

In [1]:

```
# from google.colab import drive
```

In [2]:

```
# drive.mount('/content/drive/')
```

## Import the Libraries

In [3]:

```
import numpy as np
import pandas as pd
import matplotlib.pyplot as plt
import tensorflow as tf

import keras
from keras.models import Sequential, Model, load_model
from keras.applications import vgg16
from keras.layers import Dense, Dropout, Activation, Flatten, Conv2D, Input, MaxPooling2D, InputLayer, UpSampling2D, Reshape, UpSampling1D
from keras.layers.normalization import BatchNormalization
from keras.layers.merge import concatenate
from keras import optimizers
from keras.preprocessing.image import ImageDataGenerator, load_img, img_to_array, array_to_img
import pickle
import os
import cv2
import joblib
import math

from keras.wrappers.scikit_learn import KerasClassifier
from keras.utils import np_utils
from keras.utils import multi_gpu_model
from keras.callbacks import Callback
# from keras.utils.OneCycle import OneCycle

import keras.backend as K
from sklearn.model_selection import cross_val_score
from sklearn.model_selection import KFold
from sklearn.pipeline import Pipeline
from sklearn.model_selection import StratifiedKFold
from sklearn.model_selection import train_test_split
from sklearn.metrics import accuracy_score
from sklearn.metrics import confusion_matrix
from sklearn.metrics import classification_report, precision_recall_curve
import seaborn as sns
```

Using TensorFlow backend.

In [4]:

```
PATH="./depth_data_GD"
folders=sorted(os.listdir(PATH))[0:15]
test_folders=sorted(os.listdir(PATH))[15:17]
print(folders)
```

```
['basement_0001a_out', 'basement_0001b_out', 'bathroom_0001_out', 'bathroom_0002_out', 'bathroom_0005_out', 'bathroom_0006_out', 'bathroom_0007_out', 'bathroom_0010_out', 'bathroom_0011_out', 'bathroom_0013_out', 'bathroom_0014a_out', 'bathroom_0016_out', 'bathroom_0019_out', 'bathroom_0023_out', 'bathroom_0024_out']
```

## Create training and Testing Data

In [6]:

```
training_data=[]
depth_data=[]
im_sze1=304
im_sze2=228
depth_sze1=55
depth_sze2=74

for folde in folders:
    #print(folde)
    im_list=sorted(os.listdir(os.path.join(PATH,folde)))
    #print(im_list)

    for img in im_list:
        #print(img)
        if 'jpg' in img:
            im_path=os.path.join(os.path.join(PATH,folde),img)
            #print(im_path)
            new_arr=cv2.imread(im_path)
            new_arr=cv2.resize(new_arr,(im_sze1,im_sze2))

            training_data.append(new_arr)
        elif 'png' in img:
            new_arr=cv2.imread(os.path.join(os.path.join(PATH,folde),img),0)
            new_arr=cv2.resize(new_arr,(depth_sze1,depth_sze2))
            depth_data.append(new_arr)
    #    plt.imshow(new_arr)
    #    plt.show()
```

In [7]:

```

test_data=[]
test_depth_data=[]
im_sze1=304
im_sze2=228
depth_sze1=55
depth_sze2=74

for folde in test_folders:
    #print(folde)
    im_list=sorted(os.listdir(os.path.join(PATH,folde)))
    #print(im_list)

    for img in im_list:
        #print(img)
        if 'jpg' in img:
            im_path=os.path.join(os.path.join(PATH,folde),img)
            #print(im_path)
            new_arr=cv2.imread(im_path)
            new_arr=cv2.resize(new_arr,(im_sze1,im_sze2))

            test_data.append(new_arr)
        elif 'png' in img:
            new_arr=cv2.imread(os.path.join(os.path.join(PATH,folde),img),0)
            new_arr=cv2.resize(new_arr,(depth_sze1,depth_sze2))
            test_depth_data.append(new_arr)
#         plt.imshow(new_arr)
#         plt.show()

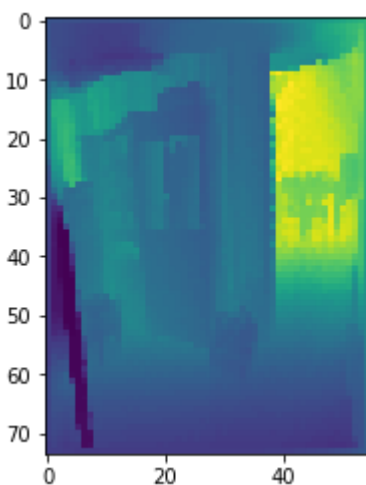
```

In [8]:

```
plt.imshow(depth_data[0])
```

Out[8]:

```
<matplotlib.image.AxesImage at 0x7f55d70acdd8>
```



In [10]:

```
depth_data_scaled=np.array(depth_data).reshape(-1,depth_sze1,depth_sze2,1).astype('float32')/255
training_data_scaled=np.array(training_data).reshape(-1,im_sze2,im_sze1,3).astype('float32')/255
```

In [11]:

```
test_depth_data_scaled=np.array(test_depth_data).reshape(-1,depth_sze1,depth_sze2,1).astype('float32')/255
test_data_scaled=np.array(test_data).reshape(-1,im_sze2,im_sze1,3).astype('float32')/255
```

In [12]:

```
print(depth_data_scaled.shape)

# plt.imshow(np.reshape(depth_data[0],[depth_sze2,depth_sze1]))
# plt.show()

plt.imshow(training_data_scaled[0])
plt.show()
# plt.imshow(np.reshape(depth_data[0],[depth_sze2,depth_sze1]))
# plt.show()
```

(1476, 55, 74, 1)



## Define Custom loss functions

In [13]:

```

def depth_loss(y_true, y_pred):

#     y_true=K.cast(y_true, dtype='float32')

#     y_pred=K.cast(y_pred, dtype='float64')
#     d=K.cast(K.log(y_pred) - K.log(y_true),dtype='float64')

#     log_diff=K.cast(K.sum(K.square(d))/(depth_sze1*depth_sze2),dtype='float64')
#     print('boo')
#     penalty=K.square(K.sum(d))/K.cast(K.square(depth_sze1*depth_sze2),dtype='float64')

    y_true=K.cast(y_true, dtype='float32')

    y_pred=K.cast(y_pred, dtype='float32')

    lnYTrue = K.switch(K.equal(y_true, 0), K.zeros_like(y_true), K.log(y_true))
    #lnYPred = K.switch(K.equal(y_pred, 0), K.zeros_like(y_pred), K.log(y_pred))

    lnYPred=K.tf.where(K.tf.math.is_inf(y_pred), K.tf.zeros_like(y_pred), y_pred
)

    #d=K.cast(K.log(y_pred) - K.log(y_true),dtype='float32')
    d_arr=K.cast(lnYTrue - lnYPred,dtype='float32')

    #d_arr=K.get_value(d)
    #d_arr[d_arr==-np.inf]=0
    #d_arr[d_arr==np.inf]=0
    #bools=K.equal(d, -np.inf)

    #print(K.eval(bools))

    #print(K.int_shape(bools))

    #d_arr = K.switch(K.equal(K.log(y_pred) - K.log(y_true), 0), K.zeros_like(K.log(y_pred) - K.log(y_true)), K.log(y_pred) - K.log(y_true))

    #has_inf = K.tf.constant([-np.inf, 1., shape=(192,192,1)])

    #wh = K.tf.where(K.tf.equal(bools,True))

    #d_arr=K.tf.where(K.tf.math.is_inf(y_pred), K.tf.zeros_like(y_pred), d)
    #d_arr=K.tf.where(K.tf.is_nan(d_arr), K.tf.zeros_like(d_arr), d_arr)

    #print(K.eval(wh))
    #var = K.zeros(shape=(192, 192, 1))
    #print(d_arr)

    #new_d=K.variable(d_arr,dtype='float32')
    #new_d=d_arr

    log_diff=K.cast(K.sum(K.square(d_arr))/(depth_sze1*depth_sze2),dtype='float32')

    print('boo')

    penalty=K.square(K.sum(d_arr))/K.cast(K.square(depth_sze1*depth_sze2),dtype=

```

```
'float32')
```

```
    loss=log_diff-penalty  
    #print(K.eval(loss))
```

```
    return loss
```

In [14]:

```

def depth_loss3(y_true, y_pred):

#     y_true=K.cast(y_true, dtype='float32')

#     y_pred=K.cast(y_pred, dtype='float64')
#     d=K.cast(K.log(y_pred) - K.log(y_true),dtype='float64')

#     log_diff=K.cast(K.sum(K.square(d))/(depth_size1*depth_size2),dtype='float64')
#     print('boo')
#     penalty=K.square(K.sum(d))/K.cast(K.square(depth_size1*depth_size2),dtype='float64')

    y_true=K.cast(y_true, dtype='float32')

    y_pred=K.cast(y_pred, dtype='float32')

    lnYTrue = K.switch(K.equal(y_true, 0), K.zeros_like(y_true), K.log(y_true))
    lnYPred = K.switch(K.equal(y_pred, 0), K.zeros_like(y_pred), K.log(y_pred))

    lnYTrue =K.tf.where(K.tf.math.is_inf(y_true), K.tf.ones_like(y_true), y_true
)

    lnYPred=K.tf.where(K.tf.math.is_inf(y_pred), K.tf.ones_like(y_pred), y_pred)

    #print(K.eval(lnYPred))

    #d=K.cast(K.log(y_pred) - K.log(y_true),dtype='float32')
    d_arr=K.cast(lnYTrue - lnYPred,dtype='float32')

    #d_arr=K.get_value(d)
    #d_arr[d_arr==-np.inf]=0
    #d_arr[d_arr==np.inf]=0
    #bools=K.equal(d, -np.inf)

    #print(K.eval(bools))

    #print(K.int_shape(bools))

    #d_arr = K.switch(K.equal(K.log(y_pred) - K.log(y_true), 0), K.zeros_like(K.log(y_pred) - K.log(y_true)), K.log(y_pred) - K.log(y_true))

    #has_inf = K.tf.constant([-np.inf, 1., shape=(192,192,1)])

    #wh = K.tf.where(K.tf.equal(bools,True))

    #d_arr=K.tf.where(K.tf.math.is_inf(y_pred), K.tf.zeros_like(y_pred), d)
    #d_arr=K.tf.where(K.tf.is_nan(d_arr), K.tf.zeros_like(d_arr), d_arr)

    #print(K.eval(wh))
    #var = K.zeros(shape=(192, 192, 1))
    #print(d_arr)

    #new_d=K.variable(d_arr,dtype='float32')
    #new_d=d_arr

    log_diff=K.cast(K.sum(K.square(d_arr))/(depth_size1*depth_size2),dtype='float32')

```

```
2')  
  
    print('boo')  
  
    penalty=K.square(K.sum(d_arr))/K.cast(K.square(depth_size1*depth_size2),dtype=  
'float32')  
  
    loss=log_diff+penalty  
    #print(K.eval(loss))  
  
    return loss
```



In [15]:

```

def depth_loss2(y_true, y_pred):

#     y_true=K.cast(y_true, dtype='float32')

#     y_pred=K.cast(y_pred, dtype='float64')
#     d=K.cast(K.log(y_pred) - K.log(y_true),dtype='float64')

#     log_diff=K.cast(K.sum(K.square(d))/(depth_sze1*depth_sze2),dtype='float64')
#     print('boo')
#     penalty=K.square(K.sum(d))/K.cast(K.square(depth_sze1*depth_sze2),dtype='float64')

    y_true=K.cast(y_true, dtype='float32')

    y_pred=K.cast(y_pred, dtype='float32')
    d=K.cast((y_pred - y_true),dtype='float32')

    #d_arr=K.get_value(d)
    #d_arr[d_arr==-np.inf]=0
    #d_arr[d_arr==np.inf]=0
    bools=K.equal(d, -np.inf)

    #print(K.eval(bools))

    #print(K.int_shape(bools))
    #has_inf = K.tf.constant([-np.inf, 1., shape=(192,192,1)])
    #wh = K.tf.where(K.tf.equal(bools,True))

    #lnYTrue = K.switch(KB.equal(d, 0), KB.zeros_like(d), KB.log(d))
    #d_arr = K.switch(KB.equal(d, 0), KB.zeros_like(d), KB.log(d))
    #d_arr=K.tf.where(K.tf.math.is_inf(d), K.tf.zeros_like(d), d)

    #d_arr=K.tf.where(K.tf.is_nan(d_arr), K.tf.zeros_like(d_arr), d_arr)

    #print(K.eval(wh))
    #var = K.zeros(shape=(192, 192, 1))
    #print(d_arr)

    #new_d=K.variable(d_arr,dtype='float32')
    #new_d=d_arr

    log_diff=K.cast(K.sum(K.square(d_arr))/(depth_sze1*depth_sze2),dtype='float32')

    print('boo')

    penalty=K.square(K.sum(d_arr))/K.cast(K.square(depth_sze1*depth_sze2),dtype='float32')

    loss=log_diff-penalty
    #print(K.eval(loss))

    return loss

```

## Testing the created loss function

In [16]:

```
y_true = np.random.rand(57,76)
y_pred = np.random.rand(57,76)
y_pred.shape,y_true.shape

print(K.eval(depth_loss3(y_true, y_pred)))

boo
0.17396288
```

## Making the Coarse Sequential Model

In [36]:

```
model=Sequential()

model.add(Conv2D(96,(11,11),strides=(4,4),input_shape=training_data_scaled.shape
[1:],padding='same'))
model.add(BatchNormalization())
model.add(Activation("relu"))
model.add(MaxPooling2D(pool_size=(2,2)))

model.add(Conv2D(256,(5,5),padding='same'))
model.add(BatchNormalization())
model.add(Activation("relu"))
model.add(MaxPooling2D(pool_size=(2,2)))

model.add(Conv2D(384,(3,3),padding='same'))
model.add(BatchNormalization())
model.add(Activation("relu"))
# model.add(MaxPooling2D(pool_size=(2,2)))

model.add(Conv2D(384,(3,3),padding='same'))
model.add(BatchNormalization())
model.add(Activation("relu"))
# model.add(MaxPooling2D(pool_size=(2,2)))

# model.add(Conv2D(256,(3,3),strides=(1,1),padding='same'))
# # model.add(BatchNormalization())
# model.add(Activation("relu"))
# model.add(MaxPooling2D(pool_size=(2,2)))

model.add(Dense(256))
model.add(BatchNormalization())
model.add(Activation("relu"))
model.add(MaxPooling2D(pool_size=(2,2)))
# model.add(Dropout(0.4))

model.add(Flatten())
model.add(Dense(4096))
model.add(BatchNormalization())
model.add(Activation("linear"))
model.add(Dropout(0.4))

model.add(Reshape((64, 64,1)))

model.add(UpSampling2D(size=(2,2)))
model.add(Conv2D(1,(74,55),padding='valid'))
model.add(BatchNormalization())
model.summary()
```

Layer (type)	Output Shape	Param #
conv2d_9 (Conv2D)	(None, 57, 76, 96)	34944
batch_normalization_11 (Batch Normalization)	(None, 57, 76, 96)	384
activation_1 (Activation)	(None, 57, 76, 96)	0
max_pooling2d_5 (MaxPooling2D)	(None, 28, 38, 96)	0
conv2d_10 (Conv2D)	(None, 28, 38, 256)	614656
batch_normalization_12 (Batch Normalization)	(None, 28, 38, 256)	1024
activation_2 (Activation)	(None, 28, 38, 256)	0
max_pooling2d_6 (MaxPooling2D)	(None, 14, 19, 256)	0
conv2d_11 (Conv2D)	(None, 14, 19, 384)	885120
batch_normalization_13 (Batch Normalization)	(None, 14, 19, 384)	1536
activation_3 (Activation)	(None, 14, 19, 384)	0
conv2d_12 (Conv2D)	(None, 14, 19, 384)	1327488
batch_normalization_14 (Batch Normalization)	(None, 14, 19, 384)	1536
activation_4 (Activation)	(None, 14, 19, 384)	0
dense_3 (Dense)	(None, 14, 19, 256)	98560
batch_normalization_15 (Batch Normalization)	(None, 14, 19, 256)	1024
activation_5 (Activation)	(None, 14, 19, 256)	0
max_pooling2d_7 (MaxPooling2D)	(None, 7, 9, 256)	0
flatten_2 (Flatten)	(None, 16128)	0
dense_4 (Dense)	(None, 4096)	66064384
batch_normalization_16 (Batch Normalization)	(None, 4096)	16384
activation_6 (Activation)	(None, 4096)	0
dropout_2 (Dropout)	(None, 4096)	0
reshape_2 (Reshape)	(None, 64, 64, 1)	0
up_sampling2d_2 (UpSampling2D)	(None, 128, 128, 1)	0
conv2d_13 (Conv2D)	(None, 55, 74, 1)	4071
batch_normalization_17 (Batch Normalization)	(None, 55, 74, 1)	4
Total params: 69,051,115		
Trainable params: 69,040,169		
Non-trainable params: 10,946		



In [37]:

```
parallel_model=multi_gpu_model(model,gpus=2)

parallel_model.compile(loss=depth_loss3, optimizer=optimizers.RMSprop(lr=1e-3),m
etrics=[depth_loss3])
histroy=parallel_model.fit(training_data_scaled,depth_data_scaled,batch_size=32,
epochs=20, validation_split=0.1)
```

boo

boo

Train on 1328 samples, validate on 148 samples

Epoch 1/20

1328/1328 [=====] - 16s 12ms/step - loss: 58.4019 - depth\_loss3: 58.4019 - val\_loss: 175.0677 - val\_depth\_loss3: 175.0677

Epoch 2/20

1328/1328 [=====] - 8s 6ms/step - loss: 41.7253 - depth\_loss3: 41.7253 - val\_loss: 237.2015 - val\_depth\_loss3: 237.2015

Epoch 3/20

1328/1328 [=====] - 7s 5ms/step - loss: 30.2943 - depth\_loss3: 30.2943 - val\_loss: 224.6244 - val\_depth\_loss3: 224.6244

Epoch 4/20

1328/1328 [=====] - 7s 5ms/step - loss: 22.3744 - depth\_loss3: 22.3744 - val\_loss: 219.0942 - val\_depth\_loss3: 219.0942

Epoch 5/20

1328/1328 [=====] - 7s 5ms/step - loss: 17.4046 - depth\_loss3: 17.4046 - val\_loss: 52.5806 - val\_depth\_loss3: 52.5806

Epoch 6/20

1328/1328 [=====] - 7s 5ms/step - loss: 14.8895 - depth\_loss3: 14.8895 - val\_loss: 67.6807 - val\_depth\_loss3: 67.6807

Epoch 7/20

1328/1328 [=====] - 7s 5ms/step - loss: 13.1273 - depth\_loss3: 13.1273 - val\_loss: 40.2175 - val\_depth\_loss3: 40.2175

Epoch 8/20

1328/1328 [=====] - 7s 5ms/step - loss: 11.5047 - depth\_loss3: 11.5047 - val\_loss: 26.5950 - val\_depth\_loss3: 26.5950

Epoch 9/20

1328/1328 [=====] - 7s 5ms/step - loss: 10.0043 - depth\_loss3: 10.0043 - val\_loss: 32.8873 - val\_depth\_loss3: 32.8873

Epoch 10/20

1328/1328 [=====] - 7s 5ms/step - loss: 8.5669 - depth\_loss3: 8.5669 - val\_loss: 33.8323 - val\_depth\_loss3: 33.8323

Epoch 11/20

1328/1328 [=====] - 7s 5ms/step - loss: 7.2573 - depth\_loss3: 7.2573 - val\_loss: 30.7151 - val\_depth\_loss3: 30.7151

Epoch 12/20

1328/1328 [=====] - 7s 5ms/step - loss: 6.0811 - depth\_loss3: 6.0811 - val\_loss: 22.9839 - val\_depth\_loss3: 22.9839

Epoch 13/20

1328/1328 [=====] - 7s 5ms/step - loss: 4.9593 - depth\_loss3: 4.9593 - val\_loss: 16.7523 - val\_depth\_loss3: 16.7523

Epoch 14/20

1328/1328 [=====] - 7s 5ms/step - loss: 4.0516 - depth\_loss3: 4.0516 - val\_loss: 8.0452 - val\_depth\_loss3: 8.0452

Epoch 15/20

1328/1328 [=====] - 7s 5ms/step - loss: 3.1

559 - depth\_loss3: 3.1559 - val\_loss: 11.4017 - val\_depth\_loss3: 11.4017

Epoch 16/20

1328/1328 [=====] - 7s 5ms/step - loss: 2.4386 - val\_loss: 7.8825 - val\_depth\_loss3: 7.8825

Epoch 17/20

1328/1328 [=====] - 7s 5ms/step - loss: 1.7644 - val\_loss: 3.5889 - val\_depth\_loss3: 3.5889

Epoch 18/20

1328/1328 [=====] - 7s 5ms/step - loss: 1.2548 - val\_loss: 2.9372 - val\_depth\_loss3: 2.9372

Epoch 19/20

1328/1328 [=====] - 7s 5ms/step - loss: 0.8685 - val\_loss: 2.4765 - val\_depth\_loss3: 2.4765

Epoch 20/20

1328/1328 [=====] - 7s 5ms/step - loss: 0.5862 - val\_loss: 1.1630 - val\_depth\_loss3: 1.1630

## Actual Images

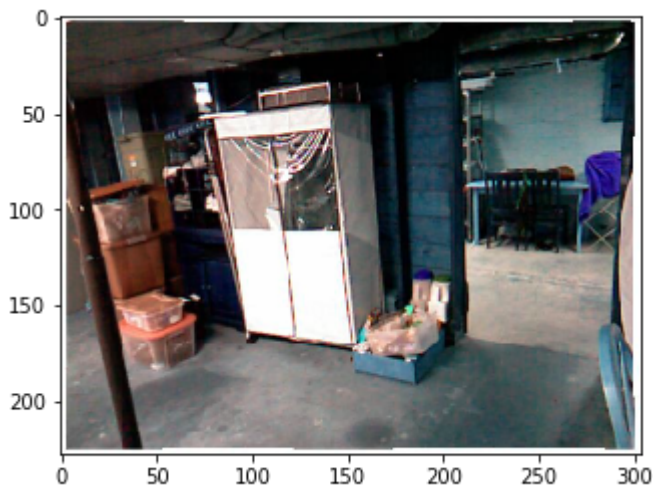


In [41]:

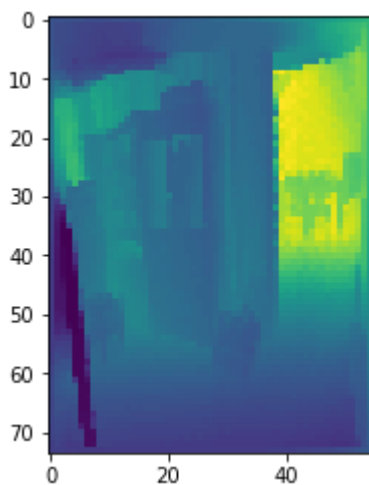
```
# print(training_data[0,:].shape)
# print(np.reshape(training_data[0,:],[im_sze1,im_sze2,3]).shape)
plt.imshow(training_data[0])
plt.show()

print(np.reshape(depth_data[0],[depth_sze1,depth_sze2]).shape)
# plt.imshow(np.reshape(depth_data[0],[depth_sze2,depth_sze1]))
plt.imshow(depth_data[0])

plt.show()
```



(55, 74)



In [46]:

```
y_pred_prob=parallel_model.predict(np.reshape(training_data[0]/255,[-1,im_sze2,im_sze1,3]))
y_pred_prob.shape
np.reshape(y_pred_prob,[depth_sze2,depth_sze1]).shape
```

Out[46]:

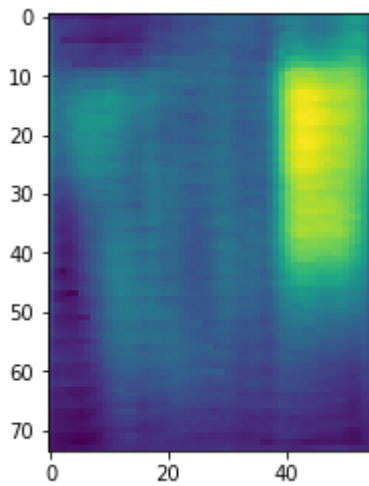
(74, 55)

## Predicted Coarse Image

In [47]:

```
print(np.reshape(y_pred_prob*255,[depth_size2,depth_size1]).shape)
plt.imshow(np.reshape(y_pred_prob*255,[depth_size2,depth_size1]))
plt.show()
```

(74, 55)



## Sample Prediction on Training Dataset

In [48]:

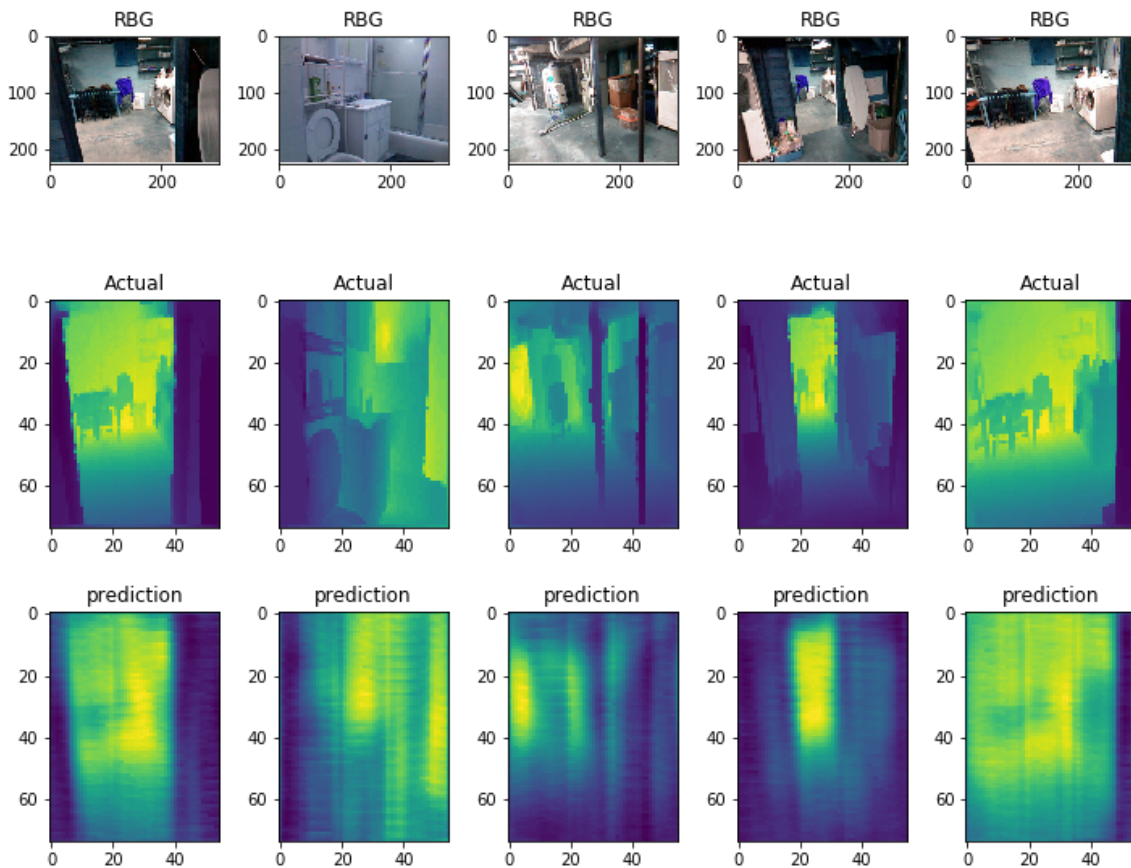
```
f = plt.figure(figsize=(10,8))
i=1
num_select=5

select=np.random.choice(len(training_data), num_select, replace=False)
for i in range(1,num_select+1):

    ax1=plt.subplot(3, num_select, i)
    ax1.imshow(training_data[select[i-1]])
    ax1.set_title('RBG')

    ax2=plt.subplot(3, num_select, i+num_select)
    ax2.imshow(depth_data[select[i-1]])
    ax2.set_title('Actual')

    y_pred_prob=parallel_model.predict(np.reshape(training_data[select[i-1]]/255
,[-1,im_size2,im_size1,3]))
    ax3=plt.subplot(3, num_select, i+2*num_select)
    ax3.imshow(np.reshape(y_pred_prob,[depth_size2,depth_size1]))
    ax3.set_title('prediction')
    #i=i+1
plt.tight_layout()
plt.show()
```



# Coarse Functional Model

In [49]:

```

first_layer=Input(training_data_scaled.shape[1:])
conv1=Conv2D(96,(11,11),strides=(4,4),activation='relu',padding='same')(first_la
yer)
b1=BatchNormalization()(conv1)
p1=MaxPooling2D(pool_size=(2,2))(b1)

conv2=Conv2D(256,(5,5),activation='relu',padding='same')(p1)
b2=BatchNormalization()(conv2)
p2=MaxPooling2D(pool_size=(2,2))(b2)

conv3=Conv2D(384,(3,3),activation='relu',padding='same')(p2)
b3=BatchNormalization()(conv3)

conv4=Conv2D(384,(3,3),activation='relu',padding='same')(b3)
b4=BatchNormalization()(conv4)

Dlayer1=Dense(256,activation='relu')(b4)
b5=BatchNormalization()(Dlayer1)
p5=MaxPooling2D(pool_size=(2,2))(b5)

flat=Flatten()(p5)
flat=Dense(4096,activation='linear')(flat)
flat=BatchNormalization()(flat)
flat=Dropout(0.4)(flat)

mat=Reshape((64,64,1))(flat)

upsamp=UpSampling2D((2,2))(mat)

out1=Conv2D(1,(74,55))(upsamp)
out1=BatchNormalization()(out1)
# model.add(Flatten())
# model.add(Dense(4096))
# model.add(BatchNormalization())
# model.add(Activation("linear"))
# model.add(Dropout(0.4))

# model.add(Reshape((64, 64,1)))

# model.add(UpSampling2D(size=(2,2)))
# model.add(Conv2D(1,(74,55),padding='valid'))
model1=Model(inputs=first_layer,outputs=out1)
model1.summary()

```

Layer (type)	Output Shape	Param #
input_3 (InputLayer)	(None, 228, 304, 3)	0
conv2d_14 (Conv2D)	(None, 57, 76, 96)	34944
batch_normalization_18 (Batch Normalization)	(None, 57, 76, 96)	384
max_pooling2d_8 (MaxPooling2D)	(None, 28, 38, 96)	0
conv2d_15 (Conv2D)	(None, 28, 38, 256)	614656
batch_normalization_19 (Batch Normalization)	(None, 28, 38, 256)	1024
max_pooling2d_9 (MaxPooling2D)	(None, 14, 19, 256)	0
conv2d_16 (Conv2D)	(None, 14, 19, 384)	885120
batch_normalization_20 (Batch Normalization)	(None, 14, 19, 384)	1536
conv2d_17 (Conv2D)	(None, 14, 19, 384)	1327488
batch_normalization_21 (Batch Normalization)	(None, 14, 19, 384)	1536
dense_5 (Dense)	(None, 14, 19, 256)	98560
batch_normalization_22 (Batch Normalization)	(None, 14, 19, 256)	1024
max_pooling2d_10 (MaxPooling2D)	(None, 7, 9, 256)	0
flatten_3 (Flatten)	(None, 16128)	0
dense_6 (Dense)	(None, 4096)	66064384
batch_normalization_23 (Batch Normalization)	(None, 4096)	16384
dropout_3 (Dropout)	(None, 4096)	0
reshape_3 (Reshape)	(None, 64, 64, 1)	0
up_sampling2d_3 (UpSampling2D)	(None, 128, 128, 1)	0
conv2d_18 (Conv2D)	(None, 55, 74, 1)	4071
batch_normalization_24 (Batch Normalization)	(None, 55, 74, 1)	4
Total params: 69,051,115		
Trainable params: 69,040,169		
Non-trainable params: 10,946		

In [50]:

```
# print(depth_data_scaled[0][:,:,0].shape)
# plt.imshow(depth_data_scaled[0][:,:,0])
```

model1.output

Out[50]:

```
<tf.Tensor 'batch_normalization_24/cond/Merge:0' shape=(?, 55, 74,
1) dtype=float32>
```

In [51]:

```
parallel_model2=multi_gpu_model(model1,gpus=2)

parallel_model2.compile(loss=depth_loss3, optimizer=optimizers.RMSprop(lr=1e-3),
metrics=[depth_loss3])
histroy=parallel_model2.fit(training_data_scaled,depth_data_scaled,batch_size=32
,epochs=30, validation_split=0.1)
```



boo

boo

Train on 1328 samples, validate on 148 samples

Epoch 1/30

1328/1328 [=====] - 12s 9ms/step - loss: 5  
8.5409 - depth\_loss3: 58.5409 - val\_loss: 339.6501 - val\_depth\_loss  
3: 339.6501

Epoch 2/30

1328/1328 [=====] - 7s 5ms/step - loss: 41.  
8850 - depth\_loss3: 41.8850 - val\_loss: 749.4695 - val\_depth\_loss3:  
749.4695

Epoch 3/30

1328/1328 [=====] - 7s 5ms/step - loss: 30.  
1996 - depth\_loss3: 30.1996 - val\_loss: 135.5185 - val\_depth\_loss3:  
135.5185

Epoch 4/30

1328/1328 [=====] - 7s 5ms/step - loss: 22.  
3063 - depth\_loss3: 22.3063 - val\_loss: 186.8483 - val\_depth\_loss3:  
186.8483

Epoch 5/30

1328/1328 [=====] - 7s 5ms/step - loss: 17.  
4000 - depth\_loss3: 17.4000 - val\_loss: 148.7182 - val\_depth\_loss3:  
148.7182

Epoch 6/30

1328/1328 [=====] - 7s 5ms/step - loss: 14.  
9231 - depth\_loss3: 14.9231 - val\_loss: 78.6712 - val\_depth\_loss3: 7  
8.6712

Epoch 7/30

1328/1328 [=====] - 7s 5ms/step - loss: 13.  
0971 - depth\_loss3: 13.0971 - val\_loss: 47.3203 - val\_depth\_loss3: 4  
7.3203

Epoch 8/30

1328/1328 [=====] - 7s 5ms/step - loss: 11.  
4683 - depth\_loss3: 11.4683 - val\_loss: 21.4715 - val\_depth\_loss3: 2  
1.4715

Epoch 9/30

1328/1328 [=====] - 7s 5ms/step - loss: 9.9  
608 - depth\_loss3: 9.9608 - val\_loss: 39.4835 - val\_depth\_loss3: 39.  
4835

Epoch 10/30

1328/1328 [=====] - 7s 5ms/step - loss: 8.5  
458 - depth\_loss3: 8.5458 - val\_loss: 25.8436 - val\_depth\_loss3: 25.  
8436

Epoch 11/30

1328/1328 [=====] - 7s 5ms/step - loss: 7.1  
934 - depth\_loss3: 7.1934 - val\_loss: 23.0582 - val\_depth\_loss3: 23.  
0582

Epoch 12/30

1328/1328 [=====] - 7s 5ms/step - loss: 6.1  
131 - depth\_loss3: 6.1131 - val\_loss: 13.9052 - val\_depth\_loss3: 13.  
9052

Epoch 13/30

1328/1328 [=====] - 7s 5ms/step - loss: 5.0  
152 - depth\_loss3: 5.0152 - val\_loss: 10.4638 - val\_depth\_loss3: 10.  
4638

Epoch 14/30

1328/1328 [=====] - 7s 5ms/step - loss: 4.0  
058 - depth\_loss3: 4.0058 - val\_loss: 10.9431 - val\_depth\_loss3: 10.  
9431

Epoch 15/30

1328/1328 [=====] - 7s 5ms/step - loss: 3.2

428 - depth\_loss3: 3.2428 - val\_loss: 4.7427 - val\_depth\_loss3: 4.7427

Epoch 16/30

1328/1328 [=====] - 7s 5ms/step - loss: 2.5

341 - depth\_loss3: 2.5341 - val\_loss: 4.9989 - val\_depth\_loss3: 4.9989

Epoch 17/30

1328/1328 [=====] - 7s 5ms/step - loss: 1.7

839 - depth\_loss3: 1.7839 - val\_loss: 4.3731 - val\_depth\_loss3: 4.3731

Epoch 18/30

1328/1328 [=====] - 7s 5ms/step - loss: 1.2

965 - depth\_loss3: 1.2965 - val\_loss: 1.6622 - val\_depth\_loss3: 1.6622

Epoch 19/30

1328/1328 [=====] - 7s 5ms/step - loss: 0.8

706 - depth\_loss3: 0.8706 - val\_loss: 2.0731 - val\_depth\_loss3: 2.0731

Epoch 20/30

1328/1328 [=====] - 7s 5ms/step - loss: 0.5

090 - depth\_loss3: 0.5090 - val\_loss: 1.2761 - val\_depth\_loss3: 1.2761

Epoch 21/30

1328/1328 [=====] - 7s 5ms/step - loss: 0.2

807 - depth\_loss3: 0.2807 - val\_loss: 0.7553 - val\_depth\_loss3: 0.7553

Epoch 22/30

1328/1328 [=====] - 7s 5ms/step - loss: 0.1

825 - depth\_loss3: 0.1825 - val\_loss: 0.5307 - val\_depth\_loss3: 0.5307

Epoch 23/30

1328/1328 [=====] - 7s 5ms/step - loss: 0.1

959 - depth\_loss3: 0.1959 - val\_loss: 0.4980 - val\_depth\_loss3: 0.4980

Epoch 24/30

1328/1328 [=====] - 7s 5ms/step - loss: 0.1

280 - depth\_loss3: 0.1280 - val\_loss: 0.3572 - val\_depth\_loss3: 0.3572

Epoch 25/30

1328/1328 [=====] - 7s 5ms/step - loss: 0.1

569 - depth\_loss3: 0.1569 - val\_loss: 0.4036 - val\_depth\_loss3: 0.4036

Epoch 26/30

1328/1328 [=====] - 7s 5ms/step - loss: 0.1

655 - depth\_loss3: 0.1655 - val\_loss: 0.4572 - val\_depth\_loss3: 0.4572

Epoch 27/30

1328/1328 [=====] - 7s 5ms/step - loss: 0.1

582 - depth\_loss3: 0.1582 - val\_loss: 0.3631 - val\_depth\_loss3: 0.3631

Epoch 28/30

1328/1328 [=====] - 7s 5ms/step - loss: 0.1

597 - depth\_loss3: 0.1597 - val\_loss: 0.4569 - val\_depth\_loss3: 0.4569

Epoch 29/30

1328/1328 [=====] - 7s 5ms/step - loss: 0.1

576 - depth\_loss3: 0.1576 - val\_loss: 0.4310 - val\_depth\_loss3: 0.4310

Epoch 30/30

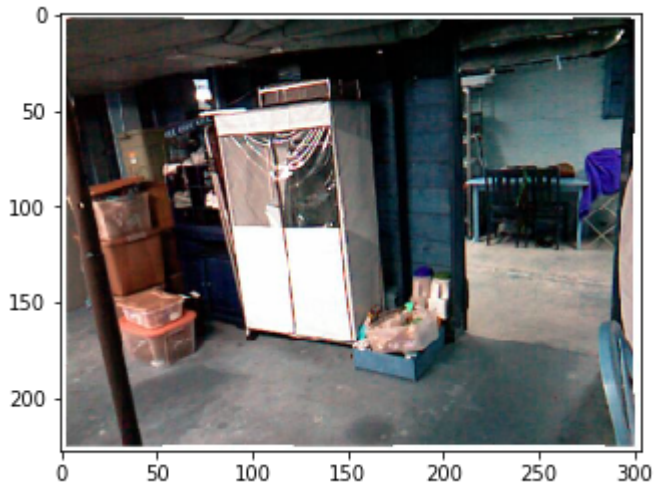
1328/1328 [=====] - 7s 5ms/step - loss: 0.1

995 - depth\_loss3: 0.1995 - val\_loss: 0.3763 - val\_depth\_loss3: 0.3763

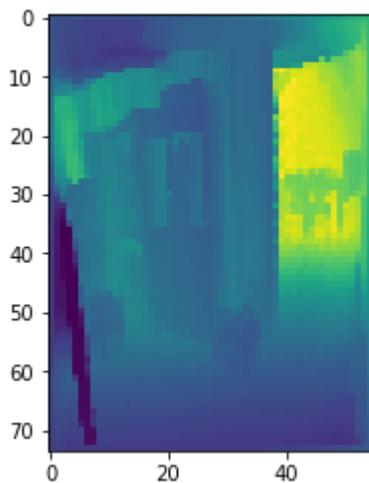
In [56]:

```
# print(training_data[0,:].shape)
# print(np.reshape(training_data[0,:],[im_size1,im_size2,3]).shape)
plt.imshow(training_data[0])
plt.show()
```

```
print(np.reshape(depth_data[0],[depth_size1,depth_size2]).shape)
plt.imshow(np.reshape(depth_data[0],[depth_size2,depth_size1]))
plt.show()
```



(55, 74)

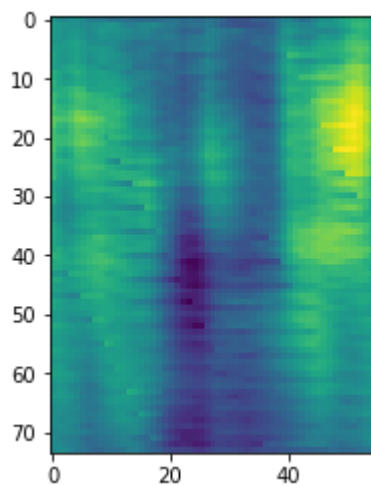


In [57]:

```
y_pred_prob=parallel_model2.predict(np.reshape(training_data[0],[-1,im_size2,im_size1,3]))
```

In [58]:

```
plt.imshow(np.reshape(y_pred_prob*255,[depth_size2,depth_size1]))  
plt.show()
```



**Sample Prediction on random examples from Training Dataset**

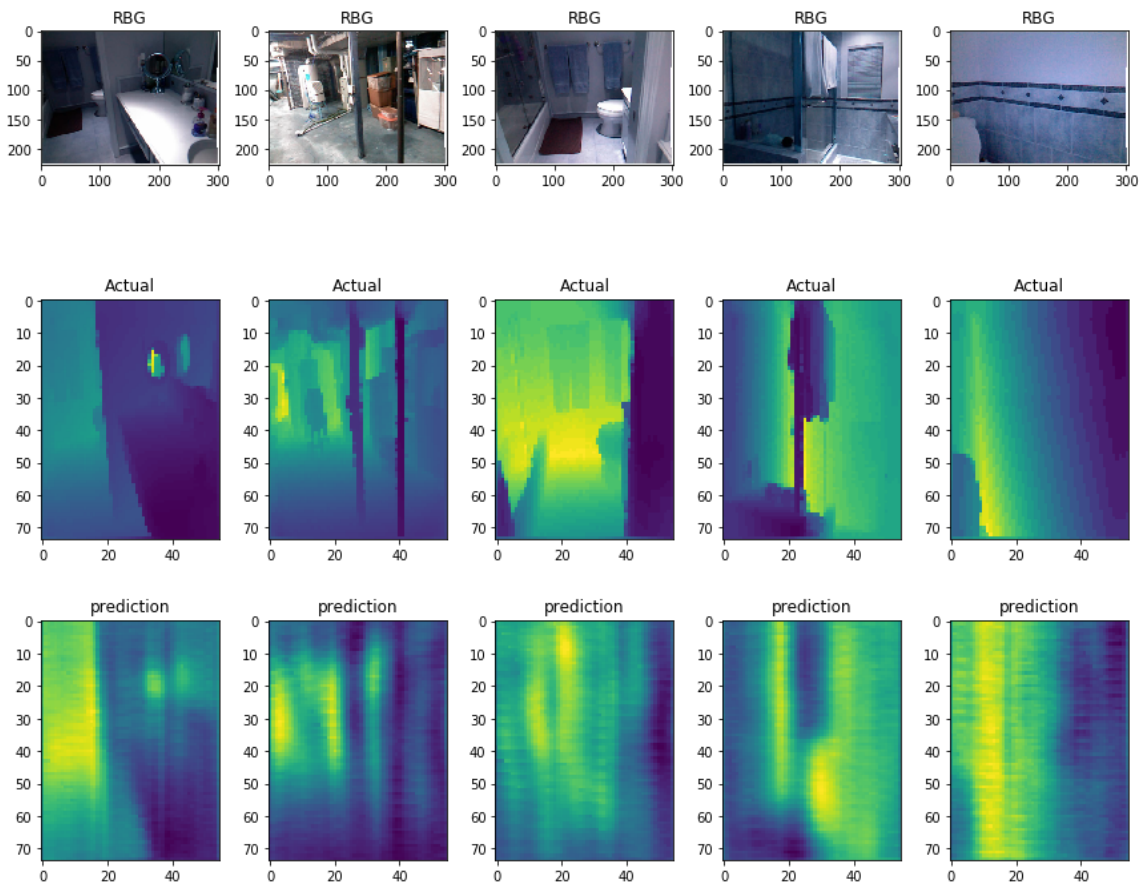
In [59]:

```
f = plt.figure(figsize=(12,10))
i=1
num_select=5
select=np.random.choice(len(training_data), num_select, replace=False)
for i in range(1,num_select+1):

    ax1=plt.subplot(3, num_select, i)
    ax1.imshow(training_data[select[i-1]])
    ax1.set_title('RGB')

    ax2=plt.subplot(3, num_select, i+num_select)
    ax2.imshow(depth_data[select[i-1]])
    ax2.set_title('Actual')

    y_pred_prob=parallel_model2.predict(np.reshape(training_data[select[i-1]]/25
5,[-1,im_size2,im_size1,3]))
    ax3=plt.subplot(3, num_select, i+2*num_select)
    ax3.imshow(np.reshape(y_pred_prob,[depth_size2,depth_size1]))
    ax3.set_title('prediction')
    #i=i+1
plt.tight_layout()
plt.show()
```



In [ ]:

```
plt.imshow(training_data[select[1]])
```

## Making the Full Model with Coarse + Fine Tune layers

In [18]:

```
second_layer=Input(training_data_scaled.shape[1:])
conv21=Conv2D(63,(9,9),strides=(2,2),padding='valid')(first_layer)
b21=BatchNormalization()(conv21)
p21=MaxPooling2D(pool_size=(2,2))(b21)

Concat=concatenate([out1, p21])
# print(type(Concat),type(p21))
conv22=Conv2D(64,(5,5),padding='same')(Concat)
b22=BatchNormalization()(conv22)

out=Conv2D(1,(5,5),padding='same')(b22)
out=BatchNormalization()(out)

final_model= Model(inputs=first_layer,outputs=out)
final_model.summary()
```

Layer (type) connected to	Output Shape	Param #	Con
input_1 (InputLayer)	(None, 228, 304, 3)	0	
conv2d_1 (Conv2D) ut_1[0][0]	(None, 57, 76, 96)	34944	inp
batch_normalization_1 (BatchNor v2d_1[0][0]	(None, 57, 76, 96)	384	con
max_pooling2d_1 (MaxPooling2D) ch_normalization_1[0][0]	(None, 28, 38, 96)	0	bat
conv2d_2 (Conv2D) _pooling2d_1[0][0]	(None, 28, 38, 256)	614656	max
batch_normalization_2 (BatchNor v2d_2[0][0]	(None, 28, 38, 256)	1024	con
max_pooling2d_2 (MaxPooling2D) ch_normalization_2[0][0]	(None, 14, 19, 256)	0	bat
conv2d_3 (Conv2D) _pooling2d_2[0][0]	(None, 14, 19, 384)	885120	max
batch_normalization_3 (BatchNor v2d_3[0][0]	(None, 14, 19, 384)	1536	con
conv2d_4 (Conv2D) ch_normalization_3[0][0]	(None, 14, 19, 384)	1327488	bat
batch_normalization_4 (BatchNor v2d_4[0][0]	(None, 14, 19, 384)	1536	con
dense_1 (Dense) ch_normalization_4[0][0]	(None, 14, 19, 256)	98560	bat
batch_normalization_5 (BatchNor se_1[0][0]	(None, 14, 19, 256)	1024	den
max_pooling2d_3 (MaxPooling2D) ch_normalization_5[0][0]	(None, 7, 9, 256)	0	bat



flatten_1 (Flatten) _pooling2d_3[0][0]	(None, 16128)	0	max
dense_2 (Dense) tten_1[0][0]	(None, 4096)	66064384	fla
batch_normalization_6 (BatchNor se_2[0][0]	(None, 4096)	16384	den
dropout_1 (Dropout) ch_normalization_6[0][0]	(None, 4096)	0	bat
reshape_1 (Reshape) pout_1[0][0]	(None, 64, 64, 1)	0	dro
up_sampling2d_1 (UpSampling2D) hape_1[0][0]	(None, 128, 128, 1)	0	res
conv2d_6 (Conv2D) ut_1[0][0]	(None, 110, 148, 63)	15372	inp
conv2d_5 (Conv2D) sampling2d_1[0][0]	(None, 55, 74, 1)	4071	up_
batch_normalization_8 (BatchNor v2d_6[0][0]	(None, 110, 148, 63)	252	con
batch_normalization_7 (BatchNor v2d_5[0][0]	(None, 55, 74, 1)	4	con
max_pooling2d_4 (MaxPooling2D) ch_normalization_8[0][0]	(None, 55, 74, 63)	0	bat
concatenate_1 (Concatenate) ch_normalization_7[0][0]	(None, 55, 74, 64)	0	bat
			max
_pooling2d_4[0][0]			
conv2d_7 (Conv2D) cate_1[0][0]	(None, 55, 74, 64)	102464	con
batch_normalization_9 (BatchNor v2d_7[0][0]	(None, 55, 74, 64)	256	con
conv2d_8 (Conv2D) ch_normalization_9[0][0]	(None, 55, 74, 1)	1601	bat

```
batch_normalization_10 (BatchNo (None, 55, 74, 1)    4      con
v2d_8[0][0])
```

```
=====
Total params: 69,171,064
Trainable params: 69,159,862
Non-trainable params: 11,202
```

In [19]:

```
# model2=Sequential()

# model2.add(Conv2D(63,(9,9),strides=(2,2),input_shape=training_data_scaled.shap
e[1:],padding='valid'))
# model2.add(BatchNormalization())
# model2.add(Activation("relu"))
# model2.add(MaxPooling2D(pool_size=(2,2)))

# model2.summary()
# Concat=concatenate([model.output, model2.output])
# final_model= Model(inputs=[model.input,model2.input],outputs=Concat)

# newlayer=Input((55,74,64))
# conv1=Conv2D(64,kernel_size=2,activation='relu')(newlayer)
# conv1=BatchNormalization()(conv1)
# # conv2=Conv2D(64,kernel_size=5,activation='relu')(conv1)

# output=Conv2D(1,kernel_size=2,activation='linear')(conv1)
# # model.add(UpSampling2D(size=(2,2)))
# # model.add(Conv2D(1,(72,53),padding='valid'))

# fin=Model(inputs=model.input, outputs=output)
# """
# CONCATENATION
# model.add(Conv2D(64,(5,5),padding='same'))
# model.add(BatchNormalization())
# model.add(Activation("relu"))
# model.add(MaxPooling2D(pool_size=(2,2)))
# """

# output.summary()
```

In [20]:

```
parallel_model3=multi_gpu_model(final_model,gpus=3)

parallel_model3.compile(loss=depth_loss3, optimizer=optimizers.RMSprop(lr=1e-3),
metrics=[depth_loss3])
histroy=parallel_model3.fit(training_data_scaled,depth_data_scaled,batch_size=32
,epochs=30, validation_split=0.1)
```

boo

boo

WARNING:tensorflow:From /apps/tensorflow/venv/lib/python3.6/site-packages/tensorflow/python/ops/math\_ops.py:3066: to\_int32 (from tensorflow.python.ops.math\_ops) is deprecated and will be removed in a future version.

Instructions for updating:

Use tf.cast instead.

Train on 1328 samples, validate on 148 samples

Epoch 1/30

1328/1328 [=====] - 30s 22ms/step - loss: 58.6774 - depth\_loss3: 58.6774 - val\_loss: 2192.5896 - val\_depth\_loss3: 2192.5896

Epoch 2/30

1328/1328 [=====] - 12s 9ms/step - loss: 42.2030 - depth\_loss3: 42.2030 - val\_loss: 91.6935 - val\_depth\_loss3: 91.6935

Epoch 3/30

1328/1328 [=====] - 12s 9ms/step - loss: 30.5563 - depth\_loss3: 30.5563 - val\_loss: 536.9134 - val\_depth\_loss3: 536.9134

Epoch 4/30

1328/1328 [=====] - 12s 9ms/step - loss: 22.4701 - depth\_loss3: 22.4701 - val\_loss: 61.6223 - val\_depth\_loss3: 61.6223

Epoch 5/30

1328/1328 [=====] - 12s 9ms/step - loss: 17.6318 - depth\_loss3: 17.6318 - val\_loss: 76.9335 - val\_depth\_loss3: 76.9335

Epoch 6/30

1328/1328 [=====] - 12s 9ms/step - loss: 15.1233 - depth\_loss3: 15.1233 - val\_loss: 79.3674 - val\_depth\_loss3: 79.3674

Epoch 7/30

1328/1328 [=====] - 12s 9ms/step - loss: 13.2728 - depth\_loss3: 13.2728 - val\_loss: 26.5768 - val\_depth\_loss3: 26.5768

Epoch 8/30

1328/1328 [=====] - 12s 9ms/step - loss: 11.6530 - depth\_loss3: 11.6530 - val\_loss: 40.1768 - val\_depth\_loss3: 40.1768

Epoch 9/30

1328/1328 [=====] - 12s 9ms/step - loss: 10.0743 - depth\_loss3: 10.0743 - val\_loss: 24.8131 - val\_depth\_loss3: 24.8131

Epoch 10/30

1328/1328 [=====] - 12s 9ms/step - loss: 8.6776 - depth\_loss3: 8.6776 - val\_loss: 26.3415 - val\_depth\_loss3: 26.3415

Epoch 11/30

1328/1328 [=====] - 12s 9ms/step - loss: 7.3528 - depth\_loss3: 7.3528 - val\_loss: 10.8918 - val\_depth\_loss3: 10.8918

Epoch 12/30

1328/1328 [=====] - 12s 9ms/step - loss: 6.1478 - depth\_loss3: 6.1478 - val\_loss: 19.0009 - val\_depth\_loss3: 19.0009

Epoch 13/30

1328/1328 [=====] - 12s 9ms/step - loss: 5.1529 - depth\_loss3: 5.1529 - val\_loss: 9.3052 - val\_depth\_loss3: 9.3052

Epoch 14/30

1328/1328 [=====] - 12s 9ms/step - loss: 4.1487 - depth\_loss3: 4.1487 - val\_loss: 10.9072 - val\_depth\_loss3: 10.9072

Epoch 15/30

1328/1328 [=====] - 12s 9ms/step - loss: 3.2989 - depth\_loss3: 3.2989 - val\_loss: 5.2829 - val\_depth\_loss3: 5.2829

Epoch 16/30

1328/1328 [=====] - 12s 9ms/step - loss: 2.4638 - depth\_loss3: 2.4638 - val\_loss: 6.2895 - val\_depth\_loss3: 6.2895

Epoch 17/30

1328/1328 [=====] - 12s 9ms/step - loss: 1.8874 - depth\_loss3: 1.8874 - val\_loss: 3.4222 - val\_depth\_loss3: 3.4222

Epoch 18/30

1328/1328 [=====] - 12s 9ms/step - loss: 1.2783 - depth\_loss3: 1.2783 - val\_loss: 1.6980 - val\_depth\_loss3: 1.6980

Epoch 19/30

1328/1328 [=====] - 12s 9ms/step - loss: 0.9355 - depth\_loss3: 0.9355 - val\_loss: 1.8047 - val\_depth\_loss3: 1.8047

Epoch 20/30

1328/1328 [=====] - 12s 9ms/step - loss: 0.5911 - depth\_loss3: 0.5911 - val\_loss: 0.9640 - val\_depth\_loss3: 0.9640

Epoch 21/30

1328/1328 [=====] - 12s 9ms/step - loss: 0.3260 - depth\_loss3: 0.3260 - val\_loss: 0.8054 - val\_depth\_loss3: 0.8054

Epoch 22/30

1328/1328 [=====] - 12s 9ms/step - loss: 0.2467 - depth\_loss3: 0.2467 - val\_loss: 0.4927 - val\_depth\_loss3: 0.4927

Epoch 23/30

1328/1328 [=====] - 12s 9ms/step - loss: 0.2233 - depth\_loss3: 0.2233 - val\_loss: 0.3628 - val\_depth\_loss3: 0.3628

Epoch 24/30

1328/1328 [=====] - 12s 9ms/step - loss: 0.1372 - depth\_loss3: 0.1372 - val\_loss: 0.4741 - val\_depth\_loss3: 0.4741

Epoch 25/30

1328/1328 [=====] - 12s 9ms/step - loss: 0.2239 - depth\_loss3: 0.2239 - val\_loss: 0.4303 - val\_depth\_loss3: 0.4303

Epoch 26/30

1328/1328 [=====] - 12s 9ms/step - loss: 0.1519 - depth\_loss3: 0.1519 - val\_loss: 0.7111 - val\_depth\_loss3: 0.7111

Epoch 27/30

1328/1328 [=====] - 12s 9ms/step - loss: 0.1691 - depth\_loss3: 0.1691 - val\_loss: 0.4743 - val\_depth\_loss3: 0.4743

Epoch 28/30

1328/1328 [=====] - 12s 9ms/step - loss: 0.1728 - depth\_loss3: 0.1728 - val\_loss: 0.4733 - val\_depth\_loss3: 0.4733

Epoch 29/30

```

1328/1328 [=====] - 12s 9ms/step - loss: 0.
2076 - depth_loss3: 0.2076 - val_loss: 0.3486 - val_depth_loss3: 0.3
486
Epoch 30/30
1328/1328 [=====] - 12s 9ms/step - loss: 0.
2280 - depth_loss3: 0.2280 - val_loss: 0.4498 - val_depth_loss3: 0.4
498

```

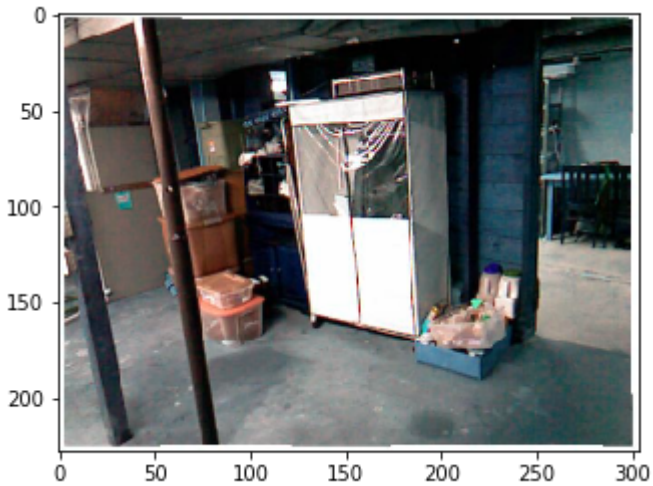
In [23]:

```

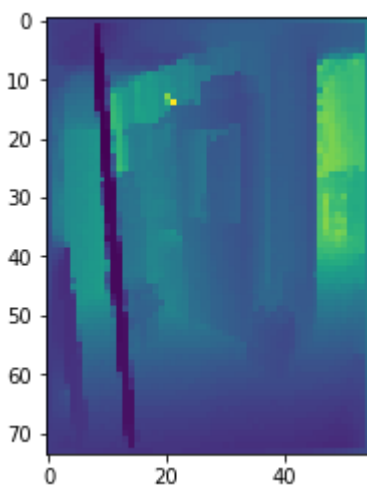
# print(training_data[0,:].shape)
# print(np.reshape(training_data[0,:],[im_sze1,im_sze2,3]).shape)
plt.imshow(training_data[1])
plt.show()

print(np.reshape(depth_data[1],[depth_sze1,depth_sze2]).shape)
plt.imshow(np.reshape(depth_data[1],[depth_sze2,depth_sze1]))
plt.show()

```

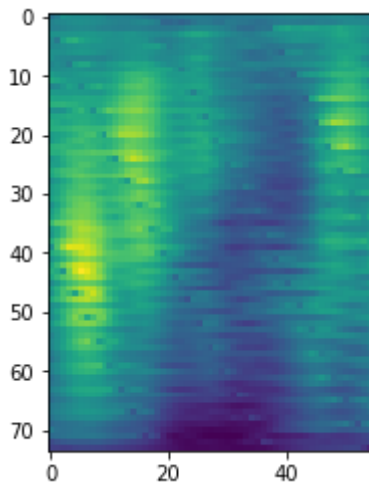


(55, 74)



In [35]:

```
y_pred_prob=parallel_model3.predict(np.reshape(training_data[1],[-1,im_size2,im_size1,3]))  
# y_pred_prob.shape  
# .shape  
  
plt.imshow(np.reshape(y_pred_prob*255,[depth_size2,depth_size1]))  
plt.show()
```



**Sample predictions on radomly selected examples from training set**

In [28]:

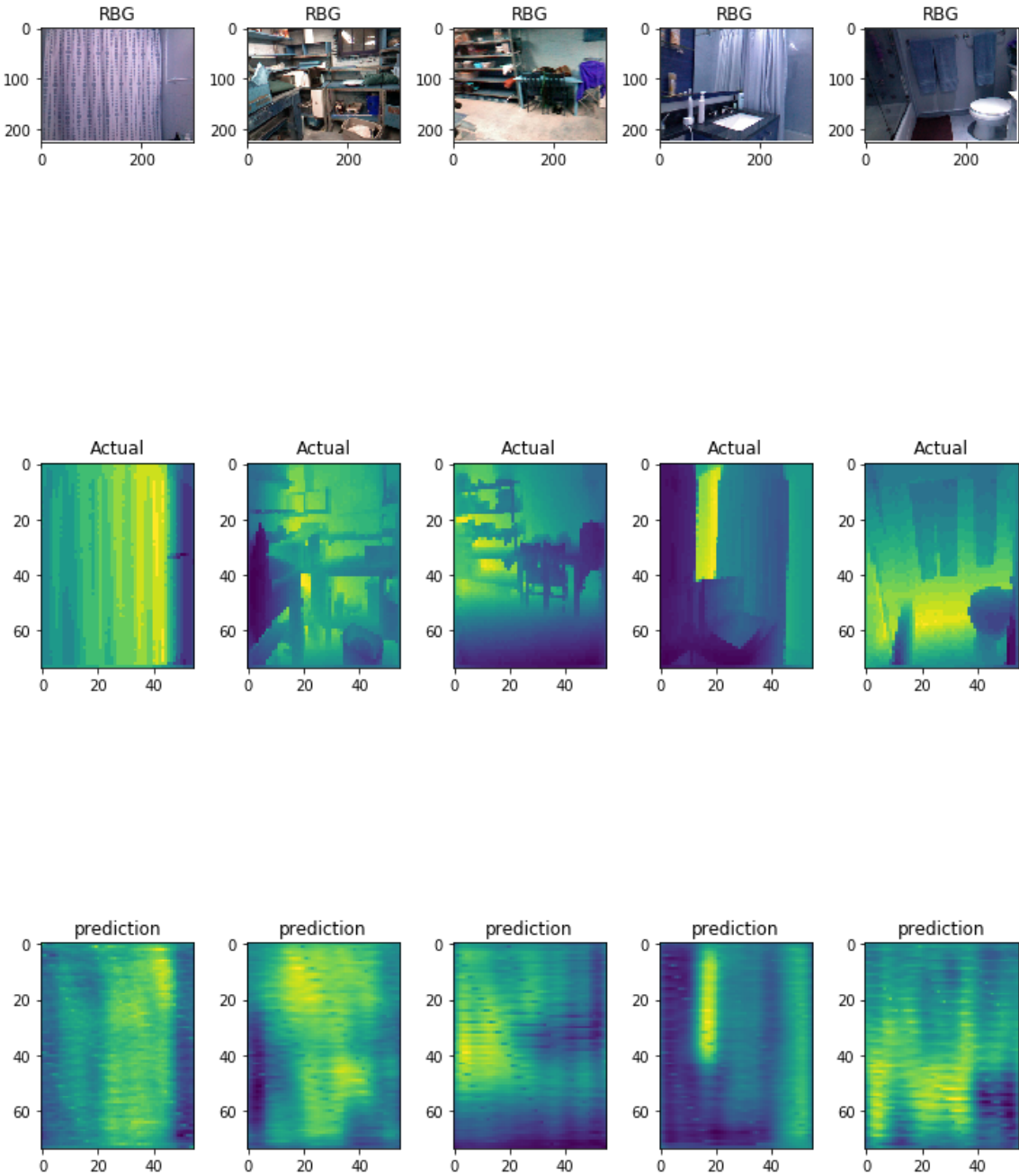
```
f = plt.figure(figsize=(10,15))
i=1
num_select=5
select=np.random.choice(len(training_data), num_select, replace=False)
for i in range(1,num_select+1):

    ax1=plt.subplot(3, num_select, i)
    ax1.imshow(training_data[select[i-1]])
    ax1.set_title('RBG')

    ax2=plt.subplot(3, num_select, i+num_select)
    ax2.imshow(depth_data[select[i-1]])
    ax2.set_title('Actual')

    y_pred_prob=parallel_model3.predict(np.reshape(training_data[select[i-1]]/25
5,[-1,im_size2,im_size1,3]))
    ax3=plt.subplot(3, num_select, i+2*num_select)
    ax3.imshow(np.reshape(y_pred_prob,[depth_size2,depth_size1]))
    ax3.set_title('prediction')
    #i=i+1
plt.tight_layout()
plt.show()
```





**Predict Test Data**

In [34]:

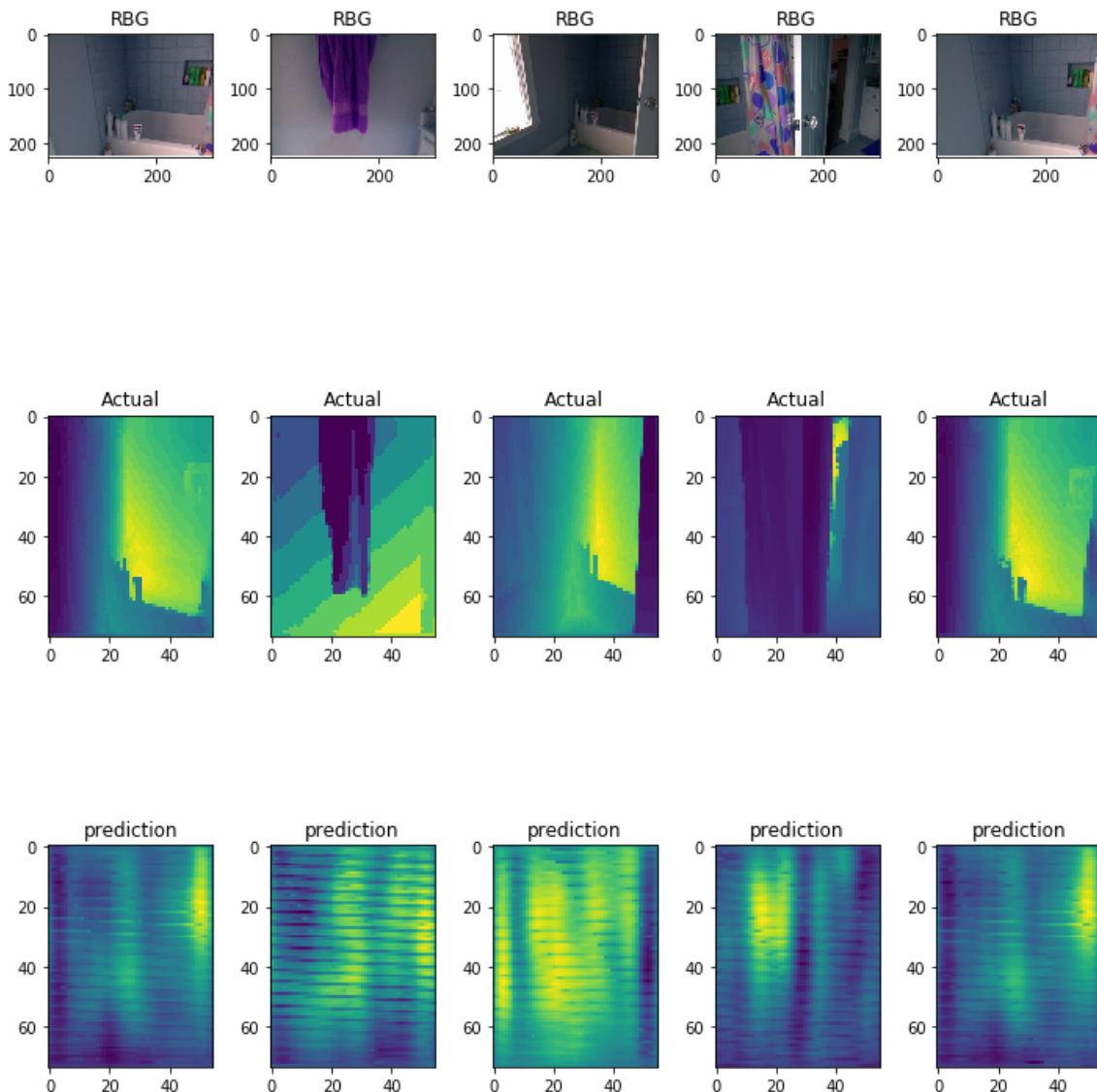
```
f = plt.figure(figsize=(10,12))
i=1
select=np.random.choice(len(test_data), 5, replace=False)
numselect=5
for i in range(1,6):
    #im1=cv2.imread(os.path.join(Datadir,'Good Parts',img1))
    #im2=cv2.imread(os.path.join(Datadir,'Defects',img2))

    ax1=plt.subplot(3, num_select, i)
    ax1.imshow(test_data[select[i-1]])
    ax1.set_title('RBG')

    ax2=plt.subplot(3, num_select, i+num_select)
    ax2.imshow(np.reshape(test_depth_data[select[i-1]],[depth_size2,depth_size1]))
    ax2.set_title('Actual')

    y_pred_prob=parallel_model3.predict(np.reshape(test_data[select[i-1]]/255,[-1,im_size2,im_size1,3]))
    ax3=plt.subplot(3, num_select, i+2*num_select)
    ax3.imshow(np.reshape(y_pred_prob*255,[depth_size2,depth_size1]))
    ax3.set_title('prediction')

plt.tight_layout()
plt.show()
```



In [ ]:

```
plt.imshow(test_data[0])  
plt.show()  
plt.imshow(test_depth_data[0])  
plt.show()
```

In [ ]:

```
selections
```

In [ ]:

```
help (np.random.choice)
```