$

$$ST(12) = \frac{1}{\sigma + \beta}$$

Figure: Sojourn times

The *utilisation* measure is the total probability that the model is in one of the states in which the resource is in use.

$$U_{Arrival_{high}} = \pi_1 + \pi_3 + \pi_6 + \pi_7 + \pi_9 + \pi_{12}$$

$$U_{Server_{on}} = \pi_1 + \pi_{10}$$

Evaluation of the System Using the PEPA Eclipse Plug-In



```

1  l = 50.0;
2  e = 10.0;
3  m = 10.0;
4  b = 10.0;
5  g = 10.0;
6  n = 100.0;
7  r = 0.1;
8  x = 100.0;
9  s = 1.0;
10
11 Q0 = (arrivalH,l).Q1 + (arrivalL,e).Q1;
12 Q1 = (arrivalH,l).Q2 + (arrivalL,e).Q2 + (service,m).Q0;
13 Q2 = (service,m).Q1;
14
15 Arrival_high = (arrivalH,l).Arrival_high + (highPeriodEnd,b).Arrival_low;
16 Arrival_low = (arrivalL,e).Arrival_low + (lowPeriodEnd,g).Arrival_high;
17
18 ServerPowering_on = (powerup, n * (1-r)).Server_on + (powerup, n*r).Server_failOn;
19 Server_on = (service,m).Server_on + (highPeriodEnd,b).ServerPowering_off;
20 ServerPowering_off = (poweroff,x*(1-r)).Server_off + (poweroff,x*r).Server_failOff;
21 Server_off = (lowPeriodEnd,g).ServerPowering_on;
22
23 Server_static = (service,m).Server_static;
24 Server_failOn = (repair,s).Server_on;
25 Server_failOff = (repair,s).Server_off;
26
27 ((Arrival_high <highPeriodEnd> Server_on <highPeriodEnd> Server_on <highPeriodEnd> Server_on) <>
   Server_static <> Server_static <> Server_static ) <> Q0

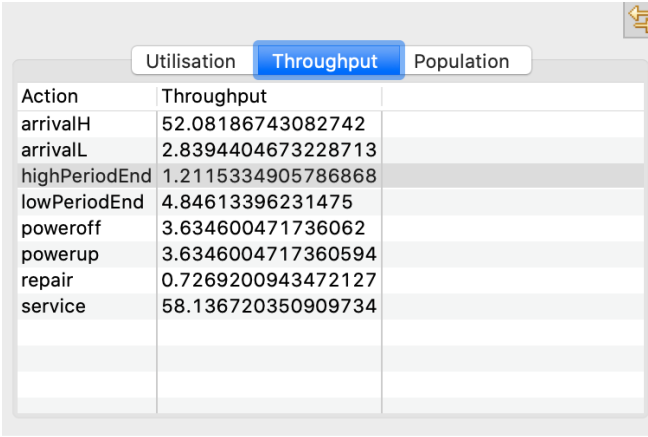
```

Figure: Code of the system expressed using PEPA Eclipse plug-in

To point out that we have modeled a system having $N = 6$ servers, which 3 of them are *dynamic* and the rest are *static* (i.e. always on).
For complexity reasons the queue capacity has been bounded at 2.

Finally the various rates were set as follows:

- ▶ **High arrival rate:** 50;
- ▶ **Low arrival rate:** 10;
- ▶ **Powering-up and down:** 100 in equally *high* and *low* period of job arrivals.



The screenshot shows a software interface with three tabs: 'Utilisation', 'Throughput' (which is selected and highlighted in blue), and 'Population'. Below the tabs is a table with three columns: 'Action', 'Throughput', and an empty column. The table contains eight rows of data, each representing a different system action and its corresponding throughput value.

Utilisation	Throughput	Population
Action	Throughput	
arrivalH	52.08186743082742	
arrivalL	2.8394404673228713	
highPeriodEnd	1.2115334905786868	
lowPeriodEnd	4.84613396231475	
poweroff	3.634600471736062	
powerup	3.6346004717360594	
repair	0.7269200943472127	
service	58.136720350909734	

Figure: Throughput evaluation of the system

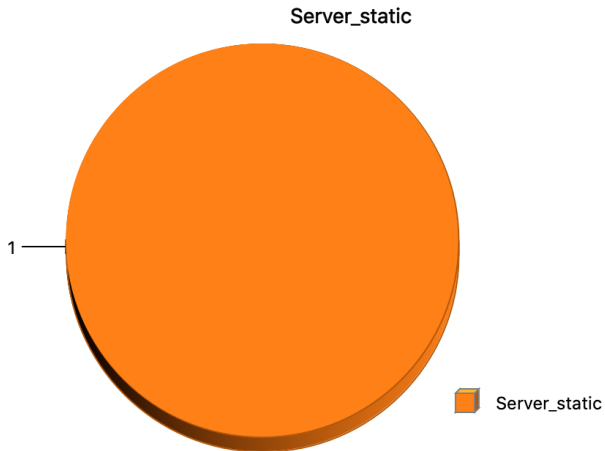


Figure: Utilization of the Static Server component

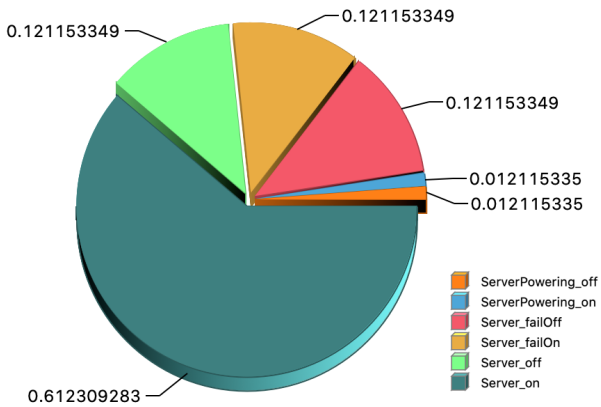


Figure: Utilisation of the Dynamic Server component



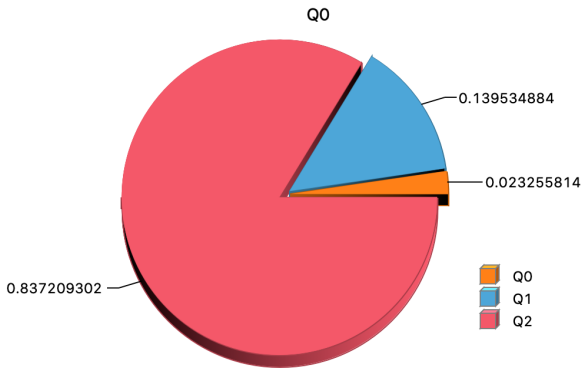


Figure: Utilisation of the Queue component

