Future Tire Conference 2016 Essen, Germany, May 25, 2016



corresponding author: antoine.schmeitz@tno.nl

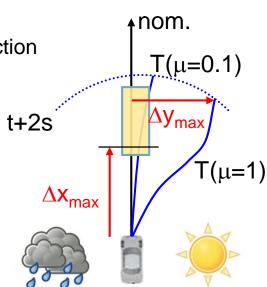
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- Smart tires
- Tire force estimation
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VEHICLE AUTOMATION AND TIRES

- Vehicle capabilities determined by tyre-road friction potential (braking, steering)
- For safe automated driving, real-time friction potential estimation is required
- > Challenges:
 - Estimate tire-road friction in normal driving
 - Also at t+∆t s
 - Deal with inhomogeneous vehicles and bad weather conditions





Cooperative Adaptive Cruise Control (C-ACC)



EU ministers to try out self-driving cars - April 2016



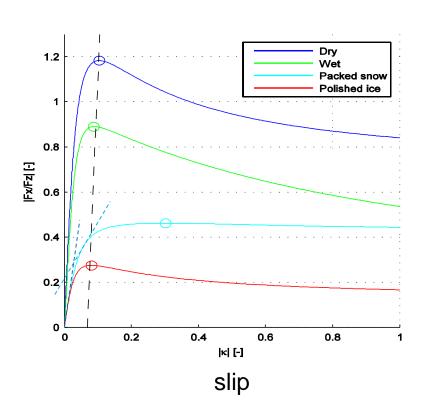
European Truck Platooning Challenge - April 2016

3 | From TPMS to smart tire technology 25 May 2016



SLIP-BASED TYRE-ROAD FRICTION ESTIMATION

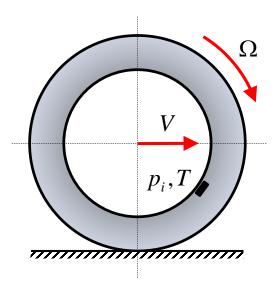
- Basic idea:
 - slope of tire slip characteristic:
 - reduces to zero when reaching the peak friction
 - many measurements show relation slip stiffness (slope at zero slip) and peak friction
- > So:
 - measure forces and slip
 - consider additional information:
 - > tire inflation pressure, temperatures, ...
 - > estimate the peak friction



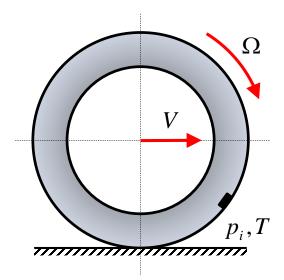


Concluding remarks

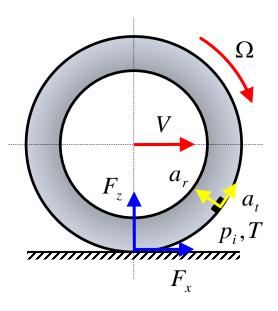
FROM TPMS TO SMART TIRE



- Tire Pressure Monitoring System
- On valve or rim



- Tire Pressure Monitoring System
- On inner liner



- Smart Tire: additional sensors & functionality
- Example: accelerometer

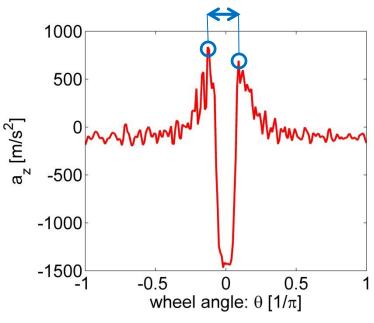


SMART TIRES

- Smart/intelligent tire systems under development for more than a decade
-) Basic principle:
 - Measuring tire deformation and relate it to tire states or road conditions:

forces, slip angle, camber angle, ... aquaplaning, road condition (wet, snow,...)

- Sensors: strain, acceleration, distance, ...
- Most promising solution: accelerometer at the tire inner liner
- Feature extraction algorithms
 to estimate tire states
 (e.g. distance between peaks in signal)



MANY CHALLENGES

- Technology:
 - sensors
 - wireless communication
 - energy
 - algorithms
 - computation power





Accelerometers

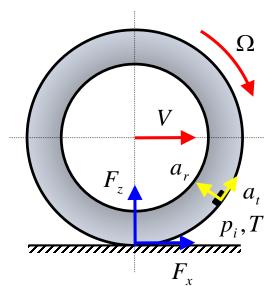
Competing technologies:

- algorithms that use standard vehicle sensors (similar to indirect TPMS)
- > new vehicle sensors, e.g. wheel force bearings, optical sensors, cameras
- > I2V (infrastructure to vehicle) applications

TIRE FORCE ESTIMATION

Force estimation example:

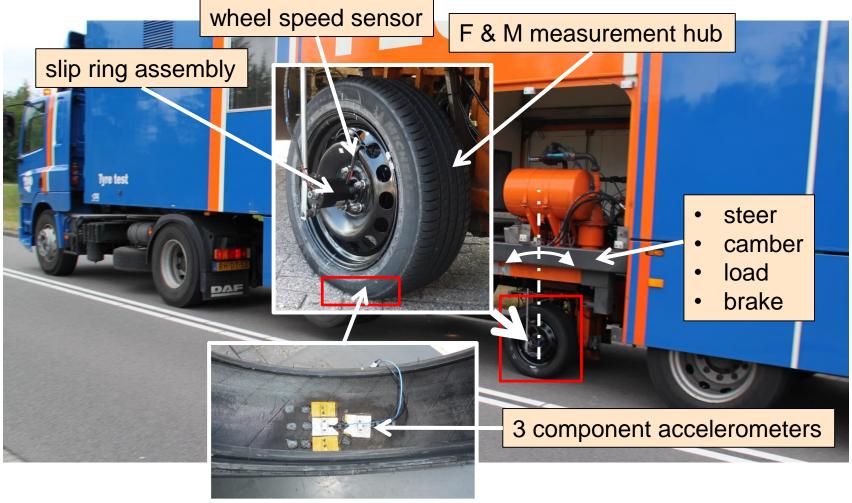




- Challenges:
 - robust algorithm working under various/all operating conditions
 - accuracy, delay, ...
- Novel solution:
 - model-based force estimator



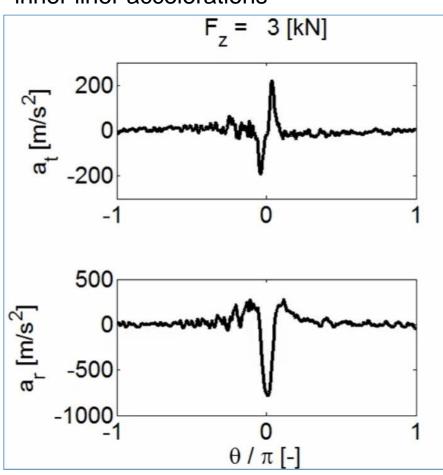
MEASUREMENT SETUP & EXPERIMENTS



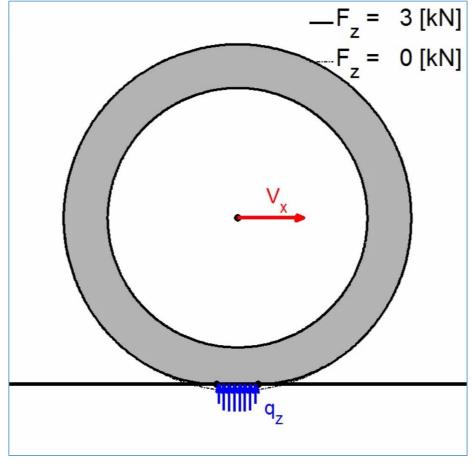


VERTICAL TIRE BEHAVIOUR

inner liner accelerations



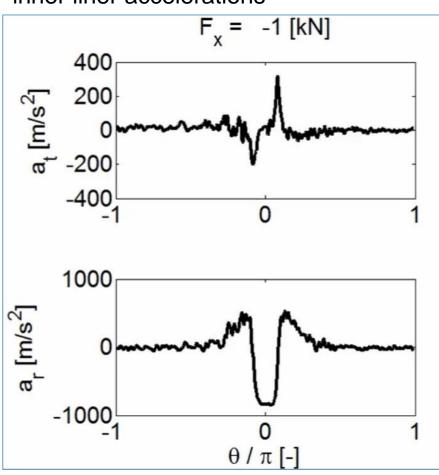
tire deformation



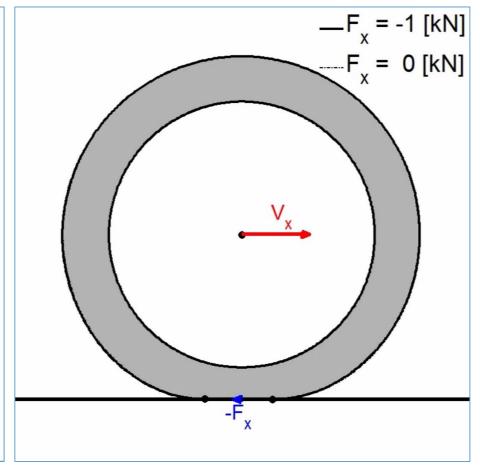


TIRE BEHAVIOUR WHILE BRAKING

inner liner accelerations

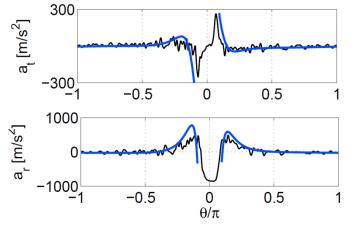


tire deformation





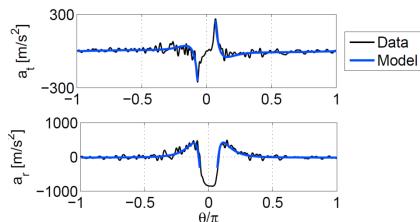
MODEL-BASED TIRE FORCE ESTIMATION



find forces that minimise



error between measurement and model

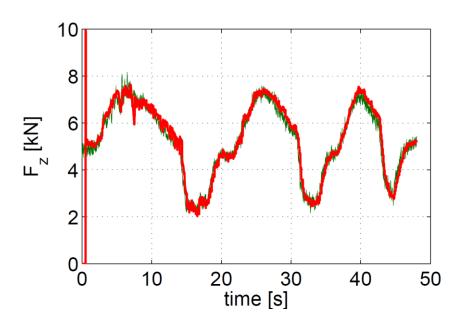


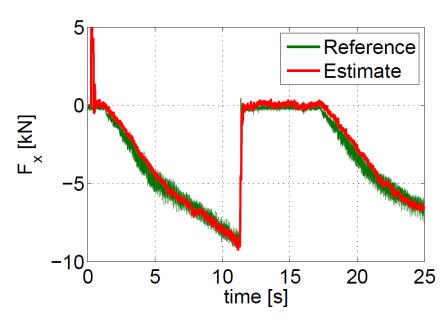


SOME RESULTS



Vertical load estimation during load and velocity changes Brake force estimation at constant vertical load





CONCLUDING REMARKS

- Future automated riving (AD) functions require real-time friction estimation
- Next step after inner liner TPMS is a smart tire that offers more functionality
- Opportunity for a smart tire that senses tire forces and eventually predicts friction
- > TPMS + accelerometer at inner liner is promising solution
- Novel model-based tire force estimator has been developed to estimate vertical and longitudinal tire forces

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