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Reverse-Engineering



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Abstract

Users of interactive visual analytics tools naturally come up with analysis strategies. Deriving those strategies is a challenging research topic. Current approaches primarily log interactions, such as click events with the system, to replicate the analysis workflow. However, visual analytics tools often do not make the raw data easily accessible. We propose that there is a way of using simple bitmap images or even sampled video sequences to get these click events. We first capture where text is in an image with a CNN and then use this information to compute bounding boxes for each letter, merge the boxes to words and classify the role of the boxes. We also classify the mark type of the chart, with the well known Alexnet [5], with all this information we can infer the specifications of each bitmap chart. We then can use this information to infer what changed from one picture to another.

We also evaluate our method of text localization and recognition with examples, see common pitfalls, and we check the performance of you mark classifier with our testset.

The contribution of this thesis is a slightly different approach compared the paper by Poco and Heer [10] on a very similar topic, and the first tries to apply this process to generate a pipeline to automatically extract click events, by only looking at different states of visualizations,

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1 Introduction

Users of interactive visual analytics tools instinctively come up with strategies to analyze data with these tools. Deriving such strategies is a difficult research topic. Most of the time current approaches rely on manually logging events, such as mouse clicks and movements, to copy a humans workflow, often this workflow logs are not accessable for researchers. We propose, that there is a way of using

However, visual analytics tools often do not make the raw data easily accessible. We propose that there is a way of using simple bitmap images or even sampled video sequences to get these click events. We first capture where text is in an image with a CNN and then use this information to compute bounding boxes for each letter, merge the boxes to words and classify the role of the boxes. We also classify the mark type of the chart, with all this information we can infer the data type and range. We then can use this information to infer what changed from one picture to another.

The primary contribution of our work is an approach to extract information from bitmap images to help researchers in analyzing human-computer interactions, just from screenshots or videos of a person performing tasks. To get this interactions, we first have to look at the states of the visualization image and transform it into text. For this we first use a CNN to get the mark type of the image, then we use another CNN and some Connected components algorithms and Trees to get bounding boxes of the words, and then we use a random forest to classify the role of the box. Then we can put this all together into a python dictionary format to show the specification of the visualization. With this specification we can then easily see what changed from one frame to another, by comparing the differences of the dictionaries.

Section 2 of this thesis covers related work. Next in the methods section, our approach and implementation details are described. Afterwards, the results of our implementation are shown and evaluated, with quantitative metrics and examples. Afterwards, the limitations of this thesis and future work are discussed. Finally in the conclusion, a summary of the obtained results is given.

2 Related Work

In this section, we discuss previous approaches to the three areas of related reverse engineering visualizations, which are chart image classification, text detection and recognition and data extraction from charts.

2.1 Chart Type Classification

Image classification of computer generated charts is a well studied problem, some papers propose that algorithms used in classification of natural scenes can be applied [16] [14] and others propose specialized techniques for classification [6].

Prasad et al.[11] considered five categories in their approach for classifying chart images. They classified bar-charts, curveplots, pie-charts, scatter-plots and surface-plots, by introducing two new features for representing structural information and using Histograms of Oriented Gradients (HOG) and the Scale Invariant Feature Transform (SIFT) descriptors to characterize the local shape, with this they represent the chart image as a set of feature vectors, which they then classify using a SVM.

Savva et al. [13] developed a classification method which first extracts low-level image features using a SVM and then they extract text features and use OCR, with their method they achive an accuracy of over 96% on the categories Area Graphs, Bar Graphs, Curve Plots, Maps, Pareto Charts, Pie Charts, Radar Plots, Scatter Plots, Tables and Venn Diagrams.

Jung et al. [3] classify the chart type by using a deep learning in their approach.

Tang et al. [15] developed DeepChart, they first use convolutional networks to extract deep hidden features of charts and then they use deep belief networks to classify the charts based on their deep hidden features. They classify the charts into 5 different categories, and their approach was evaluated against other existing methods.

2.2 Text Localization and Recognition

Chart images contain graphical elements and text, the content and the position. These textual components can be brought out of the picture using text localization, detection and recognition methods.

Kataria et al. [4] show how data and text can be automatically extracted from chart images, by extracting connected components and treating the components as candidates for text characters. Components with a too large area are removed and they merge letters to words by considering the distance between the components.

Poco and Heer [10] created a less error prone approach, than Kataria et al. [4], by using a CNN to generate a heatmap which they use to remove non-text pixel. Poco and Heer [10] generated the heatmap using prior work from Moritz [7], he generates the heatmap using Darknet [12] and lots of self collected training data.

2.3 Text Role Classification

The task of identifying the role a text plays in a chart, like axis label or legend label, was used mostly for creating better search results in search engines, but is also vital for reverse engineering visualizations.

In their search engine improvement Chen et al. [1] use bounding box feature vectors for classification and Choudhury et al. [2] used text bounding boxes and text content for a similar task. Poco and Heer [10] used a similar approach, but without the text content, since the OCR error would be further propagate through their method. We also followed a similar approach.

3 Method

This section shows all steps and implementation details, we used to obtain the results of chapter 4. Firstly, the text localization method is described, then text role classification and mark classification. Things like evaluation metrics are described right before they are used.

3.1 Text Localization

The first task we had to solve was to localize the text, since Poco and Heer [10] already created a well working way for text localization, we tried to use their code, but since some files in their github repository were missing, we adapted their approach as well as well as we could with our own code and in doing so we also learned some interesting things about the code, which we will mention in more detail later.

3.1.1 Preprocessing

Our Method starts by padding the original bitmap visualization, to a square, and then we either increase or decrease its size to fit 1200x1200 pixels, afterwards the image gets binarized using Otsu's threshold [8], this threshold assumes each pixel is either foreground or background and tries maximizing inter-class variance to get the threshold. An example of this step can be seen in figure 3.1b.

3.1.2 Heatmap

We generated our heatmap using almost the same CNN Moritz used in his project domoriz label generator [7], using his net would be impractical, since it was trained with Darknet [12]. We only left out the croping layer, because it was not needed since our input images have the same input size and shape. Our dataset for training this heatmap was collected using the data provided by Moritz on his "Amazon Web Services S3 Bucket", and we only used the acl anthology part of the data, because the arxiv data would have been more than we could store on our computer. In Figure 3.1c an example heatmap is shown.

This heatmap is then used to remove non text pixels, to do this we resized the heatmap to the same size as the preprocessed image and then ran the marching squares method to find constant valued contours, from the original image we then kept everything inside the contours and everything else was deleted, the result of this can be seen in figure 3.1d. We decided to do this differently to the approach of Poco and Heer [10], because it was more intuitive this way, and we could later on change some contour finding values easily, to make the contours more slim or wide, which can change the outcome of the entire text localization step.

3.1.3 Connected Components

We decided to run a connected components algorithm to find characters in the image, from this algorithm we get bounding boxes for each connected component in the image. To filter out boxes which are very unlikely to be actual letters, we delete boxes where width/height is smaller than 0.1 or bigger than 10, another filter criterion was, that the area of the box had to be between 4 and 4000, this proved to make the most sense in our experiments, and it also makes sense intuitively, because if a letter would have less than 4 pixels in a 1200×1200 , it would only make up 1/360000 of the image which would be somewhat unreadable, and on the other side the letter can maximally take 1/360 of an image. An example of such cases can be seen in Figure 3.2, where at the top left a slightly to big "8" is displayed and on the bottom left a 4 pixel i is displayed, but it is almost invisible, because it is so small.

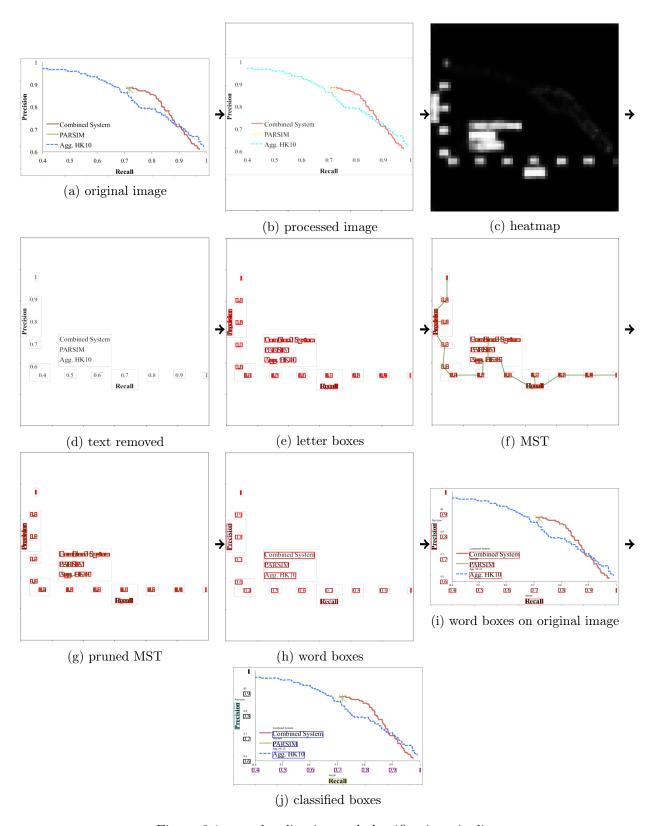


Figure 3.1: text localization and classification pipeline

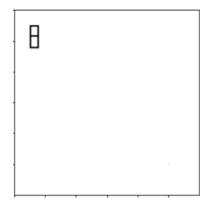


Figure 3.2: example invalid letters

3.1.4 MST

To make bounding boxes for the words of the boxes we have from the letters, we created a minimal spanning tree (MST) with Kruskal's algorithm, to do this we used the distance between the letters as the edge weight and the letters as Nodes. In Figure 3.1f such a minimal spanning tree is displayed

3.1.5 Pruning

To isolate words we decided to additionally prune the MST, we defined 3 criteria for removing edges:

- edges that are too long
 - To find edges which are to long, we created a set with all candidate characters and took the most common height of a box, since normally most characters are upright in a visualization this should give a good estimate of character height, we then discard edges which are smaller than 1.5l. In the approach by Poco and Heer [10] they made a set of all character heights and widths, but in our experiments we realized, that the most common element of this is character width, though this would have also worked, with the pruning step, we decided to go with character height.
- edges which are not aligned
 - To find edges which were not aligned for each edge we look at the bounding boxes, so if the bounding boxes overlap either horizontally or vertically more than the "height of the smaller box"/2 we count them as aligned, and if the boxes are not aligned we remove the edge.
- edges which lead to different colors
 - To filter out some bullet points before words, we remove edges which lead to different colors.
 We first calculated the CIE LAB color for each pixel in a letter, and then we delete the edge if the CIEDE2000 color difference is bigger than 20

3.1.6 Merging Boxes

To create word boxes from the letter boxes we look at every chain of connections and create the word box of the most outer part of each letter box, an example of this can be seen in Figure 3.1g and Figure 3.1h.

3.1.7 OCR

To recognize which characters and words are in the bounding boxes, we first rescaled the word box with the factor 3 in order to increaze the resolution, which should help to make the performance of our optical character recognition (OCR) Tesseract, better. Because we also get a confidence score from Tesseract, we rotate the image by 0,90 and 270 degrees and take the rotation with the highest confidence for the final prediction. If the highest confidence is below 25 we discard a box, because then it is really unlikely to be a word. We also noticed, that the OCR engine often confuses a single '0', 'o' or '1' for a 'O', 'I' or '|', since it is way more likely to be a number than a vowel, because often a axis starts or ends at 0 or 1, we decided to switch every single 'O' or 'o' to '0' and 'I' to '1'.

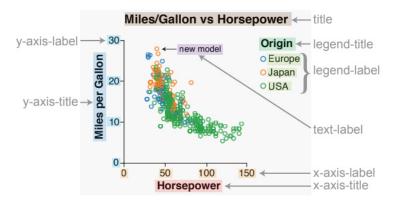


Figure 3.3: example text roles from [10]

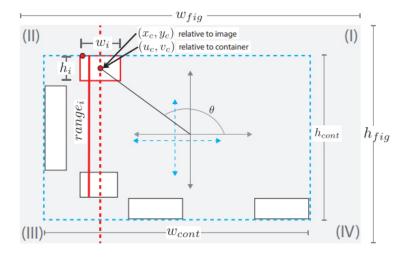


Figure 3.4: bounding box features from [10]

3.2 Text Role Classification

The second task we had to solve is to now classify the role of the localized text in the visualization, we decided to use the same 8 types Poco and Heer [10] used in their paper, an example can be seen in Figure 3.3. We calculated the role of each box by first calculating from features which we then input into a random forrest. We decided on using a random forrest classifier instead of the SVM classifier Poco and Heer [10] used, because we were not satisfied with the results we got from the SVM and the random forrest classifier worked the best, when looking at actual examples, where we got the word boxes from the earlier method.

3.2.1 Feature Calculation

Because the approach with the calculated features worked really well for Poco and Heer [10] and their data was useable, we decided to keep it, but we did not understand the calculation of certain features 100%, therefore we just left some features out and did not feed them into the SVM, when comparing the SVM with less features and the original amount of features we only noticed a drop in F1 score from around 98% to around 97% which we thought was still good.

The features we used are:

- normed x coordinate
 - $-x_c/w_fig$
- normed y coordinate
 - $-y_c/h_fig$
- aspect ratio
 - w_i/h
- quadrant
 - Figure 3.4 illustrates this concept well, the roman numerals in the brackets are the quadrant numbers, and the gray origin of the coordinates, used for θ in the middle of the figure can be seen as the border from one quadrant to another.
- normed container height
 - $-h_cont/h_fig$
- normed container width
 - w_cont/w_fig
- normalized center x-coordinate relative to the container
 - $-u_{\epsilon}$
- normalized center y-coordinate relative to the container
 - $-v_c$
- vertical score
 - Vertical score is defined as the number of all vertically intersecting boxes, with the current box divided by the number of all boxes we found in the picture. For example in Figure 3.4 the red box intersects with another box and itself vertically, therefore its verticals score is 2/5. This is conflicting to how Poco and Heer [10] described this feature in their publication, but that was how i got closest to their training data.
- horizontal score
 - same as vertical score, but horizontally

```
{'width': 861,
  'height': 534,
  'chart type': 'line_chart',
  'mark type': 'line',
  'title'.''
   'title':
                                                                                                                                                                        0.9
   'encoding': {'x': {'field': 'Recall',
   'axis': {'title': 'Recall'},
   'type': 'quantitive',
                                                                                                                                                                  Precision
       ans. { the . Netall },
'type': 'quantitive',
'scale': {'labels': ['(0.4', '0.5', '0.6', '0.7', '0.8', '0.9', '|'],
'values': [0.5, 0.6, 0.7, 0.8, 0.9],
                                                                                                                                                                        0.8
        'range': [0.5, 0.9],
'type': 'linear'}},
    'type': 'linear'},
'y': {'field': 'Precision',
'axis': {'title': 'Precision'},
'type': 'quantitive',
                                                                                                                                                                                                Combined System
                                                                                                                                                                        0.7
                                                                                                                                                                                               PARSIM
        type': 'quantitive',
scale': {'labels': ['|', '60', '0.8', '0.7', '0.6'],
'values': [60.0, 0.8, 0.7, 0.6],
                                                                                                                                                                                               Agg. HK10
                                                                                                                                                                        0.6
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                                                                                                                                                                                                    0.5
                                                                                                                                                                                                                                             0.7
                                                                                                                                                                                                                                                                                       0.9
                                                                                                                                                                               0.4
        'range': [0.6, 60.0],
'type': 'undefined'}}}}
                                                                                                                                                                                                                                          Recall
```

Figure 3.5: example specification

3.3 Mark Classification

Another vital part of a chart specification is the mark type, in general there are 3 types of marks areas, lines and points. For our purposes we decided to make a classifier which classifies lines, points, bars and areas.

3.3.1 Dataset

We got our dataset from the github repository of the paper, by Poco and Heer [10], where they shared a google drive link to download some of the data they used for their model. The classes were pretty imbalanced, we had 501 bar charts, 550 line charts, 292 scatterplots, 153 area charts. Before feeding the images into the model, we also decided to preprocess the images, by padding the image to a square and then rescaling it to 1024x1024 and we split the dataset into 80% training data and 20% test data.

3.3.2 Model

As a model we used the Alexnet [5] implementation from pytorch [9], we did not freeze any layers, unlike Poco and Heer [10], because in our experiments we got way better accuracy on the testset with this approach, and the extra training time this needed was not an issue for us, because we were able to utilize powerful GPU's from google colab.

3.4 Specification Induction

With the classified bounding boxes, the text of these boxes and the mark type we could specify a visual encoding specification for a chart image, as shown in Figure 3.5. To get this specification we used the results of the methods shown earlier in this section and we also had to infer some things.

next we will go through every specification and explain how we get it

- width and height
 - For width and height we decided to just use the width and height of the input image, since the input image should display only the visualization.
- chart type and mark type
 - Here we could just use the result of feeding the picture into the method of Section 3.3. Then
 we get something like line chart or bar chart for the chart type, and then the mark type is line
 or area.
- title, field, axis title, labels
 - These things were classified boxes, where the boxes were detected by the method from Section 3.1 and then we used the procedure described in Section 3.2 to get the role of these boxes, title corresponds to the role title, field shows the title for a given axis, axis title does the same, labels show the text, which was found by the OCR procedure described in Section 3.1.7, for all boxes classified as label of a specific axis by the method in Section 3.2 as a list.

values

To get the values of the x- or y-axis labels, we used the labels, explained right above. We go through every label and check some things, at first we just checked if we can convert it to a number without any problems, if this is not possible, then we split the string into numbers and letters, if there is no number, we move onto the next label, if there is a number we also check the letters for a common modifier, like %, which would mean that the number should be multiplied by 0.01, or M, which would mean, that the actual number should be multiplied by 1000000. If no such multiplier is found we just assume that the detected letter was just a mistake by any of the systems before. The last step is now to muliply the number by the multiplier and put the result in the values list

• type

We set the type to quantitive, if there were any numbers in the values, and nominal if there
were no numbers found for the values list.

domain

The domain is a list of the minimum and maximum value found in a label box of an axis.

range

- We defined the range as a list with the minimum and maximum coordinate where a box was found, for the x-axis we took the x-coordinates and for the y-axis we took the y-coordinate.
- type

— This type is a more specific type than the one above, if the above type is nominal, than this also set to nominal, but if the above type is set to quantitive, then this type tries to specify more specifically if the axis is logarithmic or linear. @later

3.5 Sequential Analysis with Pictures

With the entire pipeline before we can compare specifications and then say what changed from one picture to another. To do this we did not write a specific algorithm, because this would be beyond the scope of this bachelor thesis, but we can compare the specifications by just reading the output of our method. Some examples can be seen in Figure 4.8.

4 Results

Finally, the results of the methods described in the last Section, are presented. First we will go through every step and try to evaluate it.

4.1 Results for Text Localization

Our text localization pipeline was able to localize some text, create bounding boxes around the given text, and use an OCR program to read the text. The text localization pipeline was successful in most cases, but like in the paper by Poco and Heer [10] it still has some clear flaws. Some examples of the text localization can be seen in Figure 4.7, by looking at where the boxers are located, for looking at the text localization, only the location of the bounding box, and the text on top of it are relevant.

4.2 Results for Text Classification

The trained random forrest classifier reached an accuracy of around 98% on the testset on most tries, when we tried the same with the SVM proposed by Poco and Heer [10] the SVM reached an accuracy of around 97% on the testset on most tries, which is only slightly worse, but when looking at the classification, on the boxes we got with the text localization method (Section 3.1) on example pictures we noticed, that even from just slightly different boxes the class was then often wrong and the accuracy on our boxes was just around 60% with the SVM, even after their post processing step and with the random forrest, the accuracy on our boxes was around 85%

4.3 Results for Mark Classification

With our mark classification net we were able to classify 95% of our testset images correctly, which is pretty accurate, the only concerning thing is, that our testset accuracy is 100%, which could indicate overfitting of your model, we tried to solve this by freezing some layers, or implementing some dropout layers, but they all led to a worse accuracy on the testset, therefore we accepted the trade-off. In Section 3.3 we mentioned, that our dataset is imbalanced, in Figure 4.6 it can be seen, that this imbalance did not cause any problems.

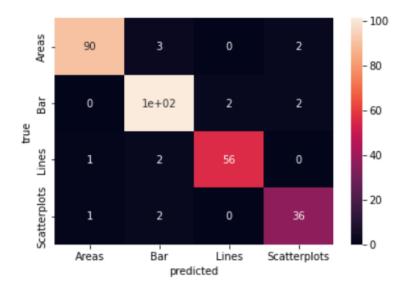


Figure 4.6: mark classification confusion matrix on the testset

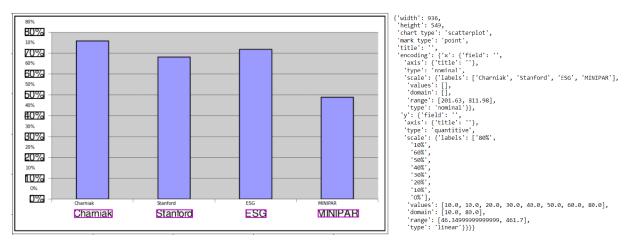
4.4 Results for Specification Induction

Our specification induction results were difficult to express in numbers, like accuracy, f1-score or other metrics, because we did not have a real dataset with these specifications, therefore we evaluated it by producing some example specifications and looking, at the pictures. In Figure 4.7 such specifications can be seen. In general, there were three different kind of mistakes the pipeline made, the first mistake is merging some boxes because the labels were to close together, this can be seen in Figure 4.7b, where the x-axis label boxes merged together, the second common mistake is misclassifying boxes which are in uncharacteristic positions, like the % sign in Figure 4.7b and the last and most common mistake the method makes is to wrongly classify some plotting signs in the middle of the plot as characters, an example can be seen in Figure 4.7c.

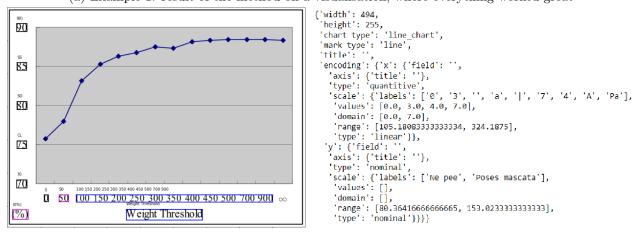
4.5 Results for Sequential Analysis

When we tried our method on screenshots or a sampled down version of a video, we had the problem, that the otsu thresholding used during the text localization process displayed some odd behaviour, which can be seen in Figure 4.9a, where from the letters the inner colour got removed. Because of this we got a really bad heatmap, which led to the heatmap removing almost every bit of text in the image and then we did not find any text. Because of time constraints, we did not examine this error any further.

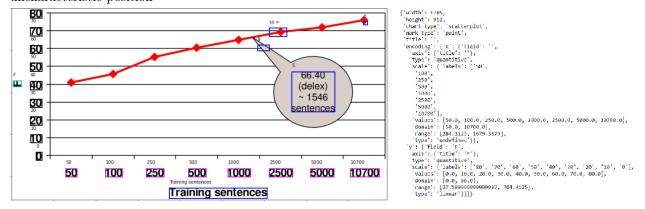
When we are able to save the figure automatically from the program it was generated with, then we were able correctly generate the specification, as it can be seen in Figure 4.7, with this it would be possible to recreate change logs from visual analytics tools, but only if the visualizations don't fall into any of the common mistakes our method makes, which were mentioned in Section 4.4.



(a) Example 1: result of the method on a visualisation, where everything worked great



(b) Example 2: result of the method on a visualisation, where the text labels merged, because they were close to each other, and the box in the bottom-left corner was misclassified, because it is a box in a really uncharacteristic position



(c) Example 3: result of the method on a visualisation, where some plotting symbols are wrongly classified as text

Figure 4.7: Example results of the method on different visualizations

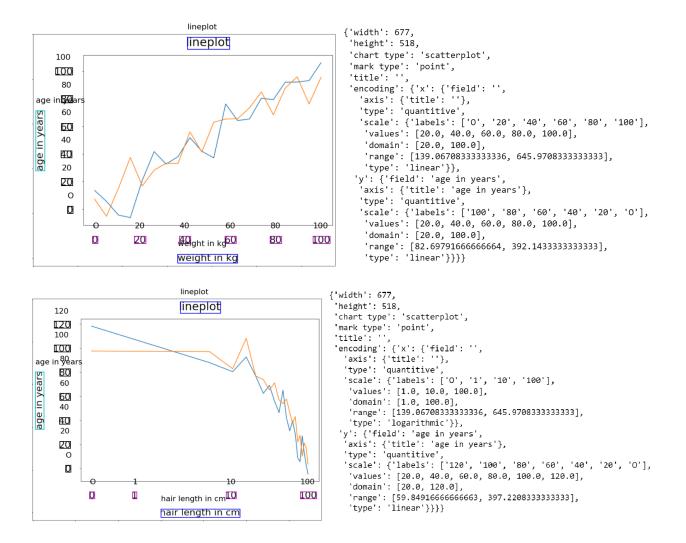
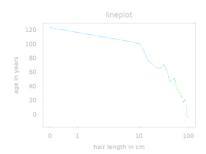
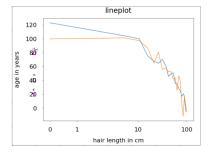


Figure 4.8: Example result, where the output specification can be compared by a computer and the difference between the visualizations can be found with our method



(a) Result of otsu thresholding on a screenshot



(b) Result of the method on a screenshot

Figure 4.9: Results on a screenshot

5 Limitations

One of our biggest limitations was, data, it was hard to find data, which was good and looked like the data we would like to use the method for, for example we had to use old and outdated visualizations, like the ones in Figure 5.10 for training the mark classifier, because this was the best we had access to. And we achieved a good accuracy on this data, but we do not know, how the classifier performs on newer visualizations with modern standards, even though we think that it should not be much worse since modern visualizations have gotten a lot more clearer and easier to understand for humans.

Another limitation was the time we had to make each step work, there could be a lot more approaches which could be tested, like trying to create distinct methods for different mark types, or trying to improve each step further.

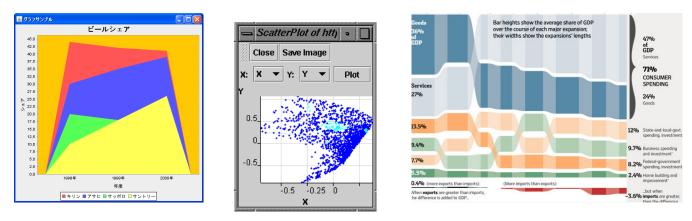


Figure 5.10: Examples of data used to train the mark classifier

6 Future Work

The specified limitations lead to some future work, first of all it would be interesting to see if each step could be improved further, for mark classification it would be interesting to see different net architectures, text localization could be improved, by making the heatmap more accurate, or by implementing a rule which sets the entire field between the axis to 0 in the heatmap, such that the plotting symbols get detected less and the text role classification could be improved, by looking at the training data and adding some new samples, which were actually detected by the text localisation method, this could maybe solve the problem, that the test data has a way higher accuracy than the real world examples.

Also there could be more metrics implemented to evaluate each step, for example Poco and Heer [10] evaluated their classifier against other popular classifiers like ReVision or ChartSense.

7 Conclusion

In this work, an approach was introduced to reverse engineer images of visualizations, applying different neural networks and existing algorithms to the images, which could help researchers in analyzing human-computer interactions, just from screenshots or videos of a person performing task. Our approach consists of the following steps, first we localize the text in an image, then we classify the role of the found text, next we classify the mark type of the visualization and then we try to generate the chart specification.

With following these steps we were able to correctly generate the specifications of some visualizations, but most of the time our method made mistakes in one of the steps, which then propagates through the entire method.

In conclusion, the fact that the method works for specific visualizations and has some very predictable mistakes shows, that the there is potential for this method to be used in the future to extract chart specifications from chat images, but there is still some work to be done to make the results more accurate and reliable. We hope that our work inspires scientists to do more research in the field of reverse engineering visualizations from bitmap images,

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