

Topic 1: Load Balancing Problem

Input: m identical machines: $M1, M2, \dots, Mm$


n jobs: $J1, J2, \dots, Jn$

Processing time of each job: t_j ($j = 1, 2, \dots, n$)

Example: 3 machines and 7 jobs ($t_j = 1, 2, 3, 4, 5, 6, 7$)

M1  T1 = 12

M2  T2 = 7

M3  T3 = 9

Makespan $T = \max \{T1, T2, T3\} = 12$

Q: What is the best assignment ?

Some General Settings of Load Balancing

Some machines are more efficient than the others

Example: M3 needs less processing times than the others.

Three Machines: M1, M2, M3

Ten Jobs: J1, J2, ..., J10

**Processing time (t_j): 2, 4, 6, ..., 20 on M1 and M2
1, 2, 3, ..., 10 on M3**

Some machines can process only a part of jobs.

Example: M1 can process J1, J2, ..., J7

M2 can process J1, J2, ..., J8

M3 can process all jobs (J1, J2, ..., J10)

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M2 can process J1, J2, ..., J8

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Topic 6: Generalized Load Balancing Problem

(Use of LP)

Input: Set of m machines: $M = \{\text{Machine } 1, \dots, \text{Machine } m\}$

Set of n jobs: $J = \{\text{Job } 1, \dots, \text{Job } n\}$

Processing time of each job: t_j ($j = 1, 2, \dots, n$)

Subset of M for each job: M_j ($j = 1, 2, \dots, n$)

Constraint: Job j should be assigned to a machine in M_j

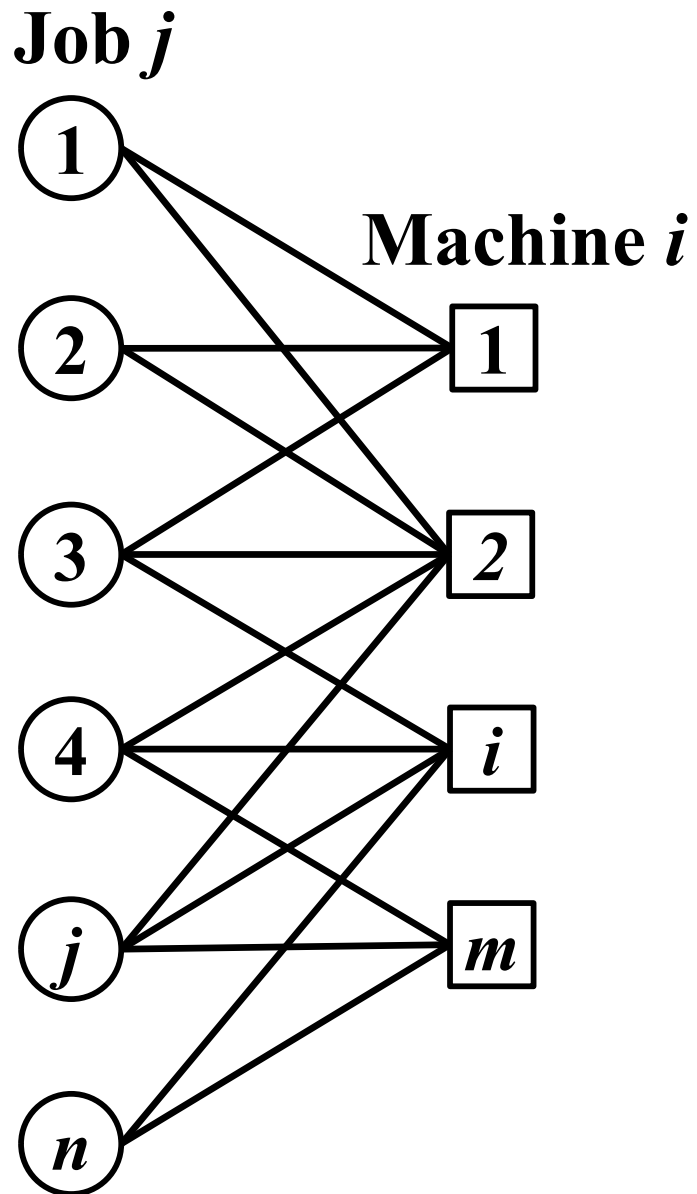
Objective: Minimization of the makespan

Output: Assignment of n jobs to m machines

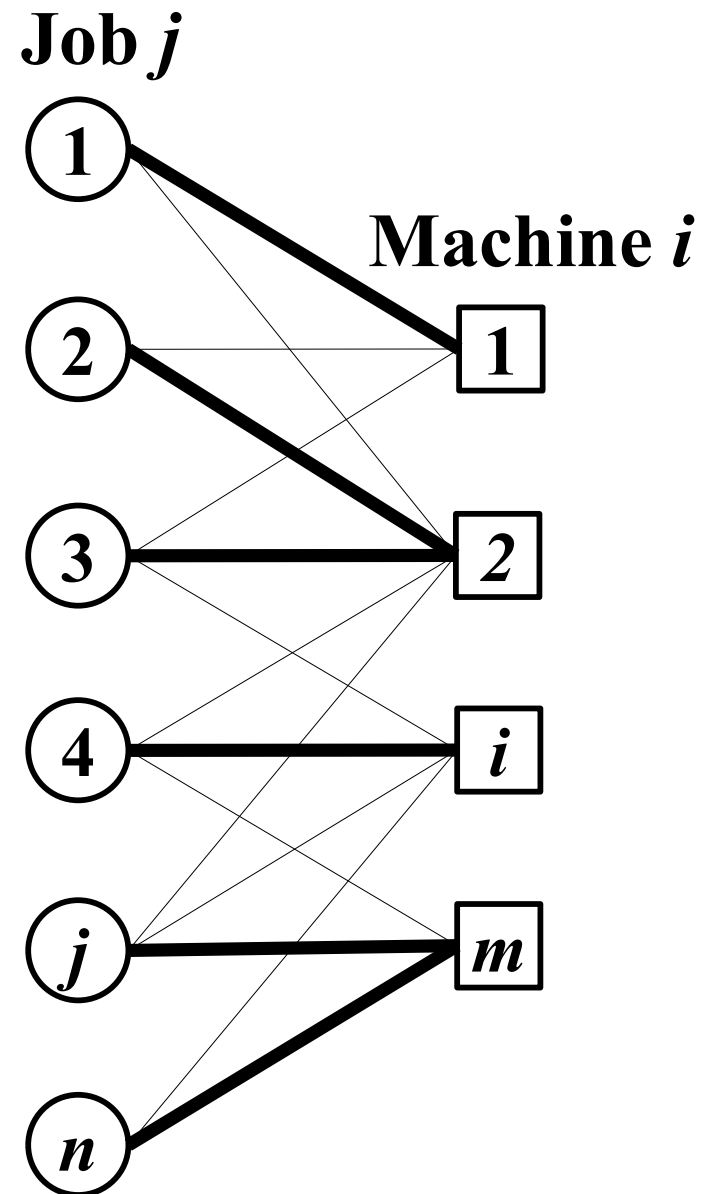
Let J_i be the set of jobs assigned to machine i . The load of machine i is $L_i = \sum_{j \in J_i} t_j$. The objective is to minimize $\text{Max}_i L_i$.

L^* : Optimal value of the objective function ($L^* \geq \text{Max}_j t_j$)

Qualified machines for each job



Example of assignment



Input: Set of m machines: $M = \{\text{Machine } 1, \dots, \text{Machine } m\}$

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Processing time of each job: t_j ($j = 1, 2, \dots, n$)

Subset of M for each job: M_j ($j = 1, 2, \dots, n$)

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Let J_i be the set of jobs assigned to machine i . The load of machine i is $L_i = \sum_{j \in J_i} t_j$. The objective is to minimize $\text{Max}_i L_i$.

Objective Function

Minimize $\text{Max}\{L_i = \sum_{j \in J_i} t_j \mid i = 1, 2, \dots, m\}$



Minimize L subject to $\sum_{j \in J_i} t_j \leq L$ for $i = 1, 2, \dots, m$

Formulation using 0-1 variables x_{ij}


Minimize L

subject to $\sum_{i=1}^m x_{ij} = 1$ for all $j \in J$ (job j in J)

Each job should select one machine.



The total processing time at each machine is equal to or smaller than L .



$\sum_{j=1}^n x_{ij} \cdot t_j \leq L$ for all $i \in M$ (machine i in M)

$x_{ij} \in \{0, 1\}$ for all $j \in J, i \in M_j$

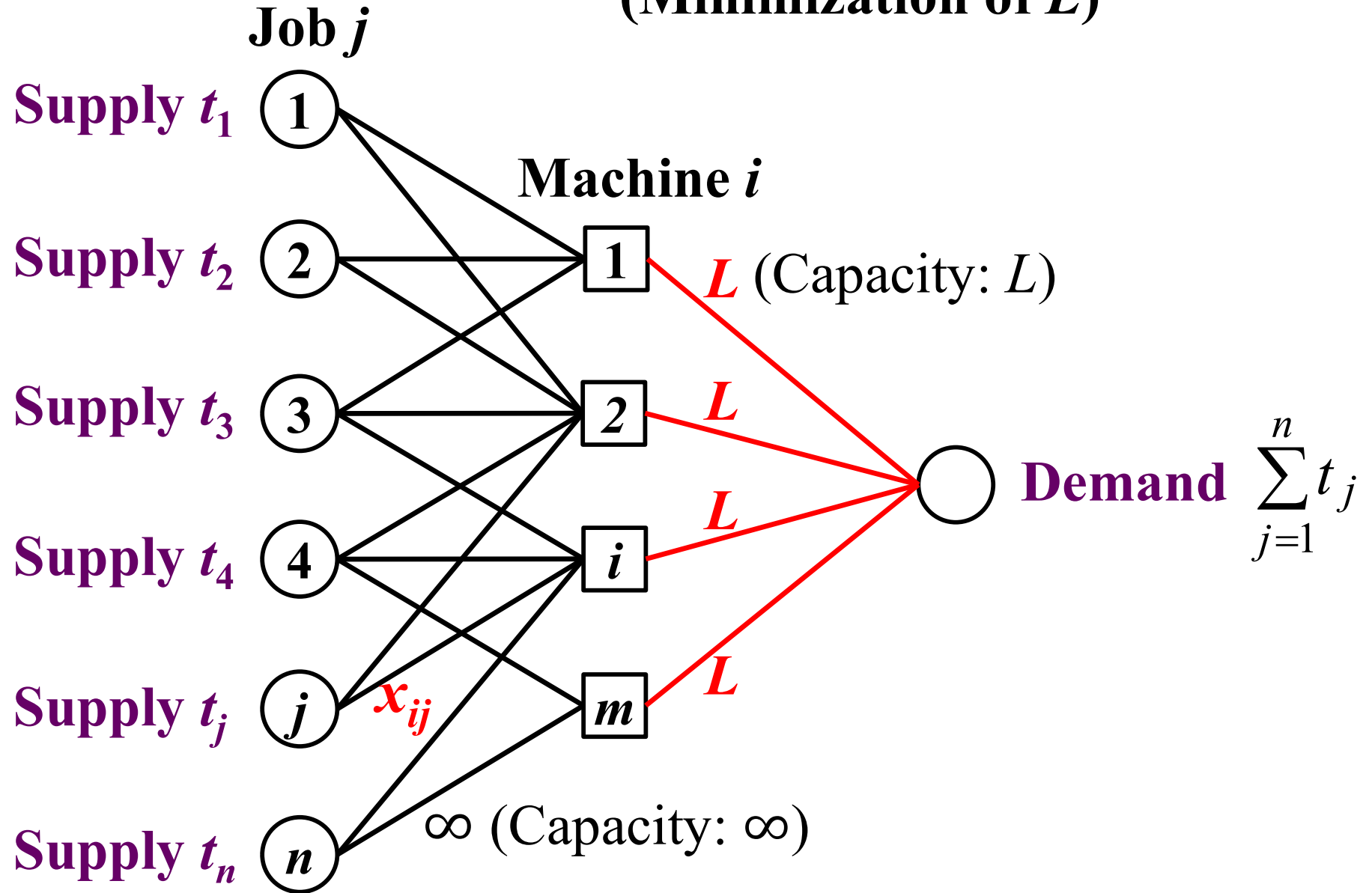
$x_{ij} = 0$ for all $j \in J, i \notin M_j$

L : variable for formulating the objective function

x_{ij} : 0-1 variable for denoting the selection of machine i by job j

Flow Formulation using real number variables x_{ij}

(Minimization of L)




x_{ij} : Flow from job j to machine i

(x_{ij} is not the 0-1 variable in the previous page)


GL-IP: Generalized Load Balancing as an Integer Problem

Minimize L

subject to $\sum_{i=1}^m x_{ij} = t_j$ for all $j \in J$ (job j in J)

 Flow from each job j is t_j .

$\sum_{j=1}^n x_{ij} \leq L$ for all $i \in M$ (machine i in M)

 Total flow to machine i .

$x_{ij} \in \{0, t_j\}$ for all $j \in J, i \in M_j$

$x_{ij} = 0$ for all $j \in J, i \notin M_j$

L : variable for formulating the objective function

x_{ij} : variable for denoting the flow from job j to machine i

L^* : Optimal value of the objective function

GL-LP: Linear Programming Relaxation of GL-IP

Minimize L

subject to $\sum_{i=1}^m x_{ij} = t_j$ for all $j \in J$ (job j in J)

$\sum_{j=1}^n x_{ij} \leq L$ for all $i \in M$ (machine i in M)

$x_{ij} \in \{0, t_j\} \Rightarrow x_{ij} \geq 0$ for all $j \in J, i \in M_j$

$x_{ij} = 0$ for all $j \in J, i \notin M_j$

$$L^* \geq L_{LP}^*$$

L_{LP}^* : Optimal value of the relaxation problem

L^* : Optimal value of the original problem

Question: Why $x_{ij} \geq 0$ instead of $0 \leq x_{ij} \leq t_j$?

$$x_{ij} \in \{0, t_j\} \Rightarrow x_{ij} \geq 0$$

If the solution of the relaxation problem satisfies

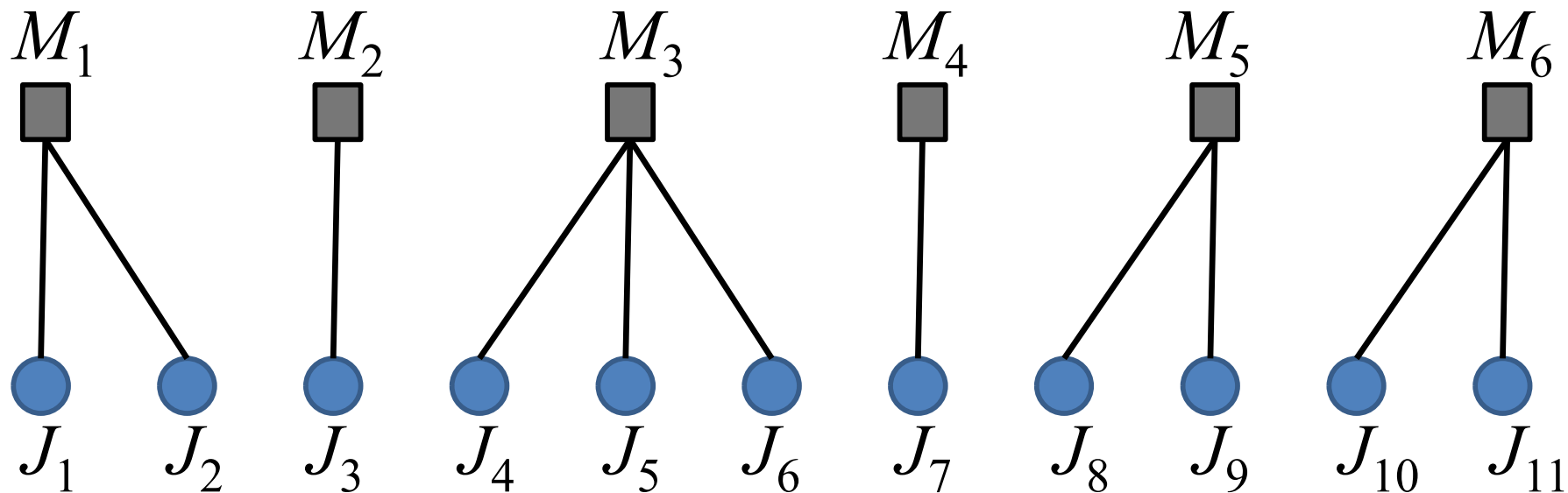
$$x_{ij} \in \{0, t_j\} \text{ for all } j \in J, i \in M_j$$

the solution is the optimal solution of the original problem.

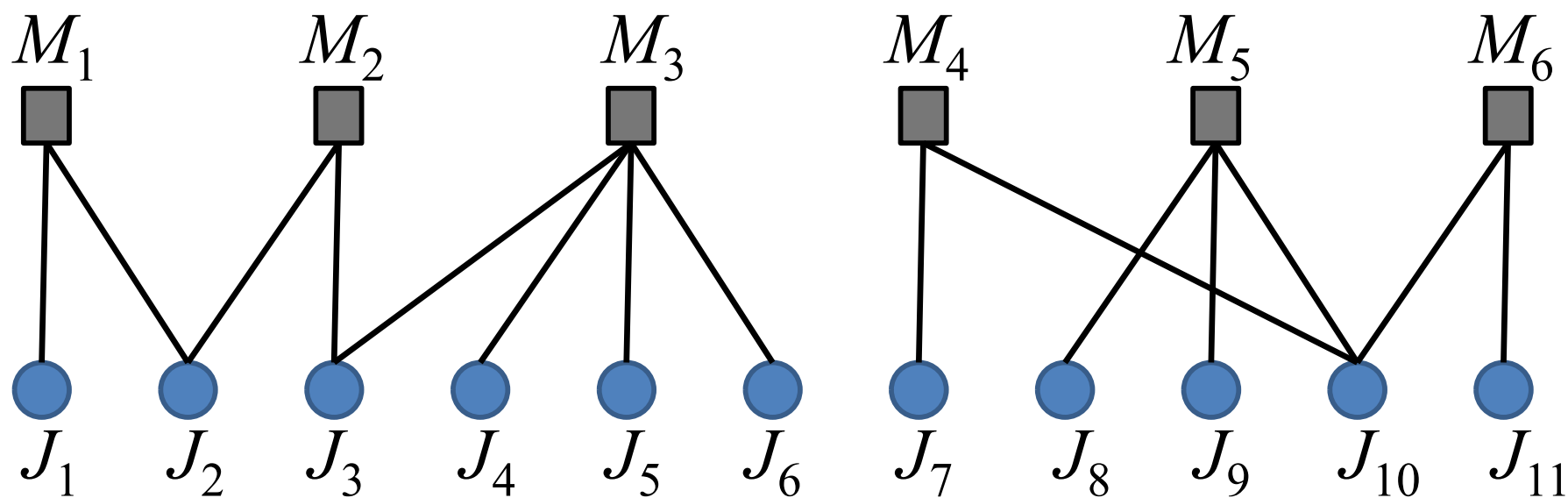
However, in general, this condition is not satisfied. That is, t_j is distributed over multiple machines (e.g., $t_j = 10$ and $x_{1j} = 2.1$, $x_{2j} = 3.8$, $x_{3j} = 4.1$), which is not a feasible solution.

Question: How to obtain a feasible solution from the obtained solution of the relaxation problem?

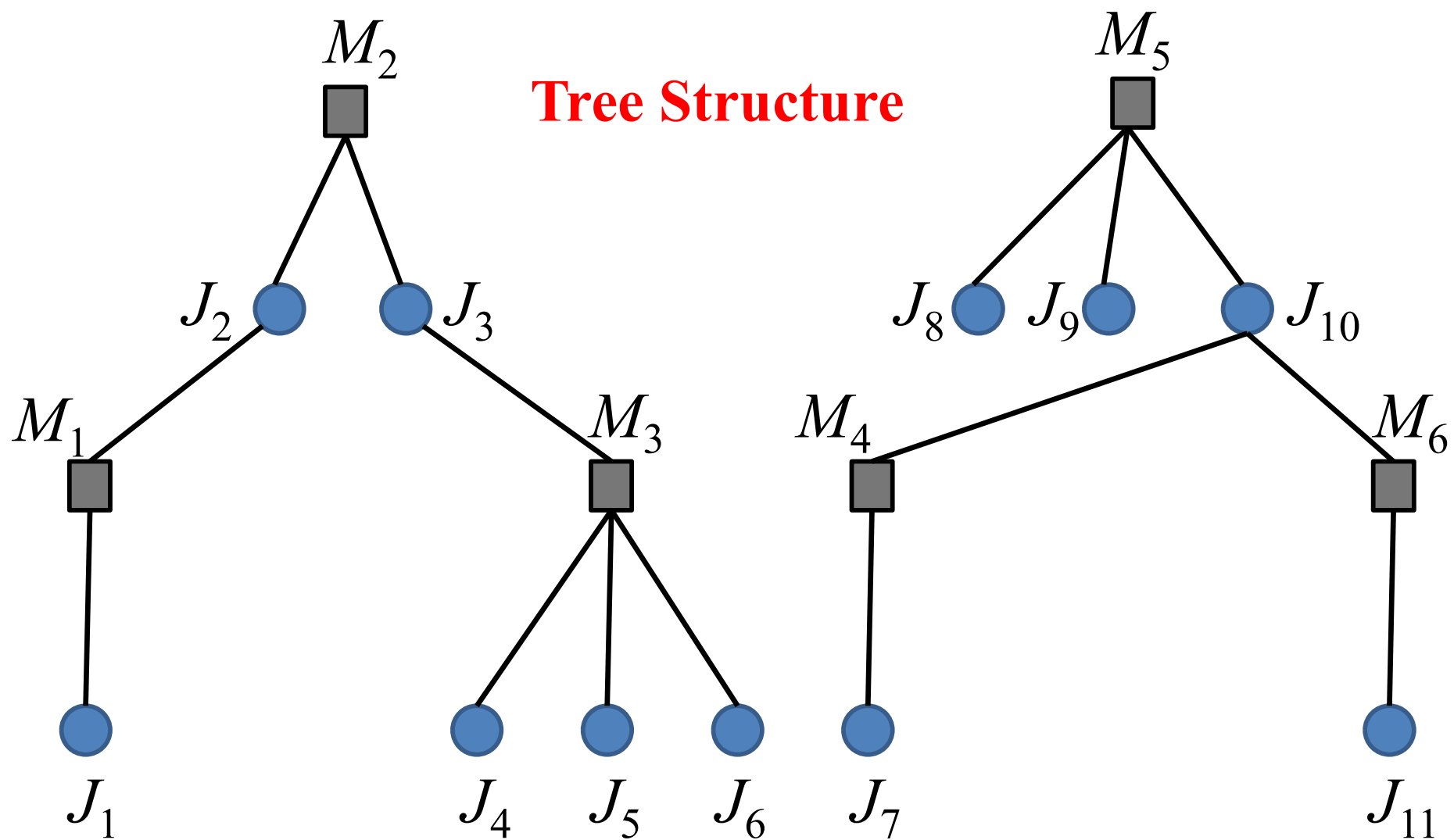
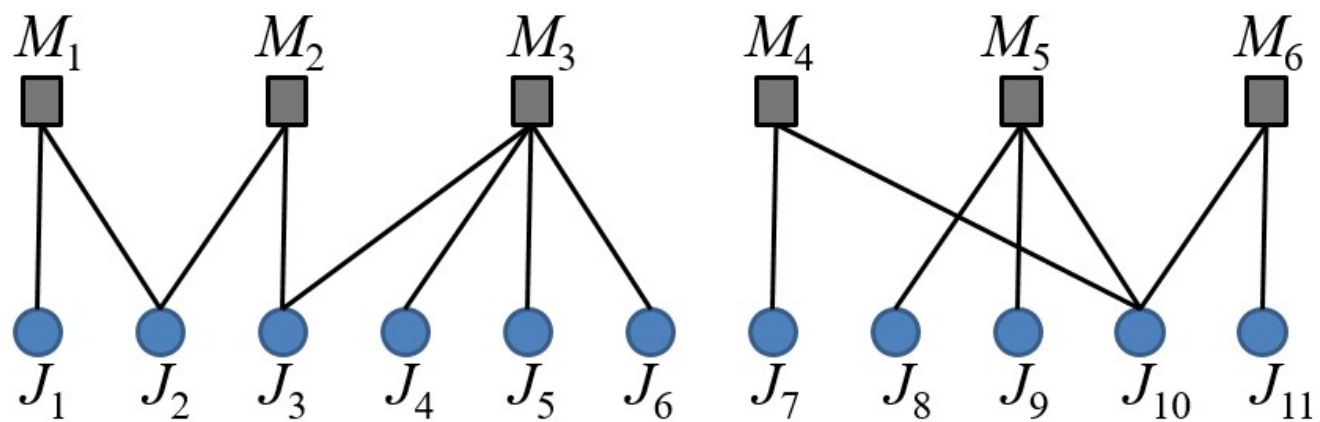
Construct a graph $G(x) = (V(x), E(x))$ where $V(x) = M \cup J$ and $(i, j) \in E(x)$ if and only if $x_{ij} > 0$. If the graph has no cycles (i.e., if the graph is acyclic), each of its connected components has a tree structure.

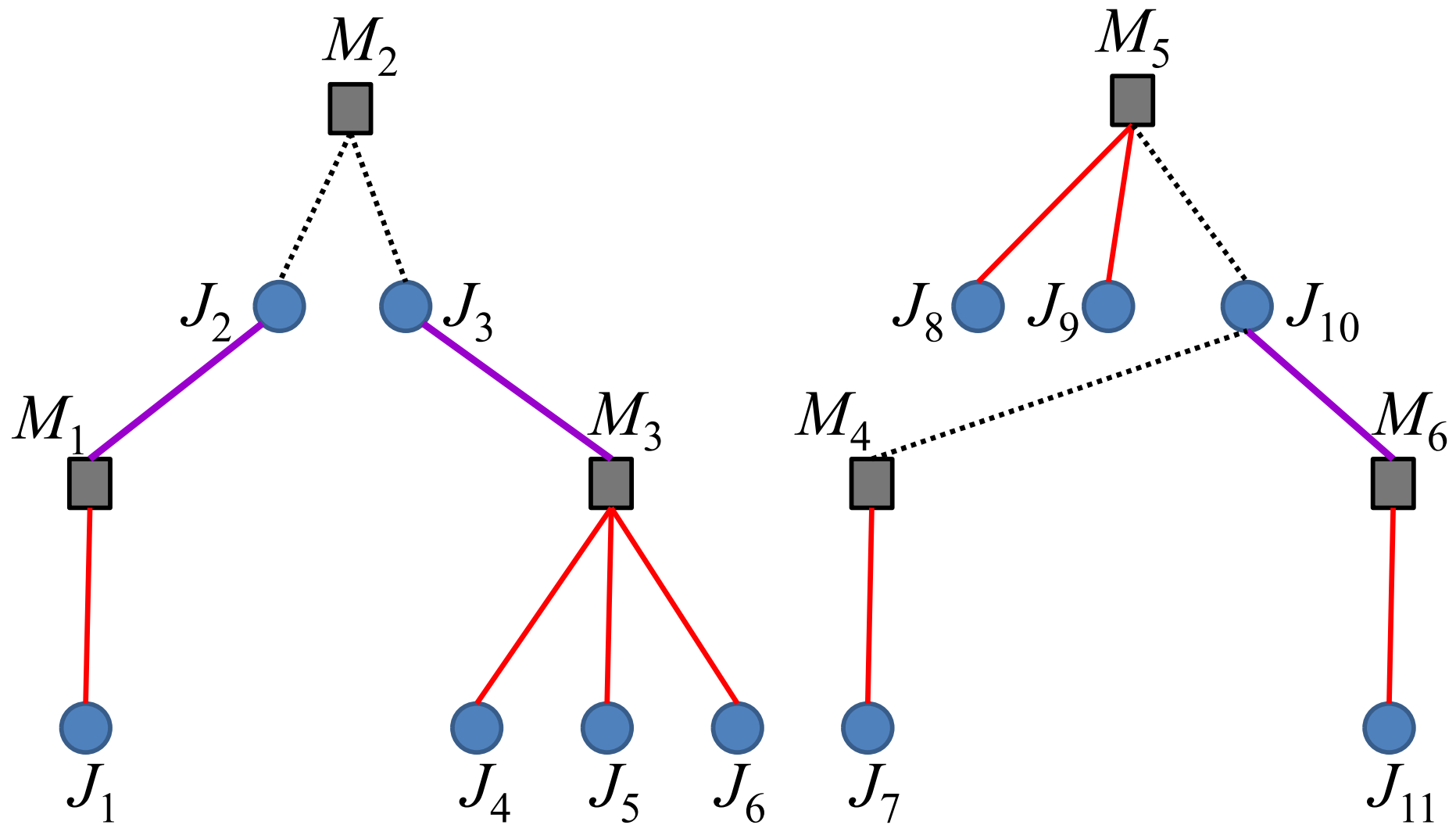


Feasible Solution



Obtained graph from the relaxation problem (no cycles)



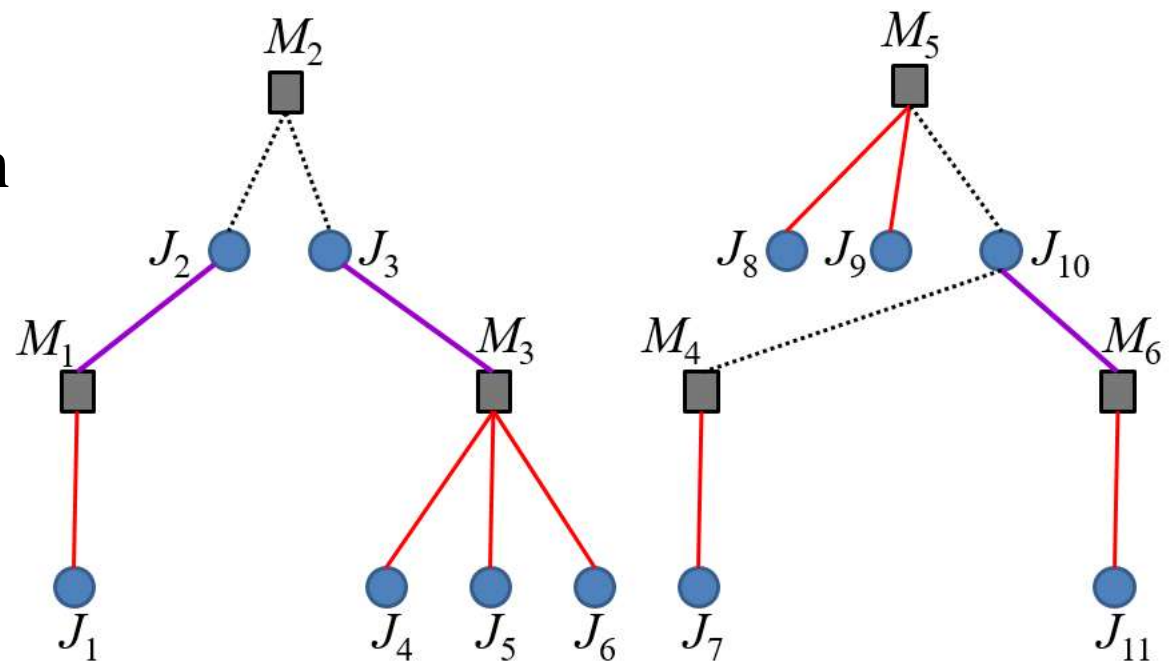


Job Assignment

- (1) Each leaf is assigned to its parent. (—)
- (2) Each intermediate job node is assigned to an arbitrary child. (—)

Upper Bound: $2L^*$

2-approximation Algorithm



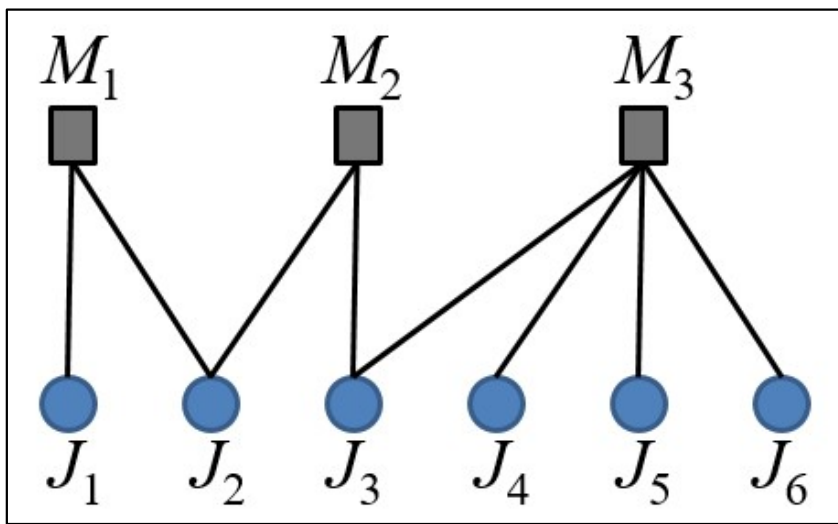
(1) Leaf job assignment to its parent machine (—)

Since each job has a single edge, $x_{ij} = t_j$ holds for each job assignment. For **those jobs** assigned by this procedure, the

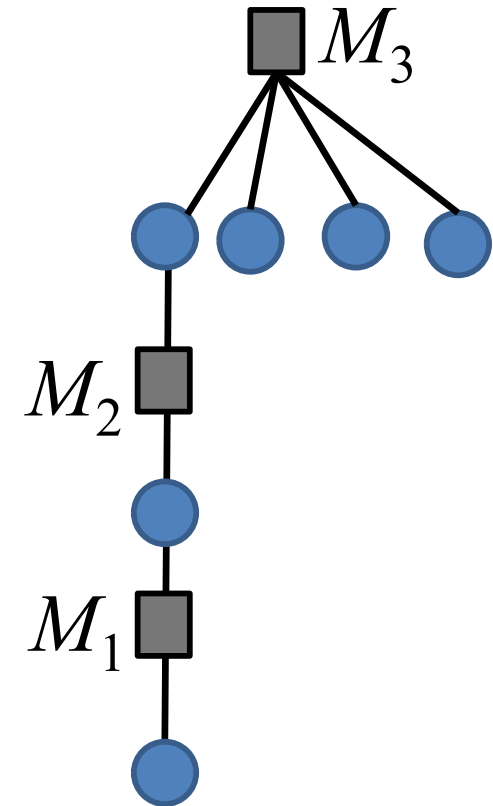
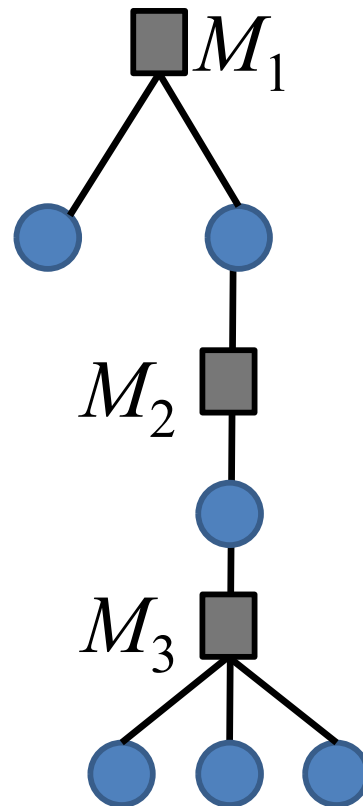
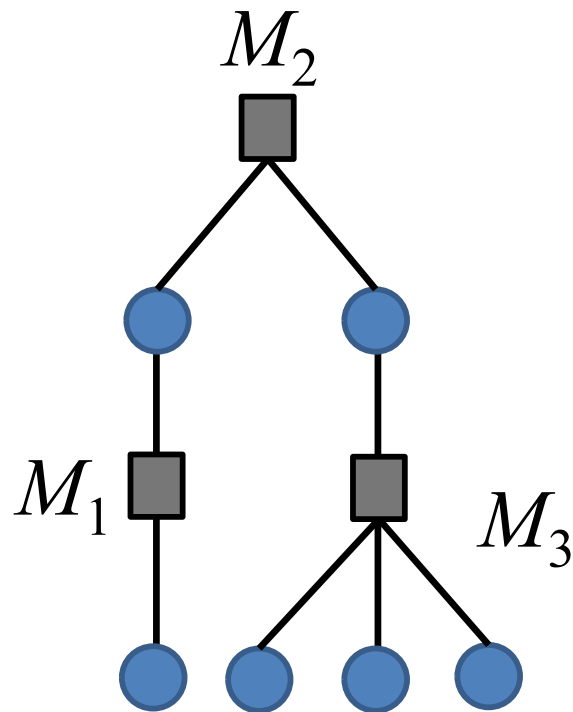
following relation holds for each machine i : $\sum_j t_j = \sum_j x_{ij} \leq L \leq L^*$

(2) Intermediate job assignment to its child machine (—)

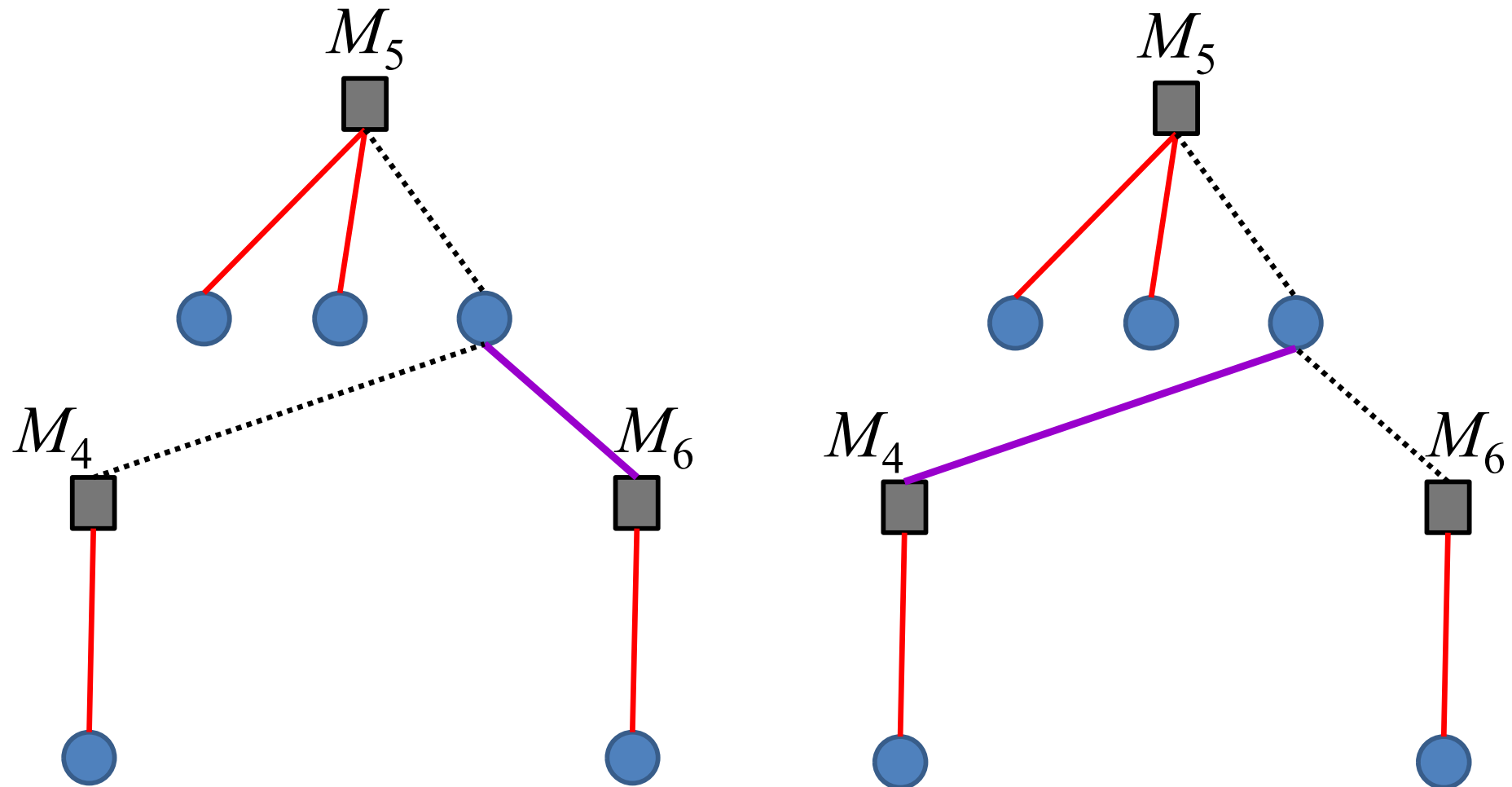
Since only a single job is assigned to some machines, the increase by this procedure is less than or equal to $\text{Max}_j t_j \leq L^*$



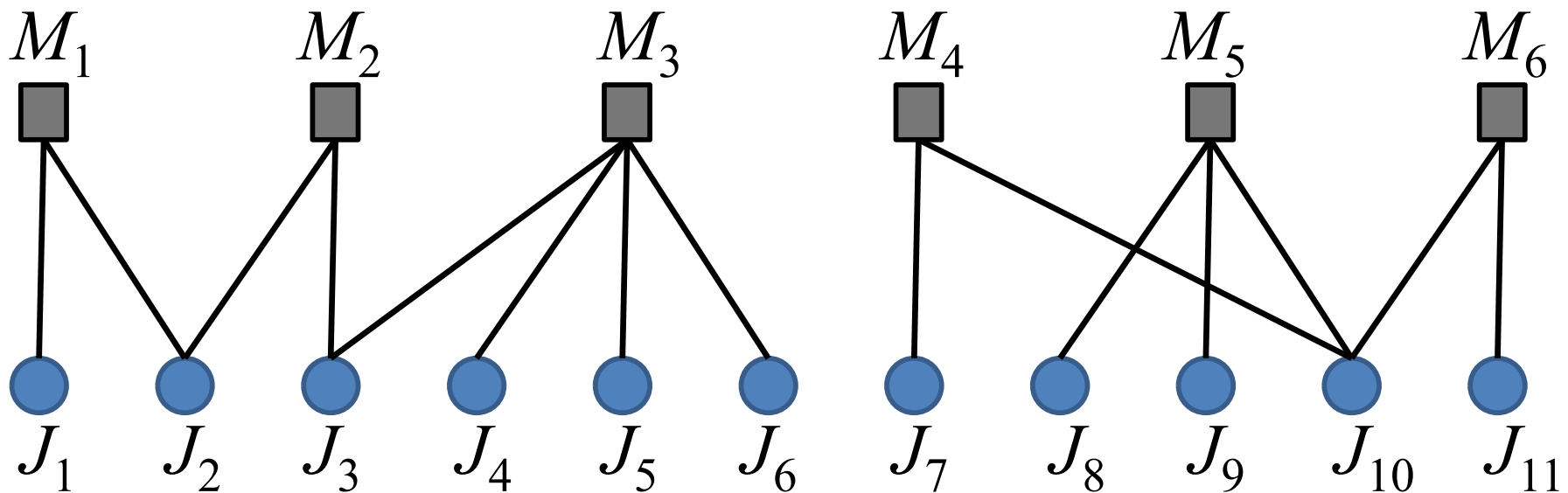
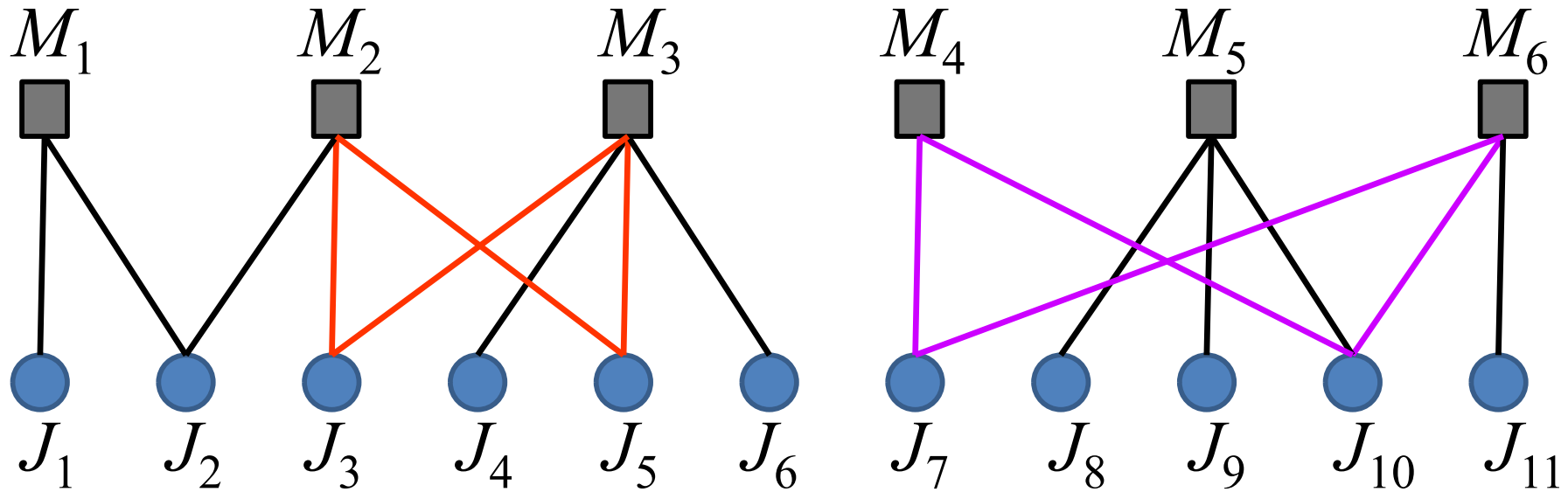
Q1: Choice of a tree structure
Which is a good choice?



Q2: Choice of a child node (which is better?)

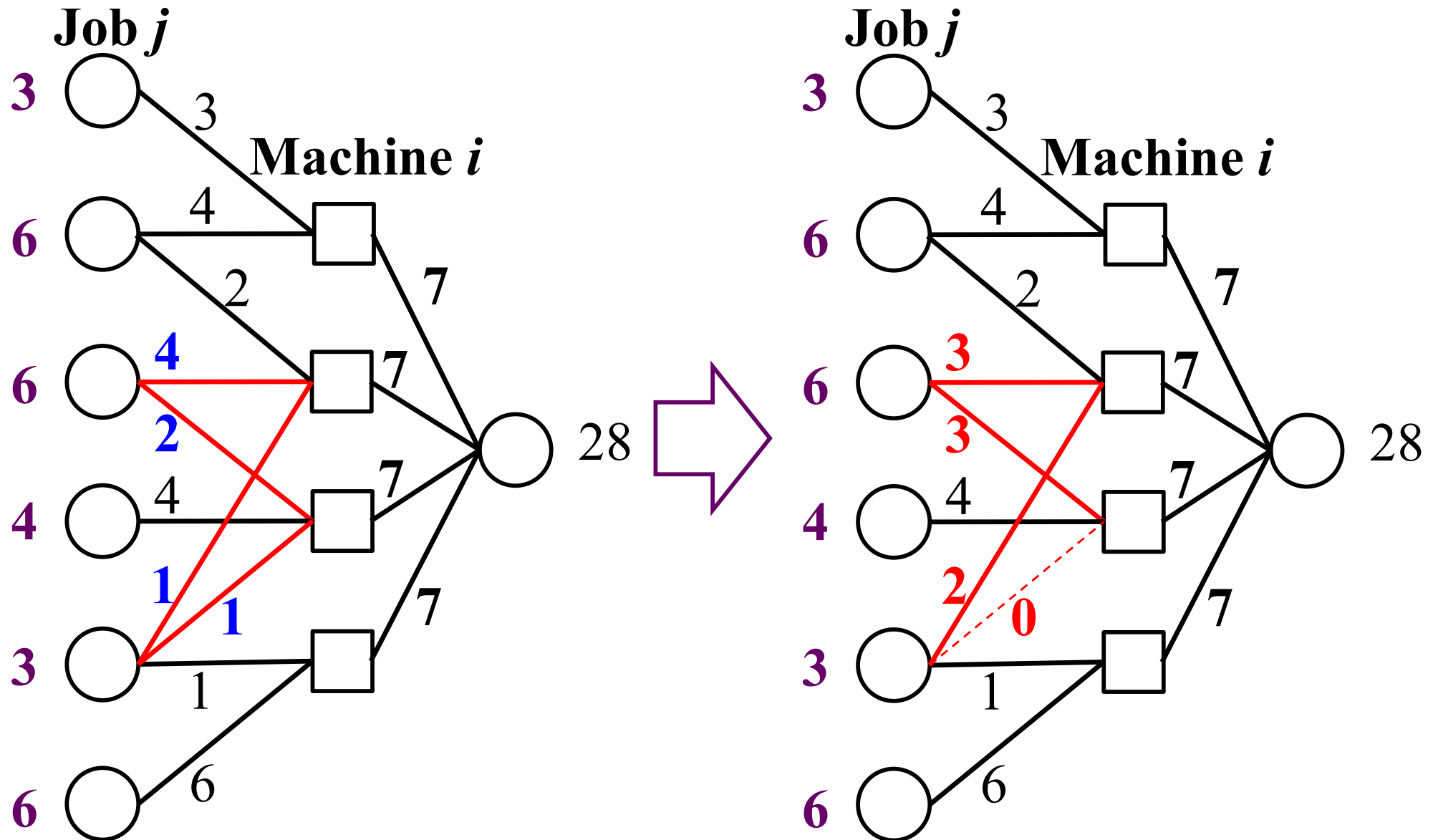


When the obtained graph from the solution of the relaxation problem has cycles, a graph with no cycles can be created without changing its objective value (makespan: L).



How to eliminate cycles from the obtained graph?

Choose a cycle. Change the flow of each edge along the cycle without changing the total input to each node and the total output from each node (i.e., without changing the objective value L).



Exercise 12-1:

Create two examples of the generalized load balancing problem where a graph with no cycle is obtained from one example and a graph with a cycle (or two cycles) is obtained from the other example. Then explain the entire procedure of the LP-based algorithm using the created examples.

Exercise 12-1: Use of LP

Create two examples of the generalized load balancing problem where a graph with no cycle is obtained from one example and a graph with a cycle (or two cycles) is obtained from the other example. Then explain the entire procedure of the LP-based algorithm using the created examples.

One example: Create an example. Apply **an LP package** to the created example. Generate a graph using the obtained LP solution. The generated graph should have no cycle.

The other example: Create an example. Apply **an LP package** to the created example. Generate a graph using the obtained LP solution. The graph should have one or more cycles.

Exercise 12-1: Use of LP

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LP Problem:

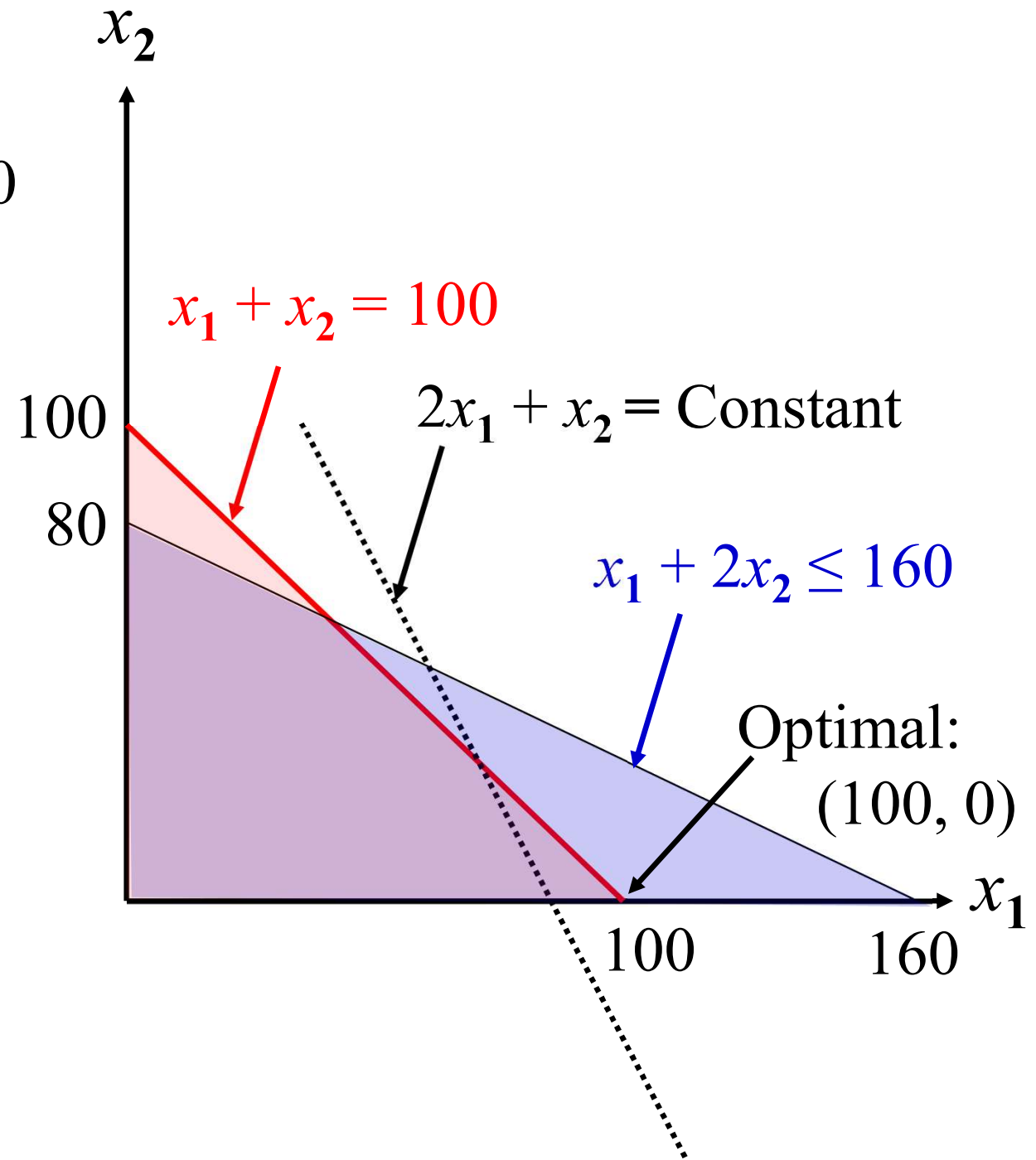
Maximize $2x_1 + x_2$

Subject to $x_1 + x_2 = 100$

$x_1 + 2x_2 \leq 160$

$x_1 \geq 0$

$x_2 \geq 0$



LP Problem:

Minimize L

Subject to $x_1 + x_2 = 100$

$$x_1 + 2x_2 \leq L$$

$$2x_1 + x_2 \leq L$$

$$x_1 \geq 0$$

$$x_2 \geq 0$$

LP Problem:

Minimize L

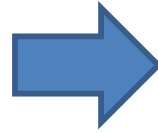
Subject to $x_1 + x_2 = 100$

$$x_1 + 2x_2 \leq L$$

$$2x_1 + x_2 \leq L$$

$$x_1 \geq 0$$

$$x_2 \geq 0$$



LP Problem:

Minimize x_3

Subject to $x_1 + x_2 = 100$

$$x_1 + 2x_2 - x_3 \leq 0$$

$$2x_1 + x_2 - x_3 \leq 0$$

$$x_1 \geq 0$$

$$x_2 \geq 0$$

LP Problem:

Minimize L

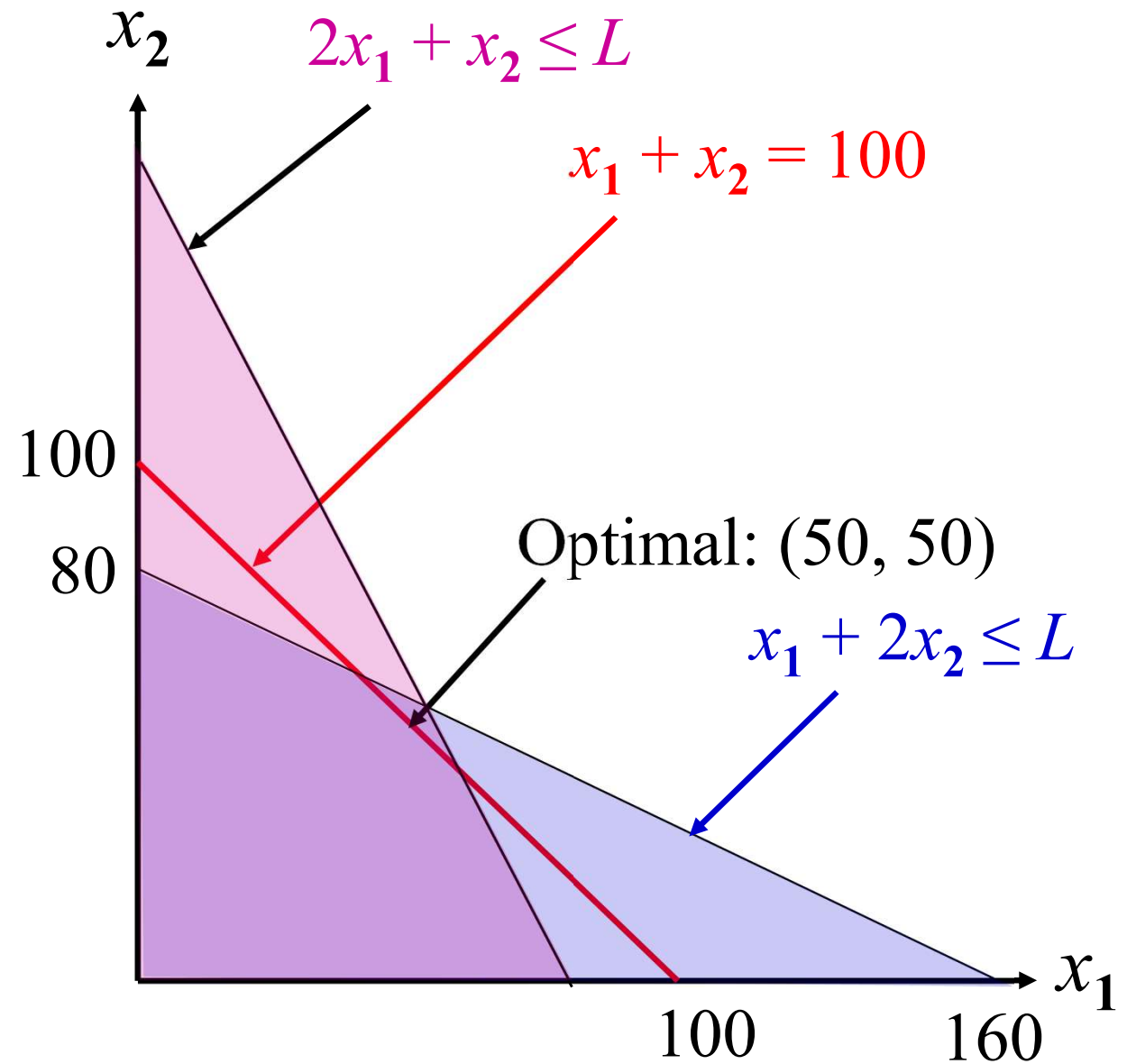
Subject to $x_1 + x_2 = 100$

$$x_1 + 2x_2 \leq L$$

$$2x_1 + x_2 \leq L$$

$$x_1 \geq 0$$

$$x_2 \geq 0$$



LP Problem:

Minimize L

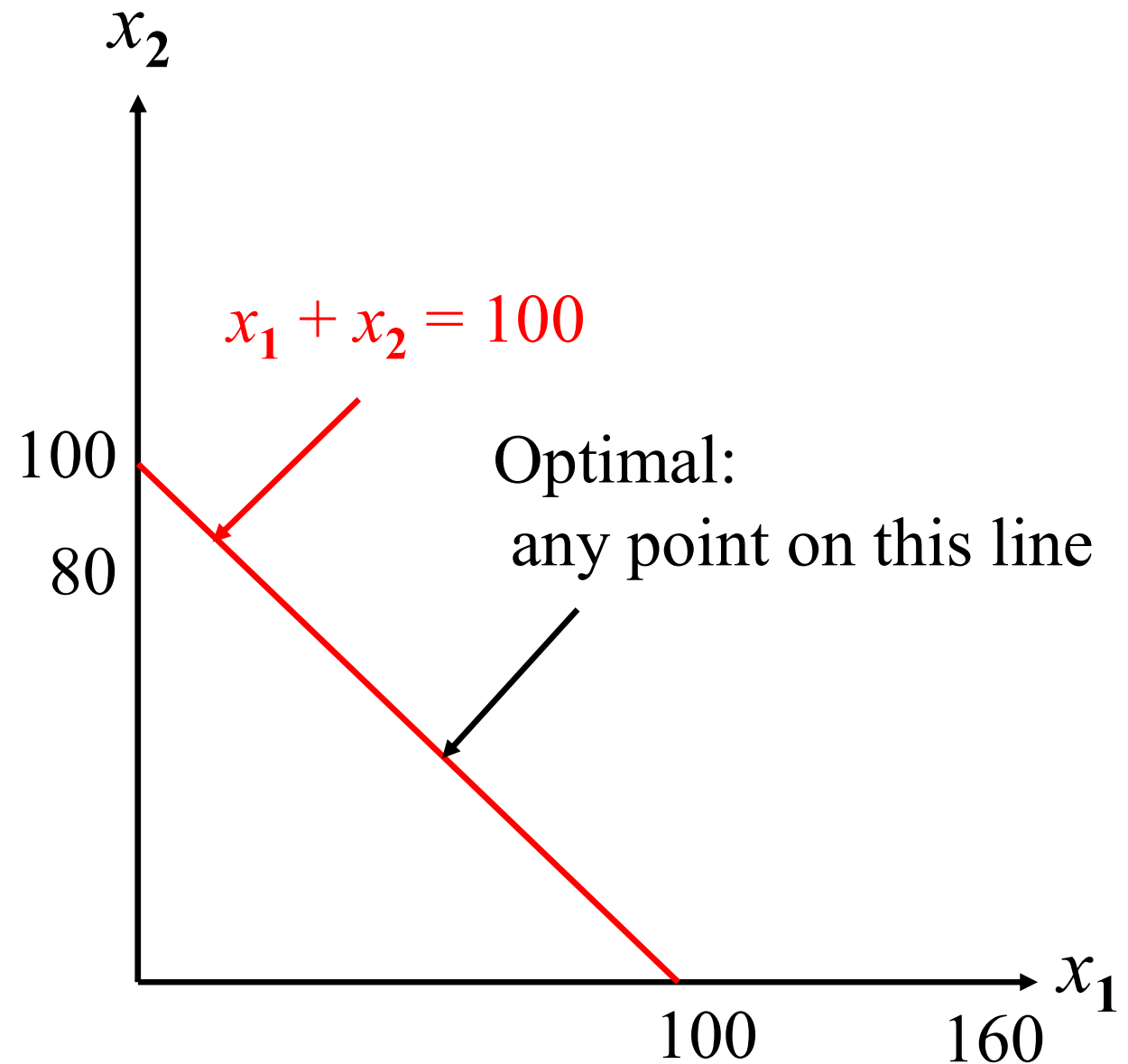
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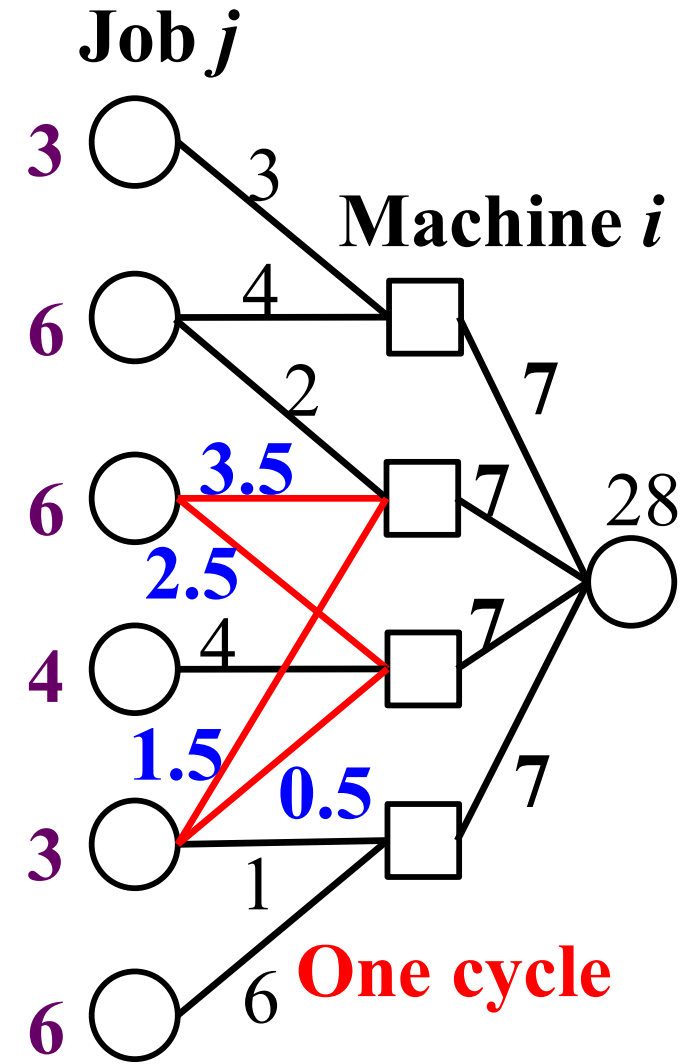
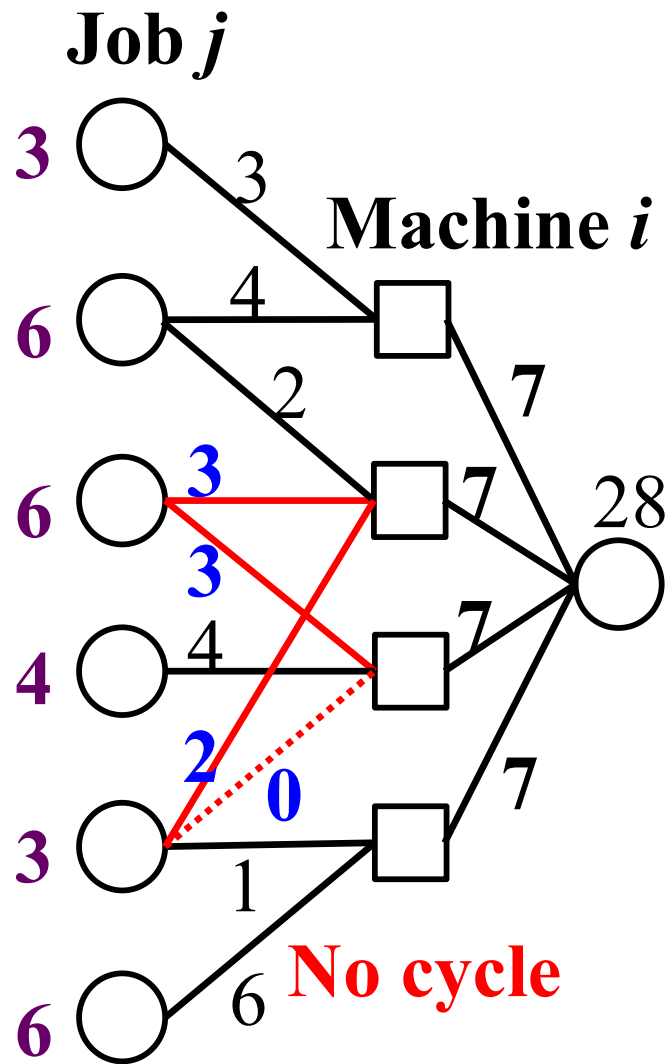
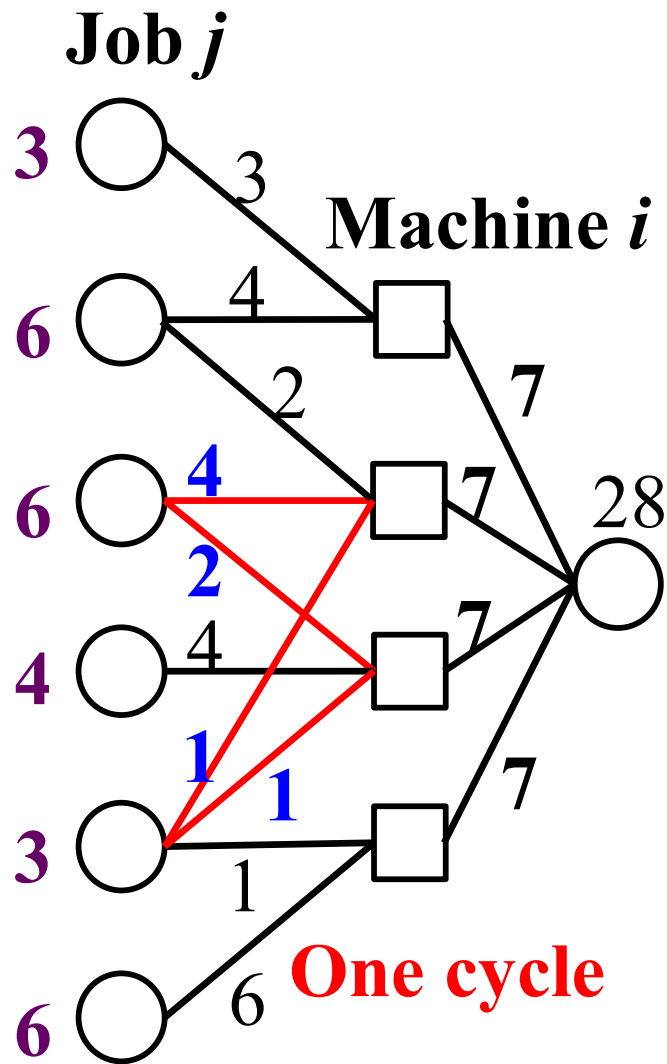
$$2x_1 + 2x_2 \leq L$$

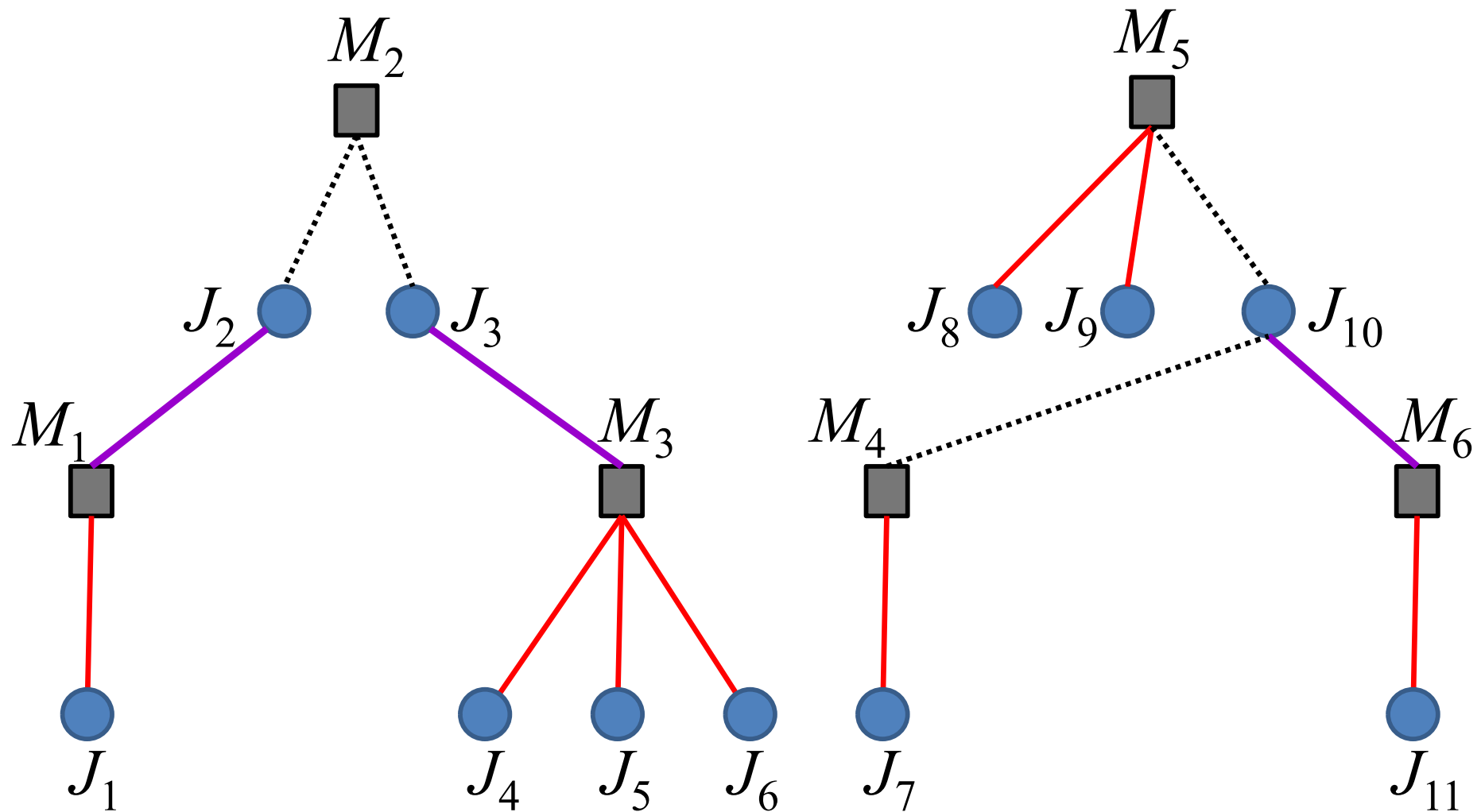
$$x_1 \geq 0$$

$$x_2 \geq 0$$



The following are examples of the optimal solutions of the LP formulation. In Exercise 11-1, a graph should be generated using the LP solution (which should be actually obtained from your LP package). That is, the point of Exercise 11-1 is to examine which graph is actually obtained by your LP package.



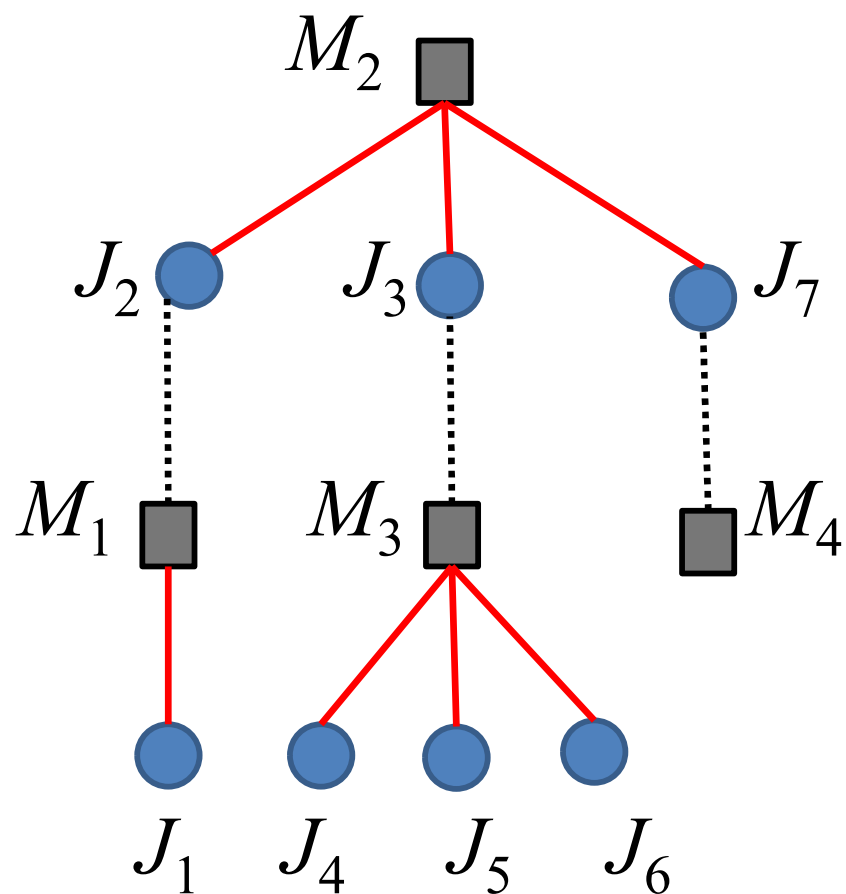
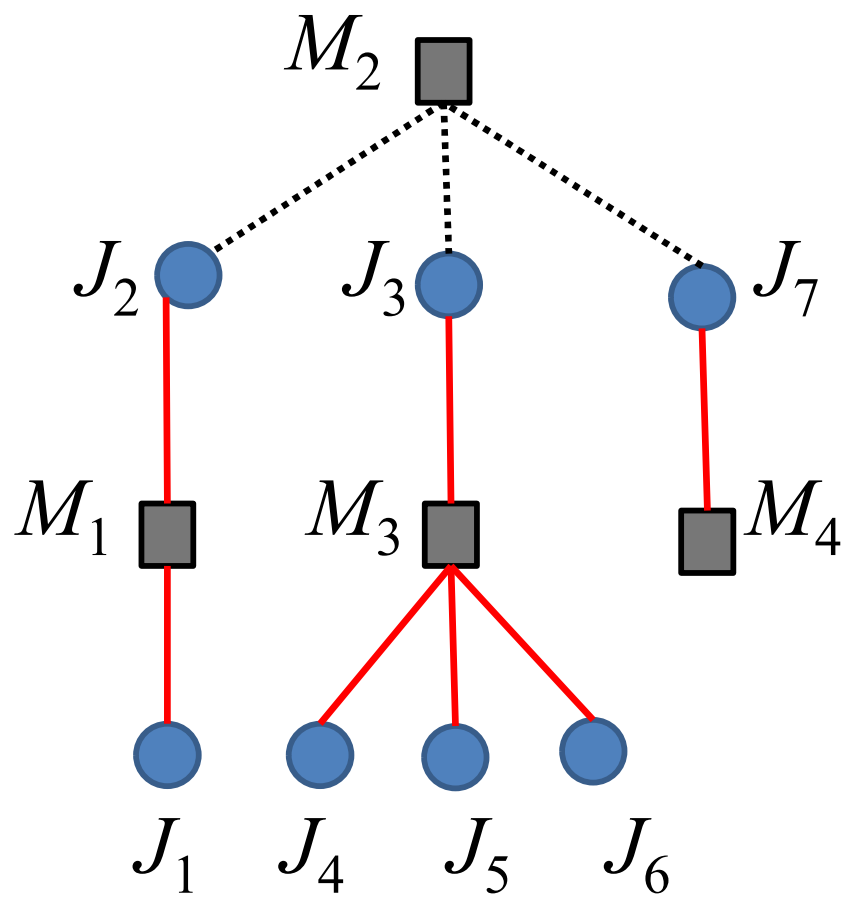
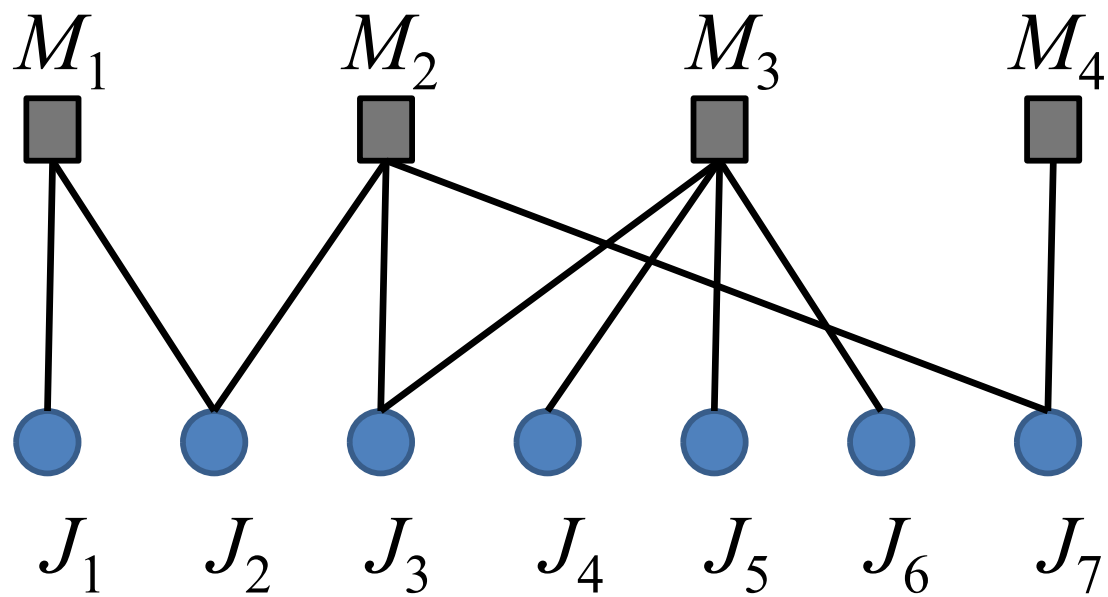


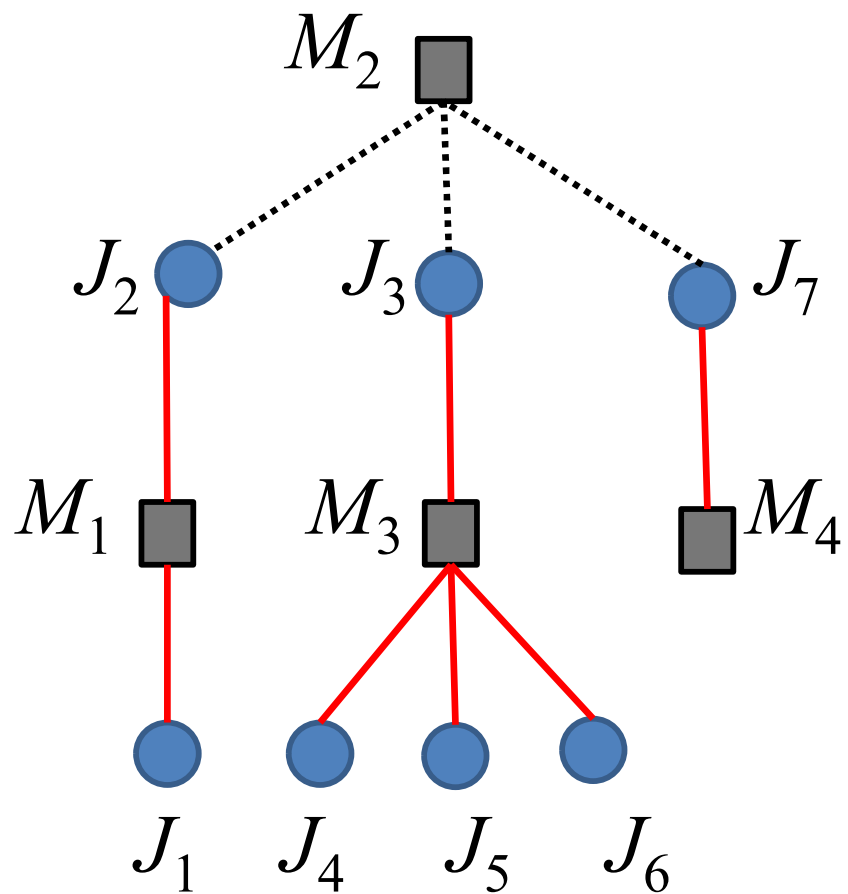
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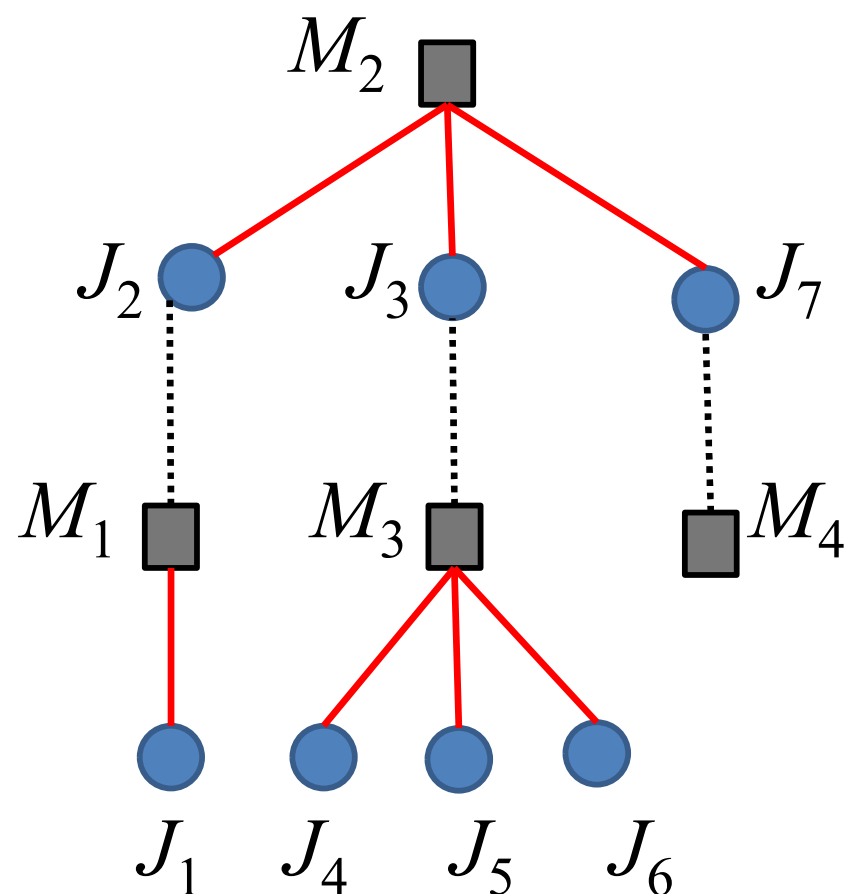
Why ?

(2) Each intermediate job node is assigned to an arbitrary child. (—)

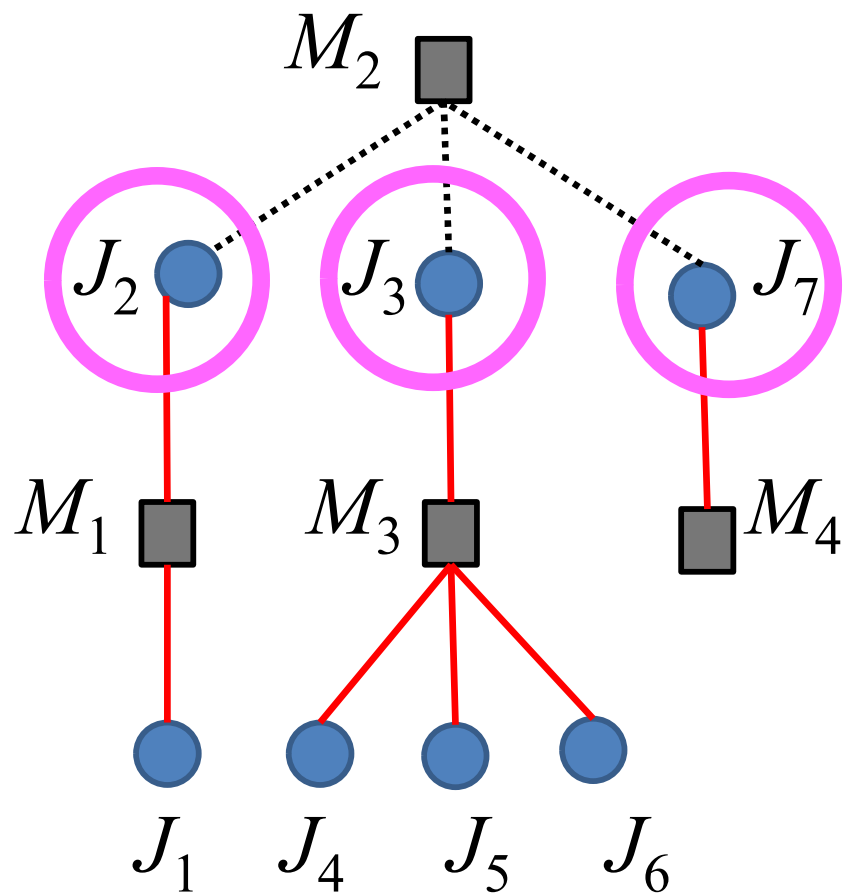




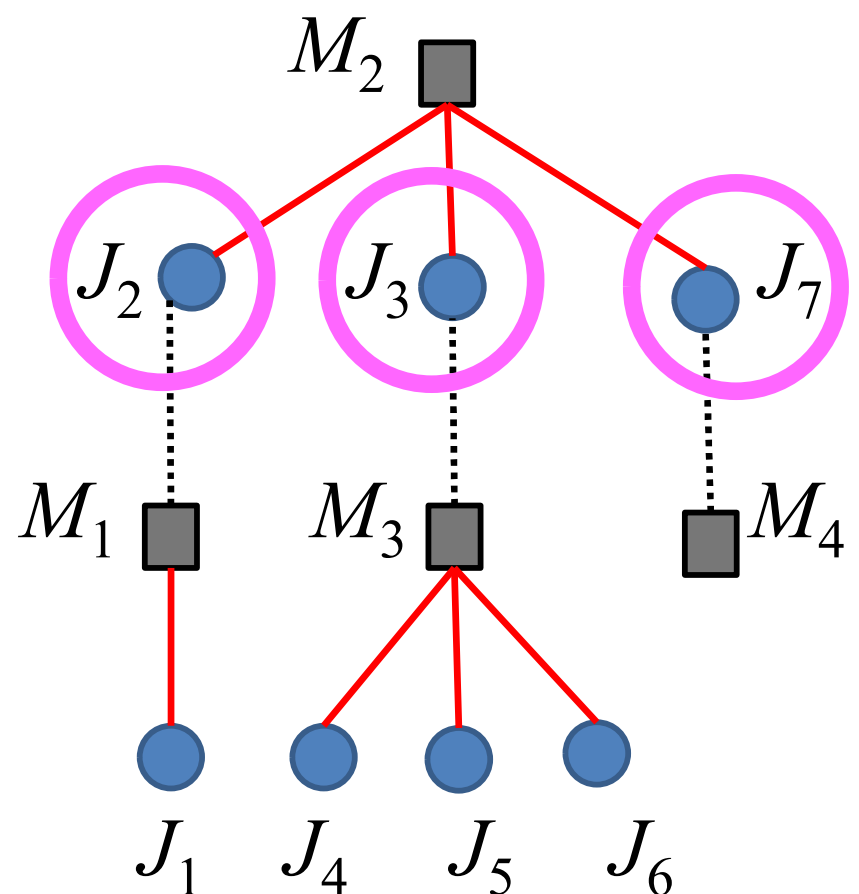
2-Approximation



Not 2-Approximation



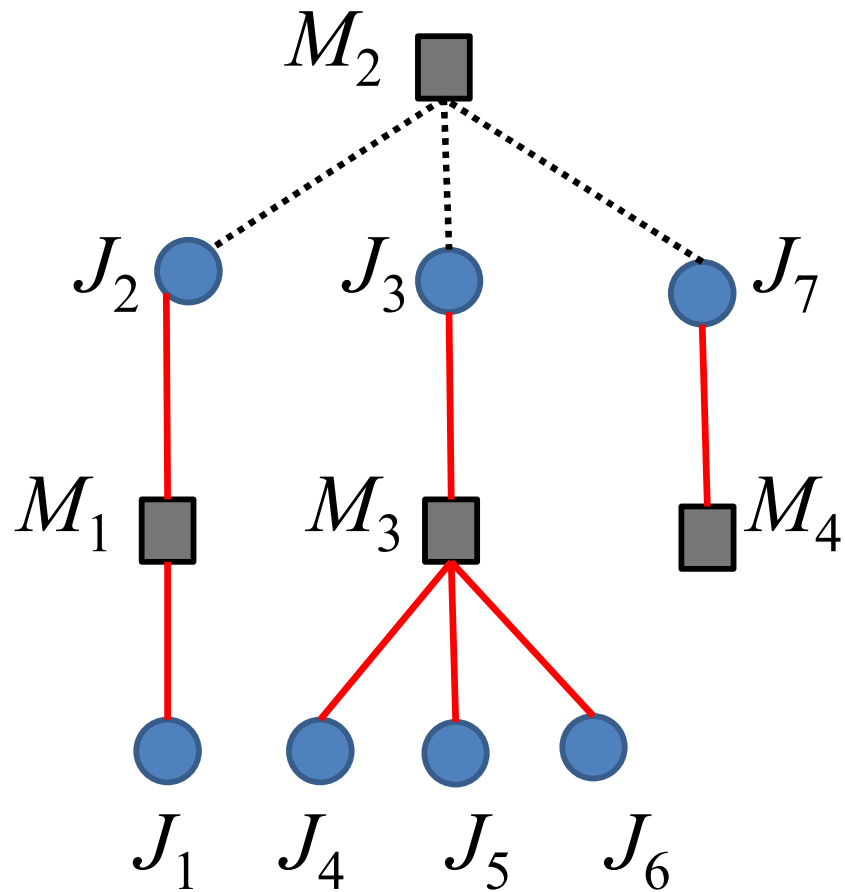
2-Approximation



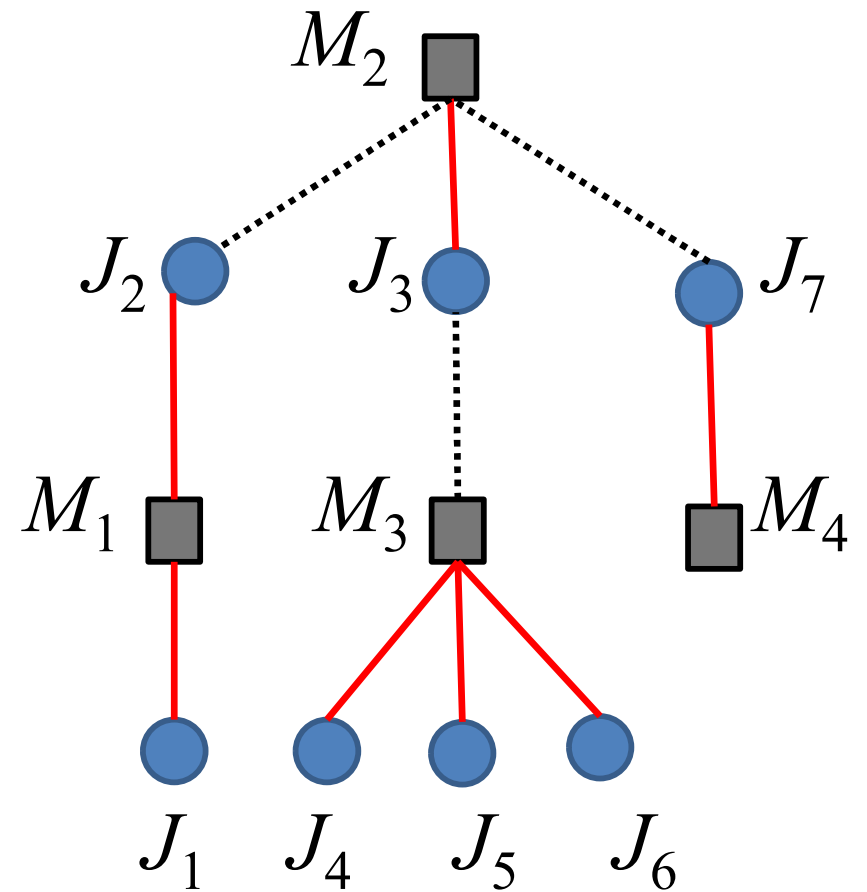
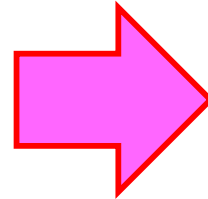
Not 2-Approximation

When t_2, t_3, t_7 are very large and t_1, t_4, t_5, t_6 are very small, the optimal value L^* is close to $\max\{t_2, t_3, t_7\}$. In the right figure, $L = t_2 + t_3 + t_7$ can be larger than $2L^*$ (which can be close to $3L^*$).

If the parent node has no job, it may be a good idea to assign one job to the parent.



2-Approximation



2-Approximation